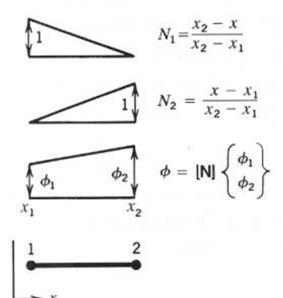
Interpolación:

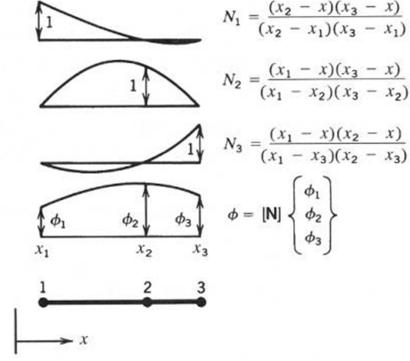
$$\phi(\mathbf{x}) \cong \widetilde{\phi}(\mathbf{x}) = \sum_{i=0}^{n} \mathbf{a}_{i} \mathbf{x}^{i}; \quad \widetilde{\phi}(\mathbf{x}) = \underbrace{\{1 \quad \mathbf{x} \quad \cdots \quad \mathbf{x}^{n}\}}_{\{\mathbf{X}(\mathbf{x})\}} \begin{bmatrix} \mathbf{a}_{0} \\ \mathbf{a}_{1} \\ \vdots \\ \mathbf{a}_{n} \end{bmatrix}; \quad \underbrace{\{\phi_{0} \\ \phi_{1} \\ \vdots \\ \phi_{n} \}}_{\{\phi_{e}\}} = \underbrace{\begin{bmatrix} 1 \quad \mathbf{x}_{0} \quad \mathbf{x}_{0}^{2} \quad \mathbf{x}_{0}^{n} \\ 1 \quad \mathbf{x}_{1} \quad \mathbf{x}_{1}^{2} \quad \mathbf{x}_{1}^{n} \\ \vdots \quad \vdots \quad \vdots \quad \vdots \\ 1 \quad \mathbf{x}_{n} \quad \mathbf{x}_{n}^{2} \quad \mathbf{x}_{n}^{n} \end{bmatrix}}_{\{\phi_{e}\}} \begin{bmatrix} \mathbf{a}_{0} \\ \mathbf{a}_{1} \\ \vdots \\ \mathbf{a}_{n} \end{bmatrix}; \quad \{\mathbf{a}\} = [\mathbf{A}]^{-1} \{\phi_{e}\}$$

$$\widetilde{\phi}(x) = \{X(x)\}\{a\} = \underbrace{\{X\}[A]^{-1}}_{\text{N}}\{\phi_e\} = [N(x)]\{\phi_e\}$$
Funciones de forma

Condiciones

$$\begin{cases}
[N_i(x_i)] = 1 \land [N_i(x_j)] = 0 \\
i \neq j \\
\sum_{i=0}^{n} N_i = 1
\end{cases}$$





Elemento Barra 3 nodos:

$$\widetilde{\phi}(\mathbf{x}) = \begin{cases} 1 & \mathbf{x} & \mathbf{x}^2 \end{cases} \begin{cases} \mathbf{a}_0 \\ \mathbf{a}_1 \\ \mathbf{a}_2 \end{cases}; \begin{cases} \mathbf{\phi}_0 \\ \mathbf{\phi}_1 \\ \mathbf{a}_2 \end{cases}; \begin{cases} \mathbf{\phi}_0 \\ \mathbf{\phi}_1 \\ \mathbf{a}_2 \end{cases}; \begin{cases} \mathbf{a}_0 \\ \mathbf{a}_1 \\ \mathbf{a}_2 \end{cases};$$

