EE 6180: Advanced Topics in Artificial Intelligence

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Lecture 14

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## 1 Follow the Perturbed Leader (FTPL)

Recall the FTPL algorithm as described in the last lecture.

Algorithm 1 Follow the Perturbed Leader

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1: procedure FTPL

2: Input: \eta > 0, \mathcal{X}

3: \Theta_1 \leftarrow 0

4: for t = 1, ..., T do

5: sample \gamma_t \sim \mathcal{N}(\mathbf{0}, I_d)

6: predict: x_t \leftarrow \operatorname{argmin}_x \langle x, \Theta_t + \eta \gamma_t \rangle

7: \Theta_{t+1} = \Theta_t + \theta_t
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**Theorem 1** (Cohen and Hazan (2015)). Assuming that  $\sum_{i=1}^{d} x_i \leq K, \forall x \in \mathcal{X}$ , using FTPL algorithm, the following bound is obtained for expectation of total regret  $R_T$  upto time T:

$$\mathbb{E}_{\gamma_1^T}[R_T] \le \sqrt{2K \ln |\mathcal{X}|} \left( \frac{KT}{\eta} + \eta \right), \tag{1}$$

Using  $\eta^* = \sqrt{KT}$ , we get the strictest upper bound:

$$\mathbb{E}_{\gamma_{\tau}^{T}}[R_{T}] \le 2K\sqrt{T\ln|\mathcal{X}|},\tag{2}$$

Let  $z = \theta + \eta \gamma$ , where  $\theta \in \mathbb{R}^d$ ,  $\gamma_i \overset{\text{i.i.d.}}{\sim} \mathcal{N}(0, 1), \forall i \in [d]$ . So,  $z \sim \mathcal{N}(\Theta, \eta^2 I)$ . Using Stein's Lemma,

$$\eta^{2} \mathbb{E} \left[ \frac{\partial g(\mathbf{z})}{\partial \mathbf{z}_{i}} \right] = \mathbb{E}[(\mathbf{z}_{i} - \theta_{i})g(\mathbf{z})]$$

$$= \eta \mathbb{E}[\gamma_{i}g(\mathbf{z})]$$

$$\implies \mathbb{E} \left[ \frac{\partial g(\mathbf{z})}{\partial \mathbf{z}_{i}} \right] = \frac{1}{\eta} \mathbb{E}[\gamma_{i}g(\mathbf{z})]$$
(3)

**Lemma 2.** Let  $g(\theta) = \min_{x \in \mathcal{X}} \langle x, \theta + \eta \gamma \rangle$ ,  $\Phi(\theta) = \mathbb{E}[g(\theta)]$  and  $H = \nabla^2 \Phi(\theta)$ , then:

$$H_{ij} = [\nabla^2 \Phi(\theta)]_{ij} = \frac{1}{\eta} \mathbb{E}[\gamma_i \widehat{x}_j]$$
 (4)

where  $\widehat{x} = \operatorname{argmin}_{x \in \mathcal{X}} \langle x, \theta + \eta \gamma \rangle$ .

Proof.

$$\begin{split} \frac{\partial \Phi(\theta)}{\partial \theta_i} &= \mathbb{E}\left[\frac{\partial g(\theta)}{\partial \theta_i}\right] \stackrel{\text{(3)}}{=} \frac{1}{\eta} \mathbb{E}[\gamma_i g(\theta)] \\ &= \frac{1}{\eta} \mathbb{E}[\gamma_i \min_{x \in \mathcal{X}} \langle x, \theta + \eta \gamma \rangle] \\ \implies H_{ij} &= \frac{\partial^2 \Phi(\theta)}{\partial \theta_i \partial \theta_j} = \frac{1}{\eta} \frac{\partial \mathbb{E}[\gamma_i \min_{x \in \mathcal{X}} \langle x, \theta + \eta \gamma \rangle]}{\partial \theta_j} = \frac{1}{\eta} \mathbb{E}[\gamma_i \widehat{x}_j] \end{split}$$

## Proposition 3.

$$-\theta_t^{\top} \nabla^2 \Phi(\tilde{\Theta}_t) \theta_t \le \frac{2K}{\eta} \sqrt{2K \ln |\mathcal{X}|}$$

*Proof.* We omit the detailed proof for this proposition. The proof uses Lemma 2 as an essential component. An interested reader is encouraged to refer (Cohen and Hazan, 2015, Lemma 2) for the proof of this proposition.

Now we proceed to prove the regret bound of FTPL.

