

Souvik Datta

+91-8961803710 | souvikdatta123@gmail.com | [Website](#) | [Google Scholar - DCqpUvMAAAAJ](#) | [GitHub – souvik0306](#)

EDUCATION

Vellore Institute of Technology

Bachelor of Technology in **Electrical and Electronics Engineering**

CGPA: 8.55/10

Chennai, India

July 2019 – May 2023

RELEVANT EXPERIENCE

Software Developer | Supervisor: Mr. Gaurav Vij

Feb 2023 – Present

Q Blocks

Toronto, Canada

- Built scalable REST APIs for SDXL, Falcon-7B, MPT-7B, and other Gen AI Models, serving 10,000+ users.
- Contributed to the development of the first pip package, achieving 4,000+ downloads in the first two months.
- Expanded our Decentralized GPU Network by integrating new data centers, increasing capacity to over 30,000+.

UAV Project Intern | Supervisor: Mr. Irnanda Setiawan | [\[Certificate\]](#) | [\[Report\]](#)

Dec 2022 – Apr 2023

PT Kaltim Prima Coal (KPC)

Sangatta, Indonesia

- Spearheaded an UAV operation for inspecting 70kV Transmission Lines, increasing revenue by \$1.26 million.
- Boosted total efficiency by 43% by planning flight routes and identifying critical inspection bottlenecks.
- Lead a team of 7 engineers, effectively managing and coordinating their efforts to meet project deliverables.

Deep Learning Research Assistant | Supervisor: [Dr. Subbulekshmi D](#)

May 2022 – Nov 2022

Vellore Institute of Technology

Chennai, India

- Worked on Deep Learning models for Brain Tumour & Skin Cancer Segmentation using Vision Transformers.
- Presented an abstract on GNN-based “Semi-Supervised Learning for Autonomous Navigation” at ICDAC, 2022.

Computer Vision Intern | Supervisor: Mr. Shivankit Arun | [\[Certificate\]](#) | [\[Report\]](#)

Jan 2022 – Jul 2022

Omnipresent Robot Technologies

New Delhi, India

- Programmed custom YOLOv5 object detection model over 6 classes for drone analytics with a 93% accuracy.
- Developed Python scripts with Geocoding APIs and Folium, increasing effective data visualization by 14%.
- Optimized Deep Learning Models by 37% for scene-change detection in Remote Sensing Applications.

Power Elec. Project Assistant | Supervisor: [Dr. Sriramalakshmi P](#)

Apr 2022 – Jun 2022

Vellore Institute of Technology

Chennai, India

- Extensively used MATLAB/Simulink on Tidal Energy Conversion Modules for Power Generation applications.
- Achieved an Output Voltage of 118V against an Input of 120V, yielding an Overall Efficiency of 98.33%.
- Conducted Fast Fourier Transform Analysis, resulting in an exceptional 0.26% Total Harmonic Distortion.

EV Research Intern | Supervisor: [Dr. Chinmaya K.A.](#) | [\[Certificate\]](#)

May 2021 – Jul 2021

Indian Institute of Technology, BHU

Varanasi, India

- Designed a Closed-Loop Converter with PI Controller having 16% more transient stability against disturbances.

PUBLICATIONS

1. S. Datta, M. Kundu, R. D. Choudhury, S. P. and S. VT, “**IoT Book Bot**”, 2022 IEEE India Council International Subsections Conference (INDISCON), 2022, pp. 1-6. | [\[Certificate\]](#) | [\[arXiv\]](#) | [\[IEEE Xplore\]](#)
2. M. Kundu, S. Datta and K.G, “**IoT-Based Anaesthesia Control and Monitoring System**”, in Reinvention of Health Applications with IoT: Challenges and Solutions, 1st ed., A. Pathy and S. S, Ed. Taylor and Francis Group, 2022, Chapter - 8, pp. 127-141, DOI: 10.1201/9781003166511-8. [\[Link\]](#)
3. Datta, S., Sriramalakshmi, P. (2023). “**Two-Stage Boost Inverter for Wave Energy Conversion**”. In: Doolla, S., Rather, Z.H., Ramadesigan, V. (eds) Advances in Renewable Energy and Its Grid Integration. ICAER 2022. Lecture Notes in Electrical Engineering, vol 1041. Springer, Singapore | [\[Certificate\]](#) | [\[Springer\]](#) | [\[DOI\]](#) | [\[PPT\]](#)
4. S. Datta, R. Bharatwaj, Subbulekshmi D., D T. and A S., “**Semi-Supervised Learning for Autonomous Navigation**”, International Conference on Data Analytics and Computing (ICDAC). Wenzhou, China, May, 2022. | [\[Certificate\]](#) | [\[Abstract\]](#) | [\[PPT\]](#)
5. S. Datta and Subbulekshmi D., “**Review of Deep Learning Algorithms for Urban Remote Sensing using Unmanned Aerial Vehicles (UAVs)**”. [Under Review] | [\[Draft\]](#)

