

Engineering Electromagnetics –Experiment 3

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Abstract

This experiment illustrates the distribution of the spatial magnetic field that is produced by an electric current loop and provide an intuitive way to calculate the magnetic field distribution and plot the relevant graphs through MATLAB.

1 Background

From the Biot–Savart law, we could derive the magnetic field on a current coil into various parts and integrate them separately to get the total magnetic field that produced by the current in the coil.

$$d\mathbf{H} = \frac{I d\mathbf{L} \times \mathbf{a}_R}{4\pi R^2} = \frac{I d\mathbf{L} \times \mathbf{R}}{4\pi R^3} \quad (1)$$

After the integration, the total magnetic field of a current coil equals:

$$\mathbf{H} = \frac{I (\pi a^2) \mathbf{a}_z}{2\pi (a^2 + z_0^2)^{3/2}} \quad (2)$$

2 Two Current Loop with Same Current Direction

2.1 Define the Paraments

To make the magnetic field more precise, we split each dimension of the space into 100 tiles. The black rectangle in the figure represents the region $y = [-2, 2], z = [-1, 1]$.

```
1      ym=10; %Set the range of y direction in the field domain
2      zm=10; %Set the range of z direction in the field domain
3      y= linspace(-ym,ym,100); % Equally divide y axis into 100 parts
4      z= linspace(-zm,zm,100); % Equally divide z axis into 100 parts
5
6      a=2; %Input the radius of the current loop
7      I=500; %Input the current value in the current loop
8      C=I/(4*pi); %Merge the constants
9      N=50; %Set the number of division
10
11     theta0=linspace(0,2*pi,N+1); %Division of the angle of circumference
12     theta1=theta0(1:N);
13     x1=a*cos(theta1); y1=a*sin(theta1); %The start point coordinate of each segment of the loop
14     theta2=theta0(2:N+1);
15     x2=a*cos(theta2); y2=a*sin(theta2); %The ending point coordinate of each segment of the loop
16
17     zc=1; xc=(x2+x1)/2; yc=(y2+y1)/2; %Calculate the 3 coordinate components of the midpoint
18     % of each segment of the loop.
19     dlz=0; dlx=x2-x1; dly=y2-y1; %Calculate the 3 length components of each segment vector dl.
20
21     NGx=100; NGy=100; %Grid dimension
22     Hy=zeros(100); Hz=zeros(100); H=zeros(100); %Construct the H matrix
```

Engineering Electromagnetics
–Experiment 3 (2020)

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Edited by

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2.2 Calculate the Sum of the Magnetic Field

```
1 %% first coil
2 for i=1:NGy %Loop computation of the value of H(x,y) in each grid
3     for j=1:NGx
4         rx=0-xc; ry=y(j)-yc; rz=z(i)-zc; %Calculate the 3 length components of the radius vector r,
5         % and r is in the z = 0 plane.
6         r3=sqrt(rx.^2+ry.^2+rz.^2).^3; %Calculate r cube (r3)
7         dLx_r_y=dLz.*rx-dLx.*rz; %Calculate the y, z components of the cross product dLxr,
8         %x component is 0.
9         dLx_r_z=dLx.*ry-dLy.*rx;
10        Hy(i,j)=sum(C.*dLx_r_y./r3); %Accumulate the magnetic field intensity created
11        %by each segment of the loop.
12        Hz(i,j)=sum(C.*dLx_r_z./r3);
13        H=(Hy.^2+Hz.^2).^0.5; %Calculate the magnitude of H
14    end
15 end
16
17 %% add the mag field of the second coil
18 zc2 = -1;
19 Hy2=zeros(100);Hz2=zeros(100);H2=zeros(100);
20 for i=1:NGy %Loop computation of the value of H(x,y) in each grid
21     for j=1:NGx
22         rx=0-xc; ry=y(j)-yc; rz=z(i)-zc2; %Calculate the 3 length components of the radius vector r,
23         % and r is in the z = 0 plane.
24         r3=sqrt(rx.^2+ry.^2+rz.^2).^3; %Calculate r cube (r3)
25         dLx_r_y=dLz.*rx-dLx.*rz; %Calculate the y, z components of the cross product dLxr,
26         %x component is 0.
27         dLx_r_z=dLx.*ry-dLy.*rx;
28         Hy2(i,j)=sum(C.*dLx_r_y./r3); %Accumulate the magnetic field intensity created
29         %by each segment of the loop.
30         Hz2(i,j)=sum(C.*dLx_r_z./r3);
31         H2=(Hy2.^2+Hz2.^2).^0.5; %Calculate the magnitude of H
32     end
33 end
```