Matriz de Rigidez:

$$\varepsilon_{x} = \underbrace{\{\partial\}[N(x)]}_{[B(x)]} \underbrace{\begin{cases} u_{1} \\ u_{2} \\ u_{3} \end{cases}} = \underbrace{\begin{bmatrix} 1 \\ 6 \\ -3 + 2x \end{bmatrix}}^{T} \underbrace{\begin{cases} u_{1} \\ u_{2} \\ u_{3} \end{cases}}; \qquad [K] = \int_{L_{e}} [B]^{T} E[B] A dL = \underbrace{\frac{AE}{36} \int_{L_{e}} \begin{cases} -12 + 4x \\ 15 - 6x \\ -3 + 2x \end{cases}}^{T} dL$$

$$[K] = \frac{AE}{36} \int_{L_e} \begin{bmatrix} (-12+4x)^2 & (-12+4x)(15-6x) & (-12+4x)(-3+2x) \\ (-12+4x)(15-6x) & (15-6x)^2 & (15-6x)(-3+2x) \\ (-12+4x)(-3+2x) & (-3+2x)(15-6x) & (-3+2x)^2 \end{bmatrix} dL = \frac{AE}{36} \begin{bmatrix} 48 & -54 & 6 \\ -54 & 81 & -27 \\ 68 & 21 \end{bmatrix}$$

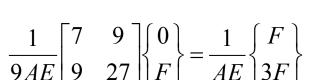
Solución Exacta:

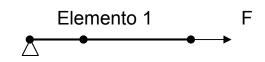
 $[K]{D} = {R}$

$$u_3 = 3\frac{F}{AE}$$

1 Elemento Barra de 3 nodos

$$\frac{AE}{12} \begin{bmatrix} 24 & -18 & 2 \\ -18 & 27 & -9 \\ 2 & -9 & 7 \end{bmatrix} \begin{bmatrix} 0 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} R \\ 0 \\ F \end{bmatrix}$$





2 Elementos Barra de 2 nodos

$$AE\begin{bmatrix} 1 & -1 & 0 \\ -1 & 1 + \frac{1}{2} & -\frac{1}{2} \\ 0 & -\frac{1}{2} & \frac{1}{2} \end{bmatrix} \begin{bmatrix} 0 \\ u_2 \\ u_3 \end{bmatrix} = \begin{bmatrix} R \\ 0 \\ F \end{bmatrix}$$

$$\frac{1}{AE} \begin{bmatrix} 1 & 1 \\ 1 & 3 \end{bmatrix} \begin{Bmatrix} 0 \\ F \end{Bmatrix} = \frac{1}{AE} \begin{Bmatrix} F \\ 3F \end{Bmatrix}$$

Elemento Viga:

$$\epsilon_{x}(x,y) = \frac{\partial u(x,y)}{\partial x} = \frac{\partial \left(-y\frac{\partial v(x)}{\partial x}\right)}{\partial x} = -y\frac{\partial^{2}v(x)}{\partial x^{2}} = -y\kappa$$

$$\kappa = \frac{\partial^{2} v(x)}{\partial x^{2}} = \frac{\partial^{2} \{N(x)\}}{\partial x^{2}} \{d\} = \begin{cases} -\frac{6}{L^{2}} + \frac{12x}{L^{3}} \\ -\frac{4}{L} + \frac{6x}{L^{2}} \\ \frac{6}{L^{2}} - \frac{12x}{L^{3}} \\ -\frac{2}{L} + \frac{6x}{L^{2}} \end{cases} \begin{cases} v_{1} \\ \theta_{z1} \\ v_{2} \\ \theta_{z2} \end{cases}$$

Matriz de Rigidez

$$[K] = \int_{L_e} [B]^T E I_z [B] dx;$$

Elemento Viga:

$$v(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 = \begin{cases} 1 & x & x^2 & x^3 \\ a_1 & a_2 \\ a_3 \end{cases}$$

$$v(x) = a_0 + a_1 x + a_2 x^2 + a_3 x^3 = \begin{cases} 1 & x & x^2 & x^3 \\ a_1 & a_2 \\ a_3 & a_3 \end{cases}$$

$$v = \frac{3x^2}{t^2} - \frac{2x^3}{t^3}$$

$$\begin{cases} V_1 \\ \theta_{z1} \\ V_2 \\ \theta_{z2} \end{cases} = \begin{cases} a_0 + a_1 x + a_2 x^2 + a_3 x^3 \\ a_1 + 2a_2 x + 3a_3 x^2 \\ a_0 + a_1 x + a_2 x^2 + a_3 x^3 \\ a_1 + 2a_2 x + 3a_3 x^2 \end{cases} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & 1 & 0 & 0 \\ 1 & L & L^2 & L^3 \\ 0 & 1 & 2L & 3L^2 \end{bmatrix} \begin{cases} a_0 \\ a_1 \\ a_2 \\ a_3 \end{cases}$$

$$\begin{vmatrix} a_1 \\ b_2 \\ a_1 \\ a_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_1 \\ b_2 \\ a_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

