

# Last Time : Linear-Phase Systems

Type I : center of symmetry  $L \in \mathbb{Z}$

Type II : center of symmetry  $L - \frac{1}{2} \in \mathbb{Z}$

Type III : center of antisymmetry  $L \in \mathbb{Z}$

Type IV : center of antisymmetry  $L - \frac{1}{2} \in \mathbb{Z}$

Recall: The frequency response of a linear-phase system looks like

$$H(e^{j\omega}) = \underbrace{e^{j(-L\omega + \phi)}}_{\text{phase}} \underbrace{|H_{\text{amp}}(\omega)|}_{\text{magnitude}}$$

Phase Response:  $\phi(\omega) = -L\omega + \phi$  linear

Group Delay: Delay of each frequency by  $h[n]$ .

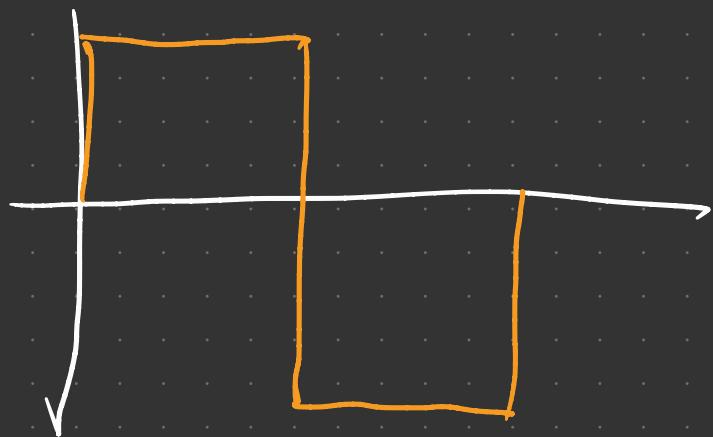
Mathematically expressed by  $-\phi'(\omega)$ .

For linear-phase systems :

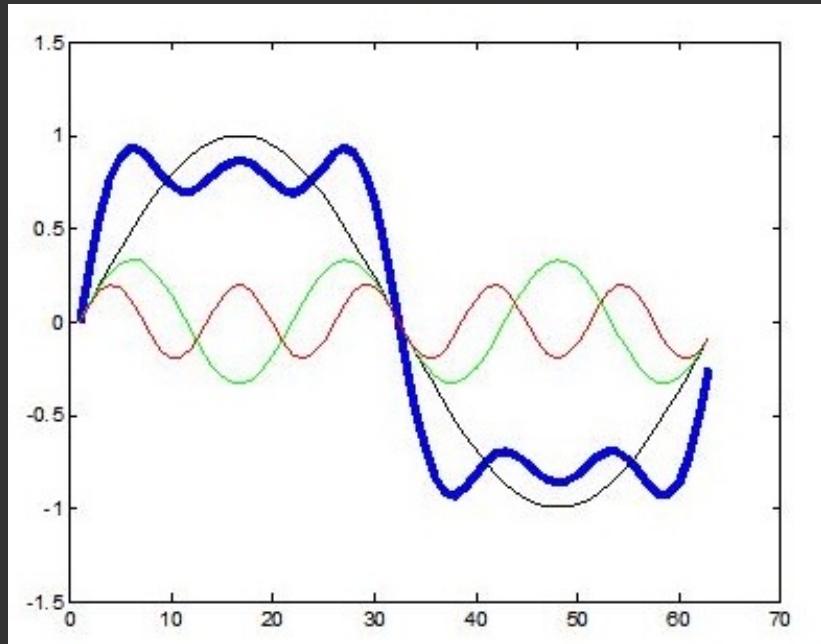
$$-\phi'(\omega) = L \quad \text{center of } h[n]$$

Obs: Linear-phase systems have constant group delay.

