

Operating System

Intro

- OS is an interface b/w user and ~~hardware~~ hardware.
- Resource allocator
- Manager → memory, processes, files, security etc.

Goals:-

- Primary → convenience
- Secondary → efficiency

- Process requires two types of time -
  - ↳ CPU time
  - ↳ I/O time

Types of OS:-

- Batch OS
- Multiprogramming
  - Process will share
- Multitasking
  - Process will not share
- Multi processing
  - Preemption is allowed
- Real time
  - Parallelism → Multiple processors
  - Throughput is improved
  - Reliability through more CPUs
  - strict deadlines for given jobs

01

Process Management

Attributes of a process:-

- Process id
- Program Counter
- Process state
- Priority
- General purpose registers
- List of open files
- List of open devices
- Protection

PCB's

- each
- ↳ for a process
- ↳ connected as linked lists
- ↳ Hold all information related to one process
- ↳ ~~It is~~ It is also called context
- ↳ Everything about a process is a context

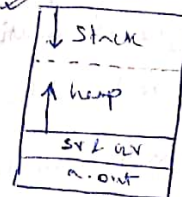
- A program resides in secondary memory generally. But subdivision of a program is sent to main memory and get ~~executed~~ <sup>called</sup> executed. This subdivision are process.

- Program is divided into several processes

- Static and Global variables remain with the process is destroyed.

- Stack and heap are also there in memory.
  - ↓ memory ↓
  - Allocated to each process (function stack/recursion stack)
  - used by processes if needed

Ex. C  
↓  
compiler  
↓  
a.out



## ✓ States of a process

- ✓ 1) New (secondary memory)
- ✓ 2) Ready (primary " )
- ✓ 3) Run ( " )
- ✓ 4) Block or wait ( ~~secondary~~ primary " )
- ✓ 5) Termination or completion

- ✓ 6) Suspend ready (secondary " )
- ✓ 7) Suspend wait or ~~suspend~~ suspend block. (secondary " )

## ✓ Operations on process

- ✓ 1) Creation
- ✓ 2) Scheduling
- ✓ 3) Execution
- ✓ 4) Killing / Delete.

## ✓ Multiprogramming

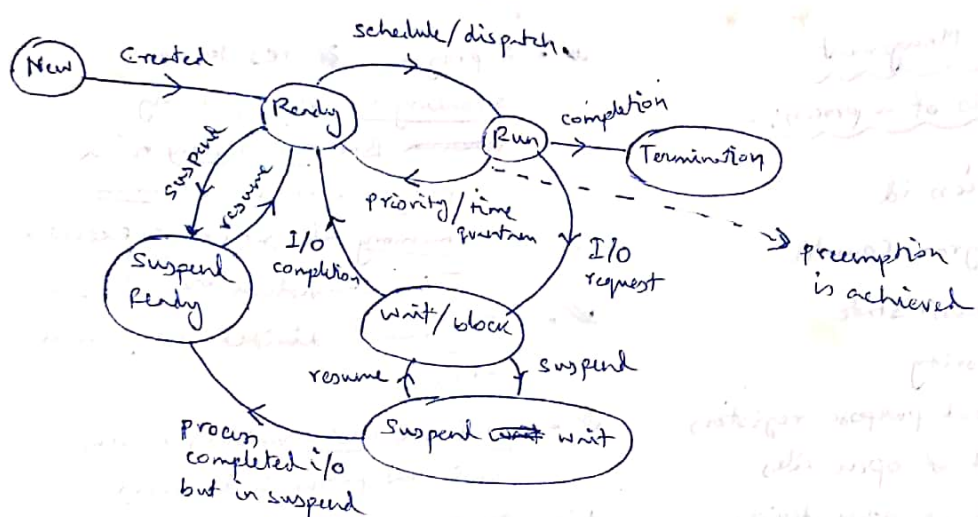
with preemption  
↓  
Also called  
→ multitasking / time sharing

→ Context Switching → switch between processes for a quantum time.

• A process's PCB is deleted after its termination.

0.3

## ✓ Process State Diagram



- ✓ 1) Long Term scheduler → take decisions about No. of process ~~creation~~ creation
- ✓ 2) Short " → select processes from ~~pool~~ ready queue
- ✓ 3) Medium " → Take suspension decision of processes

• Degree of multiprogramming is no. of processes that can be present in ready state at maximum.

