



## YuJiahe's blog

## Codeforces Round 1035 (Div. 2) Editorial

By [YuJiahe](#), [history](#), 26 hours ago, 

Sorry for misjudging the difficulty of problem D, but we still hope you enjoyed the problems!

## 2119A - Add or XOR

Author: [YuJiahe](#)[Hint 1](#) $a \oplus 1$  is equivalent to  $a - 1$  when  $a$  is an odd number, otherwise it is equivalent to  $a + 1$ .[Hint 2](#)If you apply  $a \leftarrow a \oplus 1$  when  $a$  is odd, then that operation should make  $a = b$ .[Tutorial](#)

## 2119A - Add or XOR

Obviously, if  $b < a$  and  $a \oplus 1 = b$ , the answer is  $y$ . If  $b < a$  and  $a \oplus 1 \neq b$ , there is no solution.After excluding the above, there is  $a \leq b$ . Then the bitwise XOR operation can only be used if  $a$  is even; otherwise, it will cancel out the last operation.So if  $x \leq y$ , then always use the add operation; otherwise, use the bitwise XOR operation if  $a$  is even, and use the add operation if it is odd.Let  $d = b - a$ . The minimal cost is:

$$ans = \begin{cases} \lceil d/2 \rceil \cdot \min(x, y) + \lfloor d/2 \rfloor \cdot x & a \text{ is even} \\ \lfloor d/2 \rfloor \cdot \min(x, y) + \lceil d/2 \rceil \cdot x & a \text{ is odd} \end{cases}$$

Which is computable in  $O(1)$ .  $O(b - a)$  solutions are also passable.[Implementation](#)

```
#include <algorithm>
#include <cstring>
#include <cstdio>
#include <vector>
#include <queue>
using namespace std;
int t, a, b, x, y;
int main(){scanf("%d", &t);
    while (t --){scanf("%d%d%d", &a, &b, &x, &y);
        if (a > b) printf("%d\n", (a ^ 1) == b ? y : -1);
        else {int c0 = b - a, c1 = (b + 1 >> 1) - (a + 1 >> 1);
            printf("%lld\n", y > x ? 1ll * c0 * x : 1ll * (c0 - c1) * x +
                1ll * c1 * y);}
    }
}
```

## 2119B - Line Segments

Author: [Lyz09](#)[Hint 1](#)


## → Pay attention

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Transform  $(p_x, p_y)$  to  $(q_x, q_y)$  into an operation where  $a_i$  is the distance between the two points.

### Hint 2

When  $n + 1 = 3$ , there is a solution if and only if the largest  $a_i$  is less than or equal to the sum of the remaining  $a_i$ .

### Tutorial

## 2119B - Line Segments

First, add an additional vector with magnitude equal to the distance  $d$  from  $(p_x, p_y)$  to  $(q_x, q_y)$ , directed back to the starting point. This converts the problem to checking if the  $n + 1$  vectors can sum to zero.

Now, the problem reduces to determining whether these  $n + 1$  edges can form a polygon (possibly degenerate). The necessary and sufficient condition is that no single edge exceeds the sum of the others. To see why:

- Necessity: If the longest edge  $m$  satisfies  $m > \sum_{\text{other edges}}$ , it cannot connect with the remaining edges.
- Sufficiency: Otherwise, we can arrange the edges:
  - Group the edges into three segments: the longest  $m$  and two groups with sums  $s_1, s_2$  (sums as close as possible to  $\frac{S-m}{2}$  where  $S$  is total length).
  - These three segments form a triangle because:
    - $m \leq s_1 + s_2$  (by initial condition).
    - $s_1 \leq m + s_2$  since  $s_1 \leq \frac{S-m}{2} + \frac{\max(a_i)}{2} \leq m + s_2$  when  $m \geq \max(a_i)$ .
    - Similarly,  $s_2 \leq m + s_1$ .
  - The degenerate case ( $n + 1 = 2$ ) is covered when  $s_1 = 0$  or  $s_2 = 0$ .

