FreeMat v4.0 Documentation

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Chapter 1

Introduction and Getting Started

1.1 INSTALL Installing FreeMat

1.1.1 General Instructions

Here are the general instructions for installing FreeMat. First, follow the instructions listed below for the platform of interest. Then, run the

-->pathtool

which brings up the path setup tool. More documentation on the GUI elements (and how to use them) will be forthcoming.

1.1.2 Linux

For Linux, FreeMat is now provided as a binary installation. To install it simply download the binary using your web browser, and then unpack it

tar xvfz FreeMat-<VERSION_NUMBER>-Linux-Binary.tar.gz

You can then run FreeMat directly without any additional effort

FreeMat-<VERSION_NUMBER>-Linux-Binary/Contents/bin/FreeMat

will start up FreeMat as an X application. If you want to run it as a command line application (to run from within an xterm), use the nogui flag

FreeMat-<VERSION_NUMBER>-Linux-Binary/Contents/bin/FreeMat -nogui

If you do not want FreeMat to use X at all (no graphics at all), use the noX flag

FreeMat-<VERSION_NUMBER>-Linux-Binary/Contents/bin/FreeMat -noX

For convenience, you may want to add FreeMat to your path. The exact mechanism for doing this depends on your shell. Assume that you have unpacked FreeMat-<VERSION_NUMBER>-Linux-Binary.tar.gz into the directory /home/myname. Then if you use csh or its derivatives (like tcsh) you should add the following line to your .cshrc file:

set path=(\$path /home/myname/FreeMat-<VERSION_NUMBER>-Linux/Binary/Contents/bin)

If you use bash, then add the following line to your .bash_profile

PATH=\$PATH:/home/myname/FreeMat-<VERSION_NUMBER>-Linux/Binary/Contents/bin

If the prebuilt binary package does not work for your Linux distribution, you will need to build FreeMat from source (see the source section below). When you have FreeMat running, you can setup your path using the pathtool. Note that the FREEMAT_PATH is no longer used by FreeMat. You must use the pathtool to adjust the path.

1.1.3 Windows

For Windows, FreeMat is installed via a binary installer program. To use it, simply download the setup program FreeMat-<VERSION_NUMBER>-Setup.exe, and double click it. Follow the instructions to do the installation, then setup your path using pathtool.

1.1.4 Mac OS X

For Mac OS X, FreeMat is distributed as an application bundle. To install it, simply download the compressed disk image file FreeMat-<VERSION_NUMBER>.dmg, double click to mount the disk image, and then copy the application FreeMat-<VERSION_NUMBER> to some convenient place. To run FreeMat, simply double click on the application. Run pathtool to setup your FreeMat path.

1.1.5 Source Code

The source code build is a little more complicated than previous versions of FreeMat. Here are the current build instructions for all platforms.

- 1. Build and install Qt 4.3 or later http://trolltech.com/developer/downloads/opensource
- 2. Install g77 or gfortran (use fink for Mac OS X, use gcc-g77 package for MinGW)
- 3. Download the source code FreeMat-<VERSION_NUMBER>-src.tar.gz.
- 4. Unpack the source code: tar xvfz FreeMat-<VERSION_NUMBER>-src.tar.gz.
- 5. For Windows, you will need to install MSYS as well as MINGW to build FreeMat. You will also need unzip to unpack the enclosed matio.zip archive. Alternately, you can cross-build the WIndows version of FreeMat under Linux (this is how I build it now).
- 6. If you are extraordinarily lucky (or prepared), you can issue the usual ./configure, then the make and make install. This is not likely to work because of the somewhat esoteric dependencies of FreeMat. The configure step will probably fail and indicate what external dependencies are still needed.
- 7. I assume that you are familiar with the process of installing dependencies if you are trying to build FreeMat from source.

To build a binary distributable (app bundle on the Mac, setup installer on win32, and a binary distribution on Linux), you will need to run make package instead of make install.

Chapter 2

Variables and Arrays

2.1 CELL Cell Array Definitions

2.1.1 Usage

The cell array is a fairly powerful array type that is available in FreeMat. Generally speaking, a cell array is a heterogenous array type, meaning that different elements in the array can contain variables of different type (including other cell arrays). For those of you familiar with C, it is the equivalent to the void * array. The general syntax for their construction is

```
A = {row_def1;row_def2;...;row_defN}
```

where each row consists of one or more elements, separated by commas

```
row_defi = element_i1,element_i2,...,element_iM
```

Each element can be any type of FreeMat variable, including matrices, arrays, cell-arrays, structures, strings, etc. The restriction on the definition is that each row must have the same number of elements in it.

2.1.2 Examples

Here is an example of a cell-array that contains a number, a string, and an array

A =

Note that in the output, the number and string are explicitly printed, but the array is summarized. We can create a 2-dimensional cell-array by adding another row definition

$$-->$$
 B = {pi,i;e,-1}

B =

```
[3.14159] [0+1i] [2.71828] [-1]
```

Finally, we create a new cell array by placing A and B together

```
--> C = {A,B}
C =
[1 3 cell array] [2 2 cell array]
```

2.2 Function Handles

2.2.1 Usage

Starting with version 1.11, FreeMat now supports function handles, or function pointers. A function handle is an alias for a function or script that is stored in a variable. First, the way to assign a function handle is to use the notation

```
handle = @func
```

where func is the name to point to. The function func must exist at the time we make the call. It can be a local function (i.e., a subfunction). To use the handle, we can either pass it to feval via

```
[x,y] = feval(handle,arg1,arg2).
```

Alternately, you can the function directly using the notation

```
[x,y] = handle(arg1,arg2)
```

2.3 GLOBAL Global Variables

2.3.1 Usage

Global variables are shared variables that can be seen and modified from any function or script that declares them. The syntax for the global statement is

```
global variable_1 variable_2 ...
```

The global statement must occur before the variables appear.

2.3.2 Example

Here is an example of two functions that use a global variable to communicate an array between them. The first function sets the global variable.

```
set_global.m
function set_global(x)
  global common_array
  common_array = x;
```

The second function retrieves the value from the global variable

```
get_global.m
function x = get_global
  global common_array
  x = common_array;
Here we exercise the two functions
--> set_global('Hello')
--> get_global
ans =
Hello
```

2.4 INDEXING Indexing Expressions

2.4.1 Usage

There are three classes of indexing expressions available in FreeMat: (), {}, and . Each is explained below in some detail, and with its own example section.

2.4.2 Array Indexing

We start with array indexing (), which is the most general indexing expression, and can be used on any array. There are two general forms for the indexing expression - the N-dimensional form, for which the general syntax is

```
variable(index_1,index_2,...,index_n)
and the vector form, for which the general syntax is
```

```
variable(index)
```

Here each index expression is either a scalar, a range of integer values, or the special token:, which is shorthand for 1:end. The keyword end, when included in an indexing expression, is assigned the length of the array in that dimension. The concept is easier to demonstrate than explain. Consider the following examples:

```
--> A = zeros(4)

A =

0 0 0 0

0 0 0 0

0 0 0 0

0 0 0 0

--> B = float(randn(2))
```

Here the array indexing was used on the left hand side only. It can also be used for right hand side indexing, as in

Note that we used the end keyword to avoid having to know that A has 4 columns. Of course, we could also use the : token instead:

An extremely useful example of : with array indexing is for slicing. Suppose we have a 3-D array, that is $2 \times 2 \times 3$, and we want to set the middle slice:

```
--> D = zeros(2,2,3)

D =

(:,:,1) =
0 0
0 0

(:,:,2) =
0 0
0 0

(:,:,3) =
0 0
```

```
0 0
--> D(:,:,2) = int32(10*rand(2,2))
D =
(:,:,1) =
0 0
0 0
(:,:,2) =
5 4
2 6
(:,:,3) =
0 0
0 0
```

In another level of nuance, the assignment expression will automatically fill in the indexed rectangle on the left using data from the right hand side, as long as the lengths match. So we can take a vector and roll it into a matrix using this approach:

```
--> A = zeros(4)
A =
0 0 0 0
0 0 0 0
0 0 0 0
0 0 0 0
--> v = [1;2;3;4]
v =
1
 2
 3
--> A(2:3,2:3) = v
A =
0 0 0 0
0 1 3 0
0 2 4 0
0 0 0 0
```

The N-dimensional form of the variable index is limited to accessing only (hyper-) rectangular regions of the array. You cannot, for example, use it to access only the diagonal elements of the

array. To do that, you use the second form of the array access (or a loop). The vector form treats an arbitrary N-dimensional array as though it were a column vector. You can then access arbitrary subsets of the arrays elements (for example, through a find expression) efficiently. Note that in vector form, the end keyword takes the meaning of the total length of the array (defined as the product of its dimensions), as opposed to the size along the first dimension.

2.4.3 Cell Indexing

The second form of indexing operates, to a large extent, in the same manner as the array indexing, but it is by no means interchangable. As the name implies, cell-indexing applies only to cell arrays. For those familiar with C, cell-indexing is equivalent to pointer derefencing in C. First, the syntax:

```
variable{index_1,index_2,...,index_n}
```

and the vector form, for which the general syntax is

```
variable{index}
```

The rules and interpretation for N-dimensional and vector indexing are identical to (), so we will describe only the differences. In simple terms, applying () to a cell-array returns another cell array that is a subset of the original array. On the other hand, applying {} to a cell-array returns the contents of that cell array. A simple example makes the difference quite clear:

```
--> A = {1, 'hello', [1:4]}

A =
    [1] [hello] [1 4 double array]

--> A(1:2)

ans =
    [1] [hello]

--> A{1:2}

ans =

1 of 2:
    1

2 of 2:
hello
```

You may be surprised by the response to the last line. The output is multiple assignments to ans!. The output of a cell-array dereference can be used anywhere a list of expressions is required. This includes arguments and returns for function calls, matrix construction, etc. Here is an example of using cell-arrays to pass parameters to a function:

```
--> A = {[1,3,0],[5,2,7]}

A =
    [1 3 double array] [1 3 double array]

--> max(A{1:end})

ans =
    5 3 7

And here, cell-arrays are used to capture the return.

--> [K{1:2}] = max(randn(1,4))

K =
    [1.06943] [4]

Here, cell-arrays are used in the matrix construction process:

--> C = [A{1};A{2}]

C =
    1 3 0
    5 2 7
```

Note that this form of indexing is used to implement variable length arguments to function. See varargin and varargout for more details.

2.4.4 Structure Indexing

The third form of indexing is structure indexing. It can only be applied to structure arrays, and has the general syntax

```
variable.fieldname
```

where fieldname is one of the fields on the structure. Note that in FreeMat, fields are allocated dynamically, so if you reference a field that does not exist in an assignment, it is created automatically for you. If variable is an array, then the result of the . reference is an expression list, exactly like the {} operator. Hence, we can use structure indexing in a simple fashion:

Or in more complicated ways using expression lists for function arguments

```
--> clear A
--> A(1).maxargs = [1,6,7,3]
    maxargs: 1 4 double array
--> A(2).maxargs = [5,2,9,0]
A =
Fields
    maxargs
--> max(A.maxargs)
ans =
5 6 9 3
or to store function outputs
--> clear A
--> A(1).maxreturn = [];
--> A(2).maxreturn = [];
--> [A.maxreturn] = max(randn(1,4))
A =
Fields
    maxreturn
```

FreeMat now also supports the so called dynamic-field indexing expressions. In this mode, the fieldname is supplied through an expression instead of being explicitly provided. For example, suppose we have a set of structure indexed by color,

```
--> x.red = 430;

--> x.green = 240;

--> x.blue = 53;

--> x.yello = 105

x =

red: 430

green: 240

blue: 53

yello: 105

Then we can index into the second
```

Then we can index into the structure x using a dynamic field reference:

```
--> y = 'green'
y =
green
--> a = x.(y)
```

```
a =
 240
```

Note that the indexing expression has to resolve to a string for dynamic field indexing to work.

2.4.5Complex Indexing

The indexing expressions described above can be freely combined to affect complicated indexing expressions. Here is an example that exercises all three indexing expressions in one assignment.

```
--> Z{3}.foo(2) = pi
Z =
 [0] [0] [1 1 struct array]
```

From this statement, FreeMat infers that Z is a cell-array of length 3, that the third element is a structure array (with one element), and that this structure array contains a field named 'foo' with two double elements, the second of which is assigned a value of pi.

2.5 MATRIX Matrix Definitions

2.5.1Usage

The matrix is the basic datatype of FreeMat. Matrices can be defined using the following syntax

```
A = [row_def1;row_def2;...,row_defN]
```

where each row consists of one or more elements, separated by commas

```
row_defi = element_i1,element_i2,...,element_iM
```

Each element can either be a scalar value or another matrix, provided that the resulting matrix definition makes sense. In general this means that all of the elements belonging to a row have the same number of rows themselves, and that all of the row definitions have the same number of columns. Matrices are actually special cases of N-dimensional arrays where N<=2. Higher dimensional arrays cannot be constructed using the bracket notation described above. The type of a matrix defined in this way (using the bracket notation) is determined by examining the types of the elements. The resulting type is chosen so no information is lost on any of the elements (or equivalently, by choosing the highest order type from those present in the elements).

2.5.2Examples

Here is an example of a matrix of int32 elements (note that untyped integer constants default to type int32).

```
--> A = [1,2;5,8]
```

A = 1 2

5 8

Now we define a new matrix by adding a column to the right of A, and using float constants.

```
--> B = [A,[3.2f;5.1f]]

B =

1.0000    2.0000    3.2000
5.0000    8.0000    5.1000
```

Next, we add extend B by adding a row at the bottom. Note how the use of an untyped floating point constant forces the result to be of type double

```
--> C = [B;5.2,1.0,0.0]

C =

1.0000    2.0000    3.2000
5.0000    8.0000    5.1000
5.2000    1.0000    0
```

If we instead add a row of complex values (recall that i is a complex constant, not a dcomplex constant)

```
--> D = [B;2.0f+3.0f*i,i,0.0f]

D =

1.0000 + 0.0000i  2.0000 + 0.0000i  3.2000 + 0.0000i
5.0000 + 0.0000i  8.0000 + 0.0000i  5.1000 + 0.0000i
2.0000 + 3.0000i  0.0000 + 1.0000i  0
```

Likewise, but using dcomplex constants

```
--> E = [B;2.0+3.0*i,i,0.0]
   1.0000 +
                       2.0000 + 0.0000i
             0.0000i
                                           3.2000 + 0.0000i
   5.0000 +
             0.0000i
                       8.0000 +
                                 0.0000i
                                           5.1000 +
                                                      0.0000i
   2.0000 +
             3.0000i
                       0.0000 +
                                 1.0000i
                                                 0
```

Finally, in FreeMat, you can construct matrices with strings as contents, but you have to make sure that if the matrix has more than one row, that all the strings have the same length.

```
--> F = ['hello';'there']
F =
hello
there
```

2.6 PERSISTENT Persistent Variables

2.6.1 Usage

Persistent variables are variables whose value persists between calls to a function or script. The general syntax for its use is

```
persistent variable1 variable2 ... variableN
```

The persistent statement must occur before the variable is the tagged as persistent. Per the MATLAB API documentation an empty variable is created when the persistent statement is called.

2.6.2 Example

count_calls.m

Here is an example of a function that counts how many times it has been called.

```
function count_calls
  persistent ccount
  if (~exist('ccount')) ccount = 0; end;
  ccount = ccount + 1;
  printf('Function has been called %d times\n',ccount);
We now call the function several times:
--> for i=1:10; count_calls; end
Function has been called 0 times
```

2.7 STRUCT Structure Array Constructor

2.7.1 Usage

Creates an array of structures from a set of field, value pairs. The syntax is

```
y = struct(n_1, v_1, n_2, v_2, ...)
```

where n_i are the names of the fields in the structure array, and v_i are the values. The values v_i must either all be scalars, or be cell-arrays of all the same dimensions. In the latter case, the output structure array will have dimensions dictated by this common size. Scalar entries for the v_i are

replicated to fill out their dimensions. An error is raised if the inputs are not properly matched (i.e., are not pairs of field names and values), or if the size of any two non-scalar values cell-arrays are different.

Another use of the struct function is to convert a class into a structure. This allows you to access the members of the class, directly but removes the class information from the object.

2.7.2 Example

This example creates a 3-element structure array with three fields, foo bar and key, where the contents of foo and bar are provided explicitly as cell arrays of the same size, and the contents of bar are replicated from a scalar.

```
--> y = struct('foo', {1,3,4}, 'bar', {'cheese', 'cola', 'beer'}, 'key', 508)
у =
Fields
    foo
    bar
    key
--> y(1)
ans =
    foo: 1
    bar: cheese
    key: 508
--> y(2)
ans =
    foo: 3
    bar: cola
    key: 508
--> y(3)
ans =
    foo: 4
    bar: beer
    key: 508
```

An alternate way to create a structure array is to initialize the last element of each field of the structure

```
--> Test(2,3).Type = 'Beer';

--> Test(2,3).Ounces = 12;

--> Test(2,3).Container = 'Can';

--> Test(2,3)

ans =
```

Type: Beer
Ounces: 12
Container: Can
--> Test(1,1)

ans =

Type: 0
Ounces: 0
Container: 0

Chapter 3

Functions and Scripts

3.1 ANONYMOUS Anonymous Functions

3.1.1 Usage

Anonymous functions are simple, nameless functions that can be defined anywhere (in a script, function, or at the prompt). They are intended to supplant inline functions. The syntax for an anonymous function is simple:

```
y = @(arg1,arg2,...,argn) expression
```

where arg1,arg2,...,argn is a list of valid identifiers that define the arguments to the function, and expression is the expression to compute in the function. The returned value y is a function handle for the anonymous function that can then be used to evaluate the expression. Note that y will capture the value of variables that are not indicated in the argument list from the current scope or workspace at the time it is defined. So, for example, consider the simple anonymous function definition

$$y = Q(x) a*(x+b)$$

In order for this definition to work, the variables **a** and **b** need to be defined in the current workspace. Whatever value they have is captured in the function handle **y**. To change the values of **a** and **b** in the anonymous function, you must recreate the handle using another call. See the examples section for more information. In order to use the anonymous function, you can use it just like any other function handle. For example,

```
p = y(3)
p = y()
p = feval(y,3)
```

are all examples of using the y anonymous function to perform a calculation.

3.1.2 Examples

Here are some examples of using an anonymous function

```
--> a = 2; b = 4;
                    % define a and b (slope and intercept)
--> y = 0(x) a*x+b
                   % create the anonymous function
               % create the anonymous function
 (x)
       a*x+b
--> y(2)
                     % evaluate it for x = 2
ans =
8
--> a = 5; b = 7;
                  % change a and b
--> y(2)
                    % the value did not change! because a=2,b=4 are captured in y
ans =
8
--> y = 0(x) a*x+b
                   % recreate the function
y =
 0(x)
               % recreate the function
        a*x+b
                     % now the new values are used
--> y(2)
ans =
 17
```

3.2 FUNCTION Function Declarations

3.2.1 Usage

There are several forms for function declarations in FreeMat. The most general syntax for a function declaration is the following:

```
function [out_1,...,out_M,varargout] = fname(in_1,...,in_N,varargin)
```

where out_i are the output parameters, in_i are the input parameters, and varargout and varargin are special keywords used for functions that have variable inputs or outputs. For functions with a fixed number of input or output parameters, the syntax is somewhat simpler:

```
function [out_1,...,out_M] = fname(in_1,...,in_N)
```

Note that functions that have no return arguments can omit the return argument list (of out_i) and the equals sign:

```
function fname(in_1,...,in_N)
```

Likewise, a function with no arguments can eliminate the list of parameters in the declaration:

```
function [out_1,...,out_M] = fname
```

Functions that return only a single value can omit the brackets

```
function out_1 = fname(in_1,...,in_N)
```

In the body of the function in_i are initialized with the values passed when the function is called. Also, the function must assign values for out_i to pass values to the caller. Note that by default, FreeMat passes arguments by value, meaning that if we modify the contents of in_i inside the function, it has no effect on any variables used by the caller. Arguments can be passed by reference by prepending an ampersand & before the name of the input, e.g.

```
function [out1,...,out_M] = fname(in_1,&in_2,in_3,...,in_N)
```

in which case in_2 is passed by reference and not by value. Also, FreeMat works like C in that the caller does not have to supply the full list of arguments. Also, when keywords (see help keywords) are used, an arbitrary subset of the parameters may be unspecified. To assist in deciphering the exact parameters that were passed, FreeMat also defines two variables inside the function context: nargin and nargout, which provide the number of input and output parameters of the caller, respectively. See help for nargin and nargout for more details. In some circumstances, it is necessary to have functions that take a variable number of arguments, or that return a variable number of results. In these cases, the last argument to the parameter list is the special argument varargin. Inside the function, varargin is a cell-array that contains all arguments passed to the function that have not already been accounted for. Similarly, the function can create a cell array named varargout for variable length output lists. See help varargin and varargout for more details.

The function name fname can be any legal FreeMat identifier. Functions are stored in files with the .m extension. Note that the name of the file (and not the function name fname used in the declaration) is how the function appears in FreeMat. So, for example, if the file is named foo.m, but the declaration uses bar for the name of the function, in FreeMat, it will still appear as function foo. Note that this is only true for the first function that appears in a .m file. Additional functions that appear after the first function are known as helper functions or local functions. These are functions that can only be called by other functions in the same .m file. Furthermore the names of these helper functions are determined by their declaration and not by the name of the .m file. An example of using helper functions is included in the examples.

Another important feature of functions, as opposed to, say scripts, is that they have their own scope. That means that variables defined or modified inside a function do not affect the scope of the caller. That means that a function can freely define and use variables without unintentionally using a variable name reserved elsewhere. The flip side of this fact is that functions are harder to debug than scripts without using the keyboard function, because the intermediate calculations used in the function are not available once the function exits.

3.2.2 Examples

Here is an example of a trivial function that adds its first argument to twice its second argument:

```
addtest.m
function c = addtest(a,b)
  c = a + 2*b;
```

```
--> addtest(1,3)
ans =
7
--> addtest(3,0)
ans =
3
```

Suppose, however, we want to replace the value of the first argument by the computed sum. A first attempt at doing so has no effect:

```
addtest2.m
function addtest2(a,b)
    a = a + 2*b;

--> arg1 = 1

arg1 =
    1

--> arg2 = 3

arg2 =
    3

--> addtest2(arg1,arg2)
--> arg1

ans =
    1

--> arg2
ans =
    3
```

The values of arg1 and arg2 are unchanged, because they are passed by value, so that any changes to a and b inside the function do not affect arg1 and arg2. We can change that by passing the first argument by reference:

```
addtest3.m
function addtest3(&a,b)
a = a + 2*b
```

Note that it is now illegal to pass a literal value for a when calling addtest3:

```
--> addtest3(3,4)

a =
11

Error: Must have lvalue in argument passed by reference
--> addtest3(arg1,arg2)

a =
7

--> arg1

ans =
7

--> arg2

ans =
3
```

The first example fails because we cannot pass a literal like the number 3 by reference. However, the second call succeeds, and note that <code>arg1</code> has now changed. Note: please be careful when passing by reference - this feature is not available in MATLAB and you must be clear that you are using it.

As variable argument and return functions are covered elsewhere, as are keywords, we include one final example that demonstrates the use of helper functions, or local functions, where multiple function declarations occur in the same file.

```
euclidlength.m
function y = foo(x,y)
   square_me(x);
   square_me(y);
   y = sqrt(x+y);

function square_me(&t)
   t = t^2;

--> euclidlength(3,4)

ans =
   5

--> euclidlength(2,0)

ans =
   2
```

3.3 KEYWORDS Function Keywords

3.3.1 Usage

A feature of IDL that FreeMat has adopted is a modified form of keywords. The purpose of keywords is to allow you to call a function with the arguments to the function specified in an arbitrary order. To specify the syntax of keywords, suppose there is a function with prototype

```
function [out_1,...,out_M] = foo(in_1,...,in_N)
Then the general syntax for calling function foo using keywords is
foo(val_1, val_2, /in_k=3)
which is exactly equivalent to
foo(val_1, val_2, [], [], ..., [], 3),
where the 3 is passed as the k-th argument, or alternately,
foo(val_1, val_2, /in_k)
which is exactly equivalent to
foo(val_1, val_2, [], [], ..., [], logical(1)),
```

Note that you can even pass reference arguments using keywords.

3.3.2 Example

The most common use of keywords is in controlling options for functions. For example, the following function takes a number of binary options that control its behavior. For example, consider the following function with two arguments and two options. The function has been written to properly use and handle keywords. The result is much cleaner than the MATLAB approach involving testing all possible values of nargin, and forcing explicit empty brackets for don't care parameters.

```
keyfunc.m
function c = keyfunc(a,b,operation,printit)
  if (~isset('a') | ~isset('b'))
    error('keyfunc requires at least the first two 2 arguments');
  end;
  if (~isset('operation'))
    % user did not define the operation, default to '+'
    operation = '+';
  end
  if (~isset('printit'))
    % user did not specify the printit flag, default is false
    printit = 0;
  end
  % simple operation...
```

```
eval(['c = a ' operation ' b;']);
  if (printit)
    printf('%f %s %f = %f\n',a,operation,b,c);
Now some examples of how this function can be called using keywords.
--> keyfunc(1,3)
                                % specify a and b, defaults for the others
ans =
--> keyfunc(1,3,/printit)
                                % specify printit is true
1.000000 + 3.000000 = 4.000000
ans =
4
--> keyfunc(/operation='-',2,3) % assigns a=2, b=3
ans =
-1
--> keyfunc(4,/operation='*',/printit) % error as b is unspecified
In /home/basu/dev/branches/FreeMat4/help/tmp/keyfunc.m(keyfunc) at line 3
    In scratch() at line 1
    In base(base)
    In base()
    In global()
Error: keyfunc requires at least the first two 2 arguments
```

3.4 NARGIN Number of Input Arguments

3.4.1 Usage

The nargin function returns the number of arguments passed to a function when it was called. The general syntax for its use is

```
y = nargin
```

FreeMat allows for fewer arguments to be passed to a function than were declared, and nargin, along with isset can be used to determine exactly what subset of the arguments were defined.

3.4.2 Example

Here is a function that is declared to take five arguments, and that simply prints the value of nargin each time it is called.

```
nargintest.m
function nargintest(a1,a2,a3,a4,a5)
  printf('nargin = %d\n',nargin);

--> nargintest(3);
nargin = 1
--> nargintest(3,'h');
nargin = 2
--> nargintest(3,'h',1.34);
nargin = 3
--> nargintest(3,'h',1.34,pi,e);
nargin = 5
```

3.5 NARGOUT Number of Output Arguments

3.5.1 Usage

The nargout function computes the number of return values requested from a function when it was called. The general syntax for its use

```
y = nargout
```

FreeMat allows for fewer return values to be requested from a function than were declared, and nargout can be used to determine exactly what subset of the functions outputs are required.

3.5.2 Example

Here is a function that is declared to return five values, and that simply prints the value of nargout each time it is called.

```
nargouttest.m
function [a1,a2,a3,a4,a5] = nargouttest
  printf('nargout = %d\n',nargout);
  a1 = 1; a2 = 2; a3 = 3; a4 = 4; a5 = 5;

--> a1 = nargouttest
nargout = 1

a1 =
  1

--> [a1,a2] = nargouttest
nargout = 2
a1 =
  1
```

```
2
--> [a1,a2,a3] = nargouttest
nargout = 3
a1 =
1
a2 =
 2
a3 =
3
--> [a1,a2,a3,a4,a5] = nargouttest
nargout = 5
a1 =
 1
a2 =
 2
a3 =
 3
a4 =
 4
a5 =
5
```

3.6 SCRIPT Script Files

3.6.1 Usage

A script is a sequence of FreeMat commands contained in a .m file. When the script is called (via the name of the file), the effect is the same as if the commands inside the script file were issued one at a time from the keyboard. Unlike function files (which have the same extension, but have a function declaration), script files share the same environment as their callers. Hence, assignments, etc, made inside a script are visible to the caller (which is not the case for functions.

3.6.2 Example

Here is an example of a script that makes some simple assignments and printf statements.

```
tscript.m
a = 13;
```

```
printf('a is %d\n',a);
b = a + 32
If we execute the script and then look at the defined variables
--> tscript
a is 13
b =
 45
--> who
  Variable Name
                                                     Size
                         Туре
                                 Flags
                                                   [1 1]
                     double
                а
                                                   [0 0]
             ans
                     double
                     double
                                                   [1 \ 1]
                b
```

we see that a and b are defined appropriately.

3.7 SPECIAL Special Calling Syntax

3.7.1 Usage

To reduce the effort to call certain functions, FreeMat supports a special calling syntax for functions that take string arguments. In particular, the three following syntaxes are equivalent, with one caveat:

```
functionname('arg1','arg2',...,'argn')
```

or the parenthesis and commas can be removed

```
functionname 'arg1' 'arg2' ... 'argn'
```

The quotes are also optional (providing, of course, that the argument strings have no spaces in them)

```
functionname arg1 arg2 ... argn
```

This special syntax enables you to type hold on instead of the more cumbersome hold('on'). The caveat is that FreeMat currently only recognizes the special calling syntax as the first statement on a line of input. Thus, the following construction

```
for i=1:10; plot(vec(i)); hold on; end
```

would not work. This limitation may be removed in a future version.

3.7.2 Example

Here is a function that takes two string arguments and returns the concatenation of them.

```
strcattest.m
function strcattest(str1,str2)
   str3 = [str1,str2];
   printf('str1 = %s, str2 = %s, str3 = %s\n',str1,str2,str3);
We call strcattest using all three syntaxes.
--> strcattest('hi','ho')
str1 = hi, str2 = ho, str3 = hiho
--> strcattest 'hi' 'ho'
str1 = hi, str2 = ho, str3 = hiho
--> strcattest hi ho
str1 = hi, str2 = ho, str3 = hiho
```

3.8 VARARGIN Variable Input Arguments

3.8.1 Usage

FreeMat functions can take a variable number of input arguments by setting the last argument in the argument list to varargin. This special keyword indicates that all arguments to the function (beyond the last non-varargin keyword) are assigned to a cell array named varargin available to the function. Variable argument functions are usually used when writing driver functions, i.e., functions that need to pass arguments to another function. The general syntax for a function that takes a variable number of arguments is

```
function [out_1,...,out_M] = fname(in_1,...,in_M,varargin)
```

Inside the function body, varargin collects the arguments to fname that are not assigned to the in_k.

3.8.2 Example

Here is a simple wrapper to feval that demonstrates the use of variable arguments functions.

```
wrapcall.m
function wrapcall(fname, varargin)
feval(fname, varargin{:});
```

Now we show a call of the wrapcall function with a number of arguments

```
--> wrapcall('printf','%f...%f\n',pi,e) 3.141593...2.718282
```

A more serious driver routine could, for example, optimize a one dimensional function that takes a number of auxilliary parameters that are passed through varargin.

3.9 VARARGOUT Variable Output Arguments

3.9.1 Usage

FreeMat functions can return a variable number of output arguments by setting the last argument in the argument list to varargout. This special keyword indicates that the number of return values is variable. The general syntax for a function that returns a variable number of outputs is

```
function [out_1,...,out_M,varargout] = fname(in_1,...,in_M)
```

The function is responsible for ensuring that varargout is a cell array that contains the values to assign to the outputs beyond out_M. Generally, variable output functions use nargout to figure out how many outputs have been requested.

3.9.2 Example

This is a function that returns a varying number of values depending on the value of the argument.

```
varoutfunc.m
function [varargout] = varoutfunc
switch(nargout)
  case 1
    varargout = {'one of one'};
  case 2
    varargout = {'one of two', 'two of two'};
  case 3
    varargout = {'one of three', 'two of three', 'three of three'};
end
```

Here are some examples of exercising varoutfunc:

```
--> [c1] = varoutfunc
c1 =
one of one
--> [c1,c2] = varoutfunc
c1 =
one of two
c2 =
two of two
--> [c1,c2,c3] = varoutfunc
c1 =
one of three
c2 =
two of three
c3 =
three of three
```

Chapter 4

Mathematical Operators

4.1 COLON Index Generation Operator

4.1.1 Usage

There are two distinct syntaxes for the colon: operator - the two argument form

$$y = a : c$$

and the three argument form

$$y = a : b : c$$

The two argument form is exactly equivalent to a:1:c. The output y is the vector

$$y = [a, a+b, a+2b, \dots, a+nb]$$

where a+nb <= c. There is a third form of the colon operator, the no-argument form used in indexing (see indexing for more details).

4.1.2 Function Internals

The colon operator turns out to be trickier to implement than one might believe at first, primarily because the floating point versions should do the right thing, which is not the obvious behavior. For example, suppose the user issues a three point colon command

$$y = a : b : c$$

The first question that one might need to answer is: how many points in this vector? If you answered

$$n = \frac{c - a}{b} + 1$$

then you would be doing the straighforward, but not correct thing. because a, b, and c are all floating point values, there are errors associated with each of the quantities that can lead to n not

being an integer. A better way (and the way FreeMat currently does the calculation) is to compute the bounding values (for b positive)

$$n \in \left[\frac{(c-a) \to 0}{b \to \infty}, \frac{(c-a) \to \infty}{b \to 0}\right] + 1$$

where

$$x \to y$$

means we replace x by the floating point number that is closest to it in the direction of y. Once we have determined the number of points we have to compute the intermediate values

$$[a, a + b, a + 2 * b, \dots, a + n * b]$$

but one can readily verify for themselves that this may not be the same as the vector

fliplr[
$$c, c - b, c - 2 * b, \dots, c - n * b$$
]

even for the case where

$$c = a + n * b$$

for some n. The reason is that the roundoff in the calculations may be different depending on the nature of the sum. FreeMat uses the following strategy to compute the double-colon vector:

- 1. The value n is computed by taking the floor of the larger value in the interval defined above.
- 2. If n falls inside the interval defined above, then it is assumed that the user intended c = a + n*b, and the symmetric algorithm is used. Otherwise, the nonsymmetric algorithm is used.
- 3. The symmetric algorithm computes the vector via

$$[a, a + b, a + 2b, \dots, c - 2b, c - b, c]$$

working symmetrically from both ends of the vector (hence the nomenclature), while the nonsymmetric algorithm computes

$$[a, a + b, a + 2b, \dots, a + nb]$$

In practice, the entries are computed by repeated accumulation instead of multiplying the step size by an integer.

4. The real interval calculation is modified so that we get the exact same result with a:b:c and c:-b:a (which basically means that instead of moving towards infinity, we move towards the signed infinity where the sign is inherited from b).

If you think this is all very obscure, it is. But without it, you will be confronted by mysterious vectors where the last entry is dropped, or where the values show progressively larger amounts of accumulated roundoff error.

4.1.3 Examples

```
Some simple examples of index generation.
```

```
--> y = 1:4
```

y = 1 2 3 4

Now by half-steps:

$$--> y = 1:.5:4$$

y =

Columns 1 to 6

1.0000 1.5000 2.0000 2.5000 3.0000 3.5000

Columns 7 to 7

4.0000

Now going backwards (negative steps)

$$--> y = 4:-.5:1$$

y =

Columns 1 to 6

4.0000 3.5000 3.0000 2.5000 2.0000 1.5000

Columns 7 to 7

1.0000

If the endpoints are the same, one point is generated, regardless of the step size (middle argument)

$$--> y = 4:1:4$$

y =

If the endpoints define an empty interval, the output is an empty matrix:

$$--> y = 5:4$$

v =

Empty array 1 0

4.2 COMPARISONOPS Array Comparison Operators

4.2.1 Usage

There are a total of six comparison operators available in FreeMat, all of which are binary operators with the following syntax

```
y = a < b
y = a <= b
y = a > b
y = a >= b
y = a ~= b
y = a == b
```

where a and b are numerical arrays or scalars, and y is a logical array of the appropriate size. Each of the operators has three modes of operation, summarized in the following list:

- 1. a is a scalar, b is an n-dimensional array the output is then the same size as b, and contains the result of comparing each element in b to the scalar a.
- 2. a is an n-dimensional array, b is a scalar the output is the same size as a, and contains the result of comparing each element in a to the scalar b.
- 3. a and b are both n-dimensional arrays of the same size the output is then the same size as both a and b, and contains the result of an element-wise comparison between a and b.

The operators behave the same way as in C, with unequal types being promoted using the standard type promotion rules prior to comparisons. The only difference is that in FreeMat, the not-equals operator is ~= instead of !=.

4.2.2 Examples

Some simple examples of comparison operations. First a comparison with a scalar:

4.3 DOTLEFTDIVIDE Element-wise Left-Division Operator

4.3.1 Usage

Divides two numerical arrays (elementwise) - gets its name from the fact that the divisor is on the left. There are two forms for its use, both with the same general syntax:

$$y = a . \ b$$

where a and b are n-dimensional arrays of numerical type. In the first case, the two arguments are the same size, in which case, the output y is the same size as the inputs, and is the element-wise division of b by a. In the second case, either a or b is a scalar, in which case y is the same size as the larger argument, and is the division of the scalar with each element of the other argument.

The rules for manipulating types has changed in FreeMat 4.0. See typerules for more details.

4.3.2 Function Internals

There are three formulae for the dot-left-divide operator, depending on the sizes of the three arguments. In the most general case, in which the two arguments are the same size, the output is computed via:

$$y(m_1,\ldots,m_d) = \frac{b(m_1,\ldots,m_d)}{a(m_1,\ldots,m_d)}$$

If a is a scalar, then the output is computed via

$$y(m_1, \dots, m_d) = \frac{b(m_1, \dots, m_d)}{a}$$

On the other hand, if b is a scalar, then the output is computed via

$$y(m_1,\ldots,m_d) = \frac{b}{a(m_1,\ldots,m_d)}.$$

4.3.3 Examples

--> 3 .\ 8

Here are some examples of using the dot-left-divide operator. First, a straight-forward usage of the .\\ operator. The first example is straightforward:

```
ans =
    2.6667
    We can also divide complex arguments:
--> a = 3 + 4*i
a =
    3.0000 + 4.0000i
--> b = 5 + 8*i
b =
    5.0000 + 8.0000i
--> c = b .\ a
c =
    0.5281 - 0.0449i
```

We can also demonstrate the three forms of the dot-left-divide operator. First the element-wise version:

```
--> a = [1,2;3,4]

a =
    1 2
    3 4

--> b = [2,3;6,7]

b =
    2 3
    6 7

--> c = a .\ b

c =
    2.0000    1.5000
    2.0000    1.7500
```

Then the scalar versions

4.4 DOTPOWER Element-wise Power Operator

4.4.1 Usage

Raises one numerical array to another array (elementwise). There are three operators all with the same general syntax:

$$y = a .^b$$

The result y depends on which of the following three situations applies to the arguments a and b:

- 1. a is a scalar, b is an arbitrary n-dimensional numerical array, in which case the output is a raised to the power of each element of b, and the output is the same size as b.
- 2. a is an n-dimensional numerical array, and b is a scalar, then the output is the same size as a, and is defined by each element of a raised to the power b.
- 3. a and b are both n-dimensional numerical arrays of the same size. In this case, each element of the output is the corresponding element of a raised to the power defined by the corresponding element of b.

The rules for manipulating types has changed in FreeMat 4.0. See typerules for more details.

4.4.2 Function Internals

There are three formulae for this operator. For the first form

$$y(m_1, \ldots, m_d) = a^{b(m_1, \ldots, m_d)},$$

and the second form

$$y(m_1,\ldots,m_d)=a(m_1,\ldots,m_d)^b,$$

and in the third form

$$y(m_1,...,m_d) = a(m_1,...,m_d)^{b(m_1,...,m_d)}.$$

4.4.3 Examples

We demonstrate the three forms of the dot-power operator using some simple examples. First, the case of a scalar raised to a series of values.

The second case shows a vector raised to a scalar.

The third case shows the most general use of the dot-power operator.

```
--> A = [1,2;3,2]

A =
    1 2
    3 2

--> B = [2,1.5;0.5,0.6]

B =
    2.0000    1.5000
    0.5000    0.6000

--> C = A.^B

C =
    1.0000    2.8284
    1.7321    1.5157
```

4.5 DOTRIGHTDIVIDE Element-wise Right-Division Operator

4.5.1 Usage

Divides two numerical arrays (elementwise). There are two forms for its use, both with the same general syntax:

$$y = a ./ b$$

where a and b are n-dimensional arrays of numerical type. In the first case, the two arguments are the same size, in which case, the output y is the same size as the inputs, and is the element-wise division of b by a. In the second case, either a or b is a scalar, in which case y is the same size as the larger argument, and is the division of the scalar with each element of the other argument.

The rules for manipulating types has changed in FreeMat 4.0. See typerules for more details.

4.5.2 Function Internals

There are three formulae for the dot-right-divide operator, depending on the sizes of the three arguments. In the most general case, in which the two arguments are the same size, the output is computed via:

$$y(m_1, ..., m_d) = \frac{a(m_1, ..., m_d)}{b(m_1, ..., m_d)}$$

If a is a scalar, then the output is computed via

$$y(m_1, \dots, m_d) = \frac{a}{b(m_1, \dots, m_d)}$$

On the other hand, if b is a scalar, then the output is computed via

$$y(m_1,\ldots,m_d)=\frac{a(m_1,\ldots,m_d)}{b}.$$

4.5.3 Examples

Here are some examples of using the dot-right-divide operator. First, a straight-forward usage of the ./ operator. The first example is straightforward:

ans =

0.3750

We can also divide complex arguments:

$$-->$$
 a = 3 + 4*i

a =

3.0000 + 4.0000i

We can also demonstrate the three forms of the dot-right-divide operator. First the element-wise version:

Then the scalar versions

4.6 DOTTIMES Element-wise Multiplication Operator

4.6.1 Usage

Multiplies two numerical arrays (elementwise). There are two forms for its use, both with the same general syntax:

$$y = a \cdot * b$$

where a and b are n-dimensional arrays of numerical type. In the first case, the two arguments are the same size, in which case, the output y is the same size as the inputs, and is the element-wise product of a and b. In the second case, either a or b is a scalar, in which case y is the same size as the larger argument, and is the product of the scalar with each element of the other argument.

The rules for manipulating types has changed in FreeMat 4.0. See typerules for more details.

4.6.2 Function Internals

There are three formulae for the dot-times operator, depending on the sizes of the three arguments. In the most general case, in which the two arguments are the same size, the output is computed via:

$$y(m_1,...,m_d) = a(m_1,...,m_d) \times b(m_1,...,m_d)$$

If a is a scalar, then the output is computed via

$$y(m_1,\ldots,m_d)=a\times b(m_1,\ldots,m_d).$$

On the other hand, if b is a scalar, then the output is computed via

$$y(m_1,\ldots,m_d)=a(m_1,\ldots,m_d)\times b.$$

4.6.3 Examples

Here are some examples of using the dottimes operator. First, a straight-forward usage of the .* operator. The first example is straightforward:

Next, we multiply a scalar by a vector of values:

With complex values

```
--> a = 3 + 4*i
   3.0000 + 4.0000i
--> b = a .* 2
   6.0000 + 8.0000i
Finally, the element-wise version:
--> a = [1,2;3,4]
a =
1 2
 3 4
--> b = [2,3;6,7]
b =
 2 3
 6 7
--> c = a .* b
c =
 2 6
 18 28
```

4.7 HERMITIAN Matrix Hermitian (Conjugate Transpose) Operator

4.7.1 Usage

Computes the Hermitian of the argument (a 2D matrix). The syntax for its use is

$$y = a'$$

where a is a M x N numerical matrix. The output y is a numerical matrix of the same type of size N x M. This operator is the conjugating transpose, which is different from the transpose operator .' (which does not conjugate complex values).

4.7.2 Function Internals

The Hermitian operator is defined simply as

$$y_{i,j} = \overline{a_{j,i}}$$

where y_ij is the element in the ith row and jth column of the output matrix y.

4.7.3 Examples

```
A simple transpose example:
```

```
--> A = [1,2,0;4,1,-1]

A =
    1    2    0
    4    1 -1

--> A'

ans =
    1    4
    2    1
    0 -1
```

Here, we use a complex matrix to demonstrate how the Hermitian operator conjugates the entries.

```
--> A = [1+i,2-i]

A =
    1.0000 + 1.0000i    2.0000 - 1.0000i

--> A.'

ans =
    1.0000 + 1.0000i
    2.0000 - 1.0000i
```

4.8 LEFTDIVIDE Matrix Equation Solver/Divide Operator

4.8.1 Usage

The divide operator \ is really a combination of three operators, all of which have the same general syntax:

```
Y = A \setminus B
```

where A and B are arrays of numerical type. The result Y depends on which of the following three situations applies to the arguments A and B:

- 1. A is a scalar, B is an arbitrary n-dimensional numerical array, in which case the output is each element of B divided by the scalar A.
- 2. A,B are matrices with the same number of rows, i.e., A is of size M \times K, and B is of size M \times L, in which case the output is of size K \times L.

The output follows the standard type promotion rules, although in the first two cases, if A and B are integers, the output is an integer also, while in the third case if A and B are integers, the output is of type double.

A few additional words about the third version, in which A and B are matrices. Very loosely speaking, Y is the matrix that satisfies A * Y = B. In cases where such a matrix exists. If such a matrix does not exist, then a matrix Y is returned that approximates $A * Y \setminus approx B$.

4.8.2 Function Internals

There are three formulae for the times operator. For the first form

$$Y(m_1,\ldots,m_d) = \frac{B(m_1,\ldots,m_d)}{A}.$$

In the second form, the calculation of the output depends on the size of A. Because each column of B is treated independantly, we can rewrite the equation A Y = B as

$$A[y_1, y_2, \dots, y_l] = [b_1, b_2, \dots, b_l]$$

where y_i are the columns of Y, and b_i are the columns of the matrix B. If A is a square matrix, then the LAPACK routine *gesvx (where the * is replaced with sdcz depending on the type of the arguments) is used, which uses an LU decomposition of A to solve the sequence of equations sequentially. If A is singular, then a warning is emitted.

On the other hand, if A is rectangular, then the LAPACK routine *gelsy is used. Note that these routines are designed to work with matrices A that are full rank - either full column rank or full row rank. If A fails to satisfy this assumption, a warning is emitted. If A has full column rank (and thus necessarily has more rows than columns), then theoretically, this operator finds the columns y_i that satisfy:

$$y_i = \arg\min_{y} ||Ay - b_i||_2$$

and each column is thus the Least Squares solution of A $y = b_i$. On the other hand, if A has full row rank (and thus necessarily has more columns than rows), then theoretically, this operator finds the columns y_i that satisfy

$$y_i = \arg\min_{Ay = b_i} ||y||_2$$

and each column is thus the Minimum Norm vector y_i that satisfies A y_i = b_i. In the event that the matrix A is neither full row rank nor full column rank, a solution is returned, that is the minimum norm least squares solution. The solution is computed using an orthogonal factorization technique that is documented in the LAPACK User's Guide (see the References section for details).

4.8.3 Examples

Here are some simple examples of the divide operator. We start with a simple example of a full rank, square matrix:

$$--> A = [1,1;0,1]$$

4.8. LEFTDIVIDE MATRIX EQUATION SOLVER/DIVIDE OPERATOR

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Suppose we wish to solve

$$\begin{bmatrix} 1 & 1 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} y_1 \\ y_2 \end{bmatrix} = \begin{bmatrix} 3 \\ 2 \end{bmatrix}$$

(which by inspection has the solution $y_1 = 1$, $y_2 = 2$). Thus we compute:

$$-->$$
 B = [3;2]

B =

3

2

$$--> Y = A \setminus B$$

Y =

1

Suppose we wish to solve a trivial Least Squares (LS) problem. We want to find a simple scaling of the vector [1;1] that is closest to the point [2,1]. This is equivalent to solving

$$\begin{bmatrix} 1 \\ 1 \end{bmatrix} y = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

in a least squares sense. For fun, we can calculate the solution using calculus by hand. The error we wish to minimize is

$$\varepsilon(y) = (y - 2)^2 + (y - 1)^2.$$

Taking a derivative with respect to y, and setting to zero (which we must have for an extrema when y is unconstrained)

$$2(y-2) + 2(y-1) = 0$$

which we can simplify to 4y = 6 or y = 3/2 (we must, technically, check to make sure this is a minimum, and not a maximum or an inflection point). Here is the same calculation performed using FreeMat:

$$--> A = [1;1]$$

A =

1

1

$$-->$$
 B = [2;1]

B =

2

```
1
--> A\B
ans =
1.5000
```

which is the same solution.

4.9 LOGICALOPS Logical Array Operators

4.9.1 Usage

There are three Boolean operators available in FreeMat. The syntax for their use is:

```
y = x

y = a & b

y = a | b
```

where x, a and b are logical arrays. The operators are

- NOT ($\tilde{}$) output y is true if the corresponding element of x is false, and output y is false if the corresponding element of x is true.
- OR (—) output y is true if corresponding element of a is true or if corresponding element of b is true (or if both are true).
- AND (\&) output y is true only if both the corresponding elements of a and b are both true.

The binary operators AND and OR can take scalar arguments as well as vector arguments, in which case, the scalar is operated on with each element of the vector. As of version 1.10, FreeMat supports shortcut evaluation. This means that if we have two expressions

```
if (expr1 & expr2)
```

then if expr1 evaluates to false, then expr2 is not evaluated at all. Similarly, for the expression

```
if (expr1 | expr2)
```

then if expr1 evaluates to true, then expr2 is not evaluated at all. Shortcut evaluation is useful for doing a sequence of tests, each of which is not valid unless the prior test is successful. For example,

```
if isa(p,'string') & strcmp(p,'fro')
```

is not valid without shortcut evaluation (if p is an integer, for example, the first test returns false, and an attempt to evaluate the second expression would lead to an error). Note that shortcut evaluation only works with scalar expressions.

4.9.2 Examples

Some simple examples of logical operators. Suppose we want to calculate the exclusive-or (XOR) of two vectors of logical variables. First, we create a pair of vectors to perform the XOR operation on:

```
--> a = (randn(1,6)>0)

a =
0 1 1 1 0 1

--> b = (randn(1,6)>0)

b =
0 1 0 0 1 0

Next, we can compute the OR of a and b:
--> c = a | b

c =
0 1 1 1 1 1
```

However, the XOR and OR operations differ on the fifth entry - the XOR would be false, since it is true if and only if exactly one of the two inputs is true. To isolate this case, we can AND the two vectors, to find exactly those entries that appear as true in both **a** and **b**:

```
--> d = a & b
d =
0 1 0 0 0 0
```

At this point, we can modify the contents of c in two ways – the Boolean way is to AND \sim d with c, like so

```
--> xor = c & (~d)
xor =
0 0 1 1 1 1
```

The other way to do this is simply force c(d) = 0, which uses the logical indexing mode of FreeMat (see the chapter on indexing for more details). This, however, will cause c to become an int32 type, as opposed to a logical type.

```
--> c(d) = 0
c =
0 0 1 1 1 1
```

4.10 MATRIXPOWER Matrix Power Operator

4.10.1 Usage

The power operator for scalars and square matrices. This operator is really a combination of two operators, both of which have the same general syntax:

$$y = a \hat{b}$$

The exact action taken by this operator, and the size and type of the output, depends on which of the two configurations of a and b is present:

- 1. a is a scalar, b is a square matrix
- 2. a is a square matrix, b is a scalar

4.10.2 Function Internals

In the first case that a is a scalar, and b is a square matrix, the matrix power is defined in terms of the eigenvalue decomposition of b. Let b have the following eigen-decomposition (problems arise with non-symmetric matrices b, so let us assume that b is symmetric):

$$b = E \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \dots & 0 & \lambda_n \end{bmatrix} E^{-1}$$

Then a raised to the power b is defined as

$$a^{b} = E \begin{bmatrix} a^{\lambda_{1}} & 0 & \cdots & 0 \\ 0 & a^{\lambda_{2}} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & a^{\lambda_{n}} \end{bmatrix} E^{-1}$$

Similarly, if a is a square matrix, then a has the following eigen-decomposition (again, suppose a is symmetric):

$$a = E \begin{bmatrix} \lambda_1 & 0 & \cdots & 0 \\ 0 & \lambda_2 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \lambda_n \end{bmatrix} E^{-1}$$

Then a raised to the power b is defined as

$$a^{b} = E \begin{bmatrix} \lambda_{1}^{b} & 0 & \cdots & 0 \\ 0 & \lambda_{2}^{b} & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \lambda_{n}^{b} \end{bmatrix} E^{-1}$$

4.10.3 Examples

We first define a simple 2×2 symmetric matrix

```
--> A = 1.5
    1.5000
--> B = [1,.2;.2,1]
B =
    1.0000
               0.2000
    0.2000
               1.0000
First, we raise B to the (scalar power) A:
--> C = B^A
    1.0150
               0.2995
    0.2995
               1.0150
Next, we raise A to the matrix power B:
--> C = A^B
C =
    1.5049
               0.1218
    0.1218
               1.5049
```

4.11 MINUS Subtraction Operator

4.11.1 Usage

Subtracts two numerical arrays (elementwise). There are two forms for its use, both with the same general syntax:

$$y = a - b$$

where a and b are n-dimensional arrays of numerical type. In the first case, the two arguments are the same size, in which case, the output y is the same size as the inputs, and is the element-wise difference of a and b. In the second case, either a or b is a scalar, in which case y is the same size as the larger argument, and is the difference of the scalar to each element of the other argument.

The rules for manipulating types has changed in FreeMat 4.0. See typerules for more details.

4.11.2 Function Internals

There are three formulae for the subtraction operator, depending on the sizes of the three arguments. In the most general case, in which the two arguments are the same size, the output is computed via:

$$y(m_1,...,m_d) = a(m_1,...,m_d) - b(m_1,...,m_d)$$

If a is a scalar, then the output is computed via

$$y(m_1, ..., m_d) = a - b(m_1, ..., m_d).$$

On the other hand, if b is a scalar, then the output is computed via

$$y(m_1, ..., m_d) = a(m_1, ..., m_d) - b.$$

4.11.3 Examples

Here are some examples of using the subtraction operator. First, a straight-forward usage of the minus operator. The first example is straightforward:

```
--> 3 - 8
ans =
-5
```

Next, we subtract a vector of values from a scalar:

With complex values

$$-->$$
 a = 3 - 4*i

$$--> b = a - 2$$

Finally, the element-wise version:

$$-->$$
 a = [1,2;3,4]

```
3 4

--> b = [2,3;6,7]

b = 2 3
6 7

--> c = a - b

c = -1 -1
-3 -3
```

4.12 PLUS Addition Operator

4.12.1 Usage

Adds two numerical arrays (elementwise) together. There are two forms for its use, both with the same general syntax:

$$y = a + b$$

where a and b are n-dimensional arrays of numerical type. In the first case, the two arguments are the same size, in which case, the output y is the same size as the inputs, and is the element-wise the sum of a and b. In the second case, either a or b is a scalar, in which case y is the same size as the larger argument, and is the sum of the scalar added to each element of the other argument.

The rules for manipulating types has changed in FreeMat 4.0. See typerules for more details.

4.12.2 Function Internals

There are three formulae for the addition operator, depending on the sizes of the three arguments. In the most general case, in which the two arguments are the same size, the output is computed via:

$$y(m_1,...,m_d) = a(m_1,...,m_d) + b(m_1,...,m_d)$$

If a is a scalar, then the output is computed via

$$y(m_1, \ldots, m_d) = a + b(m_1, \ldots, m_d).$$

On the other hand, if b is a scalar, then the output is computed via

$$y(m_1, ..., m_d) = a(m_1, ..., m_d) + b.$$

4.12.3 Examples

Here are some examples of using the addition operator. First, a straight-forward usage of the plus operator. The first example is straightforward:

ans = 11

Next, we add a scalar to a vector of values:

$$--> 3.1 + [2,4,5,6,7]$$

ans =

5.1000 7.1000 8.1000 9.1000 10.1000

With complex values

$$-->$$
 a = 3 + 4*i

a =

3.0000 + 4.0000i

$$-->$$
 b = a + 2

b =

5.0000 + 4.0000i

Finally, the element-wise version:

$$-->$$
 a = [1,2;3,4]

a =

1 2

3 4

--> b = [2,3;6,7]

b =

2 3

6 7

--> c = a + b

c =

3 5

9 11

4.13 RIGHTDIVIDE Matrix Equation Solver/Divide Operator

4.13.1 Usage

The divide operator / is really a combination of three operators, all of which have the same general syntax:

$$Y = A / B$$

where A and B are arrays of numerical type. The result Y depends on which of the following three situations applies to the arguments A and B:

- 1. A is a scalar, B is an arbitrary n-dimensional numerical array, in which case the output is the scalar A divided into each element of B.
- 2. B is a scalar, A is an arbitrary n-dimensional numerical array, in which case the output is each element of A divided by the scalar B.
- 3. A,B are matrices with the same number of columns, i.e., A is of size K x M, and B is of size L x M, in which case the output is of size K x L.

The output follows the standard type promotion rules, although in the first two cases, if A and B are integers, the output is an integer also, while in the third case if A and B are integers, the output is of type double.

4.13.2 Function Internals

There are three formulae for the times operator. For the first form

$$Y(m_1,\ldots,m_d) = \frac{A}{B(m_1,\ldots,m_d)},$$

and the second form

$$Y(m_1,\ldots,m_d)=\frac{A(m_1,\ldots,m_d)}{B}.$$

In the third form, the output is defined as:

$$Y = (B' \backslash A')'$$

and is used in the equation Y B = A.

4.13.3 Examples

The right-divide operator is much less frequently used than the left-divide operator, but the concepts are similar. It can be used to find least-squares and minimum norm solutions. It can also be used to solve systems of equations in much the same way. Here's a simple example:

4.14 TIMES Matrix Multiply Operator

4.14.1 Usage

Multiplies two numerical arrays. This operator is really a combination of three operators, all of which have the same general syntax:

$$y = a * b$$

where a and b are arrays of numerical type. The result y depends on which of the following three situations applies to the arguments a and b:

- 1. a is a scalar, b is an arbitrary n-dimensional numerical array, in which case the output is the element-wise product of b with the scalar a.
- 2. b is a scalar, a is an arbitrary n-dimensional numerical array, in which case the output is the element-wise product of a with the scalar b.
- 3. a,b are conformant matrices, i.e., a is of size M \times K, and b is of size K \times N, in which case the output is of size M \times N and is the matrix product of a, and b.

Matrix multiplication is only defined for matrices of type double and single.

4.14.2 Function Internals

There are three formulae for the times operator. For the first form

$$y(m_1,\ldots,m_d)=a\times b(m_1,\ldots,m_d),$$

and the second form

$$y(m_1,\ldots,m_d)=a(m_1,\ldots,m_d)\times b.$$

In the third form, the output is the matrix product of the arguments

$$y(m,n) = \sum_{k=1}^{K} a(m,k)b(k,n)$$

4.14.3 Examples

Here are some examples of using the matrix multiplication operator. First, the scalar examples (types 1 and 2 from the list above):

```
--> a = [1,3,4;0,2,1]

a =
    1 3 4
    0 2 1

--> b = a * 2

b =
    2 6 8
    0 4 2
```

The matrix form, where the first argument is 2×3 , and the second argument is 3×1 , so that the product is size 2×1 .

```
--> a = [1,2,0;4,2,3]

a =
    1 2 0
    4 2 3

--> b = [5;3;1]

b =
    5
    3
    1

--> c = a*b

c =
    11
    20
```

Note that the output is double precision.

4.15 TRANSPOSE Matrix Transpose Operator

4.15.1 Usage

Performs a transpose of the argument (a 2D matrix). The syntax for its use is

```
y = a.';
```

where a is a M x N numerical matrix. The output y is a numerical matrix of the same type of size N x M. This operator is the non-conjugating transpose, which is different from the Hermitian operator ' (which conjugates complex values).

4.15.2 Function Internals

The transpose operator is defined simply as

$$y_{i,j} = a_{j,i}$$

where y_ij is the element in the ith row and jth column of the output matrix y.

4.15.3 Examples

A simple transpose example:

```
--> A = [1,2,0;4,1,-1]
A =
1  2  0
4  1 -1
```

--> A.,

Here, we use a complex matrix to demonstrate how the transpose does *not* conjugate the entries.

```
--> A = [1+i,2-i]

A =
    1.0000 + 1.0000i    2.0000 - 1.0000i

--> A.'

ans =
    1.0000 + 1.0000i
    2.0000 - 1.0000i
```

4.16 TYPERULES Type Rules for Operators

4.16.1 Usage

Starting with FreeMat 4.0, the type of **y** is determined according to the same rules as Matlab. These are the rules:

- 1. Integer types of the same class can be combined. The answer is the same type as the inputs, and the operation is performed using saturating arithmetic. Integer types can also be combined with double precision values (again, the result is of the integer type).
- 2. Single precision floating point values can be combined with double precision, logical and character array classes. The result is of class single.
- 3. Double precision floating point values can be combined with all other types. Except as noted above, the output is of double precision.

These rules look strange, and they are. In general, computations are done in double precision in almost all cases. When single precision values are involved, the computations take place in single precision.

Chapter 5

Flow Control

5.1 BREAK Exit Execution In Loop

5.1.1 Usage

The break statement is used to exit a loop prematurely. It can be used inside a for loop or a while loop. The syntax for its use is

break

inside the body of the loop. The break statement forces execution to exit the loop immediately.

5.1.2 Example

Here is a simple example of how break exits the loop. We have a loop that sums integers from 1 to 10, but that stops prematurely at 5 using a break. We will use a while loop.

```
break_ex.m
function accum = break_ex
accum = 0;
i = 1;
while (i<=10)
    accum = accum + i;
if (i == 5)
    break;
end
i = i + 1;
end</pre>
```

The function is exercised here:

```
--> break_ex
```

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t

```
ans =
15
--> sum(1:5)
ans =
15
```

5.2 CONTINUE Continue Execution In Loop

5.2.1 Usage

The continue statement is used to change the order of execution within a loop. The continue statement can be used inside a for loop or a while loop. The syntax for its use is

```
continue
```

inside the body of the loop. The continue statement forces execution to start at the top of the loop with the next iteration. The examples section shows how the continue statement works.

5.2.2 Example

Here is a simple example of using a continue statement. We want to sum the integers from 1 to 10, but not the number 5. We will use a for loop and a continue statement.

```
continue_ex.m
function accum = continue_ex
  accum = 0;
  for i=1:10
    if (i==5)
      continue;
    end
    accum = accum + 1; %skipped if i == 5!
  end

The function is exercised here:
--> continue_ex

ans =
  9
--> sum([1:4,6:10])

ans =
  50
```

5.3 ERROR Causes an Error Condition Raised

5.3.1 Usage

The error function causes an error condition (exception to be raised). The general syntax for its use is

```
error(s),
```

where s is the string message describing the error. The error function is usually used in conjunction with try and catch to provide error handling. If the string s, then (to conform to the MATLAB API), error does nothing.

5.3.2 Example

In base()

evenoddtest.m

Here is a simple example of an error being issued by a function evenoddtest:

```
function evenoddtest(n)
  if (n==0)
    error('zero is neither even nor odd');
  elseif ( n ~= fix(n) )
    error('expecting integer argument');
  end;
  if (n=int32(n/2)*2)
    printf('%d is even\n',n);
    printf('%d is odd\n',n);
  end
The normal command line prompt --> simply prints the error that occured.
--> evenoddtest(4)
4 is even
--> evenoddtest(5)
5 is odd
--> evenoddtest(0)
In /home/basu/dev/branches/FreeMat4/help/tmp/evenoddtest.m(evenoddtest) at line 3
    In scratch() at line 1
    In base(base)
    In base()
    In global()
Error: zero is neither even nor odd
--> evenoddtest(pi)
In /home/basu/dev/branches/FreeMat4/help/tmp/evenoddtest.m(evenoddtest) at line 5
    In scratch() at line 1
    In base(base)
```

```
In global()
Error: expecting integer argument
```

5.4 FOR For Loop

5.4.1 Usage

The for loop executes a set of statements with an index variable looping through each element in a vector. The syntax of a for loop is one of the following:

```
for (variable=expression)
   statements
end
```

Alternately, the parenthesis can be eliminated

```
for variable=expression
    statements
end
```

or alternately, the index variable can be pre-initialized with the vector of values it is going to take:

```
for variable
    statements
end
```

The third form is essentially equivalent to for variable=variable, where variable is both the index variable and the set of values over which the for loop executes. See the examples section for an example of this form of the for loop.

5.4.2 Examples

Here we write for loops to add all the integers from 1 to 100. We will use all three forms of the for statement.

```
--> accum = 0;
--> for (i=1:100); accum = accum + i; end
--> accum

ans =
5050

The second form is functionally the same withou
```

The second form is functionally the same, without the extra parenthesis

```
--> accum = 0;

--> for i=1:100; accum = accum + i; end

--> accum

ans =

5050
```

In the third example, we pre-initialize the loop variable with the values it is to take

5.5 IF-ELSEIF-ELSE Conditional Statements

5.5.1 Usage

The if and else statements form a control structure for conditional execution. The general syntax involves an if test, followed by zero or more elseif clauses, and finally an optional else clause:

```
if conditional_expression_1
   statements_1
elseif conditional_expression_2
   statements_2
elseif conditional_expresiion_3
   statements_3
...
else
   statements_N
end
```

Note that a conditional expression is considered true if the real part of the result of the expression contains any non-zero elements (this strange convention is adopted for compatibility with MATLAB).

5.5.2 Examples

Here is an example of a function that uses an if statement

```
if_test.m
function c = if_test(a)
  if (a == 1)
    c = 'one';
  elseif (a==2)
    c = 'two';
  elseif (a==3)
    c = 'three';
  else
    c = 'something else';
  end

Some examples of if_test in action:
--> if_test(1)
ans =
one
--> if_test(2)
```

```
ans =
two
--> if_test(3)
ans =
three
--> if_test(pi)
ans =
something else
```

5.6 KEYBOARD Initiate Interactive Debug Session

5.6.1 Usage

The keyboard statement is used to initiate an interactive session at a specific point in a function. The general syntax for the keyboard statement is

```
keyboard
```

A keyboard statement can be issued in a script, in a function, or from within another keyboard session. The result of a keyboard statement is that execution of the program is halted, and you are given a prompt of the form:

```
[scope,n] -->
```

where scope is the current scope of execution (either the name of the function we are executing, or base otherwise). And n is the depth of the keyboard session. If, for example, we are in a keyboard session, and we call a function that issues another keyboard session, the depth of that second session will be one higher. Put another way, n is the number of return statements you have to issue to get back to the base workspace. Incidentally, a return is how you exit the keyboard session and resume execution of the program from where it left off. A retall can be used to shortcut execution and return to the base workspace.

The keyboard statement is an excellent tool for debugging FreeMat code, and along with eval provide a unique set of capabilities not usually found in compiled environments. Indeed, the keyboard statement is equivalent to a debugger breakpoint in more traditional environments, but with significantly more inspection power.

5.6.2 Example

Here we demonstrate a two-level keyboard situation. We have a simple function that calls keyboard internally:

```
key_one.m
function c = key_one(a,b)
c = a + b;
keyboard
```

Now, we execute the function from the base workspace, and at the keyboard prompt, we call it again. This action puts us at depth 2. We can confirm that we are in the second invocation of the function by examining the arguments. We then issue two return statements to return to the base workspace.

```
--> key_one(1,2)
[key_one,3]--> key_one(5,7)
[key_one,3]--> a
ans =
5
[key_one,3]--> b
ans =
7
[key_one,3]--> c
ans =
12
[key_one,3]--> return
ans =
12
[key_one,3]--> a
ans =
1
[key_one,3]--> b
ans =
2
[\text{key\_one,3}] --> c
ans =
3
[key_one,3]--> return
ans =
3
```

5.7 LASTERR Retrieve Last Error Message

5.7.1 Usage

Either returns or sets the last error message. The general syntax for its use is either

```
msg = lasterr
```

which returns the last error message that occured, or

```
lasterr(msg)
```

which sets the contents of the last error message.

