

# 0306\_ESE\_MCQ\_MCA\_Sem 4

ECC 402- Microcontrollers

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1. | Which of the following parts of the microprocessor is closely related to register?

- ☐ Processor
- ☐ ALU
- ☐ CPU
- ☒ Memory

Clear selection

2. | During the execution of a program, which register is initialized first?

- ☐ Instruction registers
- ☒ Program Counter
- ☐ Stack pointer
- ☐ Program status word

Clear selection

3. | A microprocessor is clocked at a rate of 3 GHz. How long is a clock cycle?

- ☐ 0.2ns
- ☒ 0.3ns
- ☐ 1.5ns
- ☐ 1ns

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4. How can we change the speed of a DC motor using PWM in PIC 16F886 microcontroller?

- ☐ By changing amplitude of Pulse
- ☐ By keeping fixed duty cycle
- ☒ By changing duty cycle
- ☐ By increasing power of Pulse

Clear selection

5. A CPU generates 32-bit virtual addresses. The page size is 4 KB. The processor has a translation look-aside buffer (TLB), which can hold a total of 128 page table entries and is 4-way set associative. The minimum size of the TLB tag is:

- ☐ 11 bits
- ☐ 13 bits
- ☒ 15 bits
- ☐ 20 bits

Clear selection

6. The high speed memory between the CPU and main memory is called as-----

- ☒ Cache Memory
- ☐ Virtual memory
- ☐ Secondary memory
- ☐ Storage memory

Clear selection

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7.	The register that can be used as a scratch pad in 8051 is
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- ☐ Accumulator
- ☐ Stack Pointer
- ☐ Program Counter
- ☒ B register

[Clear selection](#)

8.	The registers that provide control and status information about Timer/Counters in 8051 is
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- ☐ IP, IE
- ☒ TMOD, TCON
- ☐ SCON, SBUF
- ☐ Flag register, Accumulator

[Clear selection](#)

9.	The higher and lower bytes of a 16-bit register DPTR in 8051 are represented respectively as
----	--

- ☐ LDPTR and HDPTR
- ☐ DPTRL and DPTRH
- ☒ DPH and DPL
- ☐ HDP and LDP

[Clear selection](#)

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10. The pin that is grounded for interfacing external program memory in 8051 is

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- ☒ EA(active low)
- ☐ PSEN(active low)
- ☐ OE(active low)
- ☐ ALE

Clear selection

11. The 8051 instruction that is used to complement or invert the bit of a bit addressable SFR is

- ☐ CLR C
- ☐ CPL C
- ☒ CPL Bit
- ☐ ANL Bit

Clear selection

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12. The first byte of an absolute jump instruction in 8051 consists of

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- ☐ 3 LSBs of opcode and 5 MSBs of 11-bit address
- ☒ 5 LSBs of opcode and 3 MSBs of 11-bit address
- ☐ 5 MSBs of opcode and 3 LSBs of 11-bit address
- ☐ 6 MSBs of opcode and 1 LSB of 11-bit address

Clear selection

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13. What is the function of a watchdog timer (WDT)?

- ☐ It resets the system if applied voltage increased above threshold value
- ☐ It resets the system if applied voltage decreases below threshold value
- ☒ It resets the system if the software fails to operate properly.
- ☐ It resets the system if Power failure is detected.

Clear selection

14. The instructions that change the sequence of execution are

- ☐ conditional instructions
- ☐ logical instructions
- ☒ control transfer instructions
- ☐ data transfer instructions

Clear selection

15. In the instruction "MOV TH1, #-3", what is the value that is being loaded in the TH1 register?

- ☐ 0xFCH
- ☐ 0xFBH
- ☒ 0xFDH
- ☐ 0xFEH

Clear selection

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16.	How many registers are there in ARM7?
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- ☐ 35 register( 28 GPR and 7 SPR)
- ☐ 37 registers(28 GPR and 9 SPR)
- ☒ 37 registers(31 GPR and 6 SPR)
- ☐ 35 register(30 GPR and 5 SPR)

[Clear selection](#)

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17.	How much flash memory does the Atmega328 have?
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- ☐ 13K bytes
- ☒ 32K bytes
- ☐ 256K bytes
- ☐ 16K bytes

[Clear selection](#)

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18.	What is the capability of ARM7 instruction for a second?
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- ☐ 110 MIPS
- ☒ 130 MIPS
- ☐ 150 MIPS
- ☐ 125 MIPS

[Clear selection](#)

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19.

Which of the following are pipelining stages of ARM7?

- ☐ Fetch, Decode, Write
- ☐ Fetch, Decode, Execute, Write
- ☐ Fetch, Execute, Write
- ☒ Fetch, Decode, Execute

Clear selection

20.

In ARM 7, program counter is implemented using \_\_\_\_\_

- ☐ Caches
- ☐ Heaps
- ☒ General purpose register
- ☐ Stack

Clear selection

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