After that, we sum up the magnetic field generated by each current loop respectively.

```
1 Hy = Hy + Hy2;
2 Hz = Hz + Hz2;
3 H = H + H2;
```

2.3 Plot the Diagram

Magnetic field intensity vector distribution:

```
1 %% plot1
2 figure1 = figure; %define figure
3 h = quiver(y,z,Hy,H2,'autoscalefactor',1.25); %Plot the vector graph of the magnetic field intensity
4 set(h,'linewidth',1.2)
5 hold on;
6 title('the plot of magnetic field intensity vector distribution','(represented by arrows) 樊青远 11812418');
7 pbaspect([1 1 1]);
```

```

8      axis([-3,3,-3,3]);
9      plot(2,1,'ro',-2,1,'bo'),          %Standard coil section
10     plot(2,-1,'ro',-2,-1,'bo'),        %Standard coil section
11     xlabel('y/m','fontsize',12),ylabel('z/m','fontsize',12),    %Label the axis
12     set(gcf,'Position',[10 10 500 500]);
13     saveas(gcf,'../fig/A1.jpg');

```

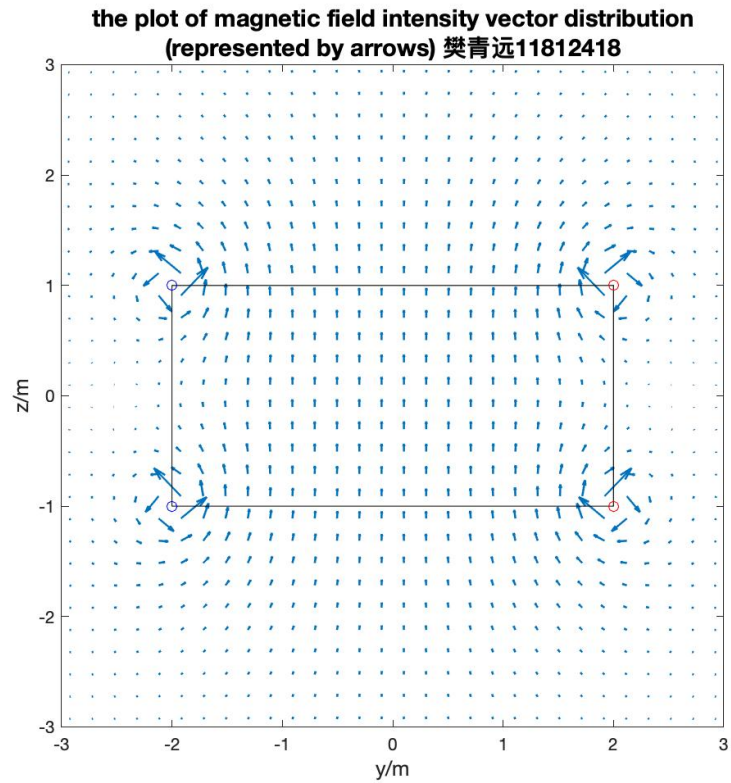


Figure 1. the plot of magnetic field intensity vector distribution (represented by arrows).

