

MST

Kruskal

Prims

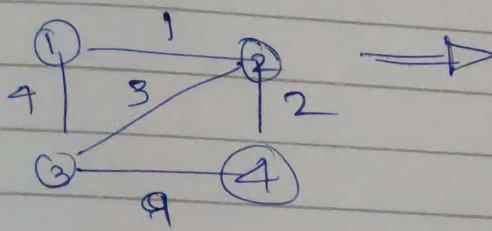
Dijkstras

Topological Ordering — Bellman Ford

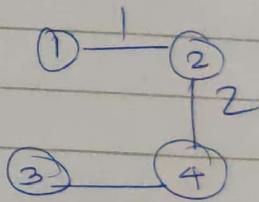
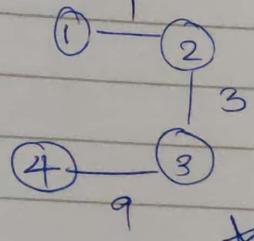
* Spanning trees is a representation of a graph in a tree like structure where all nodes are accessible when traversed from the root / start node

* Doesn't work on ~~unconnected graphs~~.

MST is a case when cost associated is the minimum from the graph



Possible spanning Trees



* (it is an acyclic graph)
etc...

Usually Trend is

E = set of edges

V = set of vertices

G = the graph

S = spanning Tree

Spanning Tree = (V', E')

where $S \subseteq G$

$$S = (V', E')$$

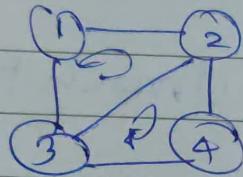
$$V' = V$$

$$|E'| = |V'| - 1$$

no. of edges = no. of nodes - 1
for a spanning tree.

not important

$$\text{No. of possible Spanning trees} = |E|^{V-1} C_{V-1} - \text{no. of cycles}$$



$$\text{no. of cycles} = 2$$

(1, 2, 3) X (2, 3, 4)

$$E = 6$$

$$V = 4$$

$$V - 1 = 3$$

$$\text{No. of possible Spanning trees} = {}^5C_3 - 3$$

$$= 5 \times 4 - 3$$

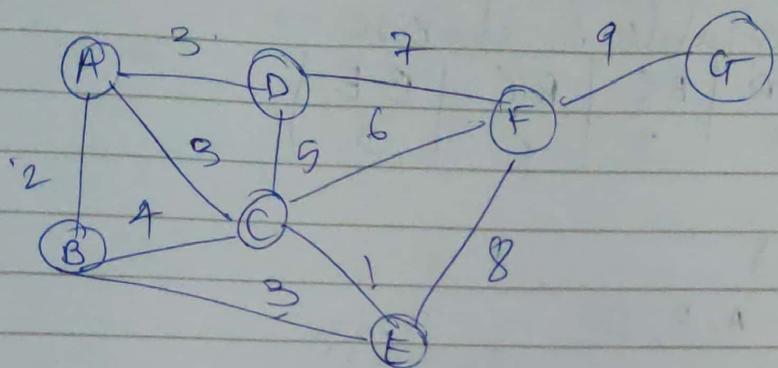
$$= \underline{\underline{9}}$$

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$$O(|E| \log |E|)$$

Prim's Algorithm

- ① It is a greedy algorithm
- ② Start at an arbitrary vertex/node
- ③ add to the visited list
- ④ choose the smallest edge connected to this starting node & add the next node to visited list, pick nodes only that have not been visited
- ⑤ Repeat till all done
- ⑥ Picking is to be done based on available edges of the visited nodes in the spanning tree
- ⑦ Always makes sure it builds a tree

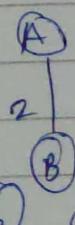


- ① let's start at say A
- ② visited = [A]
- ③ edges available from nodes in visited
- ④ edge | AB | AC | AD
cost | 2 | 3 | 3