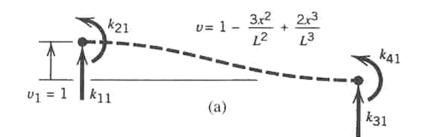
$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

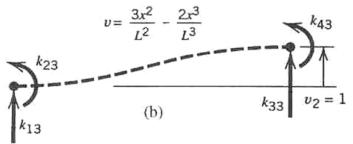
$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

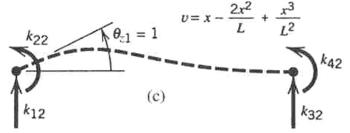
$$\begin{vmatrix} a_2 \\ b_2 \\ a_3 \end{vmatrix}$$

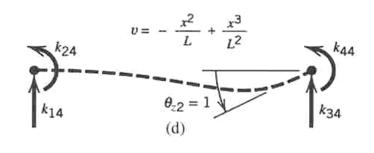
$$\begin{vmatrix} a_1 \\ b_2 \\ a_3 \end{vmatrix}$$

$$[N] \begin{cases} v_1 \\ \theta_{z1} \\ v_2 \\ \theta_{z2} \end{cases} = \{X\} [A]^{-1} \begin{cases} v_1 \\ \theta_{z1} \\ v_2 \\ \theta_{z2} \end{cases} = \begin{bmatrix} 1 - \frac{3x^2}{L^2} + \frac{2x^3}{L^3} \\ x - \frac{2x^2}{L} + \frac{x^3}{L^2} \\ -\frac{2x^3}{L^3} + \frac{3x^2}{L^2} \\ -\frac{x^2}{L} + \frac{x^3}{L^2} \end{bmatrix}^T \begin{cases} v_1 \\ \theta_{z1} \\ v_2 \\ \theta_{z2} \end{cases}$$



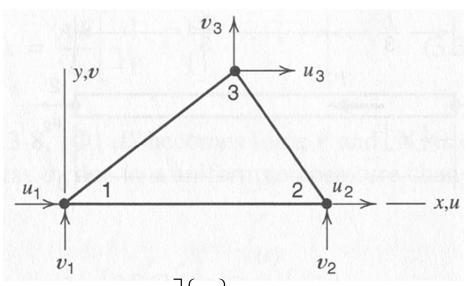






Deformación Constante - CST Problema Plano

La matriz no depende de la posición (mas facil de integrar) $u(x,y) = a_1 + a_2 x + a_3 y = \begin{cases} 1 & x & y \end{cases} \begin{cases} a_1 & \text{integrar} \\ a_2 & \text{integrar} \end{cases} \begin{cases} u(x_1,y_1) = u_1 \\ u(x_2,y_2) = u_2 \\ u(x_3,y_3) = u_3 \end{cases}$



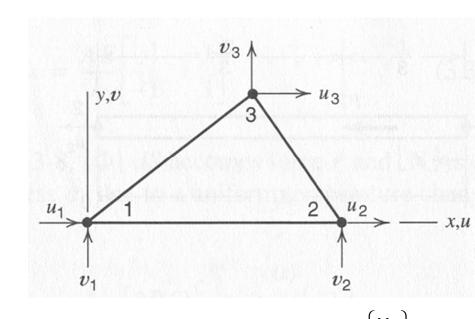
$$\begin{cases}
 a_1 \\
 a_2 \\
 a_3
\end{cases} =
\begin{bmatrix}
 1 & x_1 & y_1 \\
 1 & x_2 & y_2 \\
 1 & x_3 & y_3
\end{bmatrix}^{-1}
\begin{cases}
 u_1 \\
 u_2 \\
 u_3
\end{cases} =
\frac{1}{\det(A)}
\begin{bmatrix}
 x_2 y_3 - x_3 y_2 & x_3 y_1 - x_1 y_3 & x_1 y_2 - x_2 y_1 \\
 y_2 - y_3 & y_3 - y_1 & y_1 - y_2 \\
 x_3 - x_2 & x_1 - x_3 & x_2 - x_1
\end{bmatrix}
\begin{bmatrix}
 u_1 \\
 u_2 \\
 u_3
\end{cases}$$

