Marwin B. Alejo 2020-20221 EE274_ProgEx06

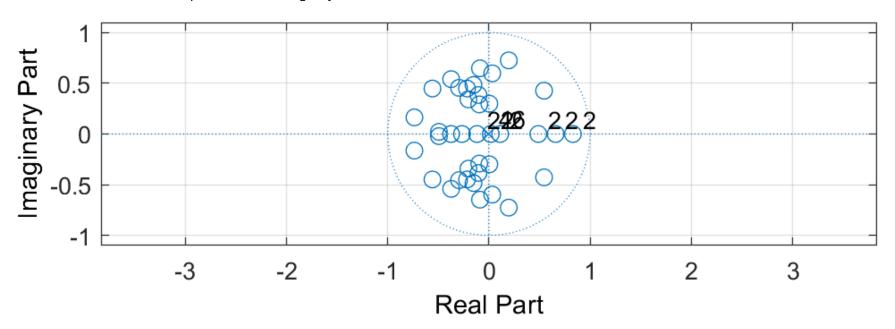
Also accessible through www.github.com/soymarwin/ee274/EE274_ProgEx06 for history tracking. Performed in MATLAB 2020b.

A.	Pole-Zero Placement	1
B.	Properties of Various Windowing Functions	3
C.	DESIGN A DIGITAL FIR LOWPASS FILTER WITH SPECS: $wp=0.2\pi$, $ws=0.3\pi$, $Rp=0.25dB$, $As=50dB$. 32
D	EPECHENICY SAMPLING (EOR GRADS ONLY)	2/

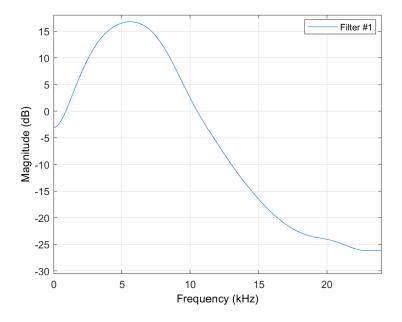
A. Pole-Zero Placement

Task in this section was performed using filter designer and was saved as an object with a filename <u>section_A.fda</u>. Given the magnitude response shown in the <u>manual</u> and through zero replacement method (no zeros required since FIR) the following below are the outputs:

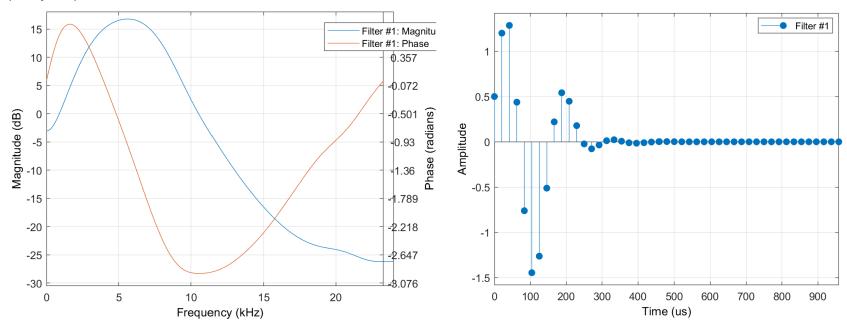
a. Zero locations of the filter. The poles are at the origin by default.



b. Magnitude Response



c. Frequency Response



B. Properties of Various Windowing Functions

Table 1 shows the summary of the configuration for designing each FIR with respective window functions. The magnitude plot of each configuration is shown in Table 2. The MATLAB scripts used in this section are *rectw.m*, *bartw.m*, *hannw.m*, *hannw.m*, *blkw.m*, and *kaisw.m* and are shown in Table 3.

