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1-1. Describe how you preprocess your data and the model architecture. (30%)

```
def convert_images(raw_images):
    raw = np.array(raw_images, dtype = float)/255.0
```

```
datagen = ImageDataGenerator(
    featurewise_center=False, # set input mean to 0 over the dataset
    samplewise_center=False, # set each sample mean to 0
    featurewise_std_normalization=False, # divide inputs by std of the dataset
    samplewise_std_normalization=False, # divide each input by its std
    zca_whitening=False, # apply ZCA whitening
    rotation_range=15, # randomly rotate images in the range (degrees, 0 to 180)
    width_shift_range=0.1, # randomly shift images horizontally (fraction of total width)
    height_shift_range=0.1, # randomly shift images vertically (fraction of total height)
    horizontal_flip=True, # randomly flip images
    vertical_flip=False) # randomly flip images
```

我利用 imagedatagenerator 去讓圖片有旋轉,以及水平翻轉,並且去同除 255 去做預處理。

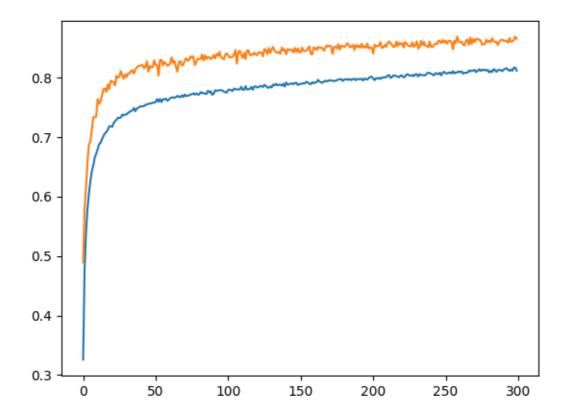
```
model = Sequential()
#model.add(Conv2D(32, (3,3), padding='same', input_shape= x_train.shape[1:]))
model.add(Conv2D(32, kernel_size=(3, 3), padding='same',input_shape=(32,32,3)))
model.add(Activation('relu'))
model.add(Conv2D(32, (3, 3)))
model.add(Activation('relu'))
model.add(Dropout(0.25))
model.add(Conv2D(64, (3, 3), padding='same'))
model.add(Activation('relu'))
model.add(Conv2D(64, (3, 3)))
model.add(Activation('relu'))
model.add(Activation('relu'))
model.add(AveragePooling2D(pool size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(128, (3, 3), padding='same'))
model.add(Activation('relu'))
model.add(Conv2D(128, (3, 3)))
model.add(Activation('relu'))
model.add(AveragePooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Conv2D(256, (3, 3), padding='same'))
model.add(Activation('relu'))
model.add(Conv2D(256, (1, 1)))
model.add(Activation('relu'))
model.add(AveragePooling2D(pool_size=(2, 2)))
model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(512))
model.add(Activation('relu'))
model.add(Dropout(0.5))
model.add(Dense(10))
model.add(Activation('softmax'))
```

上圖是我最佳的 model,我用了 6 層的 convolution 2D,並在最後面接一個 classifier 和 softmax 去分類,那中間我是用 average pooling 去處理,並加上 dropout 去訓練。

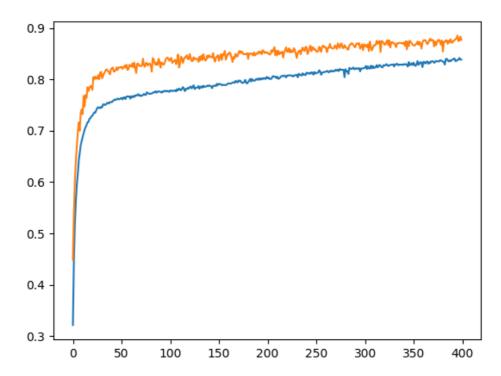
1-2. Compare different architectures or parameters and record their performance (30%)

我做了不同深度的 cnn 的比較,最佳的是六層去 train,下圖是四層 cnn model 以及結果。 我跑了 300 個 epochs 之後 acc 大概是在 0.86 左右從圖形看來,雖然成長緩慢但是仍是還可以將 epochs 加大。

```
model = Sequential()
#model.add(Conv2D(32, (3,3), padding='same', input_shape= x_train.shape[1:]))
model.add(Conv2D(32, kernel_size=(3, 3), padding='same',input_shape=(32,32,3)))
model.add(Activation('relu'))
model.add(Conv2D(32, (3, 3)))
model.add(Activation('relu'))
 model.add(Dropout(0.25))
model.add(Conv2D(64, (3, 3), padding='same'))
model.add(Activation('relu'))
model.add(Conv2D(64, (3, 3)))
model.add(Activation('relu'))
 model.add(AveragePooling2D(pool_size=(2, 2)))
 model.add(Dropout(0.25))
model.add(Conv2D(128, (3, 3), padding='same'))
model.add(Activation('relu'))
model.add(Conv2D(128, (3, 3)))
model.add(Activation('relu'))
model.add(AveragePooling2D(pool_size=(2, 2)))
 model.add(Dropout(0.25))
model.add(Flatten())
model.add(Dense(512))
model.add(Activation('relu'))
 model.add(Dropout(0.5))
model.add(Dense(10))
model.add(Activation('softmax'))
Using TensorFlow backend.
Test loss: 0.416846414292
Test accuracy: 0.8661
```



2. screenshot.png:A screenshot of the best testing set accuracy on terminal. (20%)



上面兩張圖片是我最佳的 model 的圖片,

我最好的 model 大概是跑出 0.88 左右的 accuracy,從下圖中可以看出

大概到 50 epochs 之後就就開始有趨於平緩,我總共是跑 400epochs 不過仍然有再上升 的趨勢

3.hw3.py: A script that you train and test your model (20%)

請將 cifar10 的 data_batch_1 ~ data_batch_5 還有 test_batch 跟 hw3.py 放在同一資料夾下,然後直接鍵入 python3 hw3.py 即可開始 train