

Last Time: Orthogonal Filter Banks

Exercise: Suppose that $H_1(z) = H_0(-z)$, where H_0 is FIR. Find all PR systems.

* Haar wavelet / FB

$$H_0(z) = \frac{1}{\sqrt{2}} (1 + z^{-1})$$

$$H_1(z) = \frac{1}{\sqrt{2}} (1 - z^{-1})$$

→ at least one solution exists

Soln: Use the polyphase representation.

$$H_0(z) = E_0(z^2) + z^{-1} E_1(z^2)$$

even odd
polyphase polyphase

$$H_1(z) = H_0(-z) = E_0(z^2) - z^{-1} E_1(z^2)$$

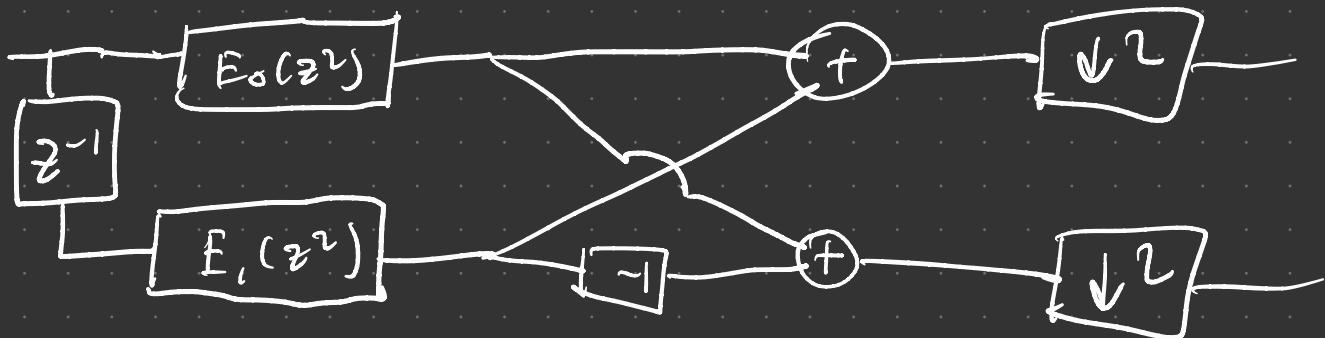
$$\begin{bmatrix} H_0(z) \\ H_1(z) \end{bmatrix} = \begin{bmatrix} E_0(z^2) & E_1(z^2) \\ E_0(z^2) & -E_1(z^2) \end{bmatrix} \begin{bmatrix} 1 \\ z^{-1} \end{bmatrix}$$

$\underbrace{\quad}_{H_P(z^2)}$

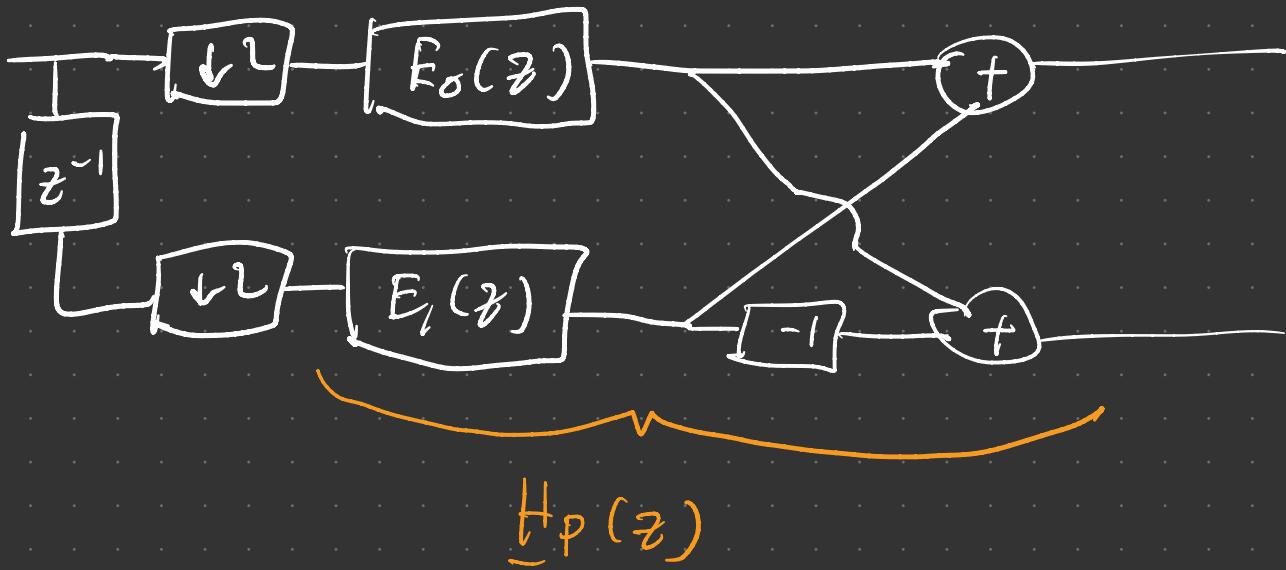
$$= \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \begin{bmatrix} E_0(z^2) & 0 \\ 0 & E_1(z^2) \end{bmatrix} \begin{bmatrix} 1 \\ z^{-1} \end{bmatrix}$$

