

# Souvik Datta

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## EDUCATION

**Vellore Institute of Technology**

Bachelor of Technology in **Electrical and Electronics Engineering**, CGPA: (8.43/10)

**Chennai, India**

July 2019 – May 2023

## WORK EXPERIENCE

**UAV Project Intern** | Supervisor: Mr. Irnanda Setiawan

Dec 2022 – Feb 2023

**PT Kaltim Prima Coal (KPC)**

Sangatta, Indonesia

- Spearheaded an entire UAV operation for inspecting 70kV Transmission Lines, **increasing revenue by \$1.26 mn.**
- Optimized **total efficiency by 43%** by planning the flight route and identifying critical bottlenecks for inspection.
- **Leading a team of 7** engineers, efficiently managing and coordinating their efforts to meet project deliverables.

**Deep Learning Research Assistant** | Supervisor: [Dr. Subbulekshmi D](#)

May 2022 – Nov 2022

**Vellore Institute of Technology**

Chennai, India

- Worked on Deep Learning models for Brain Tumour & Skin Cancer Segmentation using **Vision Transformers**.
- Developed a **U-Net** based **Neural Network Architecture** for a brain tumor-based Image Segmentation model.
- Presented an abstract on **GNN-based “Semi-Supervised Learning for Autonomous Navigation”** at **ICDAC, 2022**.

**Computer Vision Intern** | Supervisor: Mr. Shivankit Arun

Jan 2022 – Jul 2022

**Omnipresent Robot Technologies**

New Delhi, India

- Programmed custom **YOLOv5** object detection model over 6 classes for drone analytics with a **93%** accuracy.
- Deployed a **Mask R-CNN** Model for hyperbola detection with an accuracy of over **94%** on a MALA GPR.
- Developed Python scripts with **Geocoding APIs** and **Folium**, increasing effective data visualization by **14%**.
- Optimized **Deep Learning** Models by **37%** for scene-change detection in **remote sensing** applications.
- Implemented **k-means Learning Algorithm** and improved change detection on multi-spectral images by 54%.

**Project Assistant** | Supervisor: [Dr. Sriramalakshmi P](#)

Apr 2022 – Jun 2022

**Vellore Institute of Technology**

Chennai, India

- Extensively used **MATLAB/Simulink** on Tidal Energy Conversion Modules for Power Generation applications.
- Achieved an Output Voltage of **118V** against an Input of **120V**, yielding an **Overall Efficiency** of **98.33%**.
- Tested **Fast Fourier Transform** Analysis and attained a very low **Total Harmonic Distortion** of **0.26%**.

**Research Intern** | Supervisor: [Dr. Chinmaya K.A.](#)

Mar 2021 – Aug 2021

**Indian Institute of Technology, BHU**

Varanasi, India

- Designed a Closed-Loop Converter with **PI Controller** having **16%** more transient stability against disturbances.

## PROJECTS

**Jet Engine Health Prediction** | *Pandas, scikit-learn* | [\[CODE\]](#)

| Machine Learning

- Predicted **Remaining Useful Life (RUL)** for turbofan jet engines using a **Random Forest** Classifier Model.
- Performed **Exploratory Data Analysis** on NASA's Dataset and analyzed feature correlation using **Seaborn**.
- Applied hyperparameter optimization using **Randomized Search CV** and increased **F1-Score** to an overall **91.2%**.

**State Estimation using Kalman Filter** | *Numpy, Matplotlib* | [\[CODE\]](#)

| Kalman Filter

- Developed Kalman Filter-based state estimation model for precise approximation & visualization of a robot's state.
- Attained an extremely low **Mean Square Error** of **2.8%** & **1.1%** for the robot's position & velocity on evaluation.

**Semantic Segmentation on Satellite Images** | *TensorFlow, OpenCV, Keras* | [\[CODE\]](#)

| Deep Learning

- Devised a **U-Net**-based Image Segmentation Model for land cover analysis on 5 classes from LandCover Dataset.
- Developed a network based on the **ResNet34** Architecture & achieved a mean Intersection over Union (IoU) of **72%**.

**RF-Learning Robot** | *PyTorch, Pybullet, Gym-OpenAI* | [\[CODE\]](#)

| Reinforcement Learning

- Programmed a quadruped robot to exhibit walking gait using **PyTorch**-based **Reinforcement Learning** model.
- Optimized learning rate & other hyperparameters to marginally improve the **Mean Reward** of the model by **14%**.

**Soil Type Recognition** | *OpenCV, TensorFlow, Keras* | [\[CODE\]](#)

| Computer Vision

- Designed a classification model with **5 classes** and **98% testing accuracy** using a Convolutional Neural Network.
- Applied Data Augmentation & reduced **validation losses** by **23%** on implementing **MobileNetV2 Architecture**.

**3D Point Cloud from Depth Map** | *Open3D, Keras, OpenCV* | [\[CODE\]](#)

| Computer Vision

- Produced 3D point cloud data maps from 2D monocular RGB image-based depth maps using **Open3D functions**.
- Exploited a **PointNet**-based Object Detection model to classify 3D point cloud data with **81% training accuracy**.

**IoT Book Bot** | *Arduino, OpenCV, Raspberry Pi* | [\[CODE\]](#)

| Robotics

- Engineered a mobile robot using **Raspberry Pi**, **Arduino** and **esp8266** for IoT Navigation and Object Detection.
- Implemented a 2D object detection model on **MS COCO** classes and a **QR-Code** and **Barcode** decryption script.

