Simone Parisi

Curriculum Vitae

Simone@robot-learning.de

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Research Interests

Reinforcement Learning, Markov Theory, Exploration, Intrinsic Motivation, Partial Observability, Feature Learning, Transfer Learning, Multi-Objective Optimization, Deep Learning.

Work Experience

- 2022 Today **Postdoctoral Fellow**, *University of Alberta*, Edmonton, Alberta, Canada with Michael Bowling and Matthew Taylor
- 2020 2022 **Postdoctoral Researcher**, *Meta Al Research*, Pittsburgh, Pennsylvania, United States with Abhinav Gupta

Education

2014 - 2019 PhD in Computer Science, Technische Universität Darmstadt, Germany

Thesis: Reinforcement Learning with Sparse and Multiple Rewards

Advisor: Jan Peters

Honors: Magna Cum Laude

- 2017 **Research Intern**, *RIKEN Center for Advanced Intelligence Project*, Tokyo, Japan Advisors: Masashi Sugiyama, Emtiyaz Khan
- 2015 Machine Learning Summer School, Max Planck Institute, Tübingen, Germany
- 2012 Exchange Student, University of Queensland, Brisbane, Australia
- 2011 2014 MSc in Computer Science and Engineering, Politecnico di Milano, Italy

Thesis: Study and Analysis of Policy Gradient Approaches for Multi-Objective Decision

Problems

Advisors: Marcello Restelli, Matteo Pirotta

2008 - 2011 BSc in Computer Science and Engineering, Politecnico di Milano, Italy

Advisor: Carlo Ghezzi

Publications

Books

[1] Boris Belousov, Hany Abdulsamad, Pascal Klink, **Simone Parisi**, and Jan Peters, *Reinforcement Learning Algorithms: Analysis and Applications*, Springer, 2020

Journal Articles

- [2] **Simone Parisi**, Davide Tateo, Maximilian Hensel, Carlo D'Eramo, Jan Peters, and Joni Pajarinen, "Long-Term Visitation Value for Deep Exploration in Sparse Reward Reinforcement Learning", *Algorithms*, 15(3), 2022
- [3] **Simone Parisi**, Voot Tangkaratt, Jan Peters, and Mohammad Emtiyaz Khan, "TD-Regularized Actor-Critic Methods", *Machine Learning (MLJ)*, 2019
- [4] **Simone Parisi**, Matteo Pirotta, and Jan Peters, "Manifold-based Multi-objective Policy Search with Sample Reuse", *Neurocomputing*, 263:3–14, 2017

[5] **Simone Parisi**, Matteo Pirotta, and Marcello Restelli, "Multi-objective Reinforcement Learning through Continuous Pareto Manifold Approximation", *Journal of Artificial Intelligence Research* (*JAIR*), 57:187–227, 2016

