

Chapter 2

Probability Space

2.1 Random Experiments and Sample Space

The main starting idea in Probability theory is the notion of a **random experiment**. By a random experiment we refer to an experiment where we do not know exactly what the outcome is, but know that the outcome will be from a known set of possible outcomes. This set of all possible outcomes is called the **Sample Space** for the experiment, and this set will be denoted by Ω .

Example 2.1.1 The simplest example is that of tossing a coin. While we do not know what the outcome is, we know that it has to be either a Head or a Tail, which we denote by H and T respectively. Thus in this experiment we have

$$\Omega = \{H, T\} \tag{2.1.1}$$

Example 2.1.2 Suppose we toss a fair coin thrice and note the sequence of outcomes. Then for this experiment we have

$$\Omega \ = \ \{HHH, HHT, HTH, HTT, THH, THT, TTH, TTT\} \ (2.1.2)$$

Example 2.1.3 For the experiment of throwing a six faced die, with its faces numbered 1, 2, 3, 4, 5, 6 we have

$$\Omega = \{1, 2, 3, 4, 5, 6\} \tag{2.1.3}$$

Example 2.1.4 Suppose we throw a coin on the floor and note the coordinates of the centre of the coin when it lands. Let us use a reference X and Y axis and denote the points in the room by (x, y); where

$$a \le x \le b$$
 and $c \le x \le d$

Then

$$\Omega = \{(x,y) : a \le x \le b, c \le y \le d\}$$
 (2.1.4)

 $\Omega = \{(x,y): a \le x \le b, \ c \le y \le d\}$ (2.1.4) Thus the first ingredient in Probability Theory is the Sample Space of a random experiment.

The next important ingredient in Probability theory is the notion of **Events**. In the random experiment of rolling a die we may be interested in the possibility of an even number turning up. In this case we are interested in the outcome to be in the subset $\{2,4,6\}$ of the sample sapce. In general we may be particularly interested in the outcome being in some special subsets of the sample space. We shall call these as **Elementary Events**. We would like the collection of events we deal with to be set theoretically self contained. What we mean by this is that we would like the collection of events to be such that when we perform the standard set theoretic operations of these events the result is also in this collection of events. We shall now make this idea more specific.

Let \mathcal{B} be the collection of subsets, of the sample sapce Ω , that we are interested in. We would like to have the following properties of \mathcal{B} :

- 1. \mathcal{B} must be a **nonempty collection**. (We have at least some events which are of interest)
- 2. \mathcal{B} is closed under complementation, that is,

$$A \in \mathcal{B} \implies A' \in \mathcal{B}$$
 (2.1.5)

3. \mathcal{B} is closed under union, that is,

$$A, B \in \mathcal{B} \implies A \cup B \in \mathcal{B}$$
 (2.1.6)

From the above it follows that \mathcal{B} is closed under finite union, that is,

$$A_1, A_2, \cdots, A_N \in \mathcal{B} \implies \bigcup_{j=1}^N A_j \in \mathcal{B}$$
 (2.1.7)

4. \mathcal{B} is closed under intersection, that is,

$$A, B \in \mathcal{B} \implies A \cap B \in \mathcal{B}$$
 (2.1.8)

From the above it follows that \mathcal{B} is **closed under finite intersection**, that is,

$$A_1, A_2, \cdots, A_N \in \mathcal{B} \implies \bigcap_{j=1}^N A_j \in \mathcal{B}$$
 (2.1.9)

5. \mathcal{B} is closed under monotonic nondecreasing limits. What we mean by this is the following:

Suppose $\{A_n\}_{n=1,2,\dots}$ is a nondecreasing sequence of sets in \mathcal{B} , that is, $A_n \subseteq A_{n+1}$, for $n=1,2,\dots$ Then we have

$$\lim_{n \to \infty} A_n = \bigcup_{n=1}^{\infty} A_n \tag{2.1.10}$$

We want \mathcal{B} is closed with respect to this limit means that we want

$$\lim_{n \to \infty} A_n = \bigcup_{n=1}^{\infty} A_n \in \mathcal{B}$$
 (2.1.11)

for monotone non decreasing sequence $\{A_n\}_{n=1,2,\cdots}$ of sets in \mathcal{B} .

6. Similarly we want \mathcal{B} is closed under monotonic nonincreasing limits. If $\{A_n\}_{n=1,2,\dots}$ is a nonincreasing sequence of sets in \mathcal{B} , that is, $A_{n+1} \subseteq A_n$, for $n=1,2,\dots$ then we have

$$\lim_{n \to \infty} A_n = \bigcap_{n=1}^{\infty} A_n \tag{2.1.12}$$

We want \mathcal{B} is closed with respect to this limit means that we want

$$\lim_{n \to \infty} A_n = \bigcap_{n=1}^{\infty} A_n \in \mathcal{B}$$
 (2.1.13)

for monotone non increasing sequence $\{A_n\}_{n=1,2,\cdots}$ of sets in \mathcal{B} .

 $A_{n+1} \subseteq A_n$ $\lim_{n \to \infty} A_n = \bigcap_{n=1}^{\infty} A_n$ $\in B$

Using DeMorgan's laws we can easily see that if we have Properties 1,2,3 and 5 above then Properties 4 and 6 follows automatically. Hence basically we require 1,2,3 and 5 to be satisfied by \mathcal{B} . These ideas lead us to the notion of a σ -algebra. Suppose we have a collection \mathcal{B} of subsets of Ω which satisfy Properties 1,2,3 and 5 above, that is

$$\mathcal{B}$$
 is a nonempty collection (2.1.14)

$$A \in \mathcal{B} \Longrightarrow A' \in \mathcal{B} \tag{2.1.15}$$

$$A, B \in \mathcal{B} \Longrightarrow A \cup B \in \mathcal{B} \tag{2.1.16}$$

$$\{A_n\}_{n=1,2,\cdots} \in \mathcal{B}, \text{ and } A_n \subseteq A_{n+1} \text{ for } n=1,2,\cdots \Longrightarrow \bigcup_{n=1}^{\infty} A_n \in \mathcal{B}$$

$$(2.1.17)$$

Consider any sequence $\{B_n\}_{n=1,2,\dots} \in \mathcal{B}$. Now define

$$A_1 = B_1 (2.1.18)$$

$$A_n = \bigcup_{j=1}^n B_j , n = 2, 3, \cdots$$
 (2.1.19)

Then clearly we have

$$A_n = \bigcup_{j=1}^n B_j \in \mathcal{B} \text{ by equation } 2.1.16$$
 (2.1.20)

$$\bigcup_{j=1}^{n} B_j = \bigcup_{j=1}^{n} A_j \text{ for every } n$$
 (2.1.21)

$$\bigcup_{j=1}^{\infty} B_j = \bigcup_{j=1}^{\infty} A_j \tag{2.1.22}$$

Clearly $\{A_n\}_{n=1,2,\cdots}$ is a non decreasing sequence in \mathcal{B} . Hence by equation 2.1.17 we get

$$\bigcup_{n=1}^{\infty} A_n \in \mathcal{B} \tag{2.1.23}$$

 $A_1 = B_1$ $A_2 = B_1 \cup B_2$ $A_n = \bigcup_{\beta=1}^{\infty} B_n$

AneB VBneB Hence by equation 2.1.22 we get

$$\bigcup_{n=1}^{\infty} B_n \in \mathcal{B} \tag{2.1.24}$$

Thus we have

$$B_n \in \mathcal{B} \implies \bigcup_{n=1}^{\infty} B_n \in \mathcal{B}$$
 (2.1.25)

Whenever the above is true we say that \mathcal{B} is closed under countable union. Thus we have

$$2.1.14, 2.1.15, 2.1.16, 2.1.17 \implies (2.1.25), \text{ that is },$$

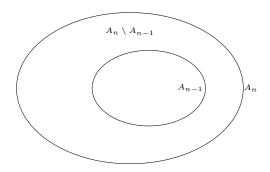
$$\mathcal{B} \text{ is closed under countable union}$$

$$(2.1.26)$$

Conversely suppose we have 2.1.14, 2.1.15, 2.1.25 Then clearly 2.1.16 is satisfied. We shall now see that 2.1.17 is also satisfied. We see this as follows: Let $\{A_n\}_{n=1,2,\dots}$ be a monotone non decreasing sequece of sets in \mathcal{B} . Define

$$B_1 = A_1 (2.1.27)$$

$$B_n = A_n \setminus A_{n-1} \text{ for } n = 2, 3 \cdots$$
 (2.1.28)



Then we have

1.
$$B_n \in \mathcal{B}$$
 for $n = 1, 2, \cdots$

2.
$$\bigcup_{j=1}^{n} B_j = \bigcup_{j=1}^{n} A_j \text{ for } n = 1, 2, 3, \cdots$$

$$3. \bigcup_{j=1}^{\infty} B_j = \bigcup_{j=1}^{\infty} A_j$$

Using 2.1.25 we see that $\bigcup_{j=1}^{\infty} B_j \in \mathcal{B}$ and hence $\bigcup_{j=1}^{\infty} A_j \in \mathcal{B}$. This means that \mathcal{B} is closed under monotone non decreasing limits. Thus we get that

This leads us to the following definition:

Definition 2.1.1 A collection \mathcal{B} , of subsets of a set Ω , is said to be a σ -algebra of subsets of Ω if

- 1. \mathcal{B} is a non empty collection,
- 2. \mathcal{B} is closed under complementation, and
- 3. \mathcal{B} is closed under countable union

From the above definition, and simple set theoretic properties we see that any σ -algebra Σ of subsets of Ω has the following additional properties:

- 1. By (2.1.16) we have Σ is closed under finite union and closed under monotone non decreasing limits
- 2. By DeMorgan's laws we have Σ is closed under
 - (a) finite intersection,
 - (b) countable intersection and
 - (c) monotone non increasing limits
- 3. We must have $\Omega \in \Sigma$ and $\phi \in \Sigma$. This follows from the fact that being a non empty collection there must be a set $A \in \Sigma$. Now by closure under complementation we must have $A^l \in \Sigma$ and hence by closure under union we have $\Omega = A \cup A^l \in \Sigma$. Now by closure under complementation we must have $\phi = \Omega^l \in \Sigma$

Remark 2.1.1 The smallest σ -algebra is the collection containing only the two sets Ω and ϕ , and the largest σ -algebra is the collection of all subsets of Ω , which is called the **Power Set** of Ω and denoted by either $\mathcal{P}(\Omega)$ or 2^{Ω} .