Magnetic field intensity magnitude distribution:

```

1      %% plot2
2      figure1 = figure; %define figure
3      surf(y,z,H);%Plot the graph of magnetic field intensity
4      shading interp; %disable the grid
5      colormap default; %set the colour map
6      hold on;
7      title({'the plot of magnetic field intensity magnitude distribution';'樊青远 11812418'}, 'fontsize',12);
8      pbaspect([1 1 1]);
9      axis([-3,3,-3,3,0,1000])
10     xlabel('y/m','fontsize',12),ylabel('z/m','fontsize',12),zlabel('H','fontsize',12);
11     colorbar;

```

```
12 set(gcf,'Position',[10 10 500 500]);  
13 saveas(gcf,'./fig/A2.jpg');
```

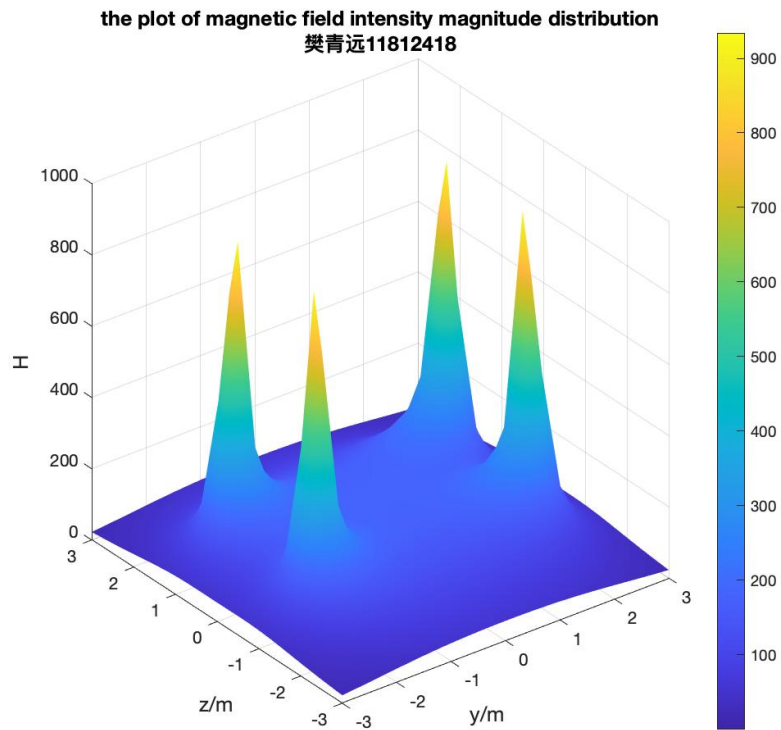


Figure 2. The plot of magnetic field intensity magnitude distribution.

