Parsing with unification

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Introduction to Computational Linguistics





Outline

- Motivation
- Unification
- Other issues
- References





Insufficiency of CFGs

- Atomic categories:
 No relation between the categories in a CFG:
 e.g. NP, N, N', VP, VP_3sg, Nsg
- Hard to express generalisations in the grammar: for every rule that operates on a number of different categories, the rule specification has to be repeated





An example

- NP → Det N
- NPsg → Detsg Nsg
 NPpl → Detpl Npl

Can we throw away the first instance of the rule?

No: sheep is underspecified, just like the, ...

We need to add the cross-product:

 NPsg → Detsg N NPpl → Detpl N NPsg → Det Nsg

NPpl → Det Npl





An example

- Alternatively, words like sheep and the could be associated with several lexical entries.
 - → only reduces the number of rules somewhat
 - → increases the lexical ambiguity considerably





More problems

- The grammar cannot rule out yet: Those sheep runs
 → subject-verb agreement is not encoded yet
- Subcategorisation frames in their different stages of saturation are to be done as well.
- However: the expansion could be done automatically from feature structure descriptions: e.g.

$$\begin{bmatrix} \texttt{CATEGORY} & \textit{noun} \\ \texttt{SUBCAT} & \langle \rangle \\ \texttt{NUMBER} & \textit{sing} \\ \texttt{PERSON} & \textit{3} \end{bmatrix} \rightarrow \mathsf{NP_3sg}$$





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More problems

- The formalism does not leave any room for generalisations like the following:
 - "All verbs have to agree in number and person with their subject."

$$S \rightarrow NP_(^*) \ VP_(^*) \ \backslash 1 = \backslash 2$$

 "In a headed phrase, the head daughter has the same category as the mother."

$$XP \to Y \; X$$

- Feature structures can do that.
- When a feature structure stands for an infinite set of categories, the grammar cannot be compiled out into a CFG.





Part II

Definitions





Outline

- 2 Definitions
 - What is a feature structure?
 - What is unification?
- Parsing
- 4 Efficiency techniques





Outline

- 2 Definitions
 - What is a feature structure?
 - What is unification?
- 3 Parsing
- 4 Efficiency techniques





Definition

A feature structure is a directed graph, consisting of nodes and labelled edges. One node is special: the *root node*, from which every node can be reached by following edges.

A feature structure is a tuple $\langle Q, \overline{q}, \delta \rangle$:

- Q is a finite set of nodes, rooted at \overline{q}
- $\overline{q} \in Q$ is the root node
- δ : Feat \times $Q \rightarrow Q$: a partial feature value function





Notation

As a graph

• As an AVM
$$\begin{bmatrix} F \mid H & \boxed{1} \\ G & \begin{bmatrix} I & \boxed{1} \\ J & 3 \end{bmatrix} \end{bmatrix}$$





Outline

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Subsumption

• An order relation between elements of a set:

$$\sqsubseteq: P \times P \qquad \langle P, \sqsubseteq \rangle$$

- It is an information ordering:
 a subsumes b iff a contains less information than b,
 alternatively iff a is more general than b.
- Special cases
 - There may be elements a, b such that $a \not\sqsubseteq b$ and $b \not\sqsubseteq a$ (incomparable)
 - Each element subsumes itself
 a □ b ∧ b □ a ⇔ a = b
 - In an anti-chain, no two elements are comparable





 Unification is the operation of merging information-bearing structures, without loss of information if the unificands are consistent (monotonicity).



Feature structure unification

- Here,
 ☐ is a relation in the set of feature structures
- Feature structure unification (□) is the operation of combining two feature structures so that the result is the most general feature structure that is subsumed by the two unificands (the least upper bound). If there is no such structure, then the unification fails.
- Two feature structures that can be unified are compatible (or consistent). Comparability entails compatibility, but not the other way round.
- There is untyped feature structure unification and typed feature structure unification.





