Proofs of the theorems in Search Space Expansion for Efficient Incremental Inductive Logic Programming from Streamed Data

Theorem 1. The set $\mathcal{G}(T') = generalise(\mathcal{C}(T), \mathcal{C}(T')) \cup \mathcal{G}(T)$ is a generalised rule space w.r.t. $\mathcal{C}(T')$.

Proof. First, we show that all rules in the generalised rule space w.r.t. $\mathcal{C}(T')$ are in $\mathcal{G}(T')$. To do this, it suffices to show that if a rule R in the generalised rule space is not in $\mathcal{G}(T)$ then it is in the set returned by generalise $(\mathcal{C}(T), \mathcal{C}(T'))$. To do so, we show the following condition is an invariant for the main for loop: $\langle R^*, subs \rangle \in G$, where R^* is the rule with the same head as R and a body containing those literals in the body of R that have already been processed and subs = $c_{R^*}^+(T')$. Note that such a tuple can never be removed by the Filter function because for each element of bls that is not in the body of R, there must be at least one rule in $c_{R^*}^+(T')$ that does not contain it (or R could not be in the generalised rule space). Hence, it remains to show that if the condition holds at the beginning of an iteration then the condition holds for NewG at the end of the iteration. Consider an arbitrary iteration where the condition holds at the beginning.

Case 1: $bl \notin body(R)$. As $R \in \mathcal{G}(T')$ there must be at least one rule in $c_R^+(T)$ that does not contain bl. Hence, $new_subs \neq subs$. So $\langle R^*, subs \rangle$ is added to NewG, so the invariant still holds.

Case 2: $bl \in body(R)$. Consider the iteration of the second for loop which corresponds to the pair $\langle R^*, subs \rangle$. Let R^*_{bl} be the rule R^* with bl appended to the body. Note that $new_subs = c^+_{R^*_{bl}}(T')$. This set clearly contains $c^+_R(T')$ and so must be non-empty (as $R \in \mathcal{G}(T')$). Hence, the pair $\langle R^*_{bl}, new_subs \rangle$ must be added to NewG, either in line 11 or in line 15. So the invariant still holds at the end of the iteration

Hence, at the end of the execution, $\langle R, c_R^+(T') \rangle \in G$, and so R is in the set returned by *generalise*.

It remains to show that every rule R in $\mathcal{G}(T')$ is in the generalised rule space w.r.t. $\mathcal{C}(T')$.

Case 1: $R \in \mathcal{G}(T)$. Then $c_R^+(T) \neq \emptyset$ and there is no rule $R' \in S_M$ s.t. R is a strict sub-rule of R' and $c_R^+(T) = c_{R'}^+(T)$. Hence $c_R^+(T') \neq \emptyset$ and there is no rule $R' \in S_M$ s.t. R is a strict sub-rule of R' and $c_R^+(T') = c_{R'}^+(T')$. So, R must be in $\mathcal{G}(T')$.

Case 2: $R \in generalise(\mathcal{C}(T), \mathcal{C}(T'))$. Then there must be a pair $\langle R, subs \rangle \in G$ at the end of the generalise execution. Assume for contradiction that $c_R^+(T') = \emptyset$. Then for each

 $R' \in \mathcal{C}^+(T)$ s.t. head(R) = head(R'), at least one element of bls must be in body(R) and not in body(R'). Hence, there must be an iteration where new_subs becomes empty, and no pair $\langle R, S \rangle$ is added to NewG. This contradicts the fact that $\langle R, subs \rangle \in G$ at the end. It remains to show that there is no $R' \in S_M$ s.t. R is a strict sub-rule of R' and $c_R^+(T) = c_{R'}^+(T)$. If this were the case then each body literal that occurs in R' but not in R would have to occur in every element of $c_R^+(T)$. But if this were the case, then the rule would be removed by the Filter at some point in the execution. Hence, R must be in $\mathcal{G}(T')$.

Theorem 2. Let $\mathcal{O}(T') = \{\langle R, \mathcal{O}_{R,T'} \rangle \mid R \in \mathcal{U}(T,T')\} \cup \{\langle R, \mathcal{O}_{R,T} \rangle \mid R \in \mathcal{G}(T') \setminus \mathcal{U}(T,T')\}. \langle \mathcal{C}(T'), \mathcal{G}(T'), \mathcal{O}(T') \rangle$ is a valid state after solving T'.

Proof. As the sets $\mathcal{U}(T,T')$ and $\mathcal{G}(T')\setminus\mathcal{U}(T,T')$ form a partition of the set $\mathcal{G}(T')$, each rule in $\mathcal{G}(T')$ is clearly represented by exactly one pair in $\mathcal{O}(T')$. It therefore remains to show that the second element of this pair is a valid optimisation of R w.r.t. T'.

Case 1: $R \in \mathcal{U}(T,T')$. In this case the second element, $\mathcal{O}_{R,T'}$ is defined according to Definition 4 of the main paper (using $\mathcal{G}(T')$ and $\mathcal{C}(T')$); hence, due to the correctness results proved in [Law *et al.*, 2020] it must be a valid optimisation of R w.r.t. T'.

Case 2: $R \notin \mathcal{U}(T,T')$. In this case, we must show that $\mathcal{O}_{R,T}$ is a valid optimisation of R w.r.t. T. Assume for contradiction that it is not. Then either there is a rule in $\mathcal{O}_{R,T}$ that violates one of the conditions in (1) of Definition 4, or an additional rule can be added without violating (1). As R is not in $\mathcal{U}(T,T')$, for each rule in $r \in \mathcal{O}_{R,T}$, v(r,T) = v(r,T'). Hence, as for any other rule in $r' \in S_M$, $v(r',T) \subseteq v(r',T')$, this cannot be the case. Contradiction!

Theorem 3. For any task T and valid state, $\langle C(T), G(T), \mathcal{O}(T) \rangle$, after solving $T, \bigcup_{\langle R, S \rangle \in \mathcal{O}(T)} R$ is OPT-sufficient.

Proof. Assume for contradiction that $O=\bigcup\limits_{\langle R,S\rangle\in\mathcal{O}(T)}R$ is not OPT-sufficient. Then T must be satisfiable. Let H^* be an optimal solution of T. There must be a rule in $h\in H^*$ such that $c_h^+(T)\neq\emptyset$ and there is no rule $h'\in O$ s.t. |h|=|h'|, $c_h^+(T)=c_{h'}^+(T)$ and $v(h',T)\subseteq v(h,T)$ – otherwise each

rule R could be replaced with its corresponding rule R', and the resulting hypothesis would be an optimal solution.

As $\mathcal{G}(T)$ is a generalised rule space, there must be a rule $h^g \in \mathcal{G}(T)$ such that $c_h^+(T) = c_{hg}^+(T)$ and h is a sub-rule of h^g . But if this were the case, as $\mathcal{O}(R,T) \subset O$, $\mathcal{O}(R,T)$ must not be a valid optimisation of R w.r.t. T, as h can be added to it without breaking (1) of Definition 4. Contradiction!

References

[Law et al., 2020] Mark Law, Alessandra Russo, Elisa Bertino, Krysia Broda, and Jorge Lobo. FastLAS: Scalable inductive logic programming incorporating domain-specific optimisation criteria. In AAAI. Association for the Advancement of Artificial Intelligence, 2020.