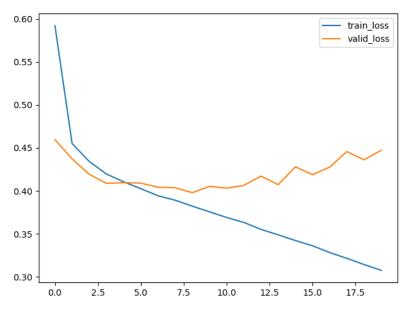
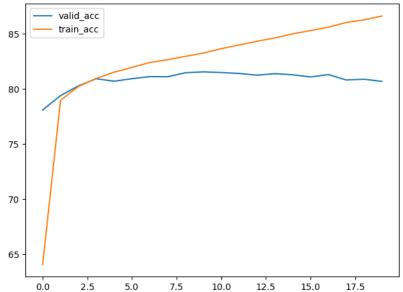
1. (0.5%) 請說明你實作之 RNN 模型架構及使用的 word embedding 方法,回報模型的正確率並繪出訓練曲線*

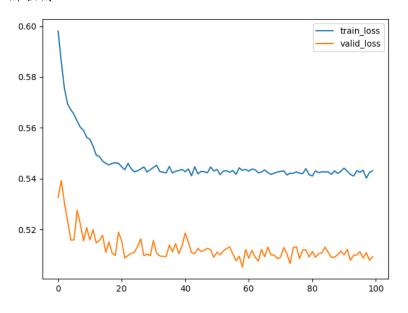


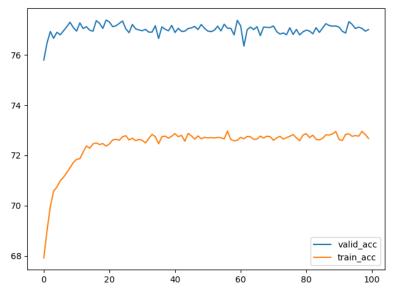


模型: 1層Word2vec Embedding (dim 30) \to 4層LSTM \to Dropout (0.75) \to 1層線性 (dim 64) \to Sigmoid

正確率: Train 0.83266, Validation 0.81559, Kaggle 0.82560

2. (0.5%) 請實作 BOW+DNN 模型, 敘述你的模型架構, 回報模型的正確率並繪出訓練曲線*。





模型: 4層線性 (dim 128), 每層間間隔dropout 0.5, 再接sigmoid

正確率: Train 0.72369, Validation 0.77386, Kaggle 0.77180

這裡發現一個現象,validation的結果比較training還好。

- 3. (0.5%) 請敍述你如何 improve performance (preprocess, embedding, 架構等) , 並解釋為何這些做法可以使模型進步。
 - i. 預處理

英文有大量的縮寫字,在預處理時先展開這些字,如[can't]→[can, not],而不是原本的[can,',t],因為撇號通常不帶有語意,把它當symbol不太合理。

ii. 改變word2vec的參數

window size調高到10, dimension調高到300, 這樣word可以看見更多的資訊, embedding有機會更準確。

另外,使用unlabeled data一起作word embedding,讓字之間距離的資訊更多。

iii. 改變rnn的參數與架講

lstm用了4層,每層dimension是64,並加上dropout 0.75和L2 regularization (係數1e-7),以減少overfitting。效果最明顯的是L2 regularization。 句子長度取45,可以涵蓋data中大部分的句子。

iv. 使用gru取代lstm

因為gru的參數較少,比較不會overfitting。但在這個dataset似乎沒有明顯進步。

v. 使用Bidirectional RNN

這樣可以讓training過程中看見之前和之後的word。

4. (0.5%) 請比較 RNN 與 BOW 兩種不同 model 對於 "Today is hot, but I am happy" 與 "I am happy, but today is hot" 這兩句話的分數 (model output) , 並討論造成差異的 原因。

	RNN	BOW
Today is hot, but I am happy:	0.8716	0.1350
I am happy, but today is hot:	0.1251	0.1350

這兩句話出現的字完全一樣,只有順序不一樣。bow只考慮出現的字,而rnn會參考往前數個字(以lstm為例),因此rnn可以分辨因語序不同造成的語意差異。

5. (3%) Math problem:

https://drive.google.com/file/d/1fEu87banB4s6Yjku1dA5sMcnwCugEPBF/view?usp=sharing

ML HW4

1. Let
$$X^{raw} = \begin{pmatrix} 1 & 4 & 3 & 1 & 5 & 7 & 9 & 3 & 11 & 10 \\ 2 & 8 & 12 & 8 & 14 & 4 & 8 & 8 & 5 & 11 \\ 3 & 5 & 9 & 5 & 2 & 1 & 9 & 1 & 6 & 7 \end{pmatrix} = \begin{pmatrix} \chi^{raw} & \chi^{raw} \\ \chi^{raw} & \chi^{raw} & \chi^{raw} & \chi^{raw} & \chi^{raw} & \chi^{raw} & \chi^{raw} \end{pmatrix}$$