5.7.2 Example

Here is an example of using the error function to set the last error, and then retrieving it using lasterr.

```
--> try; error('Test error message'); catch; end;
--> lasterr

ans =
Test error message
Or equivalently, using the second form:
--> lasterr('Test message');
--> lasterr
ans =
Test message
```

5.8 RETALL Return From All Keyboard Sessions

5.8.1 Usage

The retall statement is used to return to the base workspace from a nested keyboard session. It is equivalent to forcing execution to return to the main prompt, regardless of the level of nesting of keyboard sessions, or which functions are running. The syntax is simple

```
retall
```

The retall is a convenient way to stop debugging. In the process of debugging a complex program or set of functions, you may find yourself 5 function calls down into the program only to discover the problem. After fixing it, issueing a retall effectively forces FreeMat to exit your program and return to the interactive prompt.

5.8.2 Example

Here we demonstrate an extreme example of retall. We are debugging a recursive function self to calculate the sum of the first N integers. When the function is called, a keyboard session is initiated after the function has called itself N times. At this keyboard prompt, we issue another call to self and get another keyboard prompt, this time with a depth of 2. A retall statement returns us to the top level without executing the remainder of either the first or second call to self:

```
self.m
function y = self(n)
  if (n>1)
    y = n + self(n-1);
    printf('y is %d\n',y);
  else
    y = 1;
    printf('y is initialized to one\n');
    keyboard
  end
--> self(4)
y is initialized to one
[self,8]--> self(6)
y is initialized to one
[self,8]--> retall
```

5.9 RETURN Return From Function

5.9.1 Usage

The return statement is used to immediately return from a function, or to return from a keyboard session. The syntax for its use is

```
return
```

Inside a function, a return statement causes FreeMat to exit the function immediately. When a keyboard session is active, the return statement causes execution to resume where the keyboard session started.

5.9.2 Example

In the first example, we define a function that uses a **return** to exit the function if a certain test condition is satisfied.

```
return_func.m
function ret = return_func(a,b)
ret = 'a is greater';
if (a > b)
return;
```

```
end
ret = 'b is greater';
printf('finishing up...\n');

Next we exercise the function with a few simple test cases:
--> return_func(1,3)
finishing up...
ans =
b is greater
--> return_func(5,2)
ans =
a is greater
```

In the second example, we take the function and rewrite it to use a keyboard statement inside the if statement.

```
return_func2.m
function ret = return_func2(a,b)
if (a > b)
    ret = 'a is greater';
    keyboard;
else
    ret = 'b is greater';
end
printf('finishing up...\n');
```

Now, we call the function with a larger first argument, which triggers the keyboard session. After verifying a few values inside the keyboard session, we issue a return statement to resume execution.

```
--> return_func2(2,4)
finishing up...

ans =
b is greater
--> return_func2(5,1)
[return_func2,4]--> ret

ans =
a is greater
[return_func2,4]--> a

ans =
5
[return_func2,4]--> b
```

```
ans =
  1
[return_func2,4]--> return
finishing up...
ans =
a is greater
```

5.10 SWITCH Switch statement

5.10.1 Usage

The switch statement is used to selective execute code based on the value of either scalar value or a string. The general syntax for a switch statement is

```
switch(expression)
  case test_expression_1
    statements
  case test_expression_2
    statements
  otherwise
    statements
end
```

The otherwise clause is optional. Note that each test expression can either be a scalar value, a string to test against (if the switch expression is a string), or a cell-array of expressions to test against. Note that unlike C switch statements, the FreeMat switch does not have fall-through, meaning that the statements associated with the first matching case are executed, and then the switch ends. Also, if the switch expression matches multiple case expressions, only the first one is executed.

5.10.2 Examples

Here is an example of a switch expression that tests against a string input:

```
switch_test.m
function c = switch_test(a)
switch(a)
case {'lima beans','root beer'}
c = 'food';
case {'red','green','blue'}
c = 'color';
otherwise
c = 'not sure';
end
```

Now we exercise the switch statements

```
--> switch_test('root beer')

ans =
food
--> switch_test('red')

ans =
color
--> switch_test('carpet')

ans =
not sure
```

5.11 TRY-CATCH Try and Catch Statement

5.11.1 Usage

The try and catch statements are used for error handling and control. A concept present in C++, the try and catch statements are used with two statement blocks as follows

```
try
   statements_1
catch
   statements_2
end
```

The meaning of this construction is: try to execute statements_1, and if any errors occur during the execution, then execute the code in statements_2. An error can either be a FreeMat generated error (such as a syntax error in the use of a built in function), or an error raised with the error command.

5.11.2 Examples

Here is an example of a function that uses error control via try and catch to check for failures in fopen.

```
read_file.m
function c = read_file(filename)
try
   fp = fopen(filename,'r');
   c = fgetline(fp);
   fclose(fp);
catch
   c = ['could not open file because of error :' lasterr]
end
```

Now we try it on an example file - first one that does not exist, and then on one that we create (so that we know it exists).

```
--> read_file('this_filename_is_invalid')
c =
could not open file because of error :Access mode r requires file to exist
ans =
could not open file because of error :Access mode r requires file to exist
--> fp = fopen('test_text.txt','w');
--> fprintf(fp,'a line of text\n');
--> fclose(fp);
--> read_file('test_text.txt')
ans =
a line of text
```

5.12 WARNING Emits a Warning Message

5.12.1 Usage

The warning function causes a warning message to be sent to the user. The general syntax for its use is

```
warning(s)
```

where s is the string message containing the warning.

5.13 WHILE While Loop

5.13.1 Usage

The while loop executes a set of statements as long as a the test condition remains true. The syntax of a while loop is

```
while test_expression statements end
```

Note that a conditional expression is considered true if the real part of the result of the expression contains any non-zero elements (this strange convention is adopted for compatibility with MATLAB).

5.13.2 Examples

Here is a while loop that adds the integers from 1 to 100:

```
--> accum = 0;
--> k=1;
--> while (k<100), accum = accum + k; k = k + 1; end
--> accum
ans =
4950
   testeq.m
function x = testeq(a,b)
 if (size(a,1) ~= size(b,1) || size(a,2) ~= size(b,2))
   x = 0;
   return;
  end
 d = full(a)-full(b);
  if (strcmp(typeof(d),'double') | strcmp(typeof(d),'dcomplex'))
   x = isempty(find(abs(d)>10*eps));
   x = isempty(find(abs(d)>10*feps));
  end
```

Chapter 6

FreeMat Functions

6.1 ADDPATH Add

6.1.1 Usage

The addpath routine adds a set of directories to the current path. The first form takes a single directory and adds it to the beginning or top of the path:

```
addpath('directory')
```

The second form add several directories to the top of the path:

```
addpath('dir1','dir2',...,'dirn')
```

Finally, you can provide a flag to control where the directories get added to the path

```
addpath('dir1','dir2',...,'dirn','-flag')
```

where if flag is either '-0' or '-begin', the directories are added to the top of the path, and if the flag is either '-1' or '-end' the directories are added to the bottom (or end) of the path.

6.2 ASSIGNIN Assign Variable in Workspace

6.2.1 Usage

The assignin function allows you to assign a value to a variable in either the callers work space or the base work space. The syntax for assignin is

```
assignin(workspace, variablename, value)
```

The argument workspace must be either 'caller' or 'base'. If it is 'caller' then the variable is assigned in the caller's work space. That does not mean the caller of assignin, but the caller of the current function or script. On the other hand if the argument is 'base', then the assignment is done in the base work space. Note that the variable is created if it does not already exist.

6.3 BLASLIB Control Profiling

6.3.1 Usage

The blaslib function allows you to select the FreeMat blas library, when dynamic linking is enabled. It has two modes of operation. The first is to select blas library:

```
blaslib LIB_NAME
```

If you want to see current blas library selected issue a blaslib command with no arguments.

blaslib

6.4 BUILTIN Evaulate Builtin Function

6.4.1 Usage

The builtin function evaluates a built in function with the given name, bypassing any overloaded functions. The syntax of builtin is

```
[y1, y2, ..., yn] = builtin(fname, x1, x2, ..., xm)
```

where fname is the name of the function to call. Apart from the fact that fname must be a string, and that builtin always calls the non-overloaded method, it operates exactly like feval. Note that unlike MATLAB, builtin does not force evaluation to an actual compiled function. It simply subverts the activation of overloaded method calls.

6.5 CLC Clear Dislplay

6.5.1 Usage

The clc function clears the current display. The syntax for its use is

clc

6.6 CLOCK Get Current Time

6.6.1 Usage

Returns the current date and time as a vector. The syntax for its use is

```
y = clock
```

where y has the following format:

y = [year month day hour minute seconds]

6.6.2 Example

```
Here is the time that this manual was last built:
```

```
--> clock
ans =

1.0e+03 *
2.0090 0.0090 0.0190 0.0220 0.0360 0.0305
```

6.7 CLOCKTOTIME Convert Clock Vector to Epoch Time

6.7.1 Usage

Given the output of the clock command, this function computes the epoch time, i.e, the time in seconds since January 1,1970 at 00:00:00 UTC. This function is most useful for calculating elapsed times using the clock, and should be accurate to less than a millisecond (although the true accuracy depends on accuracy of the argument vector). The usage for clocktotime is

```
y = clocktotime(x)
where x must be in the form of the output of clock, that is
x = [year month day hour minute seconds]
```

6.7.2 Example

Here is an example of using clocktotime to time a delay of 1 second

```
--> x = clock
x =
   1.0e+03 *
    2.0090
              0.0090
                         0.0190
                                    0.0220
                                              0.0360
                                                         0.0306
--> sleep(1)
--> y = clock
y =
   1.0e+03 *
    2.0090
              0.0090
                         0.0190
                                    0.0220
                                              0.0360
                                                        0.0316
--> clocktotime(y) - clocktotime(x)
ans =
    1.0010
```

6.8 COMPUTER Computer System FreeMat is Running On

6.8.1 Usage

Returns a string describing the name of the system FreeMat is running on. The exact value of this string is subject to change, although the 'MAC' and 'PCWIN' values are probably fixed.

```
str = computer
```

Currently, the following return values are defined

- 'PCWIN' MS Windows
- 'MAC' Mac OS X
- 'UNIX' All others

6.9 DIARY Create a Log File of Console

6.9.1 Usage

The diary function controls the creation of a log file that duplicates the text that would normally appear on the console. The simplest syntax for the command is simply:

```
diary
```

which toggles the current state of the diary command. You can also explicitly set the state of the diary command via the syntax

```
\begin{array}{c} \text{diary off} \\ \text{or} \\ \\ \text{diary on} \end{array}
```

To specify a filename for the log (other than the default of diary), you can use the form:

```
diary filename
or
   diary('filename')
```

which activates the diary with an output filename of filename. Note that the diary command is thread specific, but that the output is appended to a given file. That means that if you call diary with the same filename on multiple threads, their outputs will be intermingled in the log file (just as on the console). Because the diary state is tied to individual threads, you cannot retrieve the current diary state using the get(0,'Diary') syntax from MATLAB. Instead, you must call the diary function with no inputs and one output:

```
state = diary
```

which returns a logical 1 if the output of the current thread is currently going to a diary, and a logical 0 if not.

6.10 DOCLI Start a Command Line Interface

6.10.1 Usage

The docli function is the main function that you interact with when you run FreeMat. I am not sure why you would want to use it, but hey - its there if you want to use it.

6.11 EDIT Open Editor Window

6.11.1 Usage

Brings up the editor window. The arguments of edit function are names of files for editing:

edit file1 file2 file3

6.12 EDITOR Open Editor Window

6.12.1 Usage

Brings up the editor window. The editor function takes no arguments:

editor

6.13 ERRORCOUNT Retrieve the Error Counter for the Interpreter

6.13.1 Usage

This routine retrieves the internal counter for the interpreter, and resets it to zero. The general syntax for its use is

count = errorcount

6.14 ETIME Elapsed Time Function

6.14.1 Usage

The etime calculates the elapsed time between two clock vectors x1 and x2. The syntax for its use is

y = etime(x1, x2)

where x1 and x2 are in the clock output format

x = [year month day hour minute seconds]

6.14.2 Example

Here we use etime as a substitute for tic and toc

```
--> x1 = clock;
--> sleep(1);
--> x2 = clock;
--> etime(x2,x1);
```

6.15 EVAL Evaluate a String

6.15.1 Usage

The eval function evaluates a string. The general syntax for its use is

```
eval(s)
```

where **s** is the string to evaluate. If **s** is an expression (instead of a set of statements), you can assign the output of the **eval** call to one or more variables, via

```
x = eval(s)
[x,y,z] = eval(s)
```

Another form of eval allows you to specify an expression or set of statements to execute if an error occurs. In this form, the syntax for eval is

```
eval(try_clause, catch_clause),
```

or with return values,

```
x = eval(try_clause,catch_clause)
[x,y,z] = eval(try_clause,catch_clause)
```

These later forms are useful for specifying defaults. Note that both the try_clause and catch_clause must be expressions, as the equivalent code is

```
try
  [x,y,z] = try_clause
catch
  [x,y,z] = catch_clause
end
```

so that the assignment must make sense in both cases.

6.15.2 Example

Here are some examples of eval being used.

```
--> eval('a = 32')
a =
32
--> b = eval('a')
b =
32
The primary use of the eval statement is to enable construction of expressions at run time.
--> s = ['b = a' ' + 2']
b = a + 2
--> eval(s)
b =
34
Here we demonstrate the use of the catch-clause to provide a default value
--> a = 32
a =
32
--> b = eval('a','1')
b =
32
--> b = eval('z', 'a+1')
b =
33
```

Note that in the second case, **b** takes the value of 33, indicating that the evaluation of the first expression failed (because **z** is not defined).

6.16 EVALIN Evaluate a String in Workspace

6.16.1 Usage

The evalin function is similar to the eval function, with an additional argument up front that indicates the workspace that the expressions are to be evaluated in. The various syntaxes for evalin are:

```
evalin(workspace,expression)
x = evalin(workspace,expression)
[x,y,z] = evalin(workspace,expression)
evalin(workspace,try_clause,catch_clause)
x = evalin(workspace,try_clause,catch_clause)
[x,y,z] = evalin(workspace,try_clause,catch_clause)
```

The argument workspace must be either 'caller' or 'base'. If it is 'caller', then the expression is evaluated in the caller's work space. That does not mean the caller of evalin, but the caller of the current function or script. On the other hand if the argument is 'base', then the expression is evaluated in the base work space. See eval for details on the use of each variation.

6.17 EXIT Exit Program

6.17.1 Usage

The usage is

exit

Quits FreeMat. This script is a simple synonym for quit.

6.18 FEVAL Evaluate a Function

6.18.1 Usage

The feval function executes a function using its name. The syntax of feval is

```
[y1, y2, ..., yn] = feval(f, x1, x2, ..., xm)
```

where f is the name of the function to evaluate, and xi are the arguments to the function, and yi are the return values.

Alternately, f can be a function handle to a function (see the section on function handles for more information).

Finally, FreeMat also supports f being a user defined class in which case it will atttempt to invoke the subsref method of the class.

6.18.2 Example

Here is an example of using feval to call the cos function indirectly.

```
--> feval('cos',pi/4)
ans =
0.7071
```

Now, we call it through a function handle

```
--> c = @cos
c =
@cos
--> feval(c,pi/4)
ans =
    0.7071
Here we construct an inline object (which is a user-defined class) and use feval to call it
--> afunc = inline('cos(t)+sin(t)','t')
afunc =
  inline function object
  f(t) = cos(t) + sin(t)
--> feval(afunc,pi)
ans =
   -1.0000
--> afunc(pi)
ans =
   -1.0000
```

In both cases, (the feval call and the direct invokation), FreeMat calls the subsref method of the class, which computes the requested function.

6.19 FILESEP Directory Separation Character

6.19.1 Usage

The filesep routine returns the character used to separate directory names on the current platform (basically, a forward slash for Windows, and a backward slash for all other OSes). The syntax is simple:

```
x = filesep
```

6.20 HELP Help

6.20.1 Usage

Displays help on a function available in FreeMat. The help function takes one argument:

```
help topic
```

where topic is the topic to look for help on. For scripts, the result of running help is the contents of the comments at the top of the file. If FreeMat finds no comments, then it simply displays the function declaration.

6.21 HELPWIN Online Help Window

6.21.1 Usage

Brings up the online help window with the FreeMat manual. The helpwin function takes no arguments:

```
helpwin helpwin FunctionName
```

6.22 JITCONTROL Control the Just In Time Compiler

6.22.1 Usage

The jitcontrol functionality in FreeMat allows you to control the use of the Just In Time (JIT) compiler. Starting in FreeMat version 4, the JIT compiler is enabled by default on all platforms where it is successfully built. The JIT compiler should significantly improve the performance of loop intensive, scalar code. As development progresses, more and more functionality will be enabled under the JIT. In the mean time (if you use the GUI version of FreeMat) you can use the JIT chat window to get information on why your code was JIT compiled (or not).

```
do_jit_test.m
function test_val = do_jit_test(test_name)
printf('Running %s without JIT...',test_name);
jitcontrol off
tic; A1 = feval(test_name); nojit = toc;
jitcontrol on
% Run it twice to remove the compile time
tic; A2 = feval(test_name); wjit = toc;
tic; A2 = feval(test_name); wjit = toc;
printf('Speedup is %g...',nojit/wjit);
test_val = issame(A1,A2);
if (test_val)
  printf('PASS\n');
else
  printf('FAIL\n');
end
    jit_test001.m
function A = jit_test001
  A = zeros(1,100000);
  for i=1:100000; A(i) = i; end;
```

```
jit_test002.m
function A = jit\_test002
  A = zeros(512);
  for i=1:512;
    for j=1:512;
       A(i,j) = i-j;
  end
    jit_test003.m
function A = jit\_test003
  A = zeros(512);
  for i=1:512
    for j=1:512
      k = i-j;
      if ((k < 5) \&\& (k>-5))
         A(i,j) = k;
      end
    end
  end
    jit_test004.m
function A = jit\_test004
  A = zeros(512);
  for i=1:512
    for j=1:512
      k = i-j;
      if ((k < 5) \&\& (k>-5))
         A(i,j) = k;
      else
         A(i,j) = i+j;
      end
    end
  end
    jit_test005.m
function A = jit\_test005
  A = zeros(1,1000);
  for i=1:1000
    for m=1:100
      if (i > 50)
        k = 55;
      elseif (i > 40)
        k = 45;
      elseif (i > 30)
        k = 35;
      else
```

```
k = 15;
      end
    end
    A(i) = k;
  end
    jit_test006.m
function A = jit_test006
  A = zeros(1000);
 m = 0;
  for i=1:1000;
    for j=1:1000;
     A(i,j) = i-j;
      m = i;
    end
  \quad \text{end} \quad
  A = m;
    jit_test007.m
function A = jit_test007
 B = ones(1,100000);
  j = 0;
 for i=1:100000
    j = j + B(1,i);
  end
  A = j;
    jit_test008.m
function A = jit_test008
  A = zeros(1,10000);
  for i=1:10010;
    A(i) = i;
  end
    jit_test009.m
function A = jit_test009
 B = ones(1,10000);
  A = 0;
  for k=1:10000
    A = A + B(k);
  end
    jit_test010.m
function A = jit_test010
 B = 1:100000;
  A = zeros(1,100000);
  for i=1:100000
```

```
A(i) = B(i);
  end
    jit_test011.m
function A = jit_test011
  A = zeros(1,100000);
  B = 5;
  for i=1:100000
   C = B + i;
    A(i) = C;
  end
    jit_test012.m
function A = jit_test012
  A = zeros(400);
  for i=1:500
    for j=1:500;
      A(i,j) = i-j;
  end
    jit_test013.m
function A = jit_test013
  A = zeros(512);
  for i=1:512
    for j=1:512
     A(i,j) = abs(i-j);
  end
    jit_test014.m
function A = jit_test014
 N = 500;
  A = zeros(N,N);
  for i=1:N;
    for j=1:N;
     A(j,i) = abs(i-j);
    end
  end
    jit_test015.m
function A = jit_test015
  A = 0;
  for i=0:200000
   A = A + abs(sin(i/200000*pi));
  end
```

```
jit_test016.m
function A = jit\_test016
 A = 0;
  for i=0:200000
   A = A + abs(cos(i/200000*pi));
  end
   jit_test017.m
function A = jit_test017
 A = 0;
 for j=1:100
   B = j;
   for i=1:10000
     A = A + B;
    end
  end
   jit_test018.m
function A = jit\_test018
  A = 0;
  for i=1.2:4000.2
   A = A + i;
  end
   jit_test019.m
function A = jit_test019
 A = 150000;
 C = 0;
  for b=1:A
   C = C + b;
  end
  A = C;
   jit_test020.m
function a = jit_test020
  a = zeros(1,10000);
  for i=1:10000;
   a(i) = sec(i/10000);
  end
   jit_test021.m
function A = jit_test021
  A = zeros(100,100);
  for i=1:(100*100)
   A(i) = i;
  end
```

```
jit_test022.m
function A = jit_test022
  A = 1:1000000;
 B = 0;
 for i=1:1000000;
    B = B + A(i);
  end
 A = B;
    jit_test023.m
function A = jit_test023
  A = zeros(1,100000);
  for i=1:100000;
    A(i) = i/5.0;
  end
    jit_test024.m
function A = jit_test024
  A = zeros(1,10000);
  for j=1:10
    for i=1:10000;
      A(i) = tjit_sum(A(i),i);
     end;
  end;
function y = tjit_sum(a,b)
 y = a + tjit_double(b);
function y = tjit_double(a)
 y = a*2;
```

6.23 MFILENAME Name of Current Function

6.23.1 Usage

Returns a string describing the name of the current function. For M-files this string will be the complete filename of the function. This is true even for subfunctions. The syntax for its use is

```
y = mfilename
```

6.24 PATH Get or Set FreeMat Path

6.24.1 Usage

The path routine has one of the following syntaxes. In the first form

```
x = path
```

path simply returns the current path. In the second, the current path is replaced by the argument string 'thepath'

```
path('thepath')
```

In the third form, a new path is appended to the current search path

```
path(path,'newpath')
```

In the fourth form, a new path is prepended to the current search path

```
path('newpath',path)
```

In the final form, the path command prints out the current path

path

6.25 PATHSEP Path Directories Separation Character

6.25.1 Usage

The pathsep routine returns the character used to separate multiple directories on a path string for the current platform (basically, a semicolon for Windows, and a regular colon for all other OSes). The syntax is simple:

```
x = pathsep
```

6.26 PATHTOOL Open Path Setting Tool

6.26.1 Usage

Brings up the pathtool dialog. The pathtool function takes no arguments:

```
pathtool
```

6.27 PCODE Convert a Script or Function to P-Code

6.27.1 Usage

Writes out a script or function as a P-code function. The general syntax for its use is:

```
pcode fun1 fun2 ...
```

The compiled functions are written to the current directory.

6.28 PROFILER Control Profiling

6.28.1 Usage

The profile function allows you to control the FreeMat profiler. It has two modes of operation. The first is to enable-disable the profiler. To turn on profiling:

```
profiler on
```

to turn off profiling, use

```
profiler off
```

Note that regardless of the state of the profiler, only functions and scripts are profiled. Commands entered on the command line are not profiled. To see information that has accumulated in a profile, you use the variant of the command:

```
profiler list symbol1 symbol2 ...
```

where symbol1, symbol2 are the functions or scripts on which profiling information is desired. If you want to see current profile status issue a profile command with no arguments.

profiler

6.29 QUIET Control the Verbosity of the Interpreter

6.29.1 Usage

The quiet function controls how verbose the interpreter is when executing code. The syntax for the function is

```
quiet flag
```

where flag is one of

- 'normal' normal output from the interpreter
- 'quiet' only intentional output (e.g. printf calls and disp calls) is printed. The output of expressions that are not terminated in semicolons are not printed.
- 'silent' nothing is printed to the output.

The quiet command also returns the current quiet flag.

6.30 QUIT Quit Program

6.30.1 Usage

The quit statement is used to immediately exit the FreeMat application. The syntax for its use is quit

6.31 REHASH Rehash Directory Caches

6.31.1 Usage

Usually, FreeMat will automatically determine when M Files have changed, and pick up changes you have made to M files. Sometimes, you have to force a refresh. Use the rehash command for this purpose. The syntax for its use is

rehash

6.32 RESCAN Rescan M Files for Changes

6.32.1 Usage

Usually, FreeMat will automatically determine when M Files have changed, and pick up changes you have made to M files. Sometimes, you have to force a refresh. Use the **rescan** command for this purpose. The syntax for its use is

rescan

6.33 ROOTPATH Set FreeMat Root Path

6.33.1 Usage

In order to function properly, FreeMat needs to know where to find the toolbox directory as well as the help directory. These directories are located on what is known as the root path. Normally, FreeMat should know where these directories are located. However under some circumstances (usually when FreeMat is installed into a non-default location), it may be necessary to indicate a different root path location, or to specify a particular one. Note that on the Mac OS platform, FreeMat is installed as a bundle, and will use the toolbox that is installed in the bundle regardless of the setting for rootpath. For Linux, FreeMat will typically use /usr/local/share/FreeMat-<Version>/ for the root path. Installations from source code will generally work, but binary installations (e.g., from an RPM) may need to have the rootpath set.

The rootpath function has two forms. The first form takes no arguments and allows you to browse to the rootpath directory

rootpath

The second form will set a rootpath directly from the command line

rootpath(path)

where path is the full path to where the toolbox and help directories are located. For example, rootpath('/usr/share/FreeMat-4.0'). Changes to rootpath are persistent (you do not need to run it every time you start FreeMat).

6.34 SIMKEYS Simulate Keypresses from the User

6.34.1 Usage

This routine simulates keystrokes from the user on FreeMat. The general syntax for its use is

```
otext = simkeys(text)
```

where text is a string to simulate as input to the console. The output of the commands are captured and returned in the string otext. This is primarily used by the testing infrastructure.

6.35 SLEEP Sleep For Specified Number of Seconds

6.35.1 Usage

Suspends execution of FreeMat for the specified number of seconds. The general syntax for its use is

```
sleep(n),
```

where n is the number of seconds to wait.

6.36 SOURCE Execute an Arbitrary File

6.36.1 Usage

The source function executes the contents of the given filename one line at a time (as if it had been typed at the --> prompt). The source function syntax is

```
source(filename)
```

where filename is a string containing the name of the file to process.

6.36.2 Example

First, we write some commands to a file (note that it does not end in the usual .m extension):

```
source_test
a = 32;
b = a;
printf('a is %d and b is %d\n',a,b);
Now we source the resulting file.
--> clear a b
--> source source_test
a is 32 and b is 32
```

6.37 STARTUP Startup Script

6.37.1 Usage

Upon starting, FreeMat searches for a script names startup.m, and if it finds it, it executes it. This script can be in the current directory, or on the FreeMat path (set using setpath). The contents of startup.m must be a valid script (not a function).

6.38 TIC Start Stopwatch Timer

6.38.1 Usage

Starts the stopwatch timer, which can be used to time tasks in FreeMat. The tic takes no arguments, and returns no outputs. You must use toc to get the elapsed time. The usage is

tic

6.38.2 Example

Here is an example of timing the solution of a large matrix equation.

```
--> A = rand(100);

--> b = rand(100,1);

--> tic; c = A\b; toc

ans =

0.0020
```

6.39 TOC Stop Stopwatch Timer

6.39.1 Usage

Stop the stopwatch timer, which can be used to time tasks in FreeMat. The toc function takes no arguments, and returns no outputs. You must use toc to get the elapsed time. The usage is

toc

6.39.2 Example

Here is an example of timing the solution of a large matrix equation.

```
--> A = rand(100);

--> b = rand(100,1);

--> tic; c = A\b; toc

ans =

0.0170
```

6.40. TYPE TYPE 129

6.40 TYPE Type

6.40.1 Usage

Displays the content of a m-script file or an ascii file. The type function takes one argument:

```
type filename
type ('filename')
```

This command will first look for filename in FreeMat search path, if not found it will look for m-script file by adding '.m' to filename

6.41 VERSION The Current Version Number

6.41.1 Usage

The version function returns the current version number for FreeMat (as a string). The general syntax for its use is

```
v = version
```

6.41.2 Example

The current version of FreeMat is

```
--> version
```

ans =

4.0

6.42 VERSTRING The Current Version String

6.42.1 Usage

The verstring function returns the current version string for FreeMat. The general syntax for its use is

```
version = verstring
```

6.42.2 Example

The current version of FreeMat is

```
--> verstring
```

```
ans =
```

FreeMat v4.0

Chapter 7

Debugging FreeMat Code

7.1 DBAUTO Control Dbauto Functionality

7.1.1 Usage

The dbauto functionality in FreeMat allows you to debug your FreeMat programs. When dbauto is on, then any error that occurs while the program is running causes FreeMat to stop execution at that point and return you to the command line (just as if you had placed a keyboard command there). You can then examine variables, modify them, and resume execution using return. Alternately, you can exit out of all running routines via a retall statement. Note that errors that occur inside of try/catch blocks do not (by design) cause auto breakpoints. The dbauto function toggles the dbauto state of FreeMat. The syntax for its use is

```
dbauto(state)
where state is either
  dbauto('on')
to activate dbauto, or
  dbauto('off')
to deactivate dbauto. Alternately, you can use FreeMat's string-syntax equivalence and enter
  dbauto on
or
  dbauto off
to turn dbauto on or off (respectively). Entering dbauto with no arguments returns the current
state (either 'on' or 'off').
```

7.2 DBDELETE Delete a Breakpoint

7.2.1 Usage

The dbdelete function deletes a breakpoint. The syntax for the dbdelete function is dbdelete(num)

where num is the number of the breakpoint to delete.

7.3 DBDown Move Down One Debug Level

7.3.1 Usage

The dbdown function moves up one level in the debug hierarchy. The syntax for the dbdown function is

dbdown

7.4 DBLIST List Breakpoints

7.4.1 Usage

List the current set of breakpoints. The syntax for the dblist is simply dblist

7.5 DBSTEP Step N Statements

7.5.1 Usage

Step N statements during debug mode. The synax for this is either dbstep(N)

to step N statements, or

dbstep

to step one statement.

7.6 DBSTOP

7.6.1 Usage

Set a breakpoint. The syntax for this is:

dbstop(funcname,linenumber)

where function where we want to set the breakpoint, and linenumber is the line number.

7.7 DBUP Move Up One Debug Level

7.7.1 Usage

The dbup function moves up one level in the debug hierarchy. The syntax for the dbup function is dbup

7.8 FDUMP Dump Information on Function

7.8.1 Usage

Dumps information about a function (diagnostic information only)

fdump fname

Chapter 8

Sparse Matrix Support

8.1 EIGS Sparse Matrix Eigendecomposition

8.1.1 Usage

Computes the eigendecomsition of a sparse square matrix. The eigs function has several forms. The most general form is

where A is the matrix to analyze, k is the number of eigenvalues to compute and sigma determines which eigenvalues to solve for. Valid values for sigma are 'lm' - largest magnitude 'sm' - smallest magnitude 'la' - largest algebraic (for real symmetric problems) 'sa' - smallest algebraic (for real symmetric problems) 'lr' - largest real part 'sr' - smallest real part 'li' - largest imaginary part 'si' - smallest imaginary part scalar - find the eigenvalues closest to sigma. The returned matrix V contains the eigenvectors, and D stores the eigenvalues. The related form

```
d = eigs(A,k,sigma)
```

computes only the eigenvalues and not the eigenvectors. If sigma is omitted, as in the forms

$$[V,D] = eigs(A,k)$$

and

$$d = eigs(A,k)$$

then eigs returns the largest magnitude eigenvalues (and optionally the associated eigenvectors). As an even simpler form, the forms

$$[V,D] = eigs(A)$$

and

$$d = eigs(A)$$

then eigs returns the six largest magnitude eigenvalues of A and optionally the eigenvectors. The eigs function uses ARPACK to compute the eigenvectors and/or eigenvalues. Note that due to a limitation in the interface into ARPACK from FreeMat, the number of eigenvalues that are to be computed must be strictly smaller than the number of columns (or rows) in the matrix.

8.1.2 Example

Here is an example of using eigs to calculate eigenvalues of a matrix, and a comparison of the results with eig

```
--> a = sparse(rand(9));
--> eigs(a)
ans =
   4.2673 + 0.0000i
  -0.8372 + 0.0000i
  -0.7445 + 0.3406i
  -0.7445 - 0.3406i
   0.6653 - 0.2082i
   0.6653 + 0.2082i
--> eig(full(a))
ans =
   4.2673 + 0.0000i
  -0.8372 + 0.0000i
  -0.7445 + 0.3406i
  -0.7445 -
            0.3406i
   0.1634 + 0.4595i
   0.1634 - 0.4595i
   0.6653 + 0.2082i
   0.6653 - 0.2082i
   0.0479 + 0.0000i
Next, we exercise some of the variants of eigs:
--> eigs(a,4,'sm')
ans =
   0.0479 + 0.0000i
   0.1634 + 0.4595i
   0.1634 - 0.4595i
   0.6653 + 0.2082i
--> eigs(a,4,'lr')
ans =
```

```
4.2673 + 0.0000i

0.6653 - 0.2082i

0.6653 + 0.2082i

0.1634 - 0.4595i

--> eigs(a,4,'sr')

ans =

-0.8372 + 0.0000i

-0.7445 - 0.3406i

-0.7445 + 0.3406i

0.0479 + 0.0000i
```

8.2 FULL Convert Sparse Matrix to Full Matrix

8.2.1 Usage

Converts a sparse matrix to a full matrix. The syntax for its use is

```
y = full(x)
```

The type of x is preserved. Be careful with the function. As a general rule of thumb, if you can work with the full representation of a function, you probably do not need the sparse representation.

8.2.2 Example

Here we convert a full matrix to a sparse one, and back again.

```
--> a = [1,0,4,2,0;0,0,0,0;0,1,0,0,2]

a =

1 0 4 2 0
0 0 0 0 0
0 1 0 0 2

--> A = sparse(a)

A =

1 1 1
3 2 1
1 3 4
1 4 2
3 5 2
--> full(A)

ans =

1 0 4 2 0
```

0 0 0 0 0 0 0 1 0 0 2

8.3 SPARSE Construct a Sparse Matrix

8.3.1 Usage

Creates a sparse matrix using one of several formats. The first creates a sparse matrix from a full matrix

```
y = sparse(x).
```

The second form creates a sparse matrix containing all zeros that is of the specified size (the sparse equivalent of zeros).

```
y = sparse(m,n)
```

where m and n are integers. Just like the zeros function, the sparse matrix returned is of type float. The third form constructs a sparse matrix from the IJV syntax. It has two forms. The first version autosizes the sparse matrix

```
y = sparse(i,j,v)
```

while the second version uses an explicit size specification

```
y = sparse(i,j,v,m,n)
```

8.4 SPEYE Sparse Identity Matrix

8.4.1 Usage

Creates a sparse identity matrix of the given size. The syntax for its use is

```
y = speye(m,n)
```

which forms an m x n sparse matrix with ones on the main diagonal, or

```
y = speye(n)
```

which forms an $n \times n$ sparse matrix with ones on the main diagonal. The matrix type is a float single precision matrix.

8.4.2 Example

The following creates a 5000 by 5000 identity matrix, which would be difficult to do using sparse(eye(5000)) because of the large amount of intermediate storage required.

8.5 SPONES Sparse Ones Function

8.5.1 Usage

Returns a sparse float matrix with ones where the argument matrix has nonzero values. The general syntax for it is

```
y = spones(x)
```

where x is a matrix (it may be full or sparse). The output matrix y is the same size as x, has type float, and contains ones in the nonzero positions of x.

8.5.2 Examples

Here are some examples of the spones function

```
--> a = [1,0,3,0,5;0,0,2,3,0;1,0,0,0,1]

a =
    1 0 3 0 5
    0 0 2 3 0
    1 0 0 0 1

--> b = spones(a)

b =
    1 1 1
    1 2 1
    1 3 1
    1 4 1
```

```
151
--> full(b)
ans =
11111
00000
00000
```

8.6 SPRAND Sparse Uniform Random Matrix

8.6.1 Usage

Creates a sparse matrix with uniformly distributed random entries (on [0,1]). The syntax for its use is

```
y = sprand(x)
```

where x is a sparse matrix, where y is a sparse matrix that has random entries where x is nonzero. The second form specifies the size of the matrix and the density

```
y = sprand(m,n,density)
```

--> x = [1,0,0;0,0,1;1,0,0]

where m is the number of rows in the output, n is the number of columns in the output, and density (which is between 0 and 1) is the density of nonzeros in the resulting matrix. Note that for very high densities the actual density of the output matrix may differ from the density you specify. This difference is a result of the way the random entries into the matrix are generated. If you need a very dense random matrix, it is better to generate a full matrix and zero out the entries you do not need.

8.6.2 Examples

1 1 0.478912 3 1 0.039372

Here we seed **sprand** with a full matrix (to demonstrate how the structure of the output is determined by the input matrix when using the first form).

```
x = 100
001
100

--> y = sprand(x)

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recovering the same name. Use clear j to recovering the same name.
```

```
2 3 0.806381

--> full(y)

ans =

0.4789 0 0

0 0.8064

0.0394 0 0
```

The more generic version with a density of 0.001. On many systems the following is impossible using full matrices

```
--> y = sprand(10000,10000,.001);
Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t
Warning: Newly defined variable j shadows a function of the same name. Use clear j to recover access t
--> nnz(y)/10000^2
ans =
```

8.7 SPRANDN Sparse Normal Random Matrix

8.7.1 Usage

9.9946e-04

Creates a sparse matrix with normally distributed random entries (mean 0, sigma 1). The syntax for its use is

```
y = sprandn(x)
```

where x is a sparse matrix, where y is a sparse matrix that has random entries where x is nonzero. The second form specifies the size of the matrix and the density

```
y = sprandn(m,n,density)
```

where m is the number of rows in the output, n is the number of columns in the output, and density (which is between 0 and 1) is the density of nonzeros in the resulting matrix. Note that for very high densities the actual density of the output matrix may differ from the density you specify. This difference is a result of the way the random entries into the matrix are generated. If you need a very dense random matrix, it is better to generate a full matrix and zero out the entries you do not need.

8.7.2 Examples

Here we seed **sprandn** with a full matrix (to demonstrate how the structure of the output is determined by the input matrix when using the first form).

```
--> x = [1,0,0;0,0,1;1,0,0]
x =
1 0 0
```

```
0 0 1
 1 0 0
--> y = sprandn(x)
Warning: Newly defined variable i shadows a function of the same name. Use clear i to red
Warning: Newly defined variable j shadows a function of the same name. Use clear j to red
у =
 1 1 0.770419
 3 1 0.332694
2 3 -0.589851
--> full(y)
ans =
    0.7704
                             0
                   0
                       -0.5899
    0.3327
                   0
```

The more generic version with a density of 0.001. On many systems the following is impossible using full matrices

```
--> y = sprandn(10000,10000,.001);
Warning: Newly defined variable i shadows a function of the same name. Use clear i to recommon the same name.

--> nnz(y)/10000^2

ans =
```

9.9953e-04

8.8 SPY Visualize Sparsity Pattern of a Sparse Matrix

8.8.1 Usage

Plots the sparsity pattern of a sparse matrix. The syntax for its use is

```
spy(x)
```

which uses a default color and symbol. Alternately, you can use

```
spy(x,colspec)
```

where colspec is any valid color and symbol spec accepted by plot.

8.8.2 Example

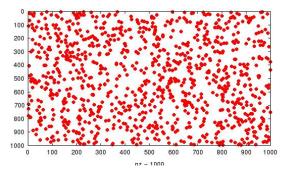
First, an example of a random sparse matrix.

```
--> y = sprand(1000, 1000, .001);
```

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t Warning: Newly defined variable j shadows a function of the same name. Use clear j to recover access t --> spy(y,'ro')

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t Warning: Newly defined variable j shadows a function of the same name. Use clear j to recover access t

which is shown here



Here is a sparse matrix with a little more structure. First we build a sparse matrix with block diagonal structure, and then use spy to visualize the structure.

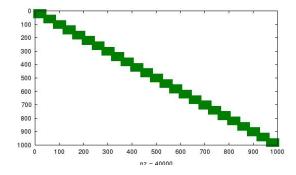
```
--> A = sparse(1000,1000);

--> for i=1:25; A((1:40) + 40*(i-1),(1:40) + 40*(i-1)) = 1; end;

--> spy(A,'gx')
```

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t Warning: Newly defined variable j shadows a function of the same name. Use clear j to recover access t

with the result shown here



Chapter 9

Mathematical Functions

9.1 ACOS Inverse Trigonometric Arccosine Function

9.1.1 Usage

Computes the acos function for its argument. The general syntax for its use is

$$y = acos(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the acos function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.1.2 Function Internals

Mathematically, the acos function is defined for all arguments x as

$$a\cos x \equiv \frac{pi}{2} + i\log\left(ix + \sqrt{1-x^2}\right).$$

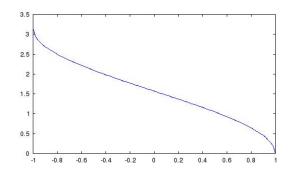
For real valued variables x in the range [-1,1], the function is computed directly using the standard C library's numerical acos function. For both real and complex arguments x, note that generally

$$a\cos(\cos(x)) \neq x$$
,

9.1.3 Example

The following code demonstates the acos function over the range [-1,1].

```
--> t = linspace(-1,1);
--> plot(t,acos(t))
```



9.2 ACOSD Inverse Cosine Degrees Function

9.2.1 Usage

Computes the inverse cosine of the argument, but returns the argument in degrees instead of radians (as is the case for acos. The syntax for its use is

```
y = acosd(x)
```

9.2.2 Examples

The inverse cosine of sqrt(2)/2 should be 45 degrees:

```
--> acosd(sqrt(2)/2)

ans =
   45.0000 + 0.0000i

and the inverse cosine of 0.5 should be 60 degrees:
--> acosd(0.5)

ans =
  60.0000 + 0.0000i
```

9.3 ACOSH Inverse Hyperbolic Cosine Function

9.3.1 Usage

Computes the inverse hyperbolic cosine of its argument. The general syntax for its use is

```
y = acosh(x)
```

where x is an n-dimensional array of numerical type.

9.3.2 Function Internals

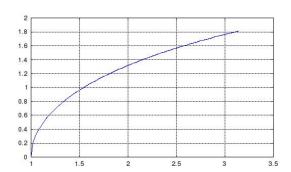
The acosh function is computed from the formula

$$\cosh^{-1}(x) = \log(x + (x^2 - 1)^0.5)$$

where the log (and square root) is taken in its most general sense.

9.3.3 Examples

Here is a simple plot of the inverse hyperbolic cosine function



9.4 ACOT Inverse Cotangent Function

9.4.1 Usage

Computes the inverse cotangent of its argument. The general syntax for its use is

$$y = acot(x)$$

where x is an n-dimensional array of numerical type.

9.4.2 Function Internals

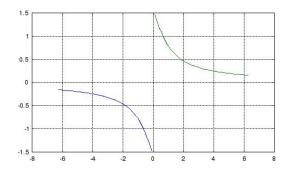
The acot function is computed from the formula

$$\cot^{-1}(x) = \tan^{-1}\left(\frac{1}{x}\right)$$

9.4.3 Examples

Here is a simple plot of the inverse cotangent function

```
--> x1 = -2*pi:pi/30:-0.1;
--> x2 = 0.1:pi/30:2*pi;
--> plot(x1,acot(x1),x2,acot(x2)); grid('on');
```



9.5 ACOTD Inverse Cotangent Degrees Function

9.5.1 Usage

Computes the inverse cotangent of its argument in degrees. The general syntax for its use is

$$y = acotd(x)$$

where x is an n-dimensional array of numerical type.

9.6 ACOTH Inverse Hyperbolic Cotangent Function

9.6.1 Usage

Computes the inverse hyperbolic cotangent of its argument. The general syntax for its use is

$$y = acoth(x)$$

where x is an n-dimensional array of numerical type.

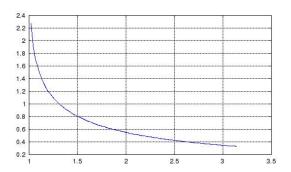
9.6.2 Function Internals

The acoth function is computed from the formula

$$\coth^{-1}(x) = \tanh^{-1}\left(\frac{1}{x}\right)$$

9.6.3 Examples

Here is a simple plot of the inverse hyperbolic cotangent function



9.7 ACSC Inverse Cosecant Function

9.7.1 Usage

Computes the inverse cosecant of its argument. The general syntax for its use is

$$y = acsc(x)$$

where x is an n-dimensional array of numerical type.

9.7.2 Function Internals

The acosh function is computed from the formula

$$\csc^{-1}(x) = \sin^{-1}\left(\frac{1}{x}\right)$$

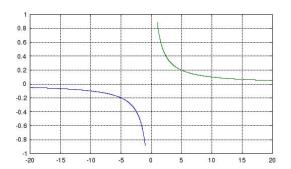
9.7.3 Examples

Here is a simple plot of the inverse cosecant function

```
--> x1 = -10:.01:-1.01;

--> x2 = 1.01:.01:10;

--> plot(x1,acsc(x1),x2,acsc(x2)); grid('on');
```



9.8 ACSCD Inverse Cosecant Degrees Function

9.8.1 Usage

Computes the inverse cosecant of the argument, but returns the argument in degrees instead of radians (as is the case for acsc. The syntax for its use is

```
y = acscd(x)
```

9.8.2 Examples

The inverse cosecant of 2/sqrt(2) should be 45 degrees:

9.9 ACSCH Inverse Hyperbolic Cosecant Function

9.9.1 Usage

Computes the inverse hyperbolic cosecant of its argument. The general syntax for its use is

```
y = acsch(x)
```

where x is an n-dimensional array of numerical type.

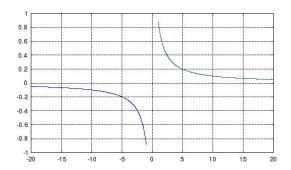
9.9.2 Function Internals

The acsch function is computed from the formula

$$\operatorname{csch}^{-1}(x) = \sinh^{-1}\left(\frac{1}{x}\right)$$

9.9.3 Examples

Here is a simple plot of the inverse hyperbolic cosecant function



9.10 ANGLE Phase Angle Function

9.10.1 Usage

Compute the phase angle in radians of a complex matrix. The general syntax for its use is

where c is an n-dimensional array of numerical type.

9.10.2 Function Internals

For a complex number x, its polar representation is given by

$$x = |x|e^{j\theta}$$

and we can compute

$$\theta = \operatorname{atan2}(\Im x, \Re x)$$

9.10.3 Example

Here are some examples of the use of angle in the polar decomposition of a complex number.

```
--> x = 3+4*i

x =

3.0000 + 4.0000i

--> a = abs(x)

a =

5

--> t = angle(x)

t =

0.9273

--> a*exp(i*t)

ans =

3.0000 + 4.0000i
```

M version contributor: M.W. Vogel 01-30-06

9.11 ASEC Inverse Secant Function

9.11.1 Usage

Computes the inverse secant of its argument. The general syntax for its use is

$$y = asec(x)$$

where x is an n-dimensional array of numerical type.

9.11.2 Function Internals

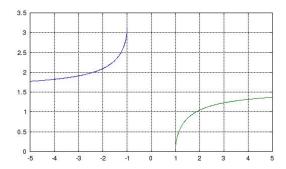
The acosh function is computed from the formula

$$\sec^{-1}(x) = \cos^{-1}\left(\frac{1}{x}\right)$$

9.11.3 Examples

Here is a simple plot of the inverse secant function

```
--> x1 = -5:.01:-1;
--> x2 = 1:.01:5;
--> plot(x1,asec(x1),x2,asec(x2)); grid('on');
```



9.12 ASECD Inverse Secant Degrees Function

9.12.1 Usage

Computes the inverse secant of the argument, but returns the argument in degrees instead of radians (as is the case for asec. The syntax for its use is

```
y = asecd(x)
```

9.12.2 Examples

```
The inverse secant of 2/sqrt(2) should be 45 degrees:
```

```
--> asecd(2/sqrt(2))

ans =
    45.0000 + 0.0000i

and the inverse secant of 2 should be 60 degrees:
--> asecd(2)

ans =
    60.0000 + 0.0000i
```

9.13 ASECH Inverse Hyperbolic Secant Function

9.13.1 Usage

Computes the inverse hyperbolic secant of its argument. The general syntax for its use is

```
y = asech(x)
```

where x is an n-dimensional array of numerical type.

9.13.2 Function Internals

The asech function is computed from the formula

$$\operatorname{sech}^{-1}(x) = \cosh^{-1}\left(\frac{1}{x}\right)$$

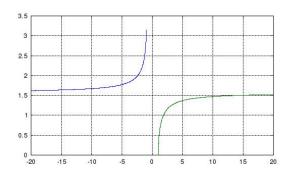
9.13.3 Examples

Here is a simple plot of the inverse hyperbolic secant function

$$--> x1 = -20:.01:-1;$$

 $--> x2 = 1:.01:20;$

--> plot(x1,imag(asech(x1)),x2,imag(asech(x2))); grid('on');



9.14 ASIN Inverse Trigonometric Arcsine Function

9.14.1 Usage

Computes the asin function for its argument. The general syntax for its use is

$$y = asin(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the asin function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.14.2 Function Internals

Mathematically, the \mathtt{asin} function is defined for all arguments \mathtt{x} as

$$a\sin x \equiv -i\log\left(ix + \sqrt{1 - x^2}\right).$$

For real valued variables x in the range [-1,1], the function is computed directly using the standard C library's numerical asin function. For both real and complex arguments x, note that generally

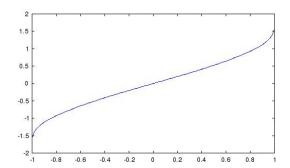
$$a\sin(\sin(x)) \neq x$$
,

due to the periodicity of sin(x).

9.14.3 Example

The following code demonstates the asin function over the range [-1,1].

```
--> t = linspace(-1,1);
--> plot(t,asin(t))
```



9.15 ASIND Inverse Sine Degrees Function

9.15.1 Usage

Computes the inverse sine of the argument, but returns the argument in degrees instead of radians (as is the case for asin). The syntax for its use is

```
y = asind(x)
```

9.15.2 Examples

```
The inverse sine of sqrt(2)/2 should be 45 degrees:
```

```
--> asind(sqrt(2)/2)

ans =
    45.0000

and the inverse sine of 0.5 should be 30 degrees:
--> asind(0.5)

ans =
    30.0000
```

9.16 ASINH Inverse Hyperbolic Sine Function

9.16.1 Usage

Computes the inverse hyperbolic sine of its argument. The general syntax for its use is

$$y = asinh(x)$$

where x is an n-dimensional array of numerical type.

9.16.2 Function Internals

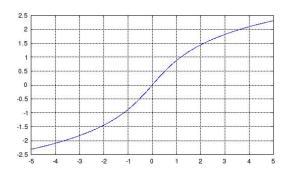
The asinh function is computed from the formula

$$\sinh^{-1}(x) = \log(x + (x^2 + 1)^0.5)$$

where the log (and square root) is taken in its most general sense.

9.16.3 Examples

Here is a simple plot of the inverse hyperbolic sine function



9.17 ATAN Inverse Trigonometric Arctangent Function

9.17.1 Usage

Computes the atan function for its argument. The general syntax for its use is

$$y = atan(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the atan function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.17.2 Function Internals

Mathematically, the atan function is defined for all arguments x as

$$atanx \equiv \frac{i}{2} (\log(1 - ix) - \log(ix + 1)).$$

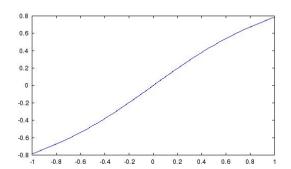
For real valued variables x, the function is computed directly using the standard C library's numerical atan function. For both real and complex arguments x, note that generally

$$atan(tan(x)) \neq x$$
,

due to the periodicity of tan(x).

9.17.3Example

The following code demonstates the atan function over the range [-1,1].



ATAN2 Inverse Trigonometric 4-Quadrant Arctangent 9.18**Function**

9.18.1Usage

Computes the atan2 function for its argument. The general syntax for its use is

$$z = atan2(y,x)$$

where x and y are n-dimensional arrays of numerical type. Integer types are promoted to the double type prior to calculation of the atan2 function. The size of the output depends on the size of x and y. If x is a scalar, then z is the same size as y, and if y is a scalar, then z is the same size as x. The type of the output is equal to the type of -y/x.

9.18.2**Function Internals**

The function is defined (for real values) to return an angle between -pi and pi. The signs of x and y are used to find the correct quadrant for the solution. For complex arguments, the two-argument arctangent is computed via

$$atan2(y,x) \equiv -i\log\left(\frac{x+iy}{\sqrt{x^2+y^2}}\right)$$

For real valued arguments x,y, the function is computed directly using the standard C library's numerical atan2 function. For both real and complex arguments x, note that generally

$$atan2(sin(x), cos(x)) \neq x$$
,

due to the periodicities of cos(x) and sin(x).

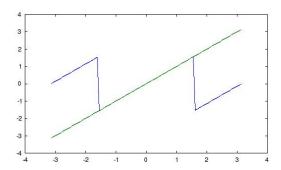
9.18.3 Example

The following code demonstates the difference between the atan2 function and the atan function over the range [-pi,pi].

```
--> x = linspace(-pi,pi);

--> sx = sin(x); cx = cos(x);

--> plot(x,atan(sx./cx),x,atan2(sx,cx))
```



Note how the two-argument atan2 function (green line) correctly "unwraps" the phase of the angle, while the atan function (red line) wraps the angle to the interval [-\pi/2,\pi/2].

9.19 ATAND Inverse Tangent Degrees Function

9.19.1 Usage

Computes the inverse tangent of the argument, but returns the argument in degrees instead of radians (as is the case for atan. The syntax for its use is

```
y = atand(x)
```

9.19.2 Examples

The inverse tangent of 1 should be 45 degrees:

```
--> atand(1)
ans =
45
```

9.20 ATANH Inverse Hyperbolic Tangent Function

9.20.1 Usage

Computes the inverse hyperbolic tangent of its argument. The general syntax for its use is

$$y = atanh(x)$$

where x is an n-dimensional array of numerical type.

9.20.2 Function Internals

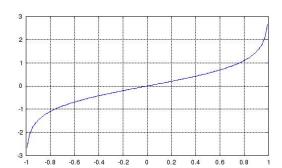
The atanh function is computed from the formula

$$\tanh^{-1}(x) = \frac{1}{2}\log\left(\frac{1+x}{1-x}\right)$$

where the log (and square root) is taken in its most general sense.

9.20.3 Examples

Here is a simple plot of the inverse hyperbolic tangent function



9.21 COS Trigonometric Cosine Function

9.21.1 Usage

Computes the cos function for its argument. The general syntax for its use is

$$y = cos(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the cos function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.21.2 Function Internals

Mathematically, the cos function is defined for all real valued arguments x by the infinite summation

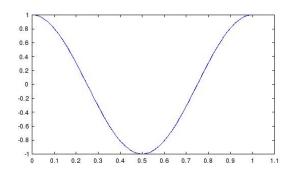
$$\cos x \equiv \sum_{n=0}^{\infty} \frac{(-1)^n x^{2n}}{(2n)!}.$$

For complex valued arguments z, the cosine is computed via

 $\cos z \equiv \cos \Re z \cosh \Im z - \sin \Re z \sinh \Im z.$

9.21.3 Example

The following piece of code plots the real-valued cos(2 pi x) function over one period of [0,1]:



9.22 COSD Cosine Degrees Function

9.22.1 Usage

Computes the cosine of the argument, but takes the argument in degrees instead of radians (as is the case for cos). The syntax for its use is

$$y = cosd(x)$$

9.22.2 Examples

The cosine of 45 degrees should be sqrt(2)/2

$$--> cosd(45)$$

ans = 0.7071

and the cosine of 60 degrees should be 0.5:

9.23 COSH Hyperbolic Cosine Function

9.23.1 Usage

Computes the hyperbolic cosine of the argument. The syntax for its use is

$$y = cosh(x)$$

9.23.2 Function Internals

The cosh function is computed from the formula

$$\cosh(x) = \frac{e^x + e^{-x}}{2}$$

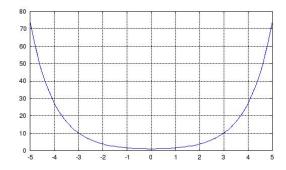
For x complex, it follows that

$$\cosh(a+i*b) = \frac{e^a(\cos(b)+i*\sin(b)) + e^{-a}(\cos(-b)+i*\sin(-b))}{2}$$

9.23.3 Examples

Here is a simple plot of the hyperbolic cosine function

```
--> x = linspace(-5,5);
--> plot(x,cosh(x)); grid('on');
```



9.24 COT Trigonometric Cotangent Function

9.24.1 Usage

Computes the cot function for its argument. The general syntax for its use is

$$y = cot(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the cot function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.24.2 Function Internals

Mathematically, the cot function is defined for all arguments x as

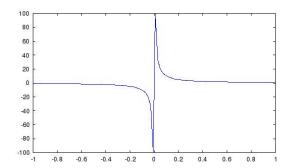
$$\cot x \equiv \frac{\cos x}{\sin x}$$

For complex valued arguments z, the cotangent is computed via

$$\cot z \equiv \frac{\cos 2\Re z + \cosh 2\Im z}{\sin 2\Re z + i \sinh 2\Im z}.$$

9.24.3 Example

The following piece of code plots the real-valued cot(x) function over the interval [-1,1]:



9.25 COTD Cotangent Degrees Function

9.25.1 Usage

Computes the cotangent of the argument, but takes the argument in degrees instead of radians (as is the case for cot). The syntax for its use is

$$y = cotd(x)$$

9.25.2 Examples

```
The cotangent of 45 degrees should be 1.
```

```
--> cotd(45)
ans =
1
```

9.26 COTD Cotangent Degrees Function

9.26.1 Usage

Computes the cotangent of the argument, but takes the argument in degrees instead of radians (as is the case for cot). The syntax for its use is

```
y = cotd(x)
```

9.26.2 Examples

The cotangent of 45 degrees should be 1.

```
--> cotd(45)
ans =
1
```

9.27 COTH Hyperbolic Cotangent Function

9.27.1 Usage

Computes the hyperbolic cotangent of the argument. The syntax for its use is

```
y = coth(x)
```

9.27.2 Function Internals

The coth function is computed from the formula

$$\coth(x) = \frac{1}{\tanh(x)}$$

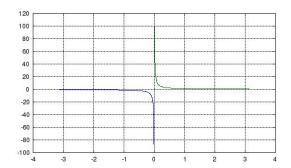
9.27.3 Examples

Here is a simple plot of the hyperbolic cotangent function

```
--> x1 = -pi+.01:.01:-.01;

--> x2 = .01:.01:pi-.01;

--> plot(x1,coth(x1),x2,coth(x2)); grid('on');
```



9.28 CROSS Cross Product of Two Vectors

9.28.1 Usage

Computes the cross product of two vectors. The general syntax for its use is

$$c = cross(a,b)$$

where a and b are 3-element vectors.

9.29 CSC Trigonometric Cosecant Function

9.29.1 Usage

Computes the csc function for its argument. The general syntax for its use is

$$y = csc(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the csc function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.29.2 Function Internals

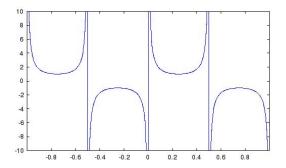
Mathematically, the csc function is defined for all arguments as

$$\csc x \equiv \frac{1}{\sin x}.$$

9.29.3 Example

The following piece of code plots the real-valued csc(2 pi x) function over the interval of [-1,1]:

--> t = linspace(-1,1,1000); --> plot(t,csc(2*pi*t)) --> axis([-1,1,-10,10]);



9.30 CSCD Cosecant Degrees Function

9.30.1 Usage

Computes the cosecant of the argument, but takes the argument in degrees instead of radians (as is the case for csc). The syntax for its use is

$$y = cscd(x)$$

9.31 CSCH Hyperbolic Cosecant Function

9.31.1 Usage

Computes the hyperbolic cosecant of the argument. The syntax for its use is

$$y = csch(x)$$

9.31.2 Function Internals

The csch function is computed from the formula

$$\operatorname{csch}(x) = \frac{1}{\sinh(x)}$$

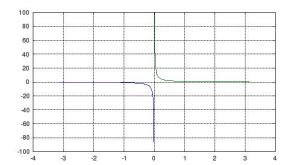
9.31.3 Examples

Here is a simple plot of the hyperbolic cosecant function

```
--> x1 = -pi+.01:.01:-.01;

--> x2 = .01:.01:pi-.01;

--> plot(x1,csch(x1),x2,csch(x2)); grid('on');
```



9.32 DEG2RAD Convert From Degrees To Radians

9.32.1 Usage

Converts the argument from degrees to radians. The syntax for its use is

$$y = deg2rad(x)$$

where x is a numeric array. Conversion is done by simply multiplying x by pi/180.

9.32.2 Example

How many radians in a circle:

ans =

9.33 ERF Error Function

9.33.1 Usage

Computes the error function for real arguments. The erf function takes only a single argument y = erf(x)

where x is either a float or double array. The output vector y is the same size (and type) as x.

9.33.2 Function Internals

The erf function is defined by the integral:

$$\operatorname{erf}(x) = \frac{2}{\sqrt{\pi}} \int_0^x e^{-t^2} dt,$$

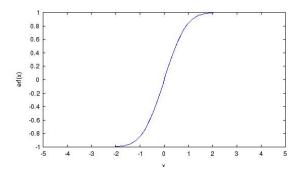
and is the integral of the normal distribution.

9.33.3 Example

Here is a plot of the erf function over the range [-5,5].

```
--> x = linspace(-5,5);
--> y = erf(x);
--> plot(x,y); xlabel('x'); ylabel('erf(x)');
```

which results in the following plot.



9.34 ERFC Complimentary Error Function

9.34.1 Usage

Computes the complimentary error function for real arguments. The erfc function takes only a single argument

$$y = erfc(x)$$

where x is either a float or double array. The output vector y is the same size (and type) as x.

9.34.2 Function Internals

The erfc function is defined by the integral:

$$\operatorname{erfc}(x) = \frac{2}{\sqrt{\pi}} \int_{x}^{\infty} e^{-t^{2}} dt,$$

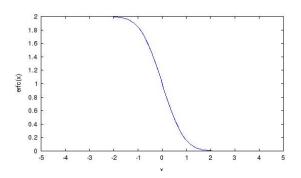
and is the integral of the normal distribution.

9.34.3 Example

Here is a plot of the erfc function over the range [-5,5].

```
--> x = linspace(-5,5);
--> y = erfc(x);
--> plot(x,y); xlabel('x'); ylabel('erfc(x)');
```

which results in the following plot.



9.35 EXP Exponential Function

9.35.1 Usage

Computes the exp function for its argument. The general syntax for its use is

$$y = exp(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the exp function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.35.2 Function Internals

Mathematically, the exp function is defined for all real valued arguments x as

$$\exp x \equiv e^x,$$

where

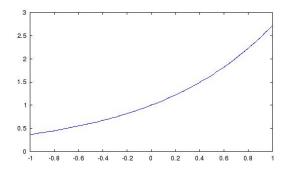
$$e = \sum_{0}^{\infty} \frac{1}{k!}$$

and is approximately 2.718281828459045 (returned by the function e). For complex values z, the famous Euler formula is used to calculate the exponential

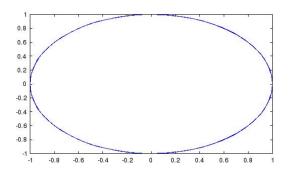
$$e^z = e^{|z|} \left[\cos \Re z + i \sin \Re z \right]$$

9.35.3 Example

The following piece of code plots the real-valued exp function over the interval [-1,1]:



In the second example, we plot the unit circle in the complex plane e^{i} 2 pi x} for x in [-1,1].



9.36 EXPM1 Exponential Minus One Function

9.36.1 Usage

Computes exp(x)-1 function accurately for x small. The syntax for its use is

$$y = expm1(x)$$

where x is an n-dimensional array of numerical type.

9.37 FIX Round Towards Zero

9.37.1 Usage

Rounds the argument array towards zero. The syntax for its use is

$$y = fix(x)$$

where x is a numeric array. For positive elements of x, the output is the largest integer smaller than x. For negative elements of x the output is the smallest integer larger than x. For complex x, the operation is applied separately to the real and imaginary parts.

9.37.2 Example

Here is a simple example of the fix operation on some values

$$-->$$
 a = [-1.8,pi,8,-pi,-0.001,2.3+0.3i]

a =

Columns 1 to 3

Columns 4 to 6

--> fix(a)

ans =

Columns 1 to 3

Columns 4 to 6

9.38 GAMMA Gamma Function

9.38.1 Usage

Computes the gamma function for real arguments. The gamma function takes only a single argument y = gamma(x)

where x is either a float or double array. The output vector y is the same size (and type) as x.

9.38.2 Function Internals

The gamma function is defined by the integral:

$$\Gamma(x) = \int_0^\infty e^{-t} t^{x-1} dt$$

The gamma function obeys the interesting relationship

$$\Gamma(x) = (x-1)\Gamma(x-1),$$

and for integer arguments, is equivalent to the factorial function.

9.38.3 Example

Here is a plot of the gamma function over the range [-5,5].

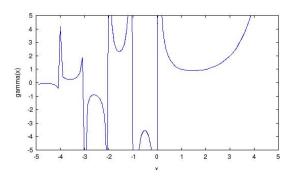
```
--> x = linspace(-5,5);

--> y = gamma(x);

--> plot(x,y); xlabel('x'); ylabel('gamma(x)');

--> axis([-5,5,-5,5]);
```

which results in the following plot.



9.39 GAMMALN Log Gamma Function

9.39.1 Usage

Computes the natural log of the gamma function for real arguments. The gammaln function takes only a single argument

```
y = gammaln(x)
```

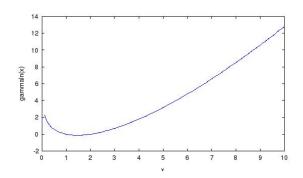
where x is either a float or double array. The output vector y is the same size (and type) as x.

9.39.2 Example

Here is a plot of the gammaln function over the range [-5,5].

```
--> x = linspace(0,10);
--> y = gammaln(x);
--> plot(x,y); xlabel('x'); ylabel('gammaln(x)');
```

which results in the following plot.



9.40 IDIV Integer Division Operation

9.40.1 Usage

Computes the integer division of two arrays. The syntax for its use is

$$y = idiv(a,b)$$

where a and b are arrays or scalars. The effect of the idiv is to compute the integer division of b into a.

9.40.2 Example

The following examples show some uses of idiv arrays.

```
--> idiv(27,6)

ans =
4

--> idiv(4,-2)

ans =
-2

--> idiv(15,3)

ans =
5
```

9.41 LOG Natural Logarithm Function

9.41.1 Usage

Computes the log function for its argument. The general syntax for its use is

$$y = log(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the log function. Output y is of the same size as the input x. For strictly positive, real inputs, the output type is the same as the input. For negative and complex arguments, the output is complex.

9.41.2 Function Internals

Mathematically, the log function is defined for all real valued arguments x by the integral

$$\log x \equiv \int_{1}^{x} \frac{dt}{t}.$$

For complex-valued arguments, z, the complex logarithm is defined as

$$\log z \equiv \log|z| + i \arg z,$$

where arg is the complex argument of z.