2-point
DFT

Analysis Bank:



By the Noble identities

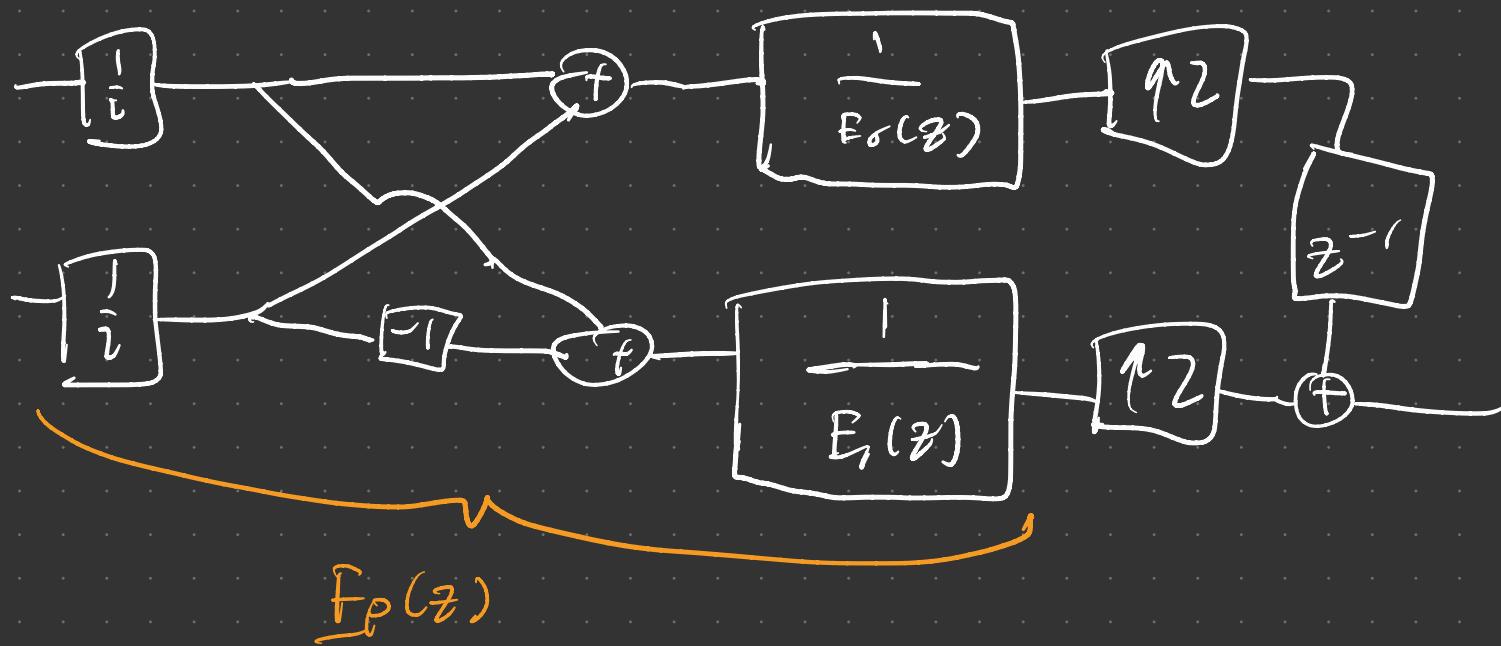


The problem has been reduced to inventing $H_p(z)$,
i.e., finding $E_p(z)$.