Therefore, we simply check if the maximum edge length  $m = \max(\max_i a_i, d)$  satisfies  $m \leq S - m$ , where  $S = d + \sum_{i=1}^n a_i$  and  $d$  is the Euclidean distance between the starting point and the terminal point.

### Implementation 1

```
#include<iostream>
#include<algorithm>
#include<cmath>
using namespace std;
#define N 100010
#define int long long
int t,n,sx,sy,tx,ty;
double a[N];
signed main()
{
    cin>>t;
    while(t--)
    {
        cin>>n;
        cin>>sx>>sy>>tx>>ty;
        for(int i=1;i<=n;i++)
            cin>>a[i];
        a[++n]=sqrt((sx-tx)*(sx-tx)+(sy-ty)*(sy-ty));
        sort(a+1,a+n+1);
        double sum=a[n];
        for(int i=1;i<=n;i++)
            sum-=a[i];
        if(sum<=0)
            puts("Yes");
        else
            puts("No");
    }
}
```

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```
    }
}
```

### Implementation 2

```
#include<iostream>
#include<algorithm>
using namespace std;
#define N 100010
#define int long long
int t,n,sx,sy,tx,ty,a[N];
signed main()
{
    cin>>t;
    while(t-->0)
    {
        cin>>n;
        cin>>sx>>sy>>tx>>ty;
        for(int i=1;i<=n;i++)
            cin>>a[i];
        sort(a+1,a+n+1);
        int p=(sx-tx)*(sx-tx)+(sy-ty)*(sy-ty);
        if(p>a[n]*a[1])
        {
            int sum=0;
            for(int i=1;i<=n;i++)
            {
                sum+=a[i];
                if(sum*sum>=p)
                    break;
            }
            if(sum*sum>=p)
                puts("Yes");
            else
                puts("No");
        }
        else
        {
            int sum=a[n];
            for(int i=1;i<=n-1;i++)
                sum-=a[i];
            if(sum<=0 || sum*sum<=p)
                puts("Yes");
            else
                puts("No");
        }
    }
}
```

### 2119C - A Good Problem

Author: [lizhous](#) Preparation: [Lyz09](#)

#### Hint 1

For odd  $n$ , setting  $a_i = l$  for all  $i$  suffices.

#### Hint 2

For even  $n$ , there does not exist a valid array  $a$  that satisfies  $a_1 = a_2 = \dots = a_{n-1} = l$ .

#### Hint 3

For even  $n$ , try to make  $a_1 = a_2 = \dots = a_{n-2} = l$ .

#### Tutorial

### 2119C - A Good Problem

For odd  $n$ , setting  $a_i = l$  for all  $i$  suffices.



Consider the even  $n > 2$  (if  $n = 2$  then the only legal array is  $[0, 0]$ , so no solution exists because  $l \geq 1$ ).

To achieve the lexicographically smallest array, we set  $a_i = l$  for  $i = 1$  to  $n - 1$ , then try choosing  $a_n \in [l, r]$ , which would require satisfying  $l \& a_n = l \oplus a_n$ . Now to determine whether there is a legal  $a_n$ , then consider each bit separately. Since  $l \geq 1$ , there must exist a bit in the binary representation of  $l$  that is 1, and we observe that for any bit where  $l$  has 1,  $l \& x \neq l \oplus x$  holds for  $x = 0$  and  $x = 1$ , so we can't just change  $a_n$ .

If no valid  $a_n$  exists, we adjust both  $a_{n-1}$  and  $a_n$ . They must satisfy  $a_{n-1} \oplus a_n = l \& a_{n-1} \& a_n, l \leq a_{n-1}, a_n \leq r$ . Per-bit constraints:

- If  $l$ 's bit is 1:  $a_{n-1}$  and  $a_n$  must both be 0.
- If  $l$ 's bit is 0:  $a_{n-1}$  and  $a_n$  must be equal (both 0 or both 1).

From the per-bit constraints,  $a_{n-1}$  and  $a_n$  must be equal at every bit, implying  $a_{n-1} = a_n$ , so  $a_{n-1} \oplus a_n = 0$  and  $a_{n-1} \& a_n = a_n$ . From  $a_{n-1} \oplus a_n = l \& a_{n-1} \& a_n$ , we have  $l \& a_n = 0$ . Finally, we solve for the minimum  $a_n$  by greedily going from high to low bit.

Let  $b$  be the highest bit set in  $l$ . Since  $a_n$  must be  $\geq l$  but have bit  $b$  unset (due to  $l \& a_n = 0$ ),  $a_n$  requires a 1 at some bit higher than  $b$ . And bit  $b$  is already different, so the lower bits may be set to 0, so eventually  $a_n$  is the smallest power of two greater than  $l$  that lies in  $[l, r]$ .

If no solution exists for  $a_{n-1}, a_n$ , then  $l$  and  $r$  share the same highest bit  $b$ . The bitwise AND value is 1, and the bitwise XOR value is 0 on this bit, so it is easy to see that there must be  $\&_{i=1}^n a_i \neq \oplus_{i=1}^n a_i$ .

#### Implementation