Untyped feature structure unification

- Token-identity: two feature structures are token-identical iff they are the same object.
- Consistent/compatible: two feature structures are consistent if they
 - have the same value,
 - the values of their common features are consistent.





Untyped unification: examples

See also Shieber (1986)

•
$$[CATEGORY noun] \sqcup [NUMBER singular] = \begin{bmatrix} CATEGORY noun \\ NUMBER singular \end{bmatrix}$$

•
$$[CAT \]] \sqcup [CAT \ | CASE \ accusative] = [CAT \ | CASE \ accusative]$$

$$\bullet \ \begin{bmatrix} \mathsf{F} & \mathsf{I} \\ \mathsf{H} & \mathsf{I} \end{bmatrix} \sqcup \ \begin{bmatrix} \mathsf{F} & \mathsf{I} \\ \mathsf{H} \mid \mathsf{G} & \mathsf{I} \end{bmatrix} = \ \begin{bmatrix} \mathsf{F} & \mathsf{I} \begin{bmatrix} \mathsf{G} & \mathsf{I} \end{bmatrix} \\ \mathsf{H} & \mathsf{I} \end{bmatrix}$$

• [CATEGORY noun] ☐ [CATEGORY verb] = fail





Untyped unification: examples

$$\begin{bmatrix} \mathsf{AGR} & \mathbb{I} \begin{bmatrix} \mathsf{NUM} & sg \end{bmatrix} \\ \mathsf{SUBJ} & \begin{bmatrix} \mathsf{AGR} & \mathbb{I} \end{bmatrix} \end{bmatrix} = \begin{bmatrix} \mathsf{SUBJ} & \begin{bmatrix} \mathsf{AGR} & [\mathsf{PERS} & \mathit{third}] \end{bmatrix} \end{bmatrix} = \begin{bmatrix} \mathsf{AGR} & \mathbb{I} \begin{bmatrix} \mathsf{NUM} & sg \\ \mathsf{PERS} & \mathit{third} \end{bmatrix} \\ \mathsf{SUBJ} & \begin{bmatrix} \mathsf{AGR} & \mathbb{I} \end{bmatrix} \end{bmatrix}$$



Destructive and non-destructive unification

In implementations, there are two ways to perform unification:

- Destructive unification: in the process of unifying two structures, one is modified and will contain the result
- Non-destructive unification: the unificands are not changed, and the result is a totally new structure.

The former is faster, but gives undesirable effects in some cases. For instance, when you apply a grammar rule, you do not want the rule to be different after the application. Non-destructive unification is easier to keep track of, but requires copying. Because it does not change the feature structures, the latter is used in implementations.





Typed unification

- Type-identity: two object are type-identical iff they are of the same type.
- Consistent: two feature structures are consistent if
 - their type values are consistent
 - their features have consistent values.





Type hierarchies

- A type hierarchy is a partially ordered set ⟨Type, ⊑⟩
- Often type hierarchies have to obey the bounded complete partial order requirement:
 - "For every set of elements with an upper bound, there is a least upper bound."
 - It ensures that every unification is unique
- Every feature structure node q has a typed value: $\theta(q)$
- In a type hierarchy, the more specific types inherit all properties from their supertypes. It is not possible to remove a property.





Typed feature structures

- A typed feature structure is a tuple $\langle Q, \overline{q}, \delta, \theta \rangle$:
 - Q is a finite set of nodes, rooted at q
 - $\overline{q} \in Q$ is the root node
 - δ : Feat \times $Q \rightarrow Q$: a partial feature value function
 - $\theta: Q \rightarrow \text{Type}$: a total type assignment function
- Typed feature structures stand in a subsumption hierarchy, the shape of which is determined by the type hierarchy and feature reentrancies. Even though the type hierarchy is finite, the feature structure hierarchy is not necessarily finite.
- It may not be immediately clear a reentrancy contains more information than a structure without. After all: the latter structure has more nodes. A reentrancy adds the knowledge that two things do not only look the same, they are the same.