We next introduce the notion of the "Smallest σ -algebra Containing a Collection of Subsets"'

Consider a collection S of subsets of Ω . This collection S may or may not be a σ -algebra. For example, if

$$\Omega = \{1, 2, 3, 4, 5, 6\}$$

then let

$$S = \{A_{12}, A_{34}, A_{56}\} \tag{2.1.30}$$

where

$$A_{12} = \{1, 2\} \tag{2.1.31}$$

$$A_{34} = \{3,4\} \tag{2.1.32}$$

$$A_{56} = \{5, 6\} \tag{2.1.33}$$

Clearly for many reasons this is not a σ -algebra. For instance $\Omega \not\in \mathcal{S}$, or $\phi \not\in \mathcal{S}$. Also it is not closed under complementation or union or intersection. Thus given a collection \mathcal{S} , of subsets of Ω , it may or not be a σ -algebra of subsets of Ω . We want to imbed this in a σ -algebra of subsets of Ω , that is, we want to have a σ -algebra Σ such that $\mathcal{S} \subseteq \Sigma$. Can we do this? Of course we can do this, since we can take Σ to be 2^{Ω} , the power set of Ω . Then clearly $\mathcal{S} \subseteq 2^{\Omega}$. Consider the above example, and let

$$\Sigma = \{\Omega, \phi, A_{12}, A_{34}, A_{56}, A_{1234}, A_{3456}, A_{1256}\}$$
 (2.1.34)

where

$$A_{1234} = \{1, 2, 3, 4\} \tag{2.1.35}$$

$$A_{3456} = \{3, 4, 5, 6\} \tag{2.1.36}$$

$$A_{1256} = \{1, 2, 5, 6\} \tag{2.1.37}$$

Then Σ is a σ -algebra, it contains \mathcal{S} and it is smaller than 2^{Ω} which is also a σ -algebra that contains \mathcal{S} . Thus we may be able to imbed \mathcal{S} in many σ -algebras. What we want to do is to do this optimally. This means we want the smallest σ -algebra that contains \mathcal{S} . This means that we are looking for a σ -algebra Σ such that

- 1. $S \subseteq \Sigma$ and
- 2. If Σ_1 is any σ -algebra that contains \mathcal{S} , that is $\mathcal{S} \subseteq \Sigma_1$, then $\Sigma \subseteq \Sigma_1$

Can we find such an optimal σ -algebra? It can be shown that this is possible and this smallest σ -algebra containing \mathcal{S} is called the σ -algebra generated by σ , and is denoted by σ . In the above example the σ given in 2.1.34 is the smallest σ -algebra generated by the σ in 2.1.30.

Remark 2.1.2 If $\Omega = \mathbb{R}$, the set of all real numbers and if we consider \mathcal{S} to be the set \mathcal{I} of all intervals then the smallest σ -algebra generated by this collection of all intervals is called the **Borel** σ -algebra in \mathbb{R} and is denoted by \mathcal{B} . Any set in \mathcal{B} is called a **Borel Set**. \mathcal{B} is also the σ -algebra generated by the any of the following collection of intervals:

- 1. S = collection of all closed intervals
- 2. S = collection of all open intervals
- 3. S = collection of all left open right closed intervals
- 4. $\mathcal{S} = \text{collection of all right open left closed intervals}$
- 5. $\mathcal{S} = \text{collection } \mathcal{S} \text{ of all intervals of the form } (-\infty, x], \ x \in \mathbb{R}$

To conclude, we want the collection of events to be a σ -algebra of subsets of Ω . Thus we have now two main ingredients for Probability theory, namely the Sample Space and a σ -algebra of events. We next look at the third important ingredient in Probability Theory, namely, the notion of a **Probability Measure**.

2.2 Probability

Let Ω be the sample space of a random experiment and \mathcal{B} the σ -algebra of events. With each event we associate an "index" with certain protocols and call this index as the probability measure. More precisely we have

Definition 2.2.1 A map

 $P:\mathcal{B}\longrightarrow\mathbb{R}$

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(2.2.1)

is called a "**Probability Measure**" on Ω if it satisfies the following properties:

$$P(\phi) = 0 \qquad (2.2.2)$$

$$0 \le P(A) \le 1 \text{ for all } A \in \mathcal{B} \qquad (2.2.3)$$

$$\{A_n\}_n \in \mathbb{N} \text{ disjoint sets in } \mathcal{B} \Rightarrow \qquad (2.2.4)$$

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} P(A_n) \qquad (2.2.4)$$

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = \sum_{n=1}^{\infty} P(A_n) \qquad (2.2.4)$$

 $P(\Omega) = 1$

Remark 2.2.1 The property expressed in equation 2.2.4 is called "Countable Additivity" of the probability measure

We observe the following properties of a probability measure:

1. A Probability measure is "Finitely Additive, that is

$$\begin{cases}
 A_j \}_{j=1}^N & \text{finite number of disjoint sets in } \mathcal{B} \\
 \Longrightarrow \\
 P \left(\bigcup_{j=1}^N A_j \right) = \sum_{j=1}^N P(A_j)
\end{cases}$$
(2.2.5)

This is obtained by applying the countable additivity property 2.2.4 by taking $A_n = \phi$ for n > N and using 2.2.2

2. Suppose $A \in \mathcal{B}$. Since \mathcal{B} is a σ -algebra we have $A' \in \mathcal{B}$. Further these two sets are disjoint and $\Omega = A \cup A'$. Hence using finite additivity property above we get

$$P(A) + P(A') = P(\Omega) = 1$$

and hence

$$P(A') = 1 - P(A)$$
 for every $A \in \mathcal{B}$ (2.2.6)

3. Let $A \subseteq B \in \mathcal{B}$ such that $A \subseteq B$. Then we have

$$B = A \cup (B \setminus A)$$

Thus we have

$$A, B \in \mathcal{B} \text{ and } A \subseteq B \Longrightarrow P(B \setminus A) = P(B) - P(A)$$
 (2.2.7)

4. An immediate consequence of the above is the "Monotonicity" of the probability measure. We have, from above

$$A \subseteq B \implies P(B \setminus A) = P(B) - P(A)$$

 $\implies P(B) = P(A) + P(B \setminus A)$
 $\implies P(B) > P(A) \text{ since } P(B \setminus A) > 0$

Thus we have

$$A, B \in \mathcal{B} \text{ and } A \subseteq B$$

$$\Longrightarrow P(A) \le P(B)$$
(2.2.8)

5. The next property is what is known as "countable subadditivity" of the probability measure. We have seen in 2.2.4 that the probability of a union of a sequence of sets is the sum of the individual probabilities when the sets are disjoint. We shall now see what happens when the sets are not necessarily disjoint. Let $\{A_n\}_{n\in\mathbb{N}}$ be a sequence of sets in \mathcal{B} which may or may not be disjoint. We define a new sequence $\{B_n\}_{n\in\mathbb{N}}$ in \mathcal{B} which are disjoint as follows:

$$B_1 = A_1$$

$$B_n = A_n \setminus \bigcup_{j=1}^{n-1} A_j \text{ for } n \ge 2$$

We see that

(a)
$$\bigcup_{j=1}^{n} B_j = \bigcup_{j=1}^{n} A_j$$

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(b)
$$\bigcup_{j=1}^{\infty} B_j = \bigcup_{j=1}^{\infty} A_j$$

- (c) B_n are disjoint
- (d) $B_n \subseteq A_n$ for all $n \in \mathbb{N}$ and hence by 2.2.8 we get $P(B_n) \leq P(A_n)$ for all $n \in \mathbb{N}$

By property (b) above we have

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = P\left(\bigcup_{n=1}^{\infty} B_n\right)$$

$$= \sum_{n=1}^{\infty} P(B_n)$$
(using countable additivity and the fact that B_n are disjoint)
$$\leq \sum_{n=1}^{\infty} P(A_n)$$
(by property (d) above)

Thus we have

$$\begin{cases}
\{A_n\}_{n\in\mathbb{N}} \in \mathcal{B} \\
\Rightarrow \\
P\left(\bigcup_{n=1}^{\infty} A_n\right) \leq \sum_{n=1}^{\infty} P(A_n)
\end{cases}$$
(2.2.9)

6. The next property we shall look at is a continuity property of the probability measure mown as "Continuity from below" property of the probability measure. Consider a sequence of sets $\{A_n\}_{n\in\mathbb{N}}$ in \mathcal{B} which is nondecreasing, that is, $A_n\subseteq A_{n+1}$ for every $n\in\mathbb{N}$. For such a sequence we have

$$\lim_{n \to \infty} A_n = \bigcup_{n=1}^{\infty} A_n$$

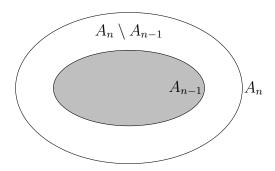
We would like the probability measure reasonably continuous in the sense that for such sequences we must have

$$P(\lim_{n\to\infty} A_n) = \lim_{n\to\infty} P(A_n)$$

We shall now see that this is indeed true. We define a sequence of sets $\{B_n\}_{n\in\mathbb{N}}$ as follows:

$$B_1 = A_1$$

$$B_n = A_n \setminus A_{n-1} \text{ for } n \ge 2$$



It is easy to see that

- (a) B_n are all in \mathcal{B}
- (b) B_n are all disjoint

(c)
$$\bigcup_{j=1}^{n} A_j = \bigcup_{j=1}^{n} B_j$$
 for every $n \in \mathbb{N}$

(d)
$$\bigcup_{n=1}^{\infty} A_j = \bigcup_{j=1}^{\infty} B_j$$

(e)
$$P(B_n) = P(A_n) - P(A_{n-1})$$
 (by equation 2.2.7)