Mean
$$\mu := \begin{pmatrix} 5.4 \\ 8 \\ 4.8 \end{pmatrix} = \frac{1}{10} \sum_{i=1}^{10} \chi_i^{\text{raw}}$$

$$X := X^{raw} - \mu = \begin{pmatrix} x^{raw} \\ -b \end{pmatrix} = \begin{pmatrix} x_1 - \mu \\ -b \end{pmatrix} = \begin{pmatrix} x_1 - x_{10} \\ -b \end{pmatrix}$$

Do singular-value decomposition:

$$X = UDV^T$$

$$\Sigma = \frac{1}{10} \sum_{i=1}^{10} \chi_i \chi_i^{\mathsf{T}} = \frac{1}{10} \chi_i^{\mathsf{T}} = \frac{1}{10} UDV^{\mathsf{T}} VDU^{\mathsf{T}} = U(\frac{1}{10}DD^{\mathsf{T}})U^{\mathsf{T}}$$

Where
$$U = (u_1 \ u_2 \ u_3) = \begin{pmatrix} -0.62 & 0.68 & -0.40 \\ -0.52 & -0.73 & -0.34 \\ -0.52 & 0.03 & 0.85 \end{pmatrix}$$

$$D = \begin{pmatrix} 12.37 & 0 & 0 & 0 \\ 0 & 10.78 & 0 & 0 & 0 \\ 0 & 0 & 7.40 & P & 0 \end{pmatrix}$$

$$D = \begin{pmatrix} 12.37 & 0.03 & 0.85 \\ 0.78 & 0.0 & 0 \\ 0.078 & 0.0 & 0 \\ 0.078 & 0.0 & 0 \\ 0.078 & 0.0 & 0 \\ 0.078 & 0.0 & 0 \\ 0.078 & 0.03 \\ 0.03 & 0.03 \end{pmatrix}, \quad U_3 = \begin{pmatrix} -0.40 \\ -0.34 \\ 0.85 \end{pmatrix}$$
(Approximately)

(b)
$$U^{T} \times \begin{array}{c} (-0.59) \\ -0.52) \end{array}$$
, $U_{2} = \begin{pmatrix} -0.60 \\ -0.73 \\ 0.03 \end{pmatrix}$, $U_{3} = \begin{pmatrix} -0.40 \\ -0.34 \\ 0.85 \end{pmatrix}$
(b) $U^{T} \times \begin{array}{c} (-0.36) \\ -0.71 \\ 1.48 \\ -0.04 \\ 0.04 \end{array}$ $\begin{array}{c} -3.36 \\ -3.03 \\ -6.53 \\ -3.06 \\ -6.53 \\ -3.06 \\ -6.84 \\ 1.84 \\ 0.47 \\ -3.81 \\ 3.95 \\ -1.11 \\ -1.75 \\$

(C) Use u, and uz since they have largest eigenvalue

Principle Component (pc) =
$$\begin{pmatrix} uI \\ u\bar{z} \end{pmatrix} \chi^{raw}$$

Reconstruction Error = $\| \begin{pmatrix} u_1 & u_2 \end{pmatrix} \begin{pmatrix} uI \\ u\bar{z} \end{pmatrix} \chi^{raw} - \chi^{raw} \|^2 = 60.64$

2. (a)
$$A \in \mathbb{R}^{m \times n}$$

 $Symmetric: (AAT)^T = AAT$
 $(ATA)^T = A^TA$

Positive Semi-definite:

$$\forall x$$
 $x^{T} AA^{T} x = ||A^{T} x||^{2} \ge 0$

$$\forall y$$
 $x^{T} A^{T} A y = ||Ay||^{2} \ge 0$

Sharing same eigenvalues:

For matrix ATA, since it's positive semidefinite, its eigenvalues are non-negative. Let positive eigenvalues be li. 12. 1k, where li≥ 12 > - 3/k > , k≤n, and corresponding

eigenvectors be VI ... VK

So $A^TAv_i = \lambda_i v_i$, $i \leq k$

Define $\sigma_i = \sqrt{\lambda_i}$, $u_i = \frac{1}{\sigma_i} A v_i$, for $i \le k$

 $\Rightarrow A^{T}u_{i} = A^{T} \frac{1}{\sigma_{i}} Av_{i} = \frac{1}{\sigma_{i}} A^{T}Av_{i} = \frac{1}{\sigma_{i}} \sigma_{i}^{2} v_{i} = \sigma_{i} v_{i}$

 \Rightarrow $AA^Tu_i = \sigma_i A_{vi} = \sigma_i^2 u_i$

⇒ or = li is also an eigenvalue of AAT

⇒ Let B='AT, we show the inverse direction (positive eigenvalues of AAT are eigenvalues of ATA)

