

5. Z-Transform for DT systems

EE 274/COE 197E

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Today's Lesson:

1. The DT complex exponential
2. Z Transform definition, examples
3. Region of Convergence
4. Properties of ROC
5. Properties of z Transform

The complex exponential

- Most of the signals that we see in DT systems can be represented by a complex exponential:

$$z^n = r e^{j\omega n}$$

- A. $5(2^n) \rightarrow$ exponentially increasing
- B. $3(-0.1^n) \rightarrow$ exponentially decreasing, oscillating
- C. $\cos(0.5n) = 0.5(e^{j0.5n}) + 0.5(e^{-j0.5n}) \rightarrow$ oscillating
- D. $5(1^n) \rightarrow$ constant

The complex exponential

- Consider a DT system, with $x[n] = z^n$ as an input

$$y[n] = h[n] * x[n], \quad x[n] = z^n$$

$$= \sum_{k=-\infty}^{\infty} h[k]x[n-k]$$

$$= \sum_{k=-\infty}^{\infty} h[k]z^{n-k}$$

The complex exponential

- Consider a DT system, with $x[n] = z^n$ as an input

$$y[n] = h[n] * x[n], \quad x[n] = z^n$$

$$= \sum_{k=-\infty}^{\infty} h[k]x[n-k]$$

$$= \sum_{k=-\infty}^{\infty} h[k]z^{n-k}$$

$$y[n] = z^n \boxed{\sum_{k=-\infty}^{\infty} h[k]z^{-k}} = z^n H(z)$$

In the perspective of z , DT
convolution becomes multiplication

The z Transform

- For a discrete-time, LTI system

$$y[n] = z^n \left(\sum_{k=-\infty}^{\infty} h[k] z^{-k} \right) = z^n H(z)$$

- Output to a complex exponential is also a complex exponential of the **same frequency**
- Output is scaled by a complex factor $H(z)$
- We define $H(z)$ as the **z-transform** of the impulse response $h[n]$.

Examples

- Determine the z-transform of the following sequences.

$$x_1[n] = \{\underset{\uparrow}{1}, 2, 3, 4, 5\}$$

$$x_2[n] = a^n u[n]$$

$$x_3[n] = -a^n u[-n - 1]$$

(a is a real number)

Examples

$$\begin{aligned}X_1(z) &= \sum_{k=-\infty}^{\infty} x_1[k]z^{-k} & x_1[n] &= \{ \underset{\uparrow}{1}, 2, 3, 4, 5 \} \\&= \sum_{k=0}^4 x_1[k]z^{-k} \\&= 1z^{-0} + 2z^{-1} + 3z^{-2} + 4z^{-3} + 5z^{-4} \\X_1(z) &= 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 5z^{-4} \\&\text{for all } z \text{ except } z = 0\end{aligned}$$

Examples

$$X_2(z) = \sum_{k=-\infty}^{\infty} x_2[k] z^{-k}$$

$$= \sum_{k=0}^{\infty} a^k z^{-k}$$

$$x_2[n] = a^n u[n]$$

$$= 1 + a^1 z^{-1} + \dots + a^k z^{-k} + \dots$$

$$= \frac{1}{1 - az^{-1}}, \text{ if } |az^{-1}| < 1$$

$$X_2(z) = \frac{1}{1 - az^{-1}}, \text{ if } |z| > |a|$$

Examples

$$X_3(z) = \sum_{k=-\infty}^{\infty} x_3[k] z^{-k}$$

$$x_3[n] = -a^n u[-n - 1]$$

$$= - \sum_{k=-\infty}^{-1} a^k z^{-k}$$

$$= - \sum_{m=0}^{\infty} (az^{-1})^{-m-1}, \text{ where } m = -k - 1$$

$$= - (az^{-1})^{-1} \sum_{m=0}^{\infty} (a^{-1}z)^m$$

Examples

$$\begin{aligned}X_3(z) &= \sum_{k=-\infty}^{\infty} x_3[k] z^{-k} \\&= - (az^{-1})^{-1} \sum_{m=0}^{\infty} (a^{-1}z)^m \quad x_3[n] = -a^n u[-n-1] \\&= - \frac{(az^{-1})^{-1}}{1 - a^{-1}z}, \text{ if } |a^{-1}z| < 1 \\X_3(z) &= \frac{1}{1 - az^{-1}}, \text{ if } |z| < |a|\end{aligned}$$

Examples

$$x_1[n] = \{\underset{\uparrow}{1}, 2, 3, 4, 5\},$$

$$x_2[n] = a^n u[n],$$

$$x_3[n] = -a^n u[-n - 1],$$

$$X_1(z) = 1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 5z^{-4},$$

$$X_2(z) = \frac{1}{1 - az^{-1}},$$

$$X_3(z) = \frac{1}{1 - az^{-1}},$$

for all z
except $z = 0$

if $|z| > |a|$

if $|z| < |a|$

- $X(z)$ is usually a rational expression in z^{-1} .
- The expression for $X(z)$ is accompanied by a restriction on the value of z . We call this restriction the **region of convergence** (ROC).