Ex: Consider a square wave:

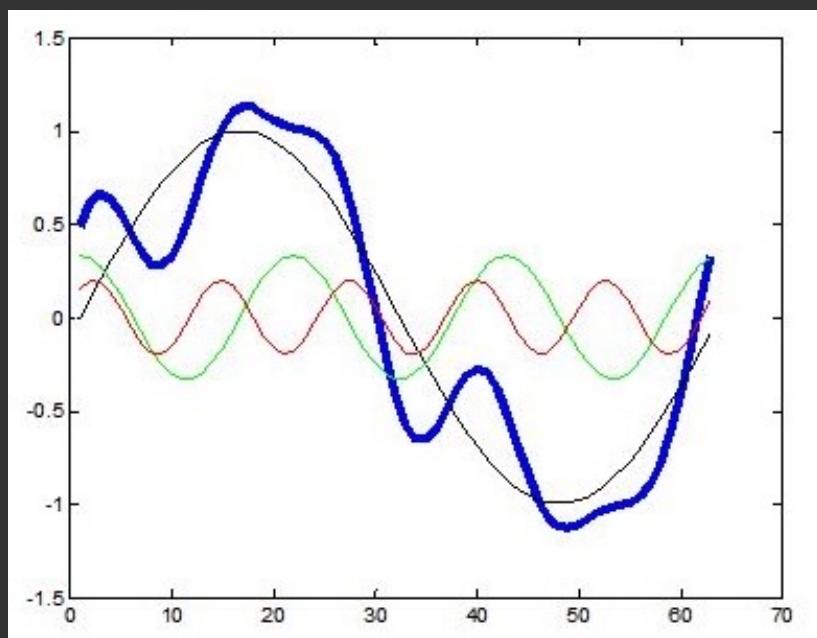


Approximate it by the first 3 nonzero terms in its Fourier series:



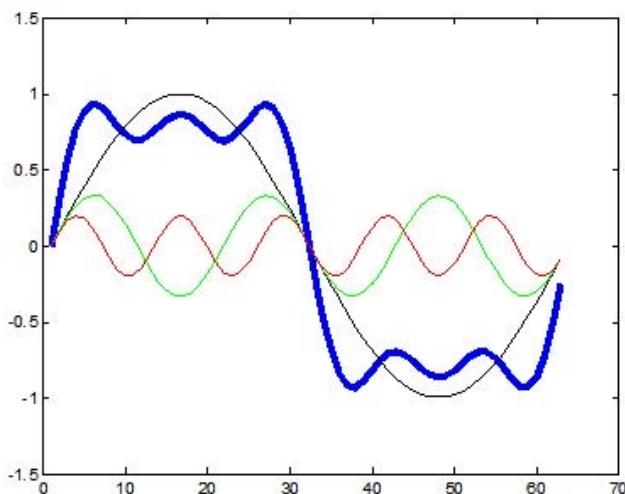
A linear-phase system will delay each pure frequency the same amount leaving the shape of the signal intact.

On the other hand, a nonlinear-phase system will shift each frequency a different amount, resulting in the loss of the waveform shape:

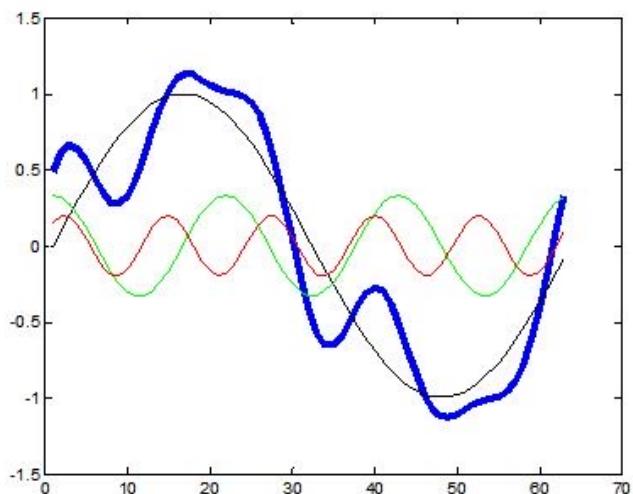


Side-by-side comparison:

