

## Auto PWT

For all below mentioned conditions monitor battery SoC and temperature during regenerative braking tests and analyse their impact on energy recovery and stability control interventions.

- Front Drive:
  1. Normal drive and dynamic manoeuvres with stability control
  2. Normal drive and skid
  3. Normal drive and decelerate without brake
  4. Normal drive and decelerate with brake
  5. Normal drive and emergency brake (Obstacle)
- Reverse Drive:
  1. Normal reverse and decelerate without brake
  2. Normal reverse and decelerate with brake