Typed feature structure unification

Let $F, F' \in \mathcal{F}$ and $F = \langle Q, \overline{q}, \theta, \delta \rangle, F' = \langle Q', \overline{q}', \theta', \delta' \rangle$. It is required that $Q \cap Q' = \emptyset$. A least equivalence relation \bowtie is defined on $Q \cup Q'$ such that

- $\overline{q} \bowtie \overline{q}'$
- $\delta(f,q) \bowtie \delta(f,q')$ if both are defined and $q \bowtie q'$

Then
$$F \sqcup F' = \langle (Q \cup Q')/_{\bowtie}, [\overline{q}]_{\bowtie}, \theta^{\bowtie}, \delta^{\bowtie} \rangle$$
 with
$$\theta^{\bowtie}([q]_{\bowtie}) = \bigcup \{(\theta \sqcup \theta')(q') \mid q \bowtie q' \}$$

$$\theta^{\bowtie}([q]_{\bowtie}) = \bigsqcup\{(\theta \cup \theta')(q')|q\bowtie q'\}$$

$$\delta^{\bowtie}(f,[q]_{\bowtie}) = \begin{cases} [(\delta \cup \delta')(f,q)]_{\bowtie} & \text{if } (\delta \cup \delta')(f,q) \text{ is defined} \\ \text{undefined} & \text{otherwise} \end{cases}$$
 if all joins in θ^{\bowtie} exist. It is undefined otherwise. (Carpenter, 1992)

$$\begin{bmatrix} \mathsf{F} & \mathsf{I} \\ \mathsf{G} & \mathsf{I} \end{bmatrix} \sqcup \begin{bmatrix} \mathsf{F} & a \\ \mathsf{G} & b \end{bmatrix} = \begin{bmatrix} \mathsf{F} & \mathsf{I} & a/b \\ \mathsf{G} & \mathsf{I} \end{bmatrix}$$



Features

- In an untyped framework, feature may be added anytime anywhere: there are no restrictions.
- In typed feature structures, the occurrence of features is limited by the type hierarchy:
 - Each feature is introduced on a unique, most general type
 - Only that type and its subtypes can carry that feature
 - Each feature is introduced with a value, and all valid values have to be subsumed by this value.
- These requirements ensure monotonicity in feature structure unification





Parsing with unification-based grammars

 In most implementations, the rules have a context-free backbone, but feature structures in the categories.
 Information can be shared between the categories in the rule.

$$\bullet \begin{bmatrix} \texttt{CATEGORY} & \textit{noun} \\ \texttt{SUBCAT} & \langle \rangle \end{bmatrix} \rightarrow \boxed{ \begin{bmatrix} \texttt{CATEGORY} & \textit{det} \end{bmatrix} } \begin{bmatrix} \texttt{CATEGORY} & \textit{noun} \\ \texttt{SUBCAT} & \langle \boxed{1} \rangle \end{bmatrix}$$

 Sometimes the rules are written in a CFG-like format, sometimes feature structures whereby a feature identifies the daughters.





Parsing

- Is there any difference in parsing?
- No. All known techniques can be used, and you will obtain a working parser, provided that you use non-destructive unification.
- But it will be (much) slower: the categories are much bigger, and the unification is non-destructive. A lot of copying is done.





Techniques to improve efficiency

- Packing (subsumption packing)
- Rule filter: not all rules can feed into all other rules
- Quick check: some paths are more likely to fail than others
- Sharing and deleting of daughters: do not keep information that can easily be (re)computed or retrieved
- Delayed copying (Tomabechi): only copy when you are sure that it will be used





- With CFGs and chart parsing, every category is only stored once for a given pair of indices to avoid recomputation.
 The criterion is a simple identity/equality check.
- Suppose we have (among others) the following feature structure in the chart:

$$\begin{bmatrix} \mathsf{CAT} & \mathsf{noun} \\ \mathsf{AGR} & \begin{bmatrix} \mathsf{PER} & \mathbf{3} \end{bmatrix} \end{bmatrix}$$