$$\mathbf{u}(\mathbf{x},\mathbf{y}) = \underbrace{\{1 \quad \mathbf{x} \quad \mathbf{y}\}[\mathbf{A}]^{-1}}_{\mathbf{1}\mathbf{x}\mathbf{3}} \underbrace{\{\mathbf{u}_{1} \\ \mathbf{u}_{2} \\ \mathbf{u}_{3}\}}_{\mathbf{1}\mathbf{x}\mathbf{3}} = \{\mathbf{N}_{1} \quad \mathbf{N}_{2} \quad \mathbf{N}_{3}\} \underbrace{\{\mathbf{u}_{1} \\ \mathbf{u}_{2} \\ \mathbf{u}_{3}\}}_{\mathbf{1}\mathbf{x}\mathbf{3}} = \mathbf{a}_{1} + \mathbf{a}_{2}\mathbf{x} + \mathbf{a}_{3}\mathbf{y}$$

$$\mathbf{v}(\mathbf{x},\mathbf{y}) = \underbrace{\{1 \quad \mathbf{x} \quad \mathbf{y}\}[\mathbf{A}]^{-1}}_{\left[\mathbf{N}\right]} \underbrace{\{\mathbf{v}_{1} \\ \mathbf{v}_{2} \\ \mathbf{v}_{3}\}}_{=} = \underbrace{\{\mathbf{N}_{1} \quad \mathbf{N}_{2} \quad \mathbf{N}_{3}\}}_{=\mathbf{v}_{3}} \underbrace{\{\mathbf{v}_{1} \\ \mathbf{v}_{2} \\ \mathbf{v}_{3}\}}_{=} = \mathbf{a}_{4} + \mathbf{a}_{5}\mathbf{x} + \mathbf{a}_{6}\mathbf{y}$$

Deformación Constante - CST Deformaciones

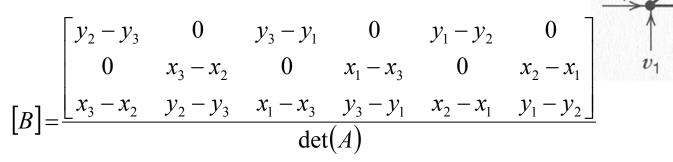
$$\begin{split} \mathbf{N}_1 &= \det(\mathbf{A})^{\!-1} \big(\big(\mathbf{x}_2 \mathbf{y}_3 - \mathbf{x}_3 \mathbf{y}_2 \big) + \mathbf{x} \big(\mathbf{y}_2 - \mathbf{y}_3 \big) + \mathbf{y} \big(\mathbf{x}_3 - \mathbf{x}_2 \big) \big) \\ \mathbf{N}_2 &= \det(\mathbf{A})^{\!-1} \big(\big(\mathbf{x}_3 \mathbf{y}_1 - \mathbf{x}_1 \mathbf{y}_3 \big) + \mathbf{x} \big(\mathbf{y}_3 - \mathbf{y}_1 \big) + \mathbf{y} \big(\mathbf{x}_1 - \mathbf{x}_3 \big) \big) \\ \mathbf{N}_3 &= \det(\mathbf{A})^{\!-1} \big(\big(\mathbf{x}_1 \mathbf{y}_2 - \mathbf{x}_2 \mathbf{y}_1 \big) + \mathbf{x} \big(\mathbf{y}_1 - \mathbf{y}_2 \big) + \mathbf{y} \big(\mathbf{x}_2 - \mathbf{x}_1 \big) \big) \end{split}$$

