

SOURISH GHOSH

<i>address:</i> CD-406, LBS Hall IIT Kharagpur, Kharagpur, WB 721302 INDIA	<i>web:</i> http://sourishghosh.com <i>email:</i> ragnarok0211@gmail.com <i>phone:</i> +91 8902234618 <i>GitHub:</i> sourishg	<i>Languages and Tools:</i> C++, Python, Java, OpenCV, ROS, Qt, OpenGL, TensorFlow, Keras, PyBullet, CVXPY, ACADO, Eigen
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EDUCATION

Indian Institute of Technology, Kharagpur	July, 2014 - April, 2019 (<i>expected</i>)	Integrated M.Sc. <i>Department:</i> Mathematics <i>Major:</i> Mathematics and Computing
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PUBLICATIONS

- [4] **Probabilistic Kinematic State Estimation for Motion Planning of Planetary Rovers**
by Sourish Ghosh, Kyohei Otsu, and Masahiro Ono
In *Intelligent Robots and Systems, IROS, 2018 IEEE/RSJ International Conference*, (Madrid, Spain)
Oct. 2018. [[PDF](#)]
- [3] **Fast Approximate Clearance Evaluation for Kinematically Constrained Articulated Suspension Systems**
by Kyohei Otsu, Guillaume Matheron, Sourish Ghosh, Olivier Toupet, and Masahiro Ono
arXiv preprint arXiv:1808.00031. [[PDF](#)]
- [2] **Joint Perception And Planning For Efficient Obstacle Avoidance Using Stereo Vision**
by Sourish Ghosh and Joydeep Biswas.
In *Intelligent Robots and Systems, IROS, 2017 IEEE/RSJ International Conference*, (Vancouver, Canada)
Sep. 2017. [[PDF](#)]
- [1] **A Fuzzy Logic System to Analyze a Student's Lifestyle**
by Sourish Ghosh et al.
In *2017 9th International Conference on Advanced Computational Intelligence, ICACI*, (Doha, Qatar)
Feb. 2017. [[PDF](#)]
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EXPERIENCE

- Princeton University**, Princeton, NJ June, 2018 - August, 2018
Summer Intern, IROm Lab
Topic: Learning Data-Driven Dynamic Models of Task-Relevant Perceptual Features for Robot Controllers
Research Areas: control theory, deep learning, variational autoencoders, model-predictive control
Adviser: [Dr. Anirudha Majumdar](#)
- Cognitive Robotics Summer School**, Massachusetts Institute of Technology July, 2018
Attended a week long workshop based on the following themes: robust execution, motion planning, activity planner, perception and manipulation, and planning under uncertainty and risk. The workshop (for 62 selected attendees) consisted of guest lectures, labs, and a grand challenge.
Organizer: MIT MERS Group
- NASA Jet Propulsion Laboratory**, Pasadena, CA May, 2017 - July, 2017
Summer Intern, 347E - Robotic Systems Estimation, Decision, and Control Group
Topic: Probabilistic Kinematic State Estimation for Motion Planning of Planetary Rovers
Research Areas: probabilistic state estimation, risk-aware motion planning
Adviser: [Dr. Masahiro Ono](#)
- University of Massachusetts**, Amherst, MA May, 2016 - August, 2016
Summer Intern, Autonomous Mobile Robotics Lab
Topic: Joint Perception and Planning for Efficient Obstacle Avoidance using Stereo Vision
Research Areas: obstacle avoidance, stereo vision, motion planning
Adviser: [Dr. Joydeep Biswas](#)

Aerial Robotics Kharagpur (ARK), IIT KharagpurFebruary, 2017 - *present*

Software Team Member

Topic: (1) Building unmanned emergency aerial vehicles to drop medical supplies in less accessible regions of rural India. (2) Controlling drones using the electrical activity (EEG) in human brain.

Research Areas: localization and mapping, motion planning, control theory

Kharagpur RoboSoccer Students' Group (KRSSG), IIT Kharagpur

February, 2015 - April, 2016

Software Team Member

Topic: Motion planning algorithms for multi-agent soccer playing robot systems.