TABLE 1 FIR Design Configuration Summary

			Transition width			Peak sidelob	е
Window name	Exact Value		(in rad)	(in dB)			
		M=31	M=61	M=121	M=31	M=61	M=121
Rectangular	$\frac{1.8\pi}{M}$	0.06π	0.03π	0.015π	20.7	21	
Bartlett	$\frac{6.1\pi}{M}$	0.203π	0.102π	0.051π	0		
Hann	$\frac{6.2\pi}{M}$	0.207π	0.103π	0.052π	44	44	
Hamming	$\frac{6.6\pi}{M}$	0.22π	0.11π	0.055π	51.4	54.3	
Blackman	$\frac{11\pi}{M}$	0.3667π	0.183π	0.0917π	0	0	
Kaiser Beta 1	1.0	0.06π	0.03π	0.015π	23.4	23.3	
Kaiser Beta 4	$\frac{1.8\pi}{M}$	0.06π	0.03π	0.015π	47.6	45.4	
Kaiser Beta 9	1.1	0.06π	0.03π	0.015π	90.7	90.3	

TABLE 2 Magnitude plot of each windowing configuration in Table 1

Window Name	Exact Value	Length	Plots
Rectangular	$\frac{1.8\pi}{M}$	31	Impulse Response 0.4 0.4 0.5 10 15 20 25 30 n Rectangular Window n Magnitude Response in dB 0.5 0.6 0.7 0.8 0.9 1 frequency in π units

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 (E) 0.2 0 10 20 30 40 50 60 Rectangular Window 0 0 10 20 30 40 50 60 N Rectangular Window 10 0 0 10 0 0 10 0 0 10 0 0 10 0 0 1

Window Name	Exact Value	Length	Plots
		121	Impulse Response

Window Name	Exact Value	Length	Plots
Bartlett	$\frac{6.1\pi}{M}$	31	Impulse Response 0.4 E 0.2 0 5 10 15 20 25 30 35 Bartlett Window Signification Signi

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 (a) 0.2 0.10 20 30 40 50 60 Bartlett Window Magnitude Response in dB Magnitude Response in dB 0.10 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1 frequency in π units

Window Name	Exact Value	Length	Plots
		121	Impulse Response 0.4 (E) 0.2 0 20 40 60 80 100 120 1 Bartlett Window 1 Magnitude Response in dB 1 Magnitude Response in dB

Window Name	Exact Value	Length	Plots
Hann	6.2π Μ	31	Impulse Response 0.4 (E) 0.2 10 15 20 25 30 10 Hanning Window 10 Magnitude Response in dB 10 10 10 10 10 10 10 10 10 1

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 E 0.2 0 10 20 30 40 50 60 70 Hanning Window 10 20 30 40 50 60 70 Magnitude Response in dB 0 40 50 60 70 Impulse Response in dB 0 10 20 30 40 50 60 70 Impulse Response in dB Impulse Response

Window Name	Exact Value	Length	Plots
		121	Impulse Response 0.4 (a) 0.20 40 60 80 100 120 Hanning Window 1 Magnitude Response in dB Magnitude Response in dB Frequency in π units

Window Name	Exact Value	Length	Plots
Hamming	$\frac{11\pi}{M}$	31	Impulse Response 0.4 (E) 0.2 0 5 10 15 20 25 30 N Hamming Window 0 5 10 15 20 25 30 N Magnitude Response in dB 100 100 100 100 100 100 100 1

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 (a) 0 10 20 30 40 50 60 Hamming Window 0 10 20 30 40 50 60 n Magnitude Response in dB 0 0 10 20 30 40 50 60 n frequency in π units

Window Name	Exact Value	Length	Plots
		121	Impulse Response 0.4 (a) 0.2 1 1 1 1 1 1 1 1 1 1 1 1 1

Window Name	Exact Value	Length	Plots
Blackman	$\frac{11\pi}{M}$	31	Impulse Response 0.4 (μ) 0.2 0 5 10 15 20 25 30 Blackman Window Magnitude Response in dB Magnitude Response in dB Frequency in π units

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 (E) 0.2 0 10 20 30 40 50 60 70 Blackman Window 10 20 30 40 50 60 70 Magnitude Response in dB (S) 200 -300 0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1 frequency in π units