9.41.3 Example

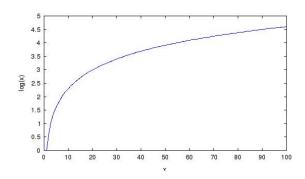
The following piece of code plots the real-valued log function over the interval [1,100]:

```
--> x = linspace(1,100);

--> plot(x,log(x))

--> xlabel('x');

--> ylabel('log(x)');
```



9.42 LOG10 Base-10 Logarithm Function

9.42.1 Usage

Computes the log10 function for its argument. The general syntax for its use is

$$y = log10(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the log10 function. Output y is of the same size as the input x. For strictly positive, real inputs, the output type is the same as the input. For negative and complex arguments, the output is complex.

9.42.2 Example

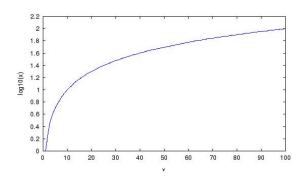
The following piece of code plots the real-valued log10 function over the interval [1,100]:

```
--> x = linspace(1,100);

--> plot(x,log10(x))

--> xlabel('x');

--> ylabel('log10(x)');
```



9.43 LOG1P Natural Logarithm of 1+P Function

9.43.1 Usage

Computes the log function for one plus its argument. The general syntax for its use is

$$y = log1p(x)$$

where x is an n-dimensional array of numerical type.

9.44 LOG2 Base-2 Logarithm Function

9.44.1 Usage

Computes the log2 function for its argument. The general syntax for its use is

$$y = log2(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the log2 function. Output y is of the same size as the input x. For strictly positive, real inputs, the output type is the same as the input. For negative and complex arguments, the output is complex.

9.44.2 Example

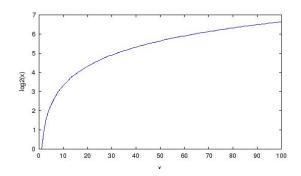
The following piece of code plots the real-valued log2 function over the interval [1,100]:

```
--> x = linspace(1,100);

--> plot(x,log2(x))

--> xlabel('x');

--> ylabel('log2(x)');
```



9.45 MOD Modulus Operation

9.45.1 Usage

Computes the modulus of an array. The syntax for its use is

```
y = mod(x,n)
```

where x is matrix, and n is the base of the modulus. The effect of the mod operator is to add or subtract multiples of n to the vector x so that each element x_i is between 0 and n (strictly). Note that n does not have to be an integer. Also, n can either be a scalar (same base for all elements of x), or a vector (different base for each element of x).

Note that the following are defined behaviors:

- $1. \mod(x,0) = x@$
- $2. \mod(x,x) = 0@$
- 3. mod(x,n)@ has the same sign as n for all other cases.

9.45.2 Example

The following examples show some uses of mod arrays.

```
--> mod(18,12)
ans =
6
```

```
--> mod(6,5)

ans =
1

--> mod(2*pi,pi)

ans =
0

Here is an example of using mod to determine if integers are even or odd:
--> mod([1,3,5,2],2)

ans =
1 1 1 0

Here we use the second form of mod, with each element using a separate base.
--> mod([9 3 2 0],[1 0 2 2])

ans =
0 3 0 0
```

9.46 MPOWER Matrix Power Function

9.46.1 Usage

Computes the matrix power operator for two arrays. It is an M-file version of the ^ operator. The syntax for its use is

```
y = mpower(a,b)
```

where $y=a^b$. See the matrixpower documentation for more details on what this function actually does.

9.47 POWER Element-wise Power Function

9.47.1 Usage

Computes the element-wise power operator for two arrays. It is an M-file version of the \cdot operator. The syntax for its use is

```
y = power(a,b)
```

where y=a.^b. See the dotpower documentation for more details on what this function actually does.

9.48 RAD2DEG Radians To Degrees Conversion Function

9.48.1 Usage

Converts the argument array from radians to degrees. The general syntax for its use is

```
y = rad2deg(x)
```

Note that the output type will be the same as the input type, and that complex arguments are allowed. The output is not wrapped to [0,360).

9.48.2 Examples

```
Some known conversion factors
```

```
--> rad2deg(1) % one radian is about 57 degrees

ans =
    57.2958

--> rad2deg(pi/4) % should be 45 degrees

ans =
    45

--> rad2deg(2*pi) % Note that this is 360 not 0 degrees

ans =
    360
```

9.49 REM Remainder After Division

9.49.1 Usage

Computes the remainder after division of an array. The syntax for its use is

```
y = rem(x,n)
```

where x is matrix, and n is the base of the modulus. The effect of the rem operator is to add or subtract multiples of n to the vector x so that each element x_i is between 0 and n (strictly). Note that n does not have to be an integer. Also, n can either be a scalar (same base for all elements of x), or a vector (different base for each element of x).

Note that the following are defined behaviors:

- 1. rem(x,0) = nan@
- 2. rem(x,x) = 0@ for nonzero x
- 3. rem(x,n) @ has the same sign as x for all other cases.

Note that rem and mod return the same value if x and n are of the same sign. But differ by n if x and y have different signs.

9.49.2 Example

```
The following examples show some uses of rem arrays.
```

```
--> rem(18,12)
ans =
 6
--> rem(6,5)
ans =
 1
--> rem(2*pi,pi)
ans =
 0
Here is an example of using rem to determine if integers are even or odd:
--> rem([1,3,5,2],2)
ans =
 1 1 1 0
Here we use the second form of rem, with each element using a separate base.
--> rem([9 3 2 0],[1 0 2 2])
ans =
          0 NaN
                         0
```

9.50 SEC Trigonometric Secant Function

9.50.1 Usage

Computes the sec function for its argument. The general syntax for its use is

$$y = sec(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the sec function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.50.2 Function Internals

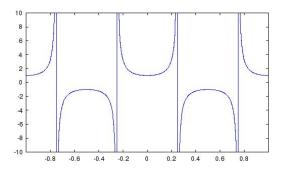
Mathematically, the sec function is defined for all arguments as

$$\sec x \equiv \frac{1}{\cos x}.$$

9.50.3 Example

The following piece of code plots the real-valued sec(2 pi x) function over the interval of [-1,1]:

```
--> t = linspace(-1,1,1000);
--> plot(t,sec(2*pi*t))
--> axis([-1,1,-10,10]);
```



9.51 SECD Secant Degrees Function

9.51.1 Usage

Computes the secant of the argument, but takes the argument in degrees instead of radians (as is the case for sec). The syntax for its use is

$$y = secd(x)$$

9.52 SECH Hyperbolic Secant Function

9.52.1 Usage

Computes the hyperbolic secant of the argument. The syntax for its use is

$$y = sech(x)$$

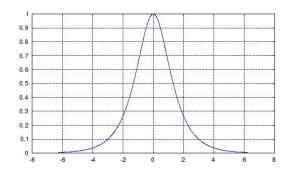
9.52.2 Function Internals

The sech function is computed from the formula

$$\operatorname{sech}(x) = \frac{1}{\cosh(x)}$$

9.52.3 Examples

Here is a simple plot of the hyperbolic secant function



9.53 SIN Trigonometric Sine Function

9.53.1 Usage

Computes the sin function for its argument. The general syntax for its use is

$$y = \sin(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the sin function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.53.2 Function Internals

Mathematically, the sin function is defined for all real valued arguments x by the infinite summation

$$\sin x \equiv \sum_{n=1}^{\infty} \frac{(-1)^{n-1} x^{2n-1}}{(2n-1)!}.$$

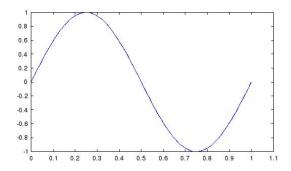
For complex valued arguments z, the sine is computed via

 $\sin z \equiv \sin \Re z \cosh \Im z - i \cos \Re z \sinh \Im z.$

9.53.3 Example

The following piece of code plots the real-valued sin(2 pi x) function over one period of [0,1]:

```
--> x = linspace(0,1);
--> plot(x,sin(2*pi*x))
```



9.54 SIND Sine Degrees Function

9.54.1 Usage

Computes the sine of the argument, but takes the argument in degrees instead of radians (as is the case for cos). The syntax for its use is

$$y = sind(x)$$

9.54.2 Examples

The sine of 45 degrees should be sqrt(2)/2

```
--> sind(45)
```

ans = 0.7071

and the sine of 30 degrees should be 0.5:

--> sind(30)

ans = 0.5000

9.55 SINH Hyperbolic Sine Function

9.55.1 Usage

Computes the hyperbolic sine of the argument. The syntax for its use is

$$y = sinh(x)$$

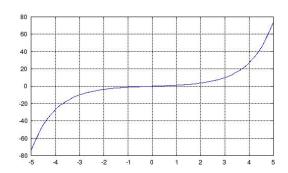
9.55.2 Function Internals

The sinh function is computed from the formula

$$\sinh(x) = \frac{e^x - e^{-x}}{2}$$

9.55.3 Examples

Here is a simple plot of the hyperbolic sine function



9.56 SQRT Square Root of an Array

9.56.1 Usage

Computes the square root of the argument matrix. The general syntax for its use is

$$y = sqrt(x)$$

where x is an N-dimensional numerical array.

9.56.2 Example

Here are some examples of using sqrt

ans =

9.57 TAN Trigonometric Tangent Function

9.57.1 Usage

Computes the tan function for its argument. The general syntax for its use is

$$y = tan(x)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the tan function. Output y is of the same size and type as the input x, (unless x is an integer, in which case y is a double type).

9.57.2 Function Internals

Mathematically, the tan function is defined for all real valued arguments x by the infinite summation

$$\tan x \equiv x + \frac{x^3}{3} + \frac{2x^5}{15} + \cdots,$$

or alternately by the ratio

$$\tan x \equiv \frac{\sin x}{\cos x}$$

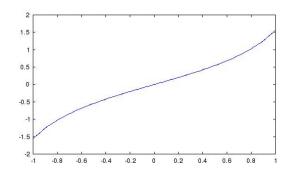
For complex valued arguments z, the tangent is computed via

$$\tan z \equiv \frac{\sin 2\Re z + i \sinh 2\Im z}{\cos 2\Re z + \cosh 2\Im z}.$$

9.57.3 Example

The following piece of code plots the real-valued tan(x) function over the interval [-1,1]:

```
--> t = linspace(-1,1);
--> plot(t,tan(t))
```



9.58 TAND Tangent Degrees Function

9.58.1 Usage

Computes the tangent of the argument, but takes the argument in degrees instead of radians (as is the case for cos). The syntax for its use is

```
y = tand(x)
```

9.58.2 Examples

The tangent of 45 degrees should be 1

```
--> tand(45)
ans =
1.0000
```

9.59 TANH Hyperbolic Tangent Function

9.59.1 Usage

Computes the hyperbolic tangent of the argument. The syntax for its use is

```
y = tanh(x)
```

9.59.2 Function Internals

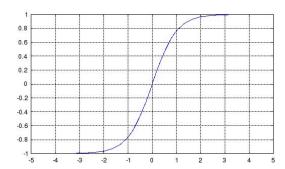
The tanh function is computed from the formula

$$\tanh(x) = \frac{\sinh(x)}{\cosh(x)}$$

9.59.3 Examples

Here is a simple plot of the hyperbolic tangent function

```
--> x = linspace(-5,5);
--> plot(x,tanh(x)); grid('on');
```



Chapter 10

Base Constants

10.1 E Euler Constant (Base of Natural Logarithm)

10.1.1 Usage

Returns a double (64-bit floating point number) value that represents Euler's constant, the base of the natural logarithm. Typical usage

y = e

This value is approximately 2.718281828459045.

10.1.2 Example

The following example demonstrates the use of the ${\tt e}$ function.

```
--> e
ans =
2.7183
--> log(e)
ans =
1
```

10.2 EPS Double Precision Floating Point Relative Machine Precision Epsilon

10.2.1 Usage

Returns eps, which quantifies the relative machine precision of floating point numbers (a machine specific quantity). The syntax for eps is:

```
y = eps
y = eps('double')
y = eps(X)
```

First form returns eps for double precision values. For most typical processors, this value is approximately 2^-52 , or 2.2204e-16. Second form return eps for class double or single. Third form returns distance to the next value greater than X.

10.2.2 Example

The following example demonstrates the use of the eps function, and one of its numerical consequences.

```
--> eps

ans =
    2.2204e-16

--> 1.0+eps

ans =
    1.0000

--> eps(1000.)

ans =
    1.1369e-13
```

10.3 FALSE Logical False

10.3.1 Usage

Returns a logical 0. The syntax for its use is

```
y = false
```

10.4 FEPS Single Precision Floating Point Relative Machine Precision Epsilon

10.4.1 Usage

Returns feps, which quantifies the relative machine precision of floating point numbers (a machine specific quantity). The syntax for feps is:

```
y = feps
```

which returns feps for single precision values. For most typical processors, this value is approximately 2^-24, or 5.9604e-8.

10.4.2 Example

The following example demonstrates the use of the feps function, and one of its numerical consequences.

```
--> feps

ans =
   1.1921e-07

--> 1.0f+eps

ans =
   1
```

10.5 I-J Square Root of Negative One

10.5.1 Usage

Returns a complex value that represents the square root of -1. There are two functions that return the same value:

```
y = i and y = j.
```

This allows either i or j to be used as loop indices. The returned value is a 32-bit complex value.

10.5.2 Example

The following examples demonstrate a few calculations with i.

```
--> i

ans =
    0.0000 + 1.0000i

--> i^2

ans =
    -1.0000 + 0.0000i

The same calculations with j:
--> j

ans =
```

```
0.0000 + 1.0000i

--> j^2

ans =
    -1.0000 + 0.0000i

Here is an example of how i can be used as a loop index and then recovered as the square root of
-1.
--> accum = 0; for i=1:100; accum = accum + i; end; accum

ans =
    5050

--> i

ans =
    100
--> clear i
--> i

ans =
    0.0000 + 1.0000i
```

10.6 INF Infinity Constant

10.6.1 Usage

Returns a value that represents positive infinity for both 32 and 64-bit floating point values. There are several forms for the Inf function. The first form returns a double precision Inf.

```
y = inf
```

The next form takes a class name that can be either 'double'

```
y = inf('double')
or 'single':
  y = inf('single')
```

With a single parameter it generates a square matrix of infs.

```
y = inf(n)
```

Alternatively, you can specify the dimensions of the array via

```
y = \inf(m,n,p,...)
```

or

$$y = \inf([m,n,p,...])$$

Finally, you can add a classname of either 'single' or 'double'.

10.6.2 Function Internals

The infinity constant has several interesting properties. In particular:

$$\begin{array}{ll} \infty \times 0 &= \operatorname{NaN} \\ \infty \times a &= \infty \operatorname{forall} a > 0 \\ \infty \times a &= -\infty \operatorname{forall} a < 0 \\ \infty / \infty &= \operatorname{NaN} \\ \infty / 0 &= \infty \end{array}$$

Note that infinities are not preserved under type conversion to integer types (see the examples below).

10.6.3 Example

The following examples demonstrate the various properties of the infinity constant.

```
--> inf*0

ans =
    NaN

--> inf*2

ans =
    Inf

--> inf*-2

ans =
    -Inf

--> inf/inf

ans =
    NaN

--> inf/0

ans =
    Inf
```

```
--> inf/nan
ans =
NaN
Note that infinities are preserved under type conversion to floating point types (i.e., float, double, complex and dcomplex types), but not integer types.
--> uint32(inf)
ans =
4294967295
```

10.7 PI Constant Pi

10.7.1 Usage

--> complex(inf)

ans =

Returns a double (64-bit floating point number) value that represents pi (ratio between the circumference and diameter of a circle...). Typical usage

```
y = pi
```

This value is approximately 3.141592653589793.

10.7.2 Example

The following example demonstrates the use of the pi function.

10.8 TEPS Type-based Epsilon Calculation

10.8.1 Usage

Returns eps for double precision arguments and feps for single precision arguments. The syntax for teps is

```
y = teps(x)
```

The teps function is most useful if you need to compute epsilon based on the type of the array.

10.8.2 Example

The following example demonstrates the use of the teps function, and one of its numerical consequences.

```
--> teps(float(3.4))

ans =
1.1921e-07

--> teps(complex(3.4+i*2))

ans =
2.2204e-16
```

10.9 TRUE Logical TRUE

10.9.1 Usage

Returns a logical 1. The syntax for its use is

```
y = true
```

Chapter 11

Elementary Functions

11.1 ABS Absolute Value Function

11.1.1 Usage

Returns the absolute value of the input array for all elements. The general syntax for its use is

```
y = abs(x)
```

where x is an n-dimensional array of numerical type. The output is the same numerical type as the input, unless the input is complex or dcomplex. For complex inputs, the absolute value is a floating point array, so that the return type is float. For dcomplex inputs, the absolute value is a double precision floating point array, so that the return type is double.

11.1.2 Example

The following demonstrates the abs applied to a complex scalar.

```
--> abs(3+4*i)

ans =
5

The abs function applied to integer and real values:
--> abs([-2,3,-4,5])

ans =
2 3 4 5

For a double-precision complex array,
--> abs([2.0+3.0*i,i])

ans =
3.6056
1.0000
```

11.2 ALL All True Function

11.2.1 Usage

Reduces a logical array along a given dimension by testing for all logical 1s. The general syntax for its use is

```
y = all(x,d)
```

where x is an n-dimensions array of logical type. The output is of logical type. The argument d is optional, and denotes the dimension along which to operate. The output y is the same size as x, except that it is singular along the operated direction. So, for example, if x is a 3 x 3 x 4 array, and we all operation along dimension d=2, then the output is of size 3 x 1 x 4.

11.2.2 Function Internals

The output is computed via

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \min_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

If d is omitted, then the minimum is taken over all elements of x.

11.2.3 Example

The following piece of code demonstrates various uses of the all function

```
--> A = [1,0,0;1,0,0;0,0,1]
```

A =

1 0 0

1 0 0

0 0 1

We start by calling all without a dimension argument, in which case it defaults to testing all values of A

```
--> all(A)
```

ans =

0 0 0

The all function is useful in expressions also.

ans =

1 1 1

Next, we apply the all operation along the rows.

```
--> all(A,2)
ans =
0
0
```

11.3 ANY Any True Function

11.3.1 Usage

Reduces a logical array along a given dimension by testing for any logical 1s. The general syntax for its use is

$$y = any(x,d)$$

where x is an n-dimensions array of logical type. The output is of logical type. The argument d is optional, and denotes the dimension along which to operate. The output y is the same size as x, except that it is singular along the operated direction. So, for example, if x is a 3 x 3 x 4 array, and we any operation along dimension d=2, then the output is of size 3 x 1 x 4.

11.3.2 Function Internals

The output is computed via

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \max_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

If d is omitted, then the summation is taken along the first non-singleton dimension of x.

11.3.3 Example

The following piece of code demonstrates various uses of the summation function

```
--> A = [1,0,0;1,0,0;0,0,1]

A =
1 0 0
1 0 0
0 0 1
```

We start by calling any without a dimension argument, in which case it defaults to the first nonsingular dimension (in this case, along the columns or d = 1).

```
--> any(A)
ans =
1 0 1
```

Next, we apply the any operation along the rows.

```
--> any(A,2)
ans =
1
1
1
```

11.4 CEIL Ceiling Function

11.4.1 Usage

Computes the ceiling of an n-dimensional array elementwise. The ceiling of a number is defined as the smallest integer that is larger than or equal to that number. The general syntax for its use is

```
y = ceil(x)
```

where x is a multidimensional array of numerical type. The ceil function preserves the type of the argument. So integer arguments are not modified, and float arrays return float arrays as outputs, and similarly for double arrays. The ceil function is not defined for complex or dcomplex types.

11.4.2 Example

The following demonstrates the ceil function applied to various (numerical) arguments. For integer arguments, the ceil function has no effect:

```
--> ceil(3)

ans =
3

--> ceil(-3)

ans =
-3

Next, we take the ceil of a floating point value:
--> ceil(float(3.023))

ans =
4

--> ceil(float(-2.341))

ans =
-2
```

Note that the return type is a float also. Finally, for a double type:

```
--> ceil(4.312)

ans =
5

--> ceil(-5.32)

ans =
-5
```

11.5 CONJ Conjugate Function

11.5.1 Usage

Returns the complex conjugate of the input array for all elements. The general syntax for its use is

```
y = conj(x)
```

where x is an n-dimensional array of numerical type. The output is the same numerical type as the input. The conj function does nothing to real and integer types.

11.5.2 Example

The following demonstrates the complex conjugate applied to a complex scalar.

```
--> conj(3+4*i)

ans =
    3.0000 - 4.0000i

The conj function has no effect on real arguments:
--> conj([2,3,4])

ans =
    2 3 4

For a double-precision complex array,
--> conj([2.0+3.0*i,i])

ans =
    2.0000 - 3.0000i 0.0000 - 1.0000i
```

11.6 CUMPROD Cumulative Product Function

11.6.1 Usage

Computes the cumulative product of an n-dimensional array along a given dimension. The general syntax for its use is

```
y = cumprod(x,d)
```

where x is a multidimensional array of numerical type, and d is the dimension along which to perform the cumulative product. The output y is the same size of x. Integer types are promoted to int32. If the dimension d is not specified, then the cumulative sum is applied along the first non-singular dimension.

11.6.2 Function Internals

The output is computed via

$$y(m_1, \dots, m_{d-1}, j, m_{d+1}, \dots, m_p) = \prod_{k=1}^{j} x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p).$$

11.6.3 Example

The default action is to perform the cumulative product along the first non-singular dimension.

```
--> A = [5,1,3;3,2,1;0,3,1]

A =
5 1 3
3 2 1
0 3 1

--> cumprod(A)

ans =
5 1 3
15 2 3
```

To compute the cumulative product along the columns:

```
--> cumprod(A,2)
ans =
5 5 15
3 6 6
```

0 6 3

The cumulative product also works along arbitrary dimensions

```
--> B(:,:,1) = [5,2;8,9];
--> B(:,:,2) = [1,0;3,0]
B =
(:,:,1) =
5 2
8 9
(:,:,2) =
1 0
3 0
--> cumprod(B,3)
ans =
(:,:,1) =
 5 2
 8 9
(:,:,2) =
 5 0
24 0
```

11.7 CUMSUM Cumulative Summation Function

11.7.1 Usage

Computes the cumulative sum of an n-dimensional array along a given dimension. The general syntax for its use is

```
y = cumsum(x,d)
```

where x is a multidimensional array of numerical type, and d is the dimension along which to perform the cumulative sum. The output y is the same size of x. Integer types are promoted to int32. If the dimension d is not specified, then the cumulative sum is applied along the first non-singular dimension.

11.7.2 Function Internals

The output is computed via

$$y(m_1, \dots, m_{d-1}, j, m_{d+1}, \dots, m_p) = \sum_{k=1}^{j} x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p).$$

(:,:,1) = 5 2

11.7.3 Example

The default action is to perform the cumulative sum along the first non-singular dimension.

```
--> A = [5,1,3;3,2,1;0,3,1]
A =
5 1 3
3 2 1
0 3 1
--> cumsum(A)
ans =
5 1 3
8 3 4
8 6 5
To compute the cumulative sum along the columns:
--> cumsum(A,2)
ans =
5 6 9
3 5 6
0 3 4
The cumulative sum also works along arbitrary dimensions
--> B(:,:,1) = [5,2;8,9];
--> B(:,:,2) = [1,0;3,0]
B =
(:,:,1) =
5 2
8 9
(:,:,2) =
1 0
 3 0
--> cumsum(B,3)
ans =
```

8 9

(:,:,2) = 6 2

11 9

11.8 DEAL Multiple Simultaneous Assignments

11.8.1 Usage

When making a function call, it is possible to assign multiple outputs in a single call, (see, e.g., max for an example). The deal call allows you to do the same thing with a simple assignment. The syntax for its use is

$$[a,b,c,...] = deal(expr)$$

where expr is an expression with multiple values. The simplest example is where expr is the dereference of a cell array, e.g. expr <-- A{:}. In this case, the deal call is equivalent to

$$a = A\{1\}; b = A\{2\}; C = A\{3\};$$

Other expressions which are multivalued are structure arrays with multiple entries (non-scalar), where field dereferencing has been applied.

11.9 DEC2HEX Convert Decimal Number to Hexadecimal

11.9.1 Usage

Converts an integer value into its hexadecimal representation. The syntax for its use is

```
y = dec2hex(x)
```

where x is an integer (and is promoted to a 64-bit integer if it is not). The returned value y is a string containing the hexadecimal representation of that integer. If you require a minimum length for the hexadecimal representation, you can specify an optional second argument

```
y = dec2hex(x,n)
```

where n indicates the minimum number of digits in the representation.

11.9.2 Example

Here are some simple examples:

```
--> dec2hex(1023)
```

ans =

3FF

376F86D

--> dec2hex(58128493)
ans =

11.10 DIFF Difference Function

11.10.1 Usage

y=diff(x)
y=diff(x,k)
y=diff(x,k,dim)

Produce difference of successive vector elements.

If x is a vector of length n, diff (x) is the vector of first differences

$$[x_2-x_1,...,x_n-x_{n-1}].$$

If x is a matrix, diff (x) is the matrix of column differences along the first non-singleton dimension.

The second argument is optional. If supplied, diff (x,k), where k is a nonnegative integer, returns the k-th differences. It is possible that k is larger than then first non-singleton dimension of the matrix. In this case, diff continues to take the differences along the next non-singleton dimension.

The dimension along which to take the difference can be explicitly stated with the optional variable dim. In this case the k-th order differences are calculated along this dimension. In the case where k exceeds size (x, dim) then an empty matrix is returned.

11.11 DOT Dot Product Function

11.11.1 Usage

Computes the scalar dot product of its two arguments. The general syntax for its use is

$$y = dot(x,z)$$

where x and z are numerical vectors of the same length. If x and z are multi-dimensional arrays of the same size, then the dot product is taken along the first non-singleton dimension. You can also specify the dimension to take the dot product along using the alternate form

$$y = dot(x,z,dim)$$

where dim specifies the dimension to take the dot product along.

11.12 FLOOR Floor Function

11.12.1 Usage

Computes the floor of an n-dimensional array elementwise. The floor of a number is defined as the smallest integer that is less than or equal to that number. The general syntax for its use is

```
y = floor(x)
```

where x is a multidimensional array of numerical type. The floor function preserves the type of the argument. So integer arguments are not modified, and float arrays return float arrays as outputs, and similarly for double arrays. The floor function is not defined for complex types.

11.12.2 Example

The following demonstrates the floor function applied to various (numerical) arguments. For integer arguments, the floor function has no effect:

```
--> floor(3)

ans =
3

--> floor(-3)

ans =
-3

Next, we take the floor of a floating point value:
--> floor(3.023)

ans =
3
--> floor(-2.341)

ans =
-3
```

11.13 GETFIELD Get Field Contents

11.13.1 Usage

Given a structure or structure array, returns the contents of the specified field. The first version is for scalar structures, and has the following syntax

```
y = getfield(x,'fieldname')
```

and is equivalent to y = x.fieldname where x is a scalar (1 x 1) structure. If x is not a scalar structure, then y is the first value, i.e., it is equivalent to y = x(1).fieldname. The second form allows you to specify a subindex into a structure array, and has the following syntax

```
y = getfield(x, {m,n}, 'fieldname')
```

and is equivalent to y = x(m,n).fieldname. You can chain multiple references together using this syntax.

11.14 HEX2DEC Convert Hexadecimal Numbers To Decimal

11.14.1 Usage

Converts a hexadecimal number (encoded as a string matrix) into integers. The syntax for its use is

y = hex2dec(x)

where x is a character matrix where each row represents an integer in hexadecimal form. The output is of type Double.

11.14.2 Examples

```
--> hex2dec('3ff')

ans =
1023

Or for a more complex example
--> hex2dec(['0ff';'2de';'123'])

ans =
255
734
291
```

11.15 IMAG Imaginary Function

11.15.1 Usage

Returns the imaginary part of the input array for all elements. The general syntax for its use is

```
y = imag(x)
```

where x is an n-dimensional array of numerical type. The output is the same numerical type as the input, unless the input is complex or dcomplex. For complex inputs, the imaginary part is a floating point array, so that the return type is float. For dcomplex inputs, the imaginary part is a double precision floating point array, so that the return type is double. The imag function returns zeros for real and integer types.

11.15.2 Example

The following demonstrates imag applied to a complex scalar.

```
--> imag(3+4*i)
ans =
4
```

The imaginary part of real and integer arguments is a vector of zeros, the same type and size of the argument.

```
--> imag([2,4,5,6])

ans =
0 0 0 0

For a double-precision complex array,
--> imag([2.0+3.0*i,i])

ans =
3 1
```

11.16 MAX Maximum Function

11.16.1 Usage

Computes the maximum of an array along a given dimension, or alternately, computes two arrays (entry-wise) and keeps the smaller value for each array. As a result, the max function has a number of syntaxes. The first one computes the maximum of an array along a given dimension. The first general syntax for its use is either

```
[y,n] = \max(x,[],d)
```

where x is a multidimensional array of numerical type, in which case the output y is the maximum of x along dimension d. The second argument n is the index that results in the maximum. In the event that multiple maxima are present with the same value, the index of the first maximum is used. The second general syntax for the use of the max function is

```
[y,n] = \max(x)
```

In this case, the maximum is taken along the first non-singleton dimension of x. For complex data types, the maximum is based on the magnitude of the numbers. NaNs are ignored in the calculations. The third general syntax for the use of the \max function is as a comparison function for pairs of arrays. Here, the general syntax is

```
y = max(x,z)
```

where \mathbf{x} and \mathbf{z} are either both numerical arrays of the same dimensions, or one of the two is a scalar. In the first case, the output is the same size as both arrays, and is defined elementwise by the smaller of the two arrays. In the second case, the output is defined elementwise by the smaller of the array entries and the scalar.

11.16.2 Function Internals

In the general version of the max function which is applied to a single array (using the max(x,[],d) or max(x) syntaxes), The output is computed via

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \max_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p),$$

and the output array n of indices is calculated via

$$n(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \arg\max_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

In the two-array version (max(x,z)), the single output is computed as

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \begin{cases} x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p) & x(\dots) \le z(\dots) \\ z(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p) & z(\dots) < x(\dots). \end{cases}$$

11.16.3 Example

The following piece of code demonstrates various uses of the maximum function. We start with the one-array version.

$$-->$$
 A = [5,1,3;3,2,1;0,3,1]

A =

5 1 3

3 2 1

0 3 1

We first take the maximum along the columns, resulting in a row vector.

ans =

5 3 3

Next, we take the maximum along the rows, resulting in a column vector.

$$-\rightarrow \max(A,[],2)$$

ans =

5

3

3

When the dimension argument is not supplied, max acts along the first non-singular dimension. For a row vector, this is the column direction:

$$--> \max([5,3,2,9])$$

ans =

9

For the two-argument version, we can compute the smaller of two arrays, as in this example:

```
--> a = int8(100*randn(4))
a =
    8 127 -51 -57
   -5 -25
           -62 -14
  -17 -73
                -73
            127
 -102
       21
             36
                  39
--> b = int8(100*randn(4))
   59 127
                  24
             46
  -98 -78
           -50 -114
 -128
       57
           127
  -64 -95
            30 127
--> max(a,b)
ans =
  59 127 46 24
  -5 -25 -50 -14
 -17 57 127 -2
 -64 21 36 127
Or alternately, we can compare an array with a scalar
--> a = randn(2)
    1.4356
             0.4894
   -0.8816
              0.6359
--> \max(a,0)
ans =
    1.4356
              0.4894
              0.6359
```

11.17 MEAN Mean Function

11.17.1 Usage

Computes the mean of an array along a given dimension. The general syntax for its use is

```
y = mean(x,d)
```

where x is an n-dimensions array of numerical type. The output is of the same numerical type as the input. The argument d is optional, and denotes the dimension along which to take the mean. The output y is the same size as x, except that it is singular along the mean direction. So, for example, if x is a 3 x 3 x 4 array, and we compute the mean along dimension d=2, then the output is of size 3 x 1 x 4.

11.17.2 Function Internals

The output is computed via

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \frac{1}{N} \sum_{k=1}^{N} x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

If d is omitted, then the mean is taken along the first non-singleton dimension of x.

11.17.3 Example

The following piece of code demonstrates various uses of the mean function

```
--> A = [5,1,3;3,2,1;0,3,1]
```

A = 5 1 3 3 2 1

0 3 1

We start by calling mean without a dimension argument, in which case it defaults to the first nonsingular dimension (in this case, along the columns or d = 1).

```
--> mean(A)
ans =
2.6667 2.0000 1.6667
```

Next, we take the mean along the rows.

```
--> mean(A,2)
```

ans =

3.0000

2.0000

1.3333

11.18 MIN Minimum Function

11.18.1 Usage

Computes the minimum of an array along a given dimension, or alternately, computes two arrays (entry-wise) and keeps the smaller value for each array. As a result, the min function has a number

of syntaxes. The first one computes the minimum of an array along a given dimension. The first general syntax for its use is either

$$[y,n] = min(x,[],d)$$

where x is a multidimensional array of numerical type, in which case the output y is the minimum of x along dimension d. The second argument n is the index that results in the minimum. In the event that multiple minima are present with the same value, the index of the first minimum is used. The second general syntax for the use of the min function is

$$[y,n] = min(x)$$

In this case, the minimum is taken along the first non-singleton dimension of x. For complex data types, the minimum is based on the magnitude of the numbers. NaNs are ignored in the calculations. The third general syntax for the use of the \min function is as a comparison function for pairs of arrays. Here, the general syntax is

$$y = min(x,z)$$

where \mathbf{x} and \mathbf{z} are either both numerical arrays of the same dimensions, or one of the two is a scalar. In the first case, the output is the same size as both arrays, and is defined elementwise by the smaller of the two arrays. In the second case, the output is defined elementwise by the smaller of the array entries and the scalar.

11.18.2 Function Internals

In the general version of the min function which is applied to a single array (using the min(x,[],d) or min(x) syntaxes), The output is computed via

$$y(m_1,\ldots,m_{d-1},1,m_{d+1},\ldots,m_p) = \min_k x(m_1,\ldots,m_{d-1},k,m_{d+1},\ldots,m_p),$$

and the output array ${\tt n}$ of indices is calculated via

$$n(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \arg\min_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

In the two-array version (min(x,z)), the single output is computed as

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \begin{cases} x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p) & x(\dots) \le z(\dots) \\ z(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p) & z(\dots) < x(\dots). \end{cases}$$

11.18.3 Example

The following piece of code demonstrates various uses of the minimum function. We start with the one-array version.

$$-->$$
 A = [5,1,3;3,2,1;0,3,1]

A =

5 1 3

3 2 1

0 3 1

We first take the minimum along the columns, resulting in a row vector.

```
--> min(A)
ans =
0 1 1
```

Next, we take the minimum along the rows, resulting in a column vector.

```
--> min(A,[],2)
ans =
1
1
0
```

When the dimension argument is not supplied, min acts along the first non-singular dimension. For a row vector, this is the column direction:

```
--> min([5,3,2,9])
ans =
2
```

For the two-argument version, we can compute the smaller of two arrays, as in this example:

```
--> a = int8(100*randn(4))
a =
   27
       61 -128
                -22
  -54 -74
           -27
                 -61
   66 -128
            127
                  34
  -13 -128
             42
                  86
--> b = int8(100*randn(4))
   56
        33
          -15
                  17
  127
       127
             29
                -97
      -45 117 -128
   99
   56 -114 127 104
--> min(a,b)
ans =
                -22
   27
        33 -128
  -54
      -74
           -27
                 -97
   66 -128
          117 -128
```

42

86

-13 -128

Or alternately, we can compare an array with a scalar

```
--> a = randn(2)

a =
    -0.2804     0.3739
    -0.8883    -0.4260

--> min(a,0)

ans =
    -0.2804      0
    -0.8883    -0.4260
```

11.19 NUM2HEX Convert Numbers to IEEE Hex Strings

11.19.1 Usage

Converts single and double precision arrays to IEEE hex strings. The syntax for its use is

```
y = num2hex(x)
```

where x is either a float or double array. The output y is a n-by-p character array, where n is the number of elements in x, and p is 16 for double arrays, and 8 for single arrays.

11.19.2 Example

```
Some interesting numbers
```

```
--> num2hex([1 0 0.1 -pi inf nan])

ans =
3ff000000000000000
000000000000000
3fb99999999999
a co0921fb54442d18
7ff0000000000000
fff800000000000
The same in single precision
--> num2hex(float([1 0 0.1 -pi inf nan]))

ans =
3f800000
00000000
3dcccccd
c0490fdb
```

7f800000 fff80000

11.20 PROD Product Function

11.20.1 Usage

Computes the product of an array along a given dimension. The general syntax for its use is

$$y = prod(x,d)$$

where x is an n-dimensions array of numerical type. The output is of the same numerical type as the input, except for integer types, which are automatically promoted to int32. The argument d is optional, and denotes the dimension along which to take the product. The output is computed via

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \prod_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

If d is omitted, then the product is taken along the first non-singleton dimension of x. Note that by definition (starting with FreeMat 2.1) prod([]) = 1.

11.20.2 Example

The following piece of code demonstrates various uses of the product function

$$-->$$
 A = [5,1,3;3,2,1;0,3,1]

A =

5 1 3

3 2 1

0 3 1

We start by calling prod without a dimension argument, in which case it defaults to the first nonsingular dimension (in this case, along the columns or d = 1).

```
--> prod(A)
```

ans =

0 6 3

Next, we take the product along the rows.

--> prod(A,2)

ans =

15

6

0

11.21 REAL Real Function

11.21.1 Usage

Returns the real part of the input array for all elements. The general syntax for its use is

```
y = real(x)
```

where x is an n-dimensional array of numerical type. The output is the same numerical type as the input, unless the input is complex or dcomplex. For complex inputs, the real part is a floating point array, so that the return type is float. For dcomplex inputs, the real part is a double precision floating point array, so that the return type is double. The real function does nothing to real and integer types.

11.21.2 Example

The following demonstrates the real applied to a complex scalar.

```
--> real(3+4*i)

ans =
3

The real function has no effect on real arguments:
--> real([2,3,4])

ans =
2 3 4

For a double-precision complex array,
--> real([2.0+3.0*i,i])

ans =
2 0
```

11.22 ROUND Round Function

11.22.1 Usage

Rounds an n-dimensional array to the nearest integer elementwise. The general syntax for its use is

```
y = round(x)
```

where x is a multidimensional array of numerical type. The round function preserves the type of the argument. So integer arguments are not modified, and float arrays return float arrays as outputs, and similarly for double arrays. The round function is not defined for complex or dcomplex types.

11.22.2 Example

The following demonstrates the **round** function applied to various (numerical) arguments. For integer arguments, the round function has no effect:

```
--> round(3)
ans =
 3
--> round(-3)
ans =
 -3
Next, we take the round of a floating point value:
--> round(3.023f)
ans =
 3
--> round(-2.341f)
ans =
 -2
Note that the return type is a float also. Finally, for a double type:
--> round(4.312)
ans =
--> round(-5.32)
ans =
-5
```

11.23 STD Standard Deviation Function

11.23.1 Usage

Computes the standard deviation of an array along a given dimension. The general syntax for its use is

```
y = std(x,d)
```

where x is an n-dimensions array of numerical type. The output is of the same numerical type as the input. The argument d is optional, and denotes the dimension along which to take the variance. The output y is the same size as x, except that it is singular along the mean direction. So, for example, if x is a 3 x 3 x 4 array, and we compute the mean along dimension d=2, then the output is of size 3 x 1 x 4.

11.23.2 Example

The following piece of code demonstrates various uses of the std function

```
--> A = [5,1,3;3,2,1;0,3,1]
A =
5 1 3
3 2 1
0 3 1
```

We start by calling std without a dimension argument, in which case it defaults to the first nonsingular dimension (in this case, along the columns or d = 1).

```
--> std(A)

ans =
    2.5166   1.0000   1.1547

Next, we take the variance along the rows.
```

```
--> std(A,2)
ans =
    2.0000
    1.0000
    1.5275
```

11.24 SUB2IND Convert Multiple Indexing To Linear Indexing

11.24.1 Usage

The sub2ind function converts a multi-dimensional indexing expression into a linear (or vector) indexing expression. The syntax for its use is

```
y = sub2ind(sizevec,d1,d2,...,dn)
```

where sizevec is the size of the array being indexed into, and each di is a vector of the same length, containing index values. The basic idea behind sub2ind is that it makes

```
[z(d1(1),d2(1),...,dn(1)),...,z(d1(n),d2(n),...,dn(n))]
```

equivalent to

```
z(sub2ind(size(z),d1,d2,...,dn))
```

where the later form is using vector indexing, and the former one is using native, multi-dimensional indexing.

11.24.2 Example

Suppose we have a simple 3 x 4 matrix A containing some random integer elements

```
--> A = randi(ones(3,4),10*ones(3,4))

A =
2  1  4  2
8  10  4  7
10  7  4  10
```

We can extract the elements (1,3),(2,3),(3,4) of A via sub2ind. To calculate which elements of A this corresponds to, we can use sub2ind as

```
--> n = sub2ind(size(A),1:3,2:4)

n =
    4  8 12

--> A(n)

ans =
    1  4 10
```

11.25 SUM Sum Function

11.25.1 Usage

Computes the summation of an array along a given dimension. The general syntax for its use is

```
y = sum(x,d)
```

where x is an n-dimensions array of numerical type. The output is of the same numerical type as the input. The argument d is optional, and denotes the dimension along which to take the summation. The output y is the same size as x, except that it is singular along the summation direction. So, for example, if x is a 3 x 3 x 4 array, and we compute the summation along dimension d=2, then the output is of size 3 x 1 x 4.

11.25.2 Function Internals

The output is computed via

$$y(m_1, \dots, m_{d-1}, 1, m_{d+1}, \dots, m_p) = \sum_k x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

If d is omitted, then the summation is taken along the first non-singleton dimension of x.

11.25.3 Example

The following piece of code demonstrates various uses of the summation function

```
--> A = [5,1,3;3,2,1;0,3,1]
A =
5 1 3
3 2 1
0 3 1
```

We start by calling sum without a dimension argument, in which case it defaults to the first nonsingular dimension (in this case, along the columns or d = 1).

```
--> sum(A)

ans =
8 6 5

Next, we take the sum along the rows.

--> sum(A,2)

ans =
9
6
```

11.26 TEST Test Function

11.26.1 Usage

Tests for the argument array to be all logical 1s. It is completely equivalent to the all function applied to a vectorized form of the input. The syntax for the test function is

```
y = test(x)
```

and the result is equivalent to all(x(:)).

11.27 VAR Variance Function

11.27.1 Usage

Computes the variance of an array along a given dimension. The general syntax for its use is

$$y = var(x,d)$$

where x is an n-dimensions array of numerical type. The output is of the same numerical type as the input. The argument d is optional, and denotes the dimension along which to take the variance. The output y is the same size as x, except that it is singular along the mean direction. So, for example, if x is a 3 x 3 x 4 array, and we compute the mean along dimension d=2, then the output is of size 3 x 1 x 4.

11.27.2 Function Internals

The output is computed via

$$y(m_1,\ldots,m_{d-1},1,m_{d+1},\ldots,m_p) = \frac{1}{N-1} \sum_{k=1}^{N} (x(m_1,\ldots,m_{d-1},k,m_{d+1},\ldots,m_p) - \bar{x})^2,$$

where

$$\bar{x} = \frac{1}{N} \sum_{k=1}^{N} x(m_1, \dots, m_{d-1}, k, m_{d+1}, \dots, m_p)$$

If d is omitted, then the mean is taken along the first non-singleton dimension of x.

11.27.3 Example

The following piece of code demonstrates various uses of the var function

$$-->$$
 A = [5,1,3;3,2,1;0,3,1]

A =

5 1 3

3 2 1

0 3 1

We start by calling var without a dimension argument, in which case it defaults to the first nonsingular dimension (in this case, along the columns or d = 1).

ans =

6.3333 1.0000 1.3333

Next, we take the variance along the rows.

```
--> var(A,2)
ans =
4.0000
1.0000
2.3333
```

11.28 VEC Reshape to a Vector

11.28.1 Usage

Reshapes an n-dimensional array into a column vector. The general syntax for its use is

$$y = vec(x)$$

where x is an n-dimensional array (not necessarily numeric). This function is equivalent to the expression y = x(:).

11.28.2 Example

A simple example of the vec operator reshaping a 2D matrix:

```
--> A = [1,2,4,3;2,3,4,5]

A =
    1 2 4 3
    2 3 4 5

--> vec(A)

ans =
    1
    2
```

Chapter 12

Inspection Functions

12.1 CLEAR Clear or Delete a Variable

12.1.1 Usage

Clears a set of variables from the current context, or alternately, delete all variables defined in the current context. There are several formats for the function call. The first is the explicit form in which a list of variables are provided:

```
clear a1 a2 ...
```

The variables can be persistent or global, and they will be deleted. The second form

```
clear 'all'
```

clears all variables and libraries from the current context. Alternately, you can use the form:

```
clear 'libs'
```

which will unload any libraries or DLLs that have been imported. Optionally, you can specify that persistent variables should be cleared via:

```
clear 'persistent'
```

and similarly for global variables:

```
clear 'global'
```

You can use

```
clear 'classes'
```

to clear all definitions of user-defined classes. With no arguments, clear defaults to clearing 'all'.

12.1.2 Example

Here is a simple example of using clear to delete a variable. First, we create a variable called a:

```
--> a = 53
a =
```

53

Next, we clear a using the clear function, and verify that it is deleted.

```
--> clear a
--> a
Error: Undefined function or variable a
```

12.2 END End Function

12.2.1 Usage

Computes the size of a variable along a given dimension. The syntax for its use is

```
y = end(x,dim,subindexes)
```

where x is the array to be analyzed, dim is the dimension along which to compute the end, and subindexes indicates how many dimensions are involved in the end calculation.

12.3 EXIST Test for Existence

12.3.1 Usage

Tests for the existence of a variable, function, directory or file. The general syntax for its use is

```
y = exist(item,kind)
```

where item is a string containing the name of the item to look for, and kind is a string indicating the type of the search. The kind must be one of

- 'builtin' checks for built-in functions
- 'dir' checks for directories
- 'file' checks for files
- 'var' checks for variables
- 'all' checks all possibilities (same as leaving out kind)

You can also leave the kind specification out, in which case the calling syntax is

```
y = exist(item)
```

The return code is one of the following:

- 0 if item does not exist
- 1 if item is a variable in the workspace
- 2 if item is an M file on the search path, a full pathname to a file, or an ordinary file on your search path
- 5 if item is a built-in FreeMat function
- 7 if item is a directory

Note: previous to version 1.10, exist used a different notion of existence for variables: a variable was said to exist if it was defined and non-empty. This test is now performed by isset.

12.3.2 Example

Some examples of the exist function. Note that generally exist is used in functions to test for keywords. For example,

```
function y = testfunc(a, b, c)
  if (~exist('c'))
    % c was not defined, so establish a default
    c = 13;
  end
  y = a + b + c;
An example of exist in action.
--> a = randn(3,5,2)
a =
(:,:,1) =
    0.0744
             -0.7000
                        -1.8022
                                   -0.0255
                                             -0.2933
   -0.0152
             -0.5401
                        -0.2030
                                   -0.5437
                                              0.9261
   -0.4359
             -1.2334
                         0.5156
                                   0.0821
                                             -0.5065
(:,:,2) =
    0.7408
              0.6302
                        -0.2798
                                   0.7279
                                              1.7674
    0.9063
             -1.7321
                                   -0.4091
                                             -0.5516
                        -0.8851
    1.4880
              0.5030
                         0.6747
                                   -0.5492
                                              1.1867
--> b = []
b =
  --> who
```

```
Variable Name
                       Type
                               Flags
                                                  Size
                    double
                                                 [3 5 2]
                    double
                                                 [0 0]
               b
--> exist('a')
ans =
 1
--> exist('b')
ans =
 1
--> exist('c')
ans =
 0
```

12.4 FIELDNAMES Fieldnames of a Structure

12.4.1 Usage

Returns a cell array containing the names of the fields in a structure array. The syntax for its use is

```
x = fieldnames(y)
```

where y is a structure array of object array. The result is a cell array, with one entry per field in y.

12.4.2 Example

We define a simple structure array:

```
--> y.foo = 3; y.goo = 'hello';
--> x = fieldnames(y)
x =
[foo]
[goo]
```

12.5 ISA Test Type of Variable

12.5.1 Usage

Tests the type of a variable. The syntax for its use is

```
y = isa(x, type)
```

where x is the variable to test, and type is the type. Supported built-in types are

- 'cell' for cell-arrays
- 'struct' for structure-arrays
- 'logical' for logical arrays
- 'uint8' for unsigned 8-bit integers
- 'int8' for signed 8-bit integers
- 'uint16' for unsigned 16-bit integers
- 'int16' for signed 16-bit integers
- 'uint32' for unsigned 32-bit integers
- 'int32' for signed 32-bit integers
- 'uint64' for unsigned 64-bit integers
- 'int64' for signed 64-bit integers
- 'single' for 32-bit floating point numbers
- 'double' for 64-bit floating point numbers
- 'char' for string arrays

If the argument is a user-defined type (via the class function), then the name of that class is returned.

12.5.2 Examples

Here are some examples of the isa call.

```
--> a = {1}

a =
  [1]

--> isa(a,'char')

ans =
  0

--> isa(a,'cell')

ans =
  1
```

Here we use isa along with shortcut boolean evaluation to safely determine if a variable contains the string 'hello'

```
--> a = 'hello'

a = hello
--> isa(a,'char') && strcmp(a,'hello')

ans = 1
```

12.6 ISCELL Test For Cell Array

12.6.1 Usage

The syntax for iscell is

```
x = iscell(y)
```

and it returns a logical 1 if the argument is a cell array and a logical 0 otherwise.

12.6.2 Example

Here are some examples of iscell

```
--> iscell('foo')

ans =
0

--> iscell(2)

ans =
0

--> iscell({1,2,3})

ans =
1
```

12.7 ISCELLSTR Test For Cell Array of Strings

12.7.1 Usage

The syntax for iscellstr is

```
x = iscellstr(y)
```

and it returns a logical 1 if the argument is a cell array in which every cell is a character array (or is empty), and a logical 0 otherwise.

12.7.2 Example

```
Here is a simple example
---> A = {'Hello','Yellow';'Mellow','Othello'}

A =
  [Hello] [Yellow]
  [Mellow] [Othello]

---> iscellstr(A)
Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t
ans =
```

12.8 ISCHAR Test For Character Array (string)

12.8.1 Usage

1

The syntax for ischar is

```
x = ischar(y)
```

and it returns a logical 1 if the argument is a string and a logical 0 otherwise.

12.9 ISEMPTY Test For Variable Empty

12.9.1 Usage

The isempty function returns a boolean that indicates if the argument variable is empty or not. The general syntax for its use is

```
y = isempty(x).
```

12.9.2 Examples

Here are some examples of the isempty function

```
--> a = []
a =
[]
```

```
--> isempty(a)
ans =
1
--> b = 1:3
b =
1 2 3
--> isempty(b)
ans =
0
Note that if the variable is not defined, isempty does not return true.
--> clear x
--> isempty(x)
Error: Undefined function or variable x
```

12.10 ISEQUAL Test For Matrix Equality

12.10.1 Usage

Test two arrays for equality. The general format for its use is

```
y = isequal(a,b)
```

This function returns true if the two arrays are equal (compared element-wise). Unlike issume the isequal function will type convert where possible to do the comparison.

12.11 ISFIELD Test for Existence of a Structure Field

12.11.1 Usage

Given a structure array, tests to see if that structure array contains a field with the given name. The syntax for its use is

```
y = isfield(x,field)
```

and returns a logical 1 if x has a field with the name field and a logical 0 if not. It also returns a logical 0 if the argument x is not a structure array.

12.11.2 Example

Here we define a simple struct, and then test for some fields

```
--> a.foo = 32

a =
foo: 32
--> a.goo = 64

a =
foo: 32
goo: 64
--> isfield(a,'goo')

ans =
1
--> isfield(a,'got')

ans =
0
--> isfield(pi,'round')

ans =
0
```

12.12 ISHANDLE Test for Graphics Handle

12.12.1 Usage

Given a constant, this routine will test to see if the constant is a valid graphics handle or not. The syntax for its use is

```
y = ishandle(h,type)
```

and returns a logical 1 if x is a handle of type type and a logical 0 if not.

12.13 ISINF Test for infinities

12.13.1 Usage

Returns true for entries of an array that are infs (i.e., infinities). The usage is

```
y = isinf(x)
```

The result is a logical array of the same size as x, which is true if x is not-a-number, and false otherwise. Note that for complex or dcomplex data types that the result is true if either the real or imaginary parts are infinite.

12.13.2 Example

```
Suppose we have an array of floats with one element that is inf:
```

12.14 ISINTTYPE Test For Integer-type Array

12.14.1 Usage

The syntax for isinttype is

```
x = isinttype(y)
```

and it returns a logical 1 if the argument is an integer type and a logical 0 otherwise. Note that this function only tests the type of the variable, not the value. So if, for example, y is a float array containing all integer values, it will still return a logical 0.

12.15 ISLOGICAL Test for Logical Array

12.15.1 Usage

The syntax for islogical is

```
x = islogical(y)
```

and it returns a logical 1 if the argument is a logical array and a logical 0 otherwise.

12.16 ISMATRIX Test For a 2D Matrix

12.16.1 Usage

This function tests to see if the argument is a matrix. The syntax for ismatrix is

```
x = ismatrix(y)
```

and it returns a logical 1 if the argument is size N x M or M x N and a logical 0 otherwise.

12.17 ISNAN Test for Not-a-Numbers

12.17.1 Usage

Returns true for entries of an array that are NaN's (i.e., Not-a-Numbers). The usage is

```
y = isnan(x)
```

The result is a logical array of the same size as x, which is true if x is not-a-number, and false otherwise. Note that for complex data types that the result is true if either the real or imaginary parts are NaNs.

12.17.2 Example

Suppose we have an array of floats with one element that is nan:

12.18 ISNUMERIC Test for Numeric Array

12.18.1 Usage

The syntax for isnumeric is

```
x = isnumeric(y)
```

and it returns a logical 1 if the argument is a numeric (i.e., not a structure array, cell array, string or user defined class), and a logical 0 otherwise.

12.19 ISREAL Test For Real Array

12.19.1 Usage

The syntax for isreal is

```
x = isreal(y)
```

and it returns a logical 1 if the argument is real valued and a logical 0 otherwise.

12.20 ISSAME Test If Two Arrays Are Identical

12.20.1 Usage

Tests for two arrays to be identical. The syntax for its use is

```
y = issame(a,b)
```

where a and b are two arrays to compare. This comparison succeeds only if a and b are of the same data type, size, and contents. Unlike numerical equivalence tests, the issame function considers NaN to be equal in both arguments.

12.21 ISSCALAR Test For Scalar

12.21.1 Usage

The syntax for isscalar is

```
x = isscalar(y)
```

and it returns a logical 1 if the argument is a scalar, and a logical 0 otherwise.

12.22 ISSET Test If Variable Set

12.22.1 Usage

Tests for the existence and non-emptiness of a variable, the general syntax for its use is

```
y = isset('name')
```

where name is the name of the variable to test. This is functionally equivalent to

```
y = exist('name','var') & ~isempty(name)
```

It returns a logical 1 if the variable is defined in the current workspace, and is not empty, and returns a 0 otherwise.

12.22.2 Example

Some simple examples of using isset

```
--> who
Variable Name Type Flags Size
--> isset('a')

ans =
0

--> a = [];
```

```
--> isset('a')

ans =
   0

--> a = 2;
--> isset('a')

ans =
   1
```

12.23 ISSPARSE Test for Sparse Matrix

12.23.1 Usage

Test a matrix to see if it is sparse or not. The general format for its use is

```
y = issparse(x)
```

This function returns true if x is encoded as a sparse matrix, and false otherwise.

12.23.2 Example

Here is an example of using issparse:

```
--> a = [1,0,0,5;0,3,2,0]

a =
    1 0 0 5
    0 3 2 0

--> issparse(a)

ans =
    0

--> A = sparse(a)

A =
    1 1 1
    2 2 3
    2 3 2
    1 4 5
--> issparse(A)

ans =
    1
```

12.24 ISSQUARE Test For a Square matrix

12.24.1 Usage

This function tests to see if the argument is a square matrix. The syntax for issquare is

```
x = issquare(y)
```

and it returns a logical 1 if the argument is size N x N logical 0 otherwise.

12.25 ISSTR Test For Character Array (string)

12.25.1 Usage

The syntax for isstr is

```
x = isstr(y)
```

and it returns a logical 1 if the argument is a string and a logical 0 otherwise.

12.26 ISSTRUCT Test For Structure Array

12.26.1 Usage

The syntax for isstruct is

```
x = isstruct(y)
```

and it returns a logical 1 if the argument is a structure array, and a logical 0 otherwise.

12.27 ISVECTOR Test For a Vector

12.27.1 Usage

This function tests to see if the argument is a vector. The syntax for isvector is

```
x = isvector(y)
```

and it returns a logical 1 if the argument is size N x 1 or 1 x N and a logical 0 otherwise.

12.28 LENGTH Length of an Array

12.28.1 Usage

Returns the length of an array x. The syntax for its use is

```
y = length(x)
```

and is defined as the maximum length of x along any of its dimensions, i.e., max(size(x)). If you want to determine the number of elements in x, use the numel function instead.

12.28.2 Example

```
For a 4 x 4 x 3 matrix, the length is 4, not 48, as you might expect.
```

```
--> x = rand(4,4,3);
--> length(x)
ans =
```

12.29 MAXDIM Maximum Dimension in Array

12.29.1 Usage

The maxdim function returns the lowest order dimension along which an array is largest. The general syntax for its use is

```
\label{eq:n_signal} \begin{split} n &= \mathtt{maxdim}(x) \\ \text{and is equivalent to } \min(\mathrm{find}(\mathrm{size}(x) == \max(\mathrm{size}(x)))). \end{split}
```

12.30 NDIMS Number of Dimensions in Array

12.30.1 Usage

The ndims function returns the number of dimensions allocated in an array. The general syntax for its use is

```
n = ndims(x)
and is equivalent to length(size(x)).
```

12.31 NNZ Number of Nonzeros

12.31.1 Usage

Returns the number of nonzero elements in a matrix. The general format for its use is

```
y = nnz(x)
```

This function returns the number of nonzero elements in a matrix or array. This function works for both sparse and non-sparse arrays. For

12.31.2 Example

```
--> a = [1,0,0,5;0,3,2,0]
a =
1 0 0 5
0 3 2 0
--> nnz(a)
ans =
 4
--> A = sparse(a)
A =
 1 1 1
 2 2 3
 2 3 2
 1 4 5
--> nnz(A)
ans =
 4
```

12.32 NUMEL Number of Elements in an Array

12.32.1 Usage

Returns the number of elements in an array \mathbf{x} , or in a subindex expression. The syntax for its use is either

```
y = numel(x)
or
y = numel(x,varargin)
```

Generally, numel returns prod(size(x)), the number of total elements in x. However, you can specify a number of indexing expressions for varagin such as index1, index2, ..., indexm. In that case, the output of numel is prod(size(x(index1,...,indexm))).

12.32.2 Example

For a 4 x 4 x 3 matrix, the length is 4, not 48, as you might expect, but numel is 48.

```
--> x = rand(4,4,3);
--> length(x)
```

```
ans =
4
--> numel(x)
ans =
48
Here is an example of using numel with indexing expressions.
--> numel(x,1:3,1:2,2)
ans =
6
```

12.33 SIZE Size of a Variable

12.33.1 Usage

Returns the size of a variable. There are two syntaxes for its use. The first syntax returns the size of the array as a vector of integers, one integer for each dimension

```
[d1,d2,...,dn] = size(x)
```

The other format returns the size of x along a particular dimension:

```
d = size(x,n)
```

where n is the dimension along which to return the size.

12.33.2 Example

```
--> a = randn(23,12,5);
--> size(a)

ans =
23 12 5

Here is an example of the second form of size.
--> size(a,2)

ans =
12
```

12.34 TYPEOF Determine the Type of an Argument

12.34.1 Usage

Returns a string describing the type of an array. The syntax for its use is

```
y = typeof(x),
```

The returned string is one of

- 'cell' for cell-arrays
- 'struct' for structure-arrays
- \bullet 'logical' for logical arrays
- 'uint8' for unsigned 8-bit integers
- 'int8' for signed 8-bit integers
- 'uint16' for unsigned 16-bit integers
- 'int16' for signed 16-bit integers
- 'uint32' for unsigned 32-bit integers
- 'int32' for signed 32-bit integers
- 'float' for 32-bit floating point numbers
- 'double' for 64-bit floating point numbers
- 'string' for string arrays

12.34.2 Example

The following piece of code demonstrates the output of the typeof command for each possible type. The first example is with a simple cell array.

```
--> typeof({1})
ans =
cell
The next example uses the struct constructor to make a simple scalar struct.
--> typeof(struct('foo',3))
ans =
struct
```

The next example uses a comparison between two scalar integers to generate a scalar logical type.

```
--> typeof(3>5)
ans =
logical
For the integers, the typecast operations are used to generate the arguments.
--> typeof(uint8(3))
ans =
uint8
--> typeof(int8(8))
ans =
int8
--> typeof(uint16(3))
ans =
uint16
--> typeof(int16(8))
ans =
int16
--> typeof(uint32(3))
ans =
uint32
--> typeof(int32(3))
ans =
int32
--> typeof(uint64(3))
ans =
uint64
--> typeof(int64(3))
ans =
int64
Float, and double can be created using the suffixes.
--> typeof(1.0f)
ans =
single
--> typeof(1.0D)
```

```
ans =
double
--> typeof(1.0f+i)

ans =
single
--> typeof(1.0D+2.0D*i)

ans =
double
```

12.35 WHERE Get Information on Program Stack

12.35.1 Usage

Returns information on the current stack. The usage is

where

The result is a kind of stack trace that indicates the state of the current call stack, and where you are relative to the stack.

12.35.2 Example

Suppose we have the following chain of functions.

```
chain1.m
function chain1
a = 32;
b = a + 5;
chain2(b)

    chain2.m
function chain2(d)
d = d + 5;
chain3

    chain3.m
function chain3
g = 54;
f = g + 1;
keyboard
```

The execution of the where command shows the stack trace.

12.36 WHICH Get Information on Function

12.36.1 Usage

Returns information on a function (if defined). The usage is

```
which(fname)
```

where fname is a string argument that contains the name of the function. For functions and scripts defined via .m files, the which command returns the location of the source file:

```
y = which(fname)
```

will return the filename for the .m file corresponding to the given function, and an empty string otherwise.

12.36.2 Example

First, we apply the which command to a built in function.

```
--> which fft
Function fft is a built in function
```

Next, we apply it to a function defined via a .m file.

```
--> which fliplr
```

Function fliplr, M-File function in file '/home/basu/dev/branches/FreeMat4/src/toolbox/array/fliplr.m'

12.37 WHO Describe Currently Defined Variables

12.37.1 Usage

Reports information on either all variables in the current context or on a specified set of variables. For each variable, the who function indicates the size and type of the variable as well as if it is a global or persistent. There are two formats for the function call. The first is the explicit form, in which a list of variables are provided:

```
who a1 a2 ...
```

In the second form

who

the who function lists all variables defined in the current context (as well as global and persistent variables). Note that there are two alternate forms for calling the who function:

```
who 'a1' 'a2' ...
and
who('a1','a2',...)
```

12.37.2 Example

Here is an example of the general use of who, which lists all of the variables defined.

```
--> c = [1,2,3];
--> f = 'hello';
--> p = randn(1,256);
--> who
  Variable Name
                                                   Size
                       Type
                               Flags
                    double
                                                 [1 3]
               С
               f
                      char
                                                 [1 5]
                    double
                                                 [1 256]
```

In the second case, we examine only a specific variable:

```
--> who c
Variable Name Type Flags Size
c double [1 3]
--> who('c')
Variable Name Type Flags Size
c double [1 3]
```

12.38 WHOS Describe Currently Defined Variables With Memory Usage

12.38.1 Usage

Reports information on either all variables in the current context or on a specified set of variables. For each variable, the who function indicates the size and type of the variable as well as if it is a global or persistent. There are two formats for the function call. The first is the explicit form, in which a list of variables are provided:

```
whos a1 a2 ...
```

12.38. WHOS DESCRIBE CURRENTLY DEFINED VARIABLES WITH MEMORY USAGE245

In the second form

whos

the whos function lists all variables defined in the current context (as well as global and persistent variables). Note that there are two alternate forms for calling the whos function:

```
whos 'a1' 'a2' ...
and
whos('a1','a2',...)
```

Chapter 13

Type Conversion Functions

13.1 BIN2DEC Convert Binary String to Decimal

13.1.1 USAGE

Converts a binary string to an integer. The syntax for its use is

```
y = bin2dec(x)
```

where x is a binary string. If x is a matrix, then the resulting y is a column vector.

13.1.2 Example

Here we convert some numbers to bits

```
--> bin2dec('101110')

ans =
46

--> bin2dec('010')

ans =
```

13.2 BIN2INT Convert Binary Arrays to Integer

13.2.1 Usage

Converts the binary decomposition of an integer array back to an integer array. The general syntax for its use is

```
y = bin2int(x)
```

where x is a multi-dimensional logical array, where the last dimension indexes the bit planes (see int2bin for an example). By default, the output of bin2int is unsigned uint32. To get a signed integer, it must be typecast correctly. A second form for bin2int takes a 'signed' flag

```
y = bin2int(x,'signed')
```

in which case the output is signed.

13.2.2 Example

The following piece of code demonstrates various uses of the int2bin function. First the simplest example:

```
--> A = [2;5;6;2]
A =
 2
 5
 6
 2
--> B = int2bin(A,8)
0 0 0 0 0 0 1 0
 0 0 0 0 0 1 0 1
 0 \ 0 \ 0 \ 0 \ 0 \ 1 \ 1 \ 0
 0 0 0 0 0 0 1 0
--> bin2int(B)
ans =
 5
 6
--> A = [1;2;-5;2]
A =
  1
  2
 -5
  2
--> B = int2bin(A,8)
```

```
B =
0 0 0 0 0 0 0 1
0 0 0 0 0 0 1 0
1 1 1 1 1 0 1 1
0 0 0 0 0 0 1 0
--> bin2int(B)
ans =
   1
   2
 251
   2
--> int32(bin2int(B))
ans =
   1
   2
 251
```

13.2.3 Tets

13.3 CAST Typecast Variable to Specified Type

13.3.1 Usage

The cast function allows you to typecast a variable from one type to another. The syntax for its use is

```
y = cast(x, toclass)
```

where toclass is the name of the class to cast x to. Note that the typecast must make sense, and that toclass must be one of the builtin types. The current list of supported types is

- 'cell' for cell-arrays
- 'struct' for structure-arrays
- 'logical' for logical arrays
- 'uint8' for unsigned 8-bit integers
- 'int8' for signed 8-bit integers
- 'uint16' for unsigned 16-bit integers
- 'int16' for signed 16-bit integers

- 'uint32' for unsigned 32-bit integers
- 'int32' for signed 32-bit integers
- 'uint64' for unsigned 64-bit integers
- 'int64' for signed 64-bit integers
- 'float' for 32-bit floating point numbers
- 'single' is a synonym for 'float'
- 'double' for 64-bit floating point numbers
- 'char' for string arrays

13.3.2 Example

Here is an example of a typecast from a float to an 8-bit integer

```
--> cast(pi,'uint8')
ans =
3
and here we cast an array of arbitrary integers to a logical array
--> cast([1 0 3 0],'logical')
ans =
1 0 1 0
```

13.4 CHAR Convert to character array or string

13.4.1 Usage

The char function can be used to convert an array into a string. It has several forms. The first form is

```
y = char(x)
```

where x is a numeric array containing character codes. FreeMat does not currently support Unicode, so the character codes must be in the range of [0,255]. The output is a string of the same size as x. A second form is

```
y = char(c)
```

where c is a cell array of strings, creates a matrix string where each row contains a string from the corresponding cell array. The third form is

```
y = char(s1, s2, s3, ...)
```

where **si** are a character arrays. The result is a matrix string where each row contains a string from the corresponding argument.