Examples

$$x_1[n] = \{\underset{\uparrow}{1}, 2, 3, 4, 5\}, \quad X_1(z) = \frac{1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 5z^{-4}}{1}, \quad \begin{array}{l} \text{for all } z \\ \text{except } z = 0 \end{array}$$

$$x_2[n] = a^n u[n], \quad X_2(z) = \frac{1}{1 - az^{-1}}, \quad \text{if } |z| > |a|$$

$$x_3[n] = -a^n u[-n - 1], \quad X_3(z) = \frac{1}{1 - az^{-1}}, \quad \text{if } |z| < |a|$$

- Note that two or more different signal can have the same expression for $X(z)$. The **complete z-domain representation** of a signal $x[n]$ **includes the expression for $X(z)$ and the ROC!**

Examples

	Sequence $x[n]$	z -Transform $X(z)$	ROC
1.	$\delta[n]$	1	All z
2.	$u[n]$	$\frac{1}{1 - z^{-1}}$	$ z > 1$
3.	$a^n u[n]$	$\frac{1}{1 - az^{-1}}$	$ z > a $
4.	$-a^n u[-n - 1]$	$\frac{1}{1 - az^{-1}}$	$ z < a $
5.	$na^n u[n]$	$\frac{az^{-1}}{(1 - az^{-1})^2}$	$ z > a $

Examples

6.	$-na^n u[-n-1]$	$\frac{az^{-1}}{(1-az^{-1})^2}$	$ z < a $
7.	$(\cos \omega_0 n) u[n]$	$\frac{1 - (\cos \omega_0) z^{-1}}{1 - 2(\cos \omega_0) z^{-1} + z^{-2}}$	$ z > 1$
8.	$(\sin \omega_0 n) u[n]$	$\frac{(\sin \omega_0) z^{-1}}{1 - 2(\cos \omega_0) z^{-1} + z^{-2}}$	$ z > 1$
9.	$(r^n \cos \omega_0 n) u[n]$	$\frac{1 - (r \cos \omega_0) z^{-1}}{1 - 2(r \cos \omega_0) z^{-1} + r^2 z^{-2}}$	$ z > r$
10.	$(r^n \sin \omega_0 n) u[n]$	$\frac{(\sin \omega_0) z^{-1}}{1 - 2(r \cos \omega_0) z^{-1} + r^2 z^{-2}}$	$ z > r$

The Region of Convergence

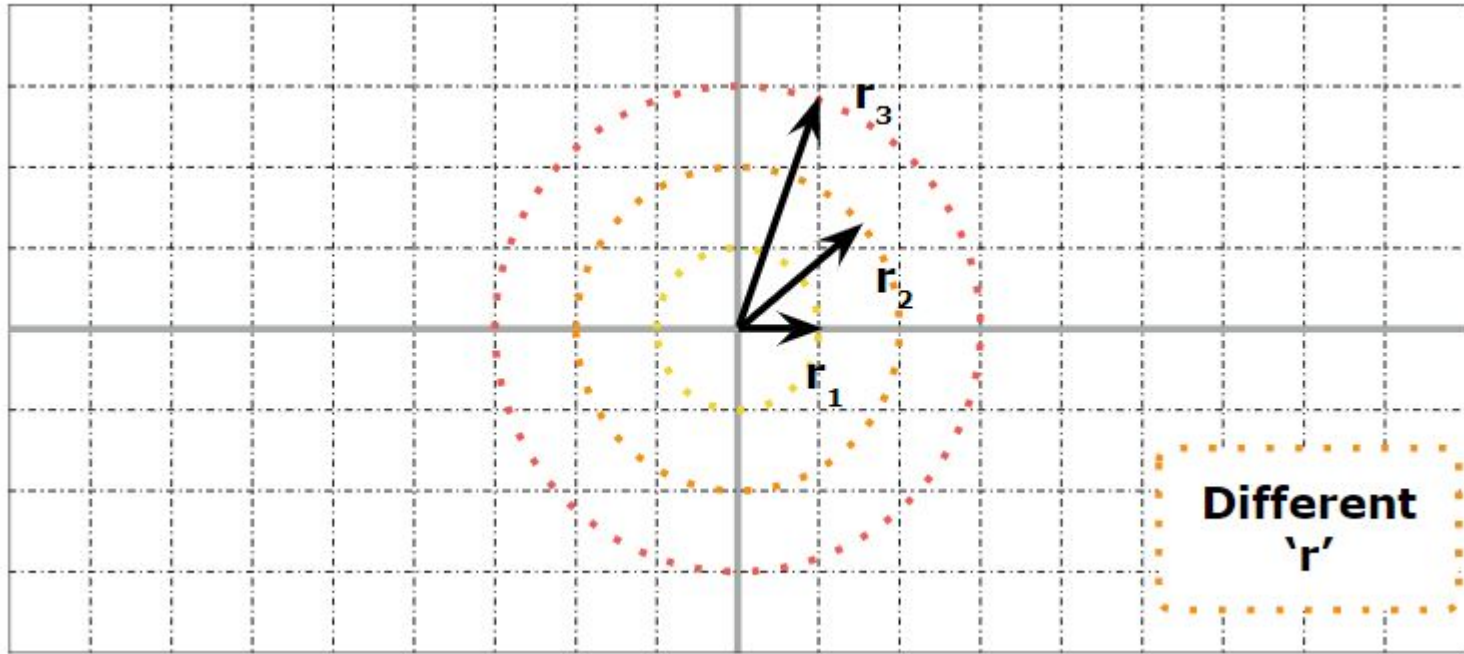
- For convergence of $X(z)$:

$$|X(z)| \leq \sum_{n=-\infty}^{\infty} |x[n]z^{-n}| = \sum_{n=-\infty}^{\infty} |x[n]r^{-n}| < \infty$$

- Since $z = re^{j\omega n}$, the magnitude of \mathbf{r} at different ω affects the convergence of $X(z)$
- Defined by **circular regions**

