Simone Parisi

Curriculum Vitae

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sparisi

Research Interests

Machine Learning: Reinforcement Learning, Exploration, Intrinsic Motivation, Policy Search, Feature Learning, Transfer Learning, Multi-objective Optimization, Deep Learning.
Autonomous Robots: Motor Skill Learning, Trajectory Optimization, Imitation Learning, Movement Primitives.

Work Experience

2020 - 2022 **Postdoctoral Researcher**, *Meta AI Research*, Pittsburgh, Pennsylvania, United States
with Abhinav Gupta

Education

2014 - 2019 **PhD in Computer Science**, *Technische Universität Darmstadt*, Germany
Thesis: *Reinforcement Learning with Sparse and Multiple Rewards*
Advisor: Jan Peters
Honors: Magna Cum Laude

2017 **Research Intern**, *RIKEN Center for Advanced Intelligence Project*, Tokyo, Japan
Advisors: Masashi Sugiyama, Emtiyaz Khan

2015 **Machine Learning Summer School**, *Max Planck Institute*, Tübingen, Germany

2012 **Exchange Student**, *University of Queensland*, Brisbane, Australia

2011 - 2014 **MSc in Computer Science and Engineering**, *Politecnico di Milano*, Italy
Thesis: *Study and Analysis of Policy Gradient Approaches for Multi-objective Decision Problems*
Advisors: Marcello Restelli, Matteo Pirotta

2008 - 2011 **BSc in Computer Science and Engineering**, *Politecnico di Milano*, Italy
Advisor: Carlo Ghezzi

Publications

Journal Articles

[1] **Simone Parisi**, Davide Tateo, Maximilian Hensel, Carlo D'Eramo, Jan Peters, and Joni Pajarinen, "Long-Term Visitation Value for Deep Exploration in Sparse Reward Reinforcement Learning", *Algorithms*, 15(3), 2022

[2] **Simone Parisi**, Voot Tangkaratt, Jan Peters, and Mohammad Emtiyaz Khan, "TD-Regularized Actor-Critic Methods", *Machine Learning (MLJ)*, 2019

[3] **Simone Parisi**, Matteo Pirotta, and Jan Peters, "Manifold-based Multi-objective Policy Search with Sample Reuse", *Neurocomputing*, 263:3–14, 2017

[4] **Simone Parisi**, Matteo Pirotta, and Marcello Restelli, "Multi-objective Reinforcement Learning through Continuous Pareto Manifold Approximation", *Journal of Artificial Intelligence Research (JAIR)*, 57:187–227, 2016

Conference and Workshop Papers

[5] **Simone Parisi**, Aravind Rajeswaran, Senthil Purushwalkam, and Abhinav Gupta, "The (Un)Surprising Effectiveness of Pre-Trained Vision Models for Control", *International Confer-*

ence on Machine Learning (ICML), 2022 **[Long oral, acc. rate 2%]**

[6] **Simone Parisi**, Victoria Dean, Deepak Pathak, and Abhinav Gupta, "Interesting Object, Curious Agent: Learning Task-Agnostic Exploration", *International Conference on Neural Information Processing Systems (NeurIPS)*, 2021 **[Oral, acc. rate <1%]**

[7] **Simone Parisi**, Voot Tangkaratt, Jan Peters, and Mohammad Emtiyaz Khan, "TD-Regularized Actor-Critic Methods", *European Conference on Machine Learning and Principles and Practice of Knowledge Discovery in Databases (ECML PKDD)*, 2019

[8] **Simone Parisi**, Voot Tangkaratt, Jan Peters, and Mohammad Emtiyaz Khan, "TD-Regularized Actor-Critic Methods", *European Workshop on Reinforcement Learning (EWRL)*, 2018

[9] **Simone Parisi**, Simon Ramstedt, and Jan Peters, "Goal-Drive Dimensionality Reduction for Reinforcement Learning", *International Conference on Intelligent Robots and Systems (IROS)*, 2017

[10] **Simone Parisi**, Voot Tangkaratt, and Jan Peters, "Regularized Contextual Policy Search via Mutual Information", *Multi-disciplinary Conference on Reinforcement Learning and Decision Making (RLDM)*, 2017

[11] Voot Tangkaratt, Herke van Hoof, **Simone Parisi**, Gerhard Neumann, Jan Peters, and Masashi Sugiyama, "Policy Search with High-Dimensional Context Variables", *AAAI Conference on Artificial Intelligence (AAAI)*, 2017

[12] **Simone Parisi**, Alexander Blank, Tobias Viernickel, and Jan Peters, "Local-utopia policy selection for multi-objective reinforcement learning", *International Symposium on Adaptive Dynamic Programming and Reinforcement Learning (ADPRL)*, 2016

[13] **Simone Parisi**, Hany Abdulsamad, Alexandros Paraschos, Christian Daniel, and Jan Peters, "Reinforcement Learning vs Human Programming in Tetherball Robot Games", *International Conference on Intelligent Robots and Systems (IROS)*, 2015

[14] Matteo Pirotta, **Simone Parisi**, and Marcello Restelli, "Multi-Objective Reinforcement Learning with Continuous Pareto Frontier Approximation", *AAAI Conference on Artificial Intelligence (AAAI)*, 2015

[15] **Simone Parisi**, Matteo Pirotta, Nicola Smacchia, Luca Bascetta, and Marcello Restelli, "Policy gradient approaches for multi-objective sequential decision making", *International Joint Conference on Neural Networks (IJCNN)*, 2014