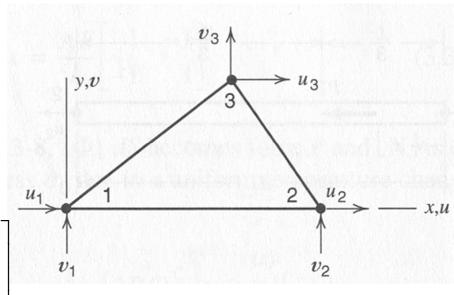


$$\begin{cases}
\epsilon_{x} \\
\epsilon_{y} \\
\gamma_{xy}
\end{cases} = \begin{bmatrix}
\frac{\partial}{\partial x} & 0 \\
0 & \frac{\partial}{\partial y} \\
\frac{\partial}{\partial y} & \frac{\partial}{\partial x}
\end{bmatrix} \begin{cases}
\mathbf{u} \\
\mathbf{v} \\
\mathbf{v}
\end{cases}; \quad \epsilon_{x} = \frac{\partial \mathbf{u}}{\partial x} = \mathbf{a}_{2} \\
\mathbf{v}_{1} \\
\mathbf{v}_{2} \\
\mathbf{v}_{2} \\
\mathbf{v}_{3} \\
\mathbf{v}_{3}
\end{cases}; \quad [\mathbf{B}] \{\mathbf{d}\} = \{\partial\} \begin{bmatrix}
\mathbf{N}_{1} & 0 & \mathbf{N}_{2} & 0 & \mathbf{N}_{3} & 0 \\
0 & \mathbf{N}_{1} & 0 & \mathbf{N}_{2} & 0 & \mathbf{N}_{3}
\end{bmatrix} \begin{cases}
\mathbf{v}_{1} \\
\mathbf{v}_{2} \\
\mathbf{v}_{2} \\
\mathbf{u}_{3} \\
\mathbf{v}_{3}
\end{cases}$$

$$\begin{bmatrix} \mathbf{B} \end{bmatrix} = \begin{bmatrix} \frac{\partial \mathbf{N}_1}{\partial \mathbf{x}} & \mathbf{0} & \mathbf{0} \\ \mathbf{0} & \frac{\partial \mathbf{N}_1}{\partial \mathbf{y}} & \cdots & \frac{\partial \mathbf{N}_3}{\partial \mathbf{y}} \\ \frac{\partial \mathbf{N}_1}{\partial \mathbf{y}} & \frac{\partial \mathbf{N}_1}{\partial \mathbf{x}} & \cdots & \frac{\partial \mathbf{N}_3}{\partial \mathbf{x}} \end{bmatrix} = \det(\mathbf{A})^{-1} \begin{bmatrix} \mathbf{y}_2 - \mathbf{y}_3 & \mathbf{0} & \mathbf{y}_3 - \mathbf{y}_1 & \mathbf{0} & \mathbf{y}_1 - \mathbf{y}_2 & \mathbf{0} \\ \mathbf{0} & \mathbf{x}_3 - \mathbf{x}_2 & \mathbf{0} & \mathbf{x}_1 - \mathbf{x}_3 & \mathbf{0} & \mathbf{x}_2 - \mathbf{x}_1 \\ \mathbf{x}_3 - \mathbf{x}_2 & \mathbf{y}_2 - \mathbf{y}_3 & \mathbf{x}_1 - \mathbf{x}_3 & \mathbf{y}_3 - \mathbf{y}_1 & \mathbf{x}_2 - \mathbf{x}_1 & \mathbf{y}_1 - \mathbf{y}_2 \end{bmatrix}$$

Deformación Constante - CST Matriz de Rigidez

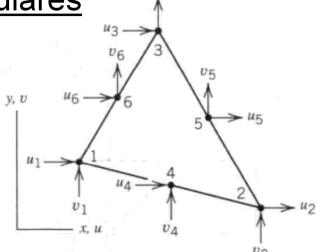


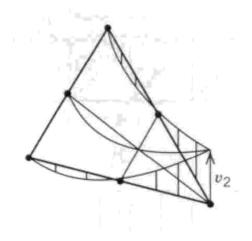


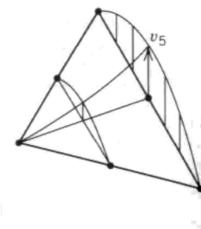
$$[K] = \int_{S} [B]^{T} [C] [B] ds$$

$$[K] = \frac{S}{\det(A)} \begin{bmatrix} y_2 - y_3 & 0 & x_3 - x_2 \\ 0 & x_3 - x_2 & y_2 - y_3 \\ y_3 - y_1 & 0 & x_1 - x_3 \\ 0 & x_1 - x_3 & y_3 - y_1 \\ y_1 - y_2 & 0 & x_2 - x_1 \\ 0 & x_2 - x_1 & y_1 - y_2 \end{bmatrix} \underbrace{E}_{1} \begin{bmatrix} 1 & \nu & 0 \\ \nu & 1 & 0 \\ 0 & 0 & \frac{1 - \nu}{2} \end{bmatrix} [B]$$