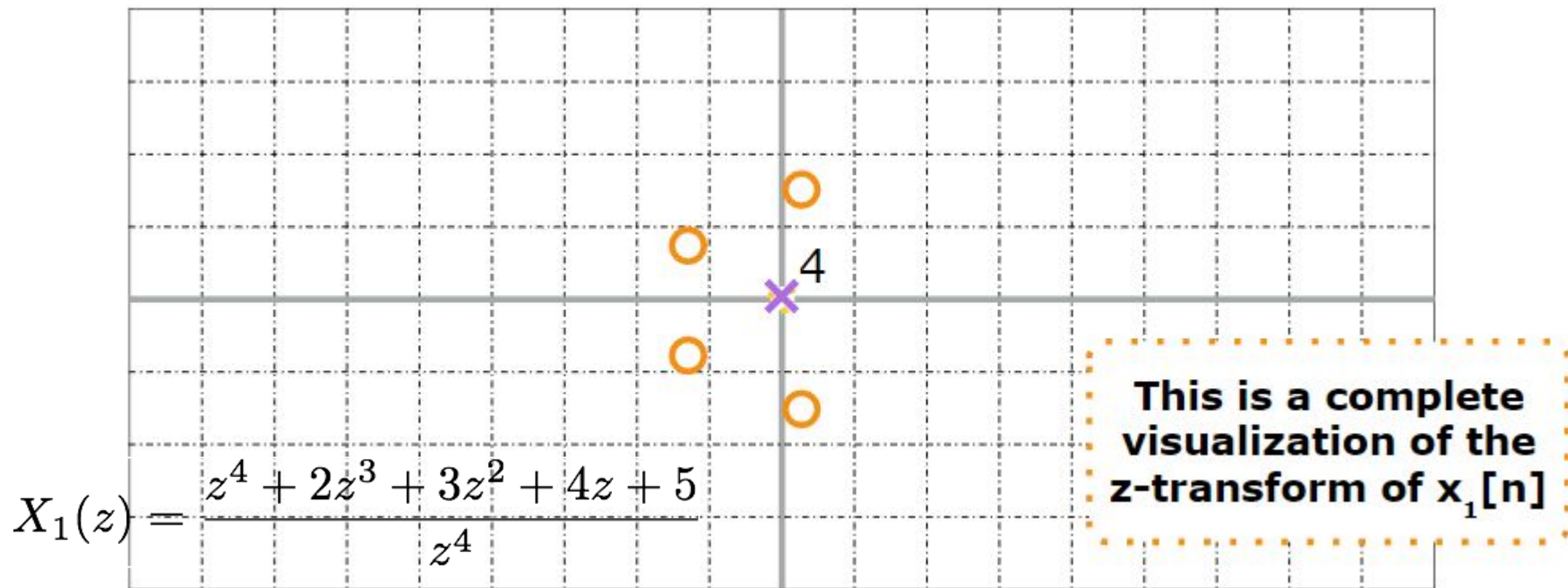
The Region of Convergence

- Illustration of $z = re^{j\omega n}$



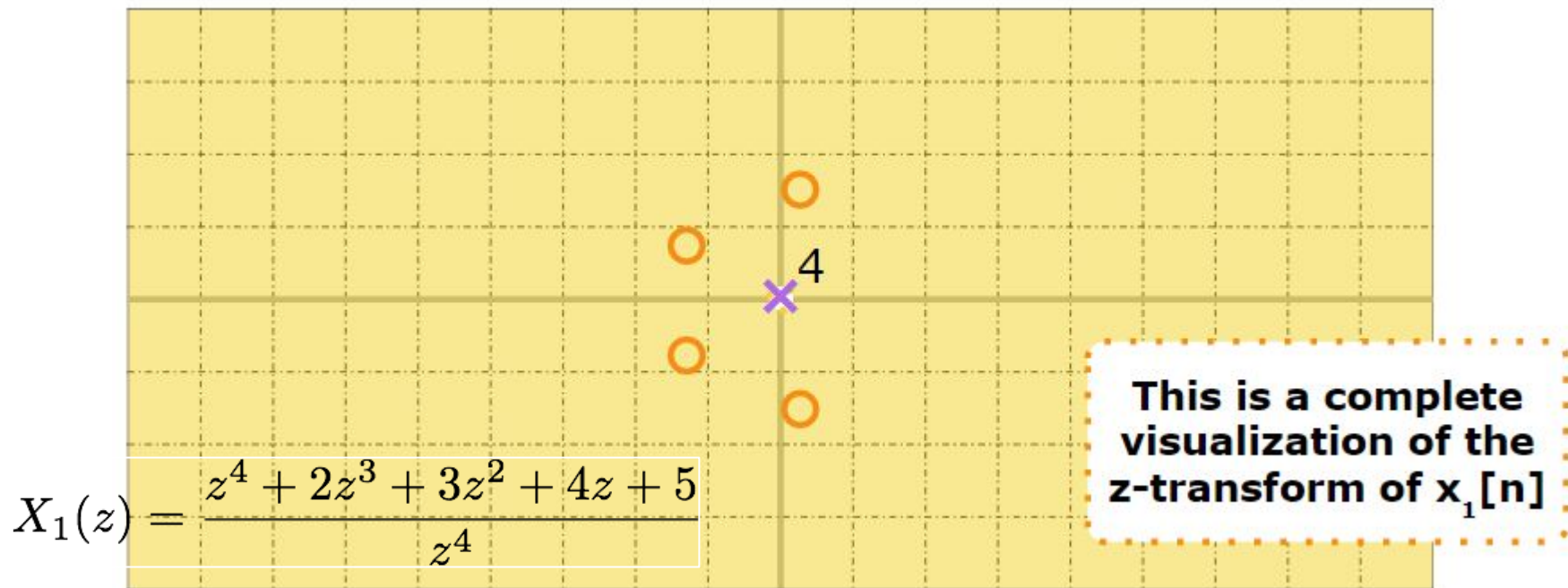
Examples

$$x_1[n] = \{1, 2, 3, 4, 5\}, \quad X_1(z) = \frac{1 + 2z^{-1} + 3z^{-2} + 4z^{-3} + 5z^{-4}}{z^4} \quad \text{for all } z \text{ except } z = 0$$



Examples

$$x_1[n] = \{1, 2, 3, 4, 5\}, \quad X_1(z) = \begin{aligned} &1 + 2z^{-1} + 3z^{-2} \\ &+ 4z^{-3} + 5z^{-4}, \end{aligned} \quad \begin{aligned} &\text{for all } z \\ &\text{except } z = 0 \end{aligned}$$