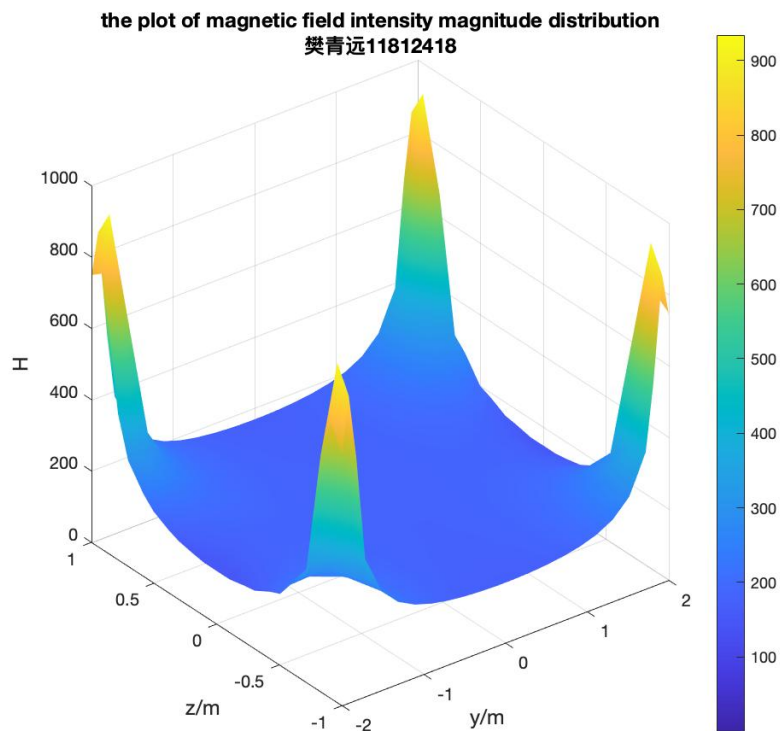


Figure 3. The plot of magnetic field intensity magnitude distribution. ($y = [-2, 2]$, $z = [-1, 1]$)

Magnetic line:

```

1      %% plot3
2      figure1 = figure; %define figure
3      theta=[0 50 60 70 80 90 100 110 120 130 180 230 240 250 260 270 280 290 300 310].*pi/180; %Set
4      ys=2.2*cos(theta); %Set the streamline starting circle' s y coordinate
5      zs=2.2*sin(theta); %Set the streamline starting circle' s z coordinate
6      streamline(y,z,Hy,Hx,ys,zs); %Outwardly plot the magnetic line of force from the starting circle.
7      streamline(y,z,-Hy,-Hx,ys,zs); %Inwardly plot the magnetic line of force from the starting circle.
8      xlabel('y/m','fontsize',12),ylabel('z/m','fontsize',12);
9      title({'the plot of magnetic line';'樊青远 11812418'}, 'fontsize',14);
10     pbaspect([1 1 1]);
11     set(gcf,'Position',[10 10 500 500]);
12     saveas.figure1,'../fig/A3.jpg');

```

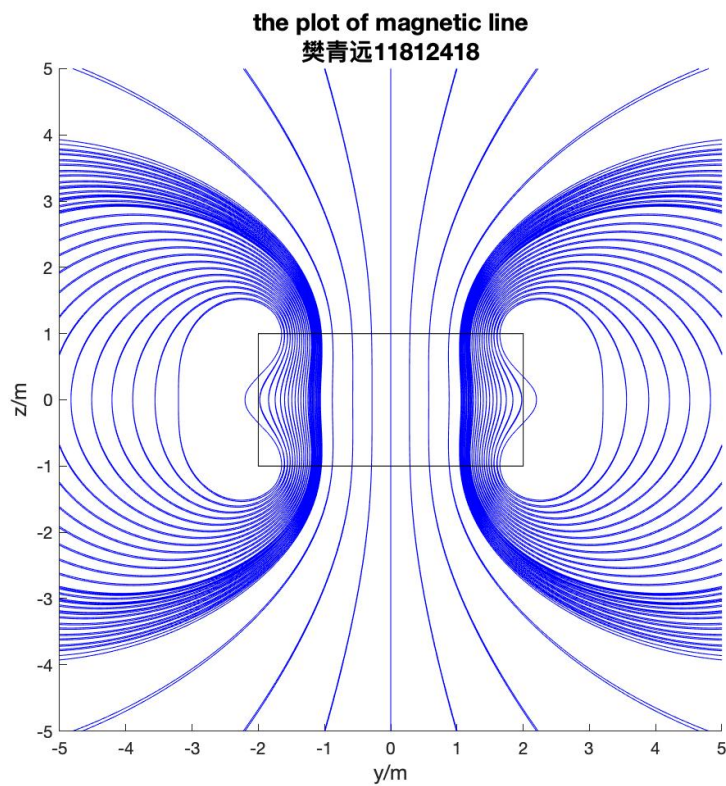


Figure 4. The plot of magnetic line.

2.4 Analyze

From the diagram, we could figure out that at the space between the two current loop, the direction of the magnetic field could be approximate as perpendicular to $x - y$ plane, especially in region $y = [-2, 2]$, $z = [-1, 1]$.

