

Lecture 12/13: Insertion, Faster Sorts

BT 3051 – Data Structures and Algorithms for Biology

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INSERTION SORT

Insertion Sort

```
def InsertionSort(a):  
    n = len(a)  
    for i in range(1,n):  
        for j in range(i, 0, -1):  
            if a[j] < a[j-1]:  
                a[j], a[j-1] = a[j-1], a[j]  
            else:  
                break  
    return a
```

Can we improve upon this?

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def InsertionSort(a):  
    n = len(a)  
    for i in range(1, n):  
        pos = i  
        currval = a[i]  
  
        while pos > 0 and a[pos - 1] > currval:  
            a[pos] = a[pos - 1]  
            pos = pos - 1  
  
        a[pos] = currval
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Properties

- ▶ Stable, $O(1)$ extra space
- ▶ $O(n^2)$ comparisons and swaps
- ▶ Adaptive: $O(n)$ when nearly sorted
- ▶ Very low overhead

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Insertion Sort

- ▶ Elementary sorting algorithm with $O(n^2)$ worst-case time; but
- ▶ Insertion sort is the algorithm of choice
 - ▶ either when the data is nearly sorted (because it is adaptive), or
 - ▶ when the problem size is small (because it has low overhead)
- ▶ It is also stable
- ▶ Insertion sort is often used as the recursive base case (when the problem size is small) for higher overhead divide-and-conquer sorting algorithms, such as merge sort or quick sort

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OVERVIEW

Sorting Algorithms

Algorithm	Complexity			In-place?
	Worst-case	Average-case	Best-case	
Selection Sort	$\Theta(n^2)$	$\Theta(n^2)$	$\Theta(n^2)$	yes
Bubble Sort	$\Theta(n^2)$	$\Theta(n^2)$	$\Theta(n)$	yes
Insertion Sort	$\Theta(n^2)$	$\Theta(n^2)$	$\Theta(n)$	yes
?	$\Theta(n \lg n)$	$\Theta(n \lg n)$	$\Theta(n \lg n)$	no
?		$\Theta(n \lg n)$		yes
?	$\Theta(n \lg n)$			yes

DIVIDE AND CONQUER

Algorithm Design: Divide and Conquer

- ▶ One of the important algorithm design strategies
- ▶ [Unfortunately] named after Roman (then British!) political strategies
 - ▶ Divide your enemies (develop distrust)
 - ▶ Conquer them individually (divide)
 - ▶ Combine the states together (conquer)

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Divide, Conquer and Combine!

Three major steps

- ▶ Split a problem into multiple sub-problems
 - ▶ Solve individual sub-problems (independently)
 - ▶ Combine solutions to individual sub-problems
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- ▶ Huge number computational problems can be solved efficiently using divide-and-conquer
 - ▶ First avenue of search for an efficient algorithm, once a brute-force solution is understood
 - ▶ Divide-and-conquer algorithms are typically recursive — since the conquer part involves invoking the same technique on a smaller sub-problem
 - ▶ Analysis of the running times of recursive programs is ~tricky
 - ▶ When merging takes less time than solving the two subproblems, we get an efficient algorithm!

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DIVIDE AND CONQUER:

ADVANTAGES

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- ▶ Efficiency
- ▶ Parallelism
- ▶ Memory access patterns

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MERGE SORT

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- ▶ Classic divide-and-conquer problem
- ▶ Also useful for on-line sorting (as data come in)

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Merge Sort

Algorithm

```
def MergeSort(a):  
    n=len(a)  
  
    if(len(a)==1):  
        return a  
    else:  
        return merge(MergeSort(a[:n//2]),MergeSort(a[n//  
                                                    2:]))
```

Where's all the work happening?

Merge Sort

merge()

```
def merge(a,b):
    c=[None]*(len(a)+len(b))
    i=j=k=0
    while (i<len(a) and j<len(b)):
        if a[i]<b[j]:
            c[k]=a[i]
            i+=1
        else:
            c[k]=b[j]
            j+=1
        k+=1
    if (i<len(a)):
        c[k:]=a[i:]
    else:
        c[k:]=b[j:]
    return c
```

Merge Sort

Time Complexity

$$T(n) = 1, \text{ if } n = 1$$

- ▶ Time to sort the first half of the array
- ▶ Time to sort the second half of the array
- ▶ Time to merge the sorted arrays

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Merge Sort

Recurrence Equation

$$T(1) = 1$$

$$T(2) = T(1) + T(1) + 2 = 4$$

$$T(3) = T(1) + T(2) + 3 = 8$$

$$T(4) = T(2) + T(2) + 4 = 12$$

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$$T(8) = T(4) + T(4) + 8 = 32$$

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$$T(n)/n = \lg n + 1$$

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Can you see a pattern?

$$T(n)/n = \lg n + 1 \Rightarrow T(n) \in \Theta(n \lg n)$$

QUICK SORT

Quick Sort

- ▶ Merge sort is very good, but does not operate in place!
- ▶ Quick sort is another divide-and-conquer algorithm
- ▶ Jon Bentley's "*Three Beautiful Quicksorts*" :
<https://www.youtube.com/watch?v=QvgYAQzg1z8>

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Quick Sort

- ▶ **Central idea: Partition the array**
- ▶ About a pivot (choice is critical!)
- ▶ All elements less than the pivot go into the *left subarray*
- ▶ All elements greater than the pivot go into the *right subarray*
- ▶ Pivot fits in between — in its place in the sorted array!
- ▶ Quicksort either half and we have the answer ...
- ▶ What is the `combine()` procedure here?

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Merge Sort	$\Theta(n \lg n)$	$\Theta(n \lg n)$	$\Theta(n \lg n)$	no
Quick Sort	$\Theta(n^2)$	$\Theta(n \lg n)$	$\Theta(n \lg n)$	yes
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Self-assessment Exercise: Read about heaps and heap-sort ...

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Many hybrid algorithms exist, e.g. quick + heap etc.

Why is Quick Sort so popular?

- ▶ *“When Quicksort is implemented well, it is typically 2-3 times faster than mergesort or heapsort!”* (Steven Skiena)
- ▶ How do we compare two $\Theta(n \lg n)$ algorithms?
- ▶ Since the difference between the two programs will be limited to a multiplicative constant factor, details of how you program each algorithm *will make a big difference!*
- ▶ Also, operations in the innermost loop are simpler
- ▶ Worst-case of quick sort is still $\Theta(n^2)$, but ...
- ▶ If you shuffle the input array, *“If you give me random input data, quicksort runs in expected $\Theta(n \lg n)$ time.”*
- ▶ Instead, if you pick a pivot at random, *“With high probability, randomized quicksort runs in $\Theta(n \lg n)$ time”*
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