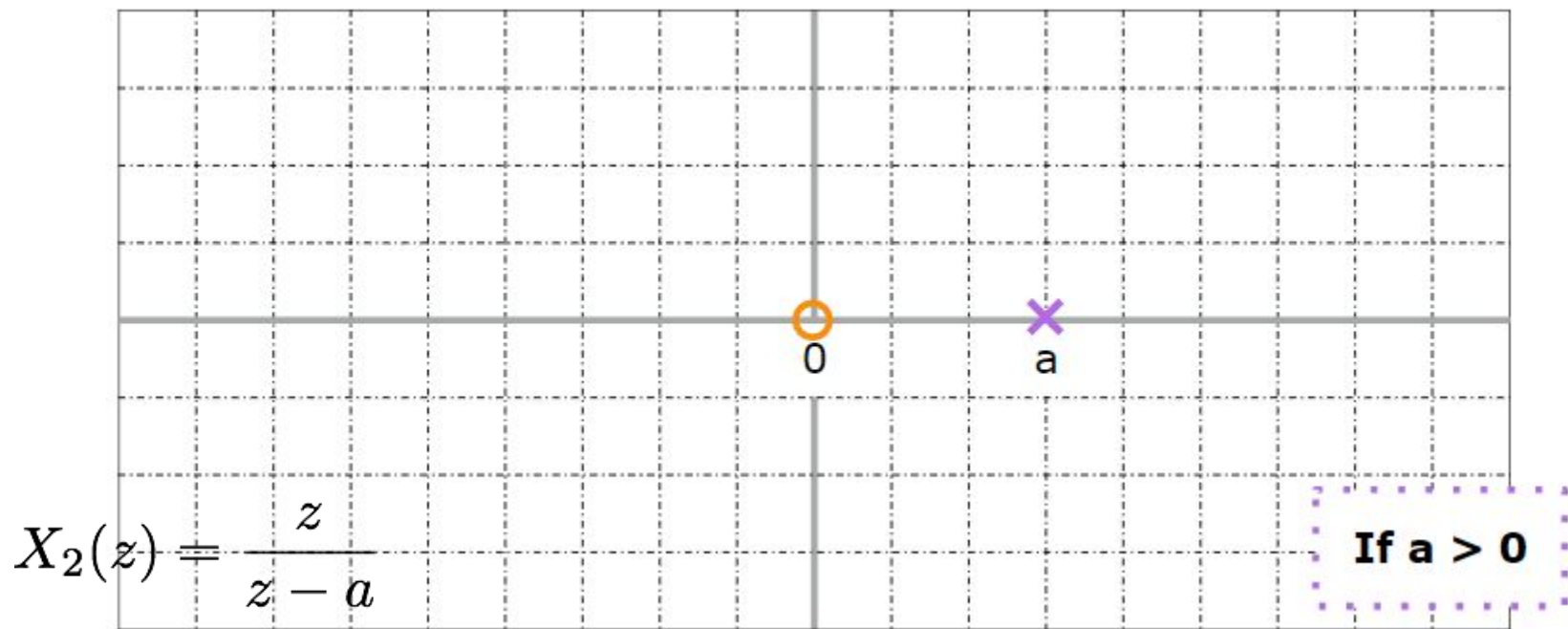


Examples

$$x_2[n] = a^n u[n],$$

$$X_2(z) = \frac{1}{1 - az^{-1}},$$

$$\text{if } |z| > |a|$$

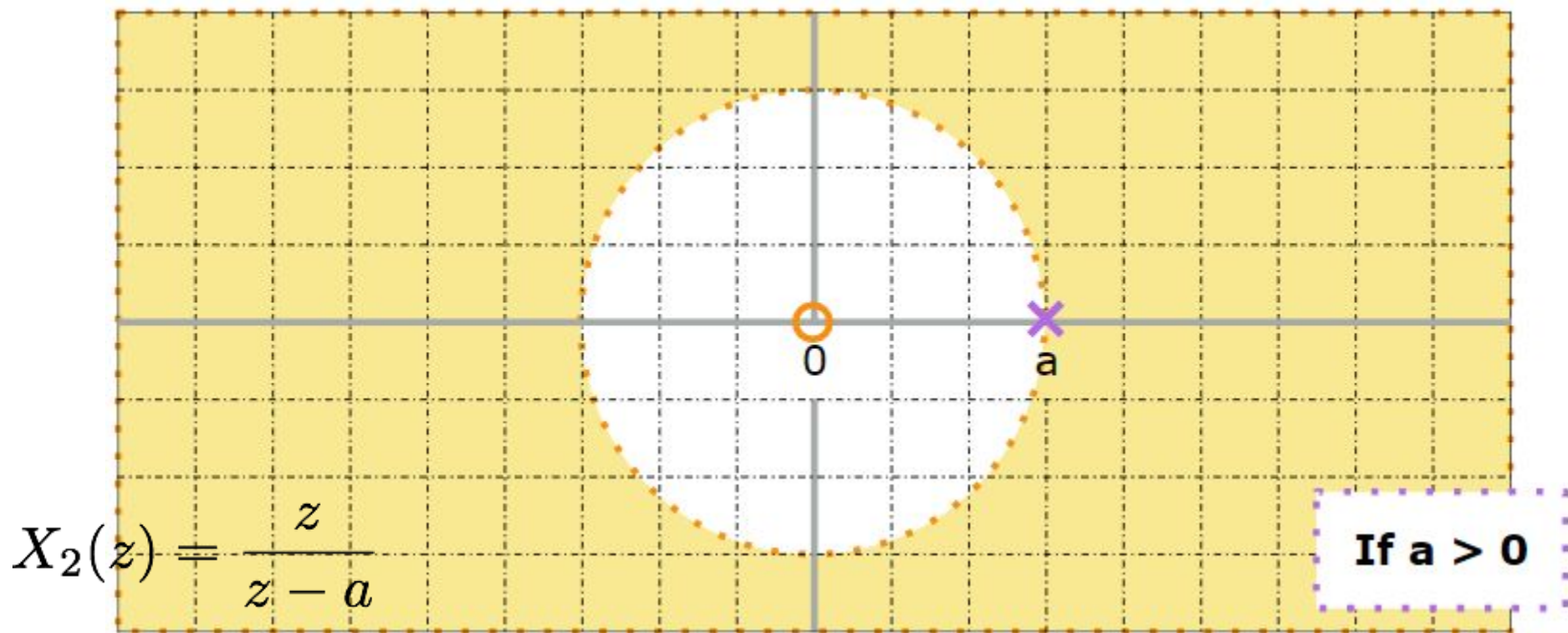


Examples