From figure 4, we could also find out that every magnetic line is closed.

The peak of the magnetic field intensity will always occurs on the current loop.

3 Two Current Loop with Same Current Direction

3.1 Define the Paraments

To make the magnetic field more precise, we split each dimension of the space into 100 tiles. The black rectangle in the figure represents the region $y = [-2, 2]$, $z = [-1, 1]$.

```
1      ym=10; %Set the range of y direction in the field domain
2      zm=10; %Set the range of z direction in the field domain
3      y= linspace(-ym,ym,100); % Equally divide y axis into 100 parts
4      z= linspace(-zm,zm,100); % Equally divide z axis into 100 parts
5
6      a=2; %Input the radius of the current loop
7      I=500; %Input the current value in the current loop
8      C=I/(4*pi); %Merge the constants
9      N=50; %Set the number of division
10
11     theta0=linspace(0,2*pi,N+1); %Division of the angle of circumference
12     theta1=theta0(1:N);
13     x1=a*cos(theta1); y1=a*sin(theta1); %The start point coordinate of each segment of the loop
14     theta2=theta0(2:N+1);
15     x2=a*cos(theta2); y2=a*sin(theta2); %The ending point coordinate of each segment of the loop
16
17     zc=1; xc=(x2+x1)/2; yc=(y2+y1)/2; %Calculate the 3 coordinate components of the midpoint
18     % of each segment of the loop.
19     dlz=0; dlx=x2-x1; dly=y2-y1; %Calculate the 3 length components of each segment vector dl.
20
21     NGx=100; NGy=100; %Grid dimension
22     Hy=zeros(100); Hz=zeros(100); H=zeros(100); %Construct the H matrix
```

3.2 Calculate the Sum of the Magnetic Field

```
1      %% first coil
2      for i=1:NGy %Loop computation of the value of H(x,y) in each grid
3          for j=1:NGx
4              rx=0-xc; ry=y(j)-yc; rz=z(i)-zc; %Calculate the 3 length components of the radius vector r,
5              % and r is in the z = 0 plane.
6              r3=sqrt(rx.^2+ry.^2+rz.^2).^3; %Calculate r cube (r3)
7              dlXr_y=dlz.*rx-dlx.*rz; %Calculate the y, z components of the cross product dlxr,
8              %x component is 0.
9              dlXr_z=dlx.*ry-dly.*rx;
10             Hy(i,j)=sum(C.*dlXr_y./r3); %Accumulate the magnetic field intensity created
11             %by each segment of the loop.
12             Hz(i,j)=sum(C.*dlXr_z./r3);
13             H=(Hy.^2+Hz.^2).^0.5; %Calculate the magnitude of H
14         end
15     end
16
17     %% add the mag field of the second coil
18     zc2 = -1;
19     Hy2=zeros(100); Hz2=zeros(100); H2=zeros(100);
20     for i=1:NGy %Loop computation of the value of H(x,y) in each grid
21         for j=1:NGx
22             rx=0-xc; ry=y(j)-yc; rz=z(i)-zc2; %Calculate the 3 length components of the radius vector r,
23             % and r is in the z = 0 plane.
24             r3=sqrt(rx.^2+ry.^2+rz.^2).^3; %Calculate r cube (r3)
25             dlXr_y=dlz.*rx-dlx.*rz; %Calculate the y, z components of the cross product dlxr,
```

```

26     %x component is 0.
27     dlXr_z=dlx.*ry-dly.*rx;
28     Hy2(i,j)=sum(C.*dlXr_y./r3);           %Accumulate the magnetic field intensity created
29     %by each segment of the loop.
30     Hz2(i,j)=sum(C.*dlXr_z./r3);
31     H2=(Hy2.^2+Hz2.^2).^0.5;               %Calculate the magnitude of H
32     end
33 end

