### LSTMs and GRUs

#### Vineeth N Balasubramanian

Department of Computer Science and Engineering Indian Institute of Technology, Hyderabad



### Review: Questions

#### Question

• How to tackle the vanishing gradient problem in RNNs with solutions that don't change the architecture?

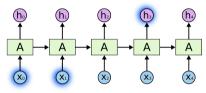
### Review: Questions

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 How to tackle the vanishing gradient problem in RNNs with solutions that don't change the architecture? Use ReLU; Regularization; Better initialization of weights; Use only short time sequences

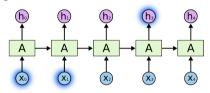
### Long-Term Dependencies: The Problem

- RNNs connect previous information to present task which:
  - may be enough for predicting the next word for "the clouds are in the sky"

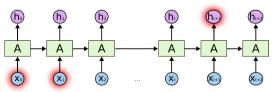


### Long-Term Dependencies: The Problem

- RNNs connect previous information to present task which:
  - may be enough for predicting the next word for "the clouds are in the sky"



 may not be enough when more context is needed: "I grew up in France ... I speak fluent French"



### Recall: Training RNNs

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- Limitations of BPTT
  - Vanishing Gradients
  - Exploding Gradients
- How to overcome by changes in RNN architecture?

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- Recommended method: Backprop Through Time (BPTT)
- Limitations of BPTT
  - Vanishing Gradients
  - Exploding Gradients
- How to overcome by changes in RNN architecture?
  - LSTMs (1997)
  - **GRUs** (2014)

 A type of RNN proposed by Hochreiter and Schmidhuber in 1997 as a solution to the long-term dependency problem

Credit: Christopher Manning, Stanford Univ

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5/21

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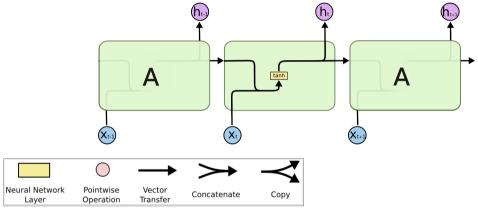
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  - On each timestep, each element of the gates can be open (1), closed (0), or somewhere in-between
  - The gates are dynamic, their value is computed based on current context

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### **LSTMs**

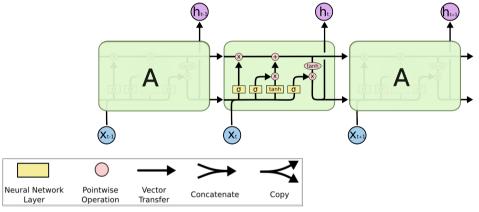
- All RNNs have the form of a chain of repeating modules of neural network
- Repeating module in a vanilla RNN is a single layer with tanh activation



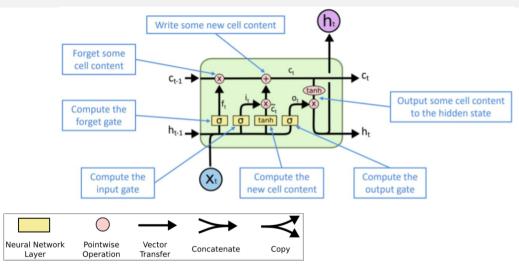
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### **LSTMs**

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- Repeating module in an LSTM contains four interacting layers

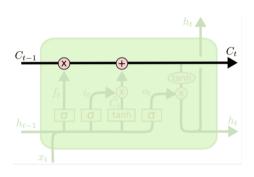


### **LSTMs**



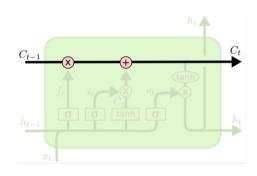
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• Cell state  $(C_t)$ :



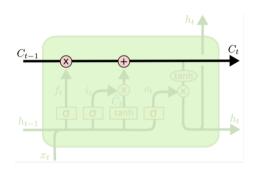
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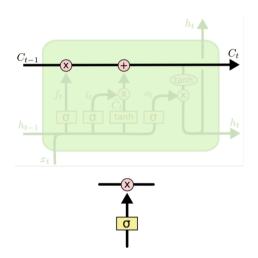
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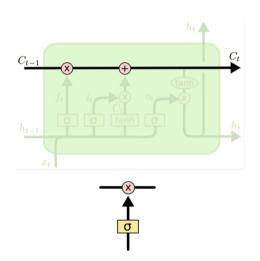