13.4.2 Example

Here is an example of the first technique being used to generate a string containing some ASCII characters

```
--> char([32:64;65:97])
ans =
 !"#$%&'()*+,-./0123456789:;<=>?@
ABCDEFGHIJKLMNOPQRSTUVWXYZ[\]^_'a
In the next example, we form a character array from a set of strings in a cell array. Note that the
character array is padded with spaces to make the rows all have the same length.
--> char({'hello','to','the','world'})
ans =
hello
to
the
world
In the last example, we pass the individual strings as explicit arguments to char
--> char('hello','to','the','world')
ans =
hello
```

13.5 COMPLEX Create a Complex Number

13.5.1 Usage

to the world

Converts the two real input arguments into the real and imaginary part (respectively) of a complex number. The syntax for its use is

```
y = complex(x,z)
```

where x and z are n-dimensional numerical arrays. The usual rules for binary operators apply (i.e., one of the arguments can be a scalar, if either is of type single the output is single, etc.).

13.6 DCOMPLEX Convert to Double Precision (deprecated)

13.6.1 Usage

The dcomplex function used to convert variables into 64-bit complex data types in prior versions of FreeMat. Starting with FreeMat 4, the type rules are the same as Matlab, hence, there is no

distinction between a 64-bit complex type and and 64-bit real type. Thus, the dcomplex function is just a synonym for double.

13.7 DEC2BIN Convert Decimal to Binary String

13.7.1 USAGE

Converts an integer to a binary string. The syntax for its use is

```
y = dec2bin(x,n)
```

where x is the positive integer, and n is the number of bits to use in the representation. Alternately, if you leave n unspecified,

```
y = dec2bin(x)
```

the minimum number of bits needed to represent x are used. If x is a vector, then the resulting y is a character matrix.

13.7.2 Example

Here we convert some numbers to bits

```
--> dec2bin(56)

ans =
111000
--> dec2bin(1039456)

ans =
11111101110001100000
--> dec2bin([63,73,32],5)

ans =
11111
01001
00000
```

13.8 DOUBLE Convert to 64-bit Floating Point

13.8.1 Usage

Converts the argument to a 64-bit floating point number. The syntax for its use is

```
y = double(x)
```

where x is an n-dimensional numerical array. Conversion follows the saturation rules. Note that both NaN and Inf are both preserved under type conversion.

13.8.2 Example

The following piece of code demonstrates several uses of double. First, we convert from an integer (the argument is an integer because no decimal is present):

```
--> double(200)
ans =
200
```

In the next example, a single precision argument is passed in (the presence of the f suffix implies single precision).

```
--> double(400.0f)
ans =
400
```

In the next example, a complex argument is passed in.

```
--> double(3.0+4.0*i)
ans =
3.0000 + 4.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> double('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> double({4})
Error: Cannot perform type conversions with this type
```

13.9 FLOAT Convert to 32-bit Floating Point

13.9.1 Usage

Converts the argument to a 32-bit floating point number. The syntax for its use is

```
y = float(x)
```

where x is an n-dimensional numerical array. Conversion follows the saturation rules. Note that both NaN and Inf are both preserved under type conversion.

13.9.2 Example

The following piece of code demonstrates several uses of float. First, we convert from an integer (the argument is an integer because no decimal is present):

```
--> float(200)

ans =
200

In the next example, a double precision argument is passed in
--> float(400.0)

ans =
400

In the next example, a complex argument is passed in.
--> float(3.0+4.0*i)

ans =
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> float('helo')
ans =
104 101 108 111
```

3.0000 + 4.0000i

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> float({4})
Error: Cannot perform type conversions with this type
```

13.10 INT16 Convert to Signed 16-bit Integer

13.10.1 Usage

Converts the argument to an signed 16-bit Integer. The syntax for its use is

```
y = int16(x)
```

where x is an n-dimensional numerical array. Conversion follows the saturation rules (e.g., if x is outside the normal range for a signed 16-bit integer of [-32767,32767], it is truncated to that range). Note that both NaN and Inf both map to 0.

13.10.2 Example

The following piece of code demonstrates several uses of int16. First, the routine uses

```
--> int16(100)

ans =
100

--> int16(-100)

ans =
-100
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the range of the data type.

```
--> int16(40000)
ans =
32767
```

In the next example, a positive double precision argument is passed in. The result is the signed integer that is closest to the argument.

```
--> int16(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the signed complex integer that is closest to the argument.

```
--> int16(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> int16('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> int16({4})
Error: Cannot perform type conversions with this type
```

13.11 INT2BIN Convert Integer Arrays to Binary

13.11.1 Usage

Computes the binary decomposition of an integer array to the specified number of bits. The general syntax for its use is

```
y = int2bin(x,n)
```

where x is a multi-dimensional integer array, and n is the number of bits to expand it to. The output array y has one extra dimension to it than the input. The bits are expanded along this extra dimension.

13.11.2 Example

The following piece of code demonstrates various uses of the int2bin function. First the simplest example:

```
--> A = [2;5;6;2]
A =
 2
 5
 6
 2
--> int2bin(A,8)
ans =
 0 0 0 0 0 0 1 0
 0 0 0 0 0 1 0 1
 0 0 0 0 0 1 1 0
 0 0 0 0 0 0 1 0
--> A = [1;2;-5;2]
A =
 1
  2
 -5
  2
--> int2bin(A,8)
ans =
 0 0 0 0 0 0 0 1
 0 0 0 0 0 0 1 0
```

13.12 INT32 Convert to Signed 32-bit Integer

13.12.1 Usage

Converts the argument to an signed 32-bit Integer. The syntax for its use is

```
y = int32(x)
```

where x is an n-dimensional numerical array. Conversion follows the saturation rules (e.g., if x is outside the normal range for a signed 32-bit integer of [-2147483647,2147483647], it is truncated to that range). Note that both NaN and Inf both map to 0.

13.12.2 Example

The following piece of code demonstrates several uses of int32. First, the routine uses

```
--> int32(100)

ans =
100

--> int32(-100)

ans =
-100
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the range of the data type.

```
--> int32(40e9)
ans =
2147483647
```

In the next example, a positive double precision argument is passed in. The result is the signed integer that is closest to the argument.

```
--> int32(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the signed complex integer that is closest to the argument.

```
--> int32(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> int32('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> int32({4})
Error: Cannot perform type conversions with this type
```

13.13 INT64 Convert to Signed 64-bit Integer

13.13.1 Usage

Converts the argument to an signed 64-bit Integer. The syntax for its use is

```
y = int64(x)
```

where x is an n-dimensional numerical array. Conversion follows the saturation rules (e.g., if x is outside the normal range for a signed 64-bit integer of $[-2^63+1,2^63-1]$, it is truncated to that range). Note that both NaN and Inf both map to 0.

13.13.2 Example

The following piece of code demonstrates several uses of int64. First, the routine uses

```
--> int64(100)

ans =
100

--> int64(-100)

ans =
-100
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the range of the data type.

```
--> int64(40e9)
ans =
40000000000
```

In the next example, a positive double precision argument is passed in. The result is the signed integer that is closest to the argument.

```
--> int64(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the complex signed integer that is closest to the argument.

```
--> int64(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> int64('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> int64({4})
Error: Cannot perform type conversions with this type
```

13.14 INT8 Convert to Signed 8-bit Integer

13.14.1 Usage

Converts the argument to an signed 8-bit Integer. The syntax for its use is

```
y = int8(x)
```

where x is an n-dimensional numerical array. Conversion follows the saturation rules (e.g., if x is outside the normal range for a signed 8-bit integer of [-127,127], it is truncated to that range. Note that both NaN and Inf both map to 0.

13.14.2 Example

The following piece of code demonstrates several uses of int8. First, the routine uses

```
--> int8(100)

ans =
100

--> int8(-100)

ans =
-100
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the range of the type.

```
--> int8(400)
ans =
127
```

In the next example, a positive double precision argument is passed in. The result is the signed integer that is closest to the argument.

```
--> int8(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the signed complex integer that is closest to the argument.

```
--> int8(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> int8('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> int8({4})
Error: Cannot perform type conversions with this type
```

13.15 LOGICAL Convert to Logical

13.15.1 Usage

Converts the argument to a logical array. The syntax for its use is

```
y = logical(x)
```

where x is an n-dimensional numerical array. Any nonzero element maps to a logical 1.

13.15.2 Example

Here we convert an integer array to logical:

```
--> logical([1,2,3,0,0,0,5,2,2])
ans =
1 1 1 0 0 0 1 1 1
```

The same example with double precision values:

```
--> logical([pi,pi,0,e,0,-1])
ans =
1 1 0 1 0 1
```

13.16 SINGLE Convert to 32-bit Floating Point

13.16.1 Usage

A synonym for the float function, converts the argument to a 32-bit floating point number. The syntax for its use is

```
y = single(x)
```

where x is an n-dimensional numerical array. Conversion follows the general C rules. Note that both NaN and Inf are both preserved under type conversion.

13.17 STRING Convert Array to String

13.17.1 Usage

Converts the argument array into a string. The syntax for its use is

```
y = string(x)
```

where x is an n-dimensional numerical array.

13.17.2 Example

Here we take an array containing ASCII codes for a string, and convert it into a string.

```
--> a = [104,101,108,108,111]

a =
   104 101 108 108 111

--> string(a)

ans =
hello
```

13.18 UINT16 Convert to Unsigned 16-bit Integer

13.18.1 Usage

Converts the argument to an unsigned 16-bit Integer. The syntax for its use is

```
y = uint16(x)
```

where x is an n-dimensional numerical array. Conversion follows saturation rules (e.g., if x is outside the normal range for an unsigned 16-bit integer of [0,65535], it is truncated to that range. Note that both NaN and Inf both map to 0.

13.18.2 Example

The following piece of code demonstrates several uses of uint16.

```
--> uint16(200)
ans =
200
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the maximum value of the data type.

```
--> uint16(99400)

ans =
65535

In the next example, a negative integer is passed in. The result is truncated to zero.
--> uint16(-100)

ans =
0
```

In the next example, a positive double precision argument is passed in. The result is the unsigned integer that is closest to the argument.

```
--> uint16(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the complex unsigned integer that is closest to the argument.

```
--> uint16(5+2*i)

ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> uint16('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> uint16({4})
```

Error: Cannot perform type conversions with this type

13.19 UINT32 Convert to Unsigned 32-bit Integer

13.19.1 Usage

Converts the argument to an unsigned 32-bit Integer. The syntax for its use is

```
y = uint32(x)
```

where x is an n-dimensional numerical array. Conversion follows saturation rules (e.g., if x is outside the normal range for an unsigned 32-bit integer of [0,4294967295], it is truncated to that range. Note that both NaN and Inf both map to 0.

13.19.2 Example

The following piece of code demonstrates several uses of uint32.

```
--> uint32(200)
ans =
200
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the maximum value of the data type.

```
--> uint32(40e9)
ans =
4294967295
```

In the next example, a negative integer is passed in. The result is truncated to zero.

```
--> uint32(-100)
ans =
0
```

In the next example, a positive double precision argument is passed in. The result is the unsigned integer that is closest to the argument.

```
--> uint32(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the complex unsigned integer that is closest to the argument.

```
--> uint32(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> uint32('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> uint32({4})
Error: Cannot perform type conversions with this type
```

13.20 UINT64 Convert to Unsigned 64-bit Integer

13.20.1 Usage

Converts the argument to an unsigned 64-bit Integer. The syntax for its use is

```
y = uint64(x)
```

where x is an n-dimensional numerical array. Conversion follows saturation rules (e.g., if x is outside the normal range for an unsigned 64-bit integer of [0,2^64-1], it is truncated to that range. Note that both NaN and Inf both map to 0.

13.20.2 Example

The following piece of code demonstrates several uses of uint64.

```
--> uint64(200)
ans =
200
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the maximum value of the data type.

```
--> uint64(40e9)
ans =
40000000000
```

In the next example, a negative integer is passed in. The result is zero.

```
--> uint64(-100)
ans =
0
```

In the next example, a positive double precision argument is passed in. The result is the unsigned integer that is closest to the argument.

```
--> uint64(pi)
ans =
3
```

In the next example, a complex argument is passed in. The result is the complex unsigned integer that is closest to the argument.

```
--> uint64(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> uint64('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> uint64({4})
```

Error: Cannot perform type conversions with this type

13.21 UINT8 Convert to Unsigned 8-bit Integer

13.21.1 Usage

Converts the argument to an unsigned 8-bit Integer. The syntax for its use is

```
y = uint8(x)
```

where x is an n-dimensional numerical array. Conversion follows saturation rules (e.g., if x is outside the normal range for an unsigned 8-bit integer of [0,255], it is truncated to that range. Note that both NaN and Inf both map to 0.

13.21.2 Example

The following piece of code demonstrates several uses of uint8.

```
--> uint8(200)
ans =
200
```

In the next example, an integer outside the range of the type is passed in. The result is truncated to the maximum value of the data type.

```
--> uint8(400)
ans =
255
```

In the next example, a negative integer is passed in. The result is trunated to zero.

```
--> uint8(-100)
ans =
0
```

In the next example, a positive double precision argument is passed in. The result is the unsigned integer that is closest to the argument.

```
--> uint8(pi)
ans =
```

In the next example, a complex argument is passed in. The result is complex unsigned integer that is closest to the argument.

```
--> uint8(5+2*i)
ans =
5.0000 + 2.0000i
```

In the next example, a string argument is passed in. The string argument is converted into an integer array corresponding to the ASCII values of each character.

```
--> uint8('helo')
ans =
104 101 108 111
```

In the last example, a cell-array is passed in. For cell-arrays and structure arrays, the result is an error.

```
--> uint8({4})
Error: Cannot perform type conversions with this type
```

Chapter 14

Array Generation and Manipulations

14.1 ASSIGN Making assignments

14.1.1 Usage

FreeMat assignments take a number of different forms, depending on the type of the variable you want to make an assignment to. For numerical arrays and strings, the form of an assignment is either

```
a(ndx) = val
```

where ndx is a set of vector indexing coordinates. This means that the values ndx takes reference the elements of a in column order. So, if, for example a is an N x M matrix, the first column has vector indices 1,2,...,N, and the second column has indices N+1,N+2,...,2N, and so on. Alternately, you can use multi-dimensional indexing to make an assignment:

$$a(ndx_1,ndx_2,...,ndx_m) = val$$

where each indexing expression ndx_i corresponds to the i-th dimension of a. In both cases, (vector or multi-dimensional indexing), the right hand side val must either be a scalar, an empty matrix, or of the same size as the indices. If val is an empty matrix, the assignment acts like a delete. Note that the type of a may be modified by the assignment. So, for example, assigning a double value to an element of a float array a will cause the array a to become double.

For cell arrays, the above forms of assignment will still work, but only if val is also a cell array. If you want to assign the contents of a cell in a cell array, you must use one of the two following forms, either

```
a{ndx} = val
or
a{ndx_1,ndx_2,...,ndx_m} = val
which will modify the contents of the cell.
```

14.2 CELL Cell Array of Empty Matrices

14.2.1 Usage

Creates a cell array of empty matrix entres. Two separate syntaxes are possible. The first syntax specifies the array dimensions as a sequence of scalar dimensions:

```
y = cell(d1, d2, ..., dn).
```

The resulting array has the given dimensions, and is filled with all zeros. The type of y is cell, a cell array.

The second syntax specifies the array dimensions as a vector, where each element in the vector specifies a dimension length:

```
y = cell([d1, d2, ..., dn]).
```

This syntax is more convenient for calling zeros using a variable for the argument. In both cases, specifying only one dimension results in a square matrix output.

14.2.2 Example

--> cell(2,3,2)

The following examples demonstrate generation of some zero arrays using the first form.

```
ans =
(:,:,1) =
 [] [] []
 [] []
(:,:,2) =
 [] [] []
 [] [] []
--> cell(1,3)
ans =
 [] [] []
The same expressions, using the second form.
--> cell([2,6])
ans =
 --> cell([1,3])
```

```
ans = [] []
```

14.3 CIRCSHIFT Circularly Shift an Array

14.3.1 USAGE

Applies a circular shift along each dimension of a given array. The syntax for its use is

```
y = circshift(x,shiftvec)
```

where x is an n-dimensional array, and shiftvec is a vector of integers, each of which specify how much to shift x along the corresponding dimension.

14.3.2 Example

The following examples show some uses of circshift on N-dimensional arrays.

```
--> x = int32(rand(4,5)*10)
x =
 5 1 5 5 9
 5 7 3 0 5
 8 4 9 9 10
 2 9 7 2 8
--> circshift(x,[1,0])
ans =
 2 9
      7
         2 8
 5 1
      5 5 9
 5 7
      3 0 5
 8 4 9 9 10
--> circshift(x,[0,-1])
ans =
 1 5 5 9 5
 7 3 0 5 5
 4 9 9 10 8
 9 7 2 8 2
--> circshift(x,[2,2])
ans =
 9 10 8 4 9
```

```
2 8 2 9 7
 5 9 5 1 5
 0 5 5 7 3
--> x = int32(rand(4,5,3)*10)
x =
(:,:,1) =
 4 4 5 10 8
 5 1 7 4 6
 8 6 3 5 8
 1 4 3 3 4
(:,:,2) =
 9 8 8 4 7
 7 7 4 5 8
 8 5 9 5 6
 8 2 5 1 3
(:,:,3) =
 6 9 2 1 10
1 6 7 9 9
10 10 2 6 1
7 4 0 6 4
--> circshift(x,[1,0,0])
ans =
(:,:,1) =
 1 4 3 3 4
 4 4 5 10 8
 5 1 7 4 6
 8 6 3 5 8
(:,:,2) =
 8 2 5 1 3
 9 8 8 4 7
 7 7 4 5 8
 8 5 9 5 6
(:,:,3) =
 7 4 0 6 4
```

6 9 2 1 10 1 6 7 9 9

```
10 10 2 6 1
--> circshift(x,[0,-1,0])
ans =
(:,:,1) =
 4 5 10 8 4
 1 7 4 6 5
 6 3 5 8 8
 4 3 3 4 1
(:,:,2) =
 8 8 4 7 9
 7 4 5 8 7
 5 9 5 6 8
 2 5 1 3 8
(:,:,3) =
 9 2 1 10 6
 6 7 9 9 1
10 2 6 1 10
4 0 6 4 7
--> circshift(x,[0,0,-1])
ans =
(:,:,1) =
 9 8 8 4 7
 7 7 4 5 8
 8 5 9 5 6
 8 2 5 1 3
(:,:,2) =
 6 9 2 1 10
 1 6 7 9 9
10 10 2 6 1
 7 4 0 6 4
(:,:,3) =
 4 4 5 10 8
 5 1 7 4 6
 8 6 3 5 8
```

1 4 3 3 4

```
--> circshift(x,[2,-3,1])
ans =
(:,:,1) =
 6 1 10 10 2
 6 4 7 4 0
 1 10 6 9 2
   9 1 6 7
(:,:,2) =
 5 8 8
        6 3
 3 4 1 4 3
10 8 4 4 5
 4 6 5 1 7
(:,:,3) =
 5 6 8 5 9
 1 3 8 2 5
   7 9 8 8
   8 7 7 4
```

14.4 COND Condition Number of a Matrix

14.4.1 Usage

Calculates the condition number of a matrix. To compute the 2-norm condition number of a matrix (ratio of largest to smallest singular values), use the syntax

```
y = cond(A)
```

where A is a matrix. If you want to compute the condition number in a different norm (e.g., the 1-norm), use the second syntax

```
y = cond(A,p)
```

where p is the norm to use when computing the condition number. The following choices of p are supported

- p = 1 returns the 1-norm, or the max column sum of A
- p = 2 returns the 2-norm (largest singular value of A)
- p = inf returns the infinity norm, or the max row sum of A
- p = 'fro' returns the Frobenius-norm (vector Euclidean norm, or RMS value)

14.4.2 Function Internals

The condition number is defined as

$$\frac{\|A\|_p}{\|A^{-1}\|_p}$$

This equation is precisely how the condition number is computed for the case $p \sim 2$. For the p=2 case, the condition number can be computed much more efficiently using the ratio of the largest and smallest singular values.

14.4.3 Example

The condition number of this matrix is large

14.5 DET Determinant of a Matrix

14.5.1 Usage

Calculates the determinant of a matrix. Note that for all but very small problems, the determinant is not particularly useful. The condition number cond gives a more reasonable estimate as to the suitability of a matrix for inversion than comparing det(A) to zero. In any case, the syntax for its use is

$$y = det(A)$$

where A is a square matrix.

14.5.2 Function Internals

The determinant is calculated via the LU decomposition. Note that the determinant of a product of matrices is the product of the determinants. Then, we have that

$$LU = PA$$

where L is lower triangular with 1s on the main diagonal, U is upper triangular, and P is a row-permutation matrix. Taking the determinant of both sides yields

$$|LU| = |L||U| = |U| = |PA| = |P||A|$$

where we have used the fact that the determinant of L is 1. The determinant of P (which is a row exchange matrix) is either 1 or -1.

14.5.3 Example

Here we assemble a random matrix and compute its determinant

```
--> A = rand(5);
--> det(A)
ans =
-0.1160
```

Then, we exchange two rows of A to demonstrate how the determinant changes sign (but the magnitude is the same)

```
--> B = A([2,1,3,4,5],:);
--> det(B)
ans =
0.1160
```

14.6 DIAG Diagonal Matrix Construction/Extraction

14.6.1 Usage

The diag function is used to either construct a diagonal matrix from a vector, or return the diagonal elements of a matrix as a vector. The general syntax for its use is

```
y = diag(x,n)
```

If x is a matrix, then y returns the n-th diagonal. If n is omitted, it is assumed to be zero. Conversely, if x is a vector, then y is a matrix with x set to the n-th diagonal.

14.6.2 Examples

Here is an example of diag being used to extract a diagonal from a matrix.

```
--> A = int32(10*rand(4,5))
A =
2 8 3 2 2
6 8 6 8 5
8 9 3 9 0
8 3 7 8 2
--> diag(A)
ans =
2
8
 3
8
--> diag(A,1)
ans =
8
6
 9
Here is an example of the second form of diag, being used to construct a diagonal matrix.
--> x = int32(10*rand(1,3))
 1 1 10
--> diag(x)
ans =
 1 0 0
 0 1 0
 0 0 10
--> diag(x,-1)
ans =
  0 0 0 0
  1 0 0 0
```

14.7 EXPM Matrix Exponential

14.7.1 Usage

Calculates e^A for a square, full rank matrix A. The syntax for its use is

$$y = expm(A)$$

Internally, expm is mapped to a simple e^A expression (which in turn uses the eigenvalue expansion of A to compute the exponential).

14.7.2 Example

An example of expm

```
--> A = [1 1 0; 0 0 2; 0 0 -1]
    1 0
 1
 0 0 2
 0 0 -1
--> expm(A)
ans =
   2.7183
                       1.0862
             1.7183
        0
             1.0000
                       1.2642
             0.0000
        0
                       0.3679
```

14.8 EYE Identity Matrix

14.8.1 USAGE

Creates an identity matrix of the specified size. The syntax for its use is

$$y = eye(n)$$

where n is the size of the identity matrix. The type of the output matrix is float.

14.8.2 Example

The following example demonstrates the identity matrix.

```
--> eye(3)
ans =
1 0 0
0 1 0
```

0 0 1

14.9 FIND Find Non-zero Elements of An Array

14.9.1 Usage

Returns a vector that contains the indicies of all non-zero elements in an array. The usage is

$$y = find(x)$$

The indices returned are generalized column indices, meaning that if the array x is of size [d1,d2,...,dn], and the element x(i1,i2,...,in) is nonzero, then y will contain the integer

$$i_1 + (i_2 - 1)d_1 + (i_3 - 1)d_1d_2 + \dots$$

The second syntax for the find command is

$$[r,c] = find(x)$$

which returns the row and column index of the nonzero entries of x. The third syntax for the find command also returns the values

$$[r,c,v] = find(x)$$
.

Note that if the argument is a row vector, then the returned vectors are also row vectors. This form is particularly useful for converting sparse matrices into IJV form.

The find command also supports some additional arguments. Each of the above forms can be combined with an integer indicating how many results to return:

```
y = find(x,k)
```

where k is the maximum number of results to return. This form will return the first k results. You can also specify an optional flag indicating whether to take the first or last k values:

```
y = find(x,k,'first')
y = find(x,k,'last')
```

in the case of the 'last' argument, the last k values are returned.

14.9.2 Example

Some simple examples of its usage, and some common uses of find in FreeMat programs.

```
--> a = [1,2,5,2,4];
--> find(a==2)
ans =
2 4
```

Here is an example of using find to replace elements of A that are 0 with the number 5.

9 -->
$$A(n) = 5$$

6

Incidentally, a better way to achieve the same concept is:

$$-->$$
 A = [1,0,3;0,2,1;3,0,0]

```
A =
1 0 3
0 2 1
3 0 0
--> A(A==0) = 5
A =
1 5 3
5 2 1
3 5 5
```

Now, we can also return the indices as row and column indices using the two argument form of find:

```
--> A = [1,0,3;0,2,1;3,0,0]
A =
1 0 3
0 2 1
3 0 0
--> [r,c] = find(A)
r =
1
3
2
 1
2
c =
1
 1
2
```

Or the three argument form of find, which returns the value also:

```
--> [r,c,v] = find(A)
r =
1
3
2
 1
 2
c =
1
1
 2
3
3
v =
1
3
2
3
 1
```

14.10 FLIPDIM Reverse a Matrix Along a Given Dimension

14.10.1 USAGE

Reverses an array along the given dimension. The syntax for its use is

```
y = flipdim(x,n)
```

where x is matrix, and n is the dimension to reverse.

14.10.2 Example

The following examples show some uses of flipdim on N-dimensional arrays.

```
The following examples show some

--> x = int32(rand(4,5,3)*10)

x =

(:,:,1) =
    5     4     5     3     9
    7     7     5     6     7
    1     6     8     4     1
    5     7     1     8     8

(:,:,2) =
    4     1     2     2     2
    5     2     3     5     4
```

5 2 3 5 4 0 3 6 8 7 9 2 3 10 8

(:,:,3) = 6 8 9 5 5 5 5 4 4 2 9 8 0 3 0 10 0 2 6 9 0

--> flipdim(x,1)

ans =

```
(:,:,1) = 5 7 1 8 8 1 6 8 4 1 7 7 5 6 7 5 4 5 3 9
```

(:,:,2) =

- 9 2 3 10 8
- 0 3 6 8 7
- 5 2 3 5 4
- 4 1 2 2 2
- (:,:,3) =
 - 0 2 6 9 0
 - 8 0 3 0 10
- 5 4 4 2 9
- 6 8 9 5 5
- --> flipdim(x,2)
- ans =
- (:,:,1) =
- 9 3 5 4 5
- 7 6 5 7 7
- 1 4 8 6 1
- 8 8 1 7 5
- (:,:,2) =
 - 2 2 2 1 4
 - 4 5 3 2 5
 - 7 8 6 3 0
- 8 10 3 2 9
- (:,:,3) =
- 5 5 9 8 6
- 9 2 4 4 5
- 10 0 3 0 8
- 0 9 6 2 0
- --> flipdim(x,3)
- ans =
- (:,:,1) =
 - 6 8 9 5 5
 - 5 4 4 2 9
 - 8 0 3 0 10
 - 0 2 6 9 0
- (:,:,2) =
 - 4 1 2 2 2
 - 5 2 3 5 4

```
0 3 6 8 7
9 2 3 10 8
(:,:,3) =
5 4 5 3 9
7 7 5 6 7
1 6 8 4 1
5 7 1 8 8
```

14.11 FLIPLR Reverse the Columns of a Matrix

14.11.1 USAGE

Reverses the columns of a matrix. The syntax for its use is

```
y = fliplr(x)
```

where x is matrix. If x is an N-dimensional array then the second dimension is reversed.

14.11.2 Example

The following example shows fliplr applied to a 2D matrix.

```
--> x = int32(rand(4)*10)

x =
6 2 7 1
1 10 10 4
7 7 6 3
8 0 8 5

--> fliplr(x)

ans =
1 7 2 6
4 10 10 1
3 6 7 7
5 8 0 8
```

For a 3D array, note how the columns in each slice are flipped.

```
--> x = int32(rand(4,4,3)*10)
x =
(:,:,1) =
2 10 7 5
```

```
0 4 5 6
 6 2 3 5
 2 0 9
(:,:,2) =
 3 3 8 5
 1 7 2 5
 4 6 8 4
 7 1 6 1
(:,:,3) =
 3 3 9
        2
 5 3 7
        6
 3 3 3 9
 6 4 0 8
--> fliplr(x)
ans =
(:,:,1) =
 5 7 10 2
 6 5 4 0
 5 3 2
        6
 6 9 0
(:,:,2) =
 5 8 3
        3
 5 2 7 1
 4 8 6 4
 1
   6 1
        7
(:,:,3) =
 2 9 3 3
 6 7 3 5
 9 3 3
        3
```

14.12 FLIPUD Reverse the Columns of a Matrix

14.12.1 USAGE

Reverses the rows of a matrix. The syntax for its use is

```
y = flipud(x)
```

where x is matrix. If x is an N-dimensional array then the first dimension is reversed.

14.12.2 Example

--> x = int32(rand(4)*10)

The following example shows flipud applied to a 2D matrix.

```
x =
 0 7 2 6
 5 7 10 1
 2 6 8 0
 1 0 9 8
--> flipud(x)
ans =
 1 0 9 8
 2 6 8 0
 5 7 10 1
 0 7 2 6
For a 3D array, note how the rows in each slice are flipped.
--> x = int32(rand(4,4,3)*10)
x =
(:,:,1) =
 8 4 6 7
 6 0 7 6
 8 9 9 0
 1 2 10 5
(:,:,2) =
 9 6 2 8
 3 10 1 7
 6 10 9 8
 3 2 4 2
(:,:,3) =
 3 1 5 0
 0 6 5 1
 9 4 9 2
 6 10 8 10
--> flipud(x)
ans =
```

```
(:,:,1) =
 1 2 10 5
 8 9 9
 6 0 7 6
 8 4 6 7
(:,:,2) =
 3 2 4
         2
 6 10 9 8
 3 10 1 7
 9 6 2 8
(:,:,3) =
 6 10 8 10
 9 4 9
         2
 0 6 5 1
 3 1 5 0
```

14.13 IPERMUTE Array Inverse Permutation Function

14.13.1 Usage

The ipermute function rearranges the contents of an array according to the inverse of the specified permutation vector. The syntx for its use is

```
y = ipermute(x,p)
```

where p is a permutation vector - i.e., a vector containing the integers 1...ndims(x) each occurring exactly once. The resulting array y contains the same data as the array x, but ordered according to the inverse of the given permutation. This function and the permute function are inverses of each other.

14.13.2 Example

First we create a large multi-dimensional array, then permute it and then inverse permute it, to retrieve the original array:

```
--> A = randn(13,5,7,2);

--> size(A)

ans =

13 5 7 2

--> B = permute(A,[3,4,2,1]);

--> size(B)
```

ans =

(:,:,4,2) = 0 0 0 0 0

14.14 ISFLOAT Test for Floating Point Array

14.14.1 Usage

The syntax for isfloat is

```
x = isfloat(y)
```

and it returns a logical 1 if the argument is a floating point array (i.e., a single or double), and a logical 0 otherwise.

14.15 ISINTEGER Test for Integer Array

14.15.1 Usage

The syntax for isinteger is

```
x = isinteger(y)
```

and it returns a logical 1 if the argument is an integer. The decision of whether the argument is an integer or not is made based on the class of y, not on its value.

14.16 LINSPACE Linearly Spaced Vector

14.16.1 Usage

Generates a row vector with the specified number of elements, with entries uniformly spaced between two specified endpoints. The syntax for its use is either

```
y = linspace(a,b,count)
or, for a default count = 100,
y = linspace(a,b);
```

14.16.2 Examples

```
Here is a simple example of using linspace
```

```
--> x = linspace(0,1,5)
x = 0 0.2500 0.5000 0.7500 1.0000
```

14.17 LOGSPACE Logarithmically Spaced Vector

14.17.1 Usage

Generates a row vector with the specified number number of elements, with entries logarithmically spaced between two specified endpoints. The syntax for its use is either

```
y = logspace(a,b,count)
or, for a default count = 50,
    y = logspace(a,b)
A third special use is when
    y = logspace(a,pi)
where it generates points between 10^a and pi
    Contributed by Paulo Xavier Candeias under GPL.
```

14.17.2 Example

```
Here is an example of the use of logspace
```

```
--> logspace(1,2,3)

ans =
   10.0000   31.6228   100.0000
```

14.18 MESHGRID Generate Grid Mesh For Plots

14.18.1 Usage

The meshgrid function generates arrays that can be used for the generation of surface plots. The syntax is one of

```
[X,Y] = meshgrid(x)
[X,Y] = meshgrid(x,y)
[X,Y,Z] = meshgrid(x,y,z)
```

where x,y,z are vectors, and X,Y,Z are matrices. In the first case [X,Y] = meshgrid(x), the rows of X and the columns of Y contain copies of the vector x. In the second case [X,Y] = meshgrid(x,y), the rows of X contain copies of x, and the columns of Y contain copies of y. In the third case, each input is copied along the row, column or slice direction of the corresponding output variable.

14.18.2 Example

```
In the first example:
```

```
--> [X,Y] = meshgrid(-2:.4:2)
X =
```

```
Columns 1 to 6
```

```
-2.0000
          -1.6000
                     -1.2000
                                -0.8000
                                          -0.4000
                                                      0.0000
-2.0000
                                          -0.4000
          -1.6000
                     -1.2000
                                -0.8000
                                                      0.0000
-2.0000
          -1.6000
                     -1.2000
                                -0.8000
                                          -0.4000
                                                      0.0000
-2.0000
          -1.6000
                     -1.2000
                                -0.8000
                                          -0.4000
                                                      0.0000
-2.0000
          -1.6000
                     -1.2000
                                -0.8000
                                          -0.4000
                                                      0.0000
-2.0000
          -1.6000
                     -1.2000
                                -0.8000
                                          -0.4000
                                                      0.0000
          -1.6000
                     -1.2000
                               -0.8000
                                          -0.4000
-2.0000
                                                      0.0000
-2.0000
          -1.6000
                     -1.2000
                               -0.8000
                                          -0.4000
                                                      0.0000
-2.0000
          -1.6000
                                -0.8000
                                          -0.4000
                     -1.2000
                                                      0.0000
-2.0000
          -1.6000
                     -1.2000
                                -0.8000
                                          -0.4000
                                                      0.0000
-2.0000
                                -0.8000
                                          -0.4000
          -1.6000
                     -1.2000
                                                      0.0000
```

Columns 7 to 11

0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000
0.4000	0.8000	1.2000	1.6000	2.0000

Y =

Columns 1 to 6

```
-1.2000
            -1.2000
                       -1.2000
                                  -1.2000
                                             -1.2000
                                                       -1.2000
  -0.8000
            -0.8000
                       -0.8000
                                  -0.8000
                                             -0.8000
                                                       -0.8000
  -0.4000
            -0.4000
                       -0.4000
                                  -0.4000
                                             -0.4000
                                                       -0.4000
   0.0000
                        0.0000
             0.0000
                                   0.0000
                                              0.0000
                                                         0.0000
   0.4000
             0.4000
                        0.4000
                                   0.4000
                                              0.4000
                                                         0.4000
   0.8000
             0.8000
                        0.8000
                                   0.8000
                                              0.8000
                                                         0.8000
   1.2000
             1.2000
                        1.2000
                                   1.2000
                                              1.2000
                                                         1.2000
   1.6000
             1.6000
                        1.6000
                                   1.6000
                                              1.6000
                                                         1.6000
                        2.0000
                                                         2.0000
   2.0000
             2.0000
                                   2.0000
                                              2.0000
Columns 7 to 11
  -2.0000
            -2.0000
                       -2.0000
                                  -2.0000
                                             -2.0000
  -1.6000
            -1.6000
                       -1.6000
                                  -1.6000
                                             -1.6000
  -1.2000
            -1.2000
                       -1.2000
                                  -1.2000
                                             -1.2000
  -0.8000
            -0.8000
                       -0.8000
                                  -0.8000
                                             -0.8000
  -0.4000
            -0.4000
                       -0.4000
                                  -0.4000
                                             -0.4000
   0.0000
             0.0000
                        0.0000
                                   0.0000
                                              0.0000
   0.4000
             0.4000
                        0.4000
                                   0.4000
                                              0.4000
   0.8000
             0.8000
                        0.8000
                                   0.8000
                                              0.8000
```

1.2000

1.6000

2.0000

1.2000

1.6000

2.0000

1.2000

1.6000

2.0000

Next, we use different vectors for X and for Y:

1.2000

1.6000

2.0000

1.2000

1.6000

2.0000

```
--> [X,Y] = meshgrid([1,2,3,4],[6,7,8])
X =
    1 2 3 4
    1 2 3 4
    1 2 3 4

Y =
    6 6 6 6
    7 7 7 7
    8 8 8 8
```

14.19 NAN Not-a-Number Constant

14.19.1 Usage

Returns a value that represents "not-a-number" for both 32 and 64-bit floating point values. This constant is meant to represent the result of arithmetic operations whose output cannot be meaningfully defined (like zero divided by zero). There are several forms for the NaN function. The first form returns a double precision NaN.

```
y = nan
```

The next form takes a class name that can be either 'double'

```
y = nan('double')
or 'single':
  y = nan('single')
```

With a single parameter it generates a square matrix of nans.

```
y = nan(n)
```

Alternatively, you can specify the dimensions of the array via

```
y = nan(m,n,p,...)
or
y = nan([m,n,p,...])
```

Finally, you can add a classname of either 'single' or 'double'.

14.19.2 Example

The following examples demonstrate a few calculations with the not-a-number constant.

```
--> nan*0

ans =
NaN

--> nan-nan

ans =
NaN
```

Note that NaNs are preserved under type conversion to floating point types (i.e., float, double, complex and dcomplex types), but not integer types.

```
--> uint32(nan)

ans =
0

--> complex(nan)

ans =
NaN
```

14.20 NDGRID Generate N-Dimensional Grid

14.20.1 Usage

Generates N-dimensional grids, each of which is constant in all but one dimension. The syntax for its use is either

which is equivalent to the first form, with x1=x2=...=xn. Each output yi is an n-dimensional array, with values such that

$$y_i(d_1, \dots, d_{i-1}, d_i, d_{i+1}, \dots, d_m) = x_i(d_i)$$

ndgrid is useful for evaluating multivariate functionals over a range of arguments. It is a generalization of meshgrid, except that meshgrid transposes the dimensions corresponding to the first two arguments to better fit graphical applications.

14.20.2 Example

Here is a simple ndgrid example

```
--> [a,b] = ndgrid(1:2,3:5)
a =
 1 1 1
 2 2 2
b =
3 4 5
3 4 5
--> [a,b,c] = ndgrid(1:2,3:5,0:1)
(:,:,1) =
 1 1 1
 2 2 2
(:,:,2) =
 1 1 1
 2 2 2
b =
(:,:,1) =
3 4 5
```

```
3 4 5

(:,:,2) =
3 4 5
3 4 5

c =

(:,:,1) =
0 0 0
0 0 0

(:,:,2) =
1 1 1
1 1 1
```

Here we use the second form

--> [a,b,c] = ndgrid(1:3)

Warning: Newly defined variable nargin shadows a function of the same name. Use clear nargin to recove a =

```
(:,:,1) =
1 1 1
2 2 2
3 3 3
(:,:,2) =
1 1 1
2 2 2
3 3 3
(:,:,3) =
1 1 1
2 2 2
3 3 3
b =
(:,:,1) =
```

(:,:,2) = 1 2 3 1 2 3

```
1 2 3
(:,:,3) =
1 2 3
1 2 3
1 2 3
c =
(:,:,1) =
1 1 1
 1 1 1
 1 1 1
(:,:,2) =
2 2 2
2 2 2
2 2 2
(:,:,3) =
3 3 3
3 3 3
3 3 3
```

14.21 NONZEROS Retrieve Nonzero Matrix Entries

14.21.1 USAGE

Returns a dense column vector containing the nonzero elements of the argument matrix. The syntax for its use is

```
y = nonzeros(x)
```

where x is the argument array. The argument matrix may be sparse as well as dense.

14.21.2 Example

Here is an example of using nonzeros on a sparse matrix.

```
--> a = rand(8); a(a>0.2) = 0;

--> A = sparse(a)

A =

4 1 0.150467

6 1 0.119605

7 1 0.0450479

3 3 0.0592569
```

```
4 3 0.185718
3 4 0.064163
7 4 0.196438
8 4 0.103669
4 5 0.160639
2 6 0.0545093
5 6 0.0226881
8 6 0.0202693
1 7 0.192362
6 8 0.101635
7 8 0.147931
--> nonzeros(A)
Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t
Warning: Newly defined variable j shadows a function of the same name. Use clear j to recover access t
ans =
   0.1505
   0.1196
   0.0450
   0.0593
   0.1857
```

NORM Norm Calculation

14.22.1Usage

14.22

0.0642 0.1964 0.1037 0.1606 0.0545 0.0227 0.0203 0.1924 0.1016 0.1479

Calculates the norm of a matrix. There are two ways to use the norm function. The general syntax

```
y = norm(A,p)
```

where A is the matrix to analyze, and p is the type norm to compute. The following choices of p are supported

- p = 1 returns the 1-norm, or the max column sum of A
- p = 2 returns the 2-norm (largest singular value of A)

- p = inf returns the infinity norm, or the max row sum of A
- p = 'fro' returns the Frobenius-norm (vector Euclidean norm, or RMS value)

For a vector, the regular norm calculations are performed:

- 1 <= $p < inf returns sum(abs(A).^p)^(1/p)$
- p unspecified returns norm(A,2)
- $p = \inf returns max(abs(A))$
- $p = -\inf returns min(abs(A))$

14.22.2 Examples

Here are the various norms calculated for a sample matrix

```
--> A = float(rand(3,4))
A =
    0.0063
              0.2224
                         0.7574
                                    0.9848
    0.7319
              0.1965
                         0.7191
                                    0.7010
    0.8319
              0.6392
                         0.8905
                                    0.9280
--> norm(A,1)
ans =
    2.6138
--> norm(A,2)
ans =
NaN
--> norm(A,inf)
ans =
    3.2896
--> norm(A,'fro')
ans =
    2.4353
Next, we calculate some vector norms.
--> A = float(rand(4,1))
```

```
A =
    0.5011
    0.3269
    0.8192
    0.7321
--> norm(A,1)
ans =
    2.3792
--> norm(A,2)
ans =
    1.2510
--> norm(A,7)
ans =
    0.8671
--> norm(A,inf)
ans =
    0.8192
--> norm(A,-inf)
ans =
    0.3269
```

14.23 NUM2STR Convert Numbers To Strings

14.23.1 Usage

Converts an array into its string representation. The general syntax for this function is

```
s = num2str(X)
```

where **s** is a string (or string matrix) and **X** is an array. By default, the **num2str** function uses 4 digits of precision and an exponent if required. If you want more digits of precision, you can specify the precition via the form

```
s = num2str(X, precision)
```

where precision is the number of digits to include in the string representation. For more control over the format of the output, you can also specify a format specifier (see printf for more details).

```
s = num2str(X, format)
```

where format is the specifier string.

14.24 ONES Array of Ones

14.24.1 Usage

Creates an array of ones of the specified size. Two seperate syntaxes are possible. The first syntax specifies the array dimensions as a sequence of scalar dimensions:

```
y = ones(d1, d2, ..., dn).
```

The resulting array has the given dimensions, and is filled with all ones. The type of y is float, a 32-bit floating point array. To get arrays of other types, use the typecast functions (e.g., uint8, int8, etc.).

The second syntax specifies the array dimensions as a vector, where each element in the vector specifies a dimension length:

```
y = ones([d1,d2,...,dn]).
```

This syntax is more convenient for calling ones using a variable for the argument. In both cases, specifying only one dimension results in a square matrix output.

14.24.2 Example

The following examples demonstrate generation of some arrays of ones using the first form.

```
--> ones(2,3,2)
ans =
(:,:,1) =
1 1 1
1 1 1
(:,:,2) =
1 1 1
1 1 1
--> ones(1,3)
ans =
1 1 1
```

The same expressions, using the second form.

```
--> ones([2,6])

ans =
    1 1 1 1 1 1
    1 1 1 1 1
    --> ones([1,3])

ans =
    1 1 1
```

Finally, an example of using the type casting function uint16 to generate an array of 16-bit unsigned integers with a value of 1.

```
--> uint16(ones(3))
ans =
1 1 1
1 1 1
1 1 1
```

14.25 PERMUTE Array Permutation Function

14.25.1 Usage

The permute function rearranges the contents of an array according to the specified permutation vector. The syntax for its use is

```
y = permute(x,p)
```

where p is a permutation vector - i.e., a vector containing the integers 1...ndims(x) each occurring exactly once. The resulting array y contains the same data as the array x, but ordered according to the permutation. This function is a generalization of the matrix transpose operation.

14.25.2 Example

Here we use permute to transpose a simple matrix (note that permute also works for sparse matrices):

```
--> A = [1,2;4,5]

A =
    1 2
    4 5

--> permute(A,[2,1])

ans =
```

```
1 4
2 5
--> A'
ans =
1 4
2 5
Now we permute a larger n-dimensional array:
--> A = randn(13,5,7,2);
--> size(A)
ans =
13 5 7 2
--> B = permute(A,[3,4,2,1]);
--> size(B)
ans =
7 2 5 13
```

14.26 PINV Moore-Penrose Pseudoinverse

14.26.1 Usage

Calculates the Moore-Penrose pseudoinverse of a matrix. The general syntax for its use is

```
y = pinv(A,tol)
```

or for a default specification of the tolerance tol,

```
y = pinv(A)
```

For any ${\tt m}$ ${\tt x}$ ${\tt n}$ matrix A, the Moore-Penrose pseudoinverse is the unique ${\tt n}$ ${\tt x}$ ${\tt m}$ matrix B that satisfies the following four conditions

- \bullet A B A = A
- \bullet B A B = B
- (A B)' = A B
- (B A), = B A

Also, it is true that B y is the minimum norm, least squares solution to A x = y. The Moore-Penrose pseudoinverse is computed from the singular value decomposition of A, with singular values smaller than tol being treated as zeros. If tol is not specified then it is chosen as

```
tol = max(size(A)) * norm(A) * teps(A).
```

14.26.2 Function Internals

The calculation of the MP pseudo-inverse is almost trivial once the svd of the matrix is available. First, for a real, diagonal matrix with positive entries, the pseudo-inverse is simply

$$\left(\Sigma^{+}\right)_{ii} = \begin{cases} 1/\sigma_{ii} & \sigma_{ii} > 0\\ 0 & \text{else} \end{cases}$$

One can quickly verify that this choice of matrix satisfies the four properties of the pseudoinverse. Then, the pseudoinverse of a general matrix A = U S V, is defined as

$$A^+ = VS^+U'$$

and again, using the facts that U' U = I and V V' = I, one can quickly verify that this choice of pseudoinverse satisfies the four defining properties of the MP pseudoinverse. Note that in practice, the diagonal pseudoinverse S^{+} is computed with a threshold (the tol argument to pinv) so that singular values smaller than tol are treated like zeros.

14.26.3 Examples

Consider a simple 1 x 2 matrix example, and note the various Moore-Penrose conditions:

```
--> A = float(rand(1,2))
    0.9526
               0.4847
--> B = pinv(A)
B =
    0.8338
    0.4243
--> A*B*A
ans =
    0.9526
               0.4847
--> B*A*B
ans =
    0.8338
    0.4243
--> A*B
ans =
```

```
1.0000
--> B*A
ans =
    0.7943
               0.4042
    0.4042
               0.2057
To demonstrate that pinv returns the least squares solution, consider the following very simple case
--> A = float([1;1;1;1])
A =
 1
 1
 1
The least squares solution to A x = b is just x = mean(b), and computing the pinv of A demon-
strates this
--> pinv(A)
ans =
    0.2500
               0.2500
                          0.2500
                                      0.2500
Similarly, we can demonstrate the minimum norm solution with the following simple case
--> A = float([1,1])
A =
 1 1
The solutions of A x = 5 are those x_1 and x_2 such that x_1 + x_2 = 5. The norm of x is
x_1^+ + x_2^2, which is x_1^2 + (5-x_1)^2, which is minimized for x_1 = x_2 = 2.5:
--> pinv(A) * 5.0
ans =
    2.5000
    2.5000
```

14.27 RANK Calculate the Rank of a Matrix

14.27.1 Usage

Returns the rank of a matrix. There are two ways to use the rank function is

```
y = rank(A,tol)
```

where tol is the tolerance to use when computing the rank. The second form is

```
y = rank(A)
```

in which case the tolerance tol is chosen as

```
tol = max(size(A))*max(s)*eps,
```

where **s** is the vector of singular values of **A**. The rank is computed using the singular value decomposition **svd**.

14.27.2 Examples

Some examples of matrix rank calculations

```
--> rank([1,3,2;4,5,6])
ans =
2
--> rank([1,2,3;2,4,6])
ans =
 1
Here we construct an ill-conditioned matrix, and show the use of the tol argument.
--> A = [1,0;0,eps/2]
A =
    1.0000
                     0
         0
               0.0000
--> rank(A)
ans =
1
--> rank(A,eps/8)
ans =
```

14.28 RCOND Reciprocal Condition Number Estimate

14.28.1 Usage

2

The rcond function is a FreeMat wrapper around LAPACKs function XGECON, which estimates the 1-norm condition number (reciprocal). For the details of the algorithm see the LAPACK documentation. The syntax for its use is

```
x = rcond(A)
```

where A is a matrix.

14.28.2 Example

Here is the reciprocal condition number for a random square matrix

```
--> A = rand(30);
--> rcond(A)
ans =
3.5040e-04
```

And here we calculate the same value using the definition of (reciprocal) condition number

```
--> 1/(norm(A,1)*norm(inv(A),1))
ans =
3.5040e-04
```

Note that the values are very similar. LAPACKs rcond function is far more efficient than the explicit calculation (which is also used by the cond function.

14.29 REPMAT Array Replication Function

14.29.1 Usage

The repmat function replicates an array the specified number of times. The source and destination arrays may be multidimensional. There are three distinct syntaxes for the repmap function. The first form:

```
y = repmat(x,n)
```

replicates the array x on an n-times-n tiling, to create a matrix y that has n times as many rows and columns as x. The output y will match x in all remaining dimensions. The second form is

```
y = repmat(x,m,n)
```

And creates a tiling of x with m copies of x in the row direction, and n copies of x in the column direction. The final form is the most general

```
y = repmat(x, [m n p...])
```

where the supplied vector indicates the replication factor in each dimension.

14.29.2 Example

Here is an example of using the **repmat** function to replicate a row 5 times. Note that the same effect can be accomplished (although somewhat less efficiently) by a multiplication.

```
--> x = [1 2 3 4]

x =
    1 2 3 4

--> y = repmat(x,[5,1])

y =
    1 2 3 4
    1 2 3 4
    1 2 3 4
    1 2 3 4
    1 2 3 4
```

The repmat function can also be used to create a matrix of scalars or to provide replication in arbitrary dimensions. Here we use it to replicate a 2D matrix into a 3D volume.

```
--> x = [1 2;3 4]

x =
    1 2
    3 4

--> y = repmat(x,[1,1,3])

y =
    (:,:,1) =
    1 2
    3 4

    (:,:,2) =
    1 2
    3 4

    (:,:,3) =
    1 2
    3 4
```

14.30 RESHAPE Reshape An Array

14.30.1 Usage

Reshapes an array from one size to another. Two seperate syntaxes are possible. The first syntax specifies the array dimensions as a sequence of scalar dimensions:

```
y = reshape(x,d1,d2,...,dn).
```

The resulting array has the given dimensions, and is filled with the contents of x. The type of y is the same as x. The second syntax specifies the array dimensions as a vector, where each element in the vector specifies a dimension length:

```
y = reshape(x,[d1,d2,...,dn]).
```

This syntax is more convenient for calling reshape using a variable for the argument. The reshape function requires that the length of x equal the product of the di values. Note that arrays are stored in column format, which means that elements in x are transferred to the new array y starting with the first column first element, then proceeding to the last element of the first column, then the first element of the second column, etc.

14.30.2 Example

Here are several examples of the use of **reshape** applied to various arrays. The first example reshapes a row vector into a matrix.

```
--> a = uint8(1:6)

a =
    1 2 3 4 5 6

--> reshape(a,2,3)

ans =
    1 3 5
    2 4 6
```

The second example reshapes a longer row vector into a volume with two planes.

```
--> a = uint8(1:12)

a =
    1 2 3 4 5 6 7 8 9 10 11 12

--> reshape(a,[2,3,2])

ans =
(:,:,1) =
```

```
1 3 5
2 4 6
(:,:,2) =
7 9 11
8 10 12
```

The third example reshapes a matrix into another matrix.

```
--> a = [1,6,7;3,4,2]

a =
    1 6 7
    3 4 2

--> reshape(a,3,2)

ans =
    1 4
    3 7
    6 2
```

14.31 RREF Reduced Row Echelon Form of a Matrix

14.31.1 Usage

Calculates the reduced row echelon form of a matrix using Gauss Jordan elimination with partial pivoting. The generic syntax for rref is

```
R = rref(A)
```

A default tolerance of max(size(A))*eps*norm(A,inf) is used to detect negligible column elements. The second form of rref returns a vector k as well as R

```
[R,k] = rref(A)
```

where k is a vector that correponds to the columns of A used as pivot columns. If you want to control the tolerance used to identify negligible elements, you can use the form

```
[R,k] = rref(A, tolerance)
```

This implementation of **rref** is based on the one from the matcompat lib for octave. It is copyright Paul Kienzle, and distributed under the GNU GPL.

14.32 SHIFTDIM Shift Array Dimensions Function

14.32.1 Usage

The shiftdim function is used to shift the dimensions of an array. The general syntax for the shiftdim function is

```
y = shiftdim(x,n)
```

where x is a multidimensional array, and n is an integer. If n is a positive integer, then shiftdim circularly shifts the dimensions of x to the left, wrapping the dimensions around as necessary. If n is a negative integer, then shiftdim shifts the dimensions of x to the right, introducing singleton dimensions as necessary. In its second form:

```
[y,n] = shiftdim(x)
```

the shiftdim function will shift away (to the left) the leading singleton dimensions of x until the leading dimension is not a singleton dimension (recall that a singleton dimension p is one for which size(x,p) == 1).

14.32.2 Example

Here are some simple examples of using shiftdim to remove the singleton dimensions of an array, and then restore them:

```
--> x = uint8(10*randn(1,1,1,3,2));
--> [y,n] = shiftdim(x);
--> n
ans =
3
--> size(y)
ans =
3 2
--> c = shiftdim(y,-n);
--> size(c)
ans =
1 1 1 3 2
--> any(c^=x)
ans =
(:,:,1,1,1) =
(:,:,1,1,2) =
```

Note that these operations (where shifting involves only singleton dimensions) do not actually cause data to be resorted, only the size of the arrays change. This is not true for the following example, which triggers a call to permute:

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```
--> z = shiftdim(x,4);

Note that z is now the transpose of x
--> squeeze(x)

ans =
0 0
0 3
0 0

--> squeeze(z)

ans =
0 0 0
0 3
0 0
0 3
```

14.33 SORT Sort

14.33.1 Usage

Sorts an n-dimensional array along the specified dimensional. The first form sorts the array along the first non-singular dimension.

```
B = sort(A)
```

Alternately, the dimension along which to sort can be explicitly specified

```
B = sort(A,dim)
```

FreeMat does not support vector arguments for dim - if you need A to be sorted along multiple dimensions (i.e., row first, then columns), make multiple calls to sort. Also, the direction of the sort can be specified using the mode argument

```
B = sort(A,dim,mode)
```

where mode = 'ascend' means to sort the data in ascending order (the default), and mode = 'descend' means to sort the data into descending order.

When two outputs are requested from sort, the indexes are also returned. Thus, for

```
[B,IX] = sort(A)
[B,IX] = sort(A,dim)
[B,IX] = sort(A,dim,mode)
```

an array IX of the same size as A, where IX records the indices of A (along the sorting dimension) corresponding to the output array B.

Two additional issues worth noting. First, a cell array can be sorted if each cell contains a string, in which case the strings are sorted by lexical order. The second issue is that FreeMat uses the same method as MATLAB to sort complex numbers. In particular, a complex number a is less than another complex number b if abs(a) < abs(b). If the magnitudes are the same then we test the angle of a, i.e. angle(a) < angle(b), where angle(a) is the phase of a between -pi,pi.

14.33.2 Example

Here are some examples of sorting on numerical arrays.

```
--> A = int32(10*rand(4,3))
A =
 8 9 3
 7 2 1
 3 0 3
 3 10 5
--> [B,IX] = sort(A)
B =
 3 0 1
 3 2 3
 7 9 3
 8 10 5
IX =
3 3 2
4 2 1
2 1 3
1 4 4
--> [B,IX] = sort(A,2)
B =
 3 8 9
 1 2 7
 0 3 3
 3 5 10
IX =
3 1 2
3 2 1
2 1 3
1 3 2
--> [B,IX] = sort(A,1,'descend')
B =
 8 10 5
 7 9 3
 3 2 3
 3 0 1
IX =
1 4 4
```

```
2 1 1
3 2 3
4 3 2

Here we sort a cell array of strings.

--> a = {'hello', 'abba', 'goodbye', 'jockey', 'cake'}
a =
  [hello] [abba] [goodbye] [jockey] [cake]

--> b = sort(a)
b =
```

[abba] [cake] [goodbye] [hello] [jockey]

14.34 SQUEEZE Remove Singleton Dimensions of an Array

14.34.1 Usage

This function removes the singleton dimensions of an array. The syntax for its use is

```
y = squeeze(x)
```

where x is a multidimensional array. Generally speaking, if x is of size $d1 \times 1 \times d2 \times \ldots$, then squeeze(x) is of size $d1 \times d2 \times \ldots$, i.e., each dimension of x that was singular (size 1) is squeezed out.

14.34.2 Example

Here is a many dimensioned, ungainly array, both before and after squeezing;

```
--> x = zeros(1,4,3,1,1,2);

--> size(x)

ans =

1 4 3 1 1 2

--> y = squeeze(x);

--> size(y)

ans =

4 3 2
```

14.35 SUBSREF Array Dereferencing

14.35.1 Usage

This function can be used to index into basic array types (or structures). It provides a functional interface to execute complex indexing expressions such as a.b(3){5} at run time (i.e. while executing a script or a function) without resorting to using eval. Note that this function should be overloaded for use with user defined classes, and that it cannot be overloaded for base types. The basic syntax of the function is:

```
b = subsref(a,s)
```

where s is a structure array with two fields. The first field is

- type is a string containing either '()' or '{}' or '.' depending on the form of the call.
- subs is a cell array or string containing the the subscript information.

When multiple indexing experssions are combined together such as $b = a(5).foo\{:\}$, the s array should contain the following entries

```
s(1).type = '()' s(1).subs = {5}
s(2).type = '.' s(2).subs = 'foo'
s(3).type = '{}' s(3).subs = ':'
```

14.36 TRANSPOSE Matrix Transpose

14.36.1 Usage

Performs a (nonconjugate) transpose of a matrix. The syntax for its use is

```
y = transpose(x)
and is a synonym for y = x.'.
```

14.36.2 Example

Here is an example of the transpose of a complex matrix. Note that the entries are not conjugated.

```
--> A = [1+i,2+i;3-2*i,4+2*i]

A =
    1.0000 + 1.0000i    2.0000 + 1.0000i
    3.0000 - 2.0000i    4.0000 + 2.0000i

--> transpose(A)

ans =
    1.0000 + 1.0000i    3.0000 - 2.0000i
    2.0000 + 1.0000i    4.0000 + 2.0000i
```

14.37 UNIQUE Unique

14.37.1 Usage

Returns a vector containing the unique elements of an array. The first form is simply

```
y = unique(x)
```

where x is either a numerical array or a cell-array of strings. The result is sorted in increasing order. You can also retrieve two sets of index vectors

```
[y, m, n] = unique(x)
```

such that y = x(m) and x = y(n). If the argument x is a matrix, you can also indicate that FreeMat should look for unique rows in the matrix via

```
y = unique(x,'rows')
and
[y, m, n] = unique(x,'rows')
```

14.37.2 Example

Here is an example in row mode

```
--> A = randi(1,3*ones(15,3))
A =
1 1 1
 3 2 2
 1 3 3
 2 2 1
 1 3 1
 2 3 1
 2 2 3
 1 2 2
 3 3 3
 2 1 1
 2 1 1
 2 3 2
 1 1 2
 2 3 1
3 3 2
--> unique(A,'rows')
ans =
1 1 1
```

```
1 1 2
1 2 2
1 3 1
1 3 3
2 1 1
2 2 1
2 2 3
2 3 1
2 3 2
3 2 2
3 3 2
3 3 3
--> [b,m,n] = unique(A,'rows');
--> b
ans =
1 1 1
1 1 2
1 2 2
1 3 1
1 3 3
2 1 1
2 2 1
2 2 3
2 3 1
2 3 2
3 2 2
3 3 2
3 3 3
--> A(m,:)
ans =
1 1 1
1 1 2
1 2 2
1 3 1
1 3 3
2 1 1
2 2 1
2 2 3
2 3 1
2 3 2
3 2 2
```

3 3 2

```
3 3 3
--> b(n,:)
ans =
1 1 1
3 2 2
1 3 3
2 2 1
1 3 1
2 3 1
2 2 3
1 2 2
3 3 3
2 1 1
2 1 1
2 3 2
1 1 2
2 3 1
3 3 2
Here is an example in vector mode
--> A = randi(1,5*ones(10,1))
A =
3
5
5
1
 3
 4
 1
5
 4
1
--> unique(A)
ans =
1
3
4
5
--> [b,m,n] = unique(A,'rows');
--> b
```

```
ans =
1
 3
 4
 5
--> A(m)
ans =
1
3
 4
 5
--> b(n)
ans =
 3
 5
 5
 1
 3
 4
 1
 5
 4
For cell arrays of strings.
--> A = {'hi', 'bye', 'good', 'tell', 'hi', 'bye'}
A =
 [hi] [bye] [good] [tell] [hi] [bye]
--> unique(A)
ans =
 [bye] [good] [hi] [tell]
```

14.38 XNRM2 BLAS Norm Calculation

14.38.1 Usage

Calculates the 2-norm of a vector. The syntax for its use is

```
y = xnrm2(A)
```

where A is the n-dimensional array to analyze. This form uses the underlying BLAS implementation to compute the 2-norm.

14.39 ZEROS Array of Zeros

14.39.1 Usage

Creates an array of zeros of the specified size. Two seperate syntaxes are possible. The first syntax specifies the array dimensions as a sequence of scalar dimensions:

```
y = zeros(d1, d2, ..., dn).
```

The resulting array has the given dimensions, and is filled with all zeros. The type of y is double, a 64-bit floating point array. To get arrays of other types, use the typecast functions (e.g., uint8, int8, etc.). An alternative syntax is to use the following notation:

```
y = zeros(d1,d2,...,dn,classname)
```

where classname is one of 'double', 'single', 'int8', 'uint8', 'int16', 'uint16', 'int32', 'uint32', 'int64', 'uint64', 'float', 'logical'.

The second syntax specifies the array dimensions as a vector, where each element in the vector specifies a dimension length:

```
y = zeros([d1,d2,...,dn]),
or
y = zeros([d1,d2,...,dn],classname).
```

This syntax is more convenient for calling zeros using a variable for the argument. In both cases, specifying only one dimension results in a square matrix output.

14.39.2 Example

The following examples demonstrate generation of some zero arrays using the first form.

```
--> zeros(2,3,2)

ans =

(:,:,1) =

0 0 0

0 0 0

(:,:,2) =

0 0 0

0 0 0
```

--> zeros(3,'int16')

```
--> zeros(1,3)
ans =
0 0 0
The same expressions, using the second form.
--> zeros([2,6])
ans =
0 0 0 0 0 0
0 0 0 0 0 0
--> zeros([1,3])
ans =
0 0 0
Finally, an example of using the type casting function uint16 to generate an array of 16-bit unsigned
integers with zero values.
--> uint16(zeros(3))
ans =
0 0 0
0 0 0
0 0 0
Here we use the second syntax where the class of the output is specified explicitly
```

Chapter 15

Random Number Generation

15.1 RAND Uniform Random Number Generator

15.1.1 Usage

Creates an array of pseudo-random numbers of the specified size. The numbers are uniformly distributed on [0,1). Two separate syntaxes are possible. The first syntax specifies the array dimensions as a sequence of scalar dimensions:

```
y = rand(d1,d2,...,dn).
```

The resulting array has the given dimensions, and is filled with random numbers. The type of y is double, a 64-bit floating point array. To get arrays of other types, use the typecast functions.

The second syntax specifies the array dimensions as a vector, where each element in the vector specifies a dimension length:

```
y = rand([d1,d2,...,dn]).
```

This syntax is more convenient for calling rand using a variable for the argument.

Finally, rand supports two additional forms that allow you to manipulate the state of the random number generator. The first retrieves the state

```
y = rand('state')
```

which is a 625 length integer vector. The second form sets the state

```
rand('state',y)
```

or alternately, you can reset the random number generator with

```
rand('state',0)
```

15.1.2 Example

The following example demonstrates an example of using the first form of the rand function.

```
--> rand(2,2,2)

ans =

(:,:,1) =
    0.3478    0.5313
    0.0276    0.9958

(:,:,2) =
    0.2079    0.7597
    0.4921    0.3365
```

The second example demonstrates the second form of the rand function.

```
--> rand([2,2,2])

ans =

(:,:,1) =
    0.8670    0.2174
    0.2714    0.6897

(:,:,2) =
    0.2305    0.3898
    0.1721    0.9545
```

The third example computes the mean and variance of a large number of uniform random numbers. Recall that the mean should be 1/2, and the variance should be 1/12 ~ 0.083.

```
--> x = rand(1,10000);

--> mean(x)

ans =

0.5023

--> var(x)

ans =

0.0840
```

Now, we use the state manipulation functions of rand to exactly reproduce a random sequence. Note that unlike using seed, we can exactly control where the random number generator starts by saving the state.