```

After that, we sum up the magnetic field generated by each current loop respectively. However, as the current direction of the second current loop is opposite to the first one, so we minus the magnetic field generate by the second current on the first current loop.

```

1     Hy = Hy - Hy2;
2     Hz = Hz - Hz2;
3     H = H - H2;

```

3.3 Plot the Diagram

Magnetic field intensity vector distribution:

```

1     %% plot1
2     figure1 = figure; %define figure
3     h = quiver(y,z,Hy,H2,'autoscalefactor',1.25);           %Plot the vector graph of the magnetic field intensi
4     set(h,'linewidth',1.2)
5     hold on;
6     title({'the plot of magnetic field intensity vector distribution';'(represented by arrows) 樊青远 118124
7     pbaspect([1 1 1]);
8     axis([-3,3,-3,3]);
9     plot(2,1,'ro',-2,1,'bo'),           %Standard coil section
10    plot(2,-1,'ro',-2,-1,'bo'),         %Standard coil section
11    xlabel('y/m','fontsize',12),ylabel('z/m','fontsize',12), %Label the axis
12    set(gcf,'Position',[10 10 500 500]);
13    saveas(figure1,'../fig/B1.jpg');

```

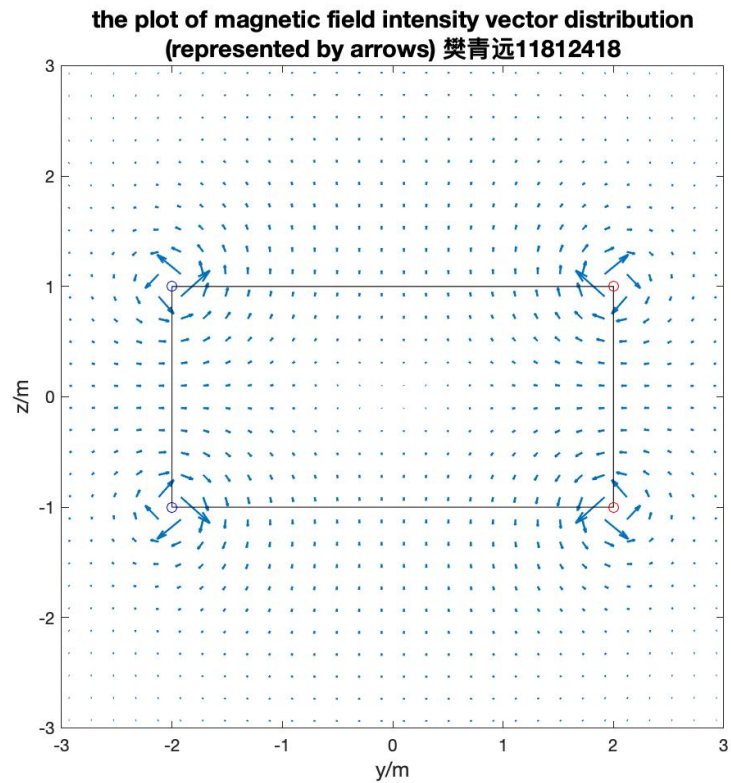



Figure 5. the plot of magnetic field intensity vector distribution (represented by arrows).

Magnetic field intensity magnitude distribution:

```

1      %% plot2
2      figure1 = figure; %define figure
3      surf(y,z,H);%Plot the graph of magnetic field intensity
4      shading interp; %disable the grid
5      colormap default; %set the colour map
6      hold on;
7      title({'the plot of magnetic field intensity magnitude distribution';'樊青远 11812418'}, 'fontsize',12);
8      pbaspect([1 1 1]);
9      axis([-3,3,-3,3,0,1000])
10     xlabel('y/m','fontsize',12),ylabel('z/m','fontsize',12),zlabel('H','fontsize',12);
11     colorbar;
12     set(gcf,'Position',[10 10 500 500]);
13     saveas.figure1,'../fig/B2.jpg');