• Long term scheduler have important impact on the performance of a system.

↓  
It should choose a mix of CPU-bound I/O bound process.

• Context switching → C.S. time can be very less by reducing the size of the PCB or context, so moving time will be less.



- Swapping is moving process from main memory to secondary memory and then secondary memory to main memory.
- Less swapping is good for performance, so good medium term scheduler should be chosen.

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Consider a system with 'N' CPU processors and 'M' processes, then

	min	max
ready	0	M
running	0	N
block	0	M

new memory  
processes can present

if all s/o

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### Important parameters of processes

- 1) Arrival time
- 2) Burst time
- 3) Completion time
- 4) Turn around time  $\rightarrow (CT - AT) / (BT + WT)$
- 5) Waiting time  $\rightarrow (TAT - BT)$
- 6) Response time  $\rightarrow \frac{WT}{BT}$

In real time, it is not possible to know the burst time of a process.

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### CPU Scheduling

- who  $\rightarrow$  Short term Scheduler
- where  $\rightarrow$  Ready state to running
- when  $\rightarrow$  when a process moves from

- i) Run  $\rightarrow$  Termination
- ii) Run  $\rightarrow$  Wait
- Run  $\rightarrow$  Ready

- ii) New  $\rightarrow$  Ready i.e. when a process is just created
- iii) Wait  $\rightarrow$  Ready

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### FCFS

Criteria: Arrival time

mode: Non-preemptive

WT	TAT	PNO	AT	BT	CT
0	4	1	0	4	4
3	6	2	1	3	7
5	6	3	2	1	8
5	7	4	3	2	10
6	11	5	4	5	15

### GNATT Chart

P1	P2	P3	P4	P5
0	4	7	8	10

$$\text{Avg TAT} = \frac{4+6+6+7+11}{5} = \frac{34}{5} = 6.8$$

$$\text{Avg WT} = \frac{0+3+5+5+6}{5} = \frac{19}{5} = 3.8$$

In non-preemptive scheduling, response time = waiting time

- FCFS has convoy effect.

✓ 08

✓ Convoy effect of FCFS

PNO	AT	BT	CT	TAT	WT
1	0	20	20	20	0
2	1	2	22	21	19
3	1	1	23	22	21

PNO	AT	BT	CT	TAT	WT
1	1	20	23	22	2
2	0	2	2	2	0
3	0	1	3	3	2

$P_1$	$P_2$	$P_3$	
0	20	22	23

$$\text{Avg WT} = \frac{0 + 19 + 21}{3} = \frac{40}{3}$$

$P_2$	$P_3$	$P_1$	
0	2	3	23

$$\text{Avg WT} = \frac{2 + 0 + 2}{3} = \frac{4}{3}$$

✓ 09

✓ FCFS example

PNO	AT	BT
1	0	2
2	3	1
3	5	6

• Gaps are created because of that time instance, remaining processes are not at ready queue, so have to wait until their AT comes.

$P_1$		$P_2$		$P_3$	
0	2	3	4	5	11

CT	TAT	WT
2	2	0
4	1	0
11	6	0

$$\text{Avg TAT} = \frac{2 + 1 + 6}{3} = 3$$

$$\text{Avg WT} = \frac{0 + 0 + 0}{3} = 0$$

• Implement by queue data structure

• Complexity  $\rightarrow O(n)$

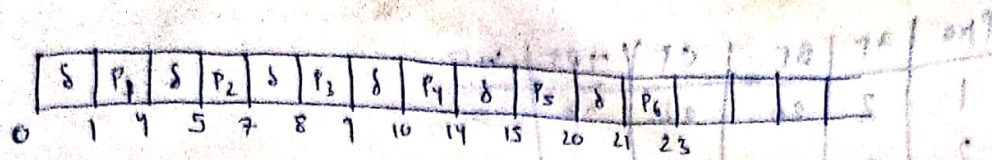
✓ 10  $\rightarrow$  context switch time FCFS with overhead

PNO	AT	BT	CT	TAT	WT
1	0	3			
2	1	2			
3	2	1			
4	3	4			
5	4	5			
6	5	2			

(Ready)

Scheduler  $\rightarrow$  Dispatching process

(Run)