$$x_2[n] = a^n u[n],$$

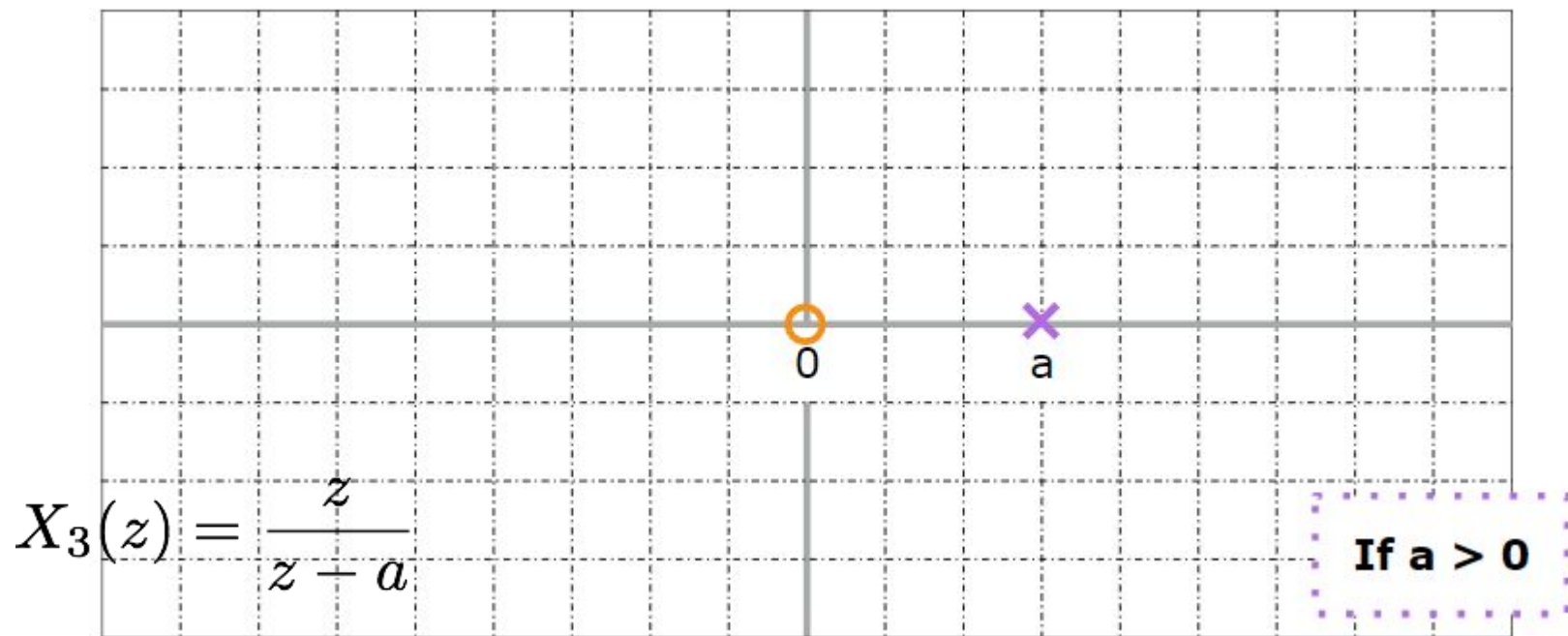
$$X_2(z) = \frac{1}{1 - az^{-1}},$$

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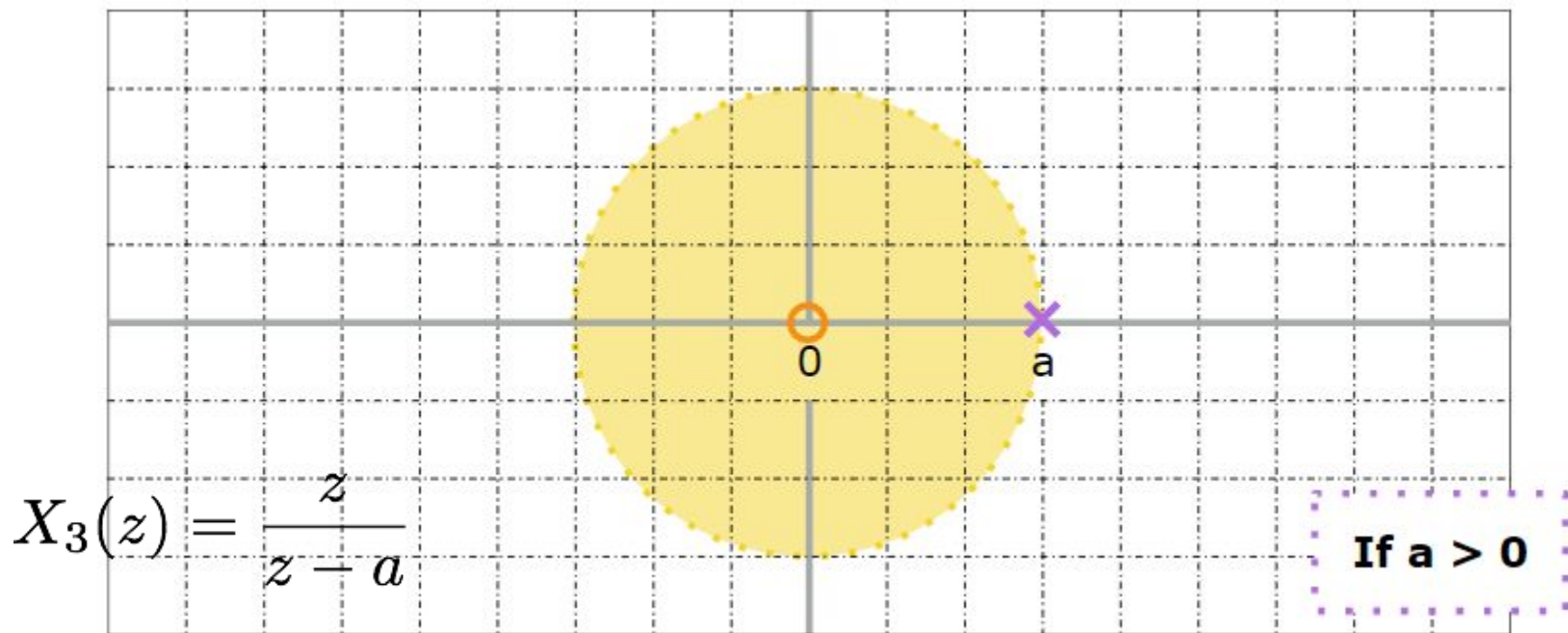
Examples

