

APPENDIX B:

CLOSED-FORM SOLUTION FOR AN INTEGRAL CONTAINING MATRIX EXPONENTIALS

As defined by Eq. 11.42 we must often compute a number of matrix integrals of the form

$$\Psi(A_1, A_2, A_3, t_f, t_0) = \int_{t_0}^{t_f} e^{A_1 \tau} A_2 e^{A_3 \tau} d\tau \quad (B.1)$$

where the constant matrices A_1 , A_2 , and A_3 are specified. To simplify the evaluation of the integral in Eq. B.1 we make the following change of variables

$$\tau = \sigma + t_0$$

leading to

$$\Psi(A_1, A_2, A_3, t_f, t_0) = e^{A_1 t_0} \Psi(A_1, A_2, A_3, t_f - t_0, 0) e^{A_3 t_0} \quad (B.2)$$

The integral involving the matrix exponentials in Eq. B.2 can be easily evaluated by forming the constant matrix

$$\Pi = \begin{bmatrix} -A_1 & A_2 \\ 0 & A_3 \end{bmatrix} \begin{matrix} \} n_1 \\ \} n_2 \end{matrix} \quad (B.3)$$

$n_1 \quad n_2$

and computing the matrix exponential (ref. B.1)

$$e^{\Pi(t_f - t_0)} = \begin{bmatrix} F_1(t_f - t_0) & G_1(t_f - t_0) \\ 0 & F_2(t_f - t_0) \end{bmatrix} \begin{matrix} \} n_1 \\ \} n_2 \end{matrix} \quad (B.4)$$

$n_1 \quad n_2$

where we have the "Van-Loan Identities":

$$F_1(t_f - t_0) = e^{-A_1(t_f - t_0)}, \quad F_2(t_f - t_0) = e^{A_3(t_f - t_0)} \quad (B.5)$$

$$G_1(t_f - t_0) = e^{-A_1(t_f - t_0)} \Psi(A_1, A_2, A_3, t_f - t_0, 0) \quad (B.6)$$

Thus the solution for the integral of Eq. B.2 follows as

$$\Psi(A_1, A_2, A_3, t_f - t_0, 0) = e^{A_1(t_f - t_0)} G_1(t_f - t_0) \quad (B.7)$$

and the solution for Eq. B.1 can be shown to be

$$\Psi(A_1, A_2, A_3, t_f, t_0) = e^{A_1 t_f} G_1(t_f - t_0) e^{A_3 t_0} \quad (B.8)$$

In order to evaluate Eq. B.8 at discrete times, the semigroup properties of exponential matrices are now exploited, yielding the following recursion relationships for the matrix partitions of $e^{\Pi(t_f - t_0)}$:

$$F_j(t + \Delta t) = F_j(\Delta t) F_j(t) \quad , \quad F_j(t_0) = I \quad , \quad j = 1, 2 \quad (B.9)$$

$$G_1(t + \Delta t) = F_1(\Delta t) G_1(t) + G_1(\Delta t) F_2(t) \quad , \quad G_1(t_0) = 0 \quad (B.10)$$

where $\Delta t = (t_f - t_0)/m$ and m is the total number of discrete time steps. As a result, the integral in Eq. B.1 can be written as

$$\Psi(A_1, A_2, A_3, t + \Delta, t_0) = e^{A_1 t} F_3(t + \Delta) G_1(t + \Delta) e^{A_3 t_0} \quad (B.11)$$

where $F_3(t) = e^{A_1 t}$ is obtained in a separate calculation and $F_3(t + \Delta t)$ is recursively generated by using a formula similar to Eq. B.9. A further simplification results when Eq. B.11 is post-multiplied by a vector

$$\begin{aligned} \Psi(A_1, A_2, A_3, t + \Delta, t_0) \sigma &= e^{A_1 t} F_3(t + \Delta) G_1(t + \Delta) e^{A_3 t_0} \sigma \\ &= e^{A_1 t} F_3(t + \Delta) v_1(t + \Delta) \end{aligned} \quad (B.12)$$

where the recursion relationship for $v_1(t)$ is given by

$$v_1(t + \Delta) = F_1(\Delta t) v_1(t) + G_1(\Delta t) v_2(t) \quad , \quad v_1(0) = 0 \quad (B.13)$$

$$v_2(t + \Delta) = F_2(\Delta t) v_2(t) \quad , \quad v_2(0) = e^{A_3 t_0} \sigma \quad (B.14)$$

References

- B.1 Van Loan, C. F., "Computing Integrals Involving Matrix Exponentials," IEEE Transactions on Automatic Control, Vol. Ac-23, No. 3, June 1978, pp. 395-404.