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# PH3205-Computational Physics

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## Worksheet 6

A notebook is provided containing solution to both the problems: [WS6\\_notebook.ipynb](#). Also individual `.py` files are provided separately for this.

### Problem 1: MC Integration using Importance Sampling

The problem is: Integrating using importance sampling: the integral is given as

$$I = \int_0^{\pi} \frac{dy}{y^2 + \cos^2(y)}$$

The weight function is given as:

$$w(y) = ae^{-y}$$

### Solution

For solving we first need to map the *Uniform Random Variables* in (0,1) to the given weight function.

$$y(x) = \int_0^x dt \times ae^{-t} = a(1 - e^{-x})$$
$$\Rightarrow x_i = -\ln\left(1 - \frac{y_i}{a}\right)$$

Thus the estimator of the integral is given by:

$$\hat{I} = \frac{1}{N} \sum_{i=1}^N \frac{1}{(x_i)^2 + \cos^2(x_i)} \frac{1}{ae^{-x_i}}$$

The `.py` file for this problem is [WS6.1.py](#), and the required plots are: [Problem1.a.jpg](#) and [Problem1.b.jpg](#). Explaining the plots:

- [Problem1.a.jpg](#) shows the variation of the estimated integral with different values of  $N$ . We see that with increasing,  $N$  the estimated value converges rapidly to the true value.
- [Problem1.b.jpg](#) Shows the variation of estimated integral with different values of  $a$  for the weight function. The first plot shows the variation of estimated integral,  $\hat{I}$  with  $a$ , and the second plot shows the variation of the variance,  $(\sigma^2)$  with  $a$ . We see that with increasing value of  $a$ , the estimated value of the integral, and we see a *monotonically decreasing variance*. This behaviour is expected as variance is not immune to scale transforms, so as the value of estimated integral decreases, the variance decreases.

## Problem 2: *Metropolis Hastings's Algorithm*

We want to sample the distribution:

$$P(x) = \mathcal{N}(\mu, \sigma)$$

We can use the Metropolis-Hastings algorithm to sample from this distribution. We define a *Markov Chain* for a possible value of  $x$  and, and the stationary distribution of the Markov Chain follows the distribution of  $P(x)$ .

### Implemented Algorithm

- We start by assigning a value to the initial state of the Markov Chain:  $x_0$ .
- In the consecutive steps we assume that we know  $x_n$  and we want  $x_{n+1}$
- Now we need to generate a candidate  $x^*$  from our proposal distribution  $Q(x^*|x_n)$  which depends the current state of Markov Chain. For our case we again sample it from a Normal Distribution:

$$x^*|x_n \sim \mathcal{N}(\mu_n, \sigma_n)$$

- Next step is to calculate the acceptance probability:

$$A_n(x_n \rightarrow x^*) = \min \left( 1, \frac{P(x^*)Q(x_n|x^*)}{P(x_n)Q(x^*|x_n)} \right)$$

where  $Q(x^*|x_n)$  is the probability of the proposal distribution given the current state of the Markov Chain. For our case, since we are sampling from a Normal Distribution  $\mathcal{N}(x_n, \sigma_n)$ ,  $Q(x^*|x_n)$ , and  $Q(x_n|x^*)$  are equal(due to symmetry), thus the acceptance probability reduces to

$$A_n(x_n \rightarrow x^*) = \min \left( 1, \frac{P(x^*)}{P(x_n)} \right)$$

- Now that we have  $x^*$  and  $A_n(x_n \rightarrow x^*)$  we can decide whether to accept the candidate or not. For that we generate a random normal  $u$  from a uniform Distribution i.e  $u \sim \text{Uniform}(0, 1)$ . Then we accept and reject based on:

$$x_{n+1} = \begin{cases} x^* & \text{if } u \leq A_n(x_n \rightarrow x^*) \\ x_n & \text{otherwise} \end{cases}$$

**NOTE :** Make sure you have **Tqdm** python library installed in your system. It is used to track the progress of code.

The `.py` file for this problem is `WS6_2.py`, and the required plots are: `Problem2_a.jpg` and `Problem2_b.jpg`. Explaining the plots:

- `Problem2_a.jpg` shows the distribution of the random number sampled from the proposal distribution.
- `Problem2_b.jpg` shows that with increasing length of the Markov chain, the distribution of the samples takes the shape of the proposal distribution.