```
#include<iostream>
using namespace std;
#define int long long
int t,n,l,r,k;
signed main()
{
    cin>>t;
    while(t--){
        cin>>n>>l>>r>>k;
        if(n%2==1){
            cout<<1<<endl;
            continue;
        }
        if(n==2){
            cout<<-1<<endl;
            continue;
        }
        int res=1;
        bool f1=0;
        while(res<=r){
            if(res>l){
                {
                    f1=1;
                    if(k<=n-2)
                        cout<<1<<endl;
                    else
                        cout<<res<<endl;
                    break;
                }
                res*=2;
            }
            if(!f1)
                cout<<-1<<endl;
        }
    }
}
```

## 2119D - Token Removing

Author: **YuJiahe**Hint 1

Calculating the weight of a single valid sequence is difficult. Try another way?

Tutorial

## 2119D - Token Removing

Consider determine which tokens will be removed first. Then we just need to count the number of ways that, for each position  $p_i$  with a token to be removed, find an closed segment  $[l_i, r_i]$  that contains position  $p_i$ , and these  $r_i$  are different to each other.

Assuming that the positions of the tokens are  $n \geq p_0 > p_1 > \dots > p_{k-1} \geq 1$ , the answer to the above is obviously  $\prod_{i=0}^{k-1} p_i(n - p_i + 1 - i)$ . This inspires the following DP state: let  $f_{i,j}$  denote the answer for the sum of  $\prod_{i=0}^{k-1} p_i(n - p_i + 1 - i)$  when  $p_{k-1} \geq n - i + 1$  and  $k = i - j$ . Consider whether  $p_{k-1}$  is equal to  $n - i + 1$ , we have:

$$f_{i,j} = f_{i-1,j-1} + (n - i + 1)(j + 1)f_{i-1,j}$$

The answer is  $\sum_{j=0}^n f_{n,j}$ . The total time complexity is  $O(n^2)$ .

Implementation