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#### • Gates:

 Composed of a sigmoid neural net layer and a pointwise multiplication operation



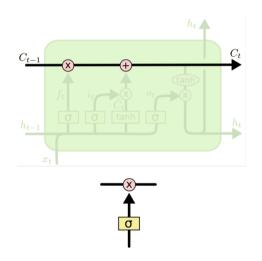


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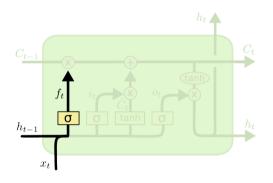
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#### • Gates:

- Composed of a sigmoid neural net layer and a pointwise multiplication operation
- Sigmoid layer outputs numbers between zero and one, describing how much of each component should be let through



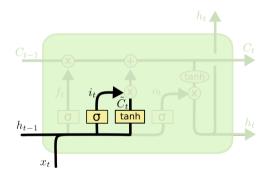
Forget gate: controls what is kept vs what is forgotten, from previous cell state



$$f_t = \sigma \left( W_f \cdot [h_{t-1}, x_t] + b_f \right)$$

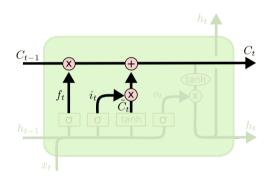
Input gate: decides what information to throw away from the cell state

Cell content: new content to be written to cell



$$i_t = \sigma \left( W_i \cdot [h_{t-1}, x_t] + b_i \right)$$
  
$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

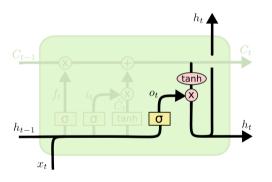
Cell state: erase ("forget") some content from last cell state, and write ("input") some new cell content



$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

Output gate: controls what parts of cell are output to hidden state

Hidden state: read ("output") some content from cell



$$o_t = \sigma (W_o [h_{t-1}, x_t] + b_o)$$
$$h_t = o_t * \tanh (C_t)$$

Forget gate: controls what is kept vs forgotten, from previous cell state

Input gate: controls what parts of the new cell content are written to cell

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New cell content: this is the new content to be written to the cell

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$$\tilde{C}_t = \tanh(W_C \cdot [h_{t-1}, x_t] + b_C)$$

$$C_t = f_t * C_{t-1} + i_t * \tilde{C}_t$$

$$h_t = c_t * \tanh(C_t)$$

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Sigmoid function: all gate values are between 0 and 1

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 What can you tell about cell  $state(C_t)$ , if forget gate is set to 1 and input gate set to 0?

Forget gate: controls what is kept vs forgotten, from previous cell state

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- What can you tell about cell  $state(C_t)$ , if forget gate is set to 1 and input gate set to 0?
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- What happens if you fix input gate to all 1s, forget gate to all 0s, output gate to all 1s?

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  - Almost standard RNN:

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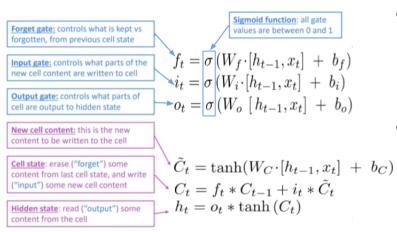
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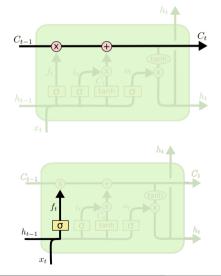
- What can you tell about cell  $state(C_t)$ , if forget gate is set to 1 and input gate set to 0?
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  - Almost standard RNN: Why almost?



- What can you tell about cell state( $C_t$ ), if forget gate is set to 1 and input gate set to 0?
  - Information of that cell is preserved indefinitely
- What happens if you fix input gate to all 1s, forget gate to all 0s, output gate to all 1s?
  - Almost standard RNN; Why almost?
  - Tanh added here

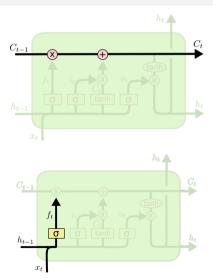
Credit: Christopher Olah; Christopher Manning, Stanford University

### LSTM: How does it solve the vanishing gradient problem?



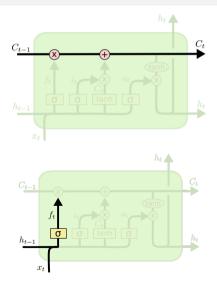
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# LSTM: How does it solve the vanishing gradient problem?



