Sourish Ghosh

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EDUCATION

IIT Kharagpur,

Indian Institute of Technology, July, 2014 - April, 2019 (expected) Integrated M.Sc.

Kharagpur Department: Mathematics

Major: Mathematics and Computing

CGPA: 8.50/10

Garden High School, Kolkata April, 2012 - February, 2014 Indian School Certificate Board

Aggregate: 94%

Publications

Joint Perception And Planning For Efficient Obstacle Avoidance Using Stereo Vision

by Sourish Ghosh and Joydeep Biswas.

In Intelligent Robots and Systems, IROS, 2017 IEEE/RSJ International Conference, (Vancouver, Canada) Sep. 2017. To appear.

A Fuzzy Logic System to Analyze a Student's Lifestyle

by Sourish Ghosh et al.

In 2017 9th International Conference on Advanced Computational Intelligence, ICACI, (Doha, Qatar)

Feb. 2017. [PDF]

RESEARCH EXPERIENCE

NASA Jet Propulsion Laboratory

May, 2017 - July, 2017

Summer Intern, 347E - Robotic Systems Estimation, Decision, and Control Group

Topic: Risk-aware Probabilistic Motion Planning for Mars Rovers

Research Areas: mobile robotics, probabilistic state estimation, motion planning

Advisor: Dr. Masahiro Ono

University of Massachusetts Amherst

May, 2016 - August, 2016

Summer Intern, Autonomous Mobile Robotics Lab

Topic: Joint Perception and Planning for Efficient Obstacle Avoidance using Stereo Vision

Research Areas: mobile robotics, stereo vision, navigation planning

Advisor: Dr. Joydeep Biswas

Aerial Robotics, IIT Kharagpur

February, 2017 - present

Software Team Member

Currently developing the software architecture to participate in IARC~2017. Also, working on active localization of ground robots on a grid-based arena using a downward facing camera from a micro aerial vehicle.

Research Areas: indoor localization, strategy planning

Kharagpur RoboSoccer Students' Group, IIT Kharagpur

February, 2015 - April, 2016

Software Team Member

Implemented motion planning algorithms for RoboCup Small Sized League and MiroSot, FIRA. Bronze winning team member at MiroSot, FIRA 2015.

Research Areas: multi-agent robot systems, robot soccer, motion planning

RESPONSIBILITIES

Technology Robotix Society, IIT Kharagpur

Governor July, 2017 - present

I am leading a three-tier team to successful planning and execution of all the year-long activities of the society which include organizing the annual Robotix fest, conducting seminars and workshops for students at IIT Kharagpur and other colleges in India, and initiating new research projects in robotics.

Head February, 2016 - January, 2017

I was responsible for designing a computer vision event which was held at *Kshitij 2017*, Asia's largest technomanagement fest. I helped conduct technical workshops across India to spread the culture of robotics. Also I organized weekly lectures on autonomous robotics for over 300 students round the year along with workshops and hackathons in my college.

IEEE Robotics Winter Workshop, IIT Kharagpur

December, 2015

Image Processing Mentor

I conducted a week-long workshop for first and second year undergraduates at IIT Kharagpur. I taught basic image processing using OpenCV and C++, and micro-controller programming using an Arduino UNO board. As a final project of the workshop I helped the students build a simple object tracking differential drive robot.

PROJECTS

Stereo Dense 3D Reconstruction Tool

This is a ROS package for real-time 3D reconstruction from stereo images. Currently this version uses LIBELAS for generating dense disparity maps as a baseline. It also has a nice tool for transforming point clouds in different reference frames.

Repository: https://github.com/sourishg/stereo-dense-reconstruction

RRT Simulator

Developed an interactive GUI interface to simulate a path generated by RRTs avoiding obstacles using C++ and Qt.

Repository: https://github.com/sourishg/rrt-simulator

Stereo Camera Calibration Tools

Developed some tools for the calibration of stereo cameras using the checker-board method using C++ and OpenCV for both pinhole model and fisheye model lenses.

Pinhole Model: https://github.com/sourishg/stereo-calibration

 $\it Fisheye \ Model: \ https://github.com/sourishg/fisheye-stereo-calibration$

Soft Computing Term Project

Developed an Android application that determines the lifestyle of a person. A fuzzy logic based approach was used to generate an analysis of how a person spends his/her day based on his/her phone's GPS data and how much time he/she spent at a particular location. Peer reviewed to be the best term project for Spring 2016.

Advisor: Dr. Sudhir Kumar Barai

Repository: https://github.com/nishnik/YOLO

code.fun.do, Mircrosoft Hackathon

Developed a mobile game for Windows Phone using C# and XAML. The idea of the game is to stop incoming missiles by tapping on them, before they reach their target.

Repository: https://github.com/sourishg/saving-private-ryan

AWARDS AND ACHIEVEMENTS

Caltech SURF Award Recipient

May, 2017 - July, 2017

Awarded the prestigious Caltech SURF fellowship for doing a summer internship on probabilistic motion planning for Mars Rovers at NASA JPL.

INSPIRE Scholarship Recipient

July, 2014 - present

A prestigious scholarship awarded by the Government of India to the top 0.07% students who appeared for the JEE Advanced examination in India, and pursuing a career in Science.

MiroSot, FIRA

July, 2015

MiroSot is an international five-a-side robot soccer tournament. I was a part of the bronze-winning team of IIT Kharagpur.

Best Term Project, Soft Computing Course

Spring, 2016

Designed a mobile application that tracks the daily lifestyle of a person. Peer reviewed as the best project.

SudoCode, Kshitij 2015

January, 2015

Participated in an online coding competition at *Kshitij 2015*, Asia's largest techno-management fest. Awarded the best fresher at IIT Kharagpur.

Best Fresher, HackerEearth Freshers' Challenge, IIT Kharagpur

October, 2014

Finished first amongst all first years in an ACM-ICPC style coding contest organised by HackerEarth.

Inter IIT Sports Meet

December, 2014

Represented IIT Kharagpur in table tennis and secured the bronze medal.

Table Tennis State Championship, West Bengal

November, 2010

Member of South 24 PGS District silver winning table tennis team.

SKILLS

Programming

C, C++, Java, Python, LATEX

Libraries and Tools

OpenCV, ROS, Qt, GNU Octave, AndroidSDK