We have

$$P\left(\bigcup_{j=1}^{\infty} A_j\right) = P\left(\bigcup_{j=1}^{\infty} B_j\right) \text{ (by property (d) above)}$$

$$= \sum_{n=1}^{\infty} P(B_n)$$
(by the fact that B_n are disjoint and P is countably additive)
$$= \lim_{n \to \infty} \sum_{j=1}^{n} P(B_j)$$

$$= \lim_{n \to \infty} \{ P(B_1) + P(B_2) + \dots + P(B_n) \}$$

$$= \lim_{n \to \infty} \{ P(A_1) + (P(A_2) - P(A_1)) + \dots + (P(A_n) - P(A_{n-1})) \}$$

$$= \lim_{n \to \infty} P(A_n)$$

Since
$$\bigcup_{n=1}^{\infty} A_n = \lim_{n \to \infty} A_n$$
 we get

$${A_n}_{n\in\mathbb{N}}$$
 nondecreasing sequence of sets in \mathcal{B}

$$\Longrightarrow P\left(\lim_{n\to\infty} A_n\right) = \lim_{n\to\infty} P(A_n) \text{ ,that is}$$

$$P\left(\bigcup_{n=1}^{\infty} A_n\right) = \lim_{n\to\infty} P(A_n)$$

7. The next property we shall look at is the dual of the above property, namely continuity from above, that is for non increasing sequences. Let $\{A_n\}_{n\in\mathbb{N}}$ be a non increasing sequence of sets in \mathcal{B} , that is , $A_{n+1}\subseteq A_n$ for every $n\in\mathbb{N}$. In this case we have

$$\lim_{n \to \infty} A_n = \bigcap_{n=1}^{\infty} A_n$$

We define a new sequence of sets $\{B_n\}_{n\in\mathbb{N}}$ as $B_n = A'_n$. Then $\{B_n\}_{n\in\mathbb{N}}$ is a nondecreasing sequence of sets in \mathcal{B} and hence by the above continuity from below property we get

$$P\left(\bigcup_{n=1}^{\infty} B_{n}\right) = \lim_{n \to \infty} P(B_{n})$$

$$P\left(\bigcup_{n=1}^{\infty} A'_{n}\right) = \lim_{n \to \infty} P(A'_{n})$$

$$P\left(\left\{\bigcap_{n=1}^{\infty} A_{n}\right\}'\right) = \lim_{n \to \infty} P(A'_{n})$$

$$\Longrightarrow$$

$$1 - P\left(\bigcap_{n=1}^{\infty} A_n\right) = 1 - \lim_{n \to \infty} P(A_n)$$

$$P\left(\bigcap_{n=1}^{\infty} A_n\right) = \lim_{n \to \infty} P(A_n)$$

Thus we get

$${A_n}_{n\in\mathbb{N}}$$
 nonincreasing sequence of sets in \mathcal{B}
 \Longrightarrow

$$P\left(\lim_{n\to\infty}A_n\right) = \lim_{n\to\infty}P(A_n) \text{ ,that is}$$

$$P\left(\bigcap_{j=1}^{\infty}A_j\right) = \lim_{n\to\infty}P(A_n)$$

$$(2.2.11)$$

8. Next we shall look at a general sequence of sets in \mathcal{B} . A general sequence of sets may not have a limit. However the limsup and liminf exist. We shall now observe a property through the notion of limsup of a sequence of sets. This property is known as the "Borel-Cantelli" Lemma. Consider a sequence $\{A_n\}_{n\in\mathbb{N}}\in\mathcal{B}$. Recall that we defined

$$\limsup_{n \to \infty} A_n = \bigcap_{n=1}^{\infty} \bigcup_{k=n}^{\infty} A_k$$

Let

$$B_n = \bigcup_{k=n}^{\infty} A_n = \sup_{k \ge n} A_k$$

Then

$$\lim_{n \to \infty} B_n = \limsup_{n \to \infty} A_n$$

The sequence $\{B_n\}_{n\in\mathbb{N}}$ is a non increasing sequence of sets in \mathcal{B} and hence by the property of continuity from above applied to the sequence $\{B_n\}_{n\in\mathbb{N}}$ (2.2.11 applied for B_n) we get

$$\lim_{n \to \infty} P(B_n) = P\left(\lim_{n \to \infty} B_n\right)$$

Substituting for B_n and using the fact that $\lim_{n\to\infty} B_n = \limsup_{n\to\infty} A_n$ we get

$$P(\limsup_{n \to \infty} A_n) = P\left(\lim_{n \to \infty} \bigcup_{k=n}^{\infty} A_k\right)$$

$$= \lim_{n \to \infty} P\left(\bigcup_{k=n}^{\infty} A_k\right)$$

$$\leq \lim_{n \to \infty} \sum_{k=n}^{\infty} A_k \text{ (by countable subadditivity property)}$$

$$= 0 \text{ if } A_n \text{ are such that } \sum_{n=1}^{\infty} P(A_n) < \infty$$

Thus we have

Lemma 2.2.1 Borel-Cantelli Lemma

$$\{A_n\}_{n\in\mathbb{N}}\in\mathcal{B} \text{ and } \sum_{n=1}^{\infty}P(A_n)<\infty \Longrightarrow P(\limsup_{n\to\infty}A_n)=0 \ (2.2.12)$$

Remark 2.2.2 Since $\limsup_{n\to\infty} A_n$ is the set of all those points in Ω which belong to an infinite number of the A_n sets we can write the Borel-Cantelli Lemma as

$${A_n}_{n\in\mathbb{N}} \in \mathcal{B} \text{ and } \sum_{n=1}^{\infty} P(A_n) < \infty$$
 \Rightarrow
 $P(\omega \in \Omega : \omega \in \text{ infinitely many of the } A_n) = 0$

$$(2.2.13)$$

2.3 Random Variables

We shall next introduce the notion of a Random Variable. In most random experiments we are not directly interested in the outcome but certain consequences of the outcome.

Example 2.3.1 Consider the random experiment of rolling a fair die. We have

$$\begin{array}{rcl} \Omega &=& \{1,2,3,4,5,6\}\\ \mathcal{B} &=& \text{The set of all subsets of } \Omega\\ P(j) &=& \frac{1}{6} \text{ for } 1 \leq j \leq 6 \end{array}$$

Suppose the person rolling the die gets a payment of j rupees if an even number j shows up and has to pay a penalty of j rupees if an odd number j shows up. Then we can express this pay off scheme as a function

$$X:\Omega\longrightarrow\mathbb{R}$$

where the values of X are given below:

j	1	2	3	4	5	6
X	-1	2	-3	4	-5	6

We now want to consider such functions on Ω . Let (Ω, \mathcal{B}, P) be a Probability space. Let

$$X:\Omega\longrightarrow\mathbb{R}$$

be a function defined on the sample space Ω . Then for each $\omega \in \Omega$ we have that $X(\omega)$ is a real number. We are interested in looking at the values of ω for which the values of the function $X(\omega)$ lie within a threshold value $x \in \mathbb{R}$, that is we are interested in the set

$$\{\omega \in \Omega: -\infty < X(\omega) \leq x\}$$

For any $x \in \mathbb{R}$ let us denote by I_x the interval $I_x = (-\infty, x]$. Thus we are interested in the set

$$X^{-1}(I_x) = \{\omega \in \Omega : X(\omega) \in I_x\}$$

Note that $X^{-1}(I_x)$ is a subset of Ω for every $x \in \mathbb{R}$. However this subset $X^{-1}(I_x)$ may not be an event, that is, $X^{-}(I_x)$ may not be in \mathcal{B} . If this set $X^{-1}(I_x)$ were in \mathcal{B} then its probability $P(X^{-1}(x))$ is defined and hence we get the probability (or the chances) that the value of the function X lies within the threshold value of x, and we can do this for every $x \in \mathbb{R}$. We shall, therefore consider only such functions and call such a function as a "Real Valued Random Variable" defined on the probability space (Ω, \mathcal{B}, P) . We therefore give the following definition:

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Definition 2.3.1 A function $X : \Omega \longrightarrow \mathbb{R}$ is said to be a Real Valued Random Variable on a probability space (Ω, \mathcal{B}, P) if

$$X^{-1}(I_x) \in \mathcal{B} ext{ for every } x ext{ in } \mathbb{R}$$

Example 2.3.2 Let us again consider the random experiment of rolling a fair die as in Example 2.3.1. In that example we had taken \mathcal{B} to be the power set and hence for every x in \mathbb{R} the set $X^{-1}(I_x)$ is in \mathcal{B} thereby maing every function $X:\Omega \longrightarrow \mathbb{R}$ a Real Valued Random Variable in this case. Let us now consider \mathcal{B} to be the following σ -algebra:

$$\mathcal{B} = \{\phi, \Omega, \{1, 2, 3\}, \{4, 5, 6\}\}$$

Consider the random variable X as in Example 2.3.1. Let x=2 and consider the interval

$$I_2=(-\infty,2]$$

We have

$$X^{-1}(I_2) = \{\omega \in \Omega : X(\omega) = -5 \text{ or } -3 \text{ or } -1 \text{ or } 2\}$$

= $\{5, 3, 1, 2\}$
 $\notin \mathcal{B}$

Note that we have an $x \in \mathbb{R}$ namely x = 2 such that $X^{-1}(I_x) \notin \mathcal{B}$. Hence this X is not a Real Valued Random Variable on the probability space (Ω, \mathcal{B}, P) where \mathcal{B} is as defined as above. Note that the same function on Ω may or may not be a random variable depending on the σ -algebra of events that is under consideration.

Example 2.3.3 Consider the random experiment of rolling a fair die repeatedly until a 6 appears. The 6 may appear in the first roll or it does not appear in the first (n-1) rolls and appears in the nth roll, (for $n=2,3,\cdots$). Thus the sample space Ω can be written down as follows: Let $A = \{1,2,3,4,5\}$ and define

$$S_1 = \{6\}$$

and for $n \geq 2$ define

$$S_n = \{k_1 k_2 \cdots k_{n-1} 6 : k_j \in A\}$$

 S_1 denotes the outcome in which the 6 appears in the first roll itself. For $n \geq 2$ the set S_n denotes the outcomes in which the first time 6 appears is in the *n*th roll. For each $n \geq 1$ the set S_n has 5^{n-1} elements. Then we have

$$\Omega = \bigcup_{n=1}^{\infty} S_n$$

Let us take \mathcal{B} , the σ -algebra of events, to be the power set $\mathcal{P}(\Omega)$. The probability measure is defined by

$$P(\omega) = \frac{1}{6} \text{ for } \omega \in S_1$$

 $P(\omega) = \frac{1}{6^n} \text{ for any } \omega \in S_n$

Since \mathcal{B} is the power set of Ω , every function $X : \Omega \longrightarrow \mathbb{R}$ is a Real Valued Random Variable on this probability space (Ω, \mathcal{B}, P) . Consider the following Real Valued Random Variable:

$$X(\omega) = Number\ of\ Rolls\ in\ \omega$$

For example

$$X(6) = 1$$

 $X(36) = 2$
 $X(56) = 2$
 $X(436) = 3$

We see that for $n \geq 1$,

$$P(S_n) = \frac{5^{n-1}}{6^n}$$

Note that the set of possible values that the random variable X can take is

$$\mathcal{R}_X = \{1, 2, 3, \cdots\}$$

Let us consider $I_3 = (-\infty, 3]$. Then

$$X^{-1}(I_3) = \{\omega \in \Omega : X(\omega) \le 3\}$$

$$= S_1 \cup S_2 \cup S_3$$

$$\Longrightarrow$$

$$P(X^{-1}(I_3)) = P(S_1) + P(S_2) + P(S_3)$$

$$= \frac{1}{6} + \frac{5}{6^2} + \frac{5^2}{6^3}$$

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Note that for any x such that $3 \le x < 4$ we have