[16] **Simone Parisi**, Matteo Pirotta, Nicola Smacchia, Luca Bascetta, and Marcello Restelli, "Policy gradient approaches for multi-objective sequential decision making: A comparison", *International Symposium on Adaptive Dynamic Programming and Reinforcement Learning (ADPRL)*, 2014

Invited Talks

14 Apr 2022 **NVIDIA, Robotics Research**, Seattle, United States
Host: Dieter Fox

30 Aug 2019 **University of Texas, Learning Agents Research Group (LARG)**, Austin, United States
Host: Peter Stone

28 Aug 2019 **Brown University, Dept. of Computer Science**, Providence, United States
Host: Michael Littman

26 Aug 2019 **Meta AI Research**, Pittsburgh, United States
Host: Abhinav Gupta

24 May 2019 **Max Planck Institute (MPI), Dept. of Empirical Inference**, Tübingen, Germany
Host: Bernhard Schölkopf

6 May 2019 **Delft University of Technology, Dept. of Cognitive Robotics (CoR)**, Delft, Netherlands
Host: Jens Kober

3 May 2019 **University of Amsterdam, Machine Learning Lab (AMLab)**, Amsterdam, Netherlands
Hosts: Herke van Hoof, Max Welling

15 Dec 2017 **Advanced Telecommunications Research Institute (ATR)**, Kyoto, Japan
Host: Jun Morimoto

2 Oct 2017 **RIKEN Center for Advanced Intelligence Project (AIP)**, Tokyo, Japan
Hosts: Emtiyaz Khan, Masashi Sugiyama

Reviewing Experience

Journals

IEEE Robotics and Automation Letters (RA-L)	*2021*
Neurocomputing	*2016, 2017*
Journal of Machine Learning Research (JMLR)	*2016*
International Journal of Advanced Robotic Systems (IJARS)	*2016*

Conferences

Conference on Neural Information Processing Systems (NeurIPS)	*2021*
IEEE/RSJ International Conference on Intelligent Robots and Systems (IROS)	*2015, 2017, 2020, 2021*
International Conference on Automated Planning and Scheduling (ICAPS)	*2020*
International Conference on Learning Representations (ICLR)	*2019, 2021, 2022*
Conference on Robot Learning (CoRL)	*2018, 2021*
AAAI Conference on Artificial Intelligence (AAAI)	*2017, 2018*
IEEE International Conference on Robotics and Automation (ICRA)	*2017, 2021*
Robotics: Science and Systems (R:SS)	*2016*
International Joint Conference on Artificial Intelligence (IJCAI)	*2016*
IEEE International Conference on Automation Science and Engineering (CASE)	*2015*

Workshops

Multi-Objective Decision Making Workshop (MODeM) Journal of Autonomous Agents and Multi-Agent Systems (JAAMAS)	*2021*
Workshop on Robot Learning Conference on Neural Information Processing Systems (NeurIPS)	*2019*
Workshop on Reinforcement Learning under Partial Observability Conference on Neural Information Processing Systems (NeurIPS)	*2018*
Workshop on Prediction and Generative Modeling in Reinforcement Learning International Conference on Flexible Automation and Intelligent Manufacturing (FAIM)	*2018*
European Workshop on Reinforcement Learning (EWRL)	*2015, 2018*

Workshop Proposals

International Conference on Robotics and Automation (ICRA)	*2020*

Teaching Experience

Teaching Assistant

2018 - 2019 Reinforcement Learning, *Technische Universität Darmstadt*

2017 Statistical Machine Learning, *Technische Universität Darmstadt*

2016 - 2017 Robot Learning, *Technische Universität Darmstadt*

2016 Statistical Machine Learning, *Technische Universität Darmstadt*

MSc Thesis Supervision

2020 Eike Mentzendorff (TUDa). *Bridging the Gap Between Multi-objective and Multi-task Deep Reinforcement Learning*

2019 Kai Cui (TUDa). *A Study on TD-regularized Actor-critic Methods*

2019 Stefan Hübecker (TUDa). *Curiosity-driven Reinforcement Learning for Autonomous Driving*

2019 Shuo Zhang (TUDa). *Integration of Self-imitation and Model-based Learning to Actor-critic Algorithms*

BSc Thesis Supervision

2019 Leon Keller (TUDa). *Application of Reinforcement Learning Algorithms to Robotics Simulators*

2016 Simon Ramstedt (TUDa). *Deep Reinforcement Learning with Continuous Actions*

Project Supervision

2021 Jacob Adkins (CMU). *Transfer Exploration in RL: A Study on Recent Count-Based Methods*

2018 Shuo Zhang, Lu Wan (TUDa). *Enhancing Exploration Through Curiosity for Robotics*

2016 - 2017 Simon Ramstedt (TUDa). *Bayesian Deep Reinforcement Learning: Tools and Methods*

2015 - 2016 Jan-Christoph Klie, Xuelei Li (TUDa). *Feature Selection for Tetherball Robot Games*

2014 - 2015 Alexander Blank, Tobias Viernickel (TUDa). *Multi-objective Reinforcement Learning for Tetherball Robot Games*

Computer Skills

Python, MATLAB, LaTeX, Git

Languages

Italian (Mother tongue), English (Fluent)

Hobbies

Strength Training, Movies, Cooking, Photography

References

Abhinav Gupta, Carnegie Mellon University, Meta AI Research ✉ gabhinav@fb.com

Jan Peters, Technische Universität Darmstadt ✉ mail@jan-peters.net

Deepak Pathak, Carnegie Mellon University ✉ dpathak@cs.cmu.edu