

Robust Estimators

Gauss-Newton \rightarrow minimize function with in the sum of the function (usually, \mathcal{L}_2 -norm) this is on subject matter

$$e^{[i]}(x) = e^{[i]}(x)^T \mathcal{J}^{[i]} e^{[i]}(x)$$

Most times

Over \mathcal{L}_2 norm $\rightarrow \|e^{[i]}(x)\|_{\mathcal{L}_2}^2$

\mathcal{L}_2 not change in the optimization

$\mathcal{L}_2 \rightarrow LL^T$ \hookrightarrow Cholesky decomposition

\downarrow
positive definite

$v' = L^T \cdot v$ \rightarrow Why? ... optimal comparison?

\mathcal{L}_1 -norm \rightarrow squared-root of \mathcal{L}_2 -norm \rightarrow grows quadratically w/ length of the error
(\equiv euclidean distance)

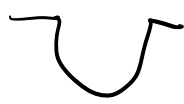
\Downarrow
errors will push away the optimal solution quadratically
 \hookrightarrow \mathcal{L}_2 over weight correction of the solution
they are few but 99 errors...

μ estimator / robust estimator \Rightarrow having a good enough INITIAL GUESS

minimize $F(x) = \sum_i \rho(\underbrace{\|e^{[i]}(x)\|_{\mathcal{L}_2}}_{\mu^{[i]}(x) \equiv \mathcal{L}_1\text{-norm}})$

ρ robustifier \rightarrow monotonically increasing of \mathcal{L}_1 -norm

if $\rho(u) = u^2 \Rightarrow \mu^{[i]}(x)^2 \equiv$ THAT'S THE
Gauss-Newton


 otherwise - if you do by, not the control the model...

$$\begin{aligned}
 e^{[i]}(x) &= e^{[i]}(x)^T \Omega^{[i]} e^{[i]}(x) \\
 &= \|e^{[i]}(x)\|_{\Omega^{[i]}}^2
 \end{aligned}$$

$$\frac{\partial \|e\|_{\Omega}^2}{\partial x} = \frac{\partial e^T}{\partial x} \Omega e(x) + e^T \Omega \frac{\partial e}{\partial x}$$

$$= e^T \underbrace{\Omega^T}_{\Omega} \frac{\partial e}{\partial x} + e^T \Omega \frac{\partial e}{\partial x}$$

$$= \underline{2 e^T \Omega \frac{\partial e}{\partial x}}$$

$$\frac{\partial \sqrt{\|e\|_{\Omega}^2}}{\partial x} = \frac{1}{2} \cdot \frac{\partial \|e\|_{\Omega}^2}{\partial x} \cdot \frac{1}{\sqrt{\|e\|_{\Omega}^2}} = \frac{1}{2 \|e\|_{\Omega}} \cdot \frac{\partial \|e\|_{\Omega}^2}{\partial x}$$

$$u^m = m \cdot u^{m-1}$$

$u(x)$ → solution

chain rule!

$$\frac{\partial \rho(u(x))}{\partial x} = \frac{\partial \rho(u)}{\partial u} \bigg|_{u=u(x)} \cdot \frac{\partial u}{\partial x}$$

$\frac{\partial u}{\partial x}$ → L2-norm

$$\frac{\partial \rho(u)}{\partial u} \cdot \frac{1}{u(x)} \cdot \frac{\partial \|e\|_{\Omega}^2}{\partial x}$$

$$\delta(x) = \frac{\partial \rho(u)}{\partial u} \bigg|_{u=u(x)} \cdot \frac{1}{u(x)}$$

impossible "all the ugly things" that multiply the derivatives of L2-norm

$\partial \ell \rightarrow J$ is a number

~~vs~~

$\frac{\partial \ell}{\partial x}$

> look similar

J compute it once it takes
and use it in the next one



assume it takes

Tutorial No-Weighted Least-Squares

reach down & up
the information matrix
to minimize the
error

J can be derived into R



only - that

apply this trick to get rid of the outliers



Robust Gauss-Newton

Example: apply identifier to detect FOP