$$x_3[n] = -a^n u[-n - 1], \quad X_3(z) = \frac{1}{1 - az^{-1}}, \quad \text{if } |z| < |a|$$



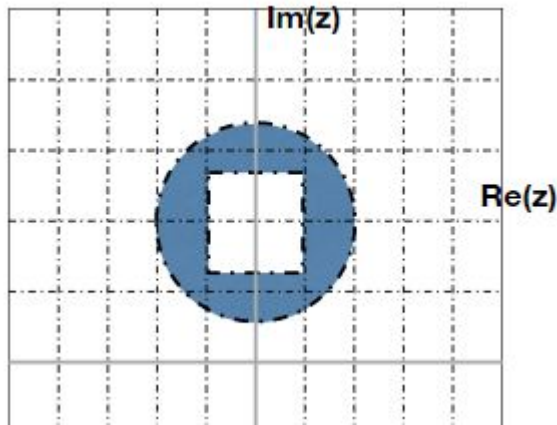
Examples

$$x_3[n] = -a^n u[-n - 1], \quad X_3(z) = \frac{1}{1 - az^{-1}}, \quad \text{if } |z| < |a|$$

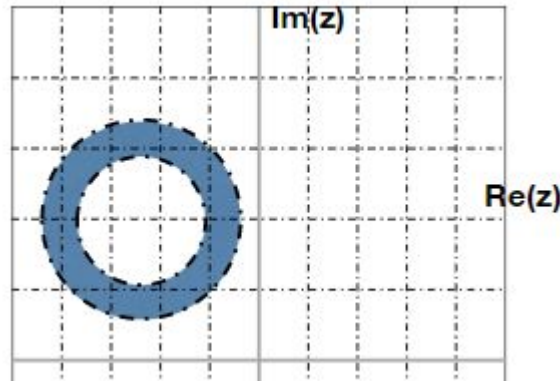


Properties of ROC

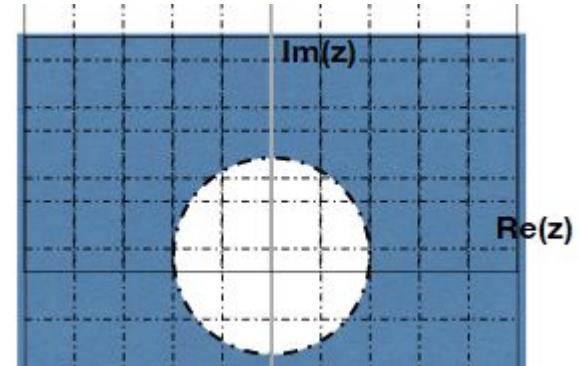
1. The ROC of $X(z)$ consists of a ring in the z -plane **centered at the origin**.



invalid



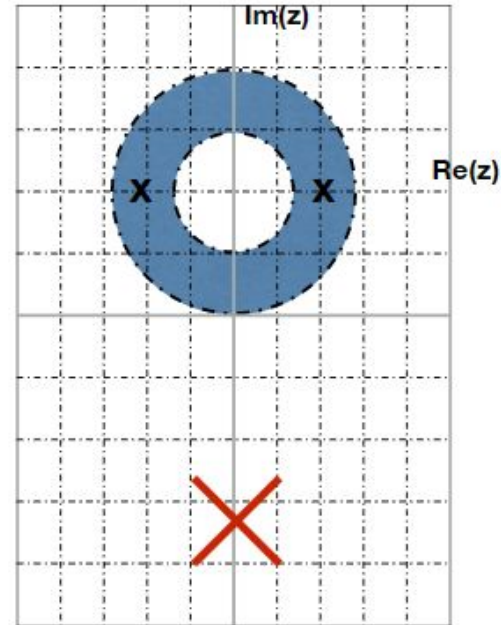
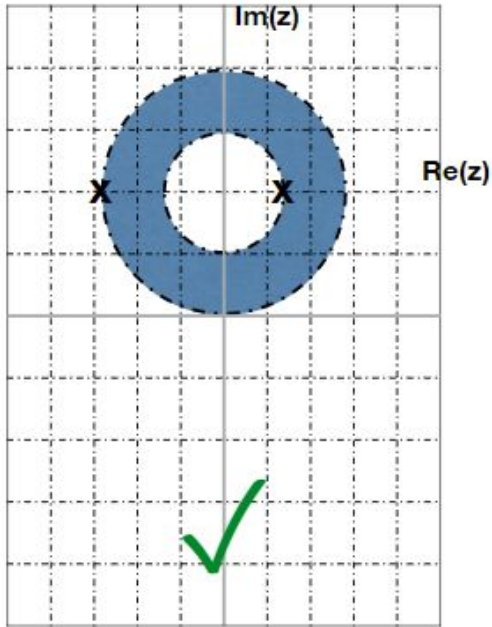
invalid