Window Name	Exact Value	Length	Plots
		121	Impulse Response 0.4 (E) 0.2 0 20 40 60 80 100 120 R Blackman Window 1 Magnitude Response in dB Magnitude Response in dB Frequency in π units

Window Name	Exact Value	Length	Plots
Kaiser Beta 1	$\frac{1.8\pi}{M}$	31	Impulse Response 0.4 (E) 0.2 0.5 10 15 20 25 30 n Kaiser Window n Magnitude Response in dB 0 9 60 0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1 frequency in π units

Window Name	Exact Value	Length	Plots
		61	Impulse Response

Window Name	Exact Value	Length	Plots
		121	Impulse Response 0.4 (a) 0.2 0 40 60 80 100 120 Raiser Window 0 20 40 60 80 100 120 N Magnitude Response in dB Magnitude Response in dB frequency in π units

Window Name	Exact Value	Length	Plots
Kaiser Beta 4		31	Impulse Response 0.4 (E) 0.2 0 5 10 15 20 25 30 Naiser Window Magnitude Response in dB Magnitude Response in dB Frequency in π units

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 (E) 0.2 0.1 0.2 0.3 0.4 0.5 0.6 0.7 Magnitude Response in dB 100 100 100 100 100 100 100 1

Window Name	Exact Value	Length	Plots
		121	Impulse Response 0.4 (a) 0 20 40 60 80 100 120 n Kaiser Window 1 Magnitude Response in dB Magnitude Response in dB 100 0 0.1 0.2 0.3 0.4 0.5 0.6 0.7 0.8 0.9 1 frequency in π units

Window Name	Exact Value	Length	Plots
Kaiser Beta 9		31	Impulse Response 0.4 (a) 0.2 0 5 10 15 20 25 30 Raiser Window Magnitude Response in dB Magnitude Response in dB Frequency in π units

Window Name	Exact Value	Length	Plots
		61	Impulse Response 0.4 0.4 0.2 0.0 0.4 0.4 0.5 0.6 0.7 Magnitude Response in dB Magnitude Response in dB 0.4 0.4 0.5 0.6 0.7 0.8 0.9 1 frequency in π units

