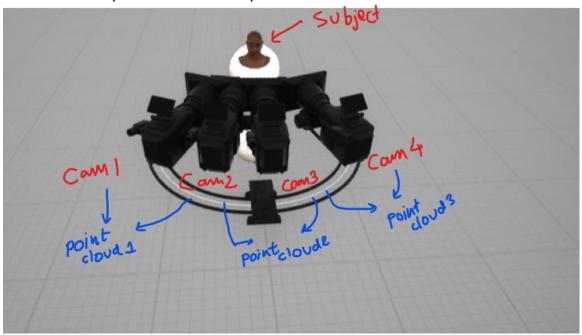
Merge Point clouds from stereo pair reconstructions

Background:

- Face reconstruction is a scanning technique for creating a high quality 3d facial geometry from multiple images.
- Accurate reconstruction can be done by arranging multiple cameras in a circular fashion around the subject and constructing point clouds from each camera pair. This is called pair-wise stereo reconstruction.



• Above figure shows point clouds generated using images from camera pairs. These point clouds then need to be merged and converted into a single mesh for usage.

Goal:

• Given multiple point clouds from different stereo camera pairs, corresponding images and the camera calibration properties(projection matrices) merge the point clouds into a single mesh.

Expected outcome:

• Single face mesh by merging multiple point cloud meshes from all views.

• Send the obj file of converted face mesh and link of the github repository.

Reference:

- <u>High-Quality Single-Shot Capture of Facial Geometry</u> (Section 2.3)
- <u>Camera Calibration and Projection matrices</u>

Data Required:

• Point Clouds, Camera Images and Calibration Parameters