```
#include <algorithm>
#include <cstring>
#include <cstdio>
#include <vector>
#include <queue>
using namespace std;
const int N = 5005;
int t, n, mod, f[N][N], ans;
inline void add(int& x, int y){x += y;if (x >= mod) x -= mod;}
int main(){scanf("%d", &t);
    while (t --){scanf("%d%d", &n, &mod), f[0][0] = 1, ans = 0;
        for (int i = 1;i <= n;i ++){
            for (int j = 0;j <= i;j ++){
                f[i][j] = 0;
                for (int i = 1;i <= n;i ++){
                    for (int j = 0, now;j < i;j ++){
                        if (now = f[i - 1][j]) add(f[i][j + 1], now),
                        f[i][j] = (f[i][j] + (n - i + 1) * (j + 1) * now) % mod;
                        for (int j = 0;j <= n;j ++){
                            add(ans, f[n][j]);printf("%d\n",
ans);
                        }
                    }
                }
            }
        }
    }
```

## 2119E - And Constraint

Author: **ma2021tyoi0037**Hint 1

As same as the title, can you find a simple necessary constraint?

Hint 2Consider  $a_i = 0$  first.Tutorial

## 2119E - Ограничение на И

First, obviously  $b_i$  must include  $a_{i-1} | a_i$ , which is the fundamental requirement.

Secondly, we can note that there are only 31 possible effective values for  $b_i$ :

1. Considering the upper bound of the problem, it is not difficult to increase all  $b_i$  to above  $2^{29}$ , then change some bits to above  $2^{30}$ , and then satisfy the previous constraints.
2. Consider how to make the effective values so few.

We might consider which  $b_i$  are more likely to be the answer. Apart from the binary bit constraints that must be satisfied, we should try to avoid having 1s in each binary bit as much as possible, because this might cause our sequence not to satisfy the conditions.

Observing the process of increasing  $b_i$ , the useful  $b_i$  exhibit a stepped pattern: the preceding bits are the same as  $b_i$ , the next bit is set to 1, and all subsequent bits are 0. Numbers not on this step are certainly useless.

However, we did not consider the bits that are forced to be included earlier. We can directly apply the bitwise OR with this constraint, and then we find the useful values.

With the useful values, we can directly design  $f_{i,j}$  to represent the minimum number of operations when the first  $i$  numbers have been determined, and the  $i$ -th number becomes  $j$ .

During the transition, we can enumerate the value  $k$  for the  $(i+1)$ -th position, and if  $j \& k$  satisfies the constraint, then we can make the transition.

The time complexity of this algorithm is  $O(n \log^2 V)$ , where  $V$  is the maximum value among  $a_i$  and  $b_i$ .

#### Implementation

```
#include <bits/stdc++.h>
using namespace std;

typedef long long ll;
struct stu{
    int x;
    ll dp;
};

int n,a[100007],b[100007];
vector<stu> f,g;
const ll inf=0x3f3f3f3f3f3f3f3f;
void Subt(){
    cin>>n;
    for(int i=1;i<=n;i++) cin>>a[i];
    for(int i=1;i<=n;i++) cin>>b[i];
    a[n]=0;
    f.clear();
    f.push_back((stu){0,0});
    for(int i=1;i<=n;i++){
        int x=0;
        g.clear();
        for(int j=30;j>=-1;j--){
            int y=x|a[i-1]|a[i];
            if(j!=-1) y|=(1<<j);
            if(y>=b[i]){
                ll mn=inf;
                for(stu l:f){
                    if((l.x&y)!=a[i-1]) continue;
                    mn=min(mn,l.dp+y-b[i]);
                }
                if(mn<inf) g.push_back((stu){y,mn});
            }
            x|=((1<<j)&b[i]);
        }
        swap(f,g);
    }
    ll mn=inf;
    for(stu l:f) mn=min(mn,l.dp);
    if(mn<inf) cout<<mn<<endl;
    else cout<<-1<<endl;
    return;
}
```