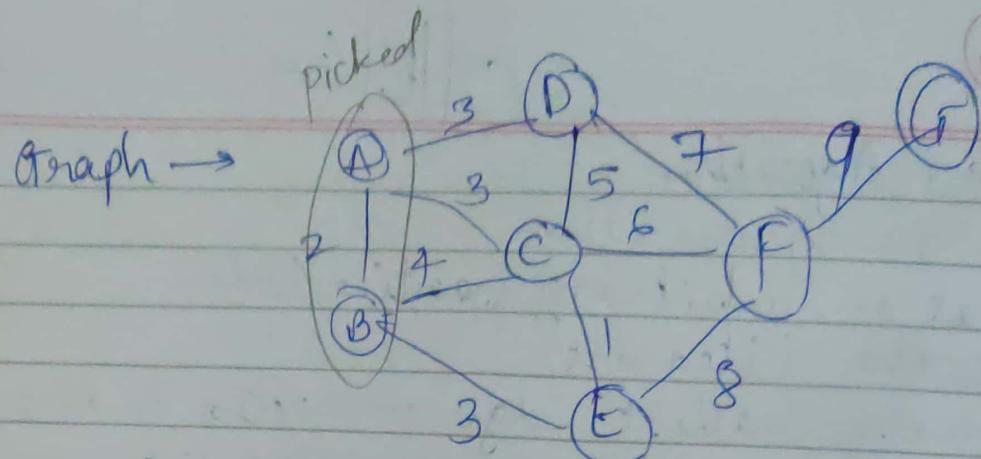
- ⑤ pick least cost edge i.e AB (2)
- ⑥ add B to visited

- ⑥ visited = A, B

- ⑦ spanning tree →



- ⑧ Repeat from ③ to ⑥ again till all nodes in visited



spanning tree = $\begin{array}{c} \textcircled{A} \\ | \\ \textcircled{B} \end{array}$

edges available to choose →

edge	AD	AC	BC	BE
cost	3	3	4	3

↑ min()

visited = A, B, D

spanning tree → $\begin{array}{c} \textcircled{A} --- \textcircled{D} \\ | \\ \textcircled{B} \end{array}$

edges available

edge	AC	BC	DC	BE	DF
cost	3	4	5	3	7

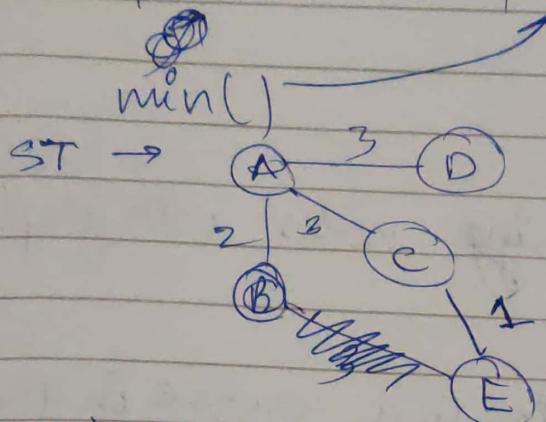
min ↴

visited = A, B, D, C

ST → $\begin{array}{c} \textcircled{A} --- \textcircled{B} \\ | \\ \textcircled{B} --- \textcircled{C} \end{array}$