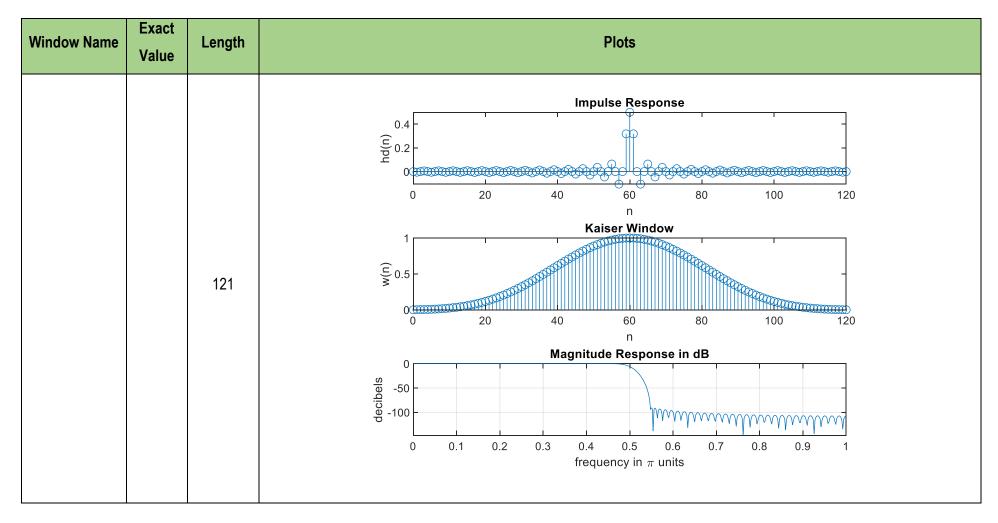


TABLE 3 Window Method MATLAB Implementation

Window	MATLAB Implementation in relevant to table 1 and 2 results			
Method	INATEAD Implementation in relevant to table 1 and 2 results			
Rectangular	% Written and performed by Marwin B. Alejo 2020-20221			
	% Return Impulse Response, Rectangular Window, and Magnitude Response plots			
(rectw.m)	% by simply providing the cut-off frequency in pi*rad and transition width.			
,	<pre>function rectw(wc,tr width)</pre>			
	<pre>M=ceil(1.8*pi/tr_width)+1;</pre>			
	n=[0:M-1];			

```
Window
                                           MATLAB Implementation in relevant to table 1 and 2 results
  Method
                alpha=(M-1)/2;
                m=n-alpha;
                fc=wc/pi;
                hd=fc*sinc(fc*m);
                w rect=(rectwin(M))';
                b=hd.*w rect;
                [H,w] = freqz(b,[1],1000,'whole');
                H = (H(1:1:501));
                w = (w(1:1:501));
                mag = abs(H);
                db = 20*log10((mag+eps)/max(mag));
                %wvtool(b); % for sidelobe measurement
                figure();
                subplot(3,1,1);stem(n,hd);title('Impulse Response');xlabel('n');ylabel('hd(n)');
                subplot(3,1,2);stem(n,w rect);title('Rectangular Window');xlabel('n');ylabel('w(n)');
                subplot(3,1,3);plot(w/pi,db);title('Magnitude Response in dB');grid;xlabel('frequency in \pi
            units'); ylabel('decibels');
            end
Bartlett
            % Written and performed by Marwin B. Alejo 2020-20221
            % Return Impulse Response, Bartlett Window, and Magnitude Response plots
(bartw.m)
            % by simply providing the cut-off frequency in pi*rad and transition width.
            function bartw(wc,tr width)
                M=ceil(6.1*pi/tr width)+1;
                n=[0:M-1];
                alpha=(M-1)/2;
                m=n-alpha;
                fc=wc/pi;
                hd=fc*sinc(fc*m);
                w bart=(bartlett(M))';
                b=hd.*w bart;
                [H,w] = freqz(b,[1],1000,'whole');
                H = (H(1:1:501));
                w = (w(1:1:501));
                mag = abs(H);
                db = 20*log10((mag+eps)/max(mag));
                %wvtool(b); % for sidelobe measurement
                figure();
                subplot(3,1,1);stem(n,hd);title('Impulse Response');xlabel('n');ylabel('hd(n)');
                subplot(3,1,2);stem(n,w bart);title('Bartlett Window');xlabel('n');ylabel('w(n)');
                subplot(3,1,3);plot(w/pi,db);title('Magnitude Response in dB');grid;xlabel('frequency in \pi
            units');ylabel('decibels');
```

```
Window
                                           MATLAB Implementation in relevant to table 1 and 2 results
  Method
            end
            % Written and performed by Marwin B. Alejo 2020-20221
Blackman
            % Return Impulse Response, Blackman Window, and Magnitude Response plots
(blkw.m)
            % by simply providing the cut-off frequency in pi*rad and transition width.
            function blkw(wc,tr width)
                M=ceil(11*pi/tr width)+1;
                n=[0:M-1];
                alpha=(M-1)/2;
                m=n-alpha;
                fc=wc/pi;
                hd=fc*sinc(fc*m);
                w blk=(blackman(M))';
                b=hd.*w blk;
                [H,w] = freqz(b,[1],1000,'whole');
                H = (H(1:1:501));
                w = (w(1:1:501));
                mag = abs(H);
                db = 20*log10((mag+eps)/max(mag));
                %wvtool(b); % for sidelobe measurement
                figure();
                subplot(3,1,1);stem(n,hd);title('Impulse Response');xlabel('n');ylabel('hd(n)');
                subplot(3,1,2);stem(n,w blk);title('Blackman Window');xlabel('n');ylabel('w(n)');
                subplot(3,1,3);plot(w/pi,db);title('Magnitude Response in dB');grid;xlabel('frequency in \pi
            units');ylabel('decibels');
            end
            % Written and performed by Marwin B. Alejo 2020-20221
Hanning
            % Return Impulse Response, Hanning Window, and Magnitude Response plots
(hannw.m)
            % by simply providing the cut-off frequency in pi*rad and transition width.
            function hannw(wc,tr width)
                M=ceil(6.2*pi/tr width)+1;
                n=[0:M-1];
                alpha=(M-1)/2;
                m=n-alpha;
                fc=wc/pi;
                hd=fc*sinc(fc*m);
                w hann=(hann(M))';
                b=hd.*w hann;
                [H,w] = freqz(b,[1],1000,'whole');
                H = (H(1:1:501));
                w = (w(1:1:501));
                mag = abs(H);
```

```
Window
                                          MATLAB Implementation in relevant to table 1 and 2 results
  Method
                db = 20*log10((mag+eps)/max(mag));
                %wvtool(b); % for sidelobe measurement
                figure();
                subplot(3,1,1);stem(n,hd);title('Impulse Response');xlabel('n');ylabel('hd(n)');
                subplot(3,1,2);stem(n,w hann);title('Hanning Window');xlabel('n');ylabel('w(n)');
                subplot(3,1,3);plot(w/pi,db);title('Magnitude Response in dB');grid;xlabel('frequency in \pi
            units'); ylabel('decibels');
            % Written and performed by Marwin B. Alejo 2020-20221
Hamming
            % Return Impulse Response, Hamming Window, and Magnitude Response plots
(hammw.m)
            % by simply providing the cut-off frequency in pi*rad and transition width.
            function hammw(wc,tr width)
                M=ceil(6.6*pi/tr width)+1;
                n=[0:M-1];
                alpha=(M-1)/2;
                m=n-alpha;
                fc=wc/pi;
                hd=fc*sinc(fc*m);
                w hamm=(hamming(M))';
                b=hd.*w hamm;
                [H,w] = freqz(b,[1],1000,'whole');
                H = (H(1:1:501));
                w = (w(1:1:501));
                mag = abs(H);
                db = 20*log10((mag+eps)/max(mag));
                %wvtool(b); % for sidelobe measurement
                figure();
                subplot(3,1,1);stem(n,hd);title('Impulse Response');xlabel('n');ylabel('hd(n)');
                subplot(3,1,2);stem(n,w hamm);title('Hamming Window');xlabel('n');ylabel('w(n)');
                subplot(3,1,3);plot(w/pi,db);title('Magnitude Response in dB');grid;xlabel('frequency in \pi
            units'); vlabel('decibels');
            end
            % Written and performed by Marwin B. Alejo 2020-20221
Kaiser
            % Return Impulse Response, Kaiser Window, and Magnitude Response plots
(kaisw.m)
            % by simply providing the cut-off frequency in pi*rad and transition width.
            function kaisw(wc,tr width, beta)
                M=ceil(1.8*pi/tr width)+1;
                n=[0:M-1];
                alpha=(M-1)/2;
                m=n-alpha;
                fc=wc/pi;
```

```
Window
                                         MATLAB Implementation in relevant to table 1 and 2 results
Method
              hd=fc*sinc(fc*m);
              w kais=(kaiser(M, beta))';
              b=hd.*w kais;
              [H,w] = freqz(b,[1],1000,'whole');
              H = (H(1:1:501));
              w = (w(1:1:501));
              mag = abs(H);
              db = 20*log10((mag+eps)/max(mag));
              %wvtool(b); % for sidelobe measurement
              figure();
              subplot(3,1,1);stem(n,hd);title('Impulse Response');xlabel('n');ylabel('hd(n)');
              subplot(3,1,2);stem(n,w kais);title('Kaiser Window');xlabel('n');ylabel('w(n)');
              subplot(3,1,3);plot(w/pi,db);title('Magnitude Response in dB');grid;xlabel('frequency in \pi
          units'); ylabel('decibels');
          end
```