Schedule time  $\rightarrow 23$

Overhead  $\rightarrow 6$

Inefficiency  $\rightarrow \left(\frac{6}{23}\right) \times 100$

$= 0.26 \times 100 = 26\%$

Efficiency  $\rightarrow \eta = \left(1 - \frac{6}{23}\right) \times 100$

$= 0.74 \times 100 = 74\%$

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SJF (Short Job First) :-

Criteria - Burst time

mode - Non preemptive

CT	PNO	AT	BT	TAT	WT
15	1	1	7	14	
8	2	2	5	6	
1	3	3	1		
3	4	4	2		
23	5	5	8		

PNO	AT	BT	CT	TAT	WT
1	1	7	8	7	0
2	2	5	16	14	9
3	3	1	9	6	5
4	4	2	11	7	5
5	5	8	24	19	11

Avg TAT

$= \frac{7+14+6+7+19}{5}$

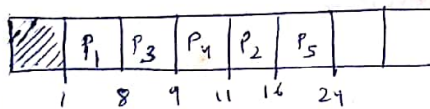
$= \frac{53}{5} = 10.6$

Avg WT

$= \frac{0+9+5+5+11}{5}$

$= 6$

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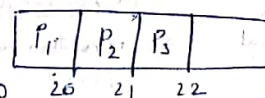


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Analysis of SJF :-

• SJF contains Convoy effect

PNO	AT	BT	CT	TAT	WT
1	0	20	20	20	0
2	1	1	21	20	19
3	2	1	22	20	19



Avg WT  $= \frac{0+19+19}{3} = \frac{38}{3} = 12.66$



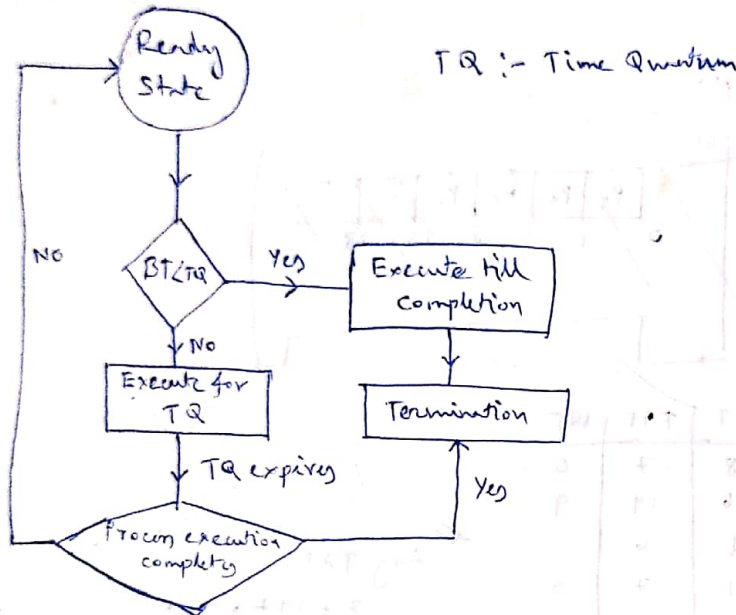
PNo	AT	BT	CT	TAT	WT
1	2	20	22	20	0
2	0	1	1	1	0
3	0	1	2	1	0

P <sub>2</sub>	P <sub>3</sub>	P <sub>1</sub>	
0	1	2	22

$$\text{Throughput} = \frac{3}{22}$$

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Round Robin Algorithm



- Practically implementable, because not dependent on burst time.
- It only has required a queue data structure.
- No starvation.

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SJF with prediction of BT

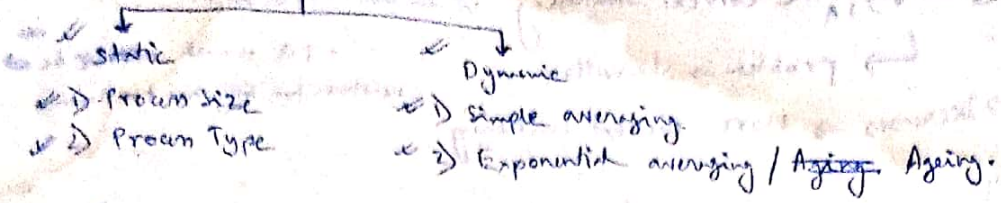
SJF

- |   |   |
|---|---|
| <p><u>Advantages</u></p> <ul style="list-style-type: none"> <li>Maximum throughput</li> <li>Minimum Avg WT and TAT</li> </ul> | <p><u>Disadvantages</u></p> <ul style="list-style-type: none"> <li>Starvation to longer jobs</li> <li>It is not implementable because BT of processes cannot be known ahead.</li> </ul> |
|---|---|

Solution :-

SJF with predicted BT.