*Proof.* Consider the potential function  $\Phi(\theta) = \mathbb{E}[\min_{x \in \mathcal{X}} \langle x, \theta + \eta \gamma \rangle]$ . Also recall that  $\Theta_t = \sum_{i=1}^{t-1} \theta_i$  where  $\theta_i$  are the adversary outputs. Consider:

$$\Phi(\Theta_t) = \mathbb{E}[\min_{x \in \mathcal{X}} \langle x, \Theta_t + \eta \gamma \rangle]$$

$$\implies \nabla_{\Theta_t} \Phi(\Theta_t) = \nabla \mathbb{E}[\min_{x \in \mathcal{X}} \langle x, \Theta_t + \eta \gamma \rangle]$$

$$= \mathbb{E}[x_t]$$
 By definition of  $x_t$  (5)

Using residual form of Taylor series expansion,

$$\begin{split} \Phi(\Theta_{t+1}) &= \Phi(\Theta_t + \theta_t) \\ &= \Phi(\Theta_t) + \langle \nabla \Phi(\Theta_t), \theta_t \rangle + \frac{1}{2} \theta_t^\top \nabla^2 \Phi(\tilde{\Theta}_t) \theta_t \\ &\stackrel{(5)}{=} \Phi(\Theta_t) + \mathbb{E}[\langle x_t, \theta_t \rangle] + \frac{1}{2} \theta_t^\top \nabla^2 \Phi(\tilde{\Theta}_t) \theta_t \end{split}$$

Summing up from t = 1 to t = T,

$$\Phi(\Theta_{T+1}) = \Phi(\Theta_1) + \sum_{t=1}^{T} \mathbb{E}[\langle x_t, \theta_t \rangle] + \frac{1}{2} \sum_{t=1}^{T} \theta_t^{\top} \nabla^2 \Phi(\tilde{\Theta}_t) \theta_t$$
 (6)

Now, consider the following:

$$\Phi(\Theta_{T+1}) = \mathbb{E}[\min_{x \in \mathcal{X}} \langle x, \Theta_{T+1} + \eta \gamma \rangle] 
\leq \min_{x \in \mathcal{X}} \mathbb{E}[\langle x, \Theta_{T+1} + \eta \gamma \rangle]$$
Jensen's inequality
$$= \min_{x \in \mathcal{X}} \langle x, \Theta_{T+1} \rangle$$

$$= \min_{x \in \mathcal{X}} \sum_{t=1}^{T} \langle x, \theta_t \rangle = L_T^*$$
(7)

Using (6) and (7), and definition of expected regret, i.e,  $\mathbb{E}[R_T] = \sum_{t=1}^T \mathbb{E}[\langle x_t, \theta_t \rangle] - L_T^*$ 

$$\sum_{t=1}^{T} \mathbb{E}[\langle x_{t}, \theta_{t} \rangle] \leq L_{T}^{*} - \Phi(\Theta_{1}) - \frac{1}{2} \sum_{t=1}^{T} \theta_{t}^{\top} \nabla^{2} \Phi(\tilde{\Theta}_{t}) \theta_{t}$$

$$\implies \mathbb{E}[R_{T}] \leq -\Phi(\Theta_{1}) - \frac{1}{2} \sum_{t=1}^{T} \theta_{t}^{\top} \nabla^{2} \Phi(\tilde{\Theta}_{t}) \theta_{t}$$
(8)

Now, we need to find upper bound on the two terms in RHS.

$$-\Phi(\Theta_1) = -\eta \mathbb{E}[\min_{x \in \mathcal{X}} \langle x, \gamma \rangle] = \eta \mathbb{E}[\max_{x \in \mathcal{X}} \langle x, \gamma \rangle] \le \eta \sqrt{2K \ln |\mathcal{X}|}$$
(9)

The last inequality follows because notice that  $\langle x, \gamma \rangle$  is (sub) Gaussian.  $\operatorname{Var}(\langle x, \gamma \rangle) = \operatorname{Var}(\sum_{i=1}^d x_i \gamma_i) = \sum_{i=1}^d x_i^2 \operatorname{Var}(\gamma_i) = \sum_{i=1}^d x_i^2 \le \sum_{i=1}^d x_i \le K$ . The last result follows from the assumption  $x_i \in [0, 1]$ . Once we establish that  $\operatorname{Var}(\langle x, \gamma \rangle) \le K$ , the rest follows from Massart's Lemma, i.e,  $\mathbb{E}[\max_i X_i] \le \sqrt{2\sigma^2 \ln |\mathcal{X}|}$  for  $X_i \in \mathcal{X}, X_i \sim \operatorname{subG}(\sigma^2)$ . Continuing from (8), using (9) and Proposition 3, we get:

$$\mathbb{E}[R_T] \le \sqrt{2K \ln |\mathcal{X}|} \left( \frac{KT}{\eta} + \eta \right)$$

## References

Alon Cohen and Tamir Hazan. Following the perturbed leader for online structured learning. volume 37 of *Proceedings of Machine Learning Research*, pages 1034–1042, Lille, France, 07–09 Jul 2015. PMLR. URL http://proceedings.mlr.press/v37/cohena15.html.