```
--> rand('state',0)
                         \mbox{\ensuremath{\mbox{\%}}} restores us to startup conditions
--> a = rand(1,3)
                         % random sequence 1
    0.3759
               0.0183
                          0.9134
--> b = rand('state'); % capture the state vector
--> c = rand(1,3)
                         % random sequence 2
c =
    0.3580
               0.7604
                          0.8077
--> rand('state',b);
                         % restart the random generator so...
--> c = rand(1,3)
                         % we get random sequence 2 again
    0.3580
               0.7604
                          0.8077
```

15.2 RANDBETA Beta Deviate Random Number Generator

15.2.1 Usage

Creates an array of beta random deviates based on the supplied two parameters. The general syntax for randbeta is

```
y = randbeta(alpha, beta)
```

where alpha and beta are the two parameters of the random deviate. There are three forms for calling randbeta. The first uses two vectors alpha and beta of the same size, in which case the output y is the same size as both inputs, and each deviate uses the corresponding values of alpha and beta from the arguments. In the other forms, either alpha or beta are scalars.

15.2.2 Function Internals

The probability density function (PDF) of a beta random variable is

$$f(x) = x^{(a-1)} * (1-x)^{(b-1)}/B(a,b)$$

for x between 0 and 1. The function B(a,b) is defined so that the integral of f(x) is 1.

15.2.3 Example

Here is a plot of the PDF of a beta random variable with a=3, b=7.

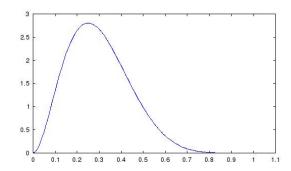
```
--> a = 3; b = 7;

--> x = (0:100)/100; t = x.^(a-1).*(1-x).^(b-1);
```

--> t =
$$t/(sum(t)*.01);$$

--> plot(x,t);

which is plotted as



If we generate a few random deviates with these values, we see they are distributed around the peak of roughly 0.25.

15.3 RANDBIN Generate Binomial Random Variables

15.3.1 Usage

Generates random variables with a binomial distribution. The general syntax for its use is

$$y = randbin(N,p)$$

where N is a vector representing the number of Bernoulli trials, and p is the success probability associated with each trial.

15.3.2 Function Internals

A Binomial random variable describes the number of successful outcomes from $\mathbb N$ Bernoulli trials, with the probability of success in each trial being p. The probability distribution is

$$P(n) = \frac{N!}{n!(N-n)!} p^{n} (1-p)^{N-n}$$

15.3.3 Example

Here we generate 10 binomial random variables, corresponding to N=100 trials, each with probability p=0.1, using both randbin and then again using rand (to simulate the trials):

```
--> randbin(100,.1*ones(1,10))

ans =
    13    6    8    9    11    9    6    9    7    10

--> sum(rand(100,10)<0.1)

ans =
    8    12    10    7    12    4    11    8    9    6
```

15.4 RANDCHI Generate Chi-Square Random Variable

15.4.1 Usage

Generates a vector of chi-square random variables with the given number of degrees of freedom. The general syntax for its use is

```
y = randchi(n)
```

where n is an array containing the degrees of freedom for each generated random variable.

15.4.2 Function Internals

A chi-square random variable is essentially distributed as the squared Euclidean norm of a vector of standard Gaussian random variables. The number of degrees of freedom is generally the number of elements in the vector. In general, the PDF of a chi-square random variable is

$$f(x) = \frac{x^{r/2 - 1}e^{-x/2}}{\Gamma(r/2)2^{r/2}}$$

15.4.3 Example

First, a plot of the PDF for a family of chi-square random variables

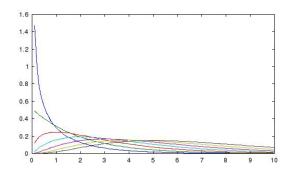
```
--> f = zeros(7,100);

--> x = (1:100)/10;

--> for n=1:7;t=x.^(n/2-1).*exp(-x/2);f(n,:)=10*t/sum(t);end

--> plot(x,f');
```

The PDF is below:



Here is an example of using randchi and randn to compute some chi-square random variables with four degrees of freedom.

--> randchi(4*ones(1,6)) ans = 4.0015 3.2578 8.9675 5.5461 2.5090 5.7587 --> sum(randn(4,6).^2) ans = 1.1941 10.6441 3.6228 8.4425 2.5031 1.9058

15.5 RANDEXP Generate Exponential Random Variable

15.5.1 Usage

Generates a vector of exponential random variables with the specified parameter. The general syntax for its use is

where lambda is a vector containing the parameters for the generated random variables.

15.5.2 Function Internals

The exponential random variable is usually associated with the waiting time between events in a Poisson random process. The PDF of an exponential random variable is:

$$f(x) = \lambda e^{-\lambda x}$$

15.5.3 Example

Here is an example of using the randexp function to generate some exponentially distributed random variables

--> randexp(ones(1,6))

ans =
 0.0608 0.0019 1.1266 0.2012 0.5079 3.4205

15.6 RANDF Generate F-Distributed Random Variable

15.6.1 Usage

Generates random variables with an F-distribution. The general syntax for its use is

$$y = randf(n,m)$$

where n and m are vectors of the number of degrees of freedom in the numerator and denominator of the chi-square random variables whose ratio defines the statistic.

15.6.2 Function Internals

The statistic $F_{n,m}$ is defined as the ratio of two chi-square random variables:

$$F_{n,m} = \frac{\chi_n^2/n}{\chi_m^2/m}$$

The PDF is given by

$$f_{n,m} = \frac{m^{m/2} n^{n/2} x^{n/2 - 1}}{(m + nx)^{(n+m)/2} B(n/2, m/2)},$$

where B(a,b) is the beta function.

15.6.3 Example

Here we use randf to generate some F-distributed random variables, and then again using the randchi function:

```
--> randf(5*ones(1,9),7)

ans =

Columns 1 to 6

1.1944  0.9069  0.7558  1.5029  0.0621  1.3860

Columns 7 to 9

1.8161  0.3755  3.5794

--> randchi(5*ones(1,9))./randchi(7*ones(1,9))
```

ans =

Columns 1 to 6

1.3085 1.2693 1.0684 0.4377 1.1158 0.7171

Columns 7 to 9

0.4151 1.8022 1.4606

15.7 RANDGAMMA Generate Gamma-Distributed Random Variable

15.7.1 Usage

Generates random variables with a gamma distribution. The general syntax for its use is

$$y = randgamma(a,r),$$

where a and r are vectors describing the parameters of the gamma distribution. Roughly speaking, if a is the mean time between changes of a Poisson random process, and we wait for the r change, the resulting wait time is Gamma distributed with parameters a and r.

15.7.2 Function Internals

The Gamma distribution arises in Poisson random processes. It represents the waiting time to the occurance of the r-th event in a process with mean time a between events. The probability distribution of a Gamma random variable is

$$P(x) = \frac{a^r x^{r-1} e^{-ax}}{\Gamma(r)}.$$

Note also that for integer values of r that a Gamma random variable is effectively the sum of r exponential random variables with parameter a.

15.7.3 Example

Here we use the randgamma function to generate Gamma-distributed random variables, and then generate them again using the randexp function.

```
--> randgamma(1,15*ones(1,9))

ans =

Columns 1 to 6

22.7804 11.5514 16.8537 12.7457 16.2303 10.7442
```

```
Columns 7 to 9
   19.3942
           16.3611
                       17.4772
--> sum(randexp(ones(15,9)))
ans =
Columns 1 to 6
   14.6404
            15.1860
                       13.3147
                                 11.4380
                                            7.2307
                                                     10.8225
Columns 7 to 9
   14.5271
            12.4631
                       11.8753
```

15.8 RANDI Uniformly Distributed Integer

15.8.1 Usage

Generates an array of uniformly distributed integers between the two supplied limits. The general syntax for randi is

```
y = randi(low,high)
```

where low and high are arrays of integers. Scalars can be used for one of the arguments. The output y is a uniformly distributed pseudo-random number between low and high (inclusive).

15.8.2 Example

Here is an example of a set of random integers between zero and 5:

```
--> randi(zeros(1,6),5*ones(1,6))
ans =
1 0 4 1 5 0
```

15.9 RANDMULTI Generate Multinomial-distributed Random Variables

15.9.1 Usage

This function generates samples from a multinomial distribution given the probability of each outcome. The general syntax for its use is

```
y = randmulti(N,pvec)
```

where N is the number of experiments to perform, and pvec is the vector of probabilities describing the distribution of outcomes.

15.9.2 Function Internals

A multinomial distribution describes the number of times each of m possible outcomes occurs out of N trials, where each outcome has a probability p_i . More generally, suppose that the probability of a Bernoulli random variable X_i is p_i , and that

$$\sum_{i=1}^{m} p_i = 1.$$

Then the probability that X_i occurs x_i times is

$$P_N(x_1, x_2, \dots, x_n) = \frac{N!}{x_1! \cdots x_n!} p_1^{x_1} \cdots p_n^{x_n}.$$

15.9.3 Example

Suppose an experiment has three possible outcomes, say heads, tails and edge, with probabilities 0.4999, 0.4999 and 0.0002, respectively. Then if we perform ten thousand coin flips we get

```
--> randmulti(10000,[0.4999,0.4999,0.0002])
```

ans = 5026 4973 1

15.10 RANDN Gaussian (Normal) Random Number Generator

15.10.1 Usage

Creates an array of pseudo-random numbers of the specified size. The numbers are normally distributed with zero mean and a unit standard deviation (i.e., mu = 0, sigma = 1). Two separate syntaxes are possible. The first syntax specifies the array dimensions as a sequence of scalar dimensions:

```
y = randn(d1, d2, ..., dn).
```

The resulting array has the given dimensions, and is filled with random numbers. The type of y is double, a 64-bit floating point array. To get arrays of other types, use the typecast functions.

The second syntax specifies the array dimensions as a vector, where each element in the vector specifies a dimension length:

```
y = randn([d1,d2,...,dn]).
```

This syntax is more convenient for calling randn using a variable for the argument.

Finally, randn supports two additional forms that allow you to manipulate the state of the random number generator. The first retrieves the state

```
y = randn('state')
```

which is a 625 length integer vector. The second form sets the state

```
randn('state',y)
```

or alternately, you can reset the random number generator with

15.10.2 Function Internals

Recall that the probability density function (PDF) of a normal random variable is

$$f(x) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{\frac{-(x-\mu)^2}{2\sigma^2}}.$$

The Gaussian random numbers are generated from pairs of uniform random numbers using a transformation technique.

15.10.3 Example

The following example demonstrates an example of using the first form of the randn function.

```
--> randn(2,2,2)
```

ans =

The second example demonstrates the second form of the randn function.

```
(:,:,2) =
0.3048 3.1685
-1.4185 -0.6130
```

In the next example, we create a large array of 10000 normally distributed pseudo-random numbers. We then shift the mean to 10, and the variance to 5. We then numerically calculate the mean and variance using mean and var, respectively.

```
--> x = 10+sqrt(5)*randn(1,10000);

--> mean(x)

ans =

10.0135

--> var(x)

ans =

4.9458
```

Now, we use the state manipulation functions of randn to exactly reproduce a random sequence. Note that unlike using seed, we can exactly control where the random number generator starts by saving the state.

```
--> randn('state',0)
                        % restores us to startup conditions
--> a = randn(1,3)
                        % random sequence 1
   -0.0362
             -0.1404
                        0.6934
--> b = randn('state'); % capture the state vector
--> c = randn(1,3)
                        % random sequence 2
c =
    0.5998
              0.7086
                       -0.9394
--> randn('state',b);
                        % restart the random generator so...
--> c = randn(1,3)
                        % we get random sequence 2 again
    0.5998
              0.7086
                       -0.9394
```

15.11 RANDNBIN Generate Negative Binomial Random Variables

15.11.1 Usage

Generates random variables with a negative binomial distribution. The general syntax for its use is

```
y = randnbin(r,p)
```

where r is a vector of integers representing the number of successes, and p is the probability of success.

15.11.2 Function Internals

A negative binomial random variable describes the number of failures x that occur in x+r bernoulli trials, with a success on the x+r trial. The pdf is given by

$$P_{r,p}(x) = {x+r-1 \choose r-1} p^r (1-p)^x.$$

15.11.3 Example

Here we generate some negative binomial random variables:

```
--> randnbin(3*ones(1,4),.01)

ans =
150 274 304 159

--> randnbin(6*ones(1,4),.01)

ans =
657 626 357 663
```

15.12 RANDNCHI Generate Noncentral Chi-Square Random Variable

15.12.1 Usage

Generates a vector of non-central chi-square random variables with the given number of degrees of freedom and the given non-centrality parameters. The general syntax for its use is

```
y = randnchi(n,mu)
```

where n is an array containing the degrees of freedom for each generated random variable (with each element of $n \neq 1$), and mu is the non-centrality shift (must be positive).

15.12.2 Function Internals

A non-central chi-square random variable is the sum of a chisquare deviate with n-1 degrees of freedom plus the square of a normal deviate with mean mu and standard deviation 1.

15.12.3 Examples

Here is an example of a non-central chi-square random variable:

--> randnchi(5*ones(1,9),0.3)

ans =

Columns 1 to 6

1.7097 6.6003 14.1463 2.0817 4.4984 5.3132

Columns 7 to 9

3.1775 3.5291 5.5185

15.13 RANDNF Generate Noncentral F-Distribution Random Variable

15.13.1 Usage

Generates a vector of non-central F-distributed random variables with the specified parameters. The general syntax for its use is

$$y = randnf(n,m,c)$$

where ${\tt n}$ is the number of degrees of freedom in the numerator, and ${\tt m}$ is the number of degrees of freedom in the denominator. The vector ${\tt c}$ determines the non-centrality shift of the numerator.

15.13.2 Function Internals

A non-central F-distributed random variable is the ratio of a non-central chi-square random variable and a central chi-square random variable, i.e.,

$$F_{n,m,c} = \frac{\chi_{n,c}^2/n}{\chi_m^2/m}.$$

15.13.3 Example

Here we use the randf to generate some non-central F-distributed random variables:

--> randnf(5*ones(1,9),7,1.34)

ans =

Columns 1 to 6

1.9422 0.5987 0.1890 0.7468 2.3759 8.2553

Columns 7 to 9

1.8047 0.2222 2.2680

15.14 RANDP Generate Poisson Random Variable

15.14.1 Usage

Generates a vector Poisson random variables with the given parameters. The general syntax for its use is

y = randp(nu),

where nu is an array containing the rate parameters for the generated random variables.

15.14.2 Function Internals

A Poisson random variable is generally defined by taking the limit of a binomial distribution as the sample size becomes large, with the expected number of successes being fixed (so that the probability of success decreases as 1/N). The Poisson distribution is given by

$$P_{\nu}(n) = \frac{\nu^n e^{-nu}}{n!}.$$

15.14.3 Example

Here is an exmaple of using randp to generate some Poisson random variables, and also using randbin to do the same using N=1000 trials to approximate the Poisson result.

```
--> randp(33*ones(1,10))

ans =
31 33 34 44 32 29 34 30 32 32

--> randbin(1000*ones(1,10),33/1000*ones(1,10))

ans =
32 36 36 39 33 34 41 33 42 32
```

15.15 RANDPERM Random permutation

15.15.1 USAGE

y = randperm(n)

y is a random permutation of integers from 1 to n. randperm calls rand and changes its state.

15.15.2 Example

```
--> y = randperm(10)
y =
4 9 6 3 10 7 2 8 1 5
```

15.16 SEED Seed the Random Number Generator

15.16.1 Usage

Seeds the random number generator using the given integer seeds. Changing the seed allows you to choose which pseudo-random sequence is generated. The seed takes two uint32 values:

```
seed(s,t)
```

where s and t are the seed values. Note that due to limitations in ranlib, the values of s, t must be between $0 \le s$, $t \le 2^30$.

15.16.2 Example

Here's an example of how the seed value can be used to reproduce a specific random number sequence.

```
--> seed(32,41);
--> rand(1,5)
ans =
    0.8589
              0.3727
                         0.5551
                                   0.9557
                                              0.7367
--> seed(32,41);
--> rand(1,5)
ans =
    0.8589
              0.3727
                         0.5551
                                   0.9557
                                              0.7367
```

Chapter 16

Input/Ouput Functions

16.1 CSVREAD Read Comma Separated Value (CSV) File

16.1.1 Usage

The csvread function reads a text file containing comma separated values (CSV), and returns the resulting numeric matrix (2D). The function supports multiple syntaxes. The first syntax for csvread is

```
x = csvread('filename')
```

which attempts to read the entire CSV file into array x. The file can contain only numeric values. Each entry in the file should be separated from other entries by a comma. However, FreeMat will attempt to make sense of the entries if the comma is missing (e.g., a space separated file will also parse correctly). For complex values, you must be careful with the spaces). The second form of csvread allows you to specify the first row and column (zero-based index)

```
x = csvread('filename',firstrow,firstcol)
```

The last form allows you to specify the range to read also. This form is

```
x = csvread('filename',firstrow,firstcol,readrange)
```

where readrange is either a 4-vector of the form [R1,C1,R2,C2], where R1,C1 is the first row and column to use, and R2,C2 is the last row and column to use. You can also specify the readrange as a spreadsheet range B12..C34, in which case the index for the range is 1-based (as in a typical spreadsheet), so that A1 is the first cell in the upper left corner. Note also that csvread is somewhat limited.

16.1.2 Example

Here is an example of a CSV file that we wish to read in

```
sample_data.csv
10, 12, 13, 00, 45, 16
```

```
09, 11, 52, 93, 05, 06
01, 03, 04, 04, 90, -3
14, 17, 13, 67, 30, 43
21, 33, 14, 44, 01, 00
We start by reading the entire file
--> csvread('sample_data.csv')
ans =
 10 12 13 0 45 16
 9 11 52 93 5 6
 1 3 4 4 90 -3
 14 17 13 67 30 43
 21 33 14 44 1 0
Next, we read everything starting with the second row, and third column
--> csvread('sample_data.csv',1,2)
ans =
 52 93 5 6
 4 4 90 -3
 13 67 30 43
 14 44 1 0
Finally, we specify that we only want the 3 x 3 submatrix starting with the second row, and third
column
--> csvread('sample_data.csv',1,2,[1,2,3,4])
ans =
 52 93 5
 4 4 90
 13 67 30
    sample_data.csv
```

16.2 CSVWRITE Write Comma Separated Value (CSV) File

16.2.1 Usage

10, 12, 13, 00, 45, 16 09, 11, 52, 93, 05, 06 01, 03, 04, 04, 90, -3 14, 17, 13, 67, 30, 43 21, 33, 14, 44, 01, 00

The csvwrite function writes a given matrix to a text file using comma separated value (CSV) notation. Note that you can create CSV files with arbitrary sized matrices, but that csvread has

limits on line length. If you need to reliably read and write large matrices, use rawwrite and rawread respectively. The syntax for csvwrite is

```
csvwrite('filename',x)
```

where x is a numeric array. The contents of x are written to filename as comma-separated values. You can also specify a row and column offset to csvwrite to force csvwrite to write the matrix x starting at the specified location in the file. This syntax of the function is

```
csvwrite('filename',x,startrow,startcol)
```

where startrow and startcol are the offsets in zero-based indexing.

16.2.2 Example

Here we create a simple matrix, and write it to a CSV file

```
--> x = [1,2,3;5,6,7]
x =
1 2 3
5 6 7
--> csvwrite('csvwrite.csv',x)
--> csvread('csvwrite.csv')
ans =
1 2 3
5 6 7
Next, we do the same with an offset.
--> csvwrite('csvwrite.csv',x,1,2)
--> csvread('csvwrite.csv')
ans =
0 0 0 0
0 1 2 3
0 5 6 7
```

Note the extra zeros.

16.3 DISP Display a Variable or Expression

16.3.1 Usage

Displays the result of a set of expressions. The disp function takes a variable number of arguments, each of which is an expression to output:

```
disp(expr1,expr2,...,exprn)
```

This is functionally equivalent to evaluating each of the expressions without a semicolon after each.

16.3.2 Example

Here are some simple examples of using disp.

```
--> a = 32;

--> b = 1:4;

--> disp(a,b,pi)

32

1 2 3 4

3.1416
```

16.4 DLMREAD Read ASCII-delimited File

16.4.1 Usage

Loads a matrix from an ASCII-formatted text file with a delimiter between the entries. This function is similar to the load -ascii command, except that it can handle complex data, and it allows you to specify the delimiter. Also, you can read only a subset of the data from the file. The general syntax for the dlmread function is

```
y = dlmread(filename)
```

where filename is a string containing the name of the file to read. In this form, FreeMat will guess at the type of the delimiter in the file. The guess is made by examining the input for common delimiter characters, which are ,;: or a whitespace (e.g., tab). The text in the file is preprocessed to replace these characters with whitespace and the file is then read in using a whitespace for the delimiter.

If you know the delimiter in the file, you can specify it using this form of the function:

```
y = dlmread(filename, delimiter)
```

where delimiter is a string containing the delimiter. If delimiter is the empty string, then the delimiter is guessed from the file.

You can also read only a portion of the file by specifying a start row and start column:

```
y = dlmread(filename, delimiter, startrow, startcol)
```

where startrow and startcol are zero-based. You can also specify the data to read using a range argument:

```
y = dlmread(filename, delimiter, range)
```

where range is either a vector [startrow,startcol,stoprow,stopcol] or is specified in spread-sheet notation as B4..ZA5.

Note that complex numbers can be present in the file if they are encoded without whitespaces inside the number, and use either i or j as the indicator. Note also that when the delimiter is given, each incidence of the delimiter counts as a separator. Multiple separators generate zeros in the matrix.

16.5 FCLOSE File Close Function

16.5.1 Usage

Closes a file handle, or all open file handles. The general syntax for its use is either

```
fclose(handle)
or
fclose('all')
```

In the first case a specific file is closed, In the second, all open files are closed. Note that until a file is closed the file buffers are not flushed. Returns a '0' if the close was successful and a '-1' if the close failed for some reason.

16.5.2 Example

A simple example of a file being opened with fopen and then closed with fclose.

```
--> fp = fopen('test.dat','wb','ieee-le')
fp =
  8
--> fclose(fp)
```

16.6 FEOF End Of File Function

16.6.1 Usage

Check to see if we are at the end of the file. The usage is

```
b = feof(handle)
```

The handle argument must be a valid and active file handle. The return is true (logical 1) if the current position is at the end of the file, and false (logical 0) otherwise. Note that simply reading to the end of a file will not cause feof to return true. You must read past the end of the file (which will cause an error anyway). See the example for more details.

16.6.2 Example

Here, we read to the end of the file to demonstrate how feof works. At first pass, we force a read of the contents of the file by specifying inf for the dimension of the array to read. We then test the end of file, and somewhat counter-intuitively, the answer is false. We then attempt to read past the end of the file, which causes an error. An feof test now returns the expected value of true.

```
--> fp = fopen('test.dat','rb');
--> x = fread(fp,[512,inf],'float');
--> feof(fp)

ans =
1
--> x = fread(fp,[1,1],'float');
--> feof(fp)

ans =
1
```

16.7 FFLUSH Force File Flush

16.7.1 Usage

Flushes any pending output to a given file. The general use of this function is

```
fflush(handle)
```

where handle is an active file handle (as returned by fopen).

16.8 FGETLINE Read a String from a File

16.8.1 Usage

Reads a string from a file. The general syntax for its use is

```
s = fgetline(handle)
```

This function reads characters from the file handle into a string array s until it encounters the end of the file or a newline. The newline, if any, is retained in the output string. If the file is at its end, (i.e., that feof would return true on this handle), fgetline returns an empty string.

16.8.2 Example

First we write a couple of strings to a test file.

```
--> fp = fopen('testtext','w');
--> fprintf(fp,'String 1\n');
--> fprintf(fp,'String 2\n');
--> fclose(fp);
```

Next, we read then back.

```
--> fp = fopen('testtext','r')
fp =
   10
--> fgetline(fp)
ans =
String 1
--> fgetline(fp)
ans =
String 2
--> fclose(fp);
```

16.9 FOPEN File Open Function

16.9.1 Usage

Opens a file and returns a handle which can be used for subsequent file manipulations. The general syntax for its use is

```
fp = fopen(fname, mode, byteorder)
```

Here fname is a string containing the name of the file to be opened. mode is the mode string for the file open command. The first character of the mode string is one of the following:

- 'r' Open file for reading. The file pointer is placed at the beginning of the file. The file can be read from, but not written to.
- 'r+' Open for reading and writing. The file pointer is placed at the beginning of the file. The file can be read from and written to, but must exist at the outset.
- 'w' Open file for writing. If the file already exists, it is truncated to zero length. Otherwise, a new file is created. The file pointer is placed at the beginning of the file.
- 'w+' Open for reading and writing. The file is created if it does not exist, otherwise it is truncated to zero length. The file pointer placed at the beginning of the file.
- 'a' Open for appending (writing at end of file). The file is created if it does not exist. The file pointer is placed at the end of the file.
- 'a+' Open for reading and appending (writing at end of file). The file is created if it does not exist. The file pointer is placed at the end of the file.

Starting with FreeMat 4, all files are treated as binary files by default. To invoke the operating systems 'CR/LF; CR' translation (on Win32) add a 't' to the mode string, as in 'rt+'.

Also, you can supply a second argument to fopen to retrieve error messages if the fopen fails.

```
[fp,messages] = fopen(fname,mode,byteorder)
```

Finally, FreeMat has the ability to read and write files of any byte-sex (endian). The third (optional) input indicates the byte-endianness of the file. If it is omitted, the native endian-ness of the machine running FreeMat is used. Otherwise, the third argument should be one of the following strings:

- 'le', 'ieee-le', 'little-endian', 'littleEndian', 'little', 'l', 'ieee-le.164', 's'
- 'be', 'ieee-be', 'big-endian', 'bigEndian', 'big', 'b', 'ieee-be.164', 'a'

If the file cannot be opened, or the file mode is illegal, then an error occurs. Otherwise, a file handle is returned (which is an integer). This file handle can then be used with fread, fwrite, or fclose for file access.

Note that three handles are assigned at initialization time:

- Handle 0 is assigned to standard input
- Handle 1 is assigned to standard output
- Handle 2 is assigned to standard error

These handles cannot be closed, so that user created file handles start at 3.

16.9.2 Examples

Here are some examples of how to use fopen. First, we create a new file, which we want to be little-endian, regardless of the type of the machine. We also use the fwrite function to write some floating point data to the file.

```
--> fp = fopen('test.dat','w','ieee-le')

fp =
    8
--> fwrite(fp,float([1.2,4.3,2.1]))

ans =
    12
--> fclose(fp)

Next, we open the file and read the data back
--> fp = fopen('test.dat','r','ieee-le')

fp =
    8
--> fread(fp,[1,3],'float')
```

```
ans =
    1.2000
               4.3000
                          2.1000
--> fclose(fp)
Now, we re-open the file in append mode and add two additional floats to the file.
--> fp = fopen('test.dat', 'a+', 'le')
fp =
--> fwrite(fp,float([pi,e]))
ans =
8
--> fclose(fp)
Finally, we read all 5 float values from the file
--> fp = fopen('test.dat','r','ieee-le')
fp =
--> fread(fp,[1,5],'float')
ans
    1.2000
               4.3000
                          2.1000
                                     3.1416
                                                2.7183
--> fclose(fp)
```

16.10 FORMAT Control the Format of Matrix Display

16.10.1 Usage

FreeMat supports several modes for displaying matrices (either through the disp function or simply by entering expressions on the command line. There are several options for the format command. The default mode is equivalent to

```
format short
```

which generally displays matrices with 4 decimals, and scales matrices if the entries have magnitudes larger than roughly 1e2 or smaller than 1e-2. For more information you can use

```
format long
```

which displays roughly 7 decimals for float and complex arrays, and 14 decimals for double and dcomplex. You can also use

```
format short e
```

to get exponential format with 4 decimals. Matrices are not scaled for exponential formats. Similarly, you can use

```
format long e
```

which displays the same decimals as format long, but in exponential format. You can also use the format command to retrieve the current format:

```
s = format
```

where **s** is a string describing the current format.

16.10.2 Example

We start with the short format, and two matrices, one of double precision, and the other of single precision.

```
--> format short
--> a = randn(4)
a =
    1.9819
             -2.4403
                         0.3082
                                  -0.8708
                                   -0.6899
    0.3885
              0.6777
                        -2.1203
   -0.8923
                                   -0.3336
              -1.0126
                        -1.1448
   -0.5528
              -0.2117
                        -0.6066
                                    0.1530
--> b = float(randn(4))
b =
    1.6282
             -0.9987
                        -0.0002
                                    0.7346
   -0.1461
             -0.4450
                         0.3260
                                    0.0591
   -0.1927
              -0.2583
                        -0.3209
                                   -1.7827
   -0.4694
              -0.2961
                        -0.3487
                                   -0.1476
```

Note that in the short format, these two matrices are displayed with the same format. In long format, however, they display differently

```
--> format long
--> a
ans =
Columns 1 to 3
```

```
1.98194242245660 -2.44033999910309 0.30822105452542
  0.38848412098646 0.67772654122050 -2.12029702950896
 -0.89231827506021 -1.01256221976480 -1.14477420632547
 -0.55283586680694 -0.21170713821002 -0.60660544623052
Columns 4 to 4
 -0.87083520854217
 -0.68985792035578
 -0.33359041318909
  0.15300924745427
--> b
ans =
  1.6282195 -0.9986902 -0.0002282 0.7346091
 -0.1460750 -0.4449911
                        0.3259999 0.0591399
 -0.1926918 \quad -0.2583237 \quad -0.3208777 \quad -1.7827009
 -0.4693597 -0.2961315 -0.3487136 -0.1476461
Note also that we we scale the contents of the matrices, FreeMat rescales the entries with a scale
premultiplier.
--> format short
--> a*1e4
ans =
  1.0e+04 *
   1.9819 -2.4403 0.3082 -0.8708
   -0.8923 -1.0126 -1.1448
                               -0.3336
  -0.5528 -0.2117
                     -0.6066
                                0.1530
--> a*1e-4
ans =
  1.0e-04 *
   1.9819 -2.4403 0.3082
                               -0.8708
```

0.6777

-0.8923 -1.0126 -1.1448

0.3885

--> b*1e4

ans =

-0.5528 -0.2117

-2.1203

-0.6066

-0.6899

-0.3336

0.1530

```
1.0e+04 *
   1.6282 -0.9987 -0.0002 0.7346
  -0.1461 -0.4450 0.3260 0.0591
           -0.2583 -0.3209
  -0.1927
                              -1.7827
  -0.4694
           -0.2961 -0.3487 -0.1476
--> b*1e-4
ans =
  1.0e-04 *
                    -0.0002
   1.6282
           -0.9987
                              0.7346
                     0.3260
  -0.1461 -0.4450
                              0.0591
  -0.1927 -0.2583 -0.3209 -1.7827
          -0.2961 -0.3487
  -0.4694
                             -0.1476
Next, we use the exponential formats:
--> format short e
--> a*1e4
ans =
 1.9819e+04 -2.4403e+04 3.0822e+03 -8.7084e+03
 3.8848e+03 6.7773e+03 -2.1203e+04 -6.8986e+03
 -8.9232e+03 -1.0126e+04 -1.1448e+04 -3.3359e+03
-5.5284e+03 -2.1171e+03 -6.0661e+03 1.5301e+03
--> a*1e-4
ans =
 1.9819e-04 -2.4403e-04 3.0822e-05 -8.7084e-05
 3.8848e-05 6.7773e-05 -2.1203e-04 -6.8986e-05
-8.9232e-05 -1.0126e-04 -1.1448e-04 -3.3359e-05
-5.5284e-05 -2.1171e-05 -6.0661e-05 1.5301e-05
--> b*1e4
ans =
 1.6282e+04 -9.9869e+03 -2.2825e+00 7.3461e+03
 -1.4608e+03 -4.4499e+03 3.2600e+03 5.9140e+02
-1.9269e+03 -2.5832e+03 -3.2088e+03 -1.7827e+04
-4.6936e+03 -2.9613e+03 -3.4871e+03 -1.4765e+03
--> b*1e-4
ans =
```

```
1.6282e-04 -9.9869e-05 -2.2825e-08 7.3461e-05
-1.4608e-05 -4.4499e-05 3.2600e-05 5.9140e-06
-1.9269e-05 -2.5832e-05 -3.2088e-05 -1.7827e-04
-4.6936e-05 -2.9613e-05 -3.4871e-05 -1.4765e-05
```

Finally, if we assign the format function to a variable, we can retrieve the current format:

```
--> format short
--> t = format
short
```

FPRINTF Formated File Output Function (C-Style) 16.11

16.11.1 Usage

Prints values to a file. The general syntax for its use is

```
fprintf(fp,format,a1,a2,...).
or,
  fprintf(format,a1,a2,...).
```

Here format is the format string, which is a string that controls the format of the output. The values of the variables ai are substituted into the output as required. It is an error if there are not enough variables to satisfy the format string. Note that this fprintf command is not vectorized! Each variable must be a scalar. The value fp is the file handle. If fp is omitted, file handle 1 is assumed, and the behavior of fprintf is effectively equivalent to printf. For more details on the format string, see printf.

16.11.2Examples

A number of examples are present in the Examples section of the printf command.

16.12 FREAD File Read Function

16.12.1 Usage

Reads a block of binary data from the given file handle into a variable of a given shape and precision. The general use of the function is

```
A = fread(handle, size, precision)
```

The handle argument must be a valid value returned by the fopen function, and accessable for reading. The size argument determines the number of values read from the file. The size argument is simply a vector indicating the size of the array A. The size argument can also contain a single inf dimension, indicating that FreeMat should calculate the size of the array along that dimension so as to read as much data as possible from the file (see the examples listed below for more details). The data is stored as columns in the file, not rows.

Alternately, you can specify two return values to the fread function, in which case the second value contains the number of elements read

```
[A,count] = fread(...)
```

where count is the number of elements in A.

The third argument determines the type of the data. Legal values for this argument are listed below:

- 'uint8', 'uchar', 'unsigned char' for an unsigned, 8-bit integer.
- 'int8', 'char', 'integer*1' for a signed, 8-bit integer.
- 'uint16', 'unsigned short' for an unsigned, 16-bit integer.
- 'int16', 'short', 'integer*2' for a signed, 16-bit integer.
- 'uint32', 'unsigned int' for an unsigned, 32-bit integer.
- 'int32', 'int', 'integer*4' for a signed, 32-bit integer.
- 'single', 'float32', 'float', 'real*4' for a 32-bit floating point.
- 'double', 'float64', 'real*8' for a 64-bit floating point.

Starting with FreeMat 4, the format for the third argument has changed. If you specify only a type, such as 'float', the data is read in as single precision, but the output type is always 'double'. This behavior is consistent with Matlab. If you want the output type to match the input type (as was previous behavior in FreeMat), you must preface the precision string with a '*'. Thus, the precision string '*float' implies that data is read in as single precision, and the output is also single precision.

The third option is to specify the input and output types explicitly. You can do this by specifying a precision string of the form 'type1 => type2', where 'type1' is the input type and 'type2' is the output type. For example, if the input type is 'double' and the output type is to be a 'float', then a type spec of 'double => float' should be used.

16.12.2 Example

First, we create an array of 512×512 Gaussian-distributed float random variables, and then writing them to a file called test.dat.

```
--> A = float(randn(512));
--> fp = fopen('test.dat','w');
--> fwrite(fp,A);
--> fclose(fp);
```

Read as many floats as possible into a row vector

Note that x is a double array. This behavior is new to FreeMat 4. Read the same floats into a 2-D float array.

```
--> fp = fopen('test.dat','r');
--> x = fread(fp,[512,inf],'float');
--> fclose(fp);
--> who x
Variable Name Type Flags Size
x double [512 512]
```

To read them as a single precision float array, we can use the following form:

16.13 FSCANF Formatted File Input Function (C-Style)

16.13.1 Usage

Reads values from a file. The general syntax for its use is

```
[a1,...,an] = fscanf(handle,format)
```

Here format is the format string, which is a string that controls the format of the input. Each value that is parsed from the file described by handle occupies one output slot. See printf for a description of the format. Note that if the file is at the end-of-file, the fscanf will return

16.14 FSEEK Seek File To A Given Position

16.14.1 Usage

Moves the file pointer associated with the given file handle to the specified offset (in bytes). The usage is

```
fseek(handle,offset,style)
```

The handle argument must be a value and active file handle. The offset parameter indicates the desired seek offset (how much the file pointer is moved in bytes). The style parameter determines how the offset is treated. Three values for the style parameter are understood:

- string 'bof' or the value -1, which indicate the seek is relative to the beginning of the file. This is equivalent to SEEK_SET in ANSI C.
- string 'cof' or the value 0, which indicates the seek is relative to the current position of the file. This is equivalent to SEEK_CUR in ANSI C.
- string 'eof' or the value 1, which indicates the seek is relative to the end of the file. This is equivalent to SEEK_END in ANSI C.

The offset can be positive or negative.

16.14.2 Example

The first example reads a file and then "rewinds" the file pointer by seeking to the beginning. The next example seeks forward by 2048 bytes from the files current position, and then reads a line of 512 floats.

```
--> % First we create the file
--> fp = fopen('test.dat', 'wb');
--> fwrite(fp,float(rand(4096,1)));
--> fclose(fp);
--> % Now we open it
--> fp = fopen('test.dat', 'rb');
--> % Read the whole thing
--> x = fread(fp,[1,inf],'float');
--> % Rewind to the beginning
--> fseek(fp,0,'bof');
--> % Read part of the file
--> y = fread(fp,[1,1024],'float');
--> who x y
  Variable Name
                             Flags
                                                Size
                      Туре
                   double
                                              [1 4096]
                   double
                                              [1 1024]
--> % Seek 2048 bytes into the file
--> fseek(fp,2048,'cof');
--> % Read 512 floats from the file
--> x = fread(fp,[512,1],'float');
--> % Close the file
--> fclose(fp);
```

16.15 FTELL File Position Function

16.15.1 Usage

Returns the current file position for a valid file handle. The general use of this function is

```
n = ftell(handle)
```

The handle argument must be a valid and active file handle. The return is the offset into the file relative to the start of the file (in bytes).

16.15.2 Example

Here is an example of using ftell to determine the current file position. We read 512 4-byte floats, which results in the file pointer being at position 512*4 = 2048.

```
--> fp = fopen('test.dat','wb');
--> fwrite(fp,randn(512,1));
--> fclose(fp);
--> fp = fopen('test.dat','rb');
--> x = fread(fp,[512,1],'float');
--> ftell(fp)
ans =
2048
```

16.16 FWRITE File Write Function

16.16.1 Usage

Writes an array to a given file handle as a block of binary (raw) data. The general use of the function is

```
n = fwrite(handle,A)
```

The handle argument must be a valid value returned by the fopen function, and accessable for writing. The array A is written to the file a column at a time. The form of the output data depends on (and is inferred from) the precision of the array A. If the write fails (because we ran out of disk space, etc.) then an error is returned. The output n indicates the number of elements successfully written.

Note that unlike MATLAB, FreeMat 4 does not default to uint8 for writing arrays to files. Alternately, the type of the data to be written to the file can be specified with the syntax

```
n = fwrite(handle,A,type)
```

where type is one of the following legal values:

- 'uint8', 'uchar', 'unsigned char' for an unsigned, 8-bit integer.
- 'int8', 'char', 'integer*1' for a signed, 8-bit integer.

- 'uint16', 'unsigned short' for an unsigned, 16-bit integer.
- 'int16', 'short', 'integer*2' for a signed, 16-bit integer.
- 'uint32', 'unsigned int' for an unsigned, 32-bit integer.
- 'int32', 'int', 'integer*4' for a signed, 32-bit integer.
- 'single', 'float32', 'float', 'real*4' for a 32-bit floating point.
- 'double', 'float64', 'real*8' for a 64-bit floating point.

16.16.2 Example

Heres an example of writing an array of 512×512 Gaussian-distributed float random variables, and then writing them to a file called test.dat.

```
--> A = float(randn(512));
--> fp = fopen('test.dat','w');
--> fwrite(fp,A,'single');
--> fclose(fp);
```

16.17 GETLINE Get a Line of Input from User

16.17.1 Usage

Reads a line (as a string) from the user. This function has two syntaxes. The first is

```
a = getline(prompt)
```

where **prompt** is a prompt supplied to the user for the query. The second syntax omits the **prompt** argument:

```
a = getline
```

Note that this function requires command line input, i.e., it will only operate correctly for programs or scripts written to run inside the FreeMat GUI environment or from the X11 terminal. If you build a stand-alone application and expect it to operate cross-platform, do not use this function (unless you include the FreeMat console in the final application).

16.18 GETPRINTLIMIT Get Limit For Printing Of Arrays

16.18.1 Usage

Returns the limit on how many elements of an array are printed using either the disp function or using expressions on the command line without a semi-colon. The default is set to one thousand elements. You can increase or decrease this limit by calling setprintlimit. This function is provided primarily so that you can temporarily change the output truncation and then restore it to the previous value (see the examples).

n=getprintlimit

where n is the current limit in use.

16.18.2 Example

Here is an example of using getprintlimit along with setprintlimit to temporarily change the output behavior of FreeMat.

```
--> A = randn(100,1);

--> n = getprintlimit

n =

1000

--> setprintlimit(5);

--> A

ans =

0.6674

-0.1948

0.5671

-0.6562

-0.4182
```

Print limit has been reached. Use setprintlimit function to enable longer printouts --> setprintlimit(n)

16.19 HTMLREAD Read an HTML Document into FreeMat

16.19.1 Usage

Given a filename, reads an HTML document, (attempts to) parse it, and returns the result as a FreeMat data structure. The syntax for its use is:

```
p = htmlread(filename)
```

where filename is a string. The resulting object p is a data structure containing the information in the document. Note that this function works by internally converting the HTML document into something closer to XHTML, and then using the XML parser to parse it. In some cases, the converted HTML cannot be properly parsed. In such cases, a third party tool such as "tidy" will probably do a better job.

16.20 IMREAD Read Image File To Matrix

16.20.1 Usage

Reads the image data from the given file into a matrix. Note that FreeMat's support for imread is not complete. Only some of the formats specified in the MATLAB API are implemented. The

syntax for its use is

```
[A,map,alpha] = imread(filename)
```

where filename is the name of the file to read from. The returned arrays A contain the image data, map contains the colormap information (for indexed images), and alpha contains the alphamap (transparency). The returned values will depend on the type of the original image. Generally you can read images in the jpg,png,xpm,ppm and some other formats.

16.21 IMWRITE Write Matrix to Image File

16.21.1 Usage

Write the image data from the matrix into a given file. Note that FreeMat's support for imwrite is not complete. You can write images in the jpg,png,xpm,ppm and some other formats. The syntax for its use is

```
imwrite(A, filename)
imwrite(A, map, filename)
imwrite(A, map, filename, 'Alpha', alpha)

or Octave-style syntax:
imwrite(filename, A)
imwrite(filename, A, map)
imwrite(filename, A, map, alpha)
```

where filename is the name of the file to write to. The input array A contains the image data (2D for gray or indexed, and 3D for color). If A is an integer array (int8, uint8, int16, uint16, int32, uint32), the values of its elements should be within 0-255. If A is a floating-point array (float or double), the value of its elements should be in the range [0,1]. map contains the colormap information (for indexed images), and alpha the alphamap (transparency).

16.21.2 Example

Here is a simple example of imread/imwrite. First, we generate a grayscale image and save it to an image file.

```
--> a = uint8(255*rand(64));
--> figure(1), image(a), colormap(gray)
--> title('image to save')
Warning: Newly defined variable nargin shadows a function of the same name. Use clear name--> imwrite(a, 'test.bmp')
Then, we read image file and show it:
```

```
--> b = imread('test.bmp');
--> figure(2), image(b), colormap(gray)
--> title('loaded image')
```

Warning: Newly defined variable nargin shadows a function of the same name. Use clear name

16.22 INPUT Get Input From User

16.22.1 Usage

The input function is used to obtain input from the user. There are two syntaxes for its use. The first is

```
r = input('prompt')
```

in which case, the prompt is presented, and the user is allowed to enter an expression. The expression is evaluated in the current workspace or context (so it can use any defined variables or functions), and returned for assignment to the variable (r in this case). In the second form of the input function, the syntax is

```
r = input('prompt','s')
```

in which case the text entered by the user is copied verbatim to the output.

16.23 LOAD Load Variables From A File

16.23.1 Usage

Loads a set of variables from a file in a machine independent format. The load function takes one argument:

```
load filename,
```

or alternately,

```
load('filename')
```

This command is the companion to save. It loads the contents of the file generated by save back into the current context. Global and persistent variables are also loaded and flagged appropriately. By default, FreeMat assumes that files that end in a .mat or .MAT extension are MATLAB-formatted files. Also, FreeMat assumes that files that end in .txt or .TXT are ASCII files. For other filenames, FreeMat first tries to open the file as a FreeMat binary format file (as created by the save function). If the file fails to open as a FreeMat binary file, then FreeMat attempts to read it as an ASCII file.

You can force FreeMat to assume a particular format for the file by using alternate forms of the load command. In particular,

```
load -ascii filename
```

will load the data in file filename as an ASCII file (space delimited numeric text) loaded into a single variable in the current workspace with the name filename (without the extension).

For MATLAB-formatted data files, you can use

```
load -mat filename
```

which forces FreeMat to assume that filename is a MAT-file, regardless of the extension on the filename

You can also specify which variables to load from a file (not from an ASCII file - only single 2-D variables can be successfully saved and retrieved from ASCII files) using the additional syntaxes of the load command. In particular, you can specify a set of variables to load by name

```
load filename Var_1 Var_2 Var_3 ...
```

where Var_n is the name of a variable to load from the file. Alternately, you can use the regular expression syntax

```
load filename -regexp expr_1 expr_2 expr_3 ...
```

where expr_n is a regular expression (roughly as expected by regexp). Note that a simpler regular expression mechanism is used for this syntax than the full mechanism used by the regexp command.

Finally, you can use load to create a variable containing the contents of the file, instead of automatically inserting the variables into the curent workspace. For this form of load you must use the function syntax, and capture the output:

```
V = load('arg1', 'arg2',...)
```

which returns a structure V with one field for each variable retrieved from the file. For ASCII files, V is a double precision matrix.

16.23.2 Example

Here is a simple example of save/load. First, we save some variables to a file.

```
--> D = \{1,5,'hello'\};
--> s = 'test string';
--> x = randn(512,1);
--> z = zeros(512);
--> who
  Variable Name
                               Flags
                                                   Size
                       Туре
                      cell
                                                 [1 3]
                                                 [1 11]
               s
                      char
                    double
                                                 [512 1]
                    double
                                                 [512 512]
--> save loadsave.dat
```

Next, we clear the variables, and then load them back from the file.

```
--> clear D s x z
--> who
Variable Name Type Flags Size
ans double [0 0]
--> load loadsave.dat
--> who
Variable Name Type Flags Size
```

D	cell	[1 3]
ans	double	[0 0]
s	char	[1 11]
x	double	[512 1]
z	double	[512 512]

16.24 PAUSE Pause Script Execution

16.24.1 Usage

The pause function can be used to pause execution of FreeMat scripts. There are several syntaxes for its use. The first form is

pause

This form of the pause function pauses FreeMat until you press any key. The second form of the pause function takes an argument

```
pause(p)
```

where **p** is the number of seconds to pause FreeMat for. The pause argument should be accurate to a millisecond on all supported platforms. Alternately, you can control all **pause** statements using:

```
pause on
```

which enables pauses and

```
pause off
```

which disables all pause statements, both with and without arguments.

16.25 PRINTF Formated Output Function (C-Style)

16.25.1 Usage

Prints values to the output. The general syntax for its use is

```
printf(format,a1,a2,...)
```

Here format is the format string, which is a string that controls the format of the output. The values of the variables a_i are substituted into the output as required. It is an error if there are not enough variables to satisfy the format string. Note that this printf command is not vectorized! Each variable must be a scalar.

It is important to point out that the printf function does not add a newline (or carriage return) to the output by default. That can lead to some confusing behavior if you do not know what to expect. For example, the command printf('Hello') does not appear to produce any output. In fact, it does produce the text, but it then gets overwritten by the prompt. To see the text, you need printf('Hello\n'). This seems odd, but allows you to assemble a line using multiple printf commands, including the '\n' when you are done with the line. You can also use the '\r' character as an explicit carriage return (with no line feed). This allows you to write to the same line many times (to show a progress string, for example).

16.25.2 Format of the format string

The format string is a character string, beginning and ending in its initial shift state, if any. The format string is composed of zero or more directives: ordinary characters (not unchanged to the output stream; and conversion specifications, each of which results in fetching zero or more subsequent arguments. Each conversion specification is introduced by the character conversion specifier. In between there may be (in this order) zero or more flags, an optional minimum field width, and an optional precision.

The arguments must correspond properly (after type promotion) with the conversion specifier, and are used in the order given.

16.25.3 The flag characters

The character % is followed by zero or more of the following flags:

- \# The value should be converted to an "alternate form". For o conversions, the first character of the output string is made zero (by prefixing a 0 if it was not zero already). For x and X conversions, a nonzero result has the string '0x' (or '0X' for X conversions) prepended to it. For a, A, e, E, f, F, g, and G conversions, the result will always contain a decimal point, even if no digits follow it (normally, a decimal point appears in the results of those conversions only if a digit follows). For g and G conversions, trailing zeros are not removed from the result as they would otherwise be. For other conversions, the result is undefined.
- 0 The value should be zero padded. For d, i, o, u, x, X, a, A, e, E, f, F, g, and G conversions, the converted value is padded on the left with zeros rather than blanks. If the 0 and flags both appear, the 0 flag is ignored. If a precision is given with a numeric conversion (d, i, o, u, x, and X), the O flag is ignored. For other conversions, the behavior is undefined.
- - The converted value is to be left adjusted on the field boundary. (The default is right justification.) Except for n conversions, the converted value is padded on the right with blanks, rather than on the left with blanks or zeros. A overrides a 0 if both are given.
- ' ' (a space) A blank should be left before a positive number (or empty string) produced by a signed conversion.
- + A sign (+ or -) always be placed before a number produced by a signed conversion. By default a sign is used only for negative numbers. A + overrides a space if both are used.

16.25.4 The field width

An optional decimal digit string (with nonzero first digit) specifying a minimum field width. If the converted value has fewer characters than the field width, it will be padded with spaces on the left (or right, if the left-adjustment flag has been given). A negative field width is taken as a '-' flag followed by a positive field width. In no case does a non-existent or small field width cause truncation of a field; if the result of a conversion is wider than the field width, the field is expanded to contain the conversion result.

16.25.5 The precision

An optional precision, in the form of a period ('.') followed by an optional decimal digit string. If the precision is given as just '.', or the precision is negative, the precision is taken to be zero. This gives the minimum number of digits to appear for d, i, o, u, x, and X conversions, the number of digits to appear after the radix character for a, A, e, E, f, and F conversions, the maximum number of significant digits for g and G conversions, or the maximum number of characters to be printed from a string for s conversions.

16.25.6 The conversion specifier

A character that specifies the type of conversion to be applied. The conversion specifiers and their meanings are:

- d,i The int argument is converted to signed decimal notation. The precision, if any, gives the minimum number of digits that must appear; if the converted value requires fewer digits, it is padded on the left with zeros. The default precision is 1. When 0 is printed with an explicit precision 0, the output is empty.
- o,u,x,X The unsigned int argument is converted to unsigned octal (o), unsigned decimal (u), or unsigned hexadecimal (x and X) notation. The letters abcdef are used for x conversions; the letters ABCDEF are used for X conversions. The precision, if any, gives the minimum number of digits that must appear; if the converted value requires fewer digits, it is padded on the left with zeros. The default precision is 1. When 0 is printed with an explicit precision 0, the output is empty.
- e,E The double argument is rounded and converted in the style [-]d.ddde dd where there is one digit before the decimal-point character and the number of digits after it is equal to the precision; if the precision is missing, it is taken as 6; if the precision is zero, no decimal-point character appears. An E conversion uses the letter E (rather than e) to introduce the exponent. The exponent always contains at least two digits; if the value is zero, the exponent is 00.
- f,F The double argument is rounded and converted to decimal notation in the style [-]ddd.ddd, where the number of digits after the decimal-point character is equal to the precision specification. If the precision is missing, it is taken as 6; if the precision is explicitly zero, no decimal-point character appears. If a decimal point appears, at least one digit appears before it.
- g,G The double argument is converted in style f or e (or F or E for G conversions). The precision specifies the number of significant digits. If the precision is missing, 6 digits are given; if the precision is zero, it is treated as 1. Style e is used if the exponent from its conversion is less than -4 or greater than or equal to the precision. Trailing zeros are removed from the fractional part of the result; a decimal point appears only if it is followed by at least one digit.
- c The int argument is converted to an unsigned char, and the resulting character is written.
- s The string argument is printed.
- % A '%' is written. No argument is converted. The complete conversion specification is '%%'.

16.25.7 Example

string value is hello

Here are some examples of the use of printf with various arguments. First we print out an integer and double value.

```
--> printf('intvalue is %d, floatvalue is %f\n',3,1.53); intvalue is 3, floatvalue is 1.530000

Next, we print out a string value.

--> printf('string value is %s\n','hello');
```

Now, we print out an integer using 12 digits, zeros up front.

```
--> printf('integer padded is %012d\n',32); integer padded is 00000000032
```

Print out a double precision value with a sign, a total of 18 characters (zero prepended if necessary), a decimal point, and 12 digit precision.

```
--> printf('float value is %+018.12f\n',pi); float value is +0003.141592653590
```

16.26 RAWREAD Read N-dimensional Array From File

16.26.1 Usage

The syntax for rawread is

```
function x = rawread(fname, size, precision, byteorder)
```

where fname is the name of the file to read from, and size is an n-dimensional vector that stores the size of the array in each dimension. The argument precision is the type of the data to read in:

- 'uint8', 'uchar', 'unsigned char' for unsigned, 8-bit integers
- 'int8', 'char', 'integer*1' for signed, 8-bit integers
- 'uint16', 'unsigned short' for unsigned, 16-bit integers
- 'int16', 'short', 'integer*2' for signed, 16-bit integers
- $\bullet\,$ 'uint32','unsigned int' for unsigned, 32-bit integers
- 'int32', 'int', 'integer*4' for signed, 32-bit integers
- 'uint64', 'unsigned int' for unsigned, 64-bit integers
- 'int64', 'int', 'integer*8' for signed, 64-bit integers
- 'single', 'float32', 'float', 'real*4' for 32-bit floating point

- 'double', 'float64', 'real*8' for 64-bit floating point
- 'complex', 'complex*8' for 64-bit complex floating point (32 bits for the real and imaginary part).
- 'dcomplex', 'complex*16' for 128-bit complex floating point (64 bits for the real and imaginary part).

As a special feature, one of the size elements can be 'inf', in which case, the largest possible array is read in. If byteorder is left unspecified, the file is assumed to be of the same byte-order as the machine FreeMat is running on. If you wish to force a particular byte order, specify the byteorder argument as

- 'le', 'ieee-le', 'little-endian', 'littleEndian', 'little'
- 'be', 'ieee-be', 'big-endian', 'bigEndian', 'big'

16.27 RAWWRITE Write N-dimensional Array From File

16.27.1 Usage

The syntax for rawwrite is

```
function rawwrite(fname,x,byteorder)
```

where fname is the name of the file to write to, and the (numeric) array x is writen to the file in its native type (e.g. if x is of type int16, then it will be written to the file as 16-bit signed integers. If byteorder is left unspecified, the file is assumed to be of the same byte-order as the machine FreeMat is running on. If you wish to force a particular byte order, specify the byteorder argument as

- 'le', 'ieee-le', 'little-endian', 'littleEndian', 'little'
- 'be', 'ieee-be', 'big-endian', 'bigEndian', 'big'

16.28 SAVE Save Variables To A File

16.28.1 Usage

Saves a set of variables to a file in a machine independent format. There are two formats for the function call. The first is the explicit form, in which a list of variables are provided to write to the file:

```
save filename a1 a2 ...
```

In the second form,

```
save filename
```

all variables in the current context are written to the file. The format of the file is a simple binary encoding (raw) of the data with enough information to restore the variables with the load command. The endianness of the machine is encoded in the file, and the resulting file should be portable between machines of similar types (in particular, machines that support IEEE floating point representation).

You can also specify both the filename as a string, in which case you also have to specify the names of the variables to save. In particular

```
save('filename','a1','a2')
```

will save variables a1 and a2 to the file.

Starting with version 2.0, FreeMat can also read and write MAT files (the file format used by MATLAB) thanks to substantial work by Thomas Beutlich. Support for MAT files in version 2.1 has improved over previous versions. In particular, classes should be saved properly, as well as a broader range of sparse matrices. Compression is supported for both reading and writing to MAT files. MAT file support is still in the alpha stages, so please be cautious with using it to store critical data. The file format is triggered by the extension. To save files with a MAT format, simply use a filename with a ".mat" ending.

The save function also supports ASCII output. This is a very limited form of the save command - it can only save numeric arrays that are 2-dimensional. This form of the save command is triggered using

```
save -ascii filename var1 var 2
```

although where -ascii appears on the command line is arbitrary (provided it comes after the save command, of course). Be default, the save command uses an 8-digit exponential format notation to save the values to the file. You can specify that you want 16-digits using the

```
save -ascii -double filename var1 var2
```

form of the command. Also, by default, save uses spaces as the delimiters between the entries in the matrix. If you want tabs instead, you can use

```
save -ascii -tabs filename var1 var2
```

(you can also use both the -tabs and -double flags simultaneously).

Finally, you can specify that save should only save variables that match a particular regular expression. Any of the above forms can be combined with the -regexp flag:

```
save filename -regexp pattern1 pattern2
```

in which case variables that match any of the patterns will be saved.

16.28.2 Example

Here is a simple example of save/load. First, we save some variables to a file.

```
--> D = {1,5,'hello'};
--> s = 'test string';
--> x = randn(512,1);
--> z = zeros(512);
```

> who			
Variable Name	Type	Flags	Size
D	cell		[1 3]
s	char		[1 11]
x	double		[512 1]
z	double		[512 512]
	• .		

--> save loadsave.dat

Next, we clear the variables, and then load them back from the file.

```
--> clear D s x z
--> who
                                                  Size
  Variable Name
                       Туре
                               Flags
                                                [0 0]
                    double
--> load loadsave.dat
--> who
  Variable Name
                                                  Size
                               Flags
                       Type
                      cell
                                                [1 3]
                                                [0 0]
            ans
                    double
                      char
                                                [1 11]
              s
                    double
                                                [512 1]
              х
                    double
                                                [512 512]
```

16.29 SETPRINTLIMIT Set Limit For Printing Of Arrays

16.29.1 Usage

Changes the limit on how many elements of an array are printed using either the disp function or using expressions on the command line without a semi-colon. The default is set to one thousand elements. You can increase or decrease this limit by calling

```
setprintlimit(n)
```

where n is the new limit to use.

16.29.2 Example

Setting a smaller print limit avoids pages of output when you forget the semicolon on an expression.

```
--> A = randn(512);
--> setprintlimit(10)
--> A
ans =
Columns 1 to 6
```

```
-0.2911 -2.2394 0.7388 0.4197 0.4382 -0.1399
0.6263 0.5764 -0.3614 0.4587
```

Print limit has been reached. Use setprintlimit function to enable longer printouts --> setprintlimit(1000)

16.30 SPRINTF Formated String Output Function (C-Style)

16.30.1 Usage

Prints values to a string. The general syntax for its use is

```
y = sprintf(format,a1,a2,...).
```

Here format is the format string, which is a string that controls the format of the output. The values of the variables a_i are substituted into the output as required. It is an error if there are not enough variables to satisfy the format string. Note that this sprintf command is not vectorized! Each variable must be a scalar. The returned value y contains the string that would normally have been printed. For more details on the format string, see printf.

16.30.2 Examples

Here is an example of a loop that generates a sequence of files based on a template name, and stores them in a cell array.