Synthesis Bank:

Observe that

$$\begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} \cdot \frac{1}{2} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$



$$\underline{E_p(z)} = \frac{1}{2} \begin{bmatrix} \frac{1}{E_0(z)} & 0 \\ 0 & \frac{1}{E_1(z)} \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$\begin{bmatrix} F_0(z) & F_1(z) \end{bmatrix} = \left[z^{-1} \quad 1 \right] \cdot \frac{1}{2} \begin{bmatrix} \overbrace{\quad}^1 & 0 \\ 0 & \overbrace{\quad}^1 \end{bmatrix} \begin{bmatrix} 1 & 1 \\ 1 & -1 \end{bmatrix}$$

$$= \left[z^{-1} \quad 1 \right] \cdot \frac{1}{2} \begin{bmatrix} \overbrace{\quad}^1 & \overbrace{\quad}^1 \\ \overbrace{\quad}^1 & -\overbrace{\quad}^1 \end{bmatrix}$$

$$= \frac{1}{2} \left[\overbrace{\quad}^1 + z^{-1} \overbrace{\quad}^1 - \overbrace{\quad}^1 + z^{-1} \overbrace{\quad}^1 \right]$$

Remark: So far, we have not assumed anything about the filters,

Q: What if we want FIR filters?

A: Polyphase components must be delays.

$$\text{i.e.) } E_0(z) = a z^{-l_0}, \quad E_1(z) = b z^{-l_1}$$

The general FIR solution takes the form:

$$\begin{aligned} H_0(z) &= E_0(z^2) + z^{-1} E_1(z^2) \\ &= az^{-2l_0} + bz^{-(2l_1+1)} \end{aligned}$$

Obs: For Haar wavelets, $l_0 = 0, l_1 = 0,$
 $a = \frac{1}{\sqrt{2}}, \quad b = \frac{1}{\sqrt{2}}$

- For IIR solutions, there are infinite possibilities.
- For causal & stable IIR solution,
 E_0 & E_1 must be min-phase.

(Zeros of E_0 & E_1 are inside unit circle)

\Rightarrow poles of $\frac{1}{E_0}$ & $\frac{1}{E_1}$ are inside
unit circle)

Orthogonal Filter Banks

$$\Lambda(z) = \begin{bmatrix} 1 & 0 \\ 0 & z^{-1} \end{bmatrix}$$

Last time we saw that, for an orthogonal FB,

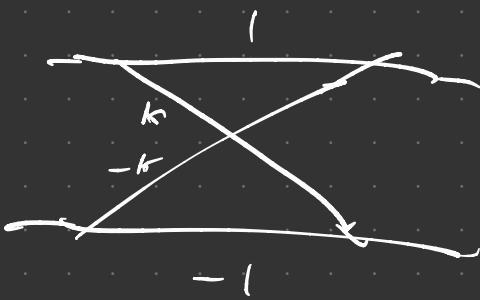
$$H_p(z) = \Lambda(-1) R_k \Lambda(z) R_{k-1} \Lambda(z) \dots \Lambda(z) R_0$$

where

$$R_\ell = \begin{bmatrix} \cos \theta_\ell & \sin \theta_\ell \\ -\sin \theta_\ell & \cos \theta_\ell \end{bmatrix} \quad \text{is a rot. matrix.}$$

$(K+1)$ parameters vs. $(4K+2)$ for a general factorization.