⇒ ATA and AAT share same non-zero eigenvalues

2. (b) : Z is symmetric and positive definite ⇒ ∑ can be diagonalize as: E = UNUT where UER is orthonormal NERMXM is diagonal $\Lambda = \operatorname{diag}\left(\frac{\sigma_1^2}{n}, \frac{\sigma_2^2}{n}, \frac{\sigma_m^2}{n}\right) \quad \text{for some } \begin{cases} \sigma_1 & \sigma_m \\ \sigma_2 & \sigma_m \end{cases} \quad \text{of } z$ $\Rightarrow \Sigma = U\left(\frac{1}{n}DD^{T}\right)U^{T} \quad \text{where } D \in \mathbb{R}^{m \times n} \quad D = \begin{pmatrix} \sigma_{T} & \sigma_{T} & \sigma_{T} \\ \sigma_{T} & \sigma_{T} & \sigma_{T} \end{pmatrix}$ = In UDVIV DIUT for some orthonormal VERNXN $= \frac{1}{n} (UDV^{T})(UDV^{T})^{T}$ $= \frac{1}{n} XX^{T}$ $= \frac{1}{n} XX^{T}$ $= \frac{1}{n} XX^{T}$ $= \frac{1}{n} (UDV^{T})(UDV^{T})^{T}$ $= \frac{1}{n} (UDV^{T})(UDV^{T})^{T}$ $= \frac{1}{n} (UDV^{T})(UDV^{T})^{T}$ $= \frac{1}{n} \sum_{i=1}^{n} \hat{x}_{i} \hat{x}_{i}^{T}$ $= \frac{1}{n} \sum_{i=1}^{n} (x_{i} - \mu)(x_{i} - \mu)^{T} \int_{-\infty}^{\infty} \det x_{i} = \hat{x}_{i} + \mu$ There always exists V such that $\frac{1}{n}\sum_{i=0}^{n}\hat{x}_{i}=0$ since: $\frac{1}{n}\sum_{i=1}^{n}\widehat{x}_{i}=0 \iff \chi\left(\frac{1}{n}\right)=0 \iff UDV^{T}\left(\frac{1}{n}\right)=0$ $\Leftrightarrow V^{T}\left(\frac{1}{2}\right)^{N} \in Nall\left(UD\right)$ Since $d_{im}\left(Null\left(UD\right)\right) = Nullity\left(UD\right) = n - Rank\left(UD\right) \geq n - m > 0$ > ∃y = V (')

So
$$\{x_i, x_i - x_i\}$$
 satisfies $\lim_{i \to 1} x_i = \lim_{i \to 1} (x_i + \mu) = \mu$
 $\lim_{i \to 1} (x_i - \mu)(x_i - \mu)^{-7} = \Sigma$

$$\begin{aligned} & \mathcal{I} \cdot (\mathcal{L}) & | \leq k \leq m \\ & \begin{cases} \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) \\ \\ \leq \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{m} | \mathbf{I}_{i}(\mathbf{d}^{T} \boldsymbol{\Sigma} \boldsymbol{\phi}) |^{2} \\ \\ = \sum_{i=1}^{$$

3. Define: Time lake
$$|\hat{y}_{i}| = \begin{pmatrix} -\frac{1}{k-1} \\ -\frac{1}{k-1} \end{pmatrix}$$
 where $|\hat{y}_{i}| = \begin{cases} 1 \text{ if this data is class } p \\ -\frac{1}{k-1} \text{ otherwise} \end{cases}$

Function $|f(x)| = \begin{pmatrix} 3t(x) \\ 9t(x) \end{pmatrix}$, $|x| = \begin{pmatrix} \alpha t \\ \alpha t \end{pmatrix}$

The loss function becomes: $|L|(gt) = \sum_{i=1}^{n} \exp\{-\hat{y}_{i}^{T}gtx_{i}\}\}$

$$= \sum_{i=1}^{n} \exp\{-\hat{y}_{i}^{T}(gt_{i}(x_{i}) + f_{t}(x_{i})x_{i})\} - \sum_{i=1}^{n} w_{i} \exp\{-f_{t}(x_{i})\hat{y}_{i}^{T}x_{i}\}\}$$

Where $|w| = \exp\{-\hat{y}_{i}^{T}gt_{i}(x_{i})\}$

$$\Rightarrow |\nabla_{ut}|L = \sum_{i=1}^{n} |w_{i}| \exp\{-f_{t}(x_{i})\hat{y}_{i}^{T}x_{i}\}\}$$

$$\Rightarrow |x| = \frac{1}{k+1} |(\log(\frac{1-\epsilon t}{\epsilon t}) + \log(k-1)]$$

Where $|\xi_{t}| = \sum_{i=1}^{n} |w_{i}| |(\log(\frac{1-\epsilon t}{\epsilon t}) + \log(k-1))$

Where $|\xi_{t}| = \sum_{i=1}^{n} |w_{i}| |(\log(\frac{1-\epsilon t}{\epsilon t}) + \log(k-1))$