$$P(X^{-1}(I_3)) = P(S_1) + P(S_2) + P(S_3)$$

= $\frac{1}{6} + \frac{5}{6^2} + \frac{5^2}{6^3}$

Example 2.3.4 Let us consider the random experiment of rolling a fair die 6 times. Then the sample space can be written as

$$\Omega = \{k_1 k_2 k_3 k_4 k_5 k_6 : k_i \in \{1, 2, 3, 4, 5, 6\}\}$$

There are 36 elements in Ω . Let \mathcal{B} be again the power set of Ω so that every function $X:\Omega\longrightarrow\mathbb{R}$ is a Real Valued Random Variable. Let the probability measure be defined as

$$P(\omega) = \frac{1}{36}$$
 for every $\omega \in \Omega$

Consider the random variable X defined as

$$X(\omega) = Number \ of \ sixes \ in \ \omega$$

For example

$$X(122636) = 2$$

The set of all possible values this random variable can take is

$$\mathcal{R}_X = \{0, 1, 2, 3, 4, 5, 6\}$$

Let x = 3 and consider the interval $I_3 = (-\infty, 3]$. Then

$$X^{-1}(I_3) = \{\omega \in \Omega : \text{there are at most 3 sixes in } \omega\}$$

= $S_0 \cup S_1 \cup S_2 \cup S_3 \text{ where}$
 $S_k = \{\omega \in \Omega : \text{there are exactly } k \text{ sixes in } \omega\}$

Hence

$$P(X^{-1}(I_3)) = P(S_0) + P(S_1) + P(S_2) + P(S_3)$$

$$= \left(\frac{5}{6}\right)^6 + \left(\frac{6}{1}\right)\frac{5^5}{6^6} + \left(\frac{6}{2}\right)\frac{5^4}{6^2} + \left(\frac{6}{3}\right)\frac{5^3}{6^3}$$

$$= \sum_{k=0}^3 \left(\frac{6}{k}\right)\frac{5^{6-k}}{6^6}$$

If we had rolled the die N times instead of 6 times then we have

$$P(X^{-1}(I_3)) = P(S_0) + P(S_1) + P(S_2) + P(S_3)$$

$$= \frac{5^N}{6^N} + {N \choose 1} \frac{5^{N-1}}{6^N} + {N \choose 2} \frac{5^{N-2}}{6^N} + {N \choose 3} \frac{5^{N-3}}{6^N}$$

$$= \sum_{k=0}^3 {N \choose k} \frac{5^{N-k}}{6^N}$$

Remark 2.3.1 Suppose now X is a Real Valued Random Variable on the probability space (Ω, \mathcal{B}, P) . Let us consider the following collection of subsets of \mathbb{R} :

$$\mathcal{C} = \{ A \subseteq \mathbb{R} : X^{-1}(A) \in \mathcal{B} \}$$

We observe the following:

- 1. Clearly \mathcal{C} is a nonempty collection because all sets of the form $A = I_x$, for any $x \in \mathbb{R}$, are in \mathcal{C} since X is a Real Valued Random Variable.
- 2. We have

$$A \in \mathcal{C} \implies X^{-1}(A) \in \mathcal{B}$$

 $\implies (X^{-1}(A))' \in \mathcal{B} \text{ (since } \mathcal{B} \text{ is a } \sigma\text{-algebra)}$
 $\implies X^{-1}(A') \in \mathcal{B} \text{ (since } X^{-1}(A') = (X^{-1}(A))')$
 $\implies A' \in \mathcal{B}$

Thus \mathcal{C} is closed under complementation

3. Further

$$\{A_n\}_{\mathbb{N}} \in \mathcal{C} \implies X^{-1}(A_n) \in \mathcal{B}$$

 $\implies \bigcup_{n=1}^{\infty} X^{-1}(A_n) \in \mathcal{B} \text{ (since } \mathcal{B} \text{ is a } \sigma\text{-algebra)}$
 $\implies X^{-1}\left(\bigcup_{n=1}^{\infty} A_n\right) \in \mathcal{B}$
 $\implies \bigcup_{n=1}^{\infty} A_n \in \mathcal{C}$

Thus \mathcal{C} is closed under countable union

From the above three properties we see that \mathcal{C} is a σ -algebra of subsets of \mathbb{R} . Further all intervals of the form $I_x = (-\infty, x]$ are in \mathcal{C} . Thus \mathcal{C} is a σ -algebra that contains all intervals of this form. But the Borel σ -algebra $\mathcal{B}_{\mathbb{R}}$ is the smallest σ -algebra that contains all these intervals. Hence $\mathcal{B}_{\mathbb{R}} \subseteq \mathcal{C}$. Thus we have

$$X$$
 is a Real Valued Random Variable
on the probability space (Ω, \mathcal{B}, P)
 \Longrightarrow
 $X^{-1}(A) \in \mathcal{B}$ for every Borel set in \mathbb{R} $(2.3.1)$

In particular since every interval is a Borel set we see that

$$X$$
 is a Real Valued Random Variable on the probability space (Ω, \mathcal{B}, P) \Longrightarrow $X^{-1}(\mathcal{I}) \in \mathcal{B}$ for every interval \mathcal{I} in \mathbb{R} $(2.3.2)$

We shall next see some examples of random variables. We shall consider two types of random variables, namely

- Discrete Random Variables
- Continuous Random Variables

2.4 Discrete Random variables

We shall first consider Discrete random variables. We introduce two types of discrete random variables

1. Random Variables which take a finite number of real values, that is, the Range \mathcal{R}_X of X is a finite set in \mathbb{R} ,

$$\mathcal{R}_X = \{x_1, x_2, x_3, \cdots, x_N\}$$

where we arrange the values as

$$x_1 < x_2 < x_3 < \dots < x_N$$

2. Random variables which take an infinite sequence of values, that is, the Range \mathcal{R}_X of X is a sequence,

$$\mathcal{R}_X = \{x_1, x_2, x_3, \cdots, x_n, \cdots\}$$

where we arrange the values as

$$x_1 < x_2 < x_3 < \dots < x_n < x_{N+1} < \dots$$

Random Variables Taking A Finite Number Of Values

We shall first consider those random variables which take a finite number of values. Let

$$\mathcal{R}_X = \{x_1, x_2, \cdots, x_N : x_j \in \mathbb{R} \text{ for } 1 \le j \le N\}$$

where

$$x_1 < x_2 < \cdots < x_N$$

Since there are only finite number of values for X we are basically interested in the values $P(\omega \in \Omega : X(\omega) = k)$ for $k = 1, 2, \dots, N$. (From now on we shall write $P(\omega \in \Omega : X(\omega) = k)$ as P(X = k) and $P(\omega \in \Omega : X(\omega) \le x)$ as $P(X \le x)$). We shall denote P(X = k) as p_k . Then we have a function

$$p_X: \mathcal{R}_X \longrightarrow \mathbb{R}$$

defined as

$$p_X(k) = p_k = P(X = k)$$

This function is called the "**Probability Mass Function**" (or pmf in short) of the random variable X. Once we know the pmf we have

$$P(X \in A) = \sum_{\{k: x_k \in A\}} p_k$$
 for any Borel set A in \mathbb{R}

Thus the pmf is the basic function that gives us the distribution of the values of the random variable X. We shall now see some typical examples:

Example 2.4.1 The simplest example is the random variable which takes only one value - say C. Then we have

$$\mathcal{R}_X = \{C\}$$

and the pmf is given by

$$p_X(X=C)=1$$
 and

For any $x \neq C$ we have P(X = x) = 0 and for any Borel set A in \mathbb{R} we have

$$P(X \in A) = \begin{cases} 1 & \text{if } C \in A \\ 0 & \text{if } C \notin A \end{cases}$$

Such random variables are called constant random variables

Example 2.4.2 The next example is that of a random variable that takes exactly two values - which are referred to as Success or Failure. We shall denote success as 1 and Failure as 0. Then we have

$$\mathcal{R}_X = \{1, 0\}$$

Then the pmf is known the moment P(X=1)=p is known, (referred to as the probability of "success"). Then we have P(X=0)=1-p=q,say - (the probability of "failure"). For any Borel set A in \mathbb{R} we have

$$P(A) = \begin{cases} 1 & \text{if } 0 \text{ and } 1 \in A \\ p & \text{if } 1 \in A \text{ and } 0 \not\in A \\ q = 1 - p & \text{if } 0 \in A \text{ and } 1 \not\in A \\ 0 & \text{if } 1 \text{ and } 0 \not\in A \end{cases}$$

Such a random variable is called a "Bernoulli Random Variable" with success probability p. We write such a random variable a as Ber(p) random variable.

As an illustration we shall consider the following two Bernoulli random variables:

1. Consider tossing a coin with probability of getting a Head as p (where 0). Define

$$X:\Omega\longrightarrow\mathbb{R}$$

as

$$X(H) = 1$$
 and $X(T) = 0$

Then X is a Bernoulli Random Variable with success probability p. This is a Ber(p) random variable. For a fair coin we get a Ber(0.5) random variable.

2. Consider the experiment of rolling a fair die. Let us consider getting 6 as a success and getting anything other than 6 a Failure. Then the random variable X becomes

$$X(\omega) = \begin{cases} 1 & \text{if } \omega = 6 \\ 0 & \text{if } \omega \neq 6 \end{cases}$$

We have

$$P(X = 1) = \frac{1}{6}$$
 and $P(X = 0) = \frac{5}{6}$

This is a $Ber(\frac{1}{6})$ random variable.