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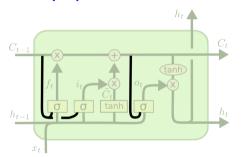
# LSTM: How does it solve the vanishing gradient problem?



- Gradient "highway"
- Gradient at  $C_t$  passed on to  $C_{t-1}$  unaffected by any other operations, but for forget gate; why does this not matter?
- Forget gate is part of the design, it reduces the gradient where it should, does not ameliorate the gradient otherwise!

#### Variants of LSTM

### • LSTM with peephole connections<sup>2</sup>



$$f_{t} = \sigma (W_{f} \cdot [C_{t-1}, h_{t-1}, x_{t}] + b_{f})$$

$$i_{t} = \sigma (W_{i} \cdot [C_{t-1}, h_{t-1}, x_{t}] + b_{i})$$

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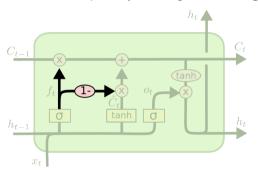
Credit: Christopher Olah

<sup>&</sup>lt;sup>2</sup>Gers and Schmidhuber, Recurrent nets that time and count, IJCNN 2000

### Variants of LSTM

#### Coupled forget and input gates

Instead of separately deciding what to forget and what to add, make decisions together



$$C_t = f_t * C_{t-1} + (1 - f_t) * \tilde{C}_t$$

Credit: Christopher Olah

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- 2005 Vanilla LSTM (as we know today) Used BPTT
  - Graves and Schmidhuber, Framewise phoneme classification with bidirectional LSTM and other neural network architectures, Neural Networks, 2005

### LSTMs: Real-world success

- 2013-2015: LSTMs started achieving state-of-the-art results
  - Successful tasks include: handwriting recognition, speech recognition, machine translation, parsing, image captioning

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- 2013-2015: LSTMs started achieving state-of-the-art results
  - Successful tasks include: handwriting recognition, speech recognition, machine translation, parsing, image captioning
- Now (2020), other approaches (e.g. Transformers) have become more dominant for certain tasks
  - Transformers use the idea of self-attention
  - In WMT 2019 ((a MT conference + competition), summary report contains "RNN" 7 times, "Transformer" 105 times

Credit: Christopher Manning, Stanford University

Proposed in 2014 as a simpler alternative to LSTM

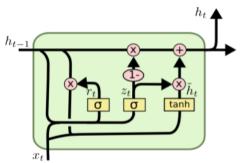
<sup>&</sup>lt;sup>2</sup>Chung et al, Empirical Evaluation of Gated Recurrent Neural Networks on Sequence Modeling, NeurIPS-W 2014

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Reset gate: controls what parts of previous hidden state are used to compute new content

New hidden state content: reset gate selects useful parts of prev hidden state. Use this and current input to compute new hidden content.

Hidden state: update gate simultaneously controls what is kept from previous hidden state, and what is updated to new hidden state content

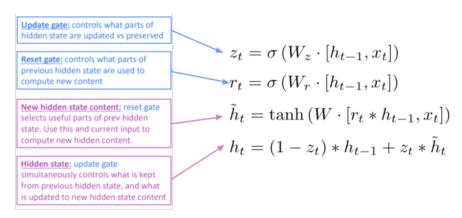
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$$r_t = \sigma \left( W_r \cdot [h_{t-1}, x_t] \right)$$

$$\tilde{h}_t = \tanh \left( W \cdot [r_t * h_{t-1}, x_t] \right)$$

$$h_t = (1 - z_t) * h_{t-1} + z_t * \tilde{h}_t$$

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• What happens if reset gate is set to all 1s and update gate to all 0s?

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  - ullet No internal memory  $(c_t)$  different from exposed hidden state
  - No output gate as in LSTMs
- LSTM a good default choice (especially if data has long-range dependencies, or if training data is large); Switch to GRUs for speed and fewer parameters

#### Homework

#### Readings

- Deep Learning book: Sections 10.1-10.7, 10.10-10.11
- Understanding LSTM Networks
- Illustrated Guide to LSTMs and GRUs: A step by step explanation
- (Optional) Recurrent Neural Network Tutorial—Implementing a GRU/LSTM RNN with Python and Theano
- (Optional) Training LSTMs using BPTT: Alex Graves' book on RNN (Sec 4.6, pg 36-38)

#### Questions

• How does GRU address vanishing gradients?

### References

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