Linear Phase ☺



Non-Linear Phase ☹



Linear-Phase = Constant Group Delay  
 = Waveform-preserving

$H_{\text{amp}}(\omega)$	$L \in \mathbb{Z}$	$L - \frac{1}{2} \in \mathbb{Z}$
Symmetric $B = 0$ $h[n] = h[2L-n]$	I $\sum_{n=0}^L a[n] \cos(n\omega)$ <ul style="list-style-type: none"> <li>No "real" constraints</li> <li>"universal"</li> </ul>	II $\sum_{n=0}^{L-\frac{1}{2}} b[n] \cos((n+\frac{1}{2})\omega)$  $\pi$ odd # of zeroes @ $\pi$ <ul style="list-style-type: none"> <li>No high-pass</li> </ul>
Anti-symmetric $B = \frac{\pi}{2}$ $h[n] = -h[2L-n]$	III $\sum_{n=0}^L c[n] \sin(n\omega)$  $\pi$ odd # of zeroes @ 0, $\pi$ <ul style="list-style-type: none"> <li>only band-pass</li> </ul>	III $\sum_{n=0}^{L-\frac{1}{2}} d[n] \sin((n+\frac{1}{2})\omega)$  $0$ odd # of zeroes @ 0 <ul style="list-style-type: none"> <li>No low-pass</li> </ul>

Last Time: High-pass filters cannot be Type II

$$|H(e^{j\omega})|$$

Proof:

$$\cos((n+\frac{1}{2})\pi) = 0 \quad \forall n \in \mathbb{Z}$$

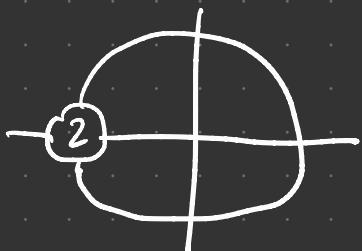


Obs: When designing filters, if there is any doubt, choose Type I.

Remark: Many wavelet filters are linear-phase.

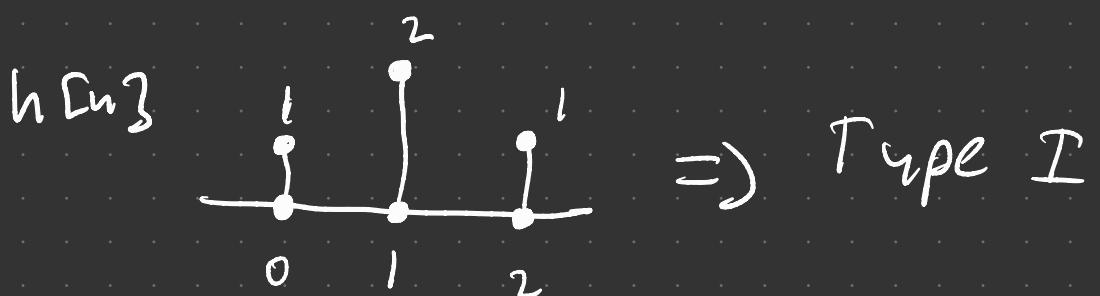
Q: What happens when you cascade two Type II filters?

Ex:  $H(e^{j\omega})$  has two zeroes @  $\pi$ .

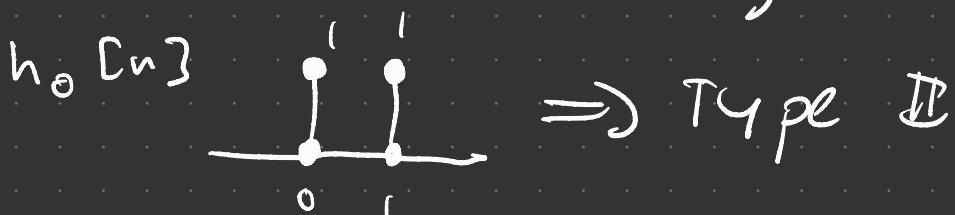


What type is this?

$$H(z) = (1 + z^{-1})^2 = 1 + 2z^{-1} + z^{-2}$$



$$H(z) = H_0(z) H_0(z), \quad H_0(z) = 1 + z^{-1}$$



Cascade  $\xrightarrow{\text{Type II}} \boxed{H_0} \xrightarrow{\text{Type II}} \boxed{H_0} \xrightarrow{\text{Type II}}$  is Type I.