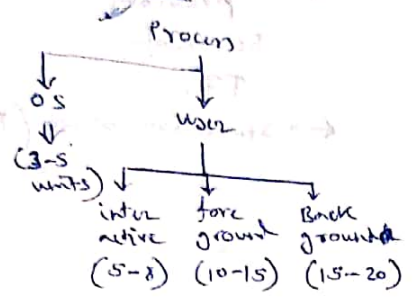
# Prediction techniques



## Process Size (Bytes)

$P_{old} = 200 \text{ KB} \Rightarrow 20 \text{ units}$   
 $\therefore P_{new} = 201 \text{ KB} \Rightarrow 20 \text{ units}$

## Process Type



## Exercise -

$\alpha = 0.5, \gamma_1 = 10$   
 actual BT  $(t_1, t_2, t_3, t_4)$   
 then  $t_5 = ?$   
 $(4, 8, 6, 7)$

$$\gamma_2 = \alpha t_1 + (1-\alpha)\gamma_1 = 0.5(4) + 0.5(10) = 7$$

$$\gamma_3 = \alpha t_2 + (1-\alpha)\gamma_2 = 0.5(8) + 0.5(7) = 7.5$$

$$\gamma_4 = \alpha t_3 + (1-\alpha)\gamma_3 = 0.5(6) + 0.5(7.5) = 6.75$$

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## Simple average

Given  $n$  processes  $(P_1, \dots, P_n)$   
 Let  $t_i$  be the actual BT  
 Let  $\gamma_i$  denote the predicted BT  

$$\gamma_{n+1} = \frac{1}{n} \sum_{i=1}^n t_i$$

## Exponential averaging / Aging

previous  $n$  processes

$$\gamma_{n+1} = \alpha t_n + (1-\alpha)\gamma_n$$

smoothing factor

$0 \leq \alpha \leq 1$

$$\gamma_n = \alpha t_{n-1} + (1-\alpha)\gamma_{n-1}$$

into i)

$$\gamma_{n+1} = \alpha t_n + (1-\alpha)\alpha t_{n-1} + (1-\alpha)^2 \gamma_{n-1}$$

... keep expanding

$$\gamma_5 = \alpha t_4 + (1-\alpha)\gamma_4 = 0.5(7) + 0.5(6.75) = 6.875$$

$$\gamma_n = \alpha t_n + (1-\alpha)\alpha t_{n-1} + (1-\alpha)^2 \alpha t_{n-2} + (1-\alpha)^3 \gamma_{n-2}$$

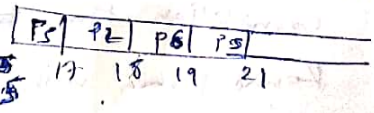
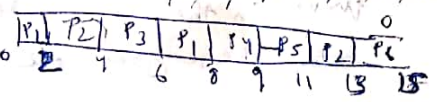
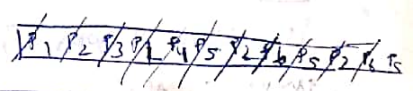
## Round Robin

TQ = 2

- TQ + AT
- preemptive

PNO	AT	BT	CT	TAT	WT
1	0	✓	8	8	4
2	1	✓	18	17	12
3	2	✓	6	4	2
4	3	✓	21	6	5
5	4	✓	19	17	4
6	6	✓	10	13	10

Avg TAT =  
 Avg WT =





- Then
- If  $TQ$  increases, the context switching ~~will be~~ decreased.
  - problem  $\rightarrow$  starvation
  - Decreases  $\rightarrow$  More context switching
  - $TQ$  should ~~not~~ be ~~neither~~ too big nor too small.

$TQ = 4$

PNO	AT	BT	CT	TAT	WT
1	0	4	4	4	0
2	1	3	19	18	13
3	2	2	10	8	4
4	3	1	11	17	9
5	4	0	21	13	10
6	5	0	18		

Context switching is less than previous because of  $TQ$ .