visited = A, B, D, E

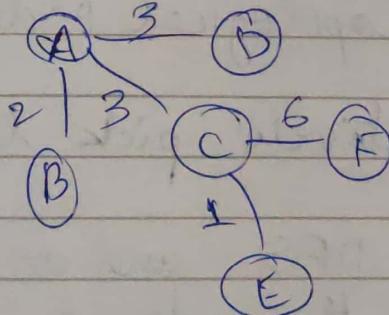
edges	BE	DF	CF	CE
cost	3	7	6	1



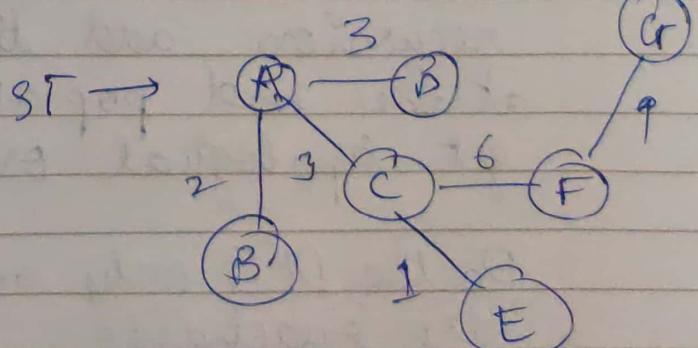
visited = A, B, D, C, E

edges	DF	CF	EF
cost	7	6	8

visited = A, B, D, C, E, F
ST →



edges	FG
cost	9



$$\text{Total cost} = \underline{\underline{2+3+7+1+6+9}}$$

$$= \underline{\underline{24}} \quad (\text{MST cost})$$

It is a greedy approach as it doesn't

~~answered in KRUSKAL,~~
~~How different Data Structure Affects Prints?~~

Topological ordering

Fancy way of ordering nodes with graph arrows towards right

Example ① pre requisites to a course in graph
Structure

② compiling resources for a program before the actual program.

- * Doesn't work on acyclic graph.
- * Aren't always unique.
- * Every tree has a topological order.

To find it, iteratively pick leaf nodes.

Do a ~~Recursive~~ DFS and on return of recursion, add the node to a stack.
at the end pop all elements of stack to get topological ordering.

Do the DFS only on unvisited nodes which are reachable.

Kruskals Algo.

- ① Pick smallest edge repeatedly to form a tree such that the new edge ~~always has at least one unvisited node~~ doesn't create a cycle.

It is a greedy approach based on ~~on~~ sorting the edge weights.

Run time $O(E \log E)$ general
 $O(e \lg v)$ with binary heap to always get the min edge.

{ Can run faster with fibonacci heap $O(e + v \lg v)$ }
 { If cardinality of edges is smaller than edges. }

Run time is mainly affected by how fast the min edge is given

~~can also be $O(E \times v)$ if edges are~~
~~new~~ already sorted

Algo →

$A = \emptyset$
 for each (node) in (graph G)
 $\text{MAKE-SET}(v)$

// sort the edges in ASC ~~at~~ order. //

foreach (u, v) from sorted list
 if ($\text{FindSet}(u) \neq \text{FindSet}(v)$)
 $A = A \cup \{(u, v)\}$
 $\text{UNION}(u, v)$

$\log v$

return A

Bellman Ford.

[Fails when there is a cycle with negative weight]

Relaxation

for edges $w(u,v)$ of vertices $u \neq v$

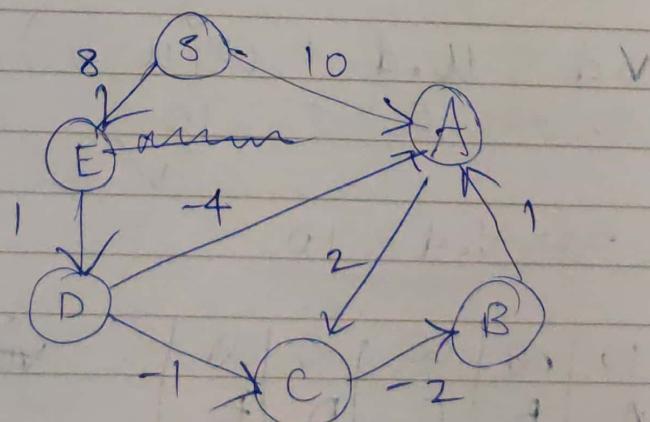
$$\text{If } d[u] + w(u,v) \cdot \text{cost} < d[v]$$

$$\Rightarrow d[v] = d[u] + w(u,v) \cdot \text{cost}$$

means if there is a better way to reach the node, calculate it and replace the old distance to that node.

It takes $|V| - 1$ iterations to find shortest path on a weighted directed graph using Bellman-Ford. ~~(Any kind of graph)~~

This algo allows negative weights.



- ① initialize all distance from S to other nodes as ∞ , S distance to itself is 0

S	0	∞	∞	∞	∞
	A	B	C	D	E

S = Starting node.