```
--> l = {}; for i = 1:5; s = sprintf('file_%d.dat',i); l(i) = {s}; end; --> l

ans =
[file_1.dat] [file_2.dat] [file_3.dat] [file_4.dat] [file_5.dat]
```

16.31 SSCANF Formated String Input Function (C-Style)

16.31.1 Usage

Reads values from a string. The general syntax for its use is

```
[a, count, errmsg, nextind] = sscanf(text,format,[size])
```

Here format is the format string, which is a string that controls the format of the input, size specifies the amount of data to be read. Values that are parsed from the text are stored in a. Note that sscanf is vectorized - the format string is reused as long as there are entries in the text string. See printf for a description of the format.

16.32 STR2NUM Convert a String to a Number

16.32.1 Usage

Converts a string to a number. The general syntax for its use is

```
x = str2num(string)
```

Here string is the data string, which contains the data to be converted into a number. The output is in double precision, and must be typecasted to the appropriate type based on what you need. Note that by definition, str2num is entirely equivalent to eval(['[' string ']'],[]) with all of the associated problems where string contains text that causes side effects.

16.33 URLWRITE Retrieve a URL into a File

16.33.1 Usage

Given a URL and a timeout, attempts to retrieve the URL and write the contents to a file. The syntax is

```
f = urlwrite(url,filename,timeout)
```

The timeout is in milliseconds. Note that the URL must be a complete spec (i.e., including the name of the resource you wish to retrieve). So for example, you cannot use http://www.google.com as a URL, but must instead use http://www.google.com/index.html.

16.34 WAVPLAY

16.34.1 Usage

Plays a linear PCM set of samples through the audio system. This function is only available if the portaudio library was available when FreeMat was built. The syntax for the command is one of:

```
wavplay(y)
wavplay(y,sampling_rate)
wavplay(...,mode)
```

where y is a matrix of audio samples. If y has two columns, then the audio playback is in stereo. The y input can be of types float, double, int32, int16, int8, uint8. For float and double types, the sample values in y must be between -1 and 1. The sampling_rate specifies the rate at which the data is recorded. If not specified, the sampling_rate defaults to 11025Hz. Finally, you can specify a playback mode of 'sync' which is synchronous playback or a playback mode of 'async' which is asynchronous playback. For 'sync' playback, the wavplay function returns when the playback is complete. For 'async' playback, the function returns immediately (unless a former playback is still issuing).

16.35 WAVREAD Read a WAV Audio File

16.35.1 Usage

The wavread function (attempts) to read the contents of a linear PCM audio WAV file. This function could definitely use improvements - it is based on a very simplistic notion of a WAV file. The simplest form for its use is

```
y = wavread(filename)
```

where filename is the name of the WAV file to read. If no extension is provided, FreeMat will add a '.wav' extension. This loads the data from the WAV file into y, and returns it in double precision, normalized format. If you want additional information on, for example, the WAV sampling rate or bit depth, you can request it via

```
[y, SamplingRate, BitDepth] = wavread(filename)
```

where SamplingRate and BitDepth are the sampling rate (in Hz) and the bit depth of the original data in the WAV file. If you only want to load part of the WAV file, you can use

```
[...] = wavread(filename, N)
```

where N indicates the number of samples to read from the file. Alternately, you can indicate a range of samples to load via

```
[...] = wavread(filename, [N1 N2])
```

which returns only the indicated samples from each channel in the file. By default, the output format is double precision. You can cntrol the format of the output by indicating

```
[...] = wavread(filename, format)
```

where format is either 'double' for double precision output, or 'native' for native precision output (meaning whatever bitdepth that was present in the original file). Finally, you can use the 'size' flag

```
y_siz = wavread(filename, 'size')
```

which returns a vector [samples channels] indicating the size of the data present in the WAV file.

16.36 WAVRECORD

16.36.1 Usage

Records linear PCM sound from the audio system. This function is only available if the portaudio library was available when FreeMat was built. The syntax for this command is one of:

```
y = wavrecord(samples, rate)
y = wavrecord(..., channels)
y = wavrecord(..., 'datatype')
```

where samples is the number of samples to record, and rate is the sampling rate. If not specified, the rate defaults to 11025Hz. If you want to record in stero, specify channels = 2. Finally, you can specify the type of the recorded data (defaults to FM_DOUBLE). Valid choices are float, double, int32, int16, int8, uint8.

16.37 WAVWRITE Write a WAV Audio File

16.37.1 Usage

The wavwrite funtion writes an audio signal to a linear PCM WAV file. The simplest form for its use is

wavwrite(y,filename)

which writes the data stored in y to a WAV file with the name filename. By default, the output data is assumed to be sampled at a rate of 8 KHz, and is output using 16 bit integer format. Each column of y is written as a separate channel. The data are clipped to the range [-1,1] prior to writing them out. If you want the data to be written with a different sampling frequency, you can use the following form of the wavwrite command:

wavwrite(y,SampleRate,filename)

where SampleRate is in Hz. Finally, you can specify the number of bits to use in the output form of the file using the form

wavwrite(y,SampleRate,NBits,filename)

where NBits is the number of bits to use. Legal values include 8,16,24,32. For less than 32 bit output format, the data is truncated to the range [-1,1], and an integer output format is used (type 1 PCM in WAV-speak). For 32 bit output format, the data is written in type 3 PCM as floating point data.

16.38 XMLREAD Read an XML Document into FreeMat

16.38.1 Usage

Given a filename, reads an XML document, parses it, and returns the result as a FreeMat data structure. The syntax for its use is:

p = xmlread(filename)

where filename is a string. The resulting object p is a data structure containing the information in the document. Note that the returned object p is not the same object as the one returned by MATLAB's xmlread, although the information content is the same. The output is largely compatible with the output of the parseXML example in the xmlread documentation of the MATLAB API.

Chapter 17

String Functions

17.1 BLANKS Create a blank string

17.1.1 Usage

```
str = blanks(n)
```

Create a string str containing n blank charaters.

17.1.2 Example

A simple example:

```
--> sprintf(['x0123456789y\n','x',blanks(10),'y\n'])
ans =
x0123456789y
x v
```

17.2 CELLSTR Convert character array to cell array of strings

17.2.1 Usage

The cellstr converts a character array matrix into a a cell array of individual strings. Each string in the matrix is placed in a different cell, and extra spaces are removed. The syntax for the command is

```
y = cellstr(x)
```

where x is an N x M array of characters as a string.

17.2.2 Example

```
Here is an example of how to use cellstr
--> a = ['quick';'brown';'fox ';'is ']
a =
quick
brown
fox
is
--> cellstr(a)
ans =
[quick]
[brown]
[fox]
[is]
```

17.3 DEBLANK Remove trailing blanks from a string

17.3.1 Usage

The deblank function removes spaces at the end of a string when used with the syntax

```
y = deblank(x)
```

where x is a string, in which case, all of the extra spaces in x are stripped from the end of the string. Alternately, you can call deblank with a cell array of strings

```
y = deblank(c)
```

in which case each string in the cell array is deblanked.

17.3.2 Example

```
A simple example

--> deblank('hello ')

ans =
hello

and a more complex example with a cell array of strings

--> deblank({'hello ','there ',' is ',' sign '})

ans =
[hello] [there] [ is] [ sign]
```

17.4 ISALPHA Test for Alpha Characters in a String

17.4.1 Usage

The isalpha functions returns a logical array that is 1 for characters in the argument string that are letters, and is a logical 0 for characters in the argument that are not letters. The syntax for its use is

```
x = isalpha(s)
```

where **s** is a **string**. Note that this function is not locale sensitive, and returns a logical 1 for letters in the classic ASCII sense (a through z, and A through Z).

17.4.2 Example

A simple example of isalpha:

```
--> isalpha('numb3r5')
ans =
1 1 1 1 0 1 0
```

17.5 ISDIGIT Test for Digit Characters in a String

17.5.1 Usage

The isdigit functions returns a logical array that is 1 for characters in the argument string that are digits, and is a logical 0 for characters in the argument that are not digits. The syntax for its use is

```
x = isdigit(s)
where s is a string.
```

17.5.2 Example

```
A simple example of isdigit:
```

```
--> isdigit('numb3r5')
ans =
0 0 0 0 1 0 1
```

17.6 ISSPACE Test for Space Characters in a String

17.6.1 Usage

The isspace functions returns a logical array that is 1 for characters in the argument string that are spaces, and is a logical 0 for characters in the argument that are not spaces. The syntax for its use is

```
x = isspace(s)
```

where **s** is a **string**. A blank character is considered a space, newline, tab, carriage return, formfeed, and vertical tab.

17.6.2 Example

A simple example of isspace:

```
--> isspace(' hello there world ')
ans =
1 1 0 0 0 0 0 1 0 0 0 0 1 0 0 0 0 1
```

17.7 LOWER Convert strings to lower case

17.7.1 Usage

The lower function converts a string to lower case with the syntax

```
y = lower(x)
```

where x is a string, in which case all of the upper case characters in x (defined as the range 'A'-'Z') are converted to lower case. Alternately, you can call lower with a cell array of strings

```
y = lower(c)
```

in which case each string in the cell array is converted to lower case.

17.7.2 Example

A simple example:

```
--> lower('this Is Strange CAPitalizaTion')

ans =
this is strange capitalization

and a more complex example with a cell array of strings

--> lower({'This','Is','Strange','CAPitalizaTion'})

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recans =
[this] [is] [strange] [capitalization]
```

17.8 REGEXP Regular Expression Matching Function

17.8.1 Usage

Matches regular expressions in the provided string. This function is complicated, and compatibility with MATLABs syntax is not perfect. The syntax for its use is

```
regexp('str','expr')
```

which returns a row vector containing the starting index of each substring of str that matches the regular expression described by expr. The second form of regexp returns six outputs in the following order:

```
[start stop tokenExtents match tokens names] = regexp('str', 'expr')
```

where the meaning of each of the outputs is defined below.

- start is a row vector containing the starting index of each substring that matches the regular expression.
- stop is a row vector containing the ending index of each substring that matches the regular expression.
- tokenExtents is a cell array containing the starting and ending indices of each substring that matches the tokens in the regular expression. A token is a captured part of the regular expression. If the 'once' mode is used, then this output is a double array.
- match is a cell array containing the text for each substring that matches the regular expression. In 'once' mode, this is a string.
- tokens is a cell array of cell arrays of strings that correspond to the tokens in the regular expression. In 'once' mode, this is a cell array of strings.
- named is a structure array containing the named tokens captured in a regular expression. Each named token is assigned a field in the resulting structure array, and each element of the array corresponds to a different match.

If you want only some of the the outputs, you can use the following variant of regexp:

```
[o1 o2 ...] = regexp('str','expr', 'p1', 'p2', ...)
```

where p1 etc. are the names of the outputs (and the order we want the outputs in). As a final variant, you can supply some mode flags to regexp

```
[o1 o2 ...] = regexp('str','expr', p1, p2, ..., 'mode1', 'mode2')
```

where acceptable mode flags are:

- 'once' only the first match is returned.
- 'matchcase' letter case must match (selected by default for regexp)
- 'ignorecase' letter case is ignored (selected by default for regexpi)

- 'dotall' the '.' operator matches any character (default)
- 'dotexceptnewline' the '.' operator does not match the newline character
- 'stringanchors' the ^ and \$ operators match at the beginning and end (respectively) of a string.
- 'lineanchors' the ^ and \$ operators match at the beginning and end (respectively) of a line.
- 'literalspacing' the space characters and comment characters # are matched as literals, just like any other ordinary character (default).
- 'freespacing' all spaces and comments are ignored in the regular expression. You must use ' ' and '#' to match spaces and comment characters, respectively.

Note the following behavior differences between MATLABs regexp and FreeMats:

- If you have an old version of pcre installed, then named tokens must use the older <?P<name> syntax, instead of the new <?<name> syntax.
- The pcre library is pickier about named tokens and their appearance in expressions. So, for example, the regexp from the MATLAB manual '(?<first>\\w+)\\s+(?<last>\\w+)(?;last; w+),

s+(?;first;

w+)'— does not work correctly (as of this writing) because the same named tokens appear multiple times. The workaround is to assign different names to each token, and then collapse the results later.

17.8.2 Example

Some examples of using the regexp function

```
--> [start,stop,tokenExtents,match,tokens,named] = regexp('quick down town zoo','(.)own')
start =
7 12

stop =
10 15

tokenExtents =
[1 2 double array] [1 2 double array]

match =
[down] [town]

tokens =
[1 1 cell array] [1 1 cell array]

named =
[]
```

17.9 REGEXPREP Regular Expression Replacement Function

17.9.1 Usage

Replaces regular expressions in the provided string. The syntax for its use is

```
outstring = regexprep(instring,pattern,replacement,modes)
```

Here instring is the string to be operated on. And pattern is a regular expression of the type accepted by regexp. For each match, the contents of the matched string are replaced with the replacement text. Tokens in the regular expression can be used in the replacement text using \$N where N is the number of the token to use. You can also specify the same mode flags that are used by regexp.

17.10 STRCMP String Compare Function

17.10.1 USAGE

Compares two strings for equality. The general syntax for its use is

```
p = strcmp(x,y)
```

where x and y are two strings. Returns true if x and y are the same size, and are equal (as strings). Otherwise, it returns false. In the second form, strcmp can be applied to a cell array of strings. The syntax for this form is

```
p = strcmp(cellstra,cellstrb)
```

where cellstra and cellstrb are cell arrays of a strings to compare. Also, you can also supply a character matrix as an argument to strcmp, in which case it will be converted via cellstr (so that trailing spaces are removed), before being compared.

17.10.2 Example

The following piece of code compares two strings:

```
--> x1 = 'astring';

--> x2 = 'bstring';

--> x3 = 'astring';

--> strcmp(x1,x2)

ans =

0

--> strcmp(x1,x3)

ans =
```

```
Here we use a cell array strings
--> x = {'astring','bstring',43,'astring'}

x =
   [astring] [bstring] [43] [astring]
--> p = strcmp(x,'astring')

p =
   1 0 0 1

Here we compare two cell arrays of strings
--> strcmp({'this','is','a','pickle'},{'what','is','to','pickle'})

ans =
   0 1 0 1

Finally, the case where one of the arguments is a matrix string
--> strcmp({'this','is','a','pickle'},['peter ';'piper ';'hated ';'pickle'])

ans =
   0 0 0 0
```

17.11 STRCMPI String Compare Case Insensitive Function

17.11.1 Usage

Compares two strings for equality ignoring case. The general syntax for its use is

```
p = strcmpi(x,y)
```

where x and y are two strings, or cell arrays of strings. See strcmp for more help.

17.12 STRFIND Find Substring in a String

17.12.1 Usage

Searches through a string for a pattern, and returns the starting positions of the pattern in an array. There are two forms for the **strfind** function. The first is for single strings

```
ndx = strfind(string, pattern)
```

the resulting array ndx contains the starting indices in string for the pattern pattern. The second form takes a cell array of strings

```
ndx = strfind(cells, pattern)
```

and applies the search operation to each string in the cell array.

17.12.2 Example

```
Here we apply strfind to a simple string
--> a = 'how now brown cow?'
a =
how now brown cow?
--> b = strfind(a,'ow')
b =
    2 6 11 16
Here we search over multiple strings contained in a cell array.
--> a = {'how now brown cow', 'quick brown fox', 'coffee anyone?'}
a =
    [how now brown cow] [quick brown fox] [coffee anyone?]
--> b = strfind(a,'ow')
b =
    [1 4 double array] [9] []
```

17.13 STRNCMP String Compare Function To Length N

17.13.1 USAGE

Compares two strings for equality, but only looks at the first N characters from each string. The general syntax for its use is

```
p = strncmp(x,y,n)
```

where x and y are two strings. Returns true if x and y are each at least n characters long, and if the first n characters from each string are the same. Otherwise, it returns false. In the second form, strncmp can be applied to a cell array of strings. The syntax for this form is

```
p = strncmp(cellstra,cellstrb,n)
```

where cellstra and cellstrb are cell arrays of a strings to compare. Also, you can also supply a character matrix as an argument to strcmp, in which case it will be converted via cellstr (so that trailing spaces are removed), before being compared.

17.13.2 Example

The following piece of code compares two strings:

```
--> x1 = 'astring';
--> x2 = 'bstring';
--> x3 = 'astring';
--> strncmp(x1,x2,4)
ans =
0
--> strncmp(x1,x3,4)
ans =
 1
Here we use a cell array strings
--> x = {'ast', 'bst', 43, 'astr'}
x =
 [ast] [bst] [43] [astr]
--> p = strncmp(x,'ast',3)
p =
1 0 0 1
Here we compare two cell arrays of strings
--> strncmp({'this','is','a','pickle'},{'think','is','to','pickle'},3)
ans =
1 0 0 1
Finally, the case where one of the arguments is a matrix string
--> strncmp({'this','is','a','pickle'},['peter ';'piper ';'hated ';'pickle'],4);
```

17.14 STRREP String Replace Function

17.14.1 Usage

Replace every occurance of one string with another. The general syntax for its use is

```
p = strrep(source,find,replace)
```

Every instance of the string find in the string source is replaced with the string replace. Any of source, find and replace can be a cell array of strings, in which case each entry has the replace operation applied.

17.14.2 Example

Here are some examples of the use of strrep. First the case where are the arguments are simple strings

```
--> strrep('Matlab is great','Matlab','FreeMat')

ans =
FreeMat is great

And here we have the replace operation for a number of strings:
--> strrep({'time is money';'A stitch in time';'No time for games'},'time','money')

ans =
[money is money]
[A stitch in money]
[No money for games]
```

17.15 STRSTR String Search Function

17.15.1 Usage

Searches for the first occurance of one string inside another. The general syntax for its use is

```
p = strstr(x,y)
```

where x and y are two strings. The returned integer p indicates the index into the string x where the substring y occurs. If no instance of y is found, then p is set to zero.

17.15.2 Example

Some examples of strstr in action

```
--> strstr('hello','lo')

ans =
4

--> strstr('quick brown fox','own')

ans =
9

--> strstr('free stuff','lunch')

ans =
0
```

17.16 STRTRIM Trim Spaces from a String

17.16.1 Usage

Removes the white-spaces at the beginning and end of a string (or a cell array of strings). See isspace for a definition of a white-space. There are two forms for the strtrim function. The first is for single strings

```
y = strtrim(strng)
```

where strng is a string. The second form operates on a cell array of strings

```
y = strtrim(cellstr)
```

and trims each string in the cell array.

17.16.2 Example

```
Here we apply strtrim to a simple string
--> strtrim(' lot of blank spaces ');
and here we apply it to a cell array
--> strtrim({' space', 'enough ', ' for ', ''})
ans =
  [space] [enough] [for] []
```

17.17 UPPER Convert strings to upper case

17.17.1 Usage

The upper function converts a string to upper case with the syntax

```
y = upper(x)
```

where x is a string, in which case all of the lower case characters in x (defined as the range 'a'-'z') are converted to upper case. Alternately, you can call upper with a cell array of strings

```
y = upper(c)
```

in which case each string in the cell array is converted to upper case.

17.17.2 Example

```
A simple example:
```

```
--> upper('this Is Strange CAPitalizaTion')
ans =
THIS IS STRANGE CAPITALIZATION
```

```
and a more complex example with a cell array of strings
--> upper({'This','Is','Strange','CAPitalizaTion'})
ans =
  [THIS] [IS] [STRANGE] [CAPITALIZATION]
```

Chapter 18

Transforms/Decompositions

18.1 EIG Eigendecomposition of a Matrix

18.1.1 Usage

Computes the eigendecomposition of a square matrix. The eig function has several forms. The first returns only the eigenvalues of the matrix:

$$s = eig(A)$$

The second form returns both the eigenvectors and eigenvalues as two matrices (the eigenvalues are stored in a diagonal matrix):

$$[V,D] = eig(A)$$

where D is the diagonal matrix of eigenvalues, and V is the matrix of eigenvectors.

Eigenvalues and eigenvectors for asymmetric matrices A normally are computed with balancing applied. Balancing is a scaling step that normaly improves the quality of the eigenvalues and eigenvectors. In some instances (see the Function Internals section for more details) it is necessary to disable balancing. For these cases, two additional forms of eig are available:

```
s = eig(A, 'nobalance'),
```

which computes the eigenvalues of A only, and does not balance the matrix prior to computation. Similarly,

```
[V,D] = eig(A,'nobalance')
```

recovers both the eigenvectors and eigenvalues of A without balancing. Note that the 'nobalance' option has no affect on symmetric matrices.

FreeMat also provides the ability to calculate generalized eigenvalues and eigenvectors. Similarly to the regular case, there are two forms for eig when computing generalized eigenvector (see the Function Internals section for a description of what a generalized eigenvector is). The first returns only the generalized eigenvalues of the matrix pair A,B

$$s = eig(A,B)$$

The second form also computes the generalized eigenvectors, and is accessible via

$$[V,D] = eig(A,B)$$

18.1.2 Function Internals

Recall that v is an eigenvector of A with associated eigenvalue d if

$$Av = dv$$
.

This decomposition can be written in matrix form as

$$AV = VD$$

where

$$V = [v_1, v_2, \dots, v_n], D = \operatorname{diag}(d_1, d_2, \dots, d_n).$$

The eig function uses the LAPACK class of functions GEEVX to compute the eigenvalue decomposition for non-symmetric (or non-Hermitian) matrices A. For symmetric matrices, SSYEV and DSYEV are used for float and double matrices (respectively). For Hermitian matrices, CHEEV and ZHEEV are used for complex and dcomplex matrices.

For some matrices, the process of balancing (in which the rows and columns of the matrix are pre-scaled to facilitate the search for eigenvalues) is detrimental to the quality of the final solution. This is particularly true if the matrix contains some elements on the order of round off error. See the Example section for an example.

A generalized eigenvector of the matrix pair ${\tt A}, {\tt B}$ is simply a vector ${\tt v}$ with associated eigenvalue ${\tt d}$ such that

$$Av = dBv$$
,

where B is a square matrix of the same size as A. This decomposition can be written in matrix form as

$$AV = BVD$$

where

$$V = [v_1, v_2, \dots, v_n], D = \text{diag}(d_1, d_2, \dots, d_n).$$

For general matrices A and B, the GGEV class of routines are used to compute the generalized eigendecomposition. If however, A and B are both symmetric (or Hermitian, as appropriate), Then FreeMat first attempts to use SSYGV and DSYGV for float and double arguments and CHEGV and ZHEGV for complex and dcomplex arguments (respectively). These routines requires that B also be positive definite, and if it fails to be, FreeMat will revert to the routines used for general arguments.

18.1.3 Example

Some examples of eigenvalue decompositions. First, for a diagonal matrix, the eigenvalues are the diagonal elements of the matrix.

Next, we compute the eigenvalues of an upper triangular matrix, where the eigenvalues are again the diagonal elements.

Next, we compute the complete eigenvalue decomposition of a random matrix, and then demonstrate the accuracy of the solution

```
--> A = float(randn(2))

A =

0.0501     0.1608
2.1808   -2.4972

--> [V,D] = eig(A)

V =

0.7754   -0.0599
0.6314     0.9982

D =

0.1811     0
```

```
0 -2.6282

--> A*V - V*D

ans =

1.0e-07 *

1.0431 -0.2980

-1.8626 0
```

--> [VN,DN] = eig(B,'nobalance')

-0.4176

0.0000

-0.1528

VN =

0.6153

Now, we consider a matrix that requires the nobalance option to compute the eigenvalues and eigenvectors properly. Here is an example from MATLAB's manual.

-0.7881	-0.3261	0.0000	0.1345
-0.0000	-0.0000	-0.0000	-0.9781
0.0189	0.8481	-1.0000	0.0443
DN =			
5.5616	0	0	0
0	1.4384	0	0
0	0	1.0000	0
0	0	0	-1.0000
> B*VN -	VN*DN		
ans =			
1.0e-16	*		
8.8818	-1.1102	-1.1592	-1.1102
-8.8818	3.3307	-0.5346	0.8327
0.1718	0.0154	0.0663	0
-0.6939	0	0	0.8327

18.2 FFT (Inverse) Fast Fourier Transform Function

18.2.1 Usage

Computes the Discrete Fourier Transform (DFT) of a vector using the Fast Fourier Transform technique. The general syntax for its use is

$$y = fft(x,n,d)$$

where x is an n-dimensional array of numerical type. Integer types are promoted to the double type prior to calculation of the DFT. The argument n is the length of the FFT, and d is the dimension along which to take the DFT. If -n— is larger than the length of x along dimension d, then d is zero-padded (by appending zeros) prior to calculation of the DFT. If d is smaller than the length of d along the given dimension, then d is truncated (by removing elements at the end) to length d is d along the given dimension, then d is truncated (by removing elements at the end) to length d is d along the given dimension, then d is d in d is d in d

If $\tt d$ is omitted, then the DFT is taken along the first non-singleton dimension of $\tt x$. If $\tt n$ is omitted, then the DFT length is chosen to match of the length of $\tt x$ along dimension $\tt d$.

Note that FFT support on Linux builds requires availability of the FFTW libraries at compile time. On Windows and Mac OS X, single and double precision FFTs are available by default.

18.2.2 Function Internals

The output is computed via

$$y(m_1,\ldots,m_{d-1},l,m_{d+1},\ldots,m_p) = \sum_{k=1}^n x(m_1,\ldots,m_{d-1},k,m_{d+1},\ldots,m_p) e^{-\frac{2\pi(k-1)l}{n}}.$$

For the inverse DFT, the calculation is similar, and the arguments have the same meanings as the DFT:

$$y(m_1,\ldots,m_{d-1},l,m_{d+1},\ldots,m_p) = \frac{1}{n} \sum_{k=1}^n x(m_1,\ldots,m_{d-1},k,m_{d+1},\ldots,m_p) e^{\frac{2\pi(k-1)l}{n}}.$$

The FFT is computed using the FFTPack library, available from netlib at http://www.netlib.org. Generally speaking, the computational cost for a FFT is (in worst case) O(n^2). However, if n is composite, and can be factored as

$$n = \prod_{k=1}^{p} m_k,$$

then the DFT can be computed in

$$O(n\sum_{k=1}^{p}m_k)$$

operations. If n is a power of 2, then the FFT can be calculated in O(n log_2 n). The calculations for the inverse FFT are identical.

18.2.3 Example

The following piece of code plots the FFT for a sinusoidal signal:

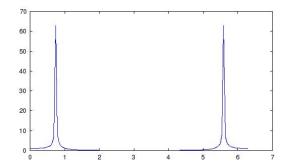
```
--> t = linspace(0,2*pi,128);

--> x = cos(15*t);

--> y = fft(x);

--> plot(t,abs(y));
```

The resulting plot is:



The FFT can also be taken along different dimensions, and with padding and/or truncation. The following example demonstrates the Fourier Transform being computed along each column, and then along each row.

$$-->$$
 A = [2,5;3,6]

```
2 5
3 6
--> real(fft(A,[],1))
ans =
5 11
-1 -1
--> real(fft(A,[],2))
ans =
7 -3
9 -3
```

Fourier transforms can also be padded using the n argument. This pads the signal with zeros prior to taking the Fourier transform. Zero padding in the time domain results in frequency interpolation. The following example demonstrates the FFT of a pulse (consisting of 10 ones) with (red line) and without (green circles) padding.

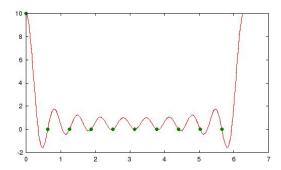
```
--> delta(1:10) = 1;

--> plot((0:255)/256*pi*2,real(fft(delta,256)),'r-');

--> hold on

--> plot((0:9)/10*pi*2,real(fft(delta)),'go');
```

The resulting plot is:



18.3 FFTN N-Dimensional Forward FFT

18.3.1 Usage

Computes the DFT of an N-dimensional numerical array along all dimensions. The general syntax for its use is

```
y = fftn(x)
```

which computes the same-size FFTs for each dimension of x. Alternately, you can specify the size vector

```
y = fftn(x,dims)
```

where dims is a vector of sizes. The array x is zero padded or truncated as necessary in each dimension so that the output is of size dims. The fftn function is implemented by a sequence of calls to fft.

18.4 FFTSHIFT Shift FFT Output

18.4.1 Usage

The fftshift function shifts the DC component (zero-frequency) of the output from an FFT to the center of the array. For vectors this means swapping the two halves of the vector. For matrices, the first and third quadrants are swapped. So on for N-dimensional arrays. The syntax for its use is

```
y = fftshift(x).
```

Alternately, you can specify that only one dimension be shifted

```
y = fftshift(x,dim).
```

18.5 HILBERT Hilbert Transform

18.5.1 Usage

The hilbert function computes the hilbert transform of the argument vector or matrix. The FreeMat hilbert function is compatible with the one from the MATLAB API. This means that the output of the hilbert function is the sum of the original function and an imaginary signal containing the Hilbert transform of it. There are two syntaxes for the hilbert function. The first is

```
y = hilbert(x)
```

where x is real vector or matrix. If x is a matrix, then he Hilbert transform is computed along the columns of x. The second syntax provides a dimension along which to take the transform.

```
y = hilbert(x,n)
```

where n is the dimension along which to apply the transformation.

18.6 IFFTN N-Dimensional Inverse FFT

18.6.1 Usage

Computes the inverse DFT of an N-dimensional numerical array along all dimensions. The general syntax for its use is

```
y = ifftn(x)
```

which computes the same-size inverse FFTs for each dimension of x. Alternately, you can specify the size vector

```
y = ifftn(x,dims)
```

where dims is a vector of sizes. The array x is zero padded or truncated as necessary in each dimension so that the output is of size dims. The ifftn function is implemented by a sequence of calls to ifft.

18.7 IFFTSHIFT Inverse Shift FFT Output

18.7.1 Usage

The ifftshift function shifts the DC component (zero-frequency) of the output from the center of the array back to the first position and iseffectively the inverse of fftshift. For vectors this means swapping the two halves of the vector. For matrices, the first and third quadrants are swapped. So on for N-dimensional arrays. The syntax for its use is

```
y = ifftshift(x).
```

Alternately, you can specify that only one dimension be shifted

```
y = ifftshift(x,dim).
```

18.8 INV Invert Matrix

18.8.1 Usage

Inverts the argument matrix, provided it is square and invertible. The syntax for its use is

```
y = inv(x)
```

Internally, the inv function uses the matrix divide operators. For sparse matrices, a sparse matrix solver is used.

18.8.2 Example

Here we invert some simple matrices

```
--> a = randi(zeros(3),5*ones(3))

a =
    1 4 3
    1 1 3
    1 4 5

--> b = inv(a)
```

```
b =
               1.3333
                         -1.5000
    1.1667
    0.3333
              -0.3333
                               0
   -0.5000
                          0.5000
                    0
--> a*b
ans =
 1 0 0
 0 1 0
 0 0 1
--> b*a
ans =
    1.0000
                               0
                    0
         0
               1.0000
                          0.0000
                          1.0000
         0
                    0
```

18.9 LU LU Decomposition for Matrices

18.9.1 Usage

Computes the LU decomposition for a matrix. The form of the command depends on the type of the argument. For full (non-sparse) matrices, the primary form for lu is

$$[L,U,P] = lu(A),$$

where L is lower triangular, U is upper triangular, and P is a permutation matrix such that L*U = P*A. The second form is

$$[V,U] = lu(A),$$

where V is P'*L (a row-permuted lower triangular matrix), and U is upper triangular. For sparse, square matrices, the LU decomposition has the following form:

```
[L,U,P,Q,R] = lu(A),
```

where A is a sparse matrix of either double or dcomplex type. The matrices are such that L*U=P*R*A*Q, where L is a lower triangular matrix, U is upper triangular, P and Q are permutation vectors and R is a diagonal matrix of row scaling factors. The decomposition is computed using UMFPACK for sparse matrices, and LAPACK for dense matrices.

18.9.2 Example

First, we compute the LU decomposition of a dense matrix.

```
--> a = float([1,2,3;4,5,8;10,12,3])
a =
 1 2 3
 4 5 8
10 12 3
--> [1,u,p] = lu(a)
            0
   1.0000
                          0
   0.1000
          1.0000
                          0
   0.4000
            0.2500
                      1.0000
u =
  10.0000
          12.0000
                      3.0000
                      2.7000
        0
            0.8000
        0
                 0
                      6.1250
p =
0 0 1
1 0 0
0 1 0
--> l*u
ans =
10 12 3
 1 2 3
 4 5 8
--> p*a
ans =
10 12 3
 1 2 3
```

Now we repeat the exercise with a sparse matrix, and demonstrate the use of the permutation vectors.

```
--> a = sparse([1,0,0,4;3,2,0,0;0,0,0,1;4,3,2,4])

a =
1 1 1
2 1 3
4 1 4
2 2 2
```

```
4 2 3
4 3 2
1 4 4
3 4 1
4 4 4
--> [1,u,p,q,r] = lu(a)
1 =
1 1 1
2 2 1
3 3 1
4 4 1
u =
1 1 0.153846
1 2 0.230769
2 2 0.4
1 3 0.307692
2 3 0.6
3 3 0.2
1 4 0.307692
3 4 0.8
4 4 1
p =
4
2
1
3
q =
3
2
 1
4
r =
1 1 0.2
2 2 0.2
3 3 1
4 4 0.0769231
--> full(1*a)
ans =
1 0 0 4
3 2 0 0
0 0 0 1
4 3 2 4
```

```
--> b = r*a
b =
1 1 0.2
2 1 0.6
 3 1 0
 4 1 0.307692
 1 2 0
 2 2 0.4
 3 2 0
 4 2 0.230769
 1 3 0
 2 3 0
 3 3 0
 4 3 0.153846
 1 4 0.8
 2 4 0
 3 4 1
4 4 0.307692
--> full(b(p,q))
ans =
    0.1538
              0.2308
                         0.3077
                                    0.3077
         0
              0.4000
                         0.6000
                                         0
         0
                         0.2000
                    0
                                    0.8000
         0
                    0
                                    1.0000
                               0
```

18.10 QR QR Decomposition of a Matrix

18.10.1 Usage

Computes the QR factorization of a matrix. The qr function has multiple forms, with and without pivoting. The non-pivot version has two forms, a compact version and a full-blown decomposition version. The compact version of the decomposition of a matrix of size M \times N is

$$[q,r] = qr(a,0)$$

where q is a matrix of size M x L and r is a matrix of size L x N and L = min(N,M), and q*r = a. The QR decomposition is such that the columns of Q are orthonormal, and R is upper triangular. The decomposition is computed using the LAPACK routine xgeqrf, where x is the precision of the matrix. FreeMat supports decompositions of single and double types.

The second form of the non-pivot decomposition omits the second 0 argument:

$$[q,r] = qr(a)$$

This second form differs from the previous form only for matrices with more rows than columns (M > N). For these matrices, the full decomposition is of a matrix Q of size $M \times M$ and a matrix R of

size M \times N. The full decomposition is computed using the same LAPACK routines as the compact decomposition, but on an augmented matrix [a 0], where enough columns are added to form a square matrix.

Generally, the QR decomposition will not return a matrix R with diagonal elements in any specific order. The remaining two forms of the qr command utilize permutations of the columns of a so that the diagonal elements of r are in decreasing magnitude. To trigger this form of the decomposition, a third argument is required, which records the permutation applied to the argument a. The compact version is

$$[q,r,e] = qr(a,0)$$

where e is an integer vector that describes the permutation of the columns of a necessary to reorder the diagonal elements of r. This result is computed using the LAPACK routines (s,d)geqp3. In the non-compact version of the QR decomposition with pivoting,

$$[q,r,e] = qr(a)$$

the returned matrix e is a permutation matrix, such that q*r*e' = a.

18.11 SVD Singular Value Decomposition of a Matrix

18.11.1 Usage

Computes the singular value decomposition (SVD) of a matrix. The svd function has three forms. The first returns only the singular values of the matrix:

$$s = svd(A)$$

The second form returns both the singular values in a diagonal matrix S, as well as the left and right eigenvectors.

$$[U,S,V] = svd(A)$$

The third form returns a more compact decomposition, with the left and right singular vectors corresponding to zero singular values being eliminated. The syntax is

$$[U,S,V] = svd(A,0)$$

18.11.2 Function Internals

Recall that $sigma_i$ is a singular value of an M x N matrix A if there exists two vectors u_i , v_i where u_i is of length M, and v_i is of length u_i and

$$Av_i = \sigma_i u_i$$

and generally

$$A = \sum_{i=1}^{K} \sigma_i u_i * v_i',$$

where K is the rank of A. In matrix form, the left singular vectors u_i are stored in the matrix U as

$$U = [u_1, \dots, u_m], V = [v_1, \dots, v_n]$$

The matrix S is then of size $M \times N$ with the singular values along the diagonal. The SVD is computed using the LAPACK class of functions GESVD (Note that this has changed. Previous versions of FreeMat used GESDD, which yields a valid, but slightly different choice of the decomposition. Starting in version 4, it was changed to GESVD to improve compatibility.

18.11.3 Examples

Here is an example of a partial and complete singular value decomposition.

```
--> A = float(randn(2,3))
A =
   -0.9542
               1.2478
                        -0.2295
    0.3075
               1.0686
                         -0.4849
--> [U,S,V] = svd(A)
U =
   -0.8410
              -0.5411
   -0.5411
               0.8410
S =
    1.8058
                               0
                    0
         0
                               0
               0.8549
V =
    0.3522
               0.9064
                          0.2331
   -0.9013
               0.2614
                          0.3454
    0.2521
              -0.3317
                          0.9091
--> U*S*V'
ans =
   -0.9542
               1.2478
                         -0.2295
                        -0.4849
    0.3075
               1.0686
--> svd(A)
ans =
    1.8058
    0.8549
```

Chapter 19

Signal Processing Functions

19.1 CONV Convolution Function

19.1.1 Usage

The conv function performs a one-dimensional convolution of two vector arguments. The syntax for its use is

```
z = conv(x,y)
```

where x and y are vectors. The output is of length nx + ny -1. The conv function calls conv2 to do the calculation. See its help for more details.

19.2 CONV2 Matrix Convolution

19.2.1 Usage

The conv2 function performs a two-dimensional convolution of matrix arguments. The syntax for its use is

```
Z = conv2(X,Y)
```

which performs the full 2-D convolution of X and Y. If the input matrices are of size [xm,xn] and [ym,yn] respectively, then the output is of size [xm+ym-1,xn+yn-1]. Another form is

```
Z = conv2(hcol,hrow,X)
```

where hcol and hrow are vectors. In this form, conv2 first convolves Y along the columns with hcol, and then convolves Y along the rows with hrow. This is equivalent to conv2(hcol(:)*hrow(:)', Y).

You can also provide an optional shape argument to conv2 via either

```
Z = conv2(X,Y,'shape')
Z = conv2(hcol,hrow,X,'shape')
```

where shape is one of the following strings

- 'full' compute the full convolution result this is the default if no shape argument is provided.
- 'same' returns the central part of the result that is the same size as X.
- 'valid' returns the portion of the convolution that is computed without the zero-padded edges. In this situation, Z has size [xm-ym+1,xn-yn+1] when xm>=ym and xn>=yn. Otherwise conv2 returns an empty matrix.

19.2.2 Function Internals

The convolution is computed explicitly using the definition:

$$Z(m,n) = \sum_{k} \sum_{j} X(k,j)Y(m-k,n-j)$$

If the full output is requested, then m ranges over $0 \le m \le xm+ym-1$ and n ranges over $0 \le n \le xn+yn-1$. For the case where shape is 'same', the output ranges over $(ym-1)/2 \le m \le xm + (ym-1)/2$ and $(yn-1)/2 \le n \le xn + (yn-1)/2$.

Chapter 20

Numerical Methods

20.1 ODE45 Numerical Solution of ODEs

20.1.1 Usage

```
function [t,y] = ode45(f,tspan,y0,options,varargin) function SOL = ode45(f,tspan,y0,options,varargin) ode45 is a solver for ordinary differential equations and initial value problems. To solve the ODE
```

$$y'(t) = f(t,y)$$

 $y(0) = y0$

over the interval tspan=[t0 t1], you can use ode 45. For example, to solve the ode $y' = y \ y(0) = 1$ whose exact solution is $y(t) = \exp(t)$, over the interval t0=0, t1=3, do

```
--> [t,y]=ode45(@(t,y) y,[0 3],1)
```

3.0000

Warning: Newly defined variable error shadows a function of the same name. Use clear error to recover

```
k =
   2

y =
   1.0000   1.0030

t =
```

1.0e-03 *

0

k =

3

y = 1.0000 1.0030 1.0182

t =

1.0e-02 * 0.3000 1.8000

k = 4

y = 1.0000 1.0030 1.0182 1.0975

t =

1.0e-02 * 0.3000 1.8000 9.3000

k = 5

y = 1.0000 1.0030 1.0182 1.0975 1.4814

t = 0 0.0030 0.0180 0.0930 0.3930

k = 6

y = 1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

t = 0 0.0030 0.0180 0.0930 0.3930 0.6930

k = 7

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 7

2.6993

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 7

0.9930

k = 8

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 8

2.6993 3.6437

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 8

0.9930 1.2930

k =

9

у =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 9

2.6993 3.6437 4.9185

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 9

0.9930 1.2930 1.5930

k =

10

у =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 10

2.6993 3.6437 4.9185 6.6392

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 10

0.9930 1.2930 1.5930 1.8930

k = 11

11

у =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 11

2.6993 3.6437 4.9185 6.6392 8.9620

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 11

0.9930 1.2930 1.5930 1.8930 2.1930

k =

12

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 12

2.6993 3.6437 4.9185 6.6392 8.9620 12.0975

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 12

0.9930 1.2930 1.5930 1.8930 2.1930 2.4930

k =

13

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 12

2.6993 3.6437 4.9185 6.6392 8.9620 12.0975

Columns 13 to 13

16.3299

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 12

0.9930 1.2930 1.5930 1.8930 2.1930 2.4930

Columns 13 to 13

2.7930

k = 14

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 12

2.6993 3.6437 4.9185 6.6392 8.9620 12.0975

Columns 13 to 14

16.3299 20.0854

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 12

0.9930 1.2930 1.5930 1.8930 2.1930 2.4930

Columns 13 to 14

2.7930 3.0000

t =

1.0000

1.0e-03 *

t =

1.0030

3.0000

```
Columns 1 to 6
         0
              0.0030
                         0.0180
                                   0.0930
                                              0.3930
                                                         0.6930
 Columns 7 to 12
    0.9930
              1.2930
                         1.5930
                                 1.8930
                                              2.1930
                                                         2.4930
 Columns 13 to 14
    2.7930
              3.0000
    1.0000
    1.0030
    1.0182
    1.0975
    1.4814
    1.9997
    2.6993
    3.6437
    4.9185
    6.6392
    8.9620
   12.0975
   16.3299
   20.0854
If you want a dense output (i.e., an output that also contains an interpolating spline), use instead
          SOL=ode45(@(t,y) y,[0 3],1)
Warning: Newly defined variable error shadows a function of the same name. Use clear error
k =
 2
```

k = 3

y = 1.0000 1.0030 1.0182

t =

1.0e-02 * 0.3000 1.8000

k = 4

y = 1.0000 1.0030 1.0182 1.0975

t =

1.0e-02 * 0 0.3000 1.8000 9.3000

k = 5

y = 1.0000 1.0030 1.0182 1.0975 1.4814

t = 0 0.0030 0.0180 0.0930 0.3930

k = 6

y = 1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

t =

0 0.0030 0.0180 0.0930 0.3930 0.6930

k =

7

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 7

2.6993

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 7

0.9930

k =

8

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 8

2.6993 3.6437

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 8

0.9930 1.2930

k =

9

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 9

2.6993 3.6437 4.9185

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 9

0.9930 1.2930 1.5930

k =

10

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 10

2.6993 3.6437 4.9185 6.6392

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 10

0.9930 1.2930 1.5930 1.8930

k =

11

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 11

2.6993 3.6437 4.9185 6.6392 8.9620

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 11

0.9930 1.2930 1.5930 1.8930 2.1930

k =

12

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

 2.6993
 3.6437
 4.9185
 6.6392
 8.9620
 12.0975

Columns 13 to 13

Columns 7 to 12

16.3299

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 12

0.9930 1.2930 1.5930 1.8930 2.1930 2.4930

Columns 13 to 13

2.7930

k =

14

y =

Columns 1 to 6

1.0000 1.0030 1.0182 1.0975 1.4814 1.9997

Columns 7 to 12

2.6993 3.6437 4.9185 6.6392 8.9620 12.0975

Columns 13 to 14

16.3299 20.0854

t =

Columns 1 to 6

0 0.0030 0.0180 0.0930 0.3930 0.6930

Columns 7 to 12

0.9930 1.2930 1.5930 1.8930 2.1930 2.4930

Columns 13 to 14

2.7930 3.0000

```
SOL =
    x: 1 14 double array
    y: 1 14 double array
    xe:
    ye:
    ie:
    solver: generic_ode_solver
    interpolant: 1 1 functionpointer array
    idata: 1 1 struct array
```

You can view the result using

```
plot(0:0.01:3,deval(SOL,0:0.01:3))
```

You will notice that this function is available for "every" value of t, while plot(t,y,'o-')

is only available at a few points.

The optional argument 'options' is a structure. It may contain any of the following fields:

'AbsTol' - Absolute tolerance, default is 1e-6. 'RelTol' - Relative tolerance, default is 1e-3. 'MaxStep' - Maximum step size, default is (tspan(2)-tspan(1))/10 'InitialStep' - Initial step size, default is maxstep/100 'Stepper' - To override the default Fehlberg integrator 'Events' - To provide an event function 'Projection' - To provide a projection function

The varargin is ignored by this function, but is passed to all your callbacks, i.e., f, the event function and the projection function.

```
==Event Function==
```

The event function can be used to detect situations where the integrator should stop, possibly because the right-hand-side has changed, because of a collision, etc...

An event function should look like

```
function [val,isterminal,direction]=event(t,y,...)
```

The return values are:

val - the value of the event function. is terminal - whether or not this event should cause termination of the integrator. direction - 1=upcrossings only matter, -1=downcrossings only, 0=both.

```
== Projection function ==
```

For geometric integration, you can provide a projection function which will be called after each time step. The projection function has the following signature:

```
function yn=project(t,yn,...);
```

If the output yn is very different from the input yn, the quality of interpolation may decrease.

Chapter 21

Operating System Functions

21.1 CD Change Working Directory Function

21.1.1 Usage

Changes the current working directory to the one specified as the argument. The general syntax for its use is

```
cd('dirname')
but this can also be expressed as
  cd 'dirname'
or
  cd dirname
```

Examples of all three usages are given below. Generally speaking, dirname is any string that would be accepted by the underlying OS as a valid directory name. For example, on most systems, '.' refers to the current directory, and '..' refers to the parent directory. Also, depending on the OS, it may be necessary to "escape" the directory seperators. In particular, if directories are seperated with the backwards-slash character '\\', then the path specification must use double-slashes '\\\'. Note: to get file-name completion to work at this time, you must use one of the first two forms of the command.

21.1.2 Example

The pwd command returns the current directory location. First, we use the simplest form of the cd command, in which the directory name argument is given unquoted.

```
--> pwd
ans =
/home/basu/dev/branches/FreeMat4/help/tmp
```

```
--> cd ..
--> pwd
ans =
/home/basu/dev/branches/FreeMat4/help
```

Next, we use the "traditional" form of the function call, using both the parenthesis and a variable to store the quoted string.

```
--> a = pwd;
--> cd(a)
--> pwd
ans =
/home/basu/dev/branches/FreeMat4/help/tmp
```

21.2 COPYFILE Copy Files

21.2.1 Usage

Copies a file or files from one location to another. There are several syntaxes for this function that are acceptable:

```
copyfile(file_in,file_out)
```

copies the file from file_in to file_out. Also, the second argument can be a directory name:

```
copyfile(file_in,directory_out)
```

in which case file_in is copied into the directory specified by directory_out. You can also use copyfile to copy entire directories as in

```
copyfile(dir_in,dir_out)
```

in which case the directory contents are copied to the destination directory (which is created if necessary). Finally, the first argument to copyfile can contain wildcards

```
copyfile(pattern,directory_out)
```

in which case all files that match the given pattern are copied to the output directory. Note that to remain compatible with the MATLAB API, this function will delete/replace destination files that already exist, unless they are marked as read-only. If you want to force the copy to succeed, you can append a 'f' argument to the copyfile function:

```
copyfile(arg1,arg2,'f')
or equivalently
copyfile arg1 arg2 f
```

21.3 DELETE Delete a File

21.3.1 Usage

Deletes a file. The general syntax for its use is

```
delete('filename')
```

or alternately

delete filename

which removes the file described by filename which must be relative to the current path.

21.4 DIR List Files Function

21.4.1 Usage

In some versions of FreeMat (pre 3.1), the dir function was aliased to the ls function. Starting with version 3.1, the dir function has been rewritten to provide compatibility with MATLAB. The general syntax for its use is

dir

in which case, a listing of the files in the current directory are output to the console. Alternately, you can specify a target via

```
dir('name')
```

or using the string syntax

```
dir name
```

If you want to capture the output of the dir command, you can assign the output to an array

```
result = dir('name')
```

(or you can omit 'name' to get a directory listing of the current directory. The resulting array result is a structure array containing the fields:

- name the filename as a string
- date the modification date and time stamp as a string
- bytes the size of the file in bytes as a uint64
- isdir a logical that is 1 if the file corresponds to a directory.

Note that 'name' can also contain wildcards (e.g., dir *.m to get a listing of all FreeMat scripts in the current directory.

21.5 DIRSEP Director Seperator

21.5.1 Usage

Returns the directory seperator character for the current platform. The general syntax for its use is

```
y = dirsep
```

This function can be used to build up paths (or see fullfile for another way to do this.

21.6 FILEPARTS Extract Filename Parts

21.6.1 Usage

The fileparts takes a filename, and returns the path, filename, extension, and (for MATLAB-compatibility) an empty version number of the file. The syntax for its use is

```
[path,name,extension,version] = fileparts(filename)
```

where filename is a string containing the description of the file, and path is the path to the file,

21.7 FULLFILE Build a Full Filename From Pieces

21.7.1 Usage

The fullfile routine constructs a full filename from a set of pieces, namely, directory names and a filename. The syntax is:

```
x = fullfile(dir1,dir2,...,dirn,filename)
```

where each of the arguments are strings. The fullfile function is equivalent to [dir1 dirsep dir2 dirsep

21.7.2 Example

```
--> fullfile('path','to','my','file.m')
ans =
path/to/my/file.m
```

21.8 GETPATH Get Current Search Path

21.8.1 Usage

Returns a string containing the current FreeMat search path. The general syntax for its use is

```
y = getpath
```

The delimiter between the paths depends on the system being used. For Win32, the delimiter is a semicolon. For all other systems, the delimiter is a colon.

21.8.2 Example

```
The getpath function is straightforward.
```

```
--> getpath

ans =
Empty array 1 0
```

21.9 LS List Files Function

21.9.1 Usage

Lists the files in a directory or directories. The general syntax for its use is

```
ls('dirname1', 'dirname2',..., 'dirnameN')
but this can also be expressed as
  ls 'dirname1' 'dirname2' ... 'dirnameN'
or
```

ls dirname1 dirname2 ... dirnameN

For compatibility with some environments, the function dir can also be used instead of ls. Generally speaking, dirname is any string that would be accepted by the underlying OS as a valid directory name. For example, on most systems, '.' refers to the current directory, and '..' refers to the parent directory. Also, depending on the OS, it may be necessary to "escape" the directory seperators. In particular, if directories are seperated with the backwards-slash character '\\', then the path specification must use double-slashes '\\\'. Two points worth mentioning about the ls function:

- To get file-name completion to work at this time, you must use one of the first two forms of the command.
- If you want to capture the output of the 1s command, use the system function instead.

21.9.2 Example

First, we use the simplest form of the ls command, in which the directory name argument is given unquoted.

```
--> ls m*.m
```

Next, we use the "traditional" form of the function call, using both the parenthesis and the quoted string.

```
--> ls('m*.m')
```

In the third version, we use only the quoted string argument without parenthesis.

```
--> ls 'm*.m'
```

21.10 MKDIR Make Directory

21.10.1 Usage

Creates a directory. The general syntax for its use is

```
mkdir('dirname')
```

which creates the directory dirname if it does not exist. The argument dirname can be either a relative path or an absolute path. For compatibility with MATLAB, the following syntax is also allowed

```
mkdir('parentdir','dirname')
```

which attempts to create a directory dirname in the directory given by parentdir. However, this simply calls mkdir([parentdir dirsep dirname]), and if this is not the required behavior, please file an enhancement request to have it changed. Note that mkdir returns a logical 1 if the call succeeded, and a logical 0 if not.

21.11 PWD Print Working Directory Function

21.11.1 Usage

Returns a string describing the current working directory. The general syntax for its use is

```
y = pwd
```

21.11.2 Example

The pwd function is fairly straightforward.

```
--> pwd
```

ans =

/home/basu/dev/branches/FreeMat4/help/tmp

21.12 RMDIR Remove Directory

21.12.1 Usage

Deletes a directory. The general syntax for its use is

```
rmdir('dirname')
```

which removes the directory dirname if it is empty. If you want to delete the directory and all subdirectories and files in it, use the syntax

```
rmdir('dirname','s')
```

21.13 SETPATH Set Current Search Path

21.13.1 Usage

Changes the current FreeMat search path. The general syntax for its use is

```
setpath(y)
```

where y is a string containing a delimited list of directories to be searched for M files and libraries. The delimiter between the paths depends on the system being used. For Win32, the delimiter is a semicolon. For all other systems, the delimiter is a colon.

@Example The setpath function is straightforward.

```
--> getpath
ans =
   Empty array 1 0
--> setpath('/usr/local/FreeMat/MFiles:/localhome/basu/MFiles')
--> getpath
ans =
/usr/local/FreeMat/MFiles:/localhome/basu/MFiles
```

21.14 SYSTEM Call an External Program

21.14.1 Usage

The system function allows you to call an external program from within FreeMat, and capture the output. The syntax of the system function is

```
y = system(cmd)
```

where cmd is the command to execute. The return array y is of type cell-array, where each entry in the array corresponds to a line from the output.

21.14.2 Example

Here is an example of calling the ls function (the list files function under Un*x-like operating system).

```
--> y = system('ls')
y =
Columns 1 to 3
[chain1.m] [chain2.m] [chain3.m]
```

```
Columns 4 to 6
[conv2_eqn1.png] [conv2_eqn.aux] [conv2_eqn.dvi]
Columns 7 to 9
[conv2_eqn.log] [conv2_eqn.tex] [cumprod_eqn1.png]
Columns 10 to 12
[cumprod_eqn.aux] [cumprod_eqn.dvi] [cumprod_eqn.log]
Columns 13 to 15
[cumprod_eqn.tex] [cumsum_eqn1.png] [cumsum_eqn.aux]
Columns 16 to 18
[cumsum_eqn.dvi] [cumsum_eqn.log] [cumsum_eqn.tex]
Columns 19 to 21
[do_jit_test.m] [eig_eqn1.png] [eig_eqn2.png]
Columns 22 to 24
[eig_eqn3.png] [eig_eqn4.png] [eig_eqn5.png]
Columns 25 to 27
[eig_eqn6.png] [eig_eqn.aux] [eig_eqn.dvi]
Columns 28 to 30
[eig_eqn.log] [eig_eqn.tex] [evenoddtest.m]
Columns 31 to 33
[fft1.jpg] [fft1.png] [fft2.jpg]
Columns 34 to 36
[fft2.png] [fft_eqn1.png] [fft_eqn2.png]
Columns 37 to 39
```

```
[fft_eqn3.png] [fft_eqn4.png] [fft_eqn.aux]
Columns 40 to 42
[fft_eqn.dvi] [fft_eqn.log] [fft_eqn.tex]
Columns 43 to 45
[find_eqn1.png] [find_eqn.aux] [find_eqn.dvi]
Columns 46 to 48
[find_eqn.log] [find_eqn.tex] [help]
Columns 49 to 51
[jit_test001.m] [jit_test002.m] [jit_test003.m]
Columns 52 to 54
[jit_test004.m] [jit_test005.m] [jit_test006.m]
Columns 55 to 57
[jit_test007.m] [jit_test008.m] [jit_test009.m]
Columns 58 to 60
[jit_test010.m] [jit_test011.m] [jit_test012.m]
Columns 61 to 63
[jit_test013.m] [jit_test014.m] [jit_test015.m]
Columns 64 to 66
[jit_test016.m] [jit_test017.m] [jit_test018.m]
Columns 67 to 69
[jit_test019.m] [jit_test020.m] [jit_test021.m]
Columns 70 to 72
[jit_test022.m] [jit_test023.m] [jit_test024.m]
```

```
Columns 73 to 75
[loadsave.dat] [max_eqn1.png] [max_eqn2.png]
Columns 76 to 78
[max_eqn3.png] [max_eqn.aux] [max_eqn.dvi]
Columns 79 to 81
[max_eqn.log] [max_eqn.tex] [mean_eqn1.png]
Columns 82 to 84
[mean_eqn.aux] [mean_eqn.dvi] [mean_eqn.log]
Columns 85 to 87
[mean_eqn.tex] [min_eqn1.png] [min_eqn2.png]
Columns 88 to 90
[min_eqn3.png] [min_eqn.aux] [min_eqn.dvi]
Columns 91 to 93
[min_eqn.log] [min_eqn.tex] [nargintest.m]
Columns 94 to 96
[nargouttest.m] [source_test] [source_test_script.m]
Columns 97 to 99
[test_assignin1.m] [test_assignin2.m] [test_bin2int1.m]
Columns 100 to 102
[test_bitand1.m] [test_bitor1.m] [test_bitxor1.m]
Columns 103 to 105
[test.bmp] [test_builtin1.m] [test_cell1.m]
Columns 106 to 108
```

```
[test_clear1.m] [test_clear2.m] [test_conv2_1.m]
Columns 109 to 111
[test_ctype1.m] [test.dat] [test_dcomplex1.m]
Columns 112 to 114
[test_diag1.m] [test_diag2.m] [test_diag3.m]
Columns 115 to 117
[test_diag4.m] [test_diag5.m] [test_dlmread1.m]
Columns 118 to 120
[test_eig1.m] [test_eig2.m] [test_eig3.m]
Columns 121 to 123
[test_eig4.m] [test_eig5.m] [test_eig6.m]
Columns 124 to 126
[test_empty.m] [test_eps1.m] [test_error1.m]
Columns 127 to 129
[test_eval1.m] [test_eval2.m] [test_eval3.m]
Columns 130 to 132
[test_evalin1.m] [test_evalin2.m] [test_exist1.m]
Columns 133 to 135
[test_exist2.m] [test_feval1.m] [test_fieldnames1.m]
Columns 136 to 138
[test_imwrite_imread.m] [test_int2bin1.m] [test_isset1.m]
Columns 139 to 141
[test_jit.m] [test_lasterr1.m] [test_load1.m]
```

```
Columns 142 to 144
 [test_lu1.m] [test_lu2.m] [test_nargin1.m]
 Columns 145 to 147
 [test_nargin2.m] [test_permute1.m] [test_permute2.m]
 Columns 148 to 150
 [test_repmat1.m] [test_repmat2.m] [test_repmat3.m]
 Columns 151 to 153
 [test_save1.m] [test_source.m] [test_sparse20.m]
 Columns 154 to 156
 [test_sparse21.m] [test_sparse45.m] [test_sparse58.m]
 Columns 157 to 159
 [test_sparse68.m] [test_sparse70.m] [test_sparse74.m]
 Columns 160 to 162
 [test_sparse75.m] [testtext] [test_typeof1.m]
 Columns 163 to 165
 [test_typeof2.m] [test_typeof3.m] [test_typeof4.m]
 Columns 166 to 168
 [test_typeof5.m] [test_typeof6.m] [test_uint64_1.m]
 Columns 169 to 169
 [toolbox]
--> y{1}
ans =
chain1.m
```

Chapter 22

Optimization and Curve Fitting

22.1 FITFUN Fit a Function

22.1.1 Usage

Fits n (non-linear) functions of m variables using least squares and the Levenberg-Marquardt algorithm. The general syntax for its usage is

```
[xopt,yopt] = fitfun(fcn,xinit,y,weights,tol,params...)
```

Where fcn is the name of the function to be fit, xinit is the initial guess for the solution (required), y is the right hand side, i.e., the vector y such that:

$$xopt = \arg\min_{x} \|\operatorname{diag}(weights) * (f(x) - y)\|_{2}^{2},$$

the output yopt is the function fcn evaluated at xopt. The vector weights must be the same size as y, and contains the relative weight to assign to an error in each output value. Generally, the ith weight should reflect your confidence in the ith measurement. The parameter tol is the tolerance used for convergence. The function fcn must return a vector of the same size as y, and params are passed to fcn after the argument x, i.e.,

```
y = fcn(x, param1, param2, ...).
```

Note that both x and y (and the output of the function) must all be real variables. Complex variables are not handled yet.

```
fitfunc_func1.m
function y = fitfunc_func1(init,junk)
c = 2;
d = 0;
init2 = [c,d];
y2 = [1:100]*3;
weights2 = y2*0+1;
tol2 = 1.e-08;
```

```
junk2 = rand(100);
[xopt2,yopt2] = fitfun('fitfunc_func2',init2,y2,weights2,tol2,junk2);
a = init(1);
b = init(2);
x = [1:100];
y = a*x + b;

fitfunc_func2.m
function y = fitfunc_func2(init,junk);
a = init(1);
b = init(2);
x = [1:100];
y = a*x+b;
```

22.2 GAUSFIT Gaussian Curve Fit

22.2.1 Usage

The gausfit routine has the following syntax

```
[mu,sigma,dc,gain,yhat] = gausfit(t,y,w,mug,sigmag,dcg,gaing).
```

where the required inputs are

- t the values of the independent variable (e.g., time samples)
- y the values of the dependant variable (e.g., f(t))

The following inputs are all optional, and default values are available for each of them.

- w the weights to use in the fitting (set to ones if omitted)
- mug initial estimate of the mean
- sigmag initial estimate of the sigma (standard deviation)
- dcg initial estimate of the DC value
- gaing initial estimate of the gain

The fit is of the form yhat=gain*exp((t-mu).^2/(2*sigma^2))+dc. The outputs are

- mu the mean of the fit
- sigma the sigma of the fit
- dc the dc term of the fit
- gain the gain of the gaussian fit
- yhat the output samples (the Gaussian fits)

Because the fit is nonlinear, a good initial guess is critical to convergence of the solution. Thus, you can supply initial guesses for each of the parameters using the mug, sigmag, dcg, gaing arguments. Any arguments not supplied are estimated using a simple algorithm. In particular, the DC value is estimated by taking the minimum value from the vector y. The gain is estimated from the range of y. The mean and standard deviation are estimated using the first and second order moments of y. This function uses fitfun.

22.2.2 Example

Suppose we want to fit a cycle of a cosine using a Gaussian shape.

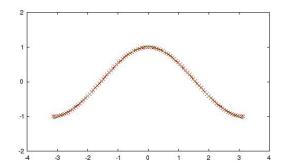
```
--> t = linspace(-pi,pi);

--> y = cos(t);

--> [mu,sigma,dc,gain,yhat] = gausfit(t,y);

--> plot(t,y,'rx',t,yhat,'g-');
```

Which results in the following plot



22.3 INTERPLIN1 Linear 1-D Interpolation

22.3.1 Usage

Given a set of monotonically increasing x coordinates and a corresponding set of y values, performs simple linear interpolation to a new set of x coordinates. The general syntax for its usage is

```
yi = interplin1(x1,y1,xi)
```

where x1 and y1 are vectors of the same length, and the entries in x1 are monotonically increasing. The output vector yi is the same size as the input vector xi. For each element of xi, the values in y1 are linearly interpolated. For values in xi that are outside the range of x1 the default value returned is nan. To change this behavior, you can specify the extrapolation flag:

```
yi = interplin1(x1,y1,xi,extrapflag)
```

Valid options for extrapflag are:

• 'nan' - extrapolated values are tagged with nans

- 'zero' extrapolated values are set to zero
- 'endpoint' extrapolated values are set to the endpoint values
- 'extrap' linear extrapolation is performed

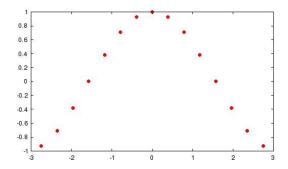
The x1 and xi vectors must be real, although complex types are allowed for y1.

22.3.2 Example

Here is an example of simple linear interpolation with the different extrapolation modes. We start with a fairly coarse sampling of a cosine.

```
--> x = linspace(-pi*7/8,pi*7/8,15);
--> y = cos(x);
--> plot(x,y,'ro');
```

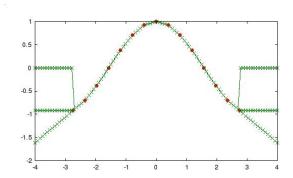
which is shown here



Next, we generate a finer sampling over a slightly broader range (in this case [-pi,pi]). First, we demonstrate the 'nan' extrapolation method

```
--> xi = linspace(-4,4,100);
--> yi_nan = interplin1(x,y,xi,'nan');
--> yi_zero = interplin1(x,y,xi,'zero');
--> yi_endpoint = interplin1(x,y,xi,'endpoint');
--> yi_extrap = interplin1(x,y,xi,'extrap');
--> plot(x,y,'ro',xi,yi_nan,'g-x',xi,yi_zero,'g-x',xi,yi_endpoint,'g-x',xi,yi_extrap,'g-x'
```

which is shown here



22.4 POLY Convert Roots To Polynomial Coefficients

22.4.1 Usage

This function calculates the polynomial coefficients for given roots

$$p = poly(r)$$

when **r** is a vector, is a vector whose elements are the coefficients of the polynomial whose roots are the elements of **r**. Alternately, you can provide a matrix

$$p = poly(A)$$

when A is an N x N square matrix, is a row vector with N+1 elements which are the coefficients of the characteristic polynomial, det(lambda*eye(size(A))-A).

Contributed by Paulo Xavier Candeias under GPL.

22.4.2 Example

Here are some examples of the use of ${\tt poly}$

```
--> A = [1,2,3;4,5,6;7,8,0]

A =
    1 2 3
    4 5 6
    7 8 0

--> p = poly(A)

p =
    1.0000  -6.0000  -72.0000  -27.0000

--> r = roots(p)
```

```
r =
12.1229
-5.7345
-0.3884
```

22.5 POLYDER Polynomial Coefficient Differentiation

22.5.1 Usage

The polyder function returns the polynomial coefficients resulting from differentiation of polynomial p. The syntax for its use is either

```
pder = polyder(p)
for the derivitave of polynomial p, or
  convp1p2der = polyder(p1,p2)
for the derivitave of polynomial conv(p1,p2), or still
  [nder,dder] = polyder(n,d)
```

for the derivative of polynomial n/d (nder is the numerator and dder is the denominator). In all cases the polynomial coefficients are assumed to be in decreasing degree. Contributed by Paulo Xavier Candeias under GPL

22.5.2 Example

Here are some examples of the use of polyder

```
--> polyder([2,3,4])

ans =
    4 3

--> polyder([2,3,4],7)

ans =
    28 21

--> [n,d] = polyder([2,3,4],5)
n =
    -20 -15

d =
    25
```

22.6 POLYFIT Fit Polynomial To Data

22.6.1 Usage

The polyfit routine has the following syntax

$$p = polyfit(x,y,n)$$

where x and y are vectors of the same size, and n is the degree of the approximating polynomial. The resulting vector p forms the coefficients of the optimal polynomial (in descending degree) that fit y with x.

22.6.2 Function Internals

The polyfit routine finds the approximating polynomial

$$p(x) = p_1 x^n + p_2 x^{n-1} + \dots + p_n x + p_{n+1}$$

such that

$$\sum_{i} (p(x_i) - y_i)^2$$

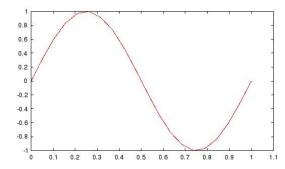
is minimized. It does so by forming the Vandermonde matrix and solving the resulting set of equations using the backslash operator. Note that the Vandermonde matrix can become poorly conditioned with large **n** quite rapidly.

22.6.3 Example

A classic example from Edwards and Penny, consider the problem of approximating a sinusoid with a polynomial. We start with a vector of points evenly spaced on the unit interval, along with a vector of the sine of these points.

```
--> x = linspace(0,1,20);
--> y = sin(2*pi*x);
--> plot(x,y,'r-')
```

The resulting plot is shown here



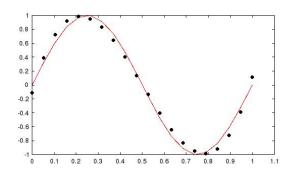
Next, we fit a third degree polynomial to the sine, and use polyval to plot it

```
--> p = polyfit(x,y,3)

p =
    21.9170 -32.8756   11.1897 -0.1156

--> f = polyval(p,x);
--> plot(x,y,'r-',x,f,'ko');
```

The resulting plot is shown here



Increasing the order improves the fit, as

```
--> p = polyfit(x,y,11)

p =

Columns 1 to 6

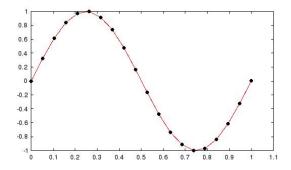
12.4644 -68.5541 130.0555 -71.0940 -38.2814 -14.1222

Columns 7 to 12

85.1018 -0.5642 -41.2861 -0.0029 6.2832 -0.0000

--> f = polyval(p,x);
--> plot(x,y,'r-',x,f,'ko');
```

The resulting plot is shown here



22.7 POLYINT Polynomial Coefficient Integration

22.7.1 Usage

The polyint function returns the polynomial coefficients resulting from integration of polynomial p. The syntax for its use is either

```
pint = polyint(p,k)
or, for a default k = 0,
pint = polyint(p);
```

where p is a vector of polynomial coefficients assumed to be in decreasing degree and k is the integration constant. Contributed by Paulo Xavier Candeias under GPL

22.7.2 Example

Here is are some examples of the use of polyint.

22.8 POLYVAL Evaluate Polynomial Fit at Selected Points

22.8.1 Usage

The polyval routine has the following syntax

$$y = polyval(p,x)$$

where p is a vector of polynomial coefficients, in decreasing degree (as generated by polyfit, for example). If x is a matrix, the polynomial is evaluated in the matrix sense (in which case x must be square).

22.8.2 Function Internals

The polynomial is evaluated using a recursion method. If the polynomial is

$$p(x) = p_1 x^n + p_2 x^{n-1} + \dots + p_n x + p_{n+1}$$

then the calculation is performed as

$$p(x) = ((p_1)x + p_2)x + p_3$$

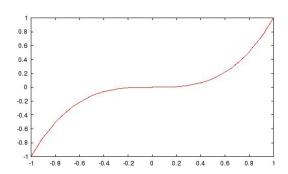
22.8.3 Example

Here is a plot of x^3 generated using polyval

```
--> p = [1 0 0 0]
p =
1 0 0 0
```

```
--> x = linspace(-1,1);
--> y = polyval(p,x);
--> plot(x,y,'r-')
```

Here is the resulting plot



22.9 ROOTS Find Roots of Polynomial

22.9.1 Usage

The roots routine will return a column vector containing the roots of a polynomial. The general syntax is

$$z = roots(p)$$

where p is a vector containing the coefficients of the polynomial ordered in descending powers.

22.9.2 Function Internals

Given a vector

$$[p_1, p_2, \dots p_n]$$

which describes a polynomial

$$p_1 x^{n-1} + p_2 x^{n-2} + \dots + p_n$$

we construct the companion matrix (which has a characteristic polynomial matching the polynomial described by p), and then find the eigenvalues of it (which are the roots of its characteristic polynomial), and which are also the roots of the polynomial of interest. This technique for finding the roots is described in the help page for roots on the Mathworks website.

22.9.3 Example

Here is an example of finding the roots to the polynomial

$$x^3 - 6x^2 - 72x - 27$$

--> roots([1 -6 -72 -27])

ans =

12.1229

-5.7345

-0.3884

Chapter 23

Handle-Based Graphics

23.1 AXES Create Handle Axes

23.1.1 Usage

This function has three different syntaxes. The first takes no arguments,

h = axes

and creates a new set of axes that are parented to the current figure (see gcf). The newly created axes are made the current axes (see gca) and are added to the end of the list of children for the current figure. The second form takes a set of property names and values

```
h = axes(propertyname, value, propertyname, value, ...)
```

Creates a new set of axes, and then sets the specified properties to the given value. This is a shortcut for calling set(h,propertyname,value) for each pair. The third form takes a handle as an argument

axes(handle)

and makes handle the current axes, placing it at the head of the list of children for the current figure.

23.2 AXIS Setup Axis Behavior

23.2.1 Usage

Control the axis behavior. There are several versions of the axis command based on what you would like the axis command to do. The first versions set scalings for the current plot. The general syntax for its use is

axis([xmin xmax ymin ymax zmin zmax cmin cmax])

which sets the limits in the X, Y, Z and color axes. You can also set only the X, Y and Z axes:

```
axis([xmin xmax ymin ymax zmin zmax])
```

or only the X and Y axes:

```
axis([xmin xmax ymin ymax])
```

To retrieve the current axis limits, use the syntax

```
x = axis
```

where x is a 4-vector for 2D plots, and a 6-vector for 3D plots.

There are a number of axis options supported by FreeMat. The first version sets the axis limits to be automatically selected by FreeMat for each dimension. This state is the default one for new axes created by FreeMat.

```
axis auto
```

The next option sets all of the axis limits to manual mode. This state turns off automatic scaling of the axis based on the children of the current axis object.

```
axis manual
```

The next option sets the axis limits to fit tightly around the data.

```
axis tight
```

The next option adjusts the axis limits and plotbox aspect ratio so that the axis fills the position rectangle.

```
axis fill
```

The next option puts the axis in matrix mode. This mode is equivalent to the standard mode, but with the vertical axis reversed. Thus, the origin of the coordinate system is at the top left corner of the plot. This mode makes plots of matrix elements look normal (i.e., an identity matrix goes from upper left to lower right).

```
axis ij
```

The next option puts the axis in normal mode, with the origin at the lower left corner.

```
axis xy
```

The next option sets the axis parameters (specifically the data aspect ratio) so that equal ticks on each axis represent equal length. In this mode, spheres look spherical insteal of ellipsoidal.

```
axis equal
```

The next option is the same as axis equal, but sets the plot box to fit tightly around the data (so no background shows through). It is the best option to use when displaying images.

```
axis image
```

The next option makes the axis box square.

axis square

The next option restores many of the normal characteristics of the axis. In particular, it undoes the effects of square image and equal modes.

axis normal

The next mode freezes axis properties so that 3D objects can be rotated properly.

```
axis vis3d
```

The next mode turns off all labels, tick marks and background.

```
axis on
```

The next mode turns on all labels, tick marks and background.

```
axis off
```

The next mode is similar to axis off, but also repacks the figure as tightly as possible. The result is a plot box that takes up the entire outerposition vector.