Example 2.4.3 Let us now consider a random variable which take finite number of values. Without loss of generality let these values be $0, 1, 2, \dots, N$. As an illustration let us consider the experiment of tossing a coin (with probability p for success) N times. Let us assume that

- 1. the probability of getting a Head in each toss is p and
- 2. the outcome in any toss is independent of the outcomes in the other tosses

Thus for instance N=5 and an outcome is HTTHT then $P(HTTHT)=p^2(1-p)^3$. In general

$$P(\omega) = p^k (1-p)^{N-k}$$
 where $k = \text{Number of Heads in } \omega$

Let us define a random variable X as follows:

$$X(\omega)$$
 = number of successes in ω

Then X can take values $0, 1, 2, \dots, N$, that is,

$$\mathcal{R}_X = \{0, 1, 2, 3, \cdots, N\}$$

Then we have

$$P(X = k) = \binom{N}{k} p^{k} (1-p)^{N-k}$$

If the coin is fair this becomes

$$P(X=k) = \binom{N}{k} \frac{1}{2^N}$$
 since $p = \frac{1}{2}$ for a fair coin

In the case of rolling a fair die where getting a six is treated as success we have $p = \frac{1}{6}$ and hence we get

$$P(X = k) = \binom{N}{k} \frac{1}{6^k} \times \frac{5^{N-k}}{6^{N-k}} = \binom{N}{k} \frac{5^{N-k}}{6^N}$$

Such Random Variables are said to have the "Binomial Distribution" (and are also called Bernoulli Trials). Thus we have

$$\mathcal{R}_X = \{0, 1, 2, \cdots, N\}$$

$$P(X = k) = \begin{pmatrix} N \\ k \end{pmatrix} p^k (1-p)^{N-k}$$

Such random variables are referred to as B(N, p) random variables

Example 2.4.4 Consider a random variable X for which again

$$\mathcal{R}_X = \{x_1, x_2, \cdots, x_N\} \tag{2.4.1}$$

where $x_1 < x_2 < \cdots < x_N$ are real numbers. (We can for example take $x_1 = 1, x_2 = 2, \cdots, x_N = N$). Suppose the random variable is such that the lower values are attained with higher probability and higher values are attained with less probability. In particular, for example, suppose $P(X = x_k)$ is proportional to $\frac{1}{k}$, that is

$$p_k = P(X = k) \propto \frac{1}{k} \tag{2.4.2}$$

Let C be the constant of proportionality. Then we have

$$p_k = P(X = k) = C \times \frac{1}{k} \tag{2.4.3}$$

Since the total probability must be one we get

$$\sum_{k=1}^{N} \left(C \times \frac{1}{k} \right) = 1$$

which gives us

$$C = \frac{1}{s_N}$$

where

$$s_N = \sum_{k=1}^{N} \frac{1}{k} = 1 = \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{N}$$

Thus we have

$$p_k = P(X = k) = \frac{1}{s_N} \frac{1}{k}$$
 (2.4.4)

Such a RV is called a **Zipf Random Variable**. Thus for a Zipf Random Variable X we have

$$\mathcal{R}_{X} = \{x_{1}, \dots, x_{N}\}\$$
 $p_{k} = P(X = x_{k}) = \frac{1}{s_{N}} \frac{1}{k} \text{ (for } k = 0, 1, 2 \dots, N)$

where

$$s_N = 1 + \frac{1}{2} + \frac{1}{3} + \dots + \frac{1}{N}$$

Remark 2.4.1 We can reverse the situation above and get a random variable which takes higher values with higher probabilities. Let us define

$$\mathcal{R}_X = \{x_1, x_2, \cdots, x_N\} \tag{2.4.5}$$

where as before, $x_1 < x_2 < \cdots < x_N$. We define

$$P(X = x_k) = \frac{1}{s_N} \frac{1}{N+1-k}$$
 (2.4.6)

so that we get

$$P(X = x_1) = \frac{1}{s_N} \frac{1}{N},$$

$$P(X = x_2) = \frac{1}{s_N} \frac{1}{N-1}, \dots,$$

$$P(X = x_{N-1}) = \frac{1}{s_N} \frac{1}{2}, \text{ and}$$

$$P(X = x_N) = \frac{1}{s_N} \frac{1}{1}$$

We can generalize this further as follows:

Let a_1, a_2, \dots, a_N be a sequence of positive real numbers, such that

$$a_1 < a_2 < \dots < a_{\scriptscriptstyle N} \tag{2.4.7}$$

Let

$$C = \sum_{k=1}^{N} a_k \tag{2.4.8}$$

Then for a random variable X for which

$$\mathcal{R}_X = \{x_1, x_2, \cdots, x_N\} \tag{2.4.9}$$

where $x_1 < x_2 < \cdots < x_N$ we can define

$$p_k = P(X = x_k) = \frac{a_k}{C}$$
 (2.4.10)

Thus we get the probability that X attains lower values is higher than that of attaining higher values. We can again reverse the situation and define

$$p_k = P(X = x_k) = \frac{a_{(N+1-k)}}{C}$$
 (2.4.11)

Now the higher values are attained with higher probabilities.

Discrete Random Variables Taking An Infinite Sequence Of Values

We shall next look at some discrete random variables which take an infinite sequence of values. In such cases we have

$$\mathcal{R}_X = \{x_1, x_2, \cdots, x_n, \cdots, \}$$

where

$$x_1 < x_2 < x_3, \dots < x_{n-1} < x_n < \dots$$

Such random variables are typically used where we repeat an experiment until we get a "success" and count the number of "failures" before getting a success, the random veritable being the number of failures before the first success. We shall describe this first with an example

Example 2.4.5 Consider the experiment of rolling a fair die until we get a six. Getting a six is treated as a success while that of getting any other number is treated as a failure. (We assume that in each roll each number is equally likely to show up independent of the other rolls). We can describe the sample space of this experiment as follows:

Let S_n denote the event that the success occurs in the nth roll. Let

$$A = \{1, 2, 3, 4, 5\}$$

Then

$$S_1 = \{6\}$$

 $S_2 = \{a_16 : a_1 \in A\}$

and in general for $n \geq 2$ we have

$$S_n = \{a_1 a_2 \cdots a_{(n-1)} 6 : a_j \in A\}$$

We have the sample space

$$\Omega = \bigcup_{n=1}^{\infty} S_n$$

$$P(S_1) = \frac{1}{6}$$

$$P(S_2) = \frac{5}{6} \times \frac{1}{6} = \frac{5}{6^2}$$

and, in general, for $n \ge 1$ we have

$$P(S_n) = \frac{5^{(n-1)}}{6^n}$$

Let us define the random variable $X:\Omega\longrightarrow\mathbb{R}$ as

$$X(\omega) = \# \text{ of rolls in } \omega$$

For example,

$$X(\omega) = n \text{ for every } \omega \in S_n$$

We have

$$P(X = n) = P(S_n) = \frac{5^{(n-1)}}{6^n}$$

In general we can take the probability of success as p and that of failure as (1-p) then we get above

$$P(X = n) = p(1-p)^{(n-1)}$$

Such a random variable is called a "Geometric Random Variable" and we denote this by Geo(p). We write $X \sim Geo(p)$.

In general we take

$$\mathcal{R}_X = \{x_0, x_1, x_2, \cdots, x_n, \cdots\}$$

where

$$x_0 < x_1 < x_2 < x_3 < \dots < x_{(n-1)} < x_n < \dots$$

We then choose a sequence of positive real numbers $p_0, p_1, p_2, \dots, p_n, \dots$ such that

$$0 < p_n < 1 \text{ for } n = 0, 1, 2, \cdots$$
$$\sum_{n=0}^{\infty} p_n = C < \infty$$

We then define

$$P(X = x_n) = \frac{p_n}{C} \text{ for } n = 0, 1, 2, \cdots$$

We next look at an example of this type of random variable by choosing suitable p_j .

Example 2.4.6 Without loss of generality we assume

$$\mathcal{R}_X = \{0, 1, 2, 3, \cdots\}$$

Let λ be a fixed positive real number. Consider the infinite series

$$\sum_{n=0}^{\infty} \frac{\lambda^n}{n!} = e^{\lambda}$$

 $(C = e^{\lambda} \text{ in this case})$ Then we can choose

$$P(X=n) = p_n = \frac{\lambda^n}{n!} e^{-\lambda}$$
 for $n = 0, 1, 2, \cdots$

Such a random variable is called "Exponential random Variable" and is denoted by $Exp(\lambda)$. We write $X \sim Exp(\lambda)$

2.5 Continuous Random Variables

We shall next consider Random Variables which take a continuum of real values. We shall consider the following three types of continuous random variables:

1. Random Variables for which the Range is a finite interval, that is,

$$\mathcal{R}_{_{X}} = [a, b] \text{ where } -\infty < a \le x < b < \infty$$

These are called **Bounded random Variables**

2. Random Variables for which the Range is a semi infinite interval, that is,

$$\mathcal{R}_{x} = [0, \infty)$$

These are called **Random Variables Bounded Below**. (Without loss of generality we have taken the lower bound to be 0)

3. Random Variables for which the Range is the full infinite interval, that is,

$$\mathcal{R}_{x} = (-\infty, \infty)$$

These are called **Unbounded Random Variables**

We shall look at some standard models of each of these types. Before we introduce these random variables we make the following observations: In the case of discrete random variables the basic pieces of information we provide are

- 1. The Range of the Random Variable, \mathcal{R}_X (which is a discrete set) and
- 2. The probability $p_k = P(X = x_k)$ for every $x_k \in \mathcal{R}_X$

We can then define a function

$$p_X: \mathcal{R}_X \longrightarrow \mathbb{R}$$

as

$$p_X(x_k) = p_k = P(X = x_k)$$

This function is called the "**Probability Mass Function**" (in short we write pmf) of the random variable X. Thus the pmf is the basic piece of information we need to prescribe a discrete random variable.