 After a rule application, we want to add one of the following feature structures:



- Which one the two should we take?
 - all: too many solutions (spurious ambiguity)
 - the first, most recent, ...: may give over/undergeneration

e.g. with (4) a solution with
$$\begin{bmatrix} CAT & noun \\ AGR & [PER & 1] \end{bmatrix}$$
 is also possible,

although that does not correspond with the original situation

 in general: when the newer category is more specific, using it may invalidate older analyses (which were based on a more general feature structure; see (2)), and vice versa





- In CFGs with atomic catgories, we use an equality check
- With feature structures, we want to be able to use unification (it is the operation we use in rule applications), but unification should not be used to perform the check.
- A subsumption check will tell us what is the most general feature structure, and that one should be stored in the chart:
 - if new
 — old, then the set of solutions from new will be a superset of the set of solutions from old, so replace old by new.
 - if old

 in new, then new should be discarded (it is already implied by old)
 - otherwise, add new.

In this way, no solutions are invalidated.



Part III

Other issues





Statistical processing with feature structures

- Applying statistical techniques to feature structures is very hard, mainly because of the presence of reentrancies (Abney, 1997, See e.g.).
- Very often the following technique is applied: simplify the feature structure, even to the type of the root node only.
 That way, the categories can be made sufficiently simple.
 Examples: Bouma et al. (2001); Toutanova et al. (2002)





Default unification

- Credulous default unification: the default FS adds as much information as possible that is not conflicting with the strict FS. It is non-deterministic.
- Sceptical default unification: the default FS adds the information that is common between each variant of credulous default unification. (Carpenter, 1993)
- Sensitive to order of processing
- Persistent associative default unification (Lascarides et al., 1996)
- Mainly used for lexical specification





Credulous default unification

• $F \mathrel{\sqcup_{c}^{<}} G = \{F \mathrel{\sqcup} G' | G' \mathrel{\sqsubseteq} G \text{ is maximal such that } F \mathrel{\sqcup} G' \text{ is defined}\}$

$$\bullet \ \, \begin{bmatrix} \mathsf{F} & a \end{bmatrix} \overset{<}{\sqcup_{\mathsf{C}}} \begin{bmatrix} \mathsf{F} & \mathsf{I} \, b \\ \mathsf{G} & \mathsf{I} \\ \mathsf{H} & c \end{bmatrix} = \{ \ \, \begin{bmatrix} \mathsf{F} & a \\ \mathsf{G} & b \\ \mathsf{H} & c \end{bmatrix}, \ \, \begin{bmatrix} \mathsf{F} & \mathsf{I} \, a \\ \mathsf{G} & \mathsf{I} \\ \mathsf{H} & c \end{bmatrix} \}$$





Sceptical default unification

•
$$F \stackrel{<}{\sqcup_s} G = \sqcap (F \stackrel{<}{\sqcup_c} G)$$

$$\bullet \ \begin{bmatrix} \mathsf{F} & a \end{bmatrix} \overset{<}{\sqcup}_{\mathsf{S}} \ \begin{bmatrix} \mathsf{F} & \square & b \\ \mathsf{G} & \square \\ \mathsf{H} & c \end{bmatrix} = \sqcap \{ \begin{bmatrix} \mathsf{F} & a \\ \mathsf{G} & b \\ \mathsf{H} & c \end{bmatrix}, \begin{bmatrix} \mathsf{F} & \square a \\ \mathsf{G} & \square \\ \mathsf{H} & c \end{bmatrix} \} = \begin{bmatrix} \mathsf{F} & a \\ \mathsf{G} & \bot \\ \mathsf{H} & c \end{bmatrix}$$





Desirable properties of default unification

- Always well-defined
- All strict information is preserved
- If F and G are consistent, it should give the same result as strict unification
- It is finite





Part IV

References





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