SOURISH GHOSH

address (office):
2103 Newell-Simon Hall
Hamerschlag Dr
Pittsburgh, PA 15213

web: http://sourishghosh.com
email: sourishg@cmu.edu
GitHub: sourishg
Google Scholar: 45-8VtAAAAAJ

Languages and Tools:
C/C++, Python, OpenCV, ROS,
TensorFlow, Pytorch,
AirSim, Gazebo, Docker

EDUCATION

Carnegie Mellon University — August, 2019 - May, 2022 — **M.S.** in Robotics
Department: Robotics Institute
GPA: 4.11/4.0

Indian Institute of Technology (IIT), Kharagpur — July, 2014 - April, 2019 — **Integrated M.Sc.**
Department: Mathematics
Major: Mathematics and Computing
GPA: 8.5/10

EXPERIENCE

Apple Inc. | Computer Vision Intern — May, 2021 - Aug, 2021
Topic: 3D Object Pose Tracking with Transformers
Research Areas: transformers, detection and tracking, temporal modeling

Carnegie Mellon University | M.S. in Robotics, AirLab — *Adviser*: Prof. Sebastian Scherer | Aug, 2019 - May, 2022
Topic: Vision-based Aircraft Detection and Tracking for Detect-and-Avoid
Research Areas: small object detection, object tracking, deep learning

Princeton University | Summer Intern, IRoM Lab — *Adviser*: Prof. Anirudha Majumdar | June - Aug, 2018
Topic: Learning Data-Driven Dynamic Models of Task-Relevant Perceptual Features for Robot Controllers
Research Areas: control theory, deep learning, variational autoencoders, model-predictive control

NASA Jet Propulsion Laboratory | Summer Intern, Group 347E — *Adviser*: Dr. Masahiro Ono | May - July, 2017
Topic: Probabilistic Kinematic State Estimation for Motion Planning of Planetary Rovers
Research Areas: probabilistic state estimation, risk-aware motion planning

University of Massachusetts Amherst | Summer Intern, AMRL — *Adviser*: Prof. Joydeep Biswas | May - Aug, 2016
Topic: Joint Perception and Planning for Efficient Obstacle Avoidance using Stereo Vision
Research Areas: obstacle avoidance, stereo vision, motion planning

Aerial Robotics Lab, Kharagpur | Software Team Member — *Adviser*: Prof. Somesh Kumar | Feb, 2017 - Apr, 2019
Topic: Building unmanned emergency aerial vehicles to drop medical supplies in less accessible regions of rural India.
Research Areas: localization and mapping, motion planning, control theory

SELECTED PUBLICATIONS

[4] **MAARS: Machine learning-based Analytics for Automated Rover Systems**
by Masahiro Ono, Brandon Rothrock, . . . , Sourish Ghosh, . . . , Hyoshin Park
In *2020 IEEE Aerospace Conference*. Mar 2020. [PDF]

[3] **Probabilistic Kinematic State Estimation for Motion Planning of Planetary Rovers**
by Sourish Ghosh, Kyohei Otsu, and Masahiro Ono
In *Intelligent Robots and Systems, IROS, 2018 IEEE/RSJ International Conference*, (Madrid, Spain). Oct 2018. [PDF]

[2] **Fast Approximate Clearance Evaluation for Rovers with Articulated Suspension Systems**
by Kyohei Otsu, Guillaume Matheron, Sourish Ghosh, Olivier Toupet, and Masahiro Ono
In *Journal of Field Robotics*. July 2019. [PDF]

[1] **Joint Perception And Planning For Efficient Obstacle Avoidance Using Stereo Vision**
by Sourish Ghosh and Joydeep Biswas.
In *Intelligent Robots and Systems, IROS, 2017 IEEE/RSJ International Conference*, (Vancouver, Canada). Sep 2017. [PDF]

SELECTED OPEN-SOURCED PROJECTS

Stereo Dense 3D Reconstruction Tool
3D reconstruction using ELAS. [CODE]

JPP
C++ implementation of [1]. [CODE]

RRT Simulator
Visualizing RRTs. [CODE]

PyBullet Turntable Controller
Task-relevant features for MPC. [CODE]

Generating Disparity Maps
Algorithms for disparity maps. [CODE]

Stereo Camera Calibration Tools
[PINHOLE] [FISHEYE] [BLOG]