$\leftarrow$  Starvation occurs ( $P_6$ )

$P_1$	$P_2$	$P_3$	$P_4$	$P_5$	$P_6$	$P_2$	$P_5$
0	4	8	10	11	15	18	21

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Round Robin example:-  $TQ = 3$

PNO	AT	BT	CT	TAT	WT	RT
1	5	5	32	27	22	10
2	4	3	27	23	17	5
3	3	2	33	30	23	3
4	1	1	30	29	20	9
5	2	0	6	4	2	2
6	6	0	21	15	12	12

First occurrence - AT

$P_4$	$P_5$	$P_3$	$P_2$	$P_4$	$P_1$	$P_6$	$P_3$	$P_2$	$P_4$	$P_1$	$P_3$		
0	1	4	6	9	12	15	16	21	24	27	30	32	33

$TQ$   $\uparrow$   $CS$   $\downarrow$   $RT$  (Better  $CS$ )

$TQ$   $\downarrow$   $CS$   $\uparrow$   $RT$  (Better  $RT$ )

First add processes from list by checking the arrival time, then add the current process if its execution is not over (queue insertion).

If  $TQ = \infty$ , then  $RR \rightarrow FCFs$

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Consider 4 jobs  $P_1, P_2, P_3$  and  $P_4$  arriving in ready queue in the same order at time = 0. If BT requirements of these jobs are 4, 1, 8, 1 respectively, what is completion time of  $P_1$ , assuming Round Robin with  $TQ = 1$ .



P<sub>1</sub> 8 8 8 8 0

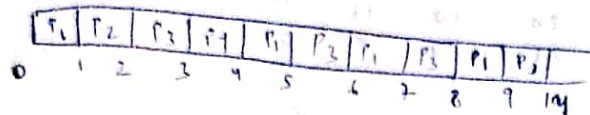
P<sub>2</sub> 1 0

P<sub>3</sub> 8 8 5

P<sub>4</sub> 4 0

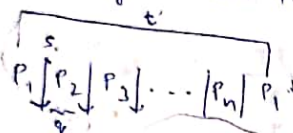
CT of P<sub>1</sub> = 9

P<sub>1</sub> P<sub>2</sub> P<sub>3</sub> P<sub>4</sub> P<sub>1</sub> P<sub>3</sub> P<sub>1</sub> P<sub>3</sub> P<sub>1</sub> P<sub>3</sub>



✓ 18

Consider 'n' processes sharing the CPU in RR fashion. If the context switch time is 's' units. What must be the time <sup>quantum</sup> 'q' such that the no. of context switches are reduced, but at the same time each process is guaranteed to get the turn of the CPU for every 't' seconds.



Let  $P_1, P_2, P_3, P_4, P_1$

4 context switches for 4 processes

$$n(s) + (n-1)q \leq t$$

$$q \leq \frac{t - ns}{(n-1)}$$

✓ 19

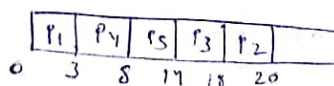
✓ Longest Job First Algorithm

Process having longest BT gets scheduled first.

Criteria :- BT

Mode :- non-preemptive

PNO	AT	BT	CT	TAT	WT	RT
1	0	3	3	3	0	0
2	1	2	20	19	17	17
3	2	4	18	16	12	12
4	3	5	8	9	0	0
5	4	6	14	10	4	4



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### Longest Remaining Time First

TR = 1

PNo	AT	BT	CT	TAT	WT	RT
1	1	2 1 0	18	17	15	0
2	2	4 3 2 1 0	19	17	13	0
3	3	6 5 4 3 2 1 0	20	17	11	0
4	4	8 7 6 5 4 3 2 1 0	21	17	9	0

	P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>	P <sub>4</sub>	P <sub>4</sub>	P <sub>2</sub>	P <sub>4</sub>	P <sub>3</sub>	P <sub>4</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>1</sub>	P <sub>1</sub>	P <sub>2</sub>	P <sub>3</sub>	P <sub>4</sub>	
0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19	20	21

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Gate 2006:-

avg TAT using LRTF?

PNo	AT	BT	CT	TAT	WT	RT
1	0	2 1 0	12	12	10	8
2	0	4 3 2 1 0	13	13	9	4
3	0	8 7 6 5 4 3 2 1 0	14	14	6	0

Avg TAT

$$= \frac{12+13+14}{3}$$

	P3	P2	P3	P2	P3	P1	P2	P3	P1	P2	P3
0	4	5	6	7	8	9	10	11	12	13	14

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### Highest Response Ratio Next (HRRN)

Criteria :- Response ratio (RR) =  $\frac{W+S}{S}$

W : waiting time for a process so far

S : service time of a process or BT.