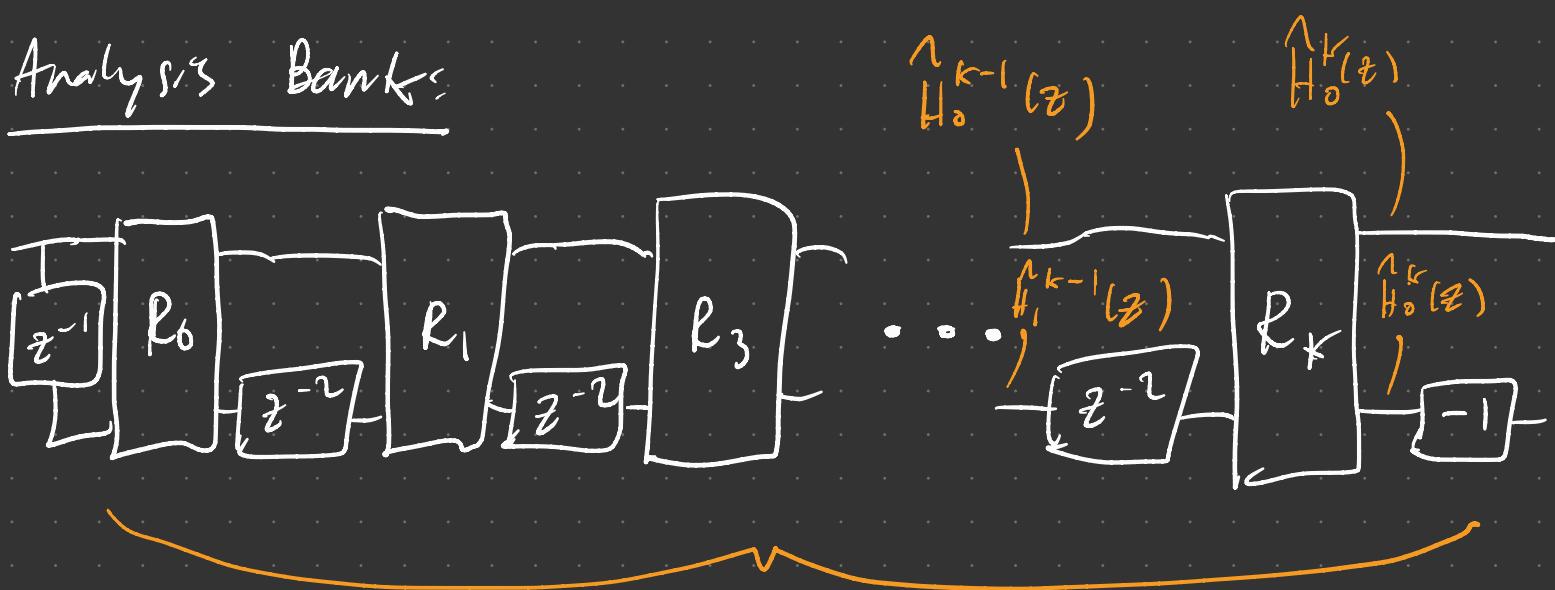
Lattice structure reduces the # of parameters.



$$R_\ell = \cos \theta \begin{bmatrix} 1 & k \\ -k & 1 \end{bmatrix}$$

$$k = \frac{\sin \theta}{\cos \theta}$$

Analysis Banks



$H_p(z^2)$: polyphase matrix for
order $2K+1$

H_o & H_i .

$$\begin{bmatrix} \hat{H}_o^{k-1}(z) \\ \hat{H}_i^{k-1}(z) \end{bmatrix} = \begin{bmatrix} c & s \\ -s & c \end{bmatrix} \begin{bmatrix} \hat{H}_o^{k-1}(z) \\ z^2 \hat{H}_i^{k-1}(z) \end{bmatrix}$$

order $2K-1$

$$= \begin{bmatrix} c \hat{H}_o^{k-1}(z) + z^{-2} s \hat{H}_i^{k-1}(z) \\ -s \hat{H}_o^{k-1}(z) + z^{-2} c \hat{H}_i^{k-1}(z) \end{bmatrix}$$

Obs: Given $\hat{H}_o^{k-1}(z)$, $\hat{H}_i^{k-1}(z)$, & θ_k we can find
 $\hat{H}_o^k(z)$ & $\hat{H}_i^k(z)$.

lower order \rightarrow higher order

Q: What about the reverse?

Given $\hat{H}_0^k(z)$ & $\hat{H}_1^k(z)$, can we find

θ_k , $\hat{h}_0^{k-1}(z)$, & $\hat{h}_1^{k-1}(z)$?

Obs: If we can do this, we have shown
that the structure above can implement
all orthogonal filter banks.

- ① $\hat{h}_0^k[2k+1] = S \hat{h}_1^{k-1}[2k-1]$ } highest-order terms
impulse response of \hat{H}_0^k
- ② $\hat{h}_0^k[2k] = S \hat{h}_1^{k-1}[2k-2]$ }
- ③ $\hat{h}_0^k[0] = C \hat{h}_0^{k-1}[0]$ } lowest-order terms
- ④ $\hat{h}_0^k[1] = C \hat{h}_0^{k-1}[1]$ }