valid

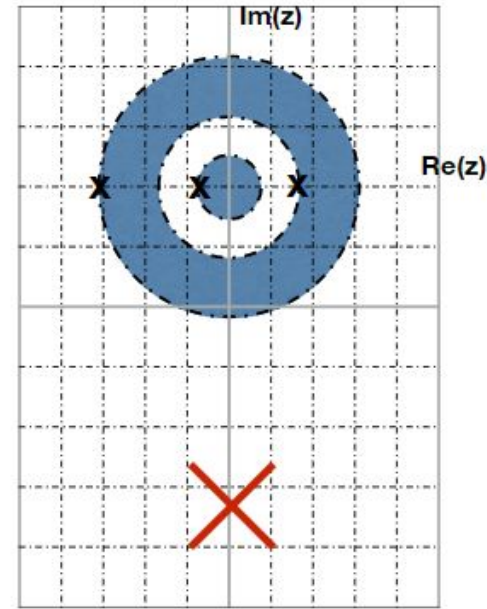
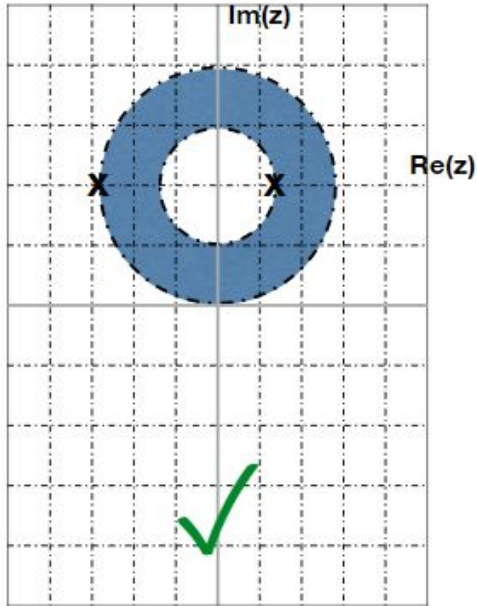
Properties of ROC

2. The ROC does not contain any poles.



Properties of ROC

3. The ROC is a connected (a single contiguous) region.



Properties of ROC

4. If $x[n]$ is of finite duration, then the ROC is the entire z -plane, except possibly $z = 0$ and/or $z = \infty$. (depends on causality)

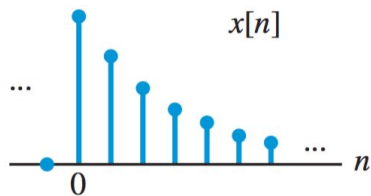
Examples:

1. $X_1 = [1 \ 2 \ 3 \ 4 \ 5 \ \underline{6}] \rightarrow \text{except } z = \infty$
2. $X_2 = [\underline{-1} \ 1 \ -1 \ 1 \ -1 \ 1] \rightarrow \text{except } z = 0$
3. $X_3 = [0 \ 1 \ \underline{0} \ 1 \ 1 \ 0] \rightarrow \text{except } z = 0, \infty$

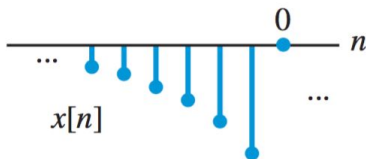
Properties of ROC

5. If $x[n]$ is a right-sided sequence, and if the circle $|z| = r_0$ is in the ROC, then all finite values of z for which $|z| > r_0$ will also be in the ROC.
6. If $x[n]$ is a left-sided sequence, and if the circle $|z| = r_0$ is in the ROC, then all finite values of z for which $|z| < r_0$ will also be in the ROC.
7. If $x[n]$ is two sided, and if the circle $|z| = r_0$ is in the ROC, then the ROC will consist of a ring in the z -plane that includes the circle $|z| = r_0$.

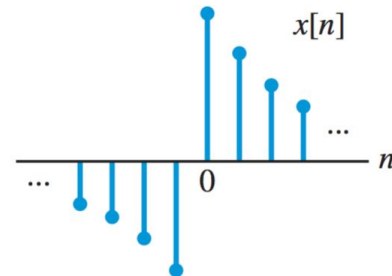
Properties of ROC



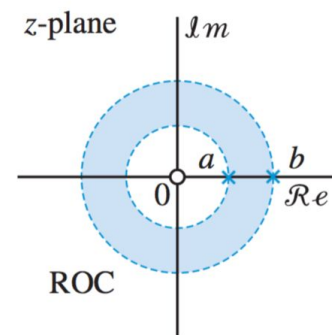
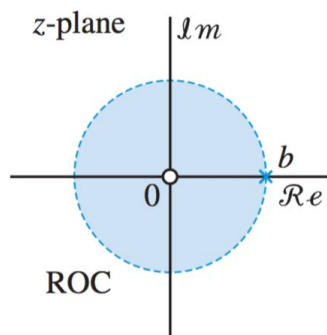
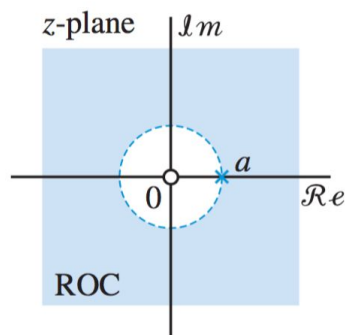
Causal sequence



