

# Primeasia University

## CSE327

### Final Exam

Ans any 5 questions

1. What is an addressing mode? what type of addressing modes are the following instructions, and what they actually mean- explain your answer. 6

```
LDAX DE
MOV B, A
MVI C, #003
LDA 678H
LDA #003
```

2. What is a transducer? Suppose the register A has a value of 11001010. What will be the final value of A after performing a RRC then RLC and again RLC. 6

3. Perform the operation and write down value and state (set/reset) of each flag register bit 6

```
11001100
+ 10111111
```

---

4. What is the basic difference between general registers and special purpose registers? If a processor has 32 bit bus line then calculate the max number of register in the memory cell for that processor. Show your full calculation

(Note: No partial marking will be provided without giving full calculation) 6

5. Is it possible to find out the depth of a sunk ship under water using ultrasonic sensor?- explain your answer.

If the total time for sound to travel from the Transmitter to Receiver is 10 seconds and the speed of sound in air is 1125 feet/second. Then the obstacle is situated how many meter away from the sonar sensor? (1 meter=3.2 feet) 6

6. Explain the colored line of the codes for an ultrasonic sensor 6

```
const int trigPin = A0;  
const int echoPin = A1;
```

```
long duration;  
int distance;
```

```
void setup()  
{  
  pinMode(trigPin, OUTPUT);  
  pinMode(echoPin, INPUT);  
  Serial.begin(9600);  
}  
void loop() {
```

```
  digitalWrite(trigPin, LOW);  
  delayMicroseconds(2);
```

```
  digitalWrite(trigPin, HIGH);  
  delayMicroseconds(10);
```

```
  digitalWrite(trigPin, LOW);
```

```
  duration = pulseIn(echoPin, HIGH);  
  distance= duration*0.034(10/5);
```

```
  Serial.print("Distance: ");  
  Serial.print(distance);  
}
```