Conference and Workshop Papers

- [6] Simone Parisi, Alireza Kazemipour, and Michael Bowling, "Beyond Optimism: Exploration With Partially Observable Rewards", Advances in Neural Information Processing Systems (NeurIPS), 2024
- [7] **Simone Parisi**, Montaser Mohammedalamen, Alireza Kazemipour, Matthew E. Taylor, and Michael Bowling, "Monitored Markov Decision Processes", *International Conference on Autonomous Agents and Multiagent Systems (AAMAS)*, 2024
- [8] **Simone Parisi**, Aravind Rajeswaran, Senthil Purushwalkam, and Abhinav Gupta, "The (Un)Surprising Effectiveness of Pre-Trained Vision Models for Control", *International Conference on Machine Learning (ICML)*, 2022 [Long oral, acc. rate 2%]
- [9] Simone Parisi, Victoria Dean, Deepak Pathak, and Abhinav Gupta, "Interesting Object, Curious Agent: Learning Task-Agnostic Exploration", Advances in Neural Information Processing Systems (NeurIPS), 2021 [Oral, acc. rate ¡1%]
- [10] Simone Parisi, Voot Tangkaratt, Jan Peters, and Mohammad Emtiyaz Khan, "TD-Regularized Actor-Critic Methods", European Conference on Machine Learning and Principles and Practice of Knowledge Discovery in Databases (ECML PKDD), 2019
- [11] **Simone Parisi**, Voot Tangkaratt, Jan Peters, and Mohammad Emtiyaz Khan, "TD-Regularized Actor-Critic Methods", *European Workshop on Reinforcement Learning (EWRL)*, 2018
- [12] Simone Parisi, Simon Ramstedt, and Jan Peters, "Goal-Drive Dimensionality Reduction for Reinforcement Learning", International Conference on Intelligent Robots and Systems (IROS), 2017
- [13] Simone Parisi, Voot Tangkaratt, and Jan Peters, "Regularized Contextual Policy Search via Mutual Information", Multi-disciplinary Conference on Reinforcement Learning and Decision Making (RLDM), 2017
- [14] Voot Tangkaratt, Herke van Hoof, **Simone Parisi**, Gerhard Neumann, Jan Peters, and Masashi Sugiyama, "Policy Search with High-Dimensional Context Variables", *AAAI Conference on Artificial Intelligence (AAAI)*, 2017
- [15] Simone Parisi, Alexander Blank, Tobias Viernickel, and Jan Peters, "Local-Utopia Policy Celection for Multi-Objective Reinforcement Learning", International Symposium on Adaptive Dynamic Programming and Reinforcement Learning (ADPRL), 2016
- [16] **Simone Parisi**, Hany Abdulsamad, Alexandros Paraschos, Christian Daniel, and Jan Peters, "Reinforcement Learning vs Human Programming in Tetherball Robot Games", *International Conference on Intelligent Robots and Systems (IROS)*, 2015
- [17] Matteo Pirotta, Simone Parisi, and Marcello Restelli, "Multi-Objective Reinforcement Learning with Continuous Pareto Frontier Approximation", AAAI Conference on Artificial Intelligence (AAAI), 2015
- [18] Simone Parisi, Matteo Pirotta, Nicola Smacchia, Luca Bascetta, and Marcello Restelli, "Policy Gradient Approaches for Multi-Objective Sequential Decision Making", International Joint Conference on Neural Networks (IJCNN), 2014
- [19] **Simone Parisi**, Matteo Pirotta, Nicola Smacchia, Luca Bascetta, and Marcello Restelli, "Policy Gradient Approaches for Multi-Objective Sequential Decision Making: A Comparison", International Symposium on Adaptive Dynamic Programming and Reinforcement Learning (ADPRL), 2014

Teaching Experience

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2024 CMPUT 655 - Reinforcement Learning 1 (Graduate Course), *University of Alberta*

Teaching Assistant

- 2018 2019 Reinforcement Learning, Technische Universität Darmstadt
 - 2017 Statistical Machine Learning, Technische Universität Darmstadt
- 2016 2017 Robot Learning, Technische Universität Darmstadt
 - 2016 Statistical Machine Learning, *Technische Universität Darmstadt*MSc Thesis Supervision
 - 2024 Alireza Kazemipour (UoA). Double MBIE: On the Use of Models to Better Explore in the Absence of Rewards
 - 2020 Eike Mentzendorff (TUDa). Bridging the Gap Between Multi-Objective and Multi-Task Deep Reinforcement Learning
 - 2019 Kai Cui (TUDa). A Study on TD-Regularized Actor-Critic Methods
 - 2019 Shuo Zhang (TUDa). Integration of Self-Imitation and Model-based Learning to Actor-Critic Algorithms
 - 2019 Stefan Hübecker (TUDa). Curiosity-Driven Reinforcement Learning for Autonomous Driving

 BSc Thesis Supervision
 - 2019 Leon Keller (TUDa). Application of Reinforcement Learning Algorithms to Robotics Simulators
 - 2016 Simon Ramstedt (TUDa). Deep Reinforcement Learning with Continuous Actions

 Project Supervision
 - 2024 Mohammadreza Daviran, Hamid Reza Dehbashi Ghorbanali (UoA). Effects of Linear Networks Depth in Rapid Reinforcement Learning
 - 2024 Seth Akins, Matthias Horgen, Nicolas Ong (UoA). The Effects of Action Delay and Action Repeats in Reinforcement Learning
 - 2024 Kiran Deol, Danila Seliayeu, Avani Tiwari (UoA). Evaluating the Evolution of Geometric Properties in DQN Representations
 - 2024 Azeez Adeniyi, Isaiah Heidt (UoA). What Hinders Reinforcement Learning More: Action Noise, Observation Noise, or Reward Noise?
 - 2024 Euijin Baek, Andrew Freeman, Minh Pham (UoA). How Much Does Corruption Affect Preference-Based Reinforcement Learning?
 - 2021 Jacob Adkins (CMU). Transfer Exploration in RL: A Study on Recent Count-Based Methods
 - 2018 Shuo Zhang, Lu Wan (TUDa). Enhancing Exploration Through Curiosity for Robotics
- 2016 2017 Simon Ramstedt (TUDa). Bayesian Deep Reinforcement Learning: Tools and Methods
- 2015 2016 Jan-Christoph Klie, Xuelei Li (TUDa). Feature Selection for Tetherball Robot Games
- 2014 2015 Alexander Blank, Tobias Viernickel (TUDa). Multi-Objective Reinforcement Learning for Tetherball Robot Games