C. Design a digital FIR lowpass filter with specs: $w_p = 0.2\pi$, $w_s = 0.3\pi$, $R_p = 0.25dB$, $A_s = 50dB$

```
function hd=ideal lp(wc,M)
%hd: ideal LPF impulse response between 0 and M-1
%wc: cut-off frequencies in radians
%M: length of the filter
    alpha=(M-1)/2;
    n=[0:M-1];
    m=n-alpha;
    fc=wc/pi;
    hd=fc*sinc(fc*m);
end
function [db,mag,pha,grd,w] = freqz m(b,a)
% Modified version of fregz subroutine
% [db,mag,pha,grd,w] = freqz m(b,a)
% db = relative magnitude in dB computed over 0 to pi radians
% mag = absolute magnitude computed over 0 to pi radians
% pha = Phase response in radians over 0 to pi radians
% grd = Group delay over 0 to pi radians
      w = 501 frequency samples between 0 to pi radians
      b = numerator polynomial of H(z)
                                        (for FIR: b=h)
      a = denominator polynomial of H(z) (for FIR: a=[1])
[H,w] = freqz(b,a,1000,'whole');
```

```
H = (H(1:1:501));
  w = (w(1:1:501));
  mag = abs(H);
  db = 20*log10((mag+eps)/max(mag));
  pha = angle(H);
  grd = grpdelay(b,a,w);
end
C wp=0.2*pi; C ws=0.3*pi; C tr width=C ws-C wp;
C M=ceil(6.6*\overline{pi}/C tr width)+1;
C n=[0:C M-1];
C wc=(C ws+C wp)/2; %ideal cutoff frequency
C hd=ideal lp(C wc,C M);
C w hamming=(hamming(C M))';
C h=C hd.*C w hamming;
[C db,C mag,C pha,C grd,C w]=freqz m(C h,[1]);
figure();
subplot(3,1,1); stem(C_n,C_h); title('Impulse Response'); xlabel('n'); ylabel('hd(n)');
subplot(3,1,2);stem(C n,C w hamming);title('Hamming Window');xlabel('n');ylabel('w(n)');
subplot(3,1,3);plot(C w/pi,C db);title('Magnitude Response in dB');grid;ylabel('decibel');
xlabel('frequency in \pi units');
```