Claim: The cascade of two linear-phase systems of the same type is always Type I.

Proof: Consider the cascade

$$H(e^{j\omega}) = H_1(e^{j\omega}) H_2(e^{j\omega})$$

with

$$H_k(e^{j\omega}) = e^{j(-L_k \omega + \beta_k)} \quad \text{Hampl}_k(\omega), \quad k=1, 2.$$

$$\boxed{\beta_k = 0 \quad \text{or} \quad \frac{\pi}{2}}$$

Then,

$$H(e^{j\omega}) = e^{j(-(L_1 + L_2)\omega + (\beta_1 + \beta_2))} \approx \text{Hampl}(\omega)$$

$$e^{j(\beta_1 + \beta_2)} = \pm 1 = e^{j((L_1 + L_2)\omega)} \approx \text{Hampl}(\omega)$$

Since the convolution of two even length filters is odd and the convolution of two odd length filters is odd, this is Type I.  $\square$

Recall: For Type I and II filters

$$h[n] = h[2L-n]$$

Take Z-transform of both sides:

$$H(z) = z^{-2L} H(z^{-1})$$

delay flip

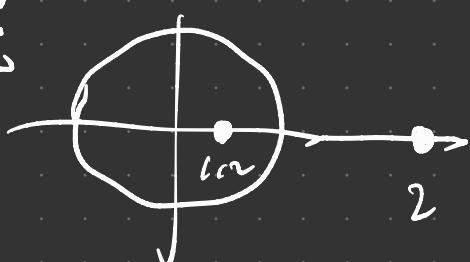
Q: How are the zeroes related?

A: Suppose  $z_0$  is a zero.

$$0 = H(z_0) = z_0^{-2L} H(z_0^{-1})$$

Therefore  $z_0^{-1}$  is also a zero.

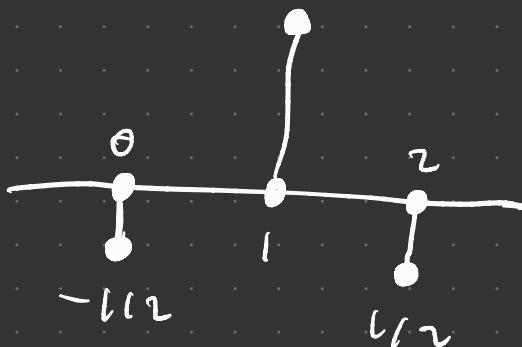
Ex:



$$H(z) = \left(1 - \frac{z^{-1}}{2}\right) \left(-\frac{1}{2} + z^{-1}\right)$$

$$= -\frac{1}{2} + \frac{5}{4}z^{-1} - \frac{1}{2}z^{-2}$$

$$h[n]$$



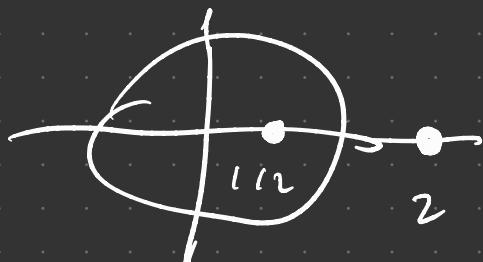
Type I

General: Four situations for the  $(z_0, z_0^{-1})$  zero pair

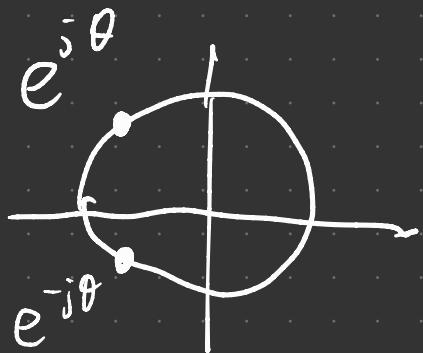
① One zero @ 1 or -1



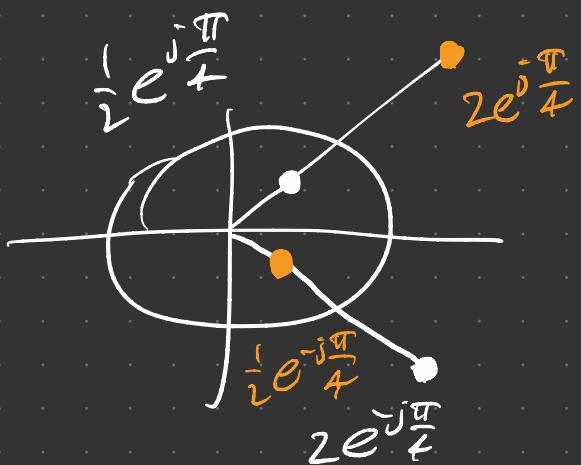
②  $(r, \frac{1}{r})$ ,  $r \in \mathbb{R}$



③  $(e^{j\theta}, e^{-j\theta})$



④  $(re^{j\theta}, \frac{1}{r}e^{-j\theta}, re^{-j\theta}, \frac{1}{r}e^{j\theta})$



Trick:

$$H_1(z) = (1 - re^{j\theta} z^{-1}) \quad \text{complex zero}$$

$$H_2(z) = (-re^{j\theta} + z^{-1}) \quad \text{complex zero}$$

flip the coeffs.

add in complex conj. so that the coeff. cts are real.

Exercise:

Given a complex zero @  $r e^{j\theta}$ ,  
determine  $H(z)$  so that it is  
a linear-phase system with  
real coefficients.

# All-Pass Systems

Def<sup>n</sup>: Given  $H(e^{j\omega})$ , the system is called all-pass if

$$|H(e^{j\omega})| = 1$$

Q: What's the point of all-pass systems?

A: To manipulate the phase response

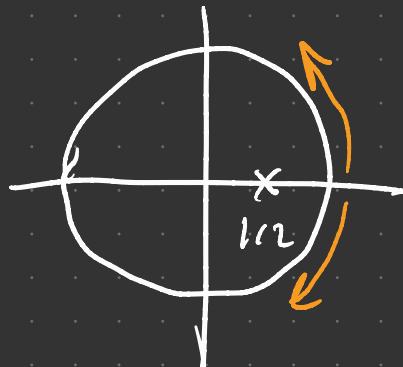
- Minimum-phase systems
- Maximum-phase systems

Ex: •  $H(z) = 1$  identity / do nothing  
 $\Rightarrow h[n] = \delta[n]$

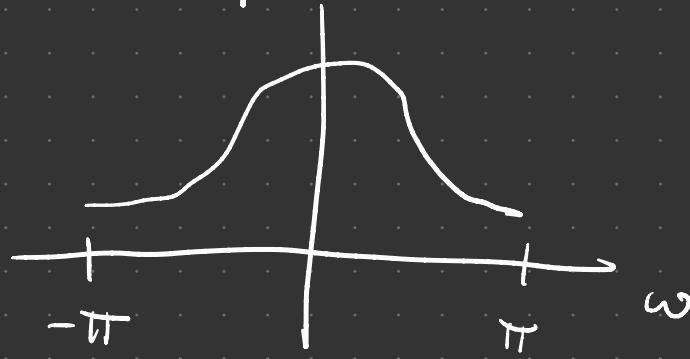
•  $H(z) = z^{-N}$  delay  
 $\Rightarrow h[n] = \delta[n-N]$

(Non)

Ex:



$|H(e^{j\omega})|$



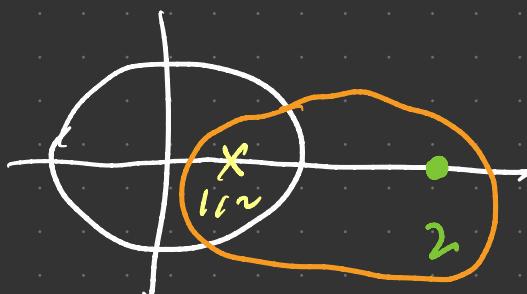
The pole "pushes" you with  
"Strength" proportional to distance  
from the pole.

Obs: This system is not all-pass.

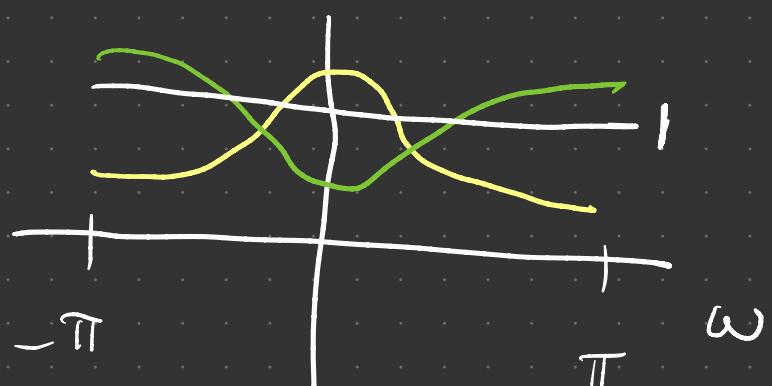
Q: How do we make it all-pass?

A: Add a zero to "counteract" the pole.

Ex:



$|H(e^{j\omega})|$



All-pass systems  
have pole-zero  
pairs

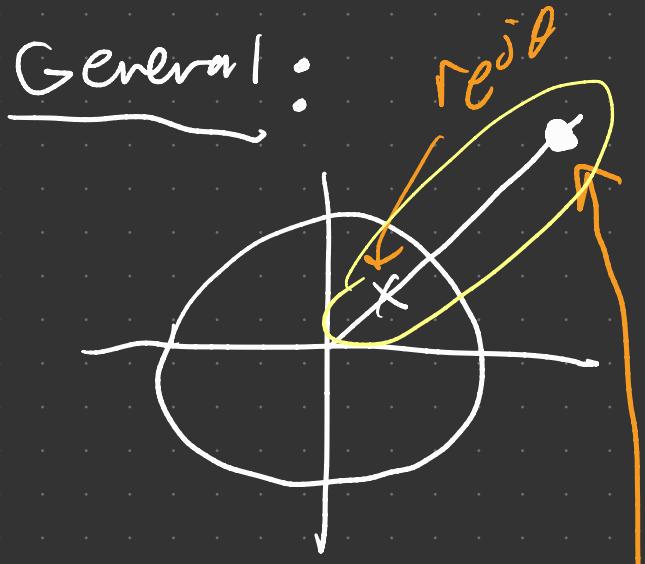
Ex (cont.):

$$H(z) = \frac{-\frac{1}{2} + z^{-1}}{1 - \frac{1}{2}z^{-1}}$$

$$H(e^{j\omega}) = \frac{-\frac{1}{2} + e^{-j\omega}}{1 - \frac{1}{2}e^{-j\omega}} = e^{-j\omega} \frac{-\frac{1}{2}e^{j\omega} + 1}{1 - \frac{1}{2}e^{-j\omega}}$$

unit magnitude  
 complex conj-pairs

$$\Rightarrow |H(e^{j\omega})| = 1$$



$$H(z) = \frac{-re^{-j\theta} + z^{-1}}{1 - re^{j\theta}z^{-1}}$$

flip coeff and take  
complex conj. of denominator  
to get numerator.

Exercise: Where is the zero?

$$z = r^{-1}e^{j\theta}$$