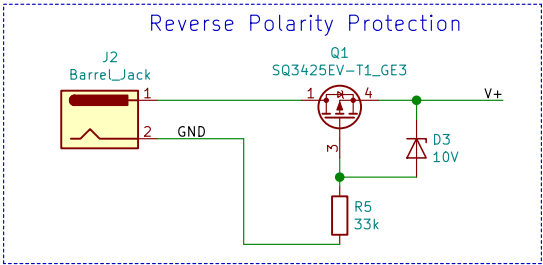
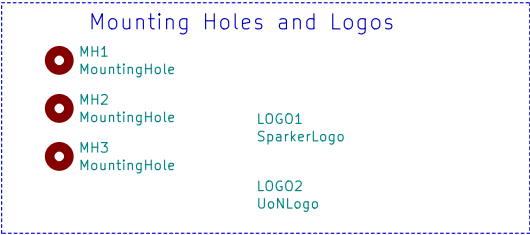
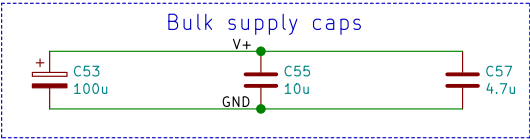
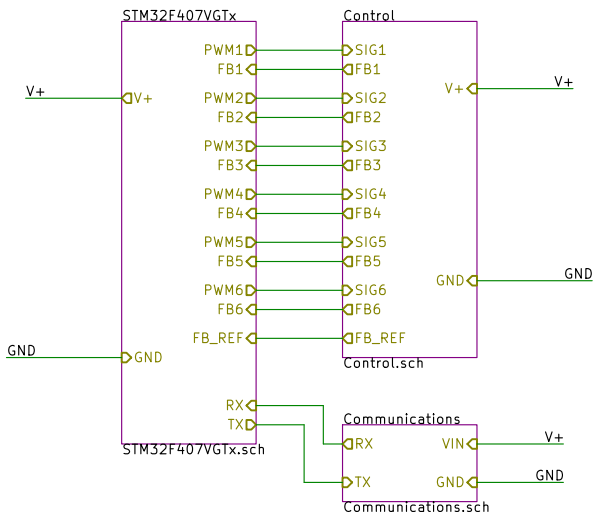
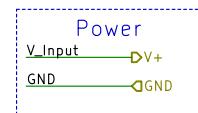
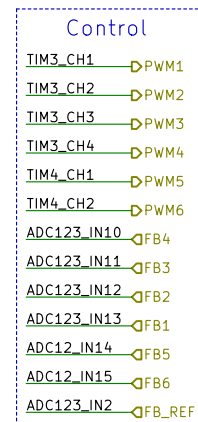
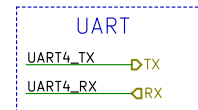