For this section to be done, two different functions were written: ideal_lp and freqz_m. The ideal_lp function returns the coefficients of an ideal LPF of order n and length M. The freqz_m function is a modified freqz function and return the relative magnitude, and absolute magnitude values of an ideal LPF.

Unlike in section B, cut-off frequency is not provided hence, among of the hidden tasks is to determine the unknown parameters to design a lowpass filter based on specification (refer to activity 6 manual for specs). This also include the length M, order number n, and transition width which are reflected on the first three lines of the code above.

After determining the length M and the ideal cut-off frequency, the next thing to do is determine the ideal LPF coefficients (hd) by using the ideal_lp function. Provided that the design sideband attenuation is 50dB, we will be using Hamming window method as its peak sideband attenuation is closer to the desired 50dB specification (refer to table 1 above) rather than when using either Kaiser or Hann methods. Using the hamming method requires that the length M be determined first. The value of M is measured using the same formula used in hammw.m and in table 1.

Since 0.25dB ripple attenuation is not necessary in the development of a filter in this section, it is used to determine whether the generated filter is correct or not.

The impulse response, hamming, and magnitude response in dB values are generated using the freqz_m function. Figure 1 below shows the plot of the above MATLAB implementation. It is also shown that the desired LPF specifications are met with the value of ripple attenuation is equal to the peak LPF coefficient in impulse response plot.