Deformación Lineal - LST







$$u = a_1 + a_2 x + a_3 y + a_4 x^2 + a_5 xy + a_6 y^2$$

$$v = a_7 + a_8 x + a_9 y + a_{10} x^2 + a_{11} xy + a_{12} y^2$$

La presición del poinomio depende de si completo un piso:

El LST tiene el segundo piso completo

Deformaciones

$$\varepsilon_{x} = \frac{\partial u}{\partial x} = a_{2} + 2a_{4}x + a_{5}y$$

$$\varepsilon_{y} = \frac{\partial v}{\partial y} = a_{9} + a_{11}x + 2a_{12}y$$

$$\gamma_{xy} = \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = a_{3} + a_{8} + (a_{5} + 2a_{10})x + (2a_{6} + a_{11})y$$

Elementos Rectangulares

Deformación Constante - Q4

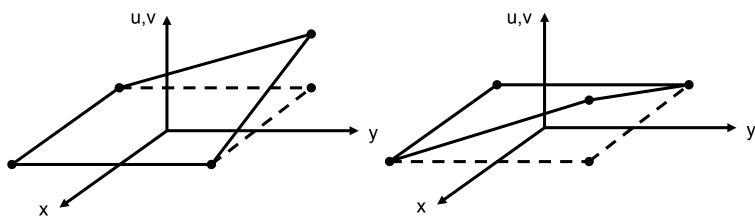
$$u = a_1 + a_2x + a_3y + a_4xy = N_1u_1 + \cdots + N_4u_4$$

 $v = a_5 + a_6x + a_7y + a_8xy = N_1v_1 + \cdots + N_4v_4$

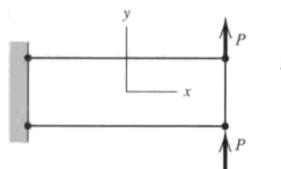
$$\varepsilon_{x} = \frac{\partial u}{\partial x} = a_{2} + a_{4}y$$

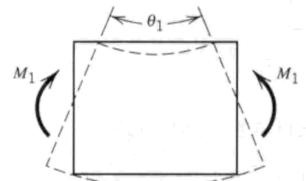
Deformaciones
$$\epsilon_y = \frac{\partial v}{\partial y} = a_7 + a_8 x$$

$$\gamma_{xy} = \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = a_3 + a_6 + a_4 x + a_8 y$$

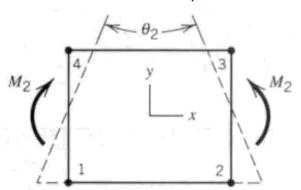


Corte Espúreo





No es bueno para simular vigas, mala deformación por corte.

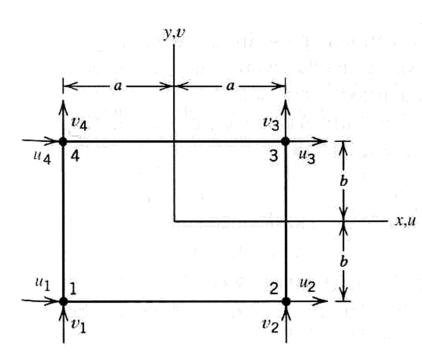


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El corte espúreo se lleva la energía de deformación a corte, que para estas cuentas no existe. Quiere decir que se va a curvar menos de lo que realmente debería.