```
axis maximal
```

The axis command can also be applied to a particular axis (as opposed to the current axis as returned by gca) handle

```
axis(M,...)
```

23.3 AXISPROPERTIES Axis Object Properties

23.3.1 Usage

Below is a summary of the properties for the axis.

- activepositionproperty four vector Not used.
- alim two vector Controls the mapping of transparency. The vector [a_1,a_2]@ defines the scale for transparency. Plots then map a_1 to a completely opaque value, and a_2 to a completely transparent value. This mapping is applied to the alpha data of the plot data.
- alimmode {'auto', 'manual'} For auto mode, we map the alpha ranges of all objects in the plot to a full scale. For manual mode, we use the alim vector.
- ambientlightcolor colorspec Not used.
- box On/Off Not used.
- cameraposition three vector Set the position for the camera in axis space.
- camerapositionmode {'auto', 'manual'} For manual mode, the camera position is picked up from the cameraposition vector. For auto mode, the camera position is set to be centered on the x and y axis limits, and beyond the z maximum limit.

- cameratarget three vector Defines the point in axis space that the camera is targetted at.
- cameratargetmode {'auto', 'manual'} For manual mode the camera target is picked up from the cameratarget vector. For auto mode, the camera target is chosen to be the center of the three axes.
- cameraupvector three vector Defines the upwards vector for the camera (what is ultimately mapped to the vertical axis of the plot or screen). This vector must not be parallel to the vector that is defined by the optical axis (i.e., the one connecting the target to the camera position).
- cameraupvectormode {'auto', 'manual'} For manual mode, the camera up vector is picked up from the cameraupvector. The auto mode chooses the up vector to point along the positive y axis.
- cameraviewangle scalar Not used.
- cameraviewanglemode {'auto', 'manual'} Not used.
- children vector of handles A vector containing handles to children of the current axis. Be careful as to how you manipulate this vector. FreeMat uses a reference counting mechanism for graphics objects, so if you remove a handle from the children property of an axis, and you have not added it to the children property of another object, it will be deleted.
- clim two vector The color range vector. This vector contains two values that dictate how children of this axis get mapped to the colormap. Values between the two endpoints of this vector are mapped to the extremes of the colormap.
- climmode {'auto', 'manual'} For auto mode, the color limits are chosen to span the colordata for all of the children objects. For manual mode, the color mapping is based on clim.
- clipping {'on','off'} Not used.
- color colorspec The color used to draw the background box for the axes. Defaults to white.
- colororder color vector A vector of color specs (in RGB) that are cycled between when drawing line plots into this axis. The default is order blue, green, red, cyan, magenta, yellow, black.
- datalimits six vector A vector that contains the x, y and z limits of the data for children of the current axis. Changes to this property are ignored it is calculated by FreeMat based on the datasets.
- dataaspectratio three vector A vector that describes the aspect ratio of the data. You can think of this as the relative scaling of units for each axis. For example, if one unit along the x axis is twice as long as one unit along the y axis, you would specify a data aspect ratio of [2,1,1].

- dataaspectratiomode {'auto', 'manual'} When the data aspect ratio is set to manual, the data is scaled by the data aspect ratio before being plotted. When the data aspect ratio mode is auto a complex set of rules are applied to determine how the data should be scaled. If dataaspectratio mode is auto and plotboxaspectratio is auto, then the default data aspect ratio is set to [1,1,1] and the default plot box aspect ratio is chosen proportional to [xrange,yrange,zrange], where xrange is the span of data along the x axis, and similarly for yrange and zrange. If plotboxaspectratio is set to [px,py,pz], then the dataaspectratio is set to [xrange/px,yrange/py,zrange/pz]. If one of the axes has been specified manually, then the data will be scaled to fit the axes as well as possible.
- fontangle {'normal', 'italic', 'oblique'} The angle of the fonts used for text labels (e.g., tick labels).
- fontsize scalar The size of fonts used for text labels (tick labels).
- fontunits Not used.
- fontweight {'normal','bold','light','demi'} The weight of the font used for tick labels.
- gridlinestyle {'-','--',':','-.','none'} The line style to use for drawing the grid lines. Defaults to ':'.
- handlevisibility Not used.
- hittest Not used.
- interruptible Not used.
- layer Not used.
- linestyleorder linestyle vector A vector of linestyles that are cycled through when plotted line series.
- linewidth scalar The width of line used to draw grid lines, axis lines, and other lines.
- minorgridlinestyle {'-','--',':','-.','none'} The line style used for drawing grid lines through minor ticks.
- nextplot {'add', 'replace', 'replacechildren'} Controls how the next plot interacts with the axis. If it is set to 'add' the next plot will be added to the current axis. If it is set to 'replace' the new plot replaces all of the previous children.
- outerposition four vector Specifies the coordinates of the outermost box that contains the axis relative to the containing figure. This vector is in normalized coordinates and corresponds to the x, y, width, height coordinates of the box.
- parent handle The handle for the containing object (a figure).
- plotboxaspectratio three vector Controls the aspect ratio of the plot box. See the entry under dataaspectratio for details on how FreeMat uses this vector in combination with the axis limits and the plotboxaspectratio to determine how to scale the data.

- plotboxaspectratiomode {'auto', 'manual'} The plot box aspect ratio mode interacts with the dataaspectratiomode and the axis limits.
- position fourvector The normalized coordinates of the plot box space. Should be inside the rectable defined by outerposition.
- positionmode {'auto', 'manual'} the position mode is normally 'auto' which means that FreeMat computes the position vector to fit the plot inside the outerposition vector. If you set the position vector manually (using a set command), this mode flag becomes 'manual' and remains that way until reset to @—'auto'.
- projection Not used.
- selected Not used.
- selectionhighlight Not used.
- tag A string that can be set to tag the axes with a name.
- textheight scalar This value is set by FreeMat to the height of the current font in pixels.
- tickdir {'in', 'out'} The direction of ticks. Defaults to 'in' for 2D plots, and 'out' for 3D plots if tickdirmode is auto.
- tickdirmode {'auto', 'manual'} When set to 'auto' the tickdir defaults to 'in' for 2D plots, and 'out' for 3D plots.
- ticklength two vector The first element is the length of the tick in 2D plots, and the second is the length of the tick in the 3D plots. The lengths are described as fractions of the longer dimension (width or height).
- tightinset Not used.
- title handle The handle of the label used to represent the title of the plot.
- type string Takes the value of 'axes' for objects of the axes type.
- units Not used.
- userdata array An arbitrary array you can set to anything you want.
- visible {'on', 'off'} If set to 'on' the axes are drawn as normal. If set to 'off', only the children of the axes are drawn. The plot box, axis lines, and tick labels are not drawn.
- xaxislocation {'top', 'bottom'} Controls placement of the x axis.
- yaxislocation {'left', 'right'} Controls placement of the y axis.
- xcolor colorspec The color of the x elements including the the x axis line, ticks, grid lines and tick labels
- ycolor colorspec The color of the y elements including the the y axis line, ticks, grid lines and tick labels.

- zcolor colorspec The color of the z elements including the the z axis line, ticks, grid lines and tick labels.
- xdir {'normal', 'reverse'} For normal, axes are drawn as you would expect (e.g, in default 2D mode, the x axis has values increasing from left to right. For reverse, the x axis has values increasing from right to left.
- ydir {'normal', 'reverse'} For normal, axes are drawn as you would expect (e.g, in default 2D mode, the y axis has values increasing from bottom to top. For reverse, the y axis has values increasing from top to bottom.
- zdir {'normal', 'reverse'} For normal, axes are drawn as you would expect. In default 3D mode, the z axis has values increasing in some direction (usually up). For reverse the z axis increases in the opposite direction.
- xgrid {'on', 'off'} Set to on to draw grid lines from ticks on the x axis.
- ygrid {'on', 'off'} Set to on to draw grid lines from ticks on the y axis.
- zgrid {'on', 'off'} Set to on to draw grid lines from ticks on the z axis.
- xlabel handle The handle of the text label attached to the x axis. The position of that label and the rotation angle is computed automatically by FreeMat.
- ylabel handle The handle of the text label attached to the y axis. The position of that label and the rotation angle is computed automatically by FreeMat.
- zlabel handle The handle of the text label attached to the z axis. The position of that label and the rotation angle is computed automatically by FreeMat.
- xlim two vector Contains the limits of the data along the x axis. These are set automatically for xlimmode. When manually set it allows you to zoom into the data. The first element of this vector should be the smallest x value you want mapped to the axis, and the second element should be the largest.
- ylim two vector Contains the limits of the data along the y axis. These are set automatically for ylimmode. When manually set it allows you to zoom into the data. The first element of this vector should be the smallest y value you want mapped to the axis, and the second element should be the largest.
- zlim two vector Contains the limits of the data along the z axis. These are set automatically for zlimmode. When manually set it allows you to zoom into the data. The first element of this vector should be the smallest z value you want mapped to the axis, and the second element should be the largest.
- xlimmode {'auto', 'manual'} Determines if xlim is determined automatically or if it is determined manually. When determined automatically, it is chosen to span the data range (at least).

- ylimmode {'auto', 'manual'} Determines if ylim is determined automatically or if it is determined manually. When determined automatically, it is chosen to span the data range (at least).
- zlimmode {'auto', 'manual'} Determines if zlim is determined automatically or if it is determined manually. When determined automatically, it is chosen to span the data range (at least).
- xminorgrid {'on', 'off'} Set to on to draw grid lines from minor ticks on the x axis.
- yminorgrid {'on', 'off'} Set to on to draw grid lines from minor ticks on the y axis.
- zminorgrid {'on', 'off'} Set to on to draw grid lines from minor ticks on the z axis.
- xscale {'linear', 'log'} Determines if the data on the x axis is linear or logarithmically scaled.
- yscale {'linear', 'log'} Determines if the data on the y axis is linear or logarithmically scaled
- zscale {'linear', 'log'} Determines if the data on the z axis is linear or logarithmically scaled.
- xtick vector A vector of x coordinates where ticks are placed on the x axis. Setting this vector allows you complete control over the placement of ticks on the axis.
- ytick vector A vector of y coordinates where ticks are placed on the y axis. Setting this vector allows you complete control over the placement of ticks on the axis.
- ztick vector A vector of z coordinates where ticks are placed on the z axis. Setting this vector allows you complete control over the placement of ticks on the axis.
- xticklabel string vector A string vector, of the form 'stringstring—string'— that contains labels to assign to the labels on the axis. If this vector is shorter than xtick, then FreeMat will cycle through the elements of this vector to fill out the labels.
- yticklabel string vector A string vector, of the form 'stringstring—string'— that contains labels to assign to the labels on the axis. If this vector is shorter than ytick, then FreeMat will cycle through the elements of this vector to fill out the labels.
- zticklabel string vector A string vector, of the form 'stringstring—string'— that contains labels to assign to the labels on the axis. If this vector is shorter than ztick, then FreeMat will cycle through the elements of this vector to fill out the labels.
- xtickmode {'auto', 'manual'} Set to 'auto' if you want FreeMat to calculate the tick locations. Setting 'xtick' will cause this property to switch to 'manual'.
- ytickmode {'auto', 'manual'} Set to 'auto' if you want FreeMat to calculate the tick locations. Setting 'ytick' will cause this property to switch to 'manual'.
- ztickmode {'auto', 'manual'} Set to 'auto' if you want FreeMat to calculate the tick locations. Setting 'ztick' will cause this property to switch to 'manual'.

- xticklabelmode {'auto', 'manual'} Set to 'auto' if you want FreeMat to set the tick labels. This will be based on the vector xtick.
- yticklabelmode {'auto', 'manual'} Set to 'auto' if you want FreeMat to set the tick labels. This will be based on the vector ytick.
- zticklabelmode {'auto', 'manual'} Set to 'auto' if you want FreeMat to set the tick labels. This will be based on the vector ztick.

23.4 CLA Clear Current Axis

23.4.1 Usage

Clears the current axes. The syntax for its use is

cla

23.5 CLABEL Add Labels To Contour Plot

23.5.1 Usage

The clabel function adds labels to a contour plot Generate contour labels for a contour plot. The syntax for its use is either:

```
handles = clabel(contourhandle,property,value,property,value,...)
```

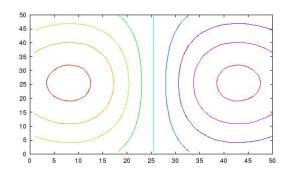
which labels all of the contours in the plot, or

```
handles = clabel(contourhandle, vals, property, value, property, value, ...)
```

which only labels those contours indicated by the vector vals. The contourhandle must be the handle to a contour plot object. The remaining property/value pairs are passed to the text function to control the parameters of the generated text labels. See the text properties for the details on what can be used in those labels.

23.5.2 Example

which results in

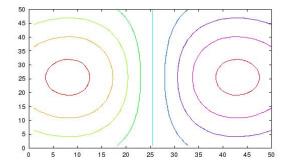


Alternately, we can just label a subset of the contours

```
--> h = contour(z);
--> clabel(h,[-.2,0,.3]);
In /home/basu/dev/branches/FreeMat4/src/toolbox/graph/text.m(text) at line 72
        In /home/basu/dev/branches/FreeMat4/src/toolbox/graph/clabel.m(clabel) at line 71
        In scratch() at line 1
        In base(base)
        In base()
        In global()
```

Error: Got error Expect a vector of length 3, got a vector of length 2 for property posit:

which results in



23.6 CLF Clear Figure

23.6.1 Usage

This function clears the contents of the current figure. The syntax for its use is

clf

23.7 CLIM Adjust Color limits of plot

23.7.1 Usage

There are several ways to use clim to adjust the color limits of a plot. The various syntaxes are

```
clim
clim([lo,hi])
clim('auto')
clim('manual')
clim('mode')
clim(handle,...)
```

The first form (without arguments), returns a 2-vector containing the current limits. The second form sets the limits on the plot to [lo,hi]. The third and fourth form set the mode for the limit to auto and manual respectively. In auto mode, FreeMat chooses the range for the axis automatically. The clim('mode') form returns the current mode for the axis (either 'auto' or 'manual').

Switching to manual mode does not change the limits, it simply allows you to modify them (and disables the automatic adjustment of the limits as more objects are added to the plot). Also, if you specify a set of limits explicitly, the mode is set to manual

Finally, you can specify the handle of an axis to manipulate instead of using the current one.

23.7.2 Example

which results in

Here is an example of using clim to change the effective window and level onto an image. First, the image with default limits

```
--> x = repmat(linspace(-1,1),[100,1]); y = x';

--> z = exp(-x.^2-y.^2);

--> image(z);

--> min(z(:))

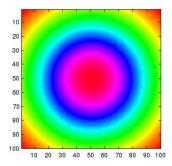
ans =

0.1353

--> max(z(:))

ans =

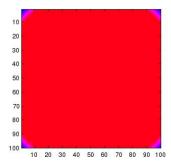
0.9998
```



Next, we change the colorscale of the image using the clim function

```
--> image(z);
--> clim([0,0.2]);
```

which results in



23.8 CLOSE Close Figure Window

23.8.1 Usage

Closes a figure window, either the currently active window, a window with a specific handle, or all figure windows. The general syntax for its use is

close(handle)

in which case the figure window with the speicified handle is closed. Alternately, issuing the command with no argument

close

is equivalent to closing the currently active figure window. Finally the command

closes all figure windows currently open.

23.9 COLORBAR Add Colorbar to Current Plot

23.9.1 Usage

There are a number of syntaxes for the colorbar command. The first takes no arguments, and adds a vertical colorbar to the right of the current axes.

colorbar

You can also pass properties to the newly created axes object using the second syntax for colorbar

colorbar(properties...)

23.10 COLORMAP Image Colormap Function

23.10.1 Usage

Changes the colormap for the current figure. The generic syntax for its use is

colormap(map)

where map is a an array organized as 3 \times N), which defines the RGB (Red Green Blue) coordinates for each color in the colormap. You can also use the function with no arguments to recover the current colormap

map = colormap

23.10.2 Function Internals

Assuming that the contents of the colormap function argument c are labeled as:

$$c = \begin{bmatrix} r_1 & g_1 & b_1 \\ r_1 & g_2 & b_2 \\ r_1 & g_3 & b_3 \\ \vdots & \vdots & \vdots \end{bmatrix}$$

then these columns for the RGB coordinates of pixel in the mapped image. Assume that the image occupies the range [a, b]. Then the RGB color of each pixel depends on the value x via the following integer

$$k = 1 + \lfloor 256 \frac{x - a}{b - a} \rfloor,$$

so that a pixel corresponding to image value x will receive RGB color $[r_k, g_k, b_k]$. Colormaps are generally used to pseudo color images to enhance visibility of features, etc.

23.10.3 Examples

We start by creating a smoothly varying image of a 2D Gaussian pulse.

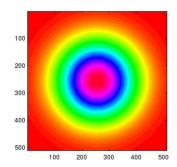
```
--> x = linspace(-1,1,512)'*ones(1,512);

--> y = x';

--> Z = exp(-(x.^2+y.^2)/0.3);

--> image(Z);
```

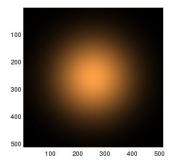
which we display with the default (grayscale) colormap here.



Next we switch to the copper colormap, and redisplay the image.

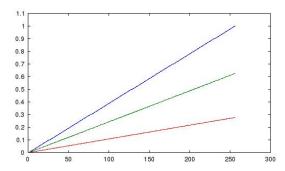
```
--> colormap(copper);
--> image(Z);
```

which results in the following image.



If we capture the output of the copper command and plot it, we obtain the following result:

```
--> a = copper;
--> plot(a);
```

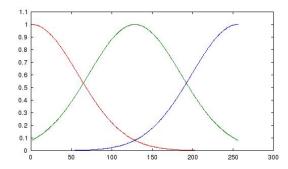


Note that in the output that each of the color components are linear functions of the index, with the ratio between the red, blue and green components remaining constant as a function of index. The result is an intensity map with a copper tint. We can similarly construct a colormap of our own by defining the three components seperately. For example, suppose we take three gaussian curves, one for each color, centered on different parts of the index space:

```
--> t = linspace(0,1,256);

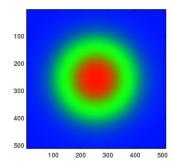
--> A = [exp(-(t-1.0).^2/0.1);exp(-(t-0.5).^2/0.1);exp(-t.^2/0.1)]';

--> plot(A);
```



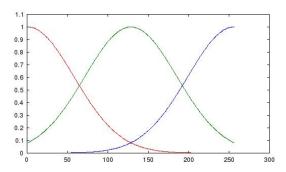
The resulting image has dark bands in it near the color transitions.

```
--> image(Z);
--> colormap(A);
```



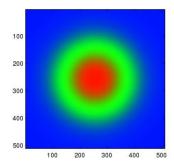
These dark bands are a result of the nonuniform color intensity, which we can correct for by renormalizing each color to have the same norm.

```
--> w = sqrt(sum(A'.^2));
--> sA = diag(1./w)*A;
--> plot(A);
```



The resulting image has no more dark bands.

```
--> image(Z);
--> colormap(A);
```



23.11 COLORSPEC Color Property Description

23.11.1 Usage

There are a number of ways of specifying a color value for a color-based property. Examples include line colors, marker colors, and the like. One option is to specify color as an RGB triplet

```
set(h,'color',[r,g,b])
```

where r,g,b are between @[0,1]@. Alternately, you can use color names to specify a color.

• 'none' - No color.

- 'y', 'yellow' The color @[1,1,0]@ in RGB space.
- 'm', 'magenta' The color @[1,0,1]@ in RGB space.
- 'c', 'cyan' The color @[0,1,1]@ in RGB space.
- 'r', 'red' The color @[1,0,0]@ in RGB space.
- 'g', 'green' The color @[0,1,0]@ in RGB space.
- 'b', 'blue' The color @[0,0,1]@ in RGB space.
- 'w', 'white' The color @[1,1,1]@ in RGB space.
- 'k', 'black' The color @[0,0,0]@ in RGB space.

23.12 CONTOUR Contour Plot Function

23.12.1 Usage

This command generates contour plots. There are several syntaxes for the command. The simplest is

```
contour(Z)
```

which generates a contour plot of the data in matrix Z, and will automatically select the contour levels. The x,y coordinates of the contour default to 1:n and 1:m, where n is the number of columns and m is the number of rows in the Z matrix. Alternately, you can specify a scalar n

```
contour(Z,n)
```

which indicates that you want n contour levels. For more control, you can provide a vector v containing the levels to contour. If you want to generate a contour for a particular level, you must pass a vector [t,t] where t is the level you want to contour. If you have data that lies on a particular X,Y grid, you can pass either vectors x,y or matrices X,Y to the contour function via

```
contour(X,Y,Z)
contour(X,Y,Z,n)
contour(X,Y,Z,v)
```

Each form of contour can optionally take a line spec to indicate the color and linestyle of the contours to draw:

```
contour(...,linespec)
```

or any of the other forms of contour. Furthermore, you can supply an axis to target the contour plot to (so that it does not get added to the current axis, which is the default):

```
contour(axis_handle,...)
```

Finally, the contour command returns a handle to the newly returned contour plot.

```
handle = contour(...)
```

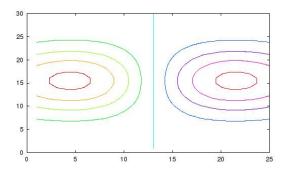
To place labels on the contour plot, use the clabel function.

23.12.2 Example

Here is a simple example of a contour plot with the default x,y coordinates:

```
--> [x,y] = meshgrid(linspace(-1,1,25),linspace(-2,2,30));
--> z = x.*exp(-x.^2-y.^2);
--> contour(z)
```

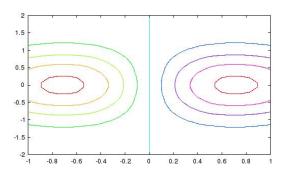
which results in the following plot



Here, we specify the x and y coordinates explictly

```
--> contour(x,y,z)
```

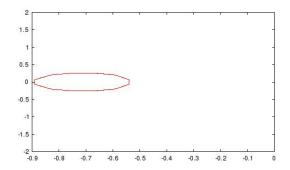
note that the axis limits have changed appropriately



By default, contours are created at values selected by FreeMat. To provide our own set of contour values (asymmetrically about zero in this case), we supply them as

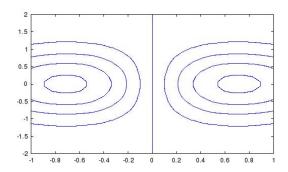
```
--> contour(x,y,z,[-.4,0.,3])
```

which is here



Also be default, contour uses the current color map and clim limits to determine the coloring of the contours. Here, we override the color spec so that we have all black contour

Warning: Newly defined variable nargin shadows a function of the same name. Use clear nargin to recove which is here



23.13 CONTOUR3 3D Contour Plot Function

23.13.1 Usage

This command generates contour plots where the lines are plotted in 3D. The syntax for its use is identical to the contour function. Please see its help for details.

23.13.2 Example

Here is a simple example of a 3D contour plot.

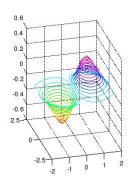
```
--> [x,y] = meshgrid([-2:.25:2]);
--> z=x.*exp(-x.^2-y.^2);
--> contour3(x,y,z,30);
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac

```
--> axis square;
--> view(-15,25)
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim

The resulting plot



23.14 COPPER Copper Colormap

23.14.1 Usage

Returns a copper colormap. The syntax for its use is

```
y = copper
```

23.14.2 Example

Here is an example of an image displayed with the copper colormap

```
--> x = linspace(-1,1,512)'*ones(1,512);

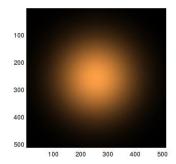
--> y = x';

--> Z = exp(-(x.^2+y.^2)/0.3);

--> image(Z);

--> colormap(copper);
```

which results in the following image



23.15 COPY Copy Figure Window

23.15.1 Usage

Copies the currently active figure window to the clipboard. The syntax for its use is:

сору

The resulting figure is copied as a bitmap to the clipboard, and can then be pasted into any suitable application.

23.16 COUNTOUR Contour Object Properties

23.16.1 Usage

Below is a summary of the properties for a line series.

- \bullet contourmatrix array the matrix containing contour data for the plot. This is a 2 x N matrix containing x and y coordinates for points on the contours. In addition, each contour line starts with a column containing the number of points and the contour value.
- displayname string The name of this line series as it appears in a legend.
- floating {'on', 'off'} set to on to have floating (3D) contours
- levellist vector a vector of Z-values for the contours
- levellistmode {'auto', 'manual'} set to auto for automatic selection of Z-values of the contours.
- linecolor color of the contour lines.
- linestyle {'-', '--', ':', '-.', 'none'} the line style to draw the contour in.
- linewidth scalar the width of the lines
- parent handle The axis that contains this object

- tag string A string that can be used to tag the object.
- type string Returns the string 'contour'.
- userdata array Available to store any variable you want in the handle object.
- visible {'on', 'off'} Controls visibility of the the line.
- xdata matrix Contains the x coordinates of the surface on which the zdata is defined. This can either be a monotonic vector of the same number of columns as zdata, or a 2D matrix that is the same size as zdata.
- xdatamode {'auto', 'manual'} When set to 'auto' FreeMat will autogenerate the x coordinates for the contours. These values will be 1,.., N where N is the number of columns of zdata.
- ydata matrix Contains the y coordinates of the surface on which the zdata is defined. This can either be a monotonic vector of the same number of rows as zdata or a 2D matrix that is the same size as zdata.
- ydatamode {'auto', 'manual'} When set to 'auto' FreeMat will autogenerate the y coordinates for the contour data.
- zdata matrix The matrix of z values that are to be contoured.

23.17 DRAWNOW Flush the Event Queue

23.17.1 Usage

The drawnow function can be used to process the events in the event queue of the FreeMat application. The syntax for its use is

drawnow

Now that FreeMat is threaded, you do not generally need to call this function, but it is provided for compatibility.

23.18 FIGLOWER Lower a Figure Window

23.18.1 Usage

Lowers a figure window indicated by the figure number. The syntax for its use is

figlower(fignum)

where fignum is the number of the figure to lower. The figure will be lowerd to the bottom of the GUI stack (meaning that it we be behind other windows). Note that this function does not cause fignum to become the current figure, you must use the figure command for that. Similarly, if fignum is the current figure, it will remain the current figure (even though the figure is now behind others).

23.19 FIGRAISE Raise a Figure Window

23.19.1 Usage

Raises a figure window indicated by the figure number. The syntax for its use is

figraise(fignum)

where fignum is the number of the figure to raise. The figure will be raised to the top of the GUI stack (meaning that it we be visible). Note that this function does not cause fignum to become the current figure, you must use the figure command for that.

23.20 FIGURE Figure Window Select and Create Function

23.20.1 Usage

Changes the active figure window to the specified figure number. The general syntax for its use is

figure(number)

where number is the figure number to use. If the figure window corresponding to number does not already exist, a new window with this number is created. If it does exist then it is brought to the forefront and made active. You can use gcf to obtain the number of the current figure.

Note that the figure number is also the handle for the figure. While for most graphical objects (e.g., axes, lines, images), the handles are large integers, for figures, the handle is the same as the figure number. This means that the figure number can be passed to set and get to modify the properties of the current figure, (e.g., the colormap). So, for figure 3, for example, you can use get(3,'colormap') to retrieve the colormap for the current figure.

23.21 FIGUREPROPERTIES Figure Object Properties

23.21.1 Usage

Below is a summary of the properties for the axis.

- alphamap vector Contains the alpha (transparency) map for the figure. If this is set to a scalar, then all values are mapped to the same transparency. It defaults to 1, which is all values being fully opaque. If you set this to a vector, the values of graphics objects will be mapped to different transparency values, based on the setting of their alphadatamapping property.
- color colorspec The background color of the figure (defaults to a gray [0.6,0.6,0.6]). During printing, this color is set to white, and then is restored.
- colormap color vector an N x 3 matrix of RGB values that specifies the colormap for the figure. Defaults to an HSV map.
- children handle vector the handles for objects that are children of this figure. These should be axis objects.

- currentaxes handle the handle for the current axes. Also returned by gca.
- doublebuffer Not used.
- parent Not used.
- position Not used.
- type string returns the string 'figure'.
- userdata array arbitrary array you can use to store data associated with the figure.
- nextplot {'add', 'replace', 'replacechildren'} If set to 'add' then additional axes are added to the list of children for the current figure. If set to 'replace', then a new axis replaces all of the existing children.
- figsize two vector the size of the figure window in pixels (width x height).
- renderer {'painters', 'opengl'} When set to 'painters' drawing is based on the Qt drawing methods (which can handle flat shading of surfaces with transparency). If you set the renderer to 'opengl' then OpenGL is used for rendering. Support for OpenGL is currently in the alpha stage, and FreeMat does not enable it automatically. You can set the renderer mode to 'opengl' manually to experiment. Also, OpenGL figures cannot be printed yet.

23.22 GCA Get Current Axis

23.22.1 Usage

Returns the handle for the current axis. The syntax for its use is

```
handle = gca
```

where handle is the handle of the active axis. All object creation functions will be children of this axis.

23.23 GCF Get Current Figure

23.23.1 Usage

Returns the figure number for the current figure (which is also its handle, and can be used to set properties of the current figure using set). The syntax for its use is

```
figure_number = gcf
```

where figure_number is the number of the active figure (also the handle of the figure).

Note that figures have handles, just like axes, images, plots, etc. However the handles for figures match the figure number (while handles for other graphics objects tend to be large, somewhat arbitrary integers). So, to retrieve the colormap of the current figure, you could use get(gcf,'colormap'), or to obtain the colormap for figure 3, use get(3,'colormap').

23.24 GET Get Object Property

23.24.1 Usage

This function allows you to retrieve the value associated with a property. The syntax for its use is

```
value = get(handle,property)
```

where property is a string containing the name of the property, and value is the value for that property. The type of the variable value depends on the property being set. See the help for the properties to see what values you can set.

23.25 GLSHOW Show a GL Assembly in a GL Window

23.25.1 Usage

Shows a GL Assembly in a GL Window. The syntax for its use is

```
glshow(name,scale)
```

which shows the glassembly named name in a new GL window, with the scale set to scale. Roughly speaking scale should represent the radial size of the object that you want to see in the window.

23.26 GRAY Gray Colormap

23.26.1 Usage

Returns a gray colormap. The syntax for its use is

```
y = gray
```

23.26.2 Example

Here is an example of an image displayed with the gray colormap

```
--> x = linspace(-1,1,512)'*ones(1,512);

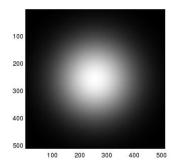
--> y = x';

--> Z = exp(-(x.^2+y.^2)/0.3);

--> image(Z);

--> colormap(gray);
```

which results in the following image



23.27 GRID Plot Grid Toggle Function

23.27.1 Usage

Toggles the drawing of grid lines on the currently active plot. The general syntax for its use is

```
grid(state)
```

where state is either

```
grid('on')
```

to activate the grid lines, or

```
grid('off')
```

to deactivate the grid lines. If you specify no argument then grid toggles the state of the grid:

```
grid
```

You can also specify a particular axis to the grid command

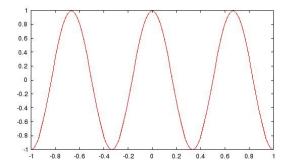
```
grid(handle,...)
```

where handle is the handle for a particular axis.

23.27.2 Example

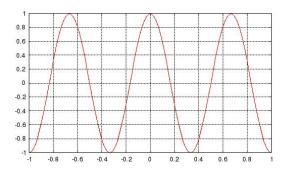
Here is a simple plot without grid lines.

```
--> x = linspace(-1,1);
--> y = cos(3*pi*x);
--> plot(x,y,'r-');
```



Next, we activate the grid lines.





23.28 HCONTOUR Create a contour object

23.28.1 Usage

Creates a contour object and parents it to the current axis. The syntax for its use is

handle = hcontour(property, value, property, value, ...)

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current axis.

23.29 HIMAGE Create a image object

23.29.1 Usage

Creates a image object and parents it to the current axis. The syntax for its use is

handle = himage(property, value, property, value, ...)

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current axis.

23.30 HIST Histogram Function

23.30.1 Usage

```
n=hist (y)
n=hist (y,x)
n=hist (y,x,norm)
```

Produce histogram counts or plots.

With one vector input argument, plot a histogram of the values with 10 bins. The range of the histogram bins is determined by the range of the data.

Given a second scalar argument, use that as the number of bins.

Given a second vector argument, use that as the centers of the bins, with the width of the bins determined from the adjacent values in the vector.

If third argument is provided, the histogram is normalised such that the sum of the bars is equal to norm.

Extreme values are lumped in the first and last bins.

23.31 HLINE Create a line object

23.31.1 Usage

Creates a line object and parents it to the current axis. The syntax for its use is

```
handle = hline(property, value, property, value, ...)
```

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current axis.

23.32 HOLD Plot Hold Toggle Function

23.32.1 Usage

Toggles the hold state on the currently active plot. The general syntax for its use is

```
hold(state)
```

where state is either

```
hold('on')
```

to turn hold on, or

```
hold('off')
```

to turn hold off. If you specify no argument then hold toggles the state of the hold:

hold

You can also specify a particular axis to the hold command

```
hold(handle,...)
```

where handle is the handle for a particular axis.

23.32.2 Function Internals

The hold function allows one to construct a plot sequence incrementally, instead of issuing all of the plots simultaneously using the plot command.

23.32.3 Example

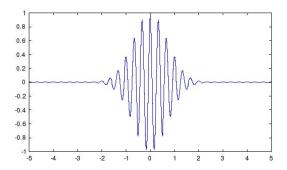
Here is an example of using both the hold command and the multiple-argument plot command to construct a plot composed of three sets of data. The first is a plot of a modulated Gaussian.

```
--> x = linspace(-5,5,500);

--> t = exp(-x.^2);

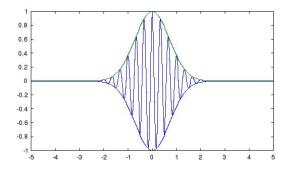
--> y = t.*cos(2*pi*x*3);

--> plot(x,y);
```



We now turn the hold state to 'on', and add another plot sequence, this time composed of the top and bottom envelopes of the modulated Gaussian. We add the two envelopes simultaneously using a single plot command. The fact that hold is 'on' means that these two envelopes are added to (instead of replace) the current contents of the plot.

```
--> plot(x,y);
--> hold on
--> plot(x,t,'g-',x,-t,'b-')
```



23.33 HPATCH Create a patch object

23.33.1 Usage

Creates a patch object and parents it to the current axis. The syntax for its use is

```
handle = hpatch(property, value, property, value, ...)
```

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current axis.

23.34 HPOINT Get Point From Window

23.34.1 Usage

This function waits for the user to click on the current figure window, and then returns the coordinates of that click. The generic syntax for its use is

[x,y] = hpoint

23.35 HRAWPLOT Generate a Raw Plot File

23.35.1 Usage

This function takes a sequence of commands, and generates a raw plot (to a file) that renders the commands. It is a useful tool for creating high quality fully customized PDF plots from within FreeMat scripts that are portable. The syntax for its use

```
hrawplot(filename,commands)
```

where filename is the name of the file to plot to, and commands is a cell array of strings. Each entry in the cell array contains a string with a command text. The commands describe a simple mini-language for describing plots. The complete dictionary of commands is given

- LINE x1 y1 x2 y2 draw a line
- FONT name size select a font of the given name and size
- TEXT x1 y1 string draw the given text string at the given location
- STYLE style select line style ('solid' or 'dotted')
- PAGE force a new page
- ullet SIZE x1 y1 Set the page mapping

23.36 HSURFACE Create a surface object

23.36.1 Usage

Creates a surface object and parents it to the current axis. The syntax for its use is

```
handle = hsurface(property, value, property, value, ...)
```

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current axis.

23.37 HTEXT Create a text object

23.37.1 Usage

Creates a text object and parents it to the current axis. The syntax for its use is

```
handle = htext(property, value, property, value, ...)
```

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current axis.

23.38 HTEXTBITMAP Get Text Rendered as a Bitmap

23.38.1 Usage

This function takes a fontname, a size, and a text string and returns a bitmap containing the text. The generic syntax for its use is

```
bitmap = htextbitmap(fontname, size, text)
```

where the output bitmap contains the text rendered into a matrix.

23.39 IMAGE Image Display Function

23.39.1 Usage

The image command has the following general syntax

```
handle = image(x,y,C,properties...)
```

where x is a two vector containing the x coordinates of the first and last pixels along a column, and y is a two vector containing the y coordinates of the first and last pixels along a row. The matrix C constitutes the image data. It must either be a scalar matrix, in which case the image is colormapped using the colormap for the current figure. If the matrix is M x N x 3, then C is intepreted as RGB data, and the image is not colormapped. The properties argument is a set of property/value pairs that affect the final image. You can also omit the x and y,

```
handle = image(C, properties...)
```

in which case they default to x = [1,size(C,2)] and y = [1,size(C,1)]. Finally, you can use the image function with only formal arguments

```
handle = image(properties...)

To support legacy FreeMat code, you can also use the following form of image image(C, zoomfactor)
```

which is equivalent to image(C) with the axes removed so that the image takes up the full figure window, and the size of the figure window adjusted to achieve the desired zoom factor using the zoom command.

23.39.2 Example

In this example, we create an image that is 512×512 pixels square, and set the background to a noise pattern. We set the central 128×256 pixels to be white.

```
--> x = rand(512);

--> x((-64:63)+256,(-128:127)+256) = 1.0;

--> figure

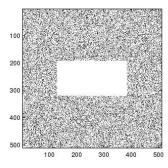
ans =

1

--> image(x)

--> colormap(gray)
```

The resulting image looks like:



Here is an example of an RGB image

```
--> t = linspace(0,1);

--> red = t'*t;

--> green = t'*(t.^2);

--> blue = t'*(0*t+1);

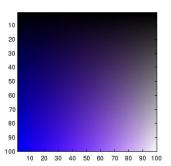
--> A(:,:,1) = red;

--> A(:,:,2) = green;

--> A(:,:,3) = blue;

--> image(A);
```

The resulting image looks like:



23.40 IMAGEPROPERTIES Image Object Properties

23.40.1 Usage

Below is a summary of the properties for the axis.

- alphadata vector This is a vector that should contain as many elements as the image data itself cdata, or a single scalar. For a single scalar, all values of the image take on the same transparency. Otherwise, the transparency of each pixel is determined by the corresponding value from the alphadata vector.
- alphadatamapping {'scaled', 'direct', 'none'} For none mode (the default), no transparency is applied to the data. For direct mode, the vector alphadata contains values between @[0,M-1]— where M is the length of the alpha map stored in the figure. For scaled mode, the alim vector for the figure is used to linearly rescale the alpha data prior to lookup in the alpha map.
- cdata array This is either a M x N array or an M x N x 3 array. If the data is M x N the image is a scalar image (indexed mode), where the color associated with each image pixel is computed using the colormap and the cdatamapping mode. If the data is M x N x 3 the image is assumed to be in RGB mode, and the colorpanes are taken directly from cdata (the colormap is ignored). Note that in this case, the data values must be between @[0,1]— for each color channel and each pixel.
- cdatamapping {'scaled', 'direct'} For scaled (the default), the pixel values are scaled using the clim vector for the figure prior to looking up in the colormap. For direct mode, the pixel values must be in the range [0,N-1 where N is the number of colors in the colormap if the data is integer type. For floating point data types, values must be in the range [1,N].
- children Not used.
- parent handle The axis containing the image.
- tag string You can set this to any string you want.

- type string Set to the string 'image'.
- xdata two vector contains the x coordinates of the first and last column (respectively). Defaults to [1,C] where C is the number of columns in the image.
- ydata two vector contains the y coordinates of the first and last row (respectively). Defaults to [1,R] where R is the number of rows in the image.
- userdata array Available to store any variable you want in the handle object.
- visible {'on', 'off'} Controls whether the image is visible or not.

23.41 IMAGESC Image Display Function

23.41.1 Usage

The imagesc command has the following general syntax

```
handle = imagesc(x,y,C,clim)
```

where x is a two vector containing the x coordinates of the first and last pixels along a column, and y is a two vector containing the y coordinates of the first and last pixels along a row. The matrix C constitutes the image data. It must either be a scalar matrix, in which case the image is colormapped using the colormap for the current figure. If the matrix is $M \times N \times 3$, then C is intepreted as RGB data, and the image is not colormapped. The clim argument is a pairs [low high] that specifies scaling. You can also omit the x and y,

```
handle = imagesc(C, clim)
```

in which case they default to x = [1,size(C,2)] and y = [1,size(C,1)]. Finally, you can use the image function with only formal arguments

```
handle = imagesc(properties...)
```

23.41.2 Example

In this example, we create an image that is 512×512 pixels square, and set the background to a noise pattern. We set the central 128×256 pixels to be white.

```
--> x = rand(512);

--> x((-64:63)+256,(-128:127)+256) = 1.0;

--> figure

ans =

1

--> imagesc(x,[0 .5])
```

Warning: Newly defined variable nargin shadows a function of the same name. Use clear name --> colormap(gray)

23.42 IS2DVIEW Test Axes For 2D View

23.42.1 Usage

This function returns true if the current axes are in a 2-D view, and false otherwise. The generic syntax for its use is

```
y = is2dview(x)
```

where x is the handle of an axes object.

23.43 ISHOLD Test Hold Status

23.43.1 Usage

Returns the state of the hold flag on the currently active plot. The general syntax for its use is ishold

and it returns a logical 1 if hold is on, and a logical 0 otherwise.

23.44 LEGEND Add Legent to Plot

23.44.1 Usage

This command adds a legend to the current plot. Currently, the following forms of the legend command are supported. The first form creates a legend with the given labels for the data series:

```
legend('label1','label2',...)
```

where 'label1' is the text label associated with data plot 1 and so on. You can also use the legend command to control the appearance of the legend in the current plot. To remove the legend from the current plot, use

```
legend('off')
```

To hide the legend for the current plot (but do not remove it)

```
legend('hide')
```

And to show the legend that has been hidden, use

```
legend('show')
```

You can also toggle the display of the box surrounding the legend. Use

```
legend('boxoff')
```

or

```
legend('boxon')
```

to turn the legend box off or on, respectively. To toggle the visible state of the current legend, use

```
legend('toggle')
```

Specifying no arguments at all (apart from an optional location argument as specified below) results in the legend being rebuilt. This form is useful for picking up font changes or relocating the legend.

legend

By default, the legend command places the new legend in the upper right corner of the current plot. To change this behavior, use the 'location' specifier (must be the last two options to the command)

```
legend(...,'location',option)
```

where option takes on the following possible values

- north,N top center of plot
- south,S bottom center of plot
- east,E middle right of plot
- west,W middle left of plot
- northeast, NE top right of plot (default behavior)
- northwest,NW top left of plot
- southeast, SE bottom right of plot
- southwest,SW bottom left of plot

This implementation of legend is incomplete relative to the MATLAB API. The functionality will be improved in future versions of FreeMat.

23.45 LINE Line Display Function

23.45.1 Usage

The line command has the following general syntax

```
handle = line(x,y,z,properties...)
```

where...

23.46 LINEPROPERTIES Line Series Object Properties

23.46.1 Usage

Below is a summary of the properties for a line series.

- color colorspec The color that is used to draw the line.
- children Not used.
- displayname The name of this line series as it appears in a legend.
- linestyle {'-', '--', ':', '-.', 'none'} The style of the line.
- linewidth scalar The width of the line.
- marker {'+','o','*','.','x','square','s','diamond','d','^','v','>','<'} The marker for data points on the line. Some of these are redundant, as 'square' 's' are synonyms, and 'diamond' and 'd' are also synonyms.
- markeredgecolor colorspec The color used to draw the marker. For some of the markers (circle, square, etc.) there are two colors used to draw the marker. This property controls the edge color (which for unfilled markers) is the primary color of the marker.
- markerfacecolor colorspec The color used to fill the marker. For some of the markers (circle, square, etc.) there are two colors used to fill the marker.
- markersize scalar Control the size of the marker. Defaults to 6, which is effectively the radius (in pixels) of the markers.
- parent handle The axis that contains this object.
- tag string A string that can be used to tag the object.
- type string Returns the string 'line'.
- visible {'on', 'off'} Controls visibility of the line.
- xdata vector Vector of x coordinates of points on the line. Must be the same size as the ydata and zdata vectors.
- ydata vector Vector of y coordinates of points on the line. Must be the same size as the xdata and zdata vectors.
- zdata vector Vector of z coordinates of points on the line. Must be the same size as the xdata and ydata vectors.
- xdatamode {'auto', 'manual'} When set to 'auto' FreeMat will autogenerate the x coordinates for the points on the line. These values will be 1,.., N where N is the number of points in the line.
- userdata array Available to store any variable you want in the handle object.

23.47 LOGLOG Log-Log Plot Function

23.47.1 Usage

This command has the exact same syntax as the plot command:

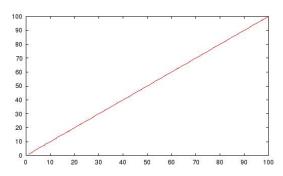
```
loglog(<data 1>,{linespec 1},<data 2>,{linespec 2}...,properties...)
```

in fact, it is a simple wrapper around plot that sets the x and y axis to have a logarithmic scale.

23.47.2 Example

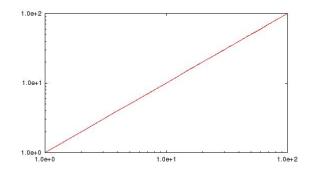
Here is an example of a doubly exponential signal plotted first on a linear plot:

```
--> x = linspace(1,100);
--> y = x;
--> plot(x,y,'r-');
```



and now on a log-log plot

```
--> loglog(x,y,'r-');
```



23.48 NEWPLOT Get Handle For Next Plot

23.48.1 Usage

Returns the handle for the next plot operation. The general syntax for its use is

```
h = newplot
```

This routine checks the nextplot properties of the current figure and axes to see if they are set to replace or not. If the figures nextplot property is set to replace, the current figure is cleared. If the axes nextplot property is set to replace then the axes are cleared for the next operation.

23.49 PATCH Patch Graphics Function

23.49.1 Usage

This routine is used to create a patch object that can be plotting 2D and 3D surfaces. A patch is a polygon defined by the xyz coordinates of its vertices and optionally by the color at the vertices. There are several forms for the patch function:

```
h = patch(X,Y,C,properties...)
h = patch(X,Y,Z,C,properties...)
h = patch(properties...)
h = patch(V)
```

Where X, Y and Z are matrices or vectors of x, y or z coordinates and C is a matrix or vector of color values (the colormap for the current fig is applied).

23.49.2 Example

Here we generate a surface specifying all four components.

```
--> x = [ 0 1 0 1];

--> y = [ 0 0 1 1];

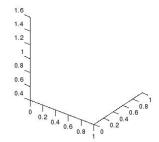
--> c = [ 1 1 1 ];

--> patch(x,y,c)

--> axis equal

--> view(3)
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac



23.50 PCOLOR Pseudocolor Plot

23.50.1 Usage

This routine is used to create a pseudocolor plot of the data. A pseudocolor plot is a essentially a surface plot seen from above. There are two forms for the pcolor command:

```
pcolor(C)
```

which uses a rectangular grid. Alternately, you can specify X,Y matrices or vectors.

```
pcolor(X,Y,C)
```

23.51 PLOT Plot Function

23.51.1 Usage

This is the basic plot command for FreeMat. The general syntax for its use is

```
plot(<data 1>,{linespec 1},<data 2>,{linespec 2}...,properties...)
```

where the <data> arguments can have various forms, and the linespec arguments are optional. We start with the <data> term, which can take on one of multiple forms:

- Vector Matrix Case In this case the argument data is a pair of variables. A set of x coordinates in a numeric vector, and a set of y coordinates in the columns of the second, numeric matrix.
 x must have as many elements as y has columns (unless y is a vector, in which case only the number of elements must match). Each column of y is plotted sequentially against the common vector x.
- Unpaired Matrix Case In this case the argument data is a single numeric matrix y that constitutes the y-values of the plot. An x vector is synthesized as x = 1:length(y), and each column of y is plotted sequentially against this common x axis.
- Complex Matrix Case Here the argument data is a complex matrix, in which case, the real part of each column is plotted against the imaginary part of each column. All columns receive the same line styles.

Multiple data arguments in a single plot command are treated as a *sequence*, meaning that all of the plots are overlapped on the same set of axes. The linespec is a string used to change the characteristics of the line. In general, the linespec is composed of three optional parts, the colorspec, the symbolspec and the linestylespec in any order. Each of these specifications is a single character that determines the corresponding characteristic. First, the colorspec:

- 'b' Color Blue
- 'g' Color Green
- 'r' Color Red
- 'c' Color Cyan

- 'm' Color Magenta
- 'y' Color Yellow
- 'k' Color Black

The symbolspec specifies the (optional) symbol to be drawn at each data point:

- '.' Dot symbol
- 'o' Circle symbol
- 'x' Times symbol
- '+' Plus symbol
- '*' Asterisk symbol
- 's' Square symbol
- 'd' Diamond symbol
- 'v' Downward-pointing triangle symbol
- '^' Upward-pointing triangle symbol
- '<' Left-pointing triangle symbol
- '>' Right-pointing triangle symbol

The linestylespec specifies the (optional) line style to use for each data series:

- '-' Solid line style
- ':' Dotted line style
- '-.' Dot-Dash-Dot-Dash line style
- \bullet '--' Dashed line style

For sequences of plots, the linespec is recycled with color order determined by the properties of the current axes. You can also use the properties argument to specify handle properties that will be inherited by all of the plots generated during this event. Finally, you can also specify the handle for the axes that are the target of the plot operation.

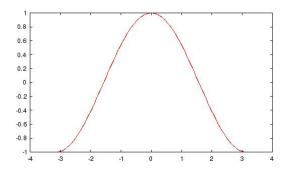
```
handle = plot(handle,...)
```

23.51.2 Example

The most common use of the plot command probably involves the vector-matrix paired case. Here, we generate a simple cosine, and plot it using a red line, with no symbols (i.e., a linespec of 'r-').

```
--> x = linspace(-pi,pi);
--> y = cos(x);
--> plot(x,y,'r-');
```

which results in the following plot.



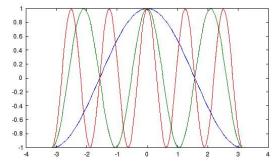
Next, we plot multiple sinusoids (at different frequencies). First, we construct a matrix, in which each column corresponds to a different sinusoid, and then plot them all at once.

```
--> x = linspace(-pi,pi);

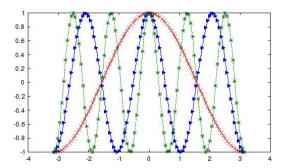
--> y = [cos(x(:)),cos(3*x(:)),cos(5*x(:))];

--> plot(x,y);
```

In this case, we do not specify a linespec, so that we cycle through the colors automatically (in the order listed in the previous section).



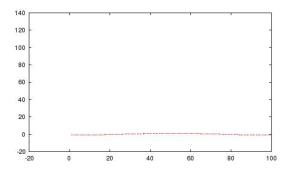
This time, we produce the same plot, but as we want to assign individual linespecs to each line, we use a sequence of arguments in a single plot command, which has the effect of plotting all of the data sets on a common axis, but which allows us to control the linespec of each plot. In the following example, the first line (harmonic) has red, solid lines with times symbols marking the data points, the second line (third harmonic) has blue, solid lines with right-pointing triangle symbols, and the third line (fifth harmonic) has green, dotted lines with asterisk symbols.



The second most frequently used case is the unpaired matrix case. Here, we need to provide only one data component, which will be automatically plotted against a vector of natural number of the appropriate length. Here, we use a plot sequence to change the style of each line to be dotted, dot-dashed, and dashed.

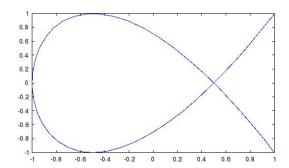
```
--> plot(y(:,1),'r:',y(:,2),'b;',y(:,3),'g|');
```

Note in the resulting plot that the x-axis no longer runs from [-pi,pi], but instead runs from [1,100].



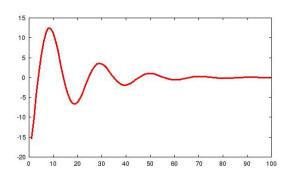
The final case is for complex matrices. For complex arguments, the real part is plotted against the imaginary part. Hence, we can generate a 2-dimensional plot from a vector as follows.

```
--> y = cos(2*x) + i * cos(3*x);
--> plot(y);
```



Here is an example of using the handle properties to influence the behavior of the generated lines.

```
--> t = linspace(-3,3);
--> plot(cos(5*t).*exp(-t),'r-','linewidth',3);
```



23.52 PLOT3 Plot 3D Function

23.52.1 Usage

This is the 3D plot command. The general syntax for its use is

where X Y and Z are the coordinates of the points on the 3D line. Note that in general, all three should be vectors. If some or all of the quantities are matrices, then FreeMat will attempt to expand the vector arguments to the same size, and then generate multiple plots, one for each column of the matrices. The linespec is optional, see plot for details. You can specify properties for the generated line plots. You can also specify a handle as an axes to target

plot3(handle,...)

23.52.2 Example

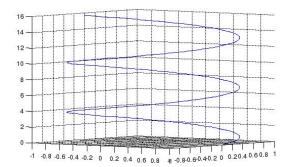
Here is a simple example of a 3D helix.

--> t = linspace(0,5*pi,200);

```
--> x = cos(t); y = sin(t); z = t;
--> plot3(x,y,z);
Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac --> view(3);
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac

Shown here



23.53 POINT Get Axis Position From Mouse Click

23.53.1 Usage

Returns information about the currently displayed image based on a use supplied mouse-click. The general syntax for its use is

The returned vector y has two elements:

$$t = [x, y]$$

where x,y are the coordinates in the current axes of the click. This function has changed since FreeMat 1.10. If the click is not inside the active area of any set of axes, a pair of NaNs are returned.

23.54 PRINT Print a Figure To A File

23.54.1 Usage

This function "prints" the currently active fig to a file. The generic syntax for its use is

```
print(filename)
```

or, alternately,

```
print filename
```

where filename is the (string) filename of the destined file. The current fig is then saved to the output file using a format that is determined by the extension of the filename. The exact output formats may vary on different platforms, but generally speaking, the following extensions should be supported cross-platform:

- jpg, jpeg JPEG file
- pdf Portable Document Format file
- png Portable Net Graphics file
- svg Scalable Vector Graphics file

Postscript (PS, EPS) is supported on non-Mac-OSX Unix only. Note that only the fig is printed, not the window displaying the fig. If you want something like that (essentially a window-capture) use a seperate utility or your operating system's built in screen capture ability.

23.54.2 Example

Here is a simple example of how the figures in this manual are generated.

```
--> x = linspace(-1,1);

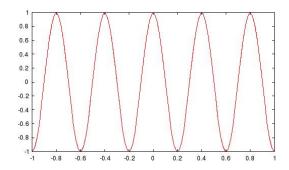
--> y = cos(5*pi*x);

--> plot(x,y,'r-');

--> print('printfig1.jpg')

--> print('printfig1.png')
```

which creates two plots printfig1.png, which is a Portable Net Graphics file, and printfig1.jpg which is a JPEG file.



23.55 PVALID Validate Property Name

23.55.1 Usage

This function checks to see if the given string is a valid property name for an object of the given type. The syntax for its use is

```
b = pvalid(type,propertyname)
```

where string is a string that contains the name of a valid graphics object type, and propertyname is a string that contains the name of the property to test for.

23.55.2 Example

Here we test for some properties on an axes object.

```
--> pvalid('axes','type')

ans =
1
--> pvalid('axes','children')

ans =
1
--> pvalid('axes','foobar')

ans =
0
```

23.56 SEMILOGX Semilog X Axis Plot Function

23.56.1 Usage

This command has the exact same syntax as the plot command:

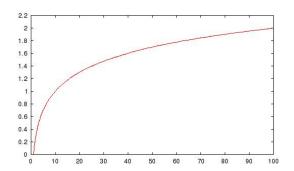
```
semilogx(<data 1>,{linespec 1},<data 2>,{linespec 2}...,properties...)
```

in fact, it is a simple wrapper around plot that sets the x axis to have a logarithmic scale.

23.56.2 Example

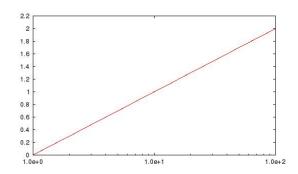
Here is an example of an exponential signal plotted first on a linear plot:

```
--> y = linspace(0,2);
--> x = (10).^y;
--> plot(x,y,'r-');
```



and now with a logarithmic x axis

--> semilogx(x,y,'r-');



23.57 SEMILOGY Semilog Y Axis Plot Function

23.57.1 Usage

This command has the exact same syntax as the plot command:

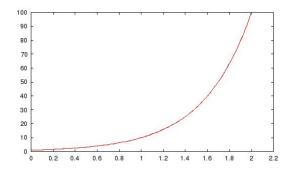
```
semilogy(<data 1>,{linespec 1},<data 2>,{linespec 2}...,properties...)
```

in fact, it is a simple wrapper around plot that sets the y axis to have a logarithmic scale.

23.57.2 Example

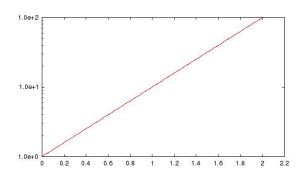
Here is an example of an exponential signal plotted first on a linear plot:

```
--> x = linspace(0,2);
--> y = 10.0.^x;
--> plot(x,y,'r-');
```



and now with a logarithmic y axis

--> semilogy(x,y,'r-');



23.58 SET Set Object Property

23.58.1 Usage

This function allows you to change the value associated with a property. The syntax for its use is set(handle,property,value,property,value,...)

where property is a string containing the name of the property, and value is the value for that property. The type of the variable value depends on the property being set. See the help for the properties to see what values you can set.

23.59 SIZEFIG Set Size of Figure

23.59.1 Usage

The **sizefig** function changes the size of the currently selected fig window. The general syntax for its use is

sizefig(width,height)

where width and height are the dimensions of the fig window.

23.60 SUBPLOT Subplot Function

23.60.1 Usage

This function divides the current figure into a 2-dimensional grid, each of which can contain a plot of some kind. The function has a number of syntaxes. The first version

```
subplot(row,col,num)
```

which either activates subplot number num, or sets up a subplot grid of size row x col, and then activates num. You can also set up subplots that cover multiple grid elements

```
subplot(row,col,[vec])
```

where vec is a set of indexes covered by the new subplot. Finally, as a shortcut, you can specify a string with three components

```
subplot('mnp')
```

or using the alternate notation

```
subplot mnp
```

where m is the number of rows, n is the number of columns and p is the index. You can also specify the location of the subplot explicitly using the syntax

```
subplot('position',[left bottom width height])
```

23.60.2 Example

Here is the use of subplot to set up a 2 x 2 grid of plots

```
--> t = linspace(-pi,pi);

--> subplot(2,2,1)

--> plot(t,cos(t).*exp(-2*t));

--> subplot(2,2,2);

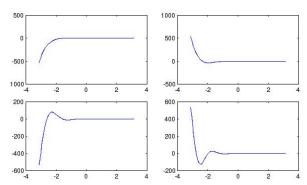
--> plot(t,cos(t*2).*exp(-2*t));

--> subplot(2,2,3);

--> plot(t,cos(t*3).*exp(-2*t));

--> subplot(2,2,4);

--> plot(t,cos(t*4).*exp(-2*t));
```



Here we use the second form of subplot to generate one subplot that is twice as large.

```
--> t = linspace(-pi,pi);

--> subplot(2,2,[1,2])

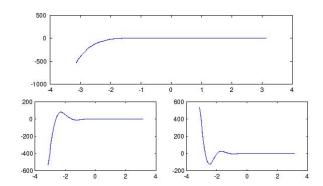
--> plot(t,cos(t).*exp(-2*t));

--> subplot(2,2,3);

--> plot(t,cos(t*3).*exp(-2*t));

--> subplot(2,2,4);

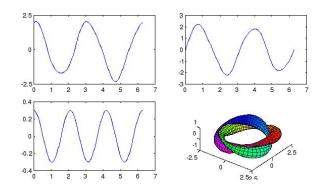
--> plot(t,cos(t*4).*exp(-2*t));
```



Note that the subplots can contain any handle graphics objects, not only simple plots.

```
--> t=0:(2*pi/100):(2*pi);
--> x=cos(t*2).*(2+sin(t*3)*.3);
--> y=sin(t*2).*(2+sin(t*3)*.3);
--> z=cos(t*3)*.3;
--> subplot(2,2,1)
--> plot(t,x);
--> subplot(2,2,2);
--> plot(t,y);
--> subplot(2,2,3);
--> plot(t,z);
--> subplot(2,2,4);
--> tubeplot(x,y,z,0.14*sin(t*5)+.29,t,10)
--> axis equal
--> view(3)
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac



23.61 SURF Surface Plot Function

23.61.1 Usage

This routine is used to create a surface plot of data. A surface plot is a 3D surface defined by the xyz coordinates of its vertices and optionally by the color at the vertices. The most general syntax for the surf function is

```
h = surf(X,Y,Z,C,properties...)
```

Where X is a matrix or vector of x coordinates, Y is a matrix or vector of y coordinates, Z is a 2D matrix of coordinates, and Z is a 2D matrix of color values (the colormap for the current fig is applied). In general, Z and Z should be the same size as Z, but FreeMat will expand vectors to match the matrix if possible. If you want the color of the surface to be defined by the height of the surface, you can omit Z

```
h = surf(X,Y,Z,properties...)
```

in which case C=Z. You can also eliminate the X and Y matrices in the specification

```
h = surf(Z,properties)
```

in which case they are set to 1:size(Z,2) and 1:size(Y,2) respectively. You can also specify a handle as the target of the surf command via

```
h = surf(handle,...)
```

23.61.2 Example

Here we generate a surface specifying all four components.

```
--> x = repmat(linspace(-1,1),[100,1]);

--> y = x';

--> r = x.^2+y.^2;

--> z = exp(-r*3).*cos(5*r);

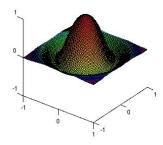
--> c = r;
```

```
--> surf(x,y,z,c)
```

--> axis equal

--> view(3)

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear ylim to recover ac



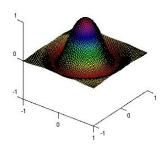
If we allow FreeMat to specify the color component, we see that the colorfield is the same as the height

--> surf(x,y,z)

--> axis equal

--> view(3)

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac



23.62 SURFACEPROPERTIES Surface Object Properties

23.62.1 Usage

Below is a summary of the properties for the axis.

- alphadata vector This is a vector that should contain as many elements as the surface data itself cdata, or a single scalar. For a single scalar, all values of the surface take on the same transparency. Otherwise, the transparency of each pixel is determined by the corresponding value from the alphadata vector.
- alphadatamapping {'scaled', 'direct', 'none'} For none mode (the default), no transparency is applied to the data. For direct mode, the vector alphadata contains values between @[0,M-1]— where M is the length of the alpha map stored in the figure. For scaled mode, the alim vector for the figure is used to linearly rescale the alpha data prior to lookup in the alpha map.
- ambientstrength Not used.
- backfacelighting Not used.
- cdata array This is either a M x N array or an M x N x 3 array. If the data is M x N the surface is a scalar surface (indexed mode), where the color associated with each surface pixel is computed using the colormap and the cdatamapping mode. If the data is M x N x 3 the surface is assumed to be in RGB mode, and the colorpanes are taken directly from cdata (the colormap is ignored). Note that in this case, the data values must be between @[0,1]— for each color channel and each point on the surface.
- cdatamapping {'scaled', 'direct'} For scaled (the default), the pixel values are scaled using the clim vector for the figure prior to looking up in the colormap. For direct mode, the pixel values must be in the range [0, N-1 where N is the number of colors in the colormap.
- children Not used.
- diffusestrength Not used.
- edgealpha {'flat','interp','scalar'} Controls how the transparency is mapped for the edges of the surface.
- edgecolor {'flat', 'interp', 'none', colorspec} Specifies how the edges are colored. For 'flat' the edges are flat colored, meaning that the line segments that make up the edges are not shaded. The color for the line is determined by the first edge point it is connected to.
- edgelighting Not used.
- facealpha {'flat', 'interp', 'texturemap', scalar} Controls how the transparency of the faces of the surface are controlled. For flat shading, the faces are constant transparency. For interp mode, the faces are smoothly transparently mapped. If set to a scalar, all faces have the same transparency.
- facecolor {'none', 'flat', 'interp', colorspec} Controls how the faces are colored. For 'none' the faces are uncolored, and the surface appears as a mesh without hidden lines removed. For 'flat' the surface faces have a constant color. For 'interp' smooth shading is applied to the surface. And if a colorspec is provided, then the faces all have the same color.
- facelighting Not used.

- linestyle {'-','--',':','-.','none'} The style of the line used to draw the edges.
- linewidth scalar The width of the line used to draw the edges.
- marker {'+','o','*','.','x','square','s','diamond','d','^','v','>','<'} The marker for data points on the line. Some of these are redundant, as 'square' 's' are synonyms, and 'diamond' and 'd' are also synonyms.
- markeredgecolor colorspec The color used to draw the marker. For some of the markers (circle, square, etc.) there are two colors used to draw the marker. This property controls the edge color (which for unfilled markers) is the primary color of the marker.
- markerfacecolor colorspec The color used to fill the marker. For some of the markers (circle, square, etc.) there are two colors used to fill the marker.
- markersize scalar Control the size of the marker. Defaults to 6, which is effectively the radius (in pixels) of the markers.
- meshstyle {'both', 'rows', 'cols} This property controls how the mesh is drawn for the surface. For rows and cols modes, only one set of edges is drawn.
- normalmode Not used.
- parent handle The axis containing the surface.
- specularcolorreflectance Not used.
- specularexponent Not used.
- specularstrength Not used.
- tag string You can set this to any string you want.
- type string Set to the string 'surface'.
- userdata array Available to store any variable you want in the handle object.
- vertexnormals Not used.
- xdata array Must be a numeric array of size M x N which contains the x location of each point in the defined surface. Must be the same size as ydata and zdata. Alternately, you can specify an array of size 1 x N in which case FreeMat replicates the vector to fill out an M x N matrix.
- xdatamode {'auto', 'manual'} When set to auto then FreeMat will automatically generate the x coordinates.
- ydata array Must be a numeric array of size M x N which contains the y location of each point in the defined surface. Must be the same size as xdata and zdata. Alternately, you can specify an array of size M x 1 in which case FreeMat replicates the vector to fill out an M x N matrix.

- ydatamode {'auto', 'manual'} When set to auto then FreeMat will automatically generate the y coordinates.
- zdata array Must be a numeric array of size M x N which contains the y location of each point in the defined surface. Must be the same size as xdata and ydata.
- visible {'on', 'off'} Controls whether the surface is visible or not.

23.63 SURFACEPROPERTIES Surface Object Properties

23.63.1 Usage

Below is a summary of the properties for the axis.

- alphadata vector This is a vector that should contain as many elements as the surface data itself cdata, or a single scalar. For a single scalar, all values of the surface take on the same transparency. Otherwise, the transparency of each pixel is determined by the corresponding value from the alphadata vector.
- alphadatamapping {'scaled', 'direct', 'none'} For none mode (the default), no transparency is applied to the data. For direct mode, the vector alphadata contains values between @[0,M-1]— where M is the length of the alpha map stored in the figure. For scaled mode, the alim vector for the figure is used to linearly rescale the alpha data prior to lookup in the alpha map.
- ambientstrength Not used.
- backfacelighting Not used.
- cdata array This is either a M x N array or an M x N x 3 array. If the data is M x N the surface is a scalar surface (indexed mode), where the color associated with each surface pixel is computed using the colormap and the cdatamapping mode. If the data is M x N x 3 the surface is assumed to be in RGB mode, and the colorpanes are taken directly from cdata (the colormap is ignored). Note that in this case, the data values must be between @[0,1]— for each color channel and each point on the surface.
- cdatamapping {'scaled', 'direct'} For scaled (the default), the pixel values are scaled using the clim vector for the figure prior to looking up in the colormap. For direct mode, the pixel values must be in the range [0, N-1 where N is the number of colors in the colormap.
- children Not used.
- diffusestrength Not used.
- edgealpha {'flat', 'interp', 'scalar'} Controls how the transparency is mapped for the edges of the surface.
- edgecolor {'flat', 'interp', 'none', colorspec} Specifies how the edges are colored. For 'flat' the edges are flat colored, meaning that the line segments that make up the edges are not shaded. The color for the line is determined by the first edge point it is connected to.