However this gets a little involved in the case of random variables which take a continuum of values. We shall briefly describe the process involved in describing a random variable, in general. We shall now see that the random variable X and the probability measure on the probability space (Ω, \mathcal{B}, P) together induce a probability measure P_X on the Borel sets in \mathbb{R} as follows: Consider a random variable X on a probability space (Ω, \mathcal{B}, P) . Now we look at \mathbb{R} as a sample space of a random experiment with the Borel sets as the events, that is now we look at $\Omega_1 = \mathbb{R}$ and $\mathcal{B}_1 = \mathcal{B}_{\mathbb{R}}$. For any Borel set $B \in \mathcal{B}_{\mathbb{R}}$ we have $X^{-1}(B) \in \mathcal{B}$ and hence we can define $P(X^{-1}(B))$. We denote this by $P_X(B)$. Thus we have a function

$$P_X: \mathcal{B}_{\mathbb{R}} \longrightarrow \mathbb{R} \tag{2.5.1}$$

We observe the following properties of the function P_X :

1. We have

$$P_X(B) = P(X^{-1}(B))$$

Since the right hand side is a probability we get

$$0 \le P_X(B) \le 1 \text{ for every } B \in \mathcal{B}_{\mathbb{R}}$$
 (2.5.2)

2. Since $X^{-1}(\mathbb{R}) = \Omega$ and $X^{-1}(\phi) = \phi$ we get

$$P_X(\mathbb{R}) = P(\Omega) = 1 \tag{2.5.3}$$

$$P_X(\phi) = P(\phi) = 0$$
 (2.5.4)

3. If B_n , $n = 1, 2, 3, \cdots$ is a sequence of mutually disjoint Borel sets in \mathbb{R} then

$$X^{-1}\left(\bigcup_{n=1}^{\infty} B_n\right) = \bigcup_{n=1}^{\infty} X^{-1}(B_n)$$

Since $E_n = X^{-1}(B_n) \in \mathcal{B}$ for $n = 1, 2, 3, \dots$, and they are disjoint we get by the countable additivity property of the probability measure P,

$$P\left(\bigcup_{n=1}^{\infty} X^{-1}(B_n)\right) = \sum_{n=1}^{\infty} P\left(X^{-1}(B_n)\right)$$

$$P_X\left(\bigcup_{n=1}^{\infty} B_n\right) = \sum_{n=1}^{\infty} P_X(B_n)$$

Hence we get that

P_X is countably additive additive

The above properties show that P_X is a probability measure on the Borel sets of \mathbb{R} . We call this the probability measure P_X on the Borel σ -algebra $\mathcal{B}_{\mathbb{R}}$ in \mathbb{R} , as the measure induced by P and X. We shall now see that this induced probability measure P_X can be analysed using a real valued function called the CDF (Cumulative Distribution Function) of the random variable X. Let X be a random variable and x be any real number. Then consider the interval,

$$I_x = (-\infty, x] \tag{2.5.5}$$

Then since I_x is a Borel set,

$$X^{-1}(I_x) \in \mathcal{B} \tag{2.5.6}$$

This means

$$\{\omega: X(\omega) \in I_x\} \in \mathcal{B} \tag{2.5.7}$$

which gives

$$\{\omega: X(\omega) \le x\} \in \mathcal{B} \quad \forall x \in \mathbb{R}$$
 (2.5.8)

Hence we can define

$$P_X(I_x) = P(-\infty < X(\omega) \le x) \text{ for every } x \in \mathbb{R}$$
 (2.5.9)

Thus we have a function

$$F_X: \mathbb{R} \longrightarrow \mathbb{R}$$

defined as

$$F_X(x) = P(X \le x) \tag{2.5.10}$$

This function is called the "Cumulative Distribution Function" (in short we write cdf) of the random variable X. It is through this function we

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describe a random variable which takes a continuum of values. We shall first look at the properties of this function so that we understand what sort of functions can be cdf of random variables.

Let us first look at discrete random variables and their cdf. (We have already seen what is meant by the pmf for such random variables). .

Example 2.5.1 Consider a random variable $X(\omega)$ which takes only one value say c on the probability space (Ω, \mathcal{E}, P) .

Then we have

$$F_X(x) = P\{\omega : X(\omega) \le x\}$$

is given by

$$F_X(x) = 0$$
 if $x < c$
= 1 if $c \le x < \infty$

Thus $F_X(x)$ is a step function, with a jump of one unit at the point c, as shown below:

c

Suppose now $X(\omega)$ takes two values c_1 and c_2 such that

$$P\{\omega : X(\omega) = c_1\} = p$$

$$P\{\omega : X(\omega) = c_2\} = q$$

where

$$p + q = 1$$
, $0 < p, q < 1$.

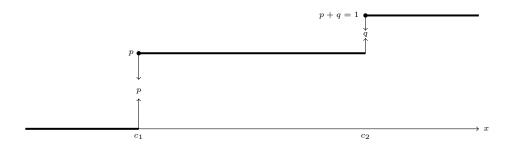
w.l.g. we assume $c_1 < c_2$. Then we have

$$F_X(x) = 0 \quad \text{if } -\infty < x < c_1$$

$$= p \quad \text{if } c_1 \le x < c_2$$

$$= p + q = 1 \quad \text{if } c_2 \le x < \infty$$

 $F_X(x)$ is again a step function with two steps, a jump of p at the point c_1 and a further jump of q at the point c_2 , as shown below:



In general if $X(\omega)$ takes k values $c_1 < c_2 < \cdots < c_k$ such that

$$P\{\omega : X(\omega) \le c_j\} = p_j$$

where

$$0 < p_j < 1, \sum_{j=1}^{k} p_j = 1$$

then

$$F_X(x) = \begin{cases} 0 & \text{if } -\infty < x < c_1 \\ p_1 & \text{if } c_1 \le x < c_2 \\ p_1 + p_2 & \text{if } c_2 \le x < c_3 \\ \cdots & \cdots \\ p_1 + p_2 + \cdots + p_j & \text{if } c_j \le x < c_{j+1} \\ \cdots & \cdots \\ 1 & \text{if } c_k \le x < \infty \end{cases}$$

The graph of $F_X(x)$ will be a piecewise constant graph having jumps p_j at c_j , for $j = 1, 2, \dots, k$.

This is typical of discrete random variables.

Properties of CDF:

We shall now look at some fundamental properties of the cumulative distribution function $F_X(x)$ of a random variable X.

- 1. $0 \le F_X(x) \le 1$; $\forall x \in \mathbb{R}$ This is because $F_X(x)$ is the probability of the event $\{\omega : X(\omega) \le x\}$
- 2. $x_1 < x_2 \Longrightarrow F_X(x_1) \le F_X(x_2)$, that is, $F_X(x)$ is a nondecreasing function.

This follows from the fact

$$\{\omega: X(\omega) \le x_1\} \subseteq \{\omega: X(\omega) \le x_2\}$$

3.
$$\lim_{x \to \infty} F_X(x) = 1$$
.

This follows from the fact for any increasing sequence of real numbers (with $x_n \to \infty$), we have the sequence of sets $E_n = (X \le x_n)$ is nondecreasing and hence

$$\lim_{n \to \infty} E_n = \bigcup_{n=1}^{\infty} E_n = \{ \omega \in \Omega : X(\omega) < \infty \} = \Omega$$

Hence by the continuity property of the probability we get

$$P(\lim_{n \to \infty} E_n) = \lim_{n \to \infty} \mathcal{P}(E_n)$$

$$\Longrightarrow$$

$$P(\Omega) = \lim_{n \to \infty} F_X(x_n)$$

$$\Longrightarrow$$

$$1 = \lim_{x \to \infty} F_X(x)$$

- 4. Similarly we can show that $\lim_{x \to -\infty} F_X(x) = 0$
- 5. $F_X(x)$ is right continuous at every $x \in \mathbb{R}$; i.e.,

$$\lim_{h \longrightarrow 0+} F_X(x+h) = F_X(x)$$

This follows from the continuity from above property of the probability measure. We have

$$E_n = \left\{ X(\omega) \le x + \frac{1}{n} \right\}$$

is a sequence of events decreasing to the event

$$E = \{X(\omega) \le x\}$$

Hence by the property of continuity from above of the probability function we get

$$\mathcal{P}(E) = \lim_{n \to \infty} \mathcal{P}(E_n)$$

$$\mathcal{P}(\{X(\omega) \le x\}) = \mathcal{P}(\left\{X(\omega) \le x + \frac{1}{n}\right\})$$

$$\Longrightarrow$$

$$F_X(x) = \lim_{n \to \infty} F_X(x + \frac{1}{n})$$

$$\Longrightarrow$$

$$F_X(x) = F_X(x + 1)$$

Thus $F_X(x)$ is right continuous at every point $x \in \mathbb{R}$.

If a function F(x) has to be the cumulative distribution function of a random variable, it must satisfy the above five properties.

We can, using the properties of the probability measure, easily find the probabilities of the sets $\{X(\omega) \in I\}$ where I is any interval. We observe the following:

1. Since the interval (x, ∞) is the complement of the interval $(-\infty, x]$ we get

$$\mathcal{P}(\{X(\omega) \in (x, \infty\}) = \mathcal{P}(\{X(\omega) \in (-\infty, x]\}')$$

$$= 1 - \mathcal{P}(\{X(\omega) \in (-\infty, x]\})$$

$$= 1 - F_X(x)$$

Thus

$$\mathcal{P}(\{X(\omega) \in (x,\infty)\}) = 1 - F_X(x)$$
 (2.5.11)

2. Next we observe that, if a < b then,

$$(a,b] = (-\infty,b] \setminus (-\infty,a]$$

$$\Longrightarrow$$

$$\mathcal{P}(\{X(\omega) \in (a,b]\}) = \mathcal{P}(\{X(\omega) \in (-\infty,b]\}) - \mathcal{P}(\{X(\omega) \in (-\infty,a]\})$$

$$\Longrightarrow$$

$$\mathcal{P}(\{X(\omega) \in (a,b]\}) = F_X(b) - F_X(a)$$

Thus we have

$$\mathcal{P}(\{X(\omega) \in (a,b]\}) = F_X(b) - F_X(a)$$
 (2.5.12)

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3. The sequence intervals

$$I_n = (-\infty, x - \frac{1}{n}]$$

increase to the interval

$$I = (-\infty, x)$$

Hence by the continuity from below property of probability we have

$$\mathcal{P}(\{X(\omega) \in (-\infty, x)\}) = \lim_{n \to \infty} \mathcal{P}(\left\{X(\omega) \in (-\infty, x - \frac{1}{n}]\right\})$$

$$\Longrightarrow$$

$$\mathcal{P}(\{X(\omega) \in (-\infty, x)\}) = \lim_{n \to \infty} F_X(x - \frac{1}{n})$$

$$= F_X(x -), \text{ (the left hand limit of } F_X(x) \text{ at the point } x)$$

Thus we have

$$\mathcal{P}(\{X(\omega) \in (-\infty, x)\}) = F_X(x-) \tag{2.5.13}$$

4. Analogously, if $a \leq b$ we can show that

$$\mathcal{P}(\{X(\omega) \in (a,b)\}) = F_X(b-) - F_X(a)$$
 (2.5.14)

$$\mathcal{P}(\{X(\omega) \in [a,b)\}) = F_X(b-) - F_X(a-)$$
 (2.5.15)

$$\mathcal{P}(\{X(\omega) \in [a,b]\}) = F_X(b) - F_X(a-)$$
 (2.5.16)

5. We can write

$${X = x} = {X \in (a, x]} \setminus {X \in (a, x)} \text{ for any } a < x$$

Hence we get

$$\mathcal{P}(\{X = x\}) = \mathcal{P}(\{X \in (a, x]\}) - \mathcal{P}(\{X \in (a, x)\})$$
$$= [F_X(x) - F_X(a)] - [F_X(x-) - F_X(a)]$$
$$= F_X(x) - F_X(x-)$$

Thus we have

$$\mathcal{P}(\{X = x\}) = F_X(x) - F_X(x-) \tag{2.5.17}$$

A random variable is said to be **continuous** if $F_X(x)$ is continuous at all x, that is, if $F_X(x)$ is also left continuous, (since we know that it is already right continuous). For continuous random variables we have $F_X(x-) = F_X(x+) = F_X(x)$ for all $x \in \mathbb{R}$. Hence we have by 2.5.17

$$\mathcal{P}(\{X=x\}) = 0$$
 for any continuous random variable X (2.5.18)

From this it follows that for a continuous random variable, for any finite interval I whose left and right end points are a and b respectively,

$$\mathcal{P}(\{X \in I\}) = F_X(b) - F_X(a) \tag{2.5.19}$$

irrespective of whether the end points are in I or not.