SKILLS

Languages: Python, MATLAB/Simulink, Docker, LaTeX

Libraries: NumPy, Matplotlib, Pandas, OpenCV, scikit-learn, TensorFlow, Keras, PyTorch, Kubernetes

Technical: CARLA, Proteus, LT-Spice, Fritzing

Environment: Git/GitHub, Linux, Raspbian OS

Hardware Boards: Arduino, Raspberry Pi, esp8266

PROJECTS

Jet Engine Health Prediction | Pandas, scikit-learn | [\[CODE\]](#) | Machine Learning

- Predicted Remaining Useful Life (RUL) for turbofan jet engines using a Random Forest Classifier Model.
- Performed Exploratory Data Analysis on NASA's Dataset and analyzed feature correlation using Seaborn.
- Applied hyperparameter optimization using Randomized Search CV & increased F1-Score to an overall 91.2%.

State Estimation using Kalman Filter | NumPy, Matplotlib | [\[CODE\]](#) | Kalman Filter

- Developed Kalman Filter-based state estm. model for precise approximation & visualization of a robot's state.
- Attained an extremely low Mean Square Error of 2.8% & 1.1% for the robot's position & velocity on evaluation.

RF-Learning Robot | PyTorch, Pybullet, Gym-OpenAI | [\[CODE\]](#) | Reinforcement Learning

- Programmed a quadruped robot to exhibit walking gait using PyTorch-based Reinforcement Learning model.
- Optimized learning rate & other hyperparameters to marginally improve the Mean Reward of the model by 14%.

3D Point Cloud from Depth Map | Open3D, Keras, OpenCV | [\[CODE\]](#) | Computer Vision

- Produced 3D point cloud data maps from 2D monocular RGB image-based depth maps using Open3D functions.
- Exploited a PointNet-based Object Detection model to classify 3D point cloud data with 81% training accuracy.

IoT Book Bot | Arduino, OpenCV, Raspberry Pi | [\[CODE\]](#) | Robotics

- Engineered a mobile robot using Raspberry Pi, Arduino and esp8266 for IoT Navigation and Object Detection.
- Implemented a 2D object detection model on MS COCO classes and a QR-Code and Barcode decryption script.

AWARDS AND HONOURS

1. Achieved an outstanding All India Rank – 10 (out of 76 teams) in the Electric BAJA SAE, 2022. [\[Certificate\]](#)
2. Secured 1st Position out of 30 teams in Aerospace Quiz League conducted by Team Aviators. [\[Certificate\]](#)
3. Found 3 asteroids under NASA International Astronomical Search Collaboration, 2021. [\[Certificate\]](#)
4. Consistently contributed to high-quality Open-Source Projects through Hacktoberfest editions 2021 & 2022.

EXTRA-CURRICULARS

Student Member, Youth Red Cross –

- Organized a fund-raising campaign that provided a full meal to over 150 underprivileged children.
- Contributed to the collection of books for 200 poor school children in North Bengal reliant on donations.
- Administered a massive fund-raising initiative to feed more than 300 community animals across pan-India.
- Arranged 3 webinars to address critical issues like - Mental Health, Drug Abuse and Child Labour.

Power Electronics Head, The Road Runners, eBAJA ATV –

- Co-Developed the design of the data acquisition system and its integration with RX/TX communication.
- Simulated models to determine EV performance using Proteus and MATLAB/Simulink software.
- Reviewed and researched relevant literature on BLDC motors and controllers for eBAJA applications.
- Used Proteus software with HC-SR04 Sensor & Magnetic Reed Switch for wheel RPM calculations.

CERTIFICATES AND MOOCs

1. **Neural Networks and Deep Learning** — DeepLearning.AI - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
Learned key NN concepts such as Optimizers, Loss functions, Activation functions, Backpropagation etc.
2. **Robotics: Aerial Robotics** — University of Pennsylvania - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
Studied essential concepts such as quadcopter kinematics, trajectory tracking, and motion planning strategies.
3. **Machine Learning** — Stanford University - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
Mastered key ML topics like Linear Algebra, Statistics, Probability, Cost Function using MATLAB scripts.
4. **Self-Driving Cars** — University of Toronto - Coursera | [\[Certificate\]](#) | [\[GitHub\]](#)
Grasped prime autonomy concepts like visual perception, localization, state estimation etc. using CARLA.
5. **3D Computer Vision** by Dr. Gim Hee Lee — National University of Singapore
Studied crucial concepts like 3D Geometry, Pose Estimation, Multi-View Stereo, Camera Calibration etc.