```
signed main(){
    ios::sync_with_stdio(0),cin.tie(0),cout.tie(0);
    int T=1;
    cin>>T;
    while(T--){
        Subt();
    }
}
```

## 2119F - Volcanic Eruptions

Author: [lizhous](#)

Hint 1

Try to determine the vertex where you were before the last move.

Hint 2

I just need to calculate the earliest time I can reach the end vertex.

Hint 3

What form of moving path from the starting vertex to the end vertex is considered optimal?

Tutorial

## 2119F - Volcanic Eruptions

We define a "TURN" as consecutively traversing the same edge. Define the endpoint as the vertex reached before the last move. Use  $(a, b)$  to define an edge  $(u, v)$  satisfied  $w_u = a, w_v = b$ .

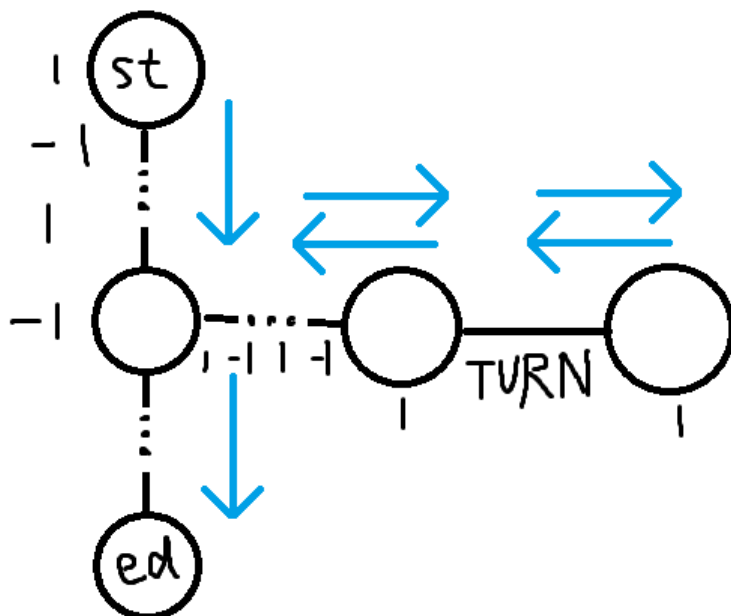
First, if the path does not traverse through the edge  $(1, 1)$ , the sequence of vertex weights along the path must alternate between  $1$  and  $-1$ . The maximum moves can be computed by enumerating endpoints  $ed$  where the path from  $st$  to  $ed$  satisfies this alternation. Then we can repeatedly increase the number of TURNS at any  $(1, -1)$  to ensure you always reach the endpoint just before the lava does. A simple parity check then suffices to compute the answer for this endpoint.

The remaining paths must include  $(1, 1)$ . We observe that performing TURNS on more than one distinct edge is suboptimal. This is because all TURNS can be adjusted to occur on the first traversal of the  $(1, 1)$  edge. Specifically, if the current path involves  $x$  TURNS, we can modify it to perform all  $x$  TURNS on the first traversal of  $(1, 1)$  and then remove all remaining TURNS. This adjustment does not affect the validity of the path:

1. Path continuity: The start and end vertices of a TURN are the same, so adding or removing a TURN does not break the path's continuity.
2. Death by lava: Since your speed matches the lava's, as long as you are not in the lava at the end, you won't encounter it midway.
3. Death by low health: Before the first  $(1, 1)$ , the path must alternate between  $1$  and  $-1$ . Removing TURNS in this segment won't cause death. Moreover, since the number of TURNS at this  $(1, 1)$  is no fewer than in the original plan, the health at the vertices after TURNS will be no lower than in the original plan, ensuring no death.

If the endpoint is  $ed$ , then based on the conclusion that TURNS occur only on one edge, the optimal path must consist of a main path from the start  $st$  to  $ed$  with a TURN branch attached. This branch must satisfy:

- Its outermost edge is  $(1, 1)$ .
- The path leading to this edge alternates between  $1$  and  $-1$ .



For a given  $ed$ , to reach the endpoint earlier, we need to find the nearest  $(1, 1)$  to the main path where the segment from the start to it alternates between  $1$  and  $-1$ . We can perform a BFS starting from each  $(1, 1)$ , selecting the next vertex under the condition that its weight  $w$  differs from the current vertex's. This allows us to preprocess the nearest  $(1, 1)$  for each vertex, which can then be directly referenced when constructing the main path.

For a given  $ed$ , the vertex with the minimum health is also determined, since the TURN branch (alternating between  $1$  and  $-1$ ) does not affect the minimum health vertex. Thus, ensuring health remains above zero at all times reduces to ensuring the minimum health vertex satisfies this condition.

For a given  $ed$ , all constraints can be easily resolved to compute the earliest arrival time at the endpoint. Since your speed matches the lava's, we only need to compare your arrival time with the lava's to determine if  $ed$  is a valid endpoint.

After fixing the endpoint, we can repeatedly increase the number of TURNS at  $(1, 1)$  to ensure you always reach the endpoint just before the lava does. A simple parity check then suffices to compute the answer for this endpoint.

The final answer is the maximum value obtained across all possible endpoints.

#### Implementation

