Q-1.1.1

The gaussian filter smoothens the image and allows to pick the overall behavior of the pixels in a region.

The laplacian of gaussian picks up the edges in the image.

Derivative of gaussian in x picks up vertical lines in the image.

Derivative of gaussian in y picks up horizontal lines on the image.

Multiple filter scales allows us to pick features from a small or large area, hence providing a better way to comprehend the image.

Q-1.1.2

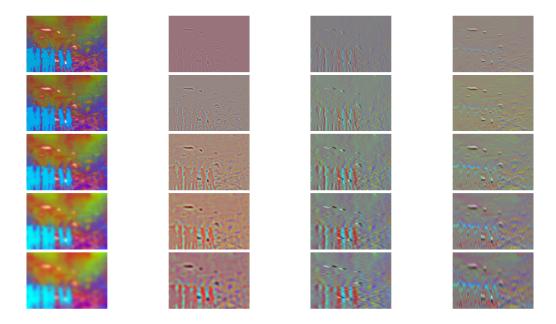


Image: aquarium/sun_aztvjgubyrgvirup.jpg Scale: [1,2,4,6,8]

```
def compute_dictionary_one_image(args):
    '''
    Extracts a random subset of filter responses of an image and save it
to disk
    This is a worker function called by compute_dictionary

Your are free to make your own interface based on how you implement
compute_dictionary
    '''
    image_path, alpha, opts, idx = args
    # print(args)
    img = Image.open(image_path)
    img = np.array(img).astype(np.float32)/255
    filter_response = extract_filter_responses(opts, img)
    x = np.random.choice(filter_response.shape[0], alpha, replace=False)
    y = np.random.choice(filter_response.shape[1], alpha, replace=False)
    pixel_response = filter_response[x,y,:]
    print("(~ ",idx," ~)")
    tmp_dir = '../tmp'
    if not os.path.exists(tmp_dir):
        os.makedirs(tmp_dir)
    np.savetxt(os.path.join(tmp_dir, str(idx) + ".csv"), pixel_response,
delimiter="," )
```

```
[saved]
   data dir = opts.data dir
   feat dir = opts.feat dir
   out dir = opts.out dir
   K = opts.K
   alpha = opts.alpha
    train files = open(join(data dir,
'train files.txt')).read().splitlines()
   image path = ["../data/" + x for x in train files]
   pool = multiprocessing.Pool(processes=n worker)
   args = zip(image path, [alpha]*len(image path),
[opts]*len(image path), range(len(image path)))
   pool.map(compute dictionary one image, args)
   tmp files = listdir("../tmp")
   pixel response path = ["../tmp/" + x for x in tmp files]
   file0=pixel response path[0]
   arr1=np.loadtxt(file0, delimiter=",")
   channel = arr1.shape[1]
   pixel response master = np.empty([0,channel])
   for file in pixel response path:
       pixel response = np.loadtxt(file, delimiter=",")
       pixel response master=np.concatenate((pixel response master,
pixel response), axis=0)
```

```
start = timer()
kmeans =
sklearn.cluster.KMeans(n_clusters=opts.K).fit(pixel_response_master)
centroids = kmeans.cluster_centers_
np.save("dictionary.npy", centroids)
```



The "word" boundaries do make sense. The regions with the same color mean that they map to the same word in the dictionary. Also, regions with the same color mean that they have similar properties, like color(actual), texture, etc.

```
def get feature from wordmap SPM(opts, wordmap):
   * hist all: numpy.ndarray of shape (K*(4^L-1)/3)
   K = opts.K
   L = opts.L
   hist all = []
       num tile=2**1
       cols = np.array split(wordmap, num tile, axis=1)
       for i in range(len(cols)):
           rows=np.array_split(cols[i], num_tile, axis=0)
               tile = rows[j]
               hist = get feature from wordmap(opts, tile)
               if l==0 | l==1:
                   weight =1
                   weight = 2**(-1)
               hist weighted = hist*weight
               hist all = np.append(hist all, hist weighted, axis=0)
   hist all = hist all/np.sum(hist all)
```

```
def build recognition system(opts, n worker=1):
   Creates a trained recognition system by generating training features
from all training images.
   * opts
   [saved]
   * SPM layer num: number of spatial pyramid layers
   data dir = opts.data dir
   out dir = opts.out dir
   SPM layer num = opts.L
   K=opts.K
   L=opts.L
   train files = open(join(data dir,
'train files.txt')).read().splitlines()
   train labels = np.loadtxt(join(data dir, 'train labels.txt'),
np.int32)
   dictionary = np.load(join(out dir, 'dictionary.npy'))
   features=np.empty([0, int(K*((4**L)-1)/3)])
   for i in range(len(train files)):
       img path=join(opts.data dir, train files[i])
       img features = get image feature(opts, img path, dictionary)
       img features = np.asarray(img features)
       img features = np.reshape(img features, (1, int(K*((4**L)-1)/3)))
       features = np.concatenate((features, img features), axis=0)
       print("Train File: ", i)
```

Q-2.5

Overall accuracy = 66.25%

Filter scale: [1,2,4]

K: 50 Alpha: 25

L: 3

Confusion matrix:

```
[[42.
                2.
                         0.
                              1.
                                  3.]
       0.
                     2.
 [ 1. 28.
            6.
                5.
                     4.
                         0.
                              2.
                                  4.]
       5. 26.
                0.
                     0.
                              3. 10.]
                         4.
 [ 0.
       0.
            0.39.10.
                         0.
                              0.
                                  1.]
 Ī 1.
       2.
            2. 10. 30.
                         2.
                              3.
                                  0.]
 [ 2.
                              1.
                1.
                     1. 38.
                                  4.]
       0.
            3.
 [ 6.
                1.
                     5.
                         4. 30.
       1.
            1.
                                   2.]
                2.
                              2. 32.]]
                     1.
```

Q-2.6

We see a great error on columns/rows 3 and 4. These columns correspond to kitchen and laundromat respectively. They are misclassified because both the categories have similar features. They have similar furniture, indoor, and floor texture.

Another instance of high error is seen at row 2 and column 7, these correspond to highway and windmill images. They too have similar features, such as open areas, trees, sky.

These similarities make the classification difficult.

Q-3.1

Filter scale: [1,2,4,6,8]

K: 50 Alpha: 25 L: 4

Accuracy: 65.5%

Filter scale: [1,2,4]

K: 50 Alpha: 25 L: 4

Accuracy: 65.5%

Filter scale: [1,2,4]

K: 100 Alpha: 25

L: 4

Accuracy: 64.0%