```

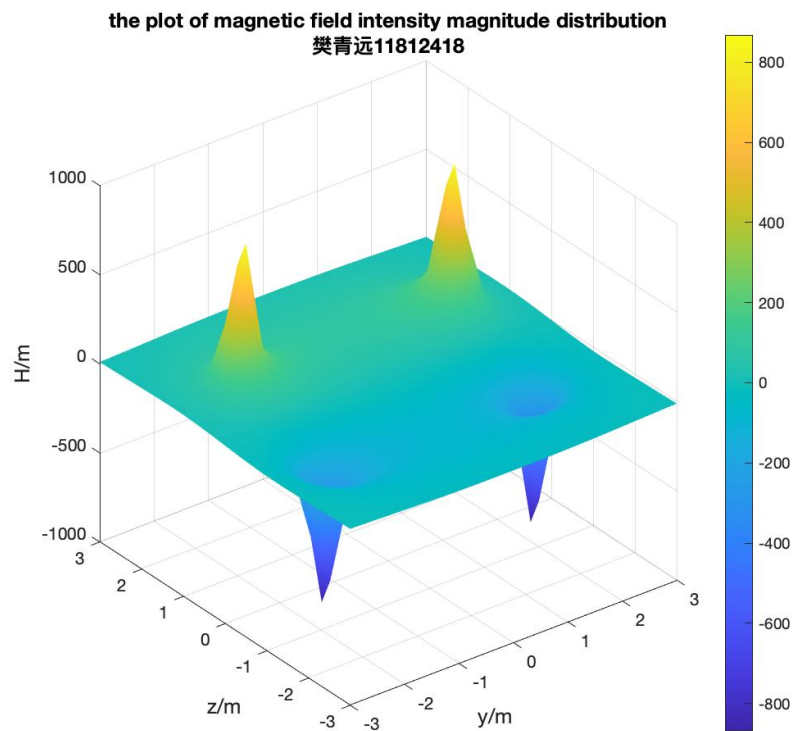


Figure 6. The plot of magnetic field intensity magnitude distribution.

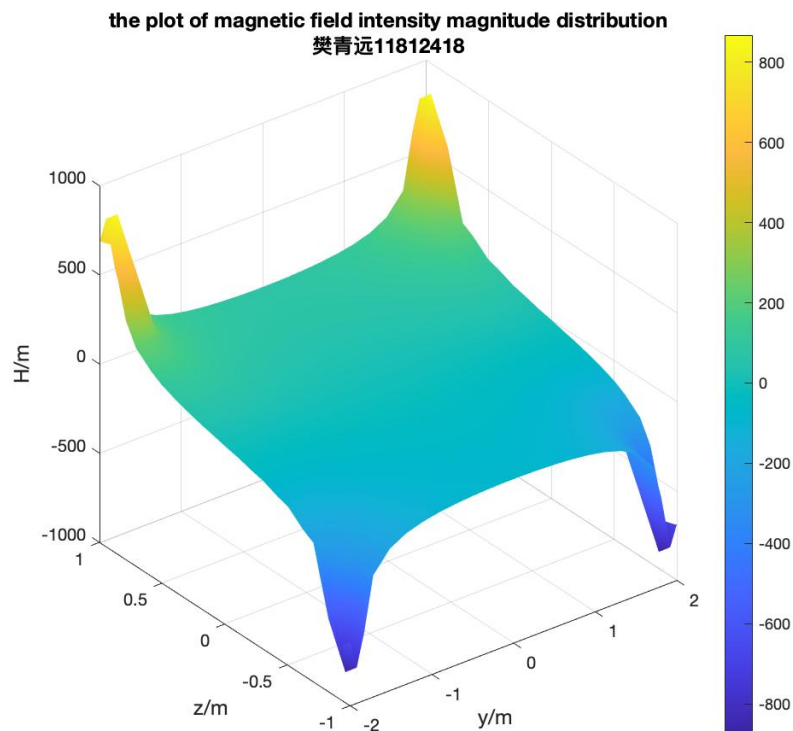


Figure 7. The plot of magnetic field intensity magnitude distribution. ($y = [-2, 2]$, $z = [-1, 1]$)