② Pass ①

now for $u = S \quad V = [A, B, C, D, E, F]$

Check relaxation condition

if $V.d < u.d + w[u, v].cost$

$V.d = u.d + \underline{w[u, v].cost}$

\uparrow edge cost
 \uparrow distance to u

Initially d is ∞ for all nodes v .

0	∞	∞	∞	∞	∞
S	A	B	C	D	E

w has cost of all edges.

Now for let say $v = A$. & $u = S$.
edge $w(u, v)$ exists with cost 10

$$\therefore V.d < u.d + w(u, v)$$

$$\infty < 0 + 10$$

✓

$$\Rightarrow V.d = 10$$

0	10	∞	∞	∞	∞
S	A	B	C	D	E

~~visited~~ S B

similarly do for all B, C, D, E and solve
only if ~~exists~~ v is reachable with them.
end of Pass ①

we get

0	10	10	12	9	8
S	A	B	C	D	E

now $v = B$

\emptyset	10	∞	∞	∞	∞
S	A	B	C	D	E

currently we don't have a path to reach B
 from the ~~set~~ using visited nodes = ~~S, A~~

move on to $v = C$ no edge available from u
~~visited = S~~

~~we have a path to e using \{A\}~~

\Rightarrow let $u = A$

$$\therefore \text{is } v.d \leq u.d + w(u, v)$$

$$\infty \leq 10 \oplus 2$$

$$\Rightarrow v.d = 12$$

\emptyset	10	∞	12	∞	∞
S	A	B	C	D	E

$v = D$ no edge,

we have another edge from $u = S$

for $v = E$

\emptyset	10	∞	∞	∞	8
S	A	B	C	D	E

Now $u = A$.

now we can reach C

\emptyset	10	∞	12	∞	8
S	A	B	C	D	E

No more edges

let $u = B$, we have edge BA but we
 don't know how to reach B, so skip

Still Pass ①

now $u = C$

0	10	∞	12	∞	8	.
s	A	B	C	D	E	.

we have edge $CB = -2$

\Rightarrow

0	10	10	12	∞	.
s	A	B	C	D	E

now $u = D$

$\therefore D \leftarrow \infty$ skip

$u = E$

we can reach D with $ED = 1$

\Rightarrow

0	10	10	12	1	8	.
s	A	B	C	D	E	.

Pass ① done

Pass ②

 $u = A$

no improvement

 $u = B$

no improve

 $u = C$ no improve $u = D$ $DA = -4$ improves cost

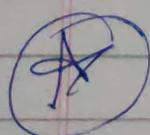
0	$\nearrow 9-4$	5	10	12	9	8
S	A	B	C	D	E	

 $DC = -1$

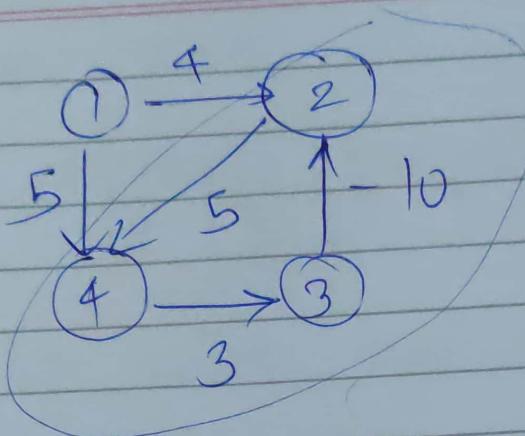
0	$\nearrow 9-1$	5	10	8	9	8
S	A	B	C	D	E	

 $u = E$

no improve



Repeat for Pass ③ and so on till
no changes occur ~~at all~~ at all in the array



→ it is a cycle

$$\begin{aligned} \text{weight} &= -10 + 5 + 3 \\ &= -2 \\ &< 0 \end{aligned}$$

✓ ∞ no of nodes

Causes relaxation even after
 $(n-1)$ iterations
which breaks the Bellman
ford algo's foundation.