→ HRRN not only favors shorter jobs but also limits the waiting time of longer jobs.

→ mode :- non-preemptive

PNo	AT	BT
0	0	3
1	2	6
2	4	4
3	6	5
4	8	2

MA SRR

	P0	P1	P4	P2	P3
0	3	9	11	15	20

HRRN

	P0	P1	P2	P4	P3
0	3	9	13	15	20



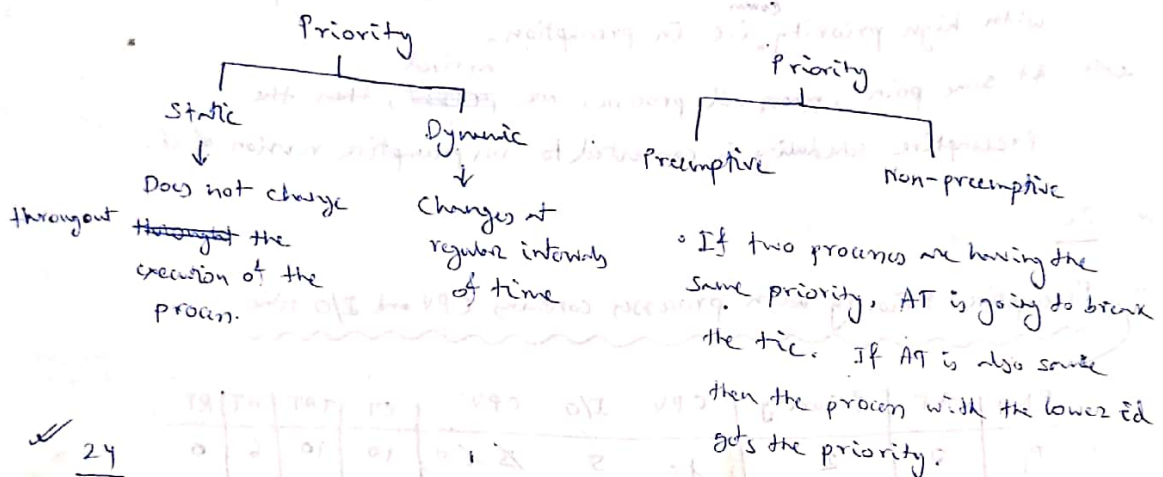
$$\begin{aligned}
 RP_2 &= \frac{(4-1)+4}{4} = \frac{5+4}{4} = \frac{9}{4} = 2.25 \\
 RP_3 &= \frac{(7-6)+5}{5} = \frac{3+5}{5} = \frac{8}{5} = 1.6 \\
 RP_4 &= \frac{(9-8)+2}{2} = \frac{1+2}{2} = \frac{3}{2} = 1.5 \\
 RP_3 &= \frac{(13-6)+5}{5} = \frac{12}{5} = 2.4 \\
 RP_4 &= \frac{(13-8)+2}{2} = \frac{7}{2} = 3.5
 \end{aligned}$$

HRRN			
CT	TAT	WT	RT
3	3	0	0
7	7	1	1
13	9	5	5
20	14	9	9
15	7	5	5

- Disadvantage → Cannot be implemented practically because BT is not known.
- Round Robin is most favourable
- HRRN is better than SJF, theoretically.

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### Priority Scheduling



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### Priority Scheduling (non-preemptive)

PNO	Priority	AT	BT	CT	TAT	WT	RT
1	4	0	4	4	4	0	0
2	4	1	2	25	24	22	22
3	6	2	3	23	21	18	18
4	10	3	5	1	6	1	1
5	8	4	1	20	16	15	15
6	12 (H)	5	4	13	8	4	4
7	9	6	6	11	13	7	7

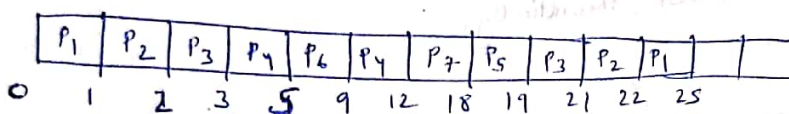
P <sub>1</sub>	P <sub>4</sub>	P <sub>6</sub>	P <sub>7</sub>	P <sub>5</sub>	P <sub>3</sub>	P <sub>2</sub>	
0	4	9	13	19	20	23	25