Research Areas: multi-agent robot systems, robot soccer, motion planning

SELECTED PROJECTS

Stereo Dense 3D Reconstruction Tool

This is a ROS package for real-time 3D reconstruction from stereo images. It uses LIBELAS for generating dense disparity maps. It also has a tool for transforming point clouds in different reference frames.

Repository: https://github.com/umass-amrl/stereo_dense_reconstruction

JPP

C++/ROS implementation of the paper: Joint Perception And Planning For Efficient Obstacle Avoidance Using Stereo Vision

Repository: <https://github.com/umass-amrl/jpp>

RRT Simulator

An interactive GUI application for visualizing the RRT algorithm for motion planning.

Repository: <https://github.com/sourishg/rrt-simulator>

Stereo Camera Calibration Tools

Tool for the calibration of monocular and stereo cameras using the checker-board method for both pinhole and fisheye model lenses.

Pinhole Model: <https://github.com/sourishg/stereo-calibration>

Fisheye Model: <https://github.com/sourishg/fisheye-stereo-calibration>

Generating Disparity Maps

Implementation of various methods to compute disparity maps.

Repository: <https://github.com/sourishg/disparity-map>

Eye Tracker Gaze Analyzer

A Visual C++ application to analyze a user's gaze response on different images displayed on a computer screen using the Tobii Eye Tracker.

Repository: <https://github.com/sourishg/tobii-eye-tracker>

RESPONSIBILITIES

Technology Robotix Society, IIT Kharagpur*Governor*

July, 2017 - April, 2018

I led a three-tier team to successful planning and execution of all the year-long activities of the society which includes organizing the annual Robotix fest, conducting seminars and workshops for students at IIT Kharagpur and other colleges in India, and initiating new research projects in robotics.

Kharagpur Winter of Code (KWOC) 2017, IIT Kharagpur

December, 2017

Mentor

I mentored 4 students in KWOC (organized by *Kharagpur Open Source Society*) which is a 5-week long GSoC-styled programme for students who are new to open source software development.

Project: <https://github.com/sourishg/stereo-calibration>

IEEE Robotics Winter Workshop, IIT Kharagpur

December, 2015

Mentor

I conducted a week-long workshop for first and second year undergraduates at IIT Kharagpur. I taught basic image processing using OpenCV and C++, and micro-controller programming using an Arduino UNO board. As a final project of the workshop I helped the students build a simple object tracking differential drive robot.

AWARDS AND ACHIEVEMENTS

IROS Travel Award

October, 2018

Received the IROS Student and Developing Countries (SDC) Travel Award for my publication at IROS 2018.

INSPIRE Scholarship

July, 2014 - *present*

A prestigious scholarship awarded by the Government of India to the top 0.07% students who appeared for the JEE Advanced 2014 examination in India, and pursuing a degree in Science.

Caltech SURF Award

May, 2017 - July, 2017

Awarded the prestigious Caltech SURF fellowship for doing a summer internship on probabilistic motion planning for Mars Rovers at NASA JPL.

Best Term Project, Soft Computing Course

Spring, 2016

Designed a mobile application that tracks the daily lifestyle of a person. Peer reviewed as the best project.

Bronze at MiroSot, FIRA

July, 2015

MiroSot is an international five-a-side robot soccer tournament. I was a part of the bronze-winning team of IIT Kharagpur.

Best Fresher, HackerEarth Freshers' Challenge, IIT Kharagpur

October, 2014

Finished first amongst all first years in an ACM-ICPC style coding contest organised by HackerEarth.

MEDIA COVERAGE

[Princeton University News](#)

August, 2018

My work at Princeton University was featured as part of a story about the International Summer Internship Program.

[Internshala Blog](#)

September, 2017

My summer internship story at NASA JPL was covered by Internshala, India's largest portal for student internships.

TECHNICAL WRITING

[Stereo calibration using C++ and OpenCV](#)

September, 2016

15k pageviews. Average time on page: 4 min.