```
#include<iostream>
#include<cstdio>
#include<algorithm>
#include<cstring>
#include<vector>
#include<set>
#include<queue>
#include<unordered_map>
#include<map>
#define int long long
using namespace std;
int n,st,dist[1000002],w[1000001],tim[1000001],ans;
vector<int> g[1000001];
int f[1000001];
queue<int> q;
void getdis(int u,int fa)
{
    for(int v:g[u])
    {
        if(v==fa) continue;
        dist[v]=dist[u]+1;
        getdis(v,u);
    }
}
```



```

void dfs(int u,int fa,int k,bool inn,int hei,int TIM,int dis)
{
    if(hei<0)
    {
        TIM=max(TIM,(-hei+1)/2*2+k*2+dis);
    }
    if(TIM<=dist[u])
    {
        ans=max(ans,dist[u]);
    }
    else
    {
        return;
    }
    for(int v:g[u])
    {
        if(v==fa) continue;
        if(inn&&w[u]!=w[v])
        {
            dfs(v,u,min(k,tim[v]),inn,hei+w[v],TIM+1,dis+1);
        }
        else
        {
            dfs(v,u,k,0,hei+w[v],TIM+1,dis+1);
        }
    }
}

int T;
signed main()
{
    ios::sync_with_stdio(false);
    cin>>T;
    int cnt=0;
    while(T--)
    {
        cnt++;
        cin>>n>>st;
        for(int i=1;i<=n;i++)
        {
            dist[i]=0;
            tim[i]=1000000000;
            g[i].clear();
            f[i]=-1000000000000000;
        }
        ans=0;
        for(int i=1;i<=n;i++)
        {
            cin>>w[i];
        }
        for(int i=1,u,v;i<=n;i++)
        {
            cin>>u>>v;
            g[u].push_back(v);
            g[v].push_back(u);
        }
        getdis(1,-1);
        for(int i=1;i<=n;i++)
        {
            for(int v:g[i])
            {
                if(w[i]==1&&w[v]==1)
                {
                    tim[i]=0;
                    q.push(i);
                    break;
                }
            }
        }
    }
}

```

```


    }
}
while(!q.empty())
{
    int u=q.front();
    q.pop();
    for(int v:g[u])
    {
        if(tim[v]==1000000000&&w[v]!=w[u])
        {
            tim[v]=tim[u]+1;
            q.push(v);
        }
    }
}
dfs(st,-1,tim[st],1,w[st],1,1);
cout<<ans+(dist[st]&1)-1<<'\n';
}
}

```

 Tutorial of Codeforces Round 1035 (Div. 2)

 +52  

 [YuJiahe](#)

 26 hours ago

 [30](#)




## Comments (30)

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YuJiahe

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Auto comment: topic has been updated by **YuJiahe** (previous revision, new revision, compare).

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ma2021tyoi0037

22 hours ago, [hide](#) <#> | 

 -22 

D is interesting and easy to code.

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 0 

ABC were easy

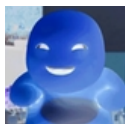


Badri41

D was just chinese for me. Hope to learn and be better for next contest. Learnt about the reverse the Summation Technique.

Thanks for the problems :)

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zac2010

20 hours ago, [hide](#) <#> [^](#) | 


 0 

An interesting thing is, I thought you were referring to the AtCoder Beginner Contest.

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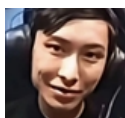
zeyd123

22 hours ago, [hide](#) <#> | 

 +8 

I see that problems so hard, and editorial too

→ [Reply](#)



Wantingfire


3 hours ago, [hide](#) <#> [^](#) | 

 0 

Me too and i only finished A during the contest.....

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22 hours ago, [hide](#) <#> | 

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Can someone explain the solution to E in simpler words? "preceding bits" "next bit"