✓ 25

### Priority Scheduling (Preemptive)

Throughput =  $\frac{7}{25} = \frac{(\text{No of processes})}{(\text{Total scheduling time})}$

PNo	Priority	AT	BT	CT	TAT	WT	PT
1	2	0	4	25	25	21	0
2	4	1	2	22	21	19	0
3	6	2	3	21	19	16	0
4	10	3	5	12	9	4	0
5	8	4	1	19	15	14	14
6	12	5	4	9	4	0	0
7	9	6	6	18	12	6	6

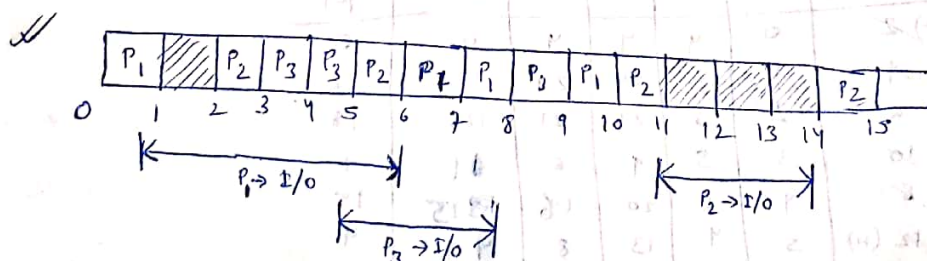


- ✓ A process can run until ~~another~~ <sup>comes</sup> the AT of another process with high priority, i.e. in preemption.
- ✓ At some point, when all processes are ~~present~~ <sup>arrived</sup>, then the preemptive scheduling is converted to non-preemptive version of it.

✓ 26

### Preemptive Priority with processes containing CPU and I/O time

PNo	AT	Priority	CPU	I/O	CPU	CT	TAT	WT	RT
P <sub>1</sub>	0	2	10	5	10	10	10	6	0
P <sub>2</sub>	2	3 (L)	1	3	1	15	13	9	0
P <sub>3</sub>	3	1 (H)	20	3	10	9	6	3	0



Inefficiency =  $\frac{4}{15} \times 100 = 26.67\%$

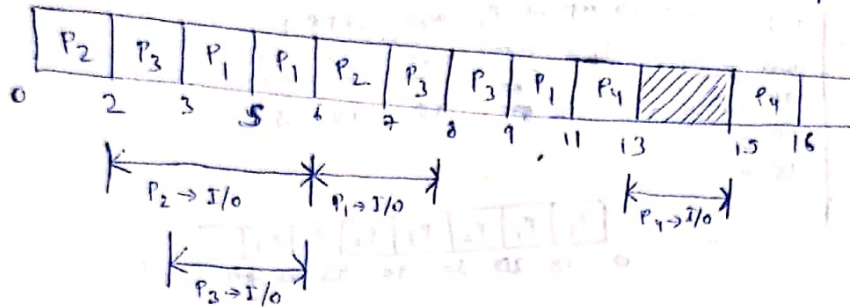
Efficiency =  $\frac{11}{15} \times 100 = 73.33\%$



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SPRTF with processes containing CPU and I/O time example 1

PNO	AT	BT	IOBT	RT	CT	TAT	WT	RT	Actual
1	0	(3) 10	2	10	11	11	6	3	BT 10, CT 11, WT 6, RT 3
2	0	(2) 0	4	0	7	7	4	0	3
3	2	(1) 0	3	0	7	7	4	0	2
4	5	(2) 0	2	0	16	11	8	6	1, 2

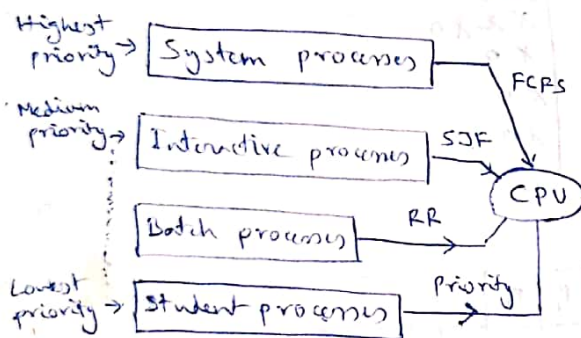


ignore this in computation and add 1st and 2nd BT.