Anticausal sequence



Two-sided sequence



DT operations in the z-domain

	Property	Sequence	Transform	ROC
		$x[n]$	$X(z)$	R_x
		$x_1[n]$	$X_1(z)$	R_{x_1}
		$x_2[n]$	$X_2(z)$	R_{x_2}
1.	Linearity	$a_1x_1[n] + a_2x_2[n]$	$a_1X_1(z) + a_2X_2(z)$	At least $R_{x_1} \cap R_{x_2}$
2.	Time shifting	$x[n - k]$	$z^{-k}X(z)$	R_x except $z = 0$ or ∞
3.	Scaling	$a^n x[n]$	$X(a^{-1}z)$	$ a R_x$
4.	Differentiation	$nx[n]$	$-z \frac{dX(z)}{dz}$	R_x
5.	Conjugation	$x^*[n]$	$X^*(z^*)$	R_x

DT operations in the z-domain

	Property	Sequence	Transform	ROC
		$x[n]$	$X(z)$	R_x
		$x_1[n]$	$X_1(z)$	R_{x_1}
		$x_2[n]$	$X_2(z)$	R_{x_2}
6.	Real-part	$\text{Re}\{x[n]\}$	$\frac{1}{2}[X(z) + X^*(z^*)]$	At least R_x
7.	Imaginary part	$\text{Im}\{x[n]\}$	$\frac{1}{2j}[X(z) - X^*(z^*)]$	At least R_x
8.	Folding	$x[-n]$	$X(1/z)$	$1/R_x$
9.	Convolution	$x_1[n] * x_2[n]$	$X_1(z)X_2(z)$	At least $R_{x_1} \cap R_{x_2}$
10.	Initial-value theorem	$x[n] = 0$ for $n < 0$	$x[0] = \lim_{z \rightarrow \infty} X(z)$	

Some Notes on Linearity

- The ROC of the linear combination is at least the **intersection of the ROCs** of the individual sequences

$$ROC : R_{x_1} \cap R_{x_2}$$

- If the linear combination yields a finite-duration sequence, the ROC becomes dependent on this resulting sequence.
- If there is no intersection on the ROCs, then there is no z-transform

Example

- Determine the z-transform of the following sequence:

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n - 1]$$

Example

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n - 1]$$

$$a^n u[n] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad |z| > |a|$$

$$-a^n u[-n - 1] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad |z| < |a|$$

$$-a^n u[-n - 1] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad |z| < |a|$$

Example

$$\left(\frac{1}{2}\right)^n u[n] \xleftrightarrow{z} \frac{1}{1 - \frac{1}{2}z^{-1}}, \quad |z| > \frac{1}{2} \quad 2^n u[-n-1] \xleftrightarrow{z} -\frac{1}{1 - 2z^{-1}}, \quad |z| < 2$$

$$x[n] = \left(\frac{1}{2}\right)^n u[n] + 2^n u[-n-1]$$

$$X(z) = \frac{1}{1 - \frac{1}{2}z^{-1}} - \frac{1}{1 - 2z^{-1}}$$

$$ROC : \left(|z| > \frac{1}{2}\right) \cap (|z| < 2) = \frac{1}{2} < |z| < 2$$

Example

- Determine the z-transform of the following sequence:

$$x[n] = 2^n u[n + 3]$$

Example

- Determine the z-transform of the following sequence:

$$x[n] = 2^n u[n + 3]$$

$$a^n u[n] \xleftrightarrow{z} \frac{1}{1 - az^{-1}}, \quad ROC : |z| > |a|$$

$$\begin{aligned} x[n] &= 2^n u[n + 3] \\ &= 2^{-3} 2^{n+3} u[n + 3] \end{aligned}$$

Example

$$\begin{aligned}x[n] &= 2^n u[n+3] \\ &= 2^{-3} 2^{n+3} u[n+3]\end{aligned}$$

$$2^n u[n] \leftrightarrow \frac{1}{1 - 2z^{-1}}, \quad |z| > 2$$

$$2^{n+3} u[n+3] \leftrightarrow \frac{z^3}{1 - 2z^{-1}}, \quad \infty > |z| > 2$$

$$2^n u[n+3] \leftrightarrow \frac{2^{-3} z^3}{1 - 2z^{-1}}, \quad \infty > |z| > 2$$

Example

- Convolve the two signals using z-transform:

$$x[n] = 3^{n+1}u[n], \quad w[n] = 3^n u[n-1]$$

Example

$$x[n] = 3^{n+1}u[n] = (3)3^n u[n]$$

$$w[n] = 3^n u[n-1] = (3)3^{n-1} u[n-1]$$

$$(3)3^n u[n] \longleftrightarrow \frac{3}{1 - 3z^{-1}}, ROC : |z| > 3$$

$$(3)3^{n-1} u[n-1] \longleftrightarrow \frac{3z^{-1}}{1 - 3z^{-1}}, ROC : |z| > 3$$

Example

$$\begin{aligned}x[n] * w[n] &\longleftrightarrow \left(\frac{3}{1 - 3z^{-1}} \right) \left(\frac{3z^{-1}}{1 - 3z^{-1}} \right), ROC : |z| > 3 \\&\longleftrightarrow \frac{9z^{-1}}{(1 - 3z^{-1})^2}, ROC : |z| > 3\end{aligned}$$

$$5. \quad na^n u[n] \quad \frac{az^{-1}}{(1 - az^{-1})^2} \quad |z| > |a|$$

$$x[n] * w[n] = (3)n3^n u[n] = n3^{n+1} u[n]$$

Summary

- Z Transform is a mathematical tool to analyze discrete time signals in a new domain
- Z Transform existence is dictated by the Region of Convergence
- Z Transform properties can be useful in analyzing and solving the responses in a DT system

For further reading...

- Chapter 3.1-3.2, 3.4
“Applied Digital Signal Processing, by Manolakis, D. & Ingle, V.”
- Chapters 10.0-10.2, 10.5
“Signals and Systems by Oppenheim, A & Willsky, A.”

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