

SourceBots

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THE SMALLPEICE TRUST

SHIP IT!: RULES

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COMPUTING, ELECTRONICS, AND ROBOTICS

1 Game Rules

- 1. The game, called *¡Ship It!*, is played in the arena defined in Specification 1. The objective is to collect containers and deposit them in scoring zones.
- 2. The game is played by two teams, each team has two robots: a crane and a forklift.
- 3. The forklift is used to pick up loose containers and move them to the docking area. Each team's forklift starts in their starting area.
- 4. The arena contains 18 containers. The containers are labeled with their owners: each team has 9 containers. One container from each team is placed within the docking area, the others are outside the docking area.
- 5. The crane is used to pick up a container from the docking area and deposit it in a team's raised area.
- 6. At the end of the game, teams will be awarded points based on the number of containers they collected, as follows:
 - (a) For each container in the docking area, the team which owns the container will be awarded *1 point*.
 - (b) For each container in the raised area, the team which owns the container will be awarded *3 points*.
- 7. Containers are "in" a zone when their centre is within the zone.
- 8. Teams may be disqualified from one or all matches by match officials, for non-compliance with regulations, or any other reason at the discretion of the judge.

2 Regulations

- 1. The Judge's decision is final.
- Any assistance from Smallpeice Trust staff and volunteers is provided without guarantees.
- 3. Competitors are expected to behave within the spirit of good sporting conduct.
- 4. All robots must be fully autonomous once started. No remote control systems are permitted.
- 5. While accidental bumps and scrapes are inevitable, this is a non-contact sport.

3 Specifications

3.1 Arena

- 1. The arena floor is a $6000 \, \text{mm} \times 12000 \, \text{mm}$ rectangle.
- 2. The layout of the arena is given in Figure 1. This figure is to scale.

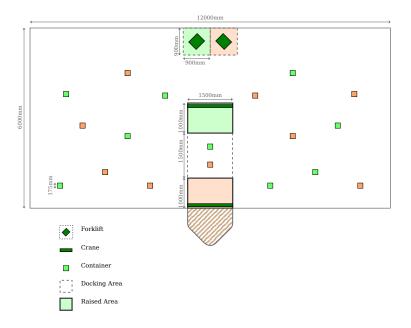


Figure 1: Layout zones and tokens in the arena.

- 3. The docking area is $1500 \, \text{mm} \times 1500 \, \text{mm}$.
- 4. The raised areas are each $1500 \, \text{mm} \times 1000 \, \text{mm}$, and raised from the floor by $500 \, \text{mm}$.
- 5. The starting zones are centrally aligned, share one side with the north wall of the arena, and are $900 \, \text{mm} \times 900 \, \text{mm}$.
- 6. The canonical definition of the arena is what is in the simulator.
- 7. Beacons positioned around the arena can be used for localization.

3.2 Containers

- 1. Containers are cuboids with side length 260 mm.
- 2. Containers are arranged as indicated in Figure 1.

3.3 Forklift

- 1. The forklift's footprint is a square with sides of length 350 mm.
- 2. TODO: Fetch the forklift dimensions from the simulator.
- 3. The forklift is equipped with the following sensors:
 - (a) Magnetic compass.
 - (b) Gyroscope.
 - (c) Radio direction finder.
 - (d) Bump sensor.

- (e) Ultrasonic distance sensor.
- 4. The forklift is equipped with the following actuators:
 - (a) Tank-steered driving wheels.
 - (b) Front grabber.

3.4 Crane

- 1. The crane is the full width of the ship, and 100 mm in both other dimensions.
- 2. The crane is equipped with the following sensors:
 - (a) Radio direction finder.
 - (b) Bump sensor.
 - (c) Ultrasonic distance sensor (mounted vertically).
- 3. The crane is equipped with the following actuators:
 - (a) Two-axis linear driving motor.
 - (b) Lifter.