Funding

- 2024 2025 Resources for Research Groups Application, 128,501 CAD
 - Title Search, Learning, and Acting Under Uncertainty
 - Source Digital Research Alliance of Canada
 - Co-PI Michael Bowling

Source	Assisted Reinforcement Learning for Real-World Tasks Digital Research Alliance of Canada Matthew Taylor				
	Resource Allocation Project, 169,000 CAD Monitored Reinforcement Learning: A Framework for Modelling Limited Reward Availability				
	in Realistic Settings				
	Alberta Machine Intelligence Institute (AMII)				
Co-PI	Co-PI: Michael Bowling, Matthew Taylor				
	Invited Talks				
10 Oct 2024	Fundamental Al Research (FAIR) at Meta, Paris, France Host: Alessandro Lazaric				
19 Sep 2024	Amazon Research, Seattle, United States Host: Lihong Li				
26 Sep 2022	Alberta Machine Intelligence Institute (AMII), Edmonton, Canada Host: Michael Bowling				
6 Sep 2022	Montréal Institute for Learning Algorithms (MILA), Montréal, Canada Host: Glen Berseth				
19 Aug 2022	UC Berkley, Robotic Artificial Intelligence and Learning Lab , Berkeley, United States Host: Sergey Levine				
14 Apr 2022	NVIDIA, Robotics Research , Seattle, United States Host: Dieter Fox				
30 Aug 2019	University of Texas, Learning Agents Research Group (LARG), Austin, United States Host: Peter Stone				
28 Aug 2019	Brown University, Dept. of Computer Science , Providence, United States Host: Michael Littman				
26 Aug 2019	Meta Al Research, Pittsburgh, United States Host: Abhinav Gupta				
24 May 2019	Max Planck Institute (MPI), Dept. of Empirical Inference, Tübingen, Germany Host: Bernhard Schölkopf				
6 May 2019	Delft University of Technology, Dept. of Cognitive Robotics (CoR) , Delft, Netherlands Host: Jens Kober				
3 May 2019	University of Amsterdam, Machine Learning Lab (AMLab), Amsterdam, Netherlands Hosts: Herke van Hoof, Max Welling				
15 Dec 2017	Advanced Telecommunications Research Institute (ATR), Kyoto, Japan Host: Jun Morimoto				
2 Oct 2017	RIKEN Center for Advanced Intelligence Project (AIP), Tokyo, Japan Hosts: Emtiyaz Khan, Masashi Sugiyama				
	Reviewing Experience				
Action Editor	Transactions on Machine Learning Research (TMLR: 2024)				
Journals	IEEE Robotics and Automation Letters (RAL: 2021), Journal of Autonomous Agents and Multi-Agent Systems (JAAMAS: 2021), Neurocomputing (2016, 2017), Journal of Machine				

2024 - 2025 Resources for Research Groups Application, 85,898 CAD

2016)

Learning Research (JMLR: 2016), International Journal of Advanced Robotic Systems (IJARS:

Conferences Advances in Neural Information Processing Systems (NeurIPS: 2018, 2019, 2021, 2023), International Conference on Intelligent Robots and Systems (IROS: 2015, 2017, 2020, 2021, 2023), International Conference on Automated Planning and Scheduling (ICAPS: 2020), International Conference on Learning Representations (ICLR: 2019, 2021, 2022), Conference on Robot Learning (CoRL: 2018, 2021), International Conference on Flexible Automation and Intelligent Manufacturing (FAIM: 2018), AAAI Conference on Artificial Intelligence (AAAI: 2017, 2018), International Conference on Robotics and Automation (ICRA: 2017, 2020, 2021), Robotics: Science and Systems (RSS: 2016), International Joint Conference on Artificial Intelligence (IJCAI: 2016), International Conference on Automation Science and Engineering (CASE: 2015), European Workshop on Reinforcement Learning (EWRL: 2015, 2018, 2024)

Computer Skills

Python, LATEX, Git

Languages

Italian (Mother tongue), English (Fluent)

References

Michael Bowling, University of Alberta Matthew Taylor, University of Alberta Abhinav Gupta, Carnegie Mellon University Jan Peters, Technische Universität Darmstadt

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- ☑ gabhinav@andrew.cmu.edu ☑ mail@jan-peters.net