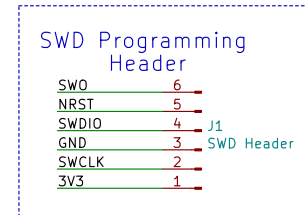
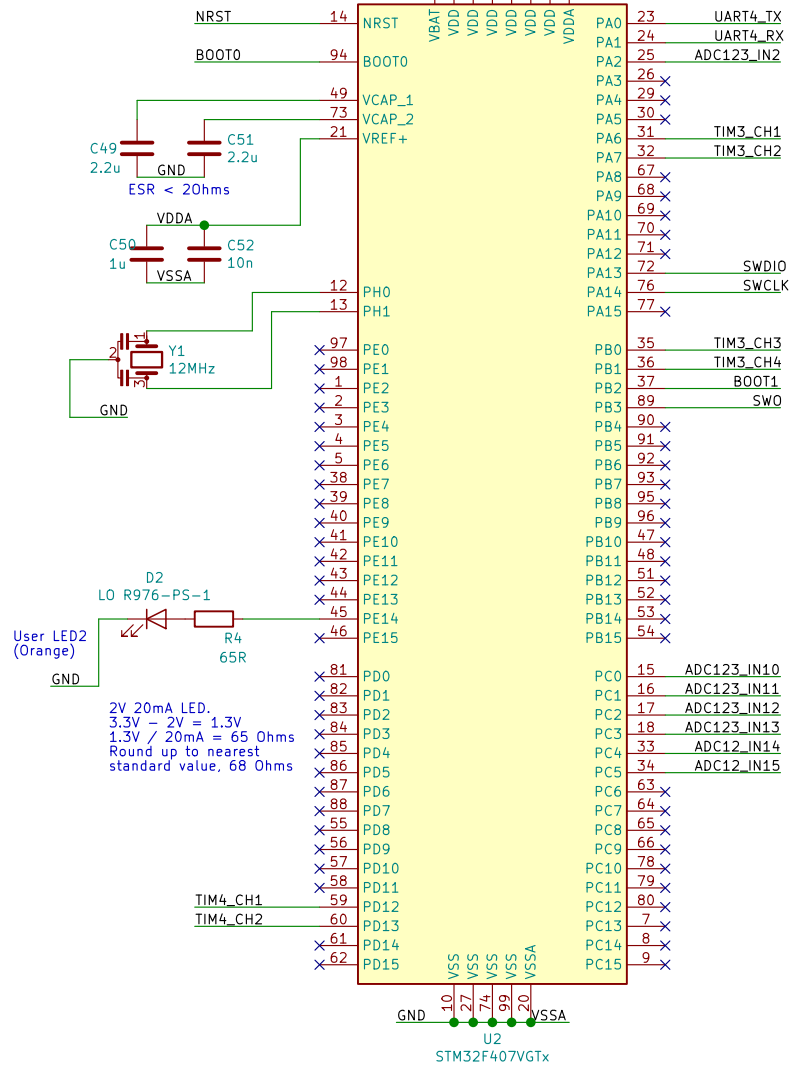
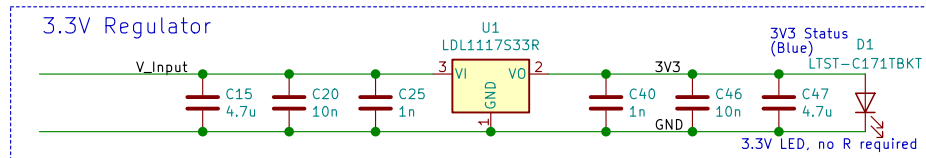
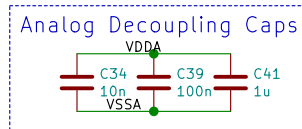
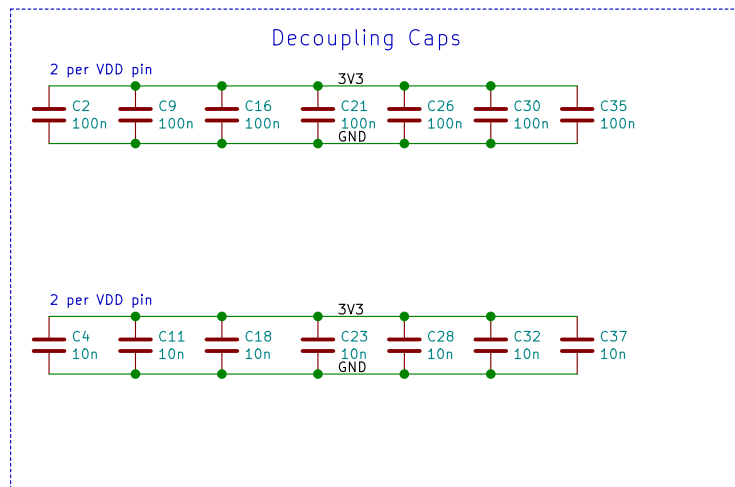
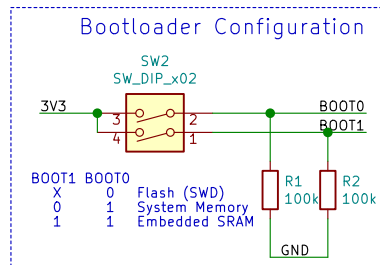
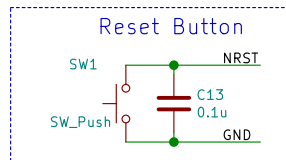