Probability Density Function (PDF):

Consider a continuous random variable X with CDF given by $F_X(x)$. Since $F_X(x)$ is a continuous nondecreasing function, its derivative exists except possibly at a sequence of points in \mathbb{R} , (the sequence can be arranged in an increaseing order). Let $f_X(x)$ be the function derived as follows:

$$f_X(x) = \begin{cases} \frac{d}{dx} F_X(x) \text{ whenever the derivative exists at } x \text{ and,} \\ \text{any arbitrary nonnegative real value at other points} \end{cases}$$
(2.5.20)

This function $f_X(x)$ is called the "**Probability Density Function**" of the random variable X. Since the function $F_X(x)$ is nondecreasing, its derivative is nonnegative, whenever it exists. Hence we have

$$f_X(x) \ge 0 \text{ for all } x \in \mathbb{R}$$
 (2.5.21)

Moreover, we have

$$F_X(x) = \int_{-\infty}^x f_X(s)ds \qquad (2.5.22)$$

Since $F_X(-\infty, \infty) = 1$ we have

$$\int_{-\infty}^{\infty} f_X(x)dx = 1 (2.5.23)$$

For any finite interval I whose left and right end points are a and b respectively, we have

$$\mathcal{P}(\{X \in I\}) = \int_a^b f_X(x)dx \qquad (2.5.24)$$

irrespective of whether the end points are in I or not.

Remark 2.5.1 For a discrete random variable, the pdf will involve the delta function. If the discrete random variable X takes the values $x_1 < x_2 < x_3 < \cdots < x_j < \cdots$ with probabilities $p_1, p_2, \cdots p_j, \cdots$ then we have to define

$$f_X(x) = \sum_{j} p_j \delta(x - x_j) \tag{2.5.25}$$

We shall next see some examples of continuous random variables

2.6 Examples Of Continuous Random Variables

We shall consider the following three types of random variables:

1. Random Variables for which the Range is a finite interval, that is,

$$\mathcal{R}_{x} = [a, b] \text{ where } -\infty < a \le x \le b < \infty$$

These are called **Bounded random Variables**

2. Random Variables for which the Range is a semi infinite interval, that is,

$$\mathcal{R}_{x} = [0, \infty)$$

These are called **Random Variables Bounded Below**. (Without loss of generality we have taken the lower bound to be 0)

3. Random Variables for which the Range is the full infinite interval, that is,

$$\mathcal{R}_{X} = (-\infty, \infty)$$

These are called Unbounded Random Variables

We shall look at some standard models of each of these types.

Bounded Random Variables

Let

$$\mathcal{R}_{x} = [a, b] \text{ where } -\infty < a \le x \le b < \infty$$
 (2.6.1)

For such a random variable clearly we have

$$P(X \le x) = 0 \text{ if } x \le a$$

since all the values of X are $\geq a$. Hence we must have

$$F_{x}(x) = P(X \le x) = 0 \text{ if } x \le a$$
 (2.6.2)

Further we must have

$$P(X \le x) = 1 \text{ if } x > b$$

since all the values of X are $\leq b$. Hence we must have

$$F_{X}(x) = P(X \ge x) = 1 \text{ if } x > b$$
 (2.6.3)

Thus different such random variables are obtained depending on how $F_X(x)$ increases from 0 at x = a to to 1 at x = b. We do this as follows:

Let g(x) be a nondecreasing, nonnegative, continuous real valued function defined over the interval [a, b]. If we define h(x) = g(x) - g(a) then h(x) is a nondecreasing, nonnegative, continuous real valued function defined over the interval [a, b] such that h(a) = g(a) - g(a) = 0. If we now define

$$\varphi(x) = \frac{h(x)}{h(b)} = \frac{g(x) - g(a)}{g(b) - g(a)}$$

then we get $\varphi(x)$ is a nondecreasing, nonnegative, continuous real valued function defined over the interval [a,b] such that $\varphi(a)=0$ and $\varphi(b)=1$. Hence we can define a random variable X by the cdf

$$F_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{g(x) - g(a)}{g(b) - g(a)} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$

For such random variables, we get by differentiating the cdf, the corresponding pdf as

$$f_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{g'(x)}{g(b) - g(a)} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$

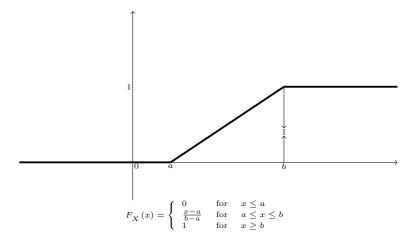
By varying a, b and g we get different Bounded Random Variables. The simplest model is obtained by making $F_x(x)$ vary linearly from 0 at x = a to 1 at x = b, that is, by taking g(x) = x. Thus $F_x(x)$ is be given by

$$F_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{x-a}{b-a} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$
 (2.6.4)

The corresponding pdf is obtained as the derivative of the cdf as,

$$f_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{1}{b-a} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$
 (2.6.5)

Such a Random Variable is said to be **Uniformly Distributed** over the interval [a, b]. We call such Random Variables as **Uniform Random Variables** and write $X \sim Uni[a, b]$. The graph of the CDF is as shown below:



If we choose $g(x) = x^2$ then $F_X(x)$ varies quadratically over [a, b] from the value 0 at x = a to the value 1 at x = b and we have a Random Variable X with cdf $F_X(x)$ given by

$$F_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{(x-a)^2}{(b-a)^2} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$
 (2.6.6)

By differentiating the cdf we get the corresponding pdf as

$$f_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{2(x-a)}{(b-a)^2} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$
 (2.6.7)

If we choose $g(x) = -e^{-x}$ then $F_X(x)$ varies exponentially over [a, b] from the value 0 at x = a to the value 1 at x = b and we have a Random Variable

X with cdf $F_x(x)$ given by

$$F_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{e^{-a} - e^{-x}}{e^{-a} - e^{-b}} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$
 (2.6.8)

By differentiating the cdf we get the corresponding pdf as

$$F_X(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{e^{-x}}{e^{-a} - e^{-b}} & \text{for } a \le x \le b \\ 1 & \text{for } x > a \end{cases}$$
 (2.6.9)

Random Variables Bounded Below:

We shall next look at Random Variables for which

$$\mathcal{R}_X = [0, \infty)$$

Clearly for such random variables we must have

$$P(X \le x) = 0 \text{ for } x < 0$$

since X does not take any negative values. Hence we must have

$$F_X(x) = 0 \text{ for } x < 0$$
 (2.6.10)

On $[0,\infty)$, we must have $F_{\scriptscriptstyle X}(x)$ to be a nondecreasing, continuous function such that

$$F_{X}(0) = 0 \text{ and}$$
 (2.6.11)

$$F_X(0) = 0 \text{ and}$$
 (2.6.11)
 $\lim_{x \to +\infty} F_X(x) = 1$ (2.6.12)

We shall now look at examples of such random variables:

Exponential Random Variable:

The function $g(x) = e^{-\lambda x}$, (where λ is real and > 0), is a decreasing function

in $[0,\infty)$ decreasing from 1 at x=0 to 0 at $+\infty$. Hence the function $-g(x)=-e^{-\lambda x}$ is an increasing function in $[0,\infty)$ increasing from -1 at x=0 to 0 at $+\infty$. Consequently the function

$$h(x) = 1 - e^{-\lambda x}$$

is an increasing function in $[0, \infty)$ increasing from 0 to 1. Thus we can define $F_X(x)$ to be this function in $[0, \infty)$. Hence we can have a random variable X whose CDF is of the form,

$$F_{x} = \begin{cases} 0 & \text{for } x < 0 \\ 1 - e^{-\lambda x} & \text{for } x \ge 0 \end{cases}$$
 (2.6.13)

The corresponding pdf is given by

$$f_{X} = \begin{cases} 0 & \text{for } x < 0 \\ \lambda e^{-\lambda x} & \text{for } x \ge 0 \end{cases}$$
 (2.6.14)

Such a RV is called "Exponential Random Variable" and for any such random variable we write $X \sim Exp(\lambda)$.

Rayleigh Random Variable

The function

$$h(x) = 1 - e^{-\beta^2 x^2}$$
 (where β is real and nonzero) (2.6.15)

increases from 0 to 1 in the interval $[0, \infty)$. Thus we can have a random variable with the CDF as

$$F_{X} = \begin{cases} 0 & \text{for } x < 0 \\ 1 - e^{-\beta^{2}x^{2}} & \text{for } x \ge 0 \end{cases}$$
 (2.6.16)

The corresponding pdf is given by

$$f_X = \begin{cases} 0 & \text{for } x < 0 \\ 2\beta^2 x e^{-\beta^2 x^2} & \text{for } x \ge 0 \end{cases}$$
 (2.6.17)

Such a random variable is called **Rayleigh Random Variable** (with parameter β) and we write such a Random Variable as $X \sim Ray(\beta)$.

Pareto Random Variable

We can also have a random variable X for which $\mathcal{R}_X = [a, \infty)$ for some

a > 0. Then the CDF will be 0 for x < a and a continuous function in $[a, \infty)$ increasing from the value 0 at a to the value 1 at ∞ . We can modify the Exponential CDF above as follows:

$$F_{\scriptscriptstyle X}(x) = \begin{cases} 0 & \text{for } x < 0 \\ \frac{e^{-\lambda a} - e^{-\lambda x}}{e^{-\lambda a}} & \text{for } x \ge a \text{(where } \lambda > 0) \end{cases}$$
 (2.6.18)

The corresponding pdf is given by

$$F_{X}(x) = \begin{cases} 0 & \text{for } x < 0 \\ \frac{\lambda e^{-\lambda x}}{e^{-\lambda a}} & \text{for } x \ge a \text{ (where } \lambda > 0) \end{cases}$$
 (2.6.19)

Such a random variable is called **Pareto Random Variable** (with parameter β) and we write such a Random Variable as $X \sim Par(\beta)$.