Recall: For orthogonal filters banks

$$\hat{H}_1^{k-1}(z) = z^{-(2k-1)} \hat{h}_o^{k-1}(-z^{-1}) \quad (5)$$

$$\hat{h}_1^{k-1}[2k-1] = -\hat{h}_o^{k-1}[0] \quad (5)$$

$$= \frac{\hat{h}_o^k[2k+1]}{S} \quad (1)$$

$$\hat{h}_o^k[0] = \frac{\hat{h}^k[0]}{C} \quad (3)$$

$$\Rightarrow -\frac{\hat{h}_o^k[2k+1]}{S} = \frac{\hat{h}_o^k[0]}{C}$$

$$\Rightarrow \frac{S}{C} = -\frac{\hat{h}_o^k[2k+1]}{\hat{h}_o^k[0]}$$

tan θ_K

$$\theta_K = \tan^{-1} \left(-\frac{\hat{h}_o^k[2k+1]}{\hat{h}_o^k[0]} \right)$$

$$\cdot \hat{h}_o^{k-1}[2k-2] = \hat{h}_o^{k-1}[1] \longrightarrow \textcircled{S}$$

$$= \frac{\hat{h}_o^k[2k]}{S} \longrightarrow \textcircled{2}$$

$$\cdot \hat{h}_o^k[1] = \frac{\hat{h}_o^k[1]}{C} \longrightarrow \textcircled{4}$$

$$\Rightarrow \frac{\hat{h}_o^k[2k]}{S} = \frac{\hat{h}_o^k[1]}{C}$$

$$\tan \theta_k = \frac{S}{C} = \frac{\hat{h}_o^k[2k]}{\hat{h}_o^k[1]}$$

$$\boxed{\theta_k = \tan^{-1} \left(\frac{\hat{h}_o^k[2k]}{\hat{h}_o^k[1]} \right)}$$

Q: IS

$$-\frac{\hat{h}_o[k+1]}{\hat{h}_o[0]} = \frac{\hat{h}_o[k]}{\hat{h}_o[1]} ?$$

Alternatively, is

$$\cancel{\hat{h}_o[k+1] \hat{h}_o[2k+1] + \hat{h}_o[k] \hat{h}_o[0]} = 0?$$

for orthogonal systems?

Hint: $P_o(z) = F_o(z) H_o(z)$

Since the system is orthogonal,

$$F_o(z) = z^{-(2k+1)} H_o(z^{-1})$$

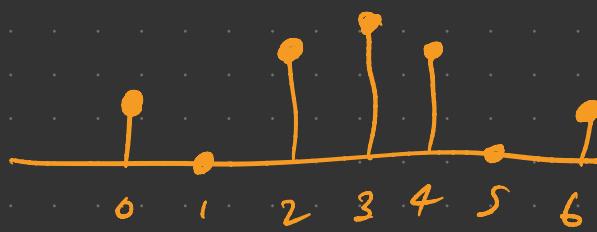
$$\Rightarrow P_o(z) = z^{-(2k+1)} H_o(z^{-1}) H_o(z)$$

is half-band.



Claim: $\cancel{\star}$ implies $\cancel{\star}$

Note: $h_o^K = h_o$



$$H_o(z) : h_o[0] \ h_o[1] \ h_o[2] \ \dots \ h_o[2k] \ h_o[2k+1]$$

$$z^{-(2k+1)} H_o(z^{-1}) : h_o[2k+1] \ h_o[2k] \ h_o[2k-1] \ \dots \ h_o[1] \ h_o[0]$$

$$z^{-1} : h_o[0] \ h_o[2k] + h_o[1] h_o[2k+1] = 0 \quad \checkmark$$

half band

Obs: This only works because the system is orthogonal & P_o is half-band.

At this point we have θ_K , which allows us to construct \hat{H}_o^{k+1} & \hat{H}_1^{k+1} .

Exercise: $H_1(z) = H_0(-z)$.

If $H_0(z)$ is Type I linear-phase, are

F_0 & F_1 causal & stable? No.

Solⁿ: Causal & stable F_0 & F_1

$\Rightarrow E_0$ & E_1 are min-phase.

Ex: $h_0[n] : a \ b \ c \ d \ c \ b \ a$

$e_0[n] : a \ c \ c \ a$

$e_1[n] : b \ d \ b$

Polyphase components of Type I linear-phase system are linear-phase.

Linear-phase systems cannot be min-phase.

Q: What if H_0 is Type II linear-phase?

No.

$$\underline{\text{Ex: }} h[n] : a \ b \ c \ d \quad | \quad d \ c \ b \ a$$

$$e_0[n] : a \ c \ d \ b$$

$$e_1[n] : b \ d \ c \ a$$

polyphase components of Type II

bilinear-phase system are flips of each other.

$$E_c(z) = z^{-L} E_o(z^{-1})$$

If one of them is min-phase, the other is max-phase.