- edgelighting Not used.
- facealpha {'flat', 'interp', 'texturemap', scalar} Controls how the transparency of the faces of the surface are controlled. For flat shading, the faces are constant transparency. For interp mode, the faces are smoothly transparently mapped. If set to a scalar, all faces have the same transparency.
- facecolor {'none', 'flat', 'interp', colorspec} Controls how the faces are colored. For 'none' the faces are uncolored, and the surface appears as a mesh without hidden lines removed. For 'flat' the surface faces have a constant color. For 'interp' smooth shading is applied to the surface. And if a colorspec is provided, then the faces all have the same color.
- facelighting Not used.
- linestyle {'-', '--', ':', '-.', 'none'} The style of the line used to draw the edges.
- linewidth scalar The width of the line used to draw the edges.
- marker {'+','o','*','.','x','square','s','diamond','d','^','v','>','<'} The marker for data points on the line. Some of these are redundant, as 'square' 's' are synonyms, and 'diamond' and 'd' are also synonyms.
- markeredgecolor colorspec The color used to draw the marker. For some of the markers (circle, square, etc.) there are two colors used to draw the marker. This property controls the edge color (which for unfilled markers) is the primary color of the marker.
- markerfacecolor colorspec The color used to fill the marker. For some of the markers (circle, square, etc.) there are two colors used to fill the marker.
- markersize scalar Control the size of the marker. Defaults to 6, which is effectively the radius (in pixels) of the markers.
- meshstyle {'both', 'rows', 'cols} This property controls how the mesh is drawn for the surface. For rows and cols modes, only one set of edges is drawn.
- normalmode Not used.
- parent handle The axis containing the surface.
- specularcolorreflectance Not used.
- specularexponent Not used.
- specularstrength Not used.
- tag string You can set this to any string you want.
- type string Set to the string 'surface'.
- userdata array Available to store any variable you want in the handle object.
- vertexnormals Not used.

- xdata array Must be a numeric array of size M x N which contains the x location of each point in the defined surface. Must be the same size as ydata and zdata. Alternately, you can specify an array of size 1 x N in which case FreeMat replicates the vector to fill out an M x N matrix.
- xdatamode {'auto', 'manual'} When set to auto then FreeMat will automatically generate the x coordinates.
- ydata array Must be a numeric array of size M x N which contains the y location of each point in the defined surface. Must be the same size as xdata and zdata. Alternately, you can specify an array of size M x 1 in which case FreeMat replicates the vector to fill out an M x N matrix.
- ydatamode {'auto', 'manual'} When set to auto then FreeMat will automatically generate the y coordinates.
- zdata array Must be a numeric array of size M x N which contains the y location of each point in the defined surface. Must be the same size as xdata and ydata.
- visible {'on', 'off'} Controls whether the surface is visible or not.

23.64 TEXT Add Text Label to Plot

23.64.1 Usage

Adds a text label to the currently active plot. The general syntax for it is use is either

```
text(x,y,'label')
```

where x and y are both vectors of the same length, in which case the text 'label' is added to the current plot at each of the coordinates x(i), y(i) (using the current axis to map these to screen coordinates). The second form supplies a cell-array of strings as the second argument, and allows you to place many labels simultaneously

```
text(x,y,{'label1','label2',....})
```

where the number of elements in the cell array must match the size of vectors \mathbf{x} and \mathbf{y} . You can also specify properties for the labels via

```
handles = text(x,y,{labels},properties...)
```

23.64.2 Example

Here is an example of a few labels being added to a random plot:

```
--> plot(rand(1,4))
--> text([2,3],[0.5,0.5],{'hello','there'})
```

Warning: Newly defined variable i shadows a function of the same name. Use clear i to red In /home/basu/dev/branches/FreeMat4/src/toolbox/graph/text.m(text) at line 72

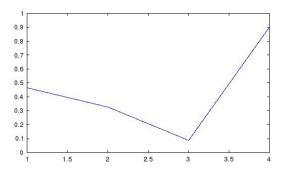
```
In scratch() at line 1
```

In base(base)

In base()

In global()

Error: Got error Expect a vector of length 3, got a vector of length 2 for property position



Here is the same example, but with larger labels:

```
--> plot(rand(1,4))
```

--> text([2,3],[0.5,0.5],{'hello','there'},'fontsize',20)

Warning: Newly defined variable i shadows a function of the same name. Use clear i to recover access t In /home/basu/dev/branches/FreeMat4/src/toolbox/graph/text.m(text) at line 72

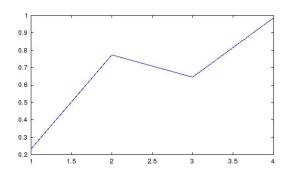
In scratch() at line 1

In base(base)

In base()

In global()

Error: Got error Expect a vector of length 3, got a vector of length 2 for property position



23.65 TEXTPROPERTIES Text Object Properties

23.65.1 Usage

Below is a summary of the properties for a text object.

• boundingbox - four vector - The size of the bounding box containing the text (in pixels). May contain negative values if the text is slanted.

- children Not used.
- string string The text contained in the label.
- extent Not used.
- horizontalalignment {'left', 'center', 'right'} Controls the alignment of the text relative to the specified position point.
- \bullet position three vector The position of the label in axis coordinates.
- rotation scalar The rotation angle (in degrees) of the label.
- units Not used.
- verticalalignment {'top', 'bottom', 'middle'} Controls the alignment fo the text relative to the specified position point in the vertical position.
- backgroundcolor colorspec The color used to fill in the background rectangle for the label. Normally this is none.
- edgecolor colorspec The color used to draw the bounding rectangle for the label. Normally this is none.
- linewidth scalar The width of the line used to draw the border.
- linestyle {'-', '--', ':', '-.', 'none'} The style of the line used to draw the border.
- margin scalar The amount of spacing to place around the text as padding when drawing the rectangle.
- fontangle {'normal', 'italic', 'oblique'} The angle of the fonts used for the labels.
- fontsize scalar The size of fonts used for the text.
- fontunits Not used.
- fontweight {'normal', 'bold', 'light', 'demi'} The weight of the font used for the label
- visible {'on', 'off'} Controls visibility of the the line.
- color colorspec The color of the text of the label.
- children Not used.
- parent The handle of the axis that owns this label.
- tag string A string that can be used to tag the object.
- type string Returns the string 'text'.
- userdata array Available to store any variable you want in the handle object.

23.66 TITLE Plot Title Function

23.66.1 Usage

This command adds a title to the plot. The general syntax for its use is

```
title('label')
or in the alternate form
title 'label'
or simply
title label
```

Here label is a string variable. You can also specify properties for the label, and a handle to serve as a target for the operation

```
title(handle, 'label', properties...)
```

23.66.2 Example

Here is an example of a simple plot with a title.

```
--> x = linspace(-1,1);

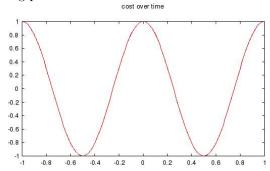
--> y = cos(2*pi*x);

--> plot(x,y,'r-');

--> title('cost over time');
```

Warning: Newly defined variable nargin shadows a function of the same name. Use clear nargin to recove

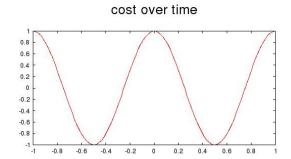
which results in the following plot.



We now increase the size of the font using the properties of the label

```
--> title('cost over time', 'fontsize', 20);
```

Warning: Newly defined variable nargin shadows a function of the same name. Use clear nargin to recove



23.67 TUBEPLOT Creates a Tubeplot

23.67.1 Usage

This tubeplot function is from the tubeplot package written by Anders Sandberg. The simplest syntax for the tubeplot routine is

plots the basic tube with radius 1, where x,y,z are vectors that describe the tube. If the radius of the tube is to be varied, use the second form

which plots the basic tube with variable radius r (either a vector or a scalar value). The third form allows you to specify the coloring using a vector of values:

where the coloring is now dependent on the values in the vector v. If you want to create a tube plot with a greater degree of tangential subdivisions (i.e., the tube is more circular, use the form

where **s** is the number of tangential subdivisions (default is 6) You can also use **tubeplot** to calculate matrices to feed to **mesh** and **surf**.

$$[X,Y,Z]$$
=tubeplot(x,y,z)

returns $N \times 3$ matrices suitable for mesh or surf.

Note that the tube may pinch at points where the normal and binormal misbehaves. It is suitable for general space curves, not ones that contain straight sections. Normally the tube is calculated using the Frenet frame, making the tube minimally twisted except at inflexion points.

To deal with this problem there is an alternative frame:

calculates the tube by setting the normal to the cross product of the tangent and the vector vec. If it is chosen so that it is always far from the tangent vector the frame will not twist unduly.

23.67.2 Example

Here is an example of a tubeplot.

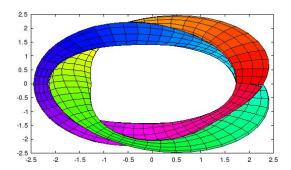
```
--> t=0:(2*pi/100):(2*pi);

--> x=cos(t*2).*(2+sin(t*3)*.3);

--> y=sin(t*2).*(2+sin(t*3)*.3);

--> z=cos(t*3)*.3;

--> tubeplot(x,y,z,0.14*sin(t*5)+.29,t,10);
```



Written by Anders Sandberg, asa@nada.kth.se, 2005 Website says the package is free for anybody to use. www.nada.kth.se/ asa/Ray/Tubeplot/tubeplot.html

23.68 UICONTROL Create a UI Control object

23.68.1 Usage

Creates a UI control object and parents it to the current figure. The syntax for its use is

```
handle = uicontrol(property, value, property, value,...)
```

where property and value are set. The handle ID for the resulting object is returned. It is automatically added to the children of the current figure.

23.69 UICONTROLPROPERTIES UI Control Properties

23.69.1 Usage

Below is a summary of the properties for user interface controls.

- backgroundcolor colorspec The background color for the widget.
- busyaction Not used.
- buttondownfcn Not used.

- callback string the callback to execute when the GUI control does its action. Clicking a button or moving a scroller will cause the callback to be executed. Also, pressing enter in a text box causes the callback to be executed.
- \bullet cdata an M x N x 3 array that represents an RGB image to use as the true color image displayed on push bottons or toggle buttons. The values must be between 0 and 1.
- children Not used.
- createfon Not used.
- deletefcn Not used;
- enable {'on', 'inactive', 'off'} For on (the default) the uicontrol behaves normally. For inactive, it is not operational, but looks the same as on. For off, the control is grayed out.
- extent a read only property that contains the extent of the text for the control.
- fontangle {'normal','italic','oblique'} The angle of the fonts used for text labels (e.g., tick labels).
- fontsize scalar The size of fonts used for text labels (tick labels).
- fontunits Not used.
- fontname string The name of the font to use for the widget.
- fontweight {'normal', 'bold', 'light', 'demi'} The weight of the font used
- foregroundcolor colorspec the foreground color for text.
- handlevisibility Not used.
- hittest Not used.
- horizontalalignment {'left', 'center', 'right} determines the justification of text.
- interruptible Not used.
- keypressfcn functionspec a string or function handle that is called when a key is pressed and a uicontrol object has focus.
- listboxtop a scalar (used only by the listbox style of uicontrols) that specifies which string appears at the top of the list box.
- max a scalar that specifies the largest value allowed for the value property. The interpretation varies depending on the type of the control
 - check boxes specifies what value is set to when the check box is selected.
 - edit box if max-min>1 then the text box allows for multiple lines of input. Otherwise,
 it is a single line only.

- list box if max-min>1 then multiple item selections are allowed. Otherwise, only single item selections are allowed.
- radio buttons specifies what value is set to when the radio button is selected.
- slider the maximum value the slider can take.
- toggle button specifies what value is set to when the toggle button is selected.
- min a scalar that specifies the smallest value for the value property. The interpretation of it depends on the type of the control
 - check boxes specifies what value is set to when the check box is not selected.
 - edit box if max-min>1 then the text box allows for multiple lines of input. Otherwise, it is a single line only.
 - list box if max-min>1 then multiple item selections are allowed. Otherwise, only single item selections are allowed.
 - radio buttons specifies what value is set to when the radio button is not selected.
 - slider the minimum value the slider can take.
 - toggle button specifies what value is set to when the toggle button is not selected.
- parent the handle of the parent object.
- position size and location of the uicontrol as a four vector [left, bottom, width, height]. If width>height then sliders are horizontal, otherwise the slider is oriented vertically.
- selected {'on', 'off'} not used.
- selectionhighlight {'on', 'off'} not used.
- sliderstep a two vector [min_step max_step] that controls the amount the slider value changes when you click the mouse on the control. If you click the arrow for the slider, the value changes by min_step, while if you click the trough, the value changes by max_step. Each value must be in the range [0,1], and is a percentage of the range max-min.
- string string the text for the control.
- style @—'pushbutton', 'toggle', 'radiobutton', 'checkbox', 'edit', 'text', 'slider', 'frame', 'listbox', 'popupmenu'—.
- tag string user specified label.
- tooltipstring string the tooltip for the control.
- type string the text is set to 'uicontrol'.
- uicontextmenu handle the handle of the uicontextmenu that shows up when you right-click over the control.
- units not used.
- userdata array any data you want to associate with the control.

- value The meaning of this property depends on the type of the control:
 - check box set to max when checked, and min when off.
 - list box set to a vector of indices corresponding to selected items, with 1 corresponding to the first item in the list.
 - pop up menu set to the index of the item selected (starting with 1)
 - radio buttons set to max when selected, and set to min when not selected.
 - sliders set to the value of the slider
 - toggle buttons set to max when selected, and set to min when not selected.
 - text controls, push buttons do not use this property.
- visible {'on', 'off'} controls whether the control is visible or not

23.70 VIEW Set Graphical View

23.70.1 Usage

The view function sets the view into the current plot. The simplest form is

```
view(n)
```

where n=2 sets a standard view (azimuth 0 and elevation 90), and n=3 sets a standard 3D view (azimuth 37.5 and elevation 30). With two arguments,

```
view(az,el)
```

you set the viewpoint to azimuth az and elevation el.

23.70.2 Example

Here is a 3D surface plot shown with a number of viewpoints. First, the default view for a 3D plot.

```
--> x = repmat(linspace(-1,1),[100,1]);

--> y = x';

--> r = x.^2+y.^2;

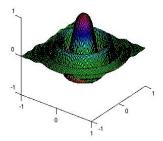
--> z = exp(-r*3).*cos(5*pi*r);

--> surf(x,y,z);

--> axis equal

--> view(3)
```

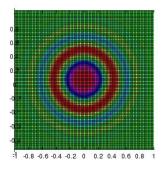
Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim



Next, we look at it as a 2D plot

```
--> surf(x,y,z);
--> axis equal
--> view(2)
```

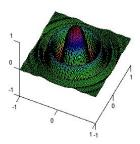
Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac



Finally, we generate a different view of the same surface.

```
--> surf(x,y,z);
--> axis equal
--> view(25,50);
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim to recover ac Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim to recover ac Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim to recover ac



23.71 WINLEV Image Window-Level Function

23.71.1 Usage

Adjusts the data range used to map the current image to the current colormap. The general syntax for its use is

winlev(window,level)

where window is the new window, and level is the new level, or

winlev

in which case it returns a vector containing the current window and level for the active image.

23.71.2 Function Internals

FreeMat deals with scalar images on the range of [0,1], and must therefor map an arbitrary image x to this range before it can be displayed. By default, the image command chooses

window =
$$\max x - \min x$$
,

and

$$level = \frac{window}{2}$$

This ensures that the entire range of image values in x are mapped to the screen. With the winlev function, you can change the range of values mapped. In general, before display, a pixel x is mapped to [0,1] via:

$$\max\left(0,\min\left(1,\frac{x-\text{level}}{\text{window}}\right)\right)$$

23.71.3 Examples

The window level function is fairly easy to demonstrate. Consider the following image, which is a Gaussian pulse image that is very narrow:

--> t = linspace(-1,1,256);

```
--> xmat = ones(256,1)*t; ymat = xmat';
--> A = \exp(-(xmat.^2 + ymat.^2)*100);
--> image(A);
The data range of A is [0,1], as we can verify numerically:
--> min(A(:))
ans =
1.3839e-87
--> max(A(:))
ans =
    0.9969
To see the tail behavior, we use the winlev command to force FreeMat to map a smaller range of A
to the colormap.
--> image(A);
--> winlev(1e-4, 0.5e-4)
The result is a look at more of the tail behavior of A. We can also use the winley function to find
out what the window and level are once set, as in the following example.
--> image(A);
--> winlev(1e-4, 0.5e-4)
--> winlev
Warning: Newly defined variable clim shadows a function of the same name. Use clear clim to recover ac
ans =
1.0000e-04
```

23.72 XLABEL Plot X-axis Label Function

23.72.1 Usage

xlabel('label',properties...)

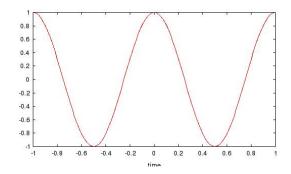
```
This command adds a label to the x-axis of the plot. The general syntax for its use is xlabel('label')
or in the alternate form
    xlabel 'label'
or simply
    xlabel label
Here label is a string variable. You can also specify properties for that label using the syntax
```

23.72.2 Example

Here is an example of a simple plot with a label on the x-axis.

```
--> x = linspace(-1,1);
--> y = cos(2*pi*x);
--> plot(x,y,'r-');
--> xlabel('time');
```

which results in the following plot.



23.73 XLIM Adjust X Axis limits of plot

23.73.1 Usage

There are several ways to use xlim to adjust the X axis limits of a plot. The various syntaxes are

```
xlim
xlim([lo,hi])
xlim('auto')
xlim('manual')
xlim('mode')
xlim(handle,...)
```

The first form (without arguments), returns a 2-vector containing the current limits. The second form sets the limits on the plot to [lo,hi]. The third and fourth form set the mode for the limit to auto and manual respectively. In auto mode, FreeMat chooses the range for the axis automatically. The xlim('mode') form returns the current mode for the axis (either 'auto' or 'manual'). Finally, you can specify the handle of an axis to manipulate instead of using the current one.

23.73.2 Example

```
--> x = linspace(-1,1);

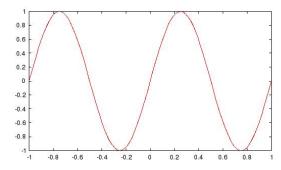
--> y = sin(2*pi*x);

--> plot(x,y,'r-');

--> xlim % what are the current limits?
```

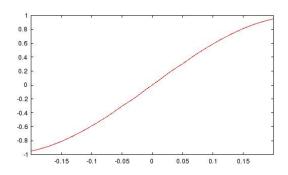
ans = -1 1

which results in



Next, we zoom in on the plot using the xlim function

which results in



23.74 YLABEL Plot Y-axis Label Function

23.74.1 Usage

This command adds a label to the y-axis of the plot. The general syntax for its use is

ylabel('label')

or in the alternate form

ylabel 'label'

or simply

ylabel label

You can also specify properties for that label using the syntax

```
ylabel('label',properties...)
```

23.74.2 Example

Here is an example of a simple plot with a label on the y-axis.

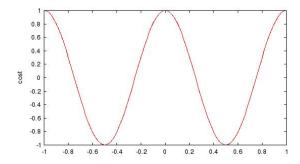
```
--> x = linspace(-1,1);

--> y = cos(2*pi*x);

--> plot(x,y,'r-');

--> ylabel('cost');
```

which results in the following plot.



23.75 YLIM Adjust Y Axis limits of plot

23.75.1 Usage

There are several ways to use ylim to adjust the Y axis limits of a plot. The various syntaxes are

```
ylim
ylim([lo,hi])
ylim('auto')
ylim('manual')
ylim('mode')
ylim(handle,...)
```

The first form (without arguments), returns a 2-vector containing the current limits. The second form sets the limits on the plot to [lo,hi]. The third and fourth form set the mode for the limit to auto and manual respectively. In auto mode, FreeMat chooses the range for the axis automatically. The ylim('mode') form returns the current mode for the axis (either 'auto' or 'manual'). Finally, you can specify the handle of an axis to manipulate instead of using the current one.

23.75.2 Example

```
--> x = linspace(-1,1);

--> y = sin(2*pi*x);

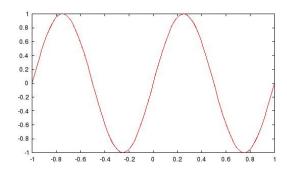
--> plot(x,y,'r-');

--> ylim % what are the current limits?

ans =

-0.9999 0.9999
```

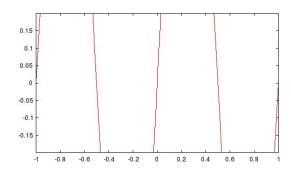
which results in



Next, we zoom in on the plot using the ylim function

```
--> plot(x,y,'r-')
--> ylim([-0.2,0.2])
```

which results in



23.76 ZLABEL Plot Z-axis Label Function

23.76.1 Usage

This command adds a label to the z-axis of the plot. The general syntax for its use is

```
zlabel('label')
```

```
or in the alternate form
```

```
zlabel 'label'
or simply
zlabel label
```

Here label is a string variable. You can also specify properties for that label using the syntax

```
zlabel('label',properties...)
```

23.76.2 Example

Here is an example of a simple plot with a label on the z-axis.

```
--> t = linspace(0,5*pi);

--> x = cos(t);

--> y = sin(t);

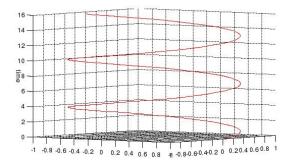
--> z = t;

--> plot3(x,y,z,'r-');
```

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim --> view(3);

Warning: Newly defined variable xlim shadows a function of the same name. Use clear xlim Warning: Newly defined variable ylim shadows a function of the same name. Use clear ylim Warning: Newly defined variable zlim shadows a function of the same name. Use clear zlim --> zlabel('time');

which results in the following plot.



23.77 ZLIM Adjust Z Axis limits of plot

23.77.1 Usage

There are several ways to use zlim to adjust the Z axis limits of a plot. The various syntaxes are

```
zlim
zlim([lo,hi])
zlim('auto')
zlim('manual')
zlim('mode')
zlim(handle,...)
```

The first form (without arguments), returns a 2-vector containing the current limits. The second form sets the limits on the plot to [lo,hi]. The third and fourth form set the mode for the limit to auto and manual respectively. In auto mode, FreeMat chooses the range for the axis automatically. The zlim('mode') form returns the current mode for the axis (either 'auto' or 'manual'). Finally, you can specify the handle of an axis to manipulate instead of using the current one.

23.77.2 Example

```
--> x = linspace(-1,1);

--> y = sin(2*pi*x);

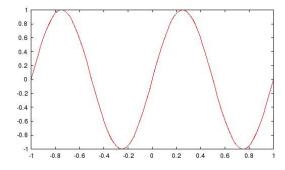
--> plot(x,y,'r-');

--> zlim % what are the current limits?

ans =

-0.5000 0.5000
```

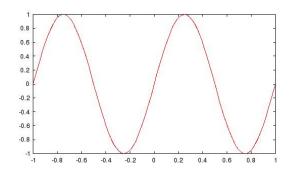
which results in



Next, we zoom in on the plot using the zlim function

```
--> plot(x,y,'r-')
--> zlim([-0.2,0.2])
```

which results in



23.78 ZOOM Image Zoom Function

23.78.1 Usage

This function changes the zoom factor associated with the currently active image. It is a legacy support function only, and thus is not quite equivalent to the zoom function from previous versions of FreeMat. However, it should achieve roughly the same effect. The generic syntax for its use is

```
zoom(x)
```

where x is the zoom factor to be used. The exact behavior of the zoom factor is as follows:

- x>0 The image is zoomed by a factor x in both directions.
- x=0 The image on display is zoomed to fit the size of the image window, but the aspect ratio of the image is not changed. (see the Examples section for more details). This is the default zoom level for images displayed with the image command.
- x<0 The image on display is zoomed to fit the size of the image window, with the zoom factor in the row and column directions chosen to fill the entire window. The aspect ratio of the image is not preserved. The exact value of x is irrelevant.

23.78.2 Example

To demonstrate the use of the zoom function, we create a rectangular image of a Gaussian pulse. We start with a display of the image using the image command, and a zoom of 1.

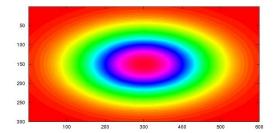
```
--> x = linspace(-1,1,300)'*ones(1,600);

--> y = ones(300,1)*linspace(-1,1,600);

--> Z = exp(-(x.^2+y.^2)/0.3);

--> image(Z);

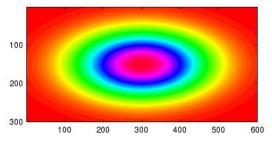
--> zoom(1.0);
```



At this point, resizing the window accomplishes nothing, as with a zoom factor greater than zero, the size of the image is fixed.

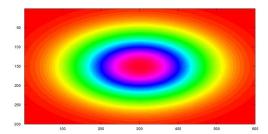
If we change the zoom to another factor larger than 1, we enlarge the image by the specified factor (or shrink it, for zoom factors 0 < x < 1. Here is the same image zoomed out to 60

```
--> image(Z);
--> zoom(0.6);
```



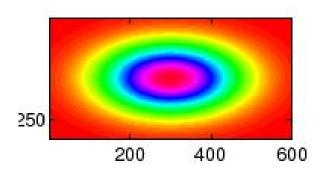
Similarly, we can enlarge it to 130

```
--> image(Z)
--> zoom(1.3);
```



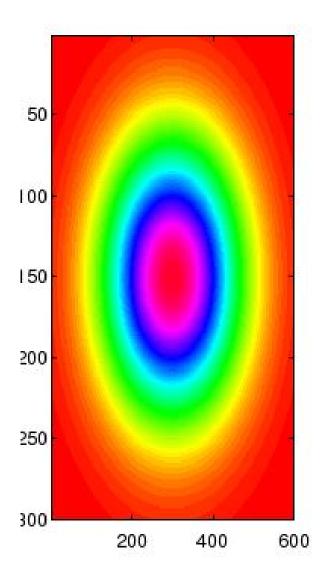
The "free" zoom of x = 0 results in the image being zoomed to fit the window without changing the aspect ratio. The image is zoomed as much as possible in one direction.

```
--> image(Z);
--> zoom(0);
--> sizefig(200,400);
```



The case of a negative zoom x < 0 results in the image being scaled arbitrarily. This allows the image aspect ratio to be changed, as in the following example.

```
--> image(Z);
--> zoom(-1);
--> sizefig(200,400);
```



23.79 ZPLANE Zero-pole plot

23.79.1 Usage

This function makes a zero-pole plot of a discrete-time system defined by its zeros and poles. The various syntaxes are

zplane(z,p)

where z and p are the zeros and the poles of the system stored as column vectors, or

zplane(b,a)

where a and b are the polynomial coefficients of the numerator and denominator stored as line vectors (roots is used to find the zeros and poles). The symbol 'o' represents a zero and the symbol 'x' represents a pole. The plot includes the unit circle for reference. Contributed by Paulo Xavier Candeias under GPL

Chapter 24

OpenGL Models

24.1 GLASSEMBLY Create a GL Assembly

24.1.1 Usage

Define a GL Assembly. A GL Assembly consists of one or more GL Nodes or GL Assemblies that are placed relative to the coordinate system of the assembly. For example, if we have glnode definitions for 'bread' and 'cheese', then a glassembly of sandwich would consist of placements of two 'bread' nodes with a 'cheese' node in between. Furthermore, a 'lunch' assembly could consist of a 'sandwich' a 'chips' and 'soda'. Hopefully, you get the idea. The syntax for the glassembly command is

```
glassembly(name,part1,transform1,part2,transform2,...)
```

where part1 is the name of the first part, and could be either a glnode or itself be another glassembly. Here transform1 is the 4 x 4 matrix that transforms the part into the local reference coordinate system.

WARNING!! Currently FreeMat does not detect or gracefully handle self-referential assemblies (i.e, if you try to make a sandwich contain a sandwich, which you can do by devious methods that I refuse to explain). Do not do this! You have been warned.

24.2 GLCLUMP Create a GL Clump

24.2.1 Usage

Defines an aggregate clump of objects that can be treated as a node. A GL Clump is defined by a vector consisting of the following elements:

```
[r1 g1 b1 n1 p1 p2 p3 ... r2 g2 b2 n2 p1 p2 p3 ... ]
```

i.e., an RGB color spec, followed by a point count ni, followed by a length ni vector of coordinates that are x,y,z triplets. The usage of this function is

```
glclump(name, vector)
```

where name is the name of the clump and vector is the aforementioned vector of points.

24.3 GLDEFMATERIAL Defines a GL Material

24.3.1 Usage

Define a material. The syntax for its use is

gldefmaterial(name,ambient,diffuse,specular,shininess)

where name is the name of the material, and ambient is a 4 x 1 vector containing the ambient component of the material property, and diffuse is a 4 x 1 vector and specular is a 4 x 1 vector containing the specular component of the material properties and shininess is the exponent that governs the shinines of the material.

24.4 GLLINES Create a GL Lineset

24.4.1 Usage

Defines a set of lines that can be treated as a node. A GL Lines is defined by a vector consisting of the following elements:

```
[m1 x1 y1 z1 ... xn yn zn m2 x1 y1 z1 ....]
```

i.e., a point count followed by that number of triplets. The usage of this function is

gllines(name, vector, color)

where name is the name of the lineset and vector is the aforementioned vector of points.

24.5 GLNODE Create a GL Node

24.5.1 Usage

Define a GL Node. A GL Node is an object that can be displayed in a GL Window. It is defined by a triangular mesh of vertices. It must also have a material that defines its appearance (i.e. color, shininess, etc.). The syntax for the glnode command is

```
glnode(name, material, pointset)
```

where material is the name of a material that has already been defined with gldefmaterial, pointset is a 3 x N matrix of points that define the geometry of the object. Note that the points are assumed to be connected in triangular facts, with the points defined counter clock-wise as seen from the outside of the facet. FreeMat will compute the normals. The name argument must be unique. If you want multiple instances of a given glnode in your GLWindow, that is fine, as instances of a glnode are created through a glassembly.

Chapter 25

Object Oriented Programming

25.1 AND Overloaded Logical And Operator

25.1.1 Usage

This is a method that is invoked to combine two variables using a logical and operator, and is invoked when you call

```
c = and(a,b)
or for
c = a & b
```

25.2 CAT Concatenation of Arrays

25.2.1 Usage

This function concatenates arrays in a given dimension. The syntax for its use is

```
cat (DIM, A, B) cat (DIM, A, B, C ...)
```

to return the concatenation along the dimension DIM of all arguments. cat(1, A, B, C) is the same as [A; B; C] or vertcat(A, B, C). cat(2, A, B, C) is the same as [A, B, C] or horzcat(A, B, C).

25.3 CLASS Class Support Function

25.3.1 Usage

There are several uses for the class function. The first version takes a single argument, and returns the class of that variable. The syntax for this form is

```
classname = class(variable)
```

and it returns a string containing the name of the class for variable. The second form of the class function is used to construct an object of a specific type based on a structure which contains data elements for the class. The syntax for this version is

```
classvar = class(template, classname, parent1, parent2,...)
```

This should be called inside the constructor for the class. The resulting class will be of the type classname, and will be derived from parent1, parent2, etc. The template argument should be a structure array that contains the members of the class. See the constructors help for some details on how to use the class function. Note that if the template argument is an empty structure matrix, then the resulting variable has no fields beyond those inherited from the parent classes.

25.4 COLON Overloaded Colon Operator

25.4.1 Usage

This is a method that is invoked in one of two forms, either the two argument version

```
c = colon(a,b)
which is also called using the notation
c = a:b
and the three argument version
d = colon(a,b,c)
which is also called using the notation
d = a:b:c
```

25.5 CONSTRUCTORS Class Constructors

25.5.1 Usage

When designing a constructor for a FreeMat class, you should design the constructor to take a certain form. The following is the code for the sample mat object

```
function p = mat(a)
  if (nargin == 0)
    p.c = [];
    p = class(p,'mat');
  elseif isa(a,'mat')
    p = a;
  else
    p.c = a;
    p = class(p,'mat');
  end
```

Generally speaking when it is provided with zero arguments, the constructor returns a default version of the class using a template structure with the right fields populated with default values. If the constructor is given a single argument that matches the class we are trying to construct, the constructor passes through the argument. This form of the constructor is used for type conversion. In particular,

```
p = mat(a)
```

guarantees that p is an array of class mat. The last form of the constructor builds a class object given the input. The meaning of this form depends on what makes sense for your class. For example, for a polynomial class, you may want to pass in the coefficients of the polynomial.

25.6 CTRANSPOSE Overloaded Conjugate Transpose Operator

25.6.1 Usage

This is a method that is invoked when a variable has the conjugate transpose operator method applied, and is invoked when you call

```
c = ctranspose(a)
or
/ c = a'
```

25.7 EQ Overloaded Equals Comparison Operator

25.7.1 Usage

This is a method that is invoked to combine two variables using an equals comparison operator, and is invoked when you call

```
c = eq(a,b)
or for
c = a == b
```

25.8 GE Overloaded Greater-Than-Equals Comparison Operator

25.8.1 Usage

This is a method that is invoked to combine two variables using a greater than or equals comparison operator, and is invoked when you call

```
c = ge(a,b)
or for
c = a >= b
```

25.9 GT Overloaded Greater Than Comparison Operator

25.9.1 Usage

This is a method that is invoked to combine two variables using a greater than comparison operator, and is invoked when you call

```
c = gt(a,b)
or for
c = a > b
```

25.10 HORZCAT Horizontal Array Concatenation

25.10.1 Usage

This function concatenates arrays horizontally (along the column dimension). The syntax for its use is

```
d = horzcat(a,b,c)
which is equivalent to the statement d = [a,b,c].
```

25.11 HORZCAT Horizontal Array Concatenation

25.11.1 Usage

This function concatenates arrays horizontally (along the column dimension). The syntax for its use is

```
d = horzcat(a,b,c)
which is equivalent to the statement d = [a,b,c].
```

25.12 LDIVIDE Overloaded Left Divide Operator

25.12.1 Usage

This is a method that is invoked when two variables are divided and is invoked when you call

```
c = 1divide(a,b)
or for
c = a . \ b
```

25.13 LE Overloaded Less-Than-Equals Comparison Operator

25.13.1 Usage

This is a method that is invoked to compare two variables using a less than or equals comparison operator, and is invoked when you call

```
c = le(a,b)
or for
c = a \le b
```

25.14 LT Overloaded Less Than Comparison Operator

25.14.1 Usage

This is a method that is invoked to compare two variables using a less than comparison operator, and is invoked when you call

```
c = lt(a,b)
or for
c = a < b
```

25.15 MINUS Overloaded Addition Operator

25.15.1 Usage

This is a method that is invoked when two variables are subtracted and is invoked when you call

```
c = minus(a,b)
or for
c = a - b
```

25.16 MLDIVIDE Overloaded Matrix Left Divide Operator

25.16.1 Usage

This is a method that is invoked when two variables are divided using the matrix (left) divide operator, and is invoked when you call

```
c = mldivide(a,b)
or for
c = a \setminus b
```

25.17 MPOWER Overloaded Matrix Power Operator

25.17.1 Usage

This is a method that is invoked when one variable is raised to another variable using the matrix power operator, and is invoked when you call

```
c = mpower(a,b)
or
c = a^b
```

25.18 MRDIVIDE Overloaded Matrix Right Divide Operator

25.18.1 Usage

This is a method that is invoked when two variables are divided using the matrix divide operator, and is invoked when you call

```
c = mrdivide(a,b)
or for
c = a / b
```

25.19 MTIMES Overloaded Matrix Multiplication Operator

25.19.1 Usage

This is a method that is invoked when two variables are multiplied using the matrix operator and is invoked when you call

```
c = mtimes(a,b)
or for
c = a * b
```

25.20 NE Overloaded Not-Equals Comparison Operator

25.20.1 Usage

This is a method that is invoked to combine two variables using a not-equals comparison operator, and is invoked when you call

```
c = ne(a,b)
or for
c = a != b
```

25.21 NOT Overloaded Logical Not Operator

25.21.1 Usage

This is a method that is invoked when a variable is logically inverted, and is invoked when you call

```
c = not(a)
or for
c = a
```

25.22 OR Overloaded Logical Or Operator

25.22.1 Usage

This is a method that is invoked to combine two variables using a logical or operator, and is invoked when you call

```
c = or(a,b)
or for
c = a \mid b
```

25.23 PLUS Overloaded Addition Operator

25.23.1 Usage

This is a method that is invoked when two variables are added and is invoked when you call

```
c = plus(a,b)
or for
c = a + b
```

25.24 POWER Overloaded Power Operator

25.24.1 Usage

This is a method that is invoked when one variable is raised to another variable using the dot-power operator, and is invoked when you call

```
c = power(a,b)
or
c = a.^b
```

25.25 RDIVIDE Overloaded Right Divide Operator

25.25.1 Usage

This is a method that is invoked when two variables are divided and is invoked when you call

```
c = rdivide(a,b)
or for
c = a ./ b
```

25.26 SUBSASGN Overloaded Class Assignment

25.26.1 Usage

This method is called for expressions of the form

```
a(b) = c, a\{b\} = c, a.b = c
```

and overloading the subsasgn method can allow you to define the meaning of these expressions for objects of class a. These expressions are mapped to a call of the form

```
a = subsasgn(a,s,b)
```

where **s** is a structure array with two fields. The first field is

- type is a string containing either '()' or '{}' or '.' depending on the form of the call.
- subs is a cell array or string containing the subscript information.

When multiple indexing experssions are combined together such as $a(5).foo\{:\}$ = b, the s array contains the following entries

```
s(1).type = '()' s(1).subs = {5}
s(2).type = '.' s(2).subs = 'foo'
s(3).type = '{}' s(3).subs = ':'
```

25.27 SUBSINDEX Overloaded Class Indexing

25.27.1 Usage

This method is called for classes in the expressions of the form

```
c = subsindex(a)
```

where a is an object, and c is an index vector. It is also called for

```
c = b(a)
```

in which case subsindex(a) must return a vector containing integers between 0 and N-1 where N is the number of elements in the vector b.

25.28 SUBSREF Overloaded Class Indexing

25.28.1 Usage

This method is called for expressions of the form

```
c = a(b), c = a\{b\}, c = a.b
```

and overloading the subsref method allows you to define the meaning of these expressions for objects of class a. These expressions are mapped to a call of the form

```
b = subsref(a,s)
```

where s is a structure array with two fields. The first field is

- type is a string containing either '()' or '{}' or '.' depending on the form of the call.
- subs is a cell array or string containing the the subscript information.

When multiple indexing experssions are combined together such as $b = a(5).foo\{:\}$, the s array contains the following entries

```
s(1).type = '()' s(1).subs = {5}
s(2).type = '.' s(2).subs = 'foo'
s(3).type = '{}' s(3).subs = ':'
```

25.29 TIMES Overloaded Multiplication Operator

25.29.1 Usage

This is a method that is invoked when two variables are multiplied and is invoked when you call

```
c = times(a,b)
or for
c = a .* b
```

25.30 TRANSPOSE Overloaded Transpose Operator

25.30.1 Usage

This is a method that is invoked when a variable has the transpose operator method applied, and is invoked when you call

```
c = transpose(a)
or
/ c = a.'
```

25.31 UMINUS Overloaded Unary Minus Operator

25.31.1 Usage

This is a method that is invoked when a variable is negated, and is invoked when you call

```
c = uminus(a)
or for
c = -a
```

25.32 UPLUS Overloaded Unary Plus Operator

25.32.1 Usage

This is a method that is invoked when a variable is preceded by a "+", and is invoked when you call

```
c = uplus(a)
or for
c = +a
```

25.33 VERTCAT Horizontal Array Concatenation

25.33.1 Usage

This function concatenates arrays vertically (along the row dimension). The syntax for its use is

```
d = vertcat(a,b,c)
```

which is equivalent to the statement d = [a;b;c].

25.34 VERTCAT Horizontal Array Concatenation

25.34.1 Usage

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```
d = vertcat(a,b,c)
```

which is equivalent to the statement d = [a;b;c].

Chapter 26

Bitwise Operations

26.1 BITAND Bitwise Boolean And Operation

26.1.1 Usage

Performs a bitwise binary and operation on the two arguments and returns the result. The syntax for its use is

```
y = bitand(a,b)
```

where a and b are multi-dimensional unsigned integer arrays. The and operation is performed using 32 bit unsigned intermediates. Note that if a or b is a scalar, then each element of the other array is and'ed with that scalar. Otherwise the two arrays must match in size.

26.1.2 Example

26.2 BITCMP Bitwise Boolean Complement Operation

26.2.1 Usage

Usage

Performs a bitwise binary complement operation on the argument and returns the result. The syntax for its use is

```
y = bitcmp(a)
```

where a is an unsigned integer arrays. This version of the command uses as many bits as required by the type of a. For example, if a is an uint8 type, then the complement is formed using 8 bits. The second form of bitcmp allows you to specify the number of bits to use,

```
y = bitcmp(a,n)
```

in which case the complement is taken with respect to n bits, where n must be less than the length of the integer type.

26.2.2 Example

```
--> bitcmp(uint16(2^14-2))

ans =
    49153

--> bitcmp(uint16(2^14-2),14)

ans =
    1
```

26.3 BITOR Bitwise Boolean Or Operation

26.3.1 Usage

Performs a bitwise binary or operation on the two arguments and returns the result. The syntax for its use is

```
y = bitor(a,b)
```

where a and b are multi-dimensional unsigned integer arrays. The and operation is performed using 32 bit unsigned intermediates. Note that if a or b is a scalar, then each element of the other array is or'ed with that scalar. Otherwise the two arrays must match in size.

26.3.2 Example

26.4 BITXOR Bitwise Boolean Exclusive-Or (XOR) Operation

26.4.1 Usage

Performs a bitwise binary xor operation on the two arguments and returns the result. The syntax for its use is

```
y = bitxor(a,b)
```

where a and b are multi-dimensional unsigned integer arrays. The and operation is performed using 32 bit unsigned intermediates. Note that if a or b is a scalar, then each element of the other array is xor'ed with that scalar. Otherwise the two arrays must match in size.

26.4.2 Example

Chapter 27

FreeMat Threads

27.1 THREADCALL Call Function In A Thread

27.1.1 Usage

The threadcall function is a convenience function for executing a function call in a thread. The syntax for its use is

```
[val1,...,valn] = threadcall(threadid,timeout,funcname,arg1,arg2,...)
```

where threadid is the ID of the thread (as returned by the threadnew function), funcname is the name of the function to call, and argi are the arguments to the function, and timeout is the amount of time (in milliseconds) that the function is allowed to take.

27.1.2 Example

Here is an example of executing a simple function in a different thread.

```
--> id = threadnew

id =
    3

--> d = threadcall(id,1000,'cos',1.02343)

d =
    0.5204

--> threadfree(id)
```

27.2 THREADFREE Free thread resources

27.2.1 Usage

The threadfree is a function to free the resources claimed by a thread that has finished. The syntax for its use is

```
threadfree(handle)
```

where handle is the handle returned by the call to threadnew. The threadfree function requires that the thread be completed. Otherwise it will wait for the thread to complete, potentially for an arbitrarily long period of time. To fix this, you can either call threadfree only on threads that are known to have completed, or you can call it using the syntax

```
threadfree(handle,timeout)
```

where timeout is a time to wait in milliseconds. If the thread fails to complete before the timeout expires, an error occurs.

27.3 THREADID Get Current Thread Handle

27.3.1 Usage

The threadid function in FreeMat tells you which thread is executing the context you are in. Normally, this is thread 1, the main thread. However, if you start a new thread using threadnew, you will be operating in a new thread, and functions that call threadid from the new thread will return their handles.

27.3.2 Example

```
From the main thread, we have

--> threadid

ans =
2

But from a launched auxilliary thread, we have

--> t_id = threadnew

t_id =
3

--> id = threadcall(t_id,1000,'threadid')

id =
3

--> threadfree(t_id);
```

27.4 THREADKILL Halt execution of a thread

27.4.1 Usage

The threadkill function stops (or attempts to stop) execution of the given thread. It works only for functions defined in M-files (i.e., not for built in or imported functions), and it works by setting a flag that causes the thread to stop execution at the next available statement. The syntax for this function is

```
threadkill(handle)
```

where handle is the value returned by a threadnew call. Note that the threadkill function returns immediately. It is still your responsibility to call threadfree to free the thread you have halted.

You cannot kill the main thread (thread id 1).

27.4.2 Example

Here is an example of stopping a runaway thread using threadkill. Note that the thread function in this case is an M-file function. We start by setting up a free running counter, where we can access the counter from the global variables.

```
--> threadstart(a, 'freecount', 0)
                                    % start the thread
--> count
                                    % it is counting
ans =
10270
                                    % Wait a bit
--> sleep(1)
                                    % it is still counting
--> count
ans =
488710
--> threadkill(a)
                                    % kill the counter
--> threadwait(a,1000)
                                    % wait for it to finish
```

27.5 THREADNEW Create a New Thread

27.5.1 Usage

The threadnew function creates a new FreeMat thread, and returns a handle to the resulting thread. The threadnew function takes no arguments. They general syntax for the threadnew function is

```
handle = threadnew
```

Once you have a handle to a thread, you can start the thread on a computation using the threadstart function. The threads returned by threadnew are in a dormant state (i.e., not running). Once you are finished with the thread you must call threadfree to free the resources associated with that thread.

Some additional important information. Thread functions operate in their own context or workspace, which means that data cannot be shared between threads. The exception is global variables, which provide a thread-safe way for multiple threads to share data. Accesses to global variables are serialized so that they can be used to share data. Threads and FreeMat are a new feature, so there is room for improvement in the API and behavior. The best way to improve threads is to experiment with them, and send feedback.

27.6 THREADSTART Start a New Thread Computation

27.6.1 Usage

The threadstart function starts a new computation on a FreeMat thread, and you must provide a function (no scripts are allowed) to run inside the thread, pass any parameters that the thread function requires, as well as the number of output arguments expected. The general syntax for the threadstart function is

```
threadstart(threadid,function,nargout,arg1,arg2,...)
```

where threadid is a thread handle (returned by threadnew), where function is a valid function name (it can be a built-in imported or M-function), nargout is the number of output arguments expected from the function, and arg1 is the first argument that is passed to the function. Because the function runs in its own thread, the return values of the function are not available imediately. Instead, execution of that function will continue in parallel with the current thread. To retrieve the output of the thread function, you must wait for the thread to complete using the threadwait function, and then call threadvalue to retrieve the result. You can also stop the running thread prematurely by using the threadkill function. It is important to call threadfree on the handle you get from threadnew when you are finished with the thread to ensure that the resoures are properly freed.

It is also perfectly reasonable to use a single thread multiple times, calling threadstart and threadreturn multiple times on a single thread. The context is preserved between threads. When calling threadstart on a pre-existing thread, FreeMat will attempt to wait on the thread. If the wait fails, then an error will occur.

Some additional important information. Thread functions operate in their own context or workspace, which means that data cannot be shared between threads. The exception is global variables, which provide a thread-safe way for multiple threads to share data. Accesses to global variables are serialized so that they can be used to share data. Threads and FreeMat are a new feature, so there is room for improvement in the API and behavior. The best way to improve threads is to experiment with them, and send feedback.

27.6.2 Example

Here we do something very simple. We want to obtain a listing of all files on the system, but do not want the results to stop our computation. So we run the system call in a thread.

The possibilities for threads are significant. For example, we can solve equations in parallel, or take Fast Fourier Transforms on multiple threads. On multi-processor machines or multicore CPUs, these threaded calculations will execute in parallel. Neat.

The reason for the nargout argument is best illustrated with an example. Suppose we want to compute the Singular Value Decomposition svd of a matrix A in a thread. The documentation for the svd function tells us that the behavior depends on the number of output arguments we request. For example, if we want a full decomposition, including the left and right singular vectors, and a diagonal singular matrix, we need to use the three-output syntax, instead of the single output syntax (which returns only the singular values in a column vector):

```
--> A = float(rand(4))
A =
    0.3256
               0.8138
                         0.8819
                                    0.2759
    0.4954
               0.7569
                         0.9476
                                    0.9368
    0.6082
               0.1744
                         0.0073
                                    0.5028
    0.8448
               0.1609
                         0.8433
                                    0.9130
--> [u,s,v] = svd(A)
                         % Compute the full decomposition
u =
   -0.4551
              -0.6585
                        -0.1575
                                   -0.5783
   -0.6358
              -0.1877
                         -0.1019
                                    0.7417
                         -0.7940
   -0.2455
               0.5238
                                   -0.1870
   -0.5731
               0.5067
                         0.5782
                                   -0.2836
s =
    2.5027
                    0
                               0
                                          0
         0
               0.8313
                               0
                                          0
         0
                    0
                         0.3646
                                          0
         0
                    0
                                    0.2569
                               0
   -0.4382
              0.5283
                        -0.2637
                                   -0.6777
   -0.3942
              -0.6076
                         -0.6878
                                    0.0489
   -0.5949
              -0.3938
                         0.6757
                                   -0.1854
   -0.5465
                        -0.0280
               0.4434
                                    0.7099
--> sigmas = svd(A)
                         % Only want the singular values
sigmas =
 NaN
 NaN
 NaN
 NaN
```

Normally, FreeMat uses the left hand side of an assignment to calculate the number of outputs for the function. When running a function in a thread, we separate the assignment of the output from the invokation of the function. Hence, we have to provide the number of arguments at the time we invoke the function. For example, to compute a full decomposition in a thread, we specify that we want 3 output arguments:

If we want to compute just the singular values, we start the thread function with only one output argument:

```
--> a = threadnew;
--> threadstart(a,'svd',1,A);
--> sigmas = threadvalue(a);
--> threadfree(a)
```

27.7 THREADVALUE Retrieve the return values from a thread

27.7.1 Usage

The threadvalue function retrieves the values returned by the function specified in the threadnew call. The syntax for its use is

```
[arg1,arg2,...,argN] = threadvalue(handle)
```

where handle is the value returned by a threadnew call. Note that there are issues with nargout. See the examples section of threadnew for details on how to work around this limitation. Because the function you have spawned with threadnew may still be executing, threadvalue must first threadwait for the function to complete before retrieving the output values. This wait may take an arbitrarily long time if the thread function is caught in an infinite loop. Hence, you can also specify a timeout parameter to threadvalue as

```
[arg1,arg2,...,argN] = threadvalue(handle,timeout)
```

where the timeout is specified in milliseconds. If the wait times out, an error is raised (that can be caught with a try and catch block.

In either case, if the thread function itself caused an error and ceased execution abruptly, then calling threadvalue will cause that function to raise an error, allowing you to retrieve the error that was caused and correct it. See the examples section for more information.

27.7.2 Example

Here we do something very simple. We want to obtain a listing of all files on the system, but do not want the results to stop our computation. So we run the system call in a thread.

In this example, we force the threaded function to cause an exception (by calling the error function as the thread function). When we call threadvalue, we get an error, instead of the return value of the function

```
--> a = threadnew

a =
3

--> threadstart(a,'error',0,'Hello world!'); % Will immediately stop due to error
--> c = threadvalue(a) % The error comes to us

Error: Thread: Hello world!
--> threadfree(a)
```

Note that the error has the text Thread: prepended to the message to help you identify that this was an error in a different thread.

27.8 THREADWAIT Wait on a thread to complete execution

27.8.1 Usage

The threadwait function waits for the given thread to complete execution, and stops execution of the current thread (the one calling threadwait) until the given thread completes. The syntax for its use is

```
success = threadwait(handle)
```

where handle is the value returned by threadnew and success is a logical vaariable that will be 1 if the wait was successful or 0 if the wait times out. By default, the wait is indefinite. It is better to use the following form of the function

```
success = threadwait(handle,timeout)
```

where timeout is the amount of time (in milliseconds) for the threadwait function to wait before a timeout occurs. If the threadwait function succeeds, then the return value is a logical 1, and if it fails, the return value is a logical 0. Note that you can call threadwait multiple times on a thread, and if the thread is completed, each one will succeed.

27.8.2 Example

Here we lauch the sleep function in a thread with a time delay of 10 seconds. This means that the thread function will not complete until 10 seconds have elapsed. When we call threadwait on this thread with a short timeout, it fails, but not when the timeout is long enough to capture the end of the function call.

```
--> a = threadnew;
--> threadstart(a,'sleep',0,10);  % start a thread that will sleep for 10
--> threadwait(a,2000)  % 2 second wait is not long enough

ans = 0
--> threadwait(a,10000)  % 10 second wait is long enough

ans = 1
--> threadfree(a)
```

Chapter 28

Function Related Functions

28.1 INLINE Construct Inline Function

28.1.1 Usage

Constructs an inline function object. The syntax for its use is either

```
y = inline(expr)
```

which uses the symvar function to identify the variables in the expression, or the explicit form

```
y = inline(expr, var1, var2, ..., varn)
```

where the variables are explicitly given. Note that inline functions are only partially supported in FreeMat. If you need features of the inline function that are not currently implemented, please file a feature request at the FreeMat website.

28.1.2 Example

Here we construct an inline expression using the autodetection of symvar

```
--> a = inline('x^2')

a =
    inline function object
    f(x) = x^2
--> a(3)

ans =
    9

--> a(i)

ans =
    -1.0000 + 0.0000i
```

```
In this case, we have multiple arguments (again, autodetected)
```

```
--> a = inline('x+y-cos(x+y)')
a =
  inline function object
  f(x,y) = x+y-cos(x+y)
--> a(pi,-pi)
ans =
-1
```

In this form, we specify which arguments we want to use (thereby also specifying the order of the arguments

```
--> a = inline('x+t-sin(x)', 'x', 't')
a =
   inline function object
   f(x,t) = x+t-sin(x)
--> a(0.5,1)
ans =
     1.0206
Inline objects can also be used with feval
--> a = inline('cos(t)')
a =
   inline function object
   f(t) = cos(t)
--> feval(a,pi/2)
ans =
   6.1230e-17
```

28.2 SYMVAR Find Symbolic Variables in an Expression

28.2.1 Usage

Finds the symbolic variables in an expression. The syntax for its use is

```
syms = symvar(expr)
```

where expr is a string containing an expression, such as 'x^2 + cos(t+alpha)'. The result is a cell array of strings containing the non-function identifiers in the expression. Because they are usually not used as identifiers in expressions, the strings 'pi', 'inf', 'nan', 'eps', 'i', 'j' are ignored.

28.2.2 Example

```
Here are some simple examples:
```

```
--> symvar('x^2+sqrt(x)') % sqrt is eliminated as a function

ans =
[x]

--> symvar('pi+3') % No identifiers here

ans =
Empty array 0 1
--> symvar('x + t*alpha') % x, t and alpha

ans =
[alpha]
[t]
[x]
```

Chapter 29

FreeMat External Interface

29.1 CENUM Lookup Enumerated C Type

29.1.1 Usage

The cenum function allows you to use the textual strings of C enumerated types (that have been defined using ctypedefine) in your FreeMat scripts isntead of the hardcoded numerical values. The general syntax for its use is

```
enum_int = cenum(enum_type,enum_string)
```

which looks up the integer value of the enumerated type based on the string. You can also supply an integer argument, in which case cenum will find the matching string

```
enum_string = cenum(enum_type,enum_int)
```

29.2 CTYPECAST Cast FreeMat Structure to C Structure

29.2.1 Usage

The ctypecast function is a convenience function for ensuring that a FreeMat structure fits the definition of a C struct (as defined via ctypedefine. It does so by encoding the structure to a byte array using ctypefreeze and then recovering it using the ctypethaw function. The usage is simply

```
s = ctypecast(s,typename)
```

where s is the structure and typename is the name of the C structure that describes the desired layout and types for elements of s. This function is equivalent to calling ctypefreeze and ctypethaw in succession on a FreeMat structure.

29.3 CTYPEDEFINE Define C Type

29.3.1 Usage

The ctypedefine function allows you to define C types for use with FreeMat. Three variants of C types can be used. You can use structures, enumerations, and aliases (typedefs). All three are defined through a single function ctypedefine. The general syntax for its use is

```
ctypedefine(typeclass,typename,...)
```

where typeclass is the variant of the type (legal values are 'struct', 'alias', 'enum'). The second argument is the name of the C type. The remaining arguments depend on what the class of the typedef is.

To define a C structure, use the 'struct' type class. The usage in this case is:

```
ctypedefine('struct',typename,field1,type1,field2,type2,...)
```

The argument typename must be a valid identifier string. Each of the field arguments is also a valid identifier string that describe in order, the elements of the C structure. The type arguments are typespecs. They can be of three types:

- Built in types, e.g. 'uint8' or 'double' to name a couple of examples.
- C types that have previously been defined with a call to ctypedefine, e.g. 'mytype' where 'mytype' has already been defined through a call to ctypedefine.
- Arrays of either built in types or previously defined C types with the length of the array coded as an integer in square brackets, for example: 'uint8[10]' or 'double[1000]'.

To define a C enumeration, use the 'enum' type class. The usage in this case is: ctypede-fine('enum',typename,name1,value1,name2,value2,...) @] The argument typename must be a valid identifier string. Each of the name arguments must also be valid identifier strings that describe the possible values that the enumeration can take an, and their corresponding integer values. Note that the names should be unique. The behavior of the various cenum functions is undefined if the names are not unique.

To define a C alias (or typedef), use the following form of ctypedefine:

```
ctypedefine('alias',typename,aliased_typename)
```

where aliased_typename is the type that is being aliased to.

29.4 CTYPEFREEZE Convert FreeMat Structure to C Type

29.4.1 Usage

The ctypefreeze function is used to convert a FreeMat structure into a C struct as defined by a C structure typedef. To use the cstructfreeze function, you must first define the type of the C structure using the ctypedefine function. The ctypefreeze function then serializes a FreeMat structure to a set of bytes, and returns it as an array. The usage for ctypefreeze is

```
byte_array = ctypefreeze(mystruct, 'typename')
```

where mystruct is the array we want to 'freeze' to a memory array, and typename is the name of the C type that we want the resulting byte array to conform to.

29.5 CTYPENEW Create New Instance of C Structure

29.5.1 Usage

The ctypenew function is a convenience function for creating a FreeMat structure that corresponds to a C structure. The entire structure is initialized with zeros. This has some negative implications, because if the structure definition uses cenums, they may come out as 'unknown' values if there are no enumerations corresponding to zero. The use of the function is

```
a = ctypenew('typename')
```

which creates a single structure of C structure type 'typename'. To create an array of structures, we can provide a second argument

```
a = ctypenew('typename',count)
```

where count is the number of elements in the structure array.

29.6 CTYPEPRINT Print C Type

29.6.1 Usage

The ctypeprint function prints a C type on the console. The usage is

```
ctypeprint(typename)
```

where typename is a string containing the name of the C type to print. Depending on the class of the C type (e.g., structure, alias or enumeration) the ctypeprint function will dump information about the type definition.

29.7 CTYPEREAD Read a C Structure From File

29.7.1 Usage

The ctyperead function is a convenience function for reading a C structure from a file. This is generally a very bad idea, as direct writing of C structures to files is notoriously unportable. Consider yourself warned. The syntax for this function is

```
a = ctyperead(fid, 'typename')
```

where 'typename' is a string containing the name of the C structure as defined using ctypedefine, and fid is the file handle returned by the fopen command. Note that this form will read a single structure from the file. If you want to read multiple structures into an array, use the following form

```
a = ctyperead(fid, 'typename', count)
```

Note that the way this function works is by using ctypesize to compute the size of the structure, reading that many bytes from the file, and then calling ctypethaw on the resulting buffer. A consequence of this behavior is that the byte-endian corrective behavior of FreeMat does not work.

29.8 CTYPESIZE Compute Size of C Struct

29.8.1 Usage

The ctypesize function is used to compute the size of a C structure that is defined using the ctypedefine function. The usage of ctypesize is

```
size = ctypesize('typename')
```

where typename is the name of the C structure you want to compute the size of. The returned count is measured in bytes. Note that as indicated in the help for ctypedefine that FreeMat does not automatically pad the entries of the structure to match the particulars of your C compiler. Instead, the assumption is that you have adequate padding entries in your structure to align the FreeMat members with the C ones. See ctypedefine for more details. You can also specify an optional count parameter if you want to determine how large multiple structures are

```
size = ctypesize('typename',count)
```

29.9 CTYPETHAW Convert C Struct to FreeMat Structure

29.9.1 Usage

The ctypethaw function is used to convert a C structure that is encoded in a byte array into a FreeMat structure using a C structure typedef. To use the ctypethaw function, you must first define the type of the C structure using the ctypedefine function. The usage of ctypethaw is

```
mystruct = ctypethaw(byte_array, 'typename')
```

where byte_array is a uint8 array containing the bytes that encode the C structure, and typename is a string that contains the type description as registered with ctypedefine. If you want to retrieve multiple structures from a single byte array, you can specify a count as

```
mystruct = ctypethaw(byte_array, 'typename', count)
```

where count is an integer containing the number of structures to retrieve. Sometimes it is also useful to retrieve only part of the structure from a byte array, and then (based on the contents of the structure) retrieve more data. In this case, you can retrieve the residual byte array using the optional second output argument of ctypethaw:

```
[mystruct,byte_array_remaining] = ctypethaw(byte_array, 'typename',...)
```

29.10 CTYPEWRITE Write a C Typedef To File

29.10.1 Usage

The ctypewrite function is a convenience function for writing a C typedef to a file. This is generally a very bad idea, as writing of C typedefs to files is notoriously unportable. Consider yourself warned. The syntax for this function is

```
ctypewrite(fid,a,'typename')
```

where a is the FreeMat typedef to write, 'typename' is a string containing the name of the C typedef to use when writing the typedef to the file (previously defined using ctypedefine), and fid is the file handle returned by fopen.

29.11 IMPORT Foreign Function Import

29.11.1 Usage

The import function allows you to call functions that are compiled into shared libraries, as if they were FreeMat functions. The usage is

import(libraryname,symbol,function,return,arguments)

The argument libraryname is the name of the library (as a string) to import the function from. The second argument symbol (also a string), is the name of the symbol to import from the library. The third argument function is the the name of the function after its been imported into Freemat. The fourth argument is a string that specifies the return type of the function. It can take on one of the following types:

- 'uint8' for an unsigned, 8-bit integer.
- 'int8' for a signed, 8-bit integer.
- 'uint16' an unsigned, 16-bit integer.
- 'int16' a signed, 16-bit integer.
- 'uint32' for an unsigned, 32-bit integer.
- 'int32' for a signed, 32-bit integer.
- 'single' for a 32-bit floating point.
- 'double' for a 64-bit floating point.
- 'void' for no return type.

The fourth argument is more complicated. It encodes the arguments of the imported function using a special syntax. In general, the argument list is a string consisting of entries of the form:

type[optional bounds check] {optional &}name

Here is a list of various scenarios (expressed in 'C'), and the corresponding entries, along with snippets of code.

Scalar variable passed by value: Suppose a function is defined in the library as

```
int fooFunction(float t),
```

i.e., it takes a scalar value (or a string) that is passed by value. Then the corresponding argument string would be

```
'float t'
```

For a C-string, which corresponds to a function prototype of

```
int fooFunction(const char *t),
```

the corresponding argument string would be

```
'string t'
```

Other types are as listed above. Note that FreeMat will automatically promote the type of scalar variables to the type expected by the C function. For example, if we call a function expecting a float with a double or int16 argument, then FreeMat will automatically apply type promotion rules prior to calling the function.

Scalar variable passed by reference: Suppose a function is defined in the library as

```
int fooFunction(float *t),
```

i.e., it takes a scalar value (or a string) that is passed as a pointer. Then the corresponding argument string would be

```
'float &t'
```

If the function fooFunction modifies t, then the argument passed in FreeMat will also be modified. Array variable passed by value: In C, it is impossible to distinguish an array being passed from a simple pointer being passed. More often than not, another argument indicates the length of the array. FreeMat has the ability to perform bounds-checking on array values. For example, suppose we have a function of the form

```
int sum_onehundred_ints(int *t),
```

where sum_onehundred_ints assumes that t is a length 100 vector. Then the corresponding FreeMat argument is

```
'float32[100] t'.
```

Note that because the argument is marked as not being passed by reference, that if $sub_onehundred_ints$ modifies the array t, this will not affect the FreeMat argument. Note that the bounds-check expression can be any legal scalar expression that evaluates to an integer, and can be a function of the arguments. For example to pass a square $N \times N$ matrix to the following function:

```
float determinantmatrix(int N, float *A),
```

we can use the following argument to import:

```
'int32 N, float[N*N] t'.
```

Array variable passed by reference: If the function in C modifies an array, and we wish this to be reflected in the FreeMat side, we must pass that argument by reference. Hence, consider the following hypothetical function that squares the elements of an array (functionally equivalent to x.²):

```
void squarearray(int N, float *A)
```

we can use the following argument to import:

```
'int32 N, float[N] &A'.
```

Note that to avoid problems with memory allocation, external functions are not allowed to return pointers. As a result, as a general operating mechanism, the FreeMat code must allocate the proper arrays, and then pass them by reference to the external function.

Sending text to the FreeMat console: Starting with FreeMat 4.0, it is possible for external code that is called using the import statement to send text to the FreeMat console. To do so, you must define in each library that wants to send text a function with the name freemat_io_handler that captures its argument (a function pointer), and stores it for use by functions in the library. That function pointer takes a standard C string argument. Here is a snippet of code to demonstrate how this works:

```
/* just to make it readable */
typedef void (*strfunc)(const char*);

/* The name we want to use for the function */
strfunc FreeMatText;

/* this name is case sensitive and must not be mangled (i.e., use extern "C") */
void freemat_io_handler(strfunc printFunc) {
   FreeMatText = printFunc;
}

double SomeImportedFunction(double t) {
   FreeMatText("I am going to double that argument!\n");
   return (t*2);
}
```

In this case, once SomeImportedFunction is called from within FreeMat, the text "I am going to double that argument" will appear in the FreeMat console.

Your freemat_io_handler function is automatically called when your library is loaded by FreeMat, which happens with the first import statement that references it.

29.11.2 Example

Here is a complete example. We have a C function that adds two float vectors of the same length, and stores the result in a third array that is modified by the function. First, the C code:

```
--> if ("strcmp(computer, MAC')) system('gcc -shared -fPIC -o add.so addArrays.c'); end;
--> import('add.so', 'addArrays', 'addArrays', 'void', 'int32 N, float[N] a, float[N] b, float
--> a = [3,2,3,1];
--> b = [5,6,0,2];
--> c = [0,0,0,0];
--> addArrays(length(a),a,b,c)

ans =

[]
--> c

ans =
```

29.12 LOADLIB Load Library Function

29.12.1 Usage

8 8 3 3

The loadlib function allows a function in an external library to be added to FreeMat dynamically. This interface is generally to be used as last resort, as the form of the function being called is assumed to match the internal implementation. In short, this is not the interface mechanism of choice. For all but very complicated functions, the import function is the preferred approach. Thus, only a very brief summary of it is presented here. The syntax for loadlib is

```
loadlib(libfile, symbolname, functionname, nargin, nargout)
```

where libfile is the complete path to the library to use, symbolname is the name of the symbol in the library, functionname is the name of the function after it is imported into FreeMat (this is optional, it defaults to the symbolname), nargin is the number of input arguments (defaults to 0), and nargout is the number of output arguments (defaults to 0). If the number of (input or output) arguments is variable then set the corresponding argument to -1.