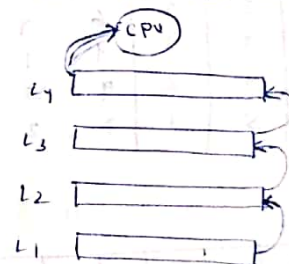
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Multilevel queues and Multilevel feedback queues

Multilevel queue scheduling



ML Feedback scheduling



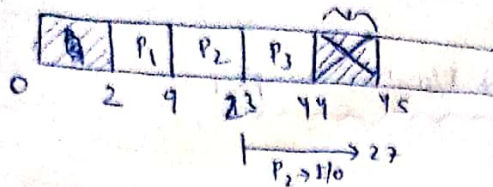
Avoid starvation completely by the concept of aging.

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example 2 (27) - SPRTF

- Three processes arriving at time zero with total execution time of 10, 20, and 30 units respectively. Each process spends the first 20% of execution time doing I/O, 70% time doing computation and last 10% time doing again I/O. Compute the % of idle time for SPRTF.

	AT	BT	10	CPU	50
P <sub>1</sub>	0	10	2	7	1
P <sub>2</sub>	0	20	4	14	2
P <sub>3</sub>	0	30	6	21	3



Inefficiency  $\rightarrow \frac{2}{44} \times 100 = 4.54$

Efficiency  $\rightarrow \frac{42}{44} \times 100 = 95.46$

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SRTP example - (Ans 2007)

PNO	AT	BT	CT	TAT	WT	RT
1	0	20	80			
2	15	25	15	55	40	15
3	20	10	0			
4	45	15	0			

P1	P1	P2	P3	P2	P2	P4
0	15	20	30	40	45	55

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SRTP

Note: ~~Preemptive~~

If TQ is not given, take it by default as default

PNO	AT	BT	CT	TAT	WT	RT
1	0	7	19	19	12	0
2	1	5	13	12	7	0
3	2	3	6	4	1	0
4	3	1	4	1	0	0
5	4	2	9	5	3	3
6	5	1	7	2	1	1

all processes are arrived.

P1	P2	P3	P4	P3	P3	P6	P5	P2	P1
0	1	2	3	4	5	6	7	9	13

~~P1, P2, P3, P4, P5, P6~~

If at any moment, BT of two processes are same, then choose the one with lower AT.

preemptive  $\rightarrow$  non-preemptive after all processes are arrived.

Cannot be implemented practically because of dependency on burst time.



SRTF example - GATE 2011

PNo	AT	BT
1	0	9
2	1	8
3	2	7

Avg WT using SRTF

CT	TAT	WT
13	13	4
5	4	0
22	20	11

$$\text{Avg WT} = \frac{4+0+11}{3}$$

$$= \frac{15}{3} = 5$$

P <sub>1</sub>	P <sub>2</sub>	P <sub>2</sub>	P <sub>1</sub>	P <sub>3</sub>
0	1	2	5	13
				22

Important short notes

1) Next CPU burst is predicted is given by:-

$$T_n = \alpha \times t_n + (1-\alpha) \times T_{n-1}; \quad 0 \leq \alpha \leq 1$$

$t_n$  is current CPU time,

$T_{n-1}$  is the past predicted value, and

$T_n$  is the new predicted value.

2) For  $n$  fork() calls,  $2^{n-1}$  child processes will be created.

3) Round Robin Algorithm:

•  $n$  processes in ready queue,  $q$  is time quantum, then each process gets  $1/n$  of the CPU time in chunks of at most  $q$  time units.

• Each process must wait no longer than  $(n-1)q$  time units until next time quantum.

• TAT also depends on the size of the time quantum.

4) If waiting time or fraction of each process is  $p$  and  $n$  is the no. of processes, then

• CPU utilization =  $1 - p^n$

• And probability that  $N$  processes will wait at the same time =  $p^N$

5) Unix Inode:

• Suppose there are 12 direct blocks and 1 indirect block and 1 double indirect block and 1 triple indirect block then the maximum size of process supported by inode is:

$$= \left[ 12 + \frac{BS}{ES} + \left( \frac{BS}{ES} \right)^2 + \left( \frac{BS}{ES} \right)^3 \right] \times BS; \text{ where}$$

$BS$  = Block size;  $ES$  = entry size (or block pointer size).