<u>Problema Plano – Tensión Plana</u>

Matriz Constitutiva (E=1,
$$v$$
=0.33): $C := \begin{pmatrix} 1.125 & 0.375 & 0 \\ 0.375 & 1.125 & 0 \\ 0 & 0 & 0.375 \end{pmatrix}$



Funciones de Forma:

$$N1(x,y) = \frac{(a-x)\cdot(b-y)}{4a\cdot b} \qquad N2 = \frac{(a+x)\cdot(b-y)}{4a\cdot b}$$

$$N3 = \frac{(a+x)\cdot(y+b)}{4a\cdot b}$$

$$N4 = \frac{(a-x)\cdot(y+b)}{4a\cdot b}$$

$$N(x,y) = \begin{pmatrix} N1(x,y) & 0 & N2(x,y) & 0 & N3(x,y) & 0 & N4(x,y) & 0 \\ 0 & N1(x,y) & 0 & N2(x,y) & 0 & N3(x,y) & 0 & N4(x,y) \end{pmatrix}$$

Matriz Desplazamiento- Deformación: [B]=[∂][N]

$$B(x,y) \coloneqq \begin{pmatrix} \frac{d}{dx}N(x,y)_1 & 0 & \frac{d}{dx}N(x,y)_2 & 0 & \frac{d}{dx}N(x,y)_3 & 0 & \frac{d}{dx}N(x,y)_4 & 0 \\ \\ 0 & \frac{d}{dy}N(x,y)_1 & 0 & \frac{d}{dy}N(x,y)_2 & 0 & \frac{d}{dy}N(x,y)_3 & 0 & \frac{d}{dy}N(x,y)_4 \\ \\ \frac{d}{dy}N(x,y)_1 & \frac{d}{dx}N(x,y)_1 & \frac{d}{dy}N(x,y)_2 & \frac{d}{dx}N(x,y)_2 & \frac{d}{dy}N(x,y)_3 & \frac{d}{dx}N(x,y)_3 & \frac{d}{dy}N(x,y)_4 & \frac{d}{dx}N(x,y)_4 \end{pmatrix}_{77}$$

Problema Plano - Tensión Plana

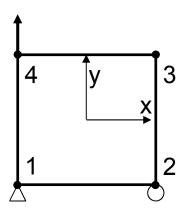
Adoptando a=1 y b=1

$$B(x,y) \rightarrow \begin{pmatrix} \frac{-1}{4} + \frac{1}{4} \cdot y & 0 & \frac{1}{4} - \frac{1}{4} \cdot y & 0 & \frac{1}{4} \cdot y + \frac{1}{4} & 0 & \frac{-1}{4} \cdot y - \frac{1}{4} & 0 \\ 0 & \frac{-1}{4} + \frac{1}{4} \cdot x & 0 & \frac{-1}{4} - \frac{1}{4} \cdot x & 0 & \frac{1}{4} + \frac{1}{4} \cdot x & 0 & \frac{1}{4} - \frac{1}{4} \cdot x \\ \frac{-1}{4} + \frac{1}{4} \cdot x & \frac{-1}{4} + \frac{1}{4} \cdot y & \frac{-1}{4} - \frac{1}{4} \cdot x & \frac{1}{4} - \frac{1}{4} \cdot y & \frac{1}{4} + \frac{1}{4} \cdot x & \frac{1}{4} \cdot y + \frac{1}{4} & \frac{1}{4} - \frac{1}{4} \cdot x & \frac{-1}{4} \cdot y - \frac{1}{4} \end{pmatrix}$$

Matriz de Rigidez

$$K = \int_{-a}^{a} \int_{-b}^{b} B(x, y)^{T} \cdot C \cdot B(x, y) dx dy$$

$$K = \begin{pmatrix} 0.5 & 0.188 & -0.313 & 0 & -0.25 & -0.188 & 0.063 & 0 \\ 0.188 & 0.5 & 0 & 0.063 & -0.188 & -0.25 & 0 & -0.313 \\ -0.313 & 0 & 0.5 & -0.188 & 0.063 & 0 & -0.25 & 0.188 \\ 0 & 0.063 & -0.188 & 0.5 & 0 & -0.313 & 0.188 & -0.25 \\ -0.25 & -0.188 & 0.063 & 0 & 0.5 & 0.188 & -0.313 & 0 \\ -0.188 & -0.25 & 0 & -0.313 & 0.188 & 0.5 & 0 & 0.063 \\ 0.063 & 0 & -0.25 & 0.188 & -0.313 & 0 & 0.5 & -0.188 \\ 0 & -0.313 & 0.188 & -0.25 & 0 & 0.063 & -0.188 & 0.5 \end{pmatrix}$$