## SKILLS

- **Languages:** Python, MATLAB/Simulink, GNU Octave, LaTeX
- **Libraries:** Numpy, Matplotlib, Pandas, OpenCV, scikit-learn, TensorFlow, Keras, PyTorch
- **Technical:** CARLA, Proteus, LT-Spice, Fritzing
- **Environment:** Git/GitHub, Raspbian OS
- **Hardware Boards:** Arduino, Raspberry Pi, esp8266

## PUBLICATIONS

- [1] **S. Datta**, M. Kundu, R. D. Choudhury, S. P. and S. VT, “**IoT Book Bot**”, 2022 *IEEE India Council International Subsections Conference (INDISCON)*, 2022, pp. 1-6. | [\[Certificate\]](#) | [\[arXiv\]](#) | [\[IEEE Xplore\]](#)
- [2] M. Kundu, **S. Datta** and K.G, “**IoT-Based Anaesthesia Control and Monitoring System**”, in *Reinvention of Health Applications with IoT: Challenges and Solutions*, 1st ed., A. Pathy and S. S, Ed. Taylor and Francis Group, 2022, Chapter - 8, pp. 127-141, DOI: 10.1201/9781003166511-8. [\[Link\]](#)
- [3] **S. Datta** and Sriramalakshmi P., “**Two Stage Boost Inverter for Wave Energy Conversion**”, 8th *International Conference on Advances in Energy Research (ICAER)*, July, 2022. | [\[Certificate\]](#) | [\[arXiv\]](#) | [\[PPT\]](#)
- [4] **S. Datta**, R. Bharatwaj, Subbulekshmi D., D T. and A S., “**Semi-Supervised Learning for Autonomous Navigation**”, *International Conference on Data Analytics and Computing (ICDAC)*. Wenzhou, China, May, 2022. | [\[Certificate\]](#) | [\[Abstract\]](#) | [\[PPT\]](#)
- [5] **S. Datta**, Subbulekshmi D. and Venkatesan R., “**Brain MRI Segmentation**”. [In Preparation]
- [6] R.D. Choudhury, M. Kundu, **S. Datta** and Sriramalakshmi P., “**IoT Campus Mart Pro**”. [In Preparation]

## AWARDS & HONOURS

1. Achieved an outstanding overall **All India Rank – 10** (out of 76 teams) in the electric BAJA SAE, 2022. [\[Certificate\]](#)
2. Secured **1st Position out of 30 teams** in Aerospace Quiz League conducted by Team Aviators. [\[Certificate\]](#)
3. Found 3 asteroids under **NASA International Astronomical Search Collaboration**, 2021. [\[Certificate\]](#)
4. Consistently contributed to high-quality **Open-Source Projects** through **Hacktoberfest** editions 2021 & 2022.

## EXTRA – CURRICULARS

### Student Member, Youth Red Cross –

1. Organized a fund-raising campaign that provided a full meal to over **150 underprivileged children**.
2. Contributed to the collection of books for **200 poor school children** in North Bengal reliant on donations.
3. Administered a massive fund-raising initiative to feed more than **300 community animals** across pan-India.
4. Arranged **3 webinars** to address critical issues like - **Mental Health, Drug Abuse** and **Child Labour**.
5. Gathered donations to provide **114 teenage** girls with sanitary napkins and to educate them on their benefits.

### Power Electronics Head, The Road Runners, eBAJA ATV –

1. Co-Developed the design of the data acquisition system and its integration with **RX/TX communication**.
2. Simulated models to determine EV performance using **Proteus** and **MATLAB/Simulink** software.
3. Reviewed and researched relevant literature on **BLDC motors** and **controllers** for eBAJA applications.
4. Extensively used **Proteus** software with HC-SR04 Sensor & Magnetic Reed Switch for wheel RPM calculations.

## RELEVANT COURSEWORK

Robotics & Control (S)| Neural Networks (A)| Differential Equations (A)| Network Theory (A)| Electric Vehicles (B)| Problem Solving & Programming (A)| IoT Domain Analyst (A)| Statistics (B)| Embedded Sys. Design (B)| Calculus (A)|

\*Grade: S – 10, A – 9, B – 8 (on a scale of 10)

## CERTIFICATIONS & MOOCs

1. **Neural Networks and Deep Learning** — DeepLearning.AI - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
  - Learned key NN concepts such as Optimizers, Loss functions, Activation functions, Backpropagation etc.
2. **Robotics: Aerial Robotics** — University of Pennsylvania - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
  - Studied essential concepts such as quadcopter kinematics, trajectory tracking, and motion planning strategies.
3. **Machine Learning** — Stanford University - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
  - Mastered key ML topics like Linear Algebra, Statistics, Probability, Cost Function etc. using MATLAB scripts.
4. **Self-Driving Cars** — University of Toronto - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
  - Grasped prime autonomy concepts like visual perception, localization, state estimation etc. using CARLA.
5. **3D Computer Vision** — National University of Singapore – Dr. Gim Hee Lee
  - Studied concepts like 3D Geometry, Pose Estimation, Multi-View Stereo, Camera Calibration, Homography etc.
6. **Reinforcement Learning** — Stanford University – Dr. Emma Brunskill (Q-Learning, Policy Gradient, Batch RL etc.)