Magnetic line:

```

1      %% plot3
2      figure1 = figure; %define figure
3      theta=[0 50 60 70 80 90 100 110 120 130 180 230 240 250 260 270 280 290 300 310].*pi/180; %Set
4      ys=2.2*cos(theta); %Set the streamline starting circle' s y coordinate
5      zs=2.2*sin(theta); %Set the streamline starting circle' s z coordinate
6      streamline(y,z,Hy,Hx,ys,zs); %Outwardly plot the magnetic line of force from the starting circle.
7      streamline(y,z,-Hy,-Hx,ys,zs); %Inwardly plot the magnetic line of force from the starting circle.
8      xlabel('y/m','fontsize',12),ylabel('z/m','fontsize',12);
9      title({'the plot of magnetic line';'樊青远 11812418'}, 'fontsize',14);
10     pbaspect([1 1 1]);
11     set(gcf,'Position',[10 10 500 500]);
12     saveas.figure1,'../fig/B3.jpg');

```

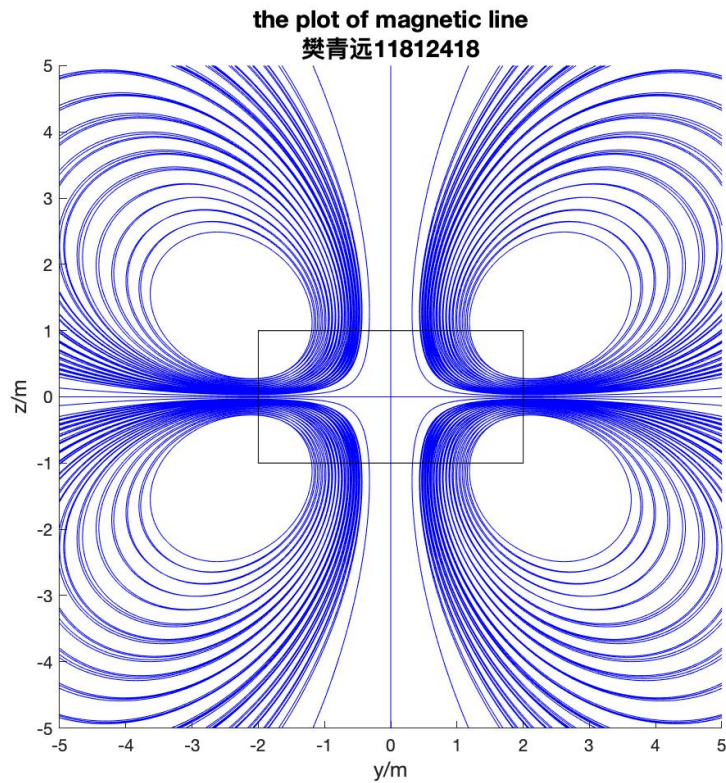


Figure 8. The plot of magnetic line.

3.4 Analyze

From the diagram, we could figure out that at the line pass through the two current loops, the direction of the magnetic field could be approximate as perpendicular to $x - y$ plane, especially in region $y = [-2, 2]$, $z = [-1, 1]$.

The magnetic field intensity at the origin of the axis equals zero.

From figure 8, we could also find out that every magnetic line is closed.

The peak of the magnetic field intensity will always occurs on the current loop.

4 Inspiration

From this experiment, we've learn a intuitive way to plot the charactristic properties that the magnetic field generated by current loop(s) and deepen our understanding of the application of the Biot–Savart law.

We also recognized that the more tiles to seperate one plane, the result will be more accurate.