Modified Rayleigh Random Variable

We can also modify the Rayleigh distribution as follows:

$$F_{X}(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{e^{-\beta^{2}a^{2}} - e^{-\beta^{2}x^{2}}}{e^{-\beta^{2}a^{2}}} & \text{for } x \ge a \text{ (where } \beta \text{ is real)} \end{cases}$$
 (2.6.20)

with the corresponding pdf as

$$F_{\scriptscriptstyle X}(x) = \begin{cases} 0 & \text{for } x < a \\ \frac{2\beta^2 x e^{-\beta^2 x^2}}{e^{-\beta^2 a^2}} & \text{for } x \ge a \text{ (where } \beta \text{ is real)} \end{cases}$$
 (2.6.21)

For such a Random Variable we have $\mathcal{R}_X = [a, \infty)$. We write such Random Variables as $\mathbf{Ray}(a; \beta)$

Unbounded Random Variables

We shall next consider some examples of unbounded random variables, that is, random variables X for which $\mathcal{R}_X = (-\infty, \infty)$. The CDF of such random

variables must be continuous functions defined on $(-\infty, \infty)$, and such that $\lim_{x \to -\infty} F_X(x) = 0$ and $\lim_{x \to +\infty} F_X(x) = 1$. We shall look at such models below:

Laplace Random Variable

The function,

$$F_X(x) = \begin{cases} \frac{1}{2}e^{\lambda x} & \text{if } x < 0\\ 1 - \frac{1}{2}e^{-\lambda x} & \text{if } 0 \le x < \infty \end{cases}$$
 (2.6.22)

(where $\lambda > 0$), satisfies all the requirements above. A random variable with the above CDF is called a **Laplace Random Variable** (with parameter λ) and is denoted as $X \sim Lap(\lambda)$. The corresponding pdf is given by

$$f_X(x) = \begin{cases} \frac{1}{2} \lambda e^{\lambda x} & \text{if } x < 0\\ \frac{1}{2} \lambda e^{-\lambda x} & \text{if } 0 \le x < \infty \end{cases}$$
 (2.6.23)

or we can write this as

$$f_X(x) = \frac{1}{2}\lambda e^{-|x|}$$
 (2.6.24)

For the Laplace Random Variable we observe the following:

$$P(X \le 0) = F_X(0) = \frac{1}{2}$$
 (2.6.25)

Hence we see that

$$P(X \ge 0) = 1 - P(X \le 0) \tag{2.6.26}$$

$$= 1 - \frac{1}{2} = \frac{1}{2} \tag{2.6.27}$$

Hence the random variable takes negative values and positive values with equal probability. We can also have Random Variables for which these two probabilities are not equal. For example, let α be a real number such that $0 < \alpha < 1$. Then we can take

$$F_{X}(x) = \begin{cases} \alpha e^{\lambda x} & \text{if } x < 0 \\ 1 - (1 - \alpha)e^{-\lambda x} & \text{if } 0 \le x < \infty \end{cases}$$
 (2.6.28)

satisfies all the requirements for a CDF with the corresponding pdf as

$$f_{X}(x) = \begin{cases} \alpha \lambda e^{\lambda x} & \text{if } x < 0 \\ (1 - \alpha)\lambda e^{-\lambda x} & \text{if } 0 \le x < \infty \end{cases}$$
 (2.6.29)

A Random Variable X with the above CDF satisfies

$$P(X \le 0) = \alpha \tag{2.6.30}$$

$$P(X > 0) = 1 - \alpha \tag{2.6.31}$$

When $\alpha = \frac{1}{2}$ this reduces to the Laplace Random Variable.

Cauchy Random Variable:

The function

$$F_X(x) = \frac{1}{2} + \frac{1}{\pi} tan^{-1} \left(\frac{x}{\alpha}\right)$$
 (2.6.32)

(where α is a positive real constant), satisfies the requirements of a CDF, with the corresponding pdf as

$$f_X(x) = \frac{\alpha}{\pi(x^2 + \alpha^2)}$$
 (2.6.33)

A random variable with this CDF is called a Cauchy Random Variable, with parameter α . We denote such ramdom variables as $X \sim Cauchy(\alpha)$. We again observe that the Cauchy Random Variable takes negative values with the same probability as it takes positive values. We can alter this by considering the following CDF: Let $0 < \beta < 1$

$$F_{X}(x) = \begin{cases} \beta + \frac{2\beta}{\pi} tan^{-1} \left(\frac{x}{\alpha}\right) & \text{for } x < 0 \\ \beta + \frac{2(1-\beta)}{\pi} tan^{-1} \left(\frac{x}{\alpha}\right) & \text{for } x \ge 0 \end{cases}$$
 (2.6.34)

with the corresponding pdf as

$$f_{X}(x) = \begin{cases} 2\frac{\beta\alpha}{\pi(x^{2} + \alpha^{2})} & \text{for } x < 0 \\ 2\frac{(1 - \beta)\alpha}{\pi(x^{2} + \alpha^{2})} & \text{for } x \ge 0 \end{cases}$$
 (2.6.35)

For this random variable we have

$$P(X<0) = \beta \tag{2.6.36}$$

$$P(X > 0) = 1 - \beta \tag{2.6.37}$$

If $\beta < \frac{1}{2}$ it takes positive values with higher probability than negative vales, and vice versa if $\beta > \frac{1}{2}$. If $\beta = \frac{1}{2}$ we get the Cauchy Random Variable which takes both positive and negative values with equal probabilities.

2.7 Conditional Probability

We nest introduce the important notion of conditional probability. Consider a random experiment and the associated probability space (Ω, \mathcal{B}, P) . Let us now begin with a simple example

Example 2.7.1 Consider the random experiment of choosing a point at random in the unit square $0 \le x \le 1, 0 \le y \le 1$ and noting its coordinates. We then have

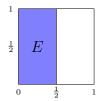
$$\Omega = \{(x,y) : 0 \le x \le 1, 0 \le y \le 1\}$$

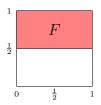
We shall consider subrectangles of the unit square as the elementary events and the probability of such events as the area of the rectangle. We shall as usual take the Borel subsets of this unit square as the collection \mathcal{B} of all events and extended concept of area to the Borel sets as the Probability measure P. Consider the following two events in this experiment:

$$E = \left\{ (x,y) : 0 \le x \le \frac{1}{2}, 0 \le y \le 1 \right\}$$

$$F = \left\{ (x,y) : 0 \le x \le 1, \frac{1}{2} \le y \le 1 \right\}$$

These events are sketched below:





2.7. CONDITIONAL PROBABILITY

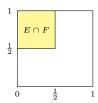
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We have

$$P(E) = \frac{1}{2}$$

$$P(F) = \frac{1}{2}$$

Let us now look at the proportion of F in E. We have $F \cap E$ as shown in Figure below:



Then we have

$$P(E \cap F) = \frac{1}{4}$$

Hence the proportion of F in E is given by

$$\frac{P(E \cap F)}{P(E)} = \frac{\left(\frac{1}{4}\right)}{\left(\frac{1}{2}\right)}$$
$$= \frac{1}{2}$$
$$= P(F)$$

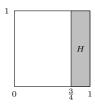
Thus the knowledge of the fact that the event E has occurred did not alter the Probability of occurrence of F. Now consider the event G sketched below:



Then we see that $E \cap G = E$ and hence

$$\frac{P(E\cap G)}{P(E)} \ = \ 1$$

In this case we see that the knowledge of occurrence of the event has enhanced completely the probability of occurrence of G. On the other hand consider the event H sketched below:



Then we see that $H \cap E = \phi$ and hence

$$\frac{P(H \cap E)}{P(E)} = 0$$

Hence in this case the knowledge of the occurrence of E has reduced the probability of occurrence of H.

From the above example we see that the knowledge of occurrence of an event may or may not affect the probability of occurrence of another event, and in the case where it affects it may either increase or decrease the probability of occurrence of the second event. This leads us to the following definitions:

Definition 2.7.1 If E and F are two events (with nonzero probabilities) then the **conditional probability of** F **given** E is denoted by P(F|E) and is defined as

$$P(F|E) = \frac{P(F \cap E)}{P(E)} \tag{2.7.1}$$

In the case that conditional probability of F given E is the same as the probability of F it means that the knowledge of occurrence of E does not affect the probability of occurrence of F. We then say F is independent of E. From above we have

$$P(F|E) = P(F)$$

$$\iff P(F \cap E)$$

$$P(E) = P(F)$$

$$\iff P(F \cap E) = P(E)P(F)$$

Note that the above is unaffected if we interchange E and F. Thus we have

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Definition 2.7.2 Two events E and F are said to be **Independent** if

$$P(E \cap F) = P(E)P(F) \tag{2.7.2}$$

(This is called the product rule of the probabilities for independence)

Example 2.7.2 In the Example 2.7.1 we have E, F are independent but E, G are not independent and also E, H are not independent.

Remark 2.7.1 It is easy to see that if E, F is an independent pair of events then the following pairs are also independent:

$$\{E, F'\}, \{E', F'\}, \{E', F\}$$

Remark 2.7.2 Note that the notion of independence of events arises from conditional probability and the definition of conditional probability is dependent on the probability measure on the random experiment. Hence the notion of independence of events is dependent on the probability measure on the probability space. Consequently two events may be independent with respect to one probability measure and not independent with respect to another probability measure.

Independence of a Collection of Events:

Let $\mathcal{C} = \{E_{\alpha}\}_{{\alpha} \in \mathcal{I}}$ be a collection of events, (where the index set \mathcal{I} can be finite or an infinite sequence or any continuum also). Then we say that the collection \mathcal{C} is independent if for **every** finite subcollection $\{E_1, E_2, \dots, E_n\}$ in \mathcal{C} , the following holds:

$$\mathcal{P}\left(\bigcap_{j=1}^{n} E_{j}\right) = \mathcal{P}(E_{1})\mathcal{P}(E_{2})\cdots\mathcal{P}(E_{n})$$
 (2.7.3)

Remark 2.7.3 Note that a for collection to be independent we need that for every finite subcollection the product rule of the probabilities hold. If it fails even for one subcollection we do not have independence of the collection. For example a collection \mathcal{C} of three events may be such that every pair in the collection may be independent but the collection may not be independent