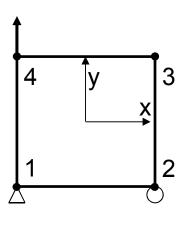
<u>Problema Plano – Tensión Plana</u>

Matriz Reducida

$$K = \begin{bmatrix} 0.5 & 0.0625 & 0 & -0.25 & 0.1875 \\ 0.0625 & 0.5 & 0.1875 & -0.3125 & 0 \\ 0 & 0.1875 & 0.5 & 0 & 0.0625 \\ -0.25 & -0.3125 & 0 & 0.5 & -0.1875 \\ 0.1875 & 0 & 0.0625 & -0.1875 & 0.5 \end{bmatrix}$$

Vector de Cargas:

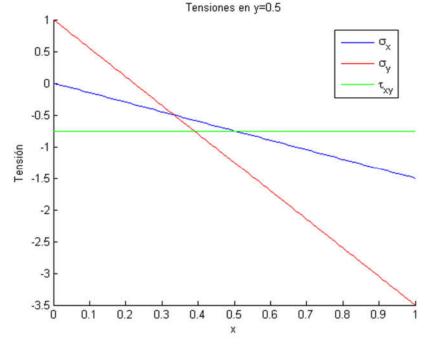
$$R = \begin{cases} 0 \\ 0 \\ 0 \\ 0 \\ 1 \end{cases}$$



Desplazamientos Globales:

$$D = K^{-1}R \qquad D = \begin{cases} -\frac{1}{3} \\ 0 \\ \frac{5}{3} \\ -1 \\ 2 \\ 3 \end{cases}$$

Variación Tensiones:



Deformaciones Elementales:

$$\varepsilon(x,y) = B(x,y)D \qquad \varepsilon(x,y) = \begin{cases} -\frac{1}{3} \\ 1-4x \\ -4y \end{cases}$$

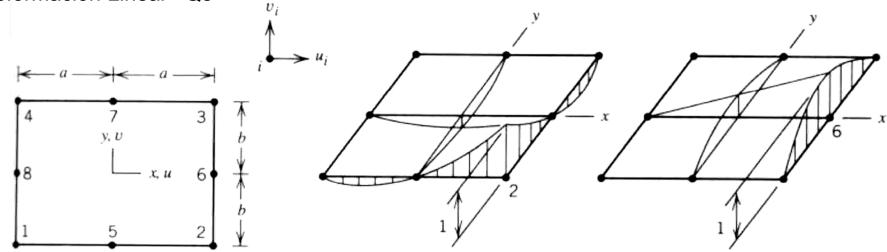
Tensiones Elementales:

Tensiones Elementales:

$$\sigma(x,y) = CB(x,y)D \qquad \sigma(x,y) = \begin{cases} -\frac{3}{2}x \\ 1-\frac{9}{2}x \\ -\frac{3}{2}y \end{cases}$$

Elementos Rectangulares

Deformación Lineal - Q8



$$u = a_1 + a_2x + a_3y + a_4x^2 + a_5xy + a_6y^2 + a_7x^2y + a_8xy^2$$

$$v = a_9 + a_{10}x + a_{11}y + a_{12}x^2 + a_{13}xy + a_{14}y^2 + a_{15}x^2y + a_{16}xy^2$$

Deformaciones

$$\begin{aligned} & \epsilon_{x} = \frac{\partial u}{\partial x} = a_{2} + 2a_{4}x + a_{5}y + 2a_{7}xy + a_{8}y^{2} \\ & \epsilon_{y} = \frac{\partial v}{\partial y} = a_{11} + a_{13}x + 2a_{14}y + a_{15}x^{2} + 2a_{16}xy \\ & \gamma_{xy} = \frac{\partial v}{\partial x} + \frac{\partial u}{\partial y} = a_{3} + a_{10} + (a_{5} + 2a_{12})x + (2a_{6} + a_{13})y + a_{7}x^{2} + 2(a_{8} + a_{15})xy + a_{16}y^{2} \end{aligned}$$