Classification and Control Board



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STM32F407VGTx



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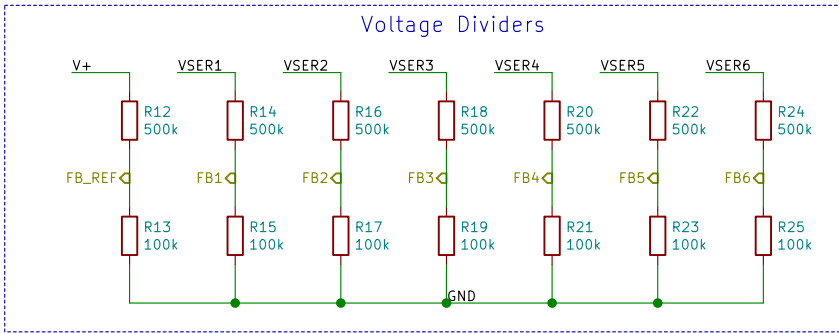
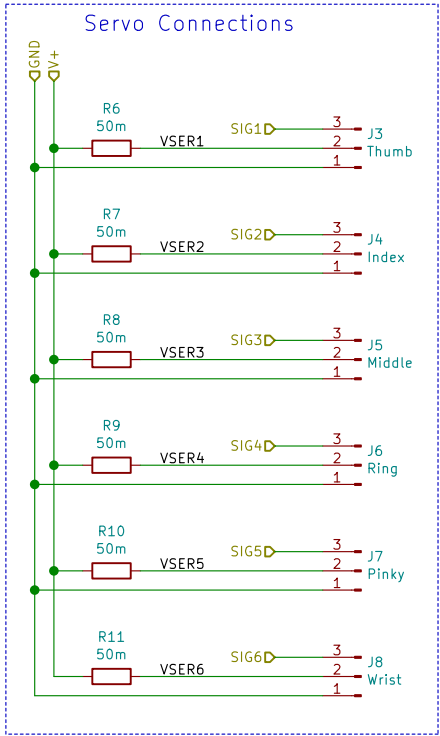
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Control



50mOhm current sense resistors.
Voltage before and after resistor passed through 1/5th voltage divider.
Voltage measured at FBx points by 16-bit ADC.
Voltage drop across resistor given by $FB_Ref - Value$.
Voltage drop across resistor $\times 5 / (50 \times 10^{-3})$ gives current consumed by each servo.
Voltage supply drop to servo should be minimal (and we are supplying near maximum end of rated voltage)

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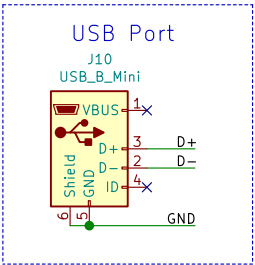
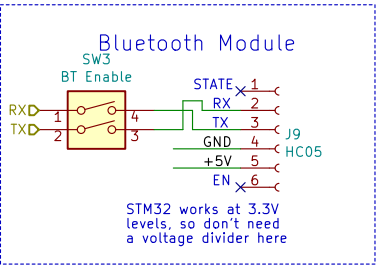
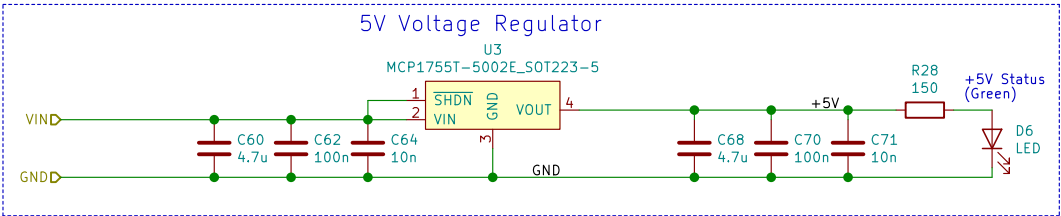
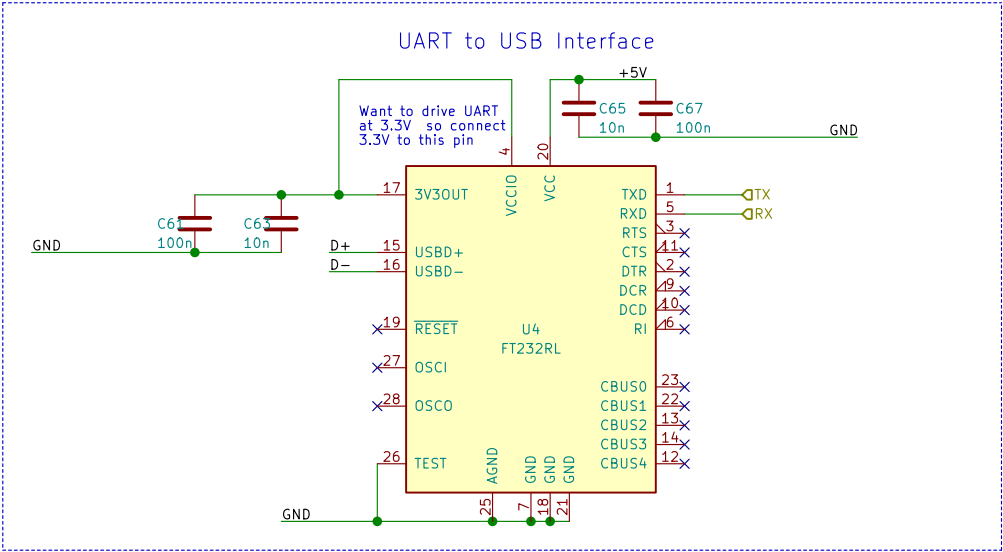
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Communications



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