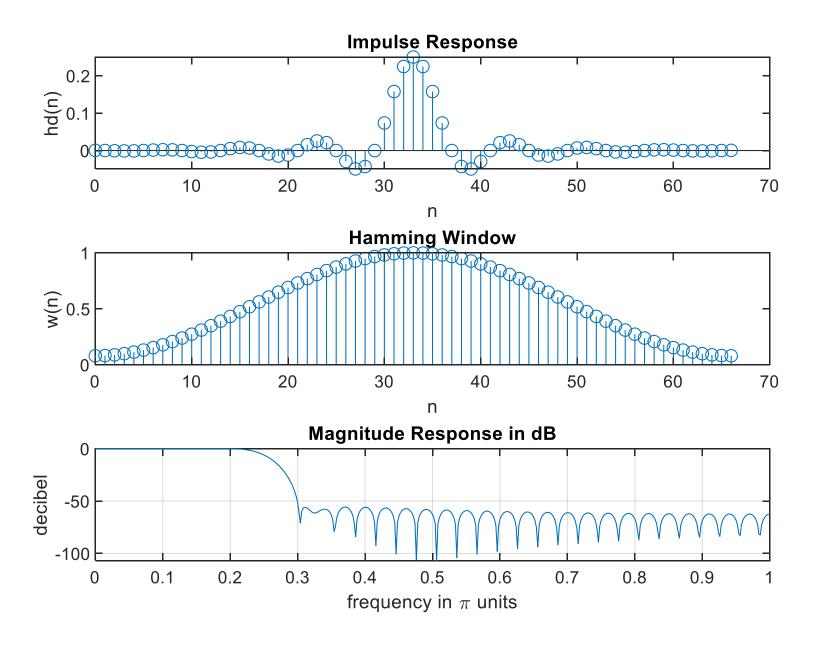


Figure 1 Impulse Response (Top), Hamming Window (Middle), Magnitude Response (Bottom) Plots

D. Frequency Sampling (for grads only)

$$H(k) = \begin{cases} (-1)^k & 0 \le k \le 7 \\ 0.5 & k = 8 \\ 0 & 9 \le k \le 23 \\ 0.5 & k = 24 \\ (-1)^k & 25 \le k \le 31 \end{cases}$$

$$D_{\mathbf{m}} = \begin{bmatrix} 0 & 0.125 & 0.1875 & 0.25 & 0.3125 & 0.375 & 0.4375 & 0.5 & 0.5 & 0.5625 & 0.625 & 0.6875 & 0.75 & 0.8125 & 0.875 & 0.9375 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & -1 & 1 & -1 & 1 & -1 & 1 & -1 & 0.5 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

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$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

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$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

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$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

$$D_{\mathbf{m}} = \begin{bmatrix} 1 & 0.5 & 0.5 & 1 \end{bmatrix};$$

Shown in figure 2 is the frequency response using frequency sampling as described by the samples in H(k) above.

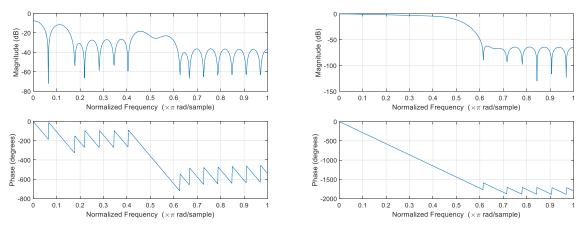


Figure 2 Frequency Response of H(k) using Frequency Sampling method.

a. What is the order of the FIR filter? Is the filter linear phase?

The FIR filter is of 32 order. Regardless of phase discontinuities which indicates that the filter has sign reversal components, it is linear phase.

b. Compare the transition bandwidth, passband, and stopband ripple heights of FIR filter design using windowing method and frequency sampling methods of the same filter order.

The frequency response of H(k) is like the frequency response plot a hamming-based FIR filter of the same length except that the passband is shorter in frequency sampling than in windowing method, the transition band is wider is frequency sampling than in windowing method, and stopband ripple heights are more optimal in windowing method than in frequency sampling method. This is in reflection of the fact below that frequency sampling method show the exact solution but is ineffective on selective precision points.

c. What is the main advantage of using frequency sampling methods with windowing methods?

Frequency sampling method is effective and practical on applications that require an exact solution at discrete frequency locations in comparison with windowing method. Frequency sampling is very simple yet impractical except on selective precision points moreover, it will be exact on frequency sample location with ripple in between.