

Importance Weighted Autoencoders with Uncertain Neural Network Weights

Daniel Hernández–Lobato

Computer Science Department
Universidad Autónoma de Madrid

<http://dhnzl.org>, daniel.hernandez@uam.es

Joint work with Thang D. Bui, Yingzhen Li, José Miguel
Hernández–Lobato and Rich E. Turner.

Unsupervised Learning and Generative Models

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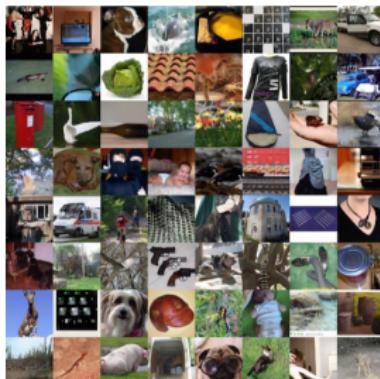
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Real Images

Generated Images

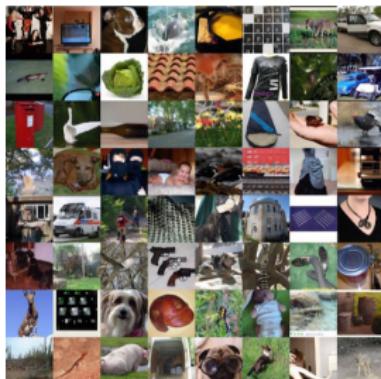
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It may be easier to generate first a **latent variable z** and then the data x .

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$$p(x) = \int p(x|z)p(z)dz$$

A Model that can Explain the Observed Data

We consider $p(\mathbf{z})$ is something simple we can sample from. Can we generate one \mathbf{x} similar to each $\{\mathbf{x}_i\}_{i=1}^N$ using a parametric $p(\mathbf{x}|\mathbf{z}; \theta)$?

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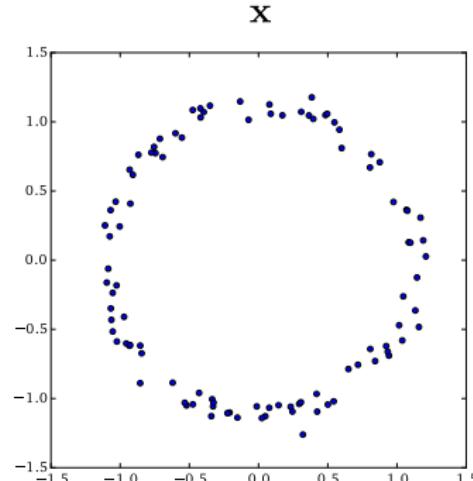
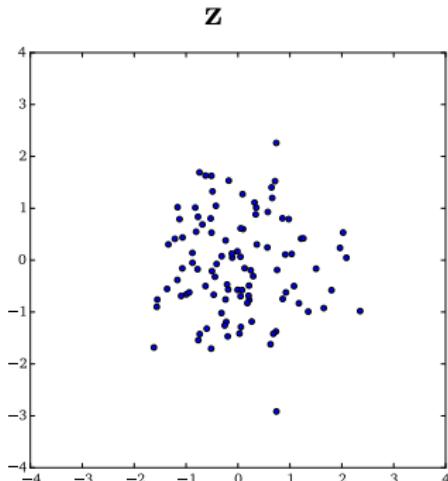
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Training the Model

Let $p(\mathbf{x}|\mathbf{z}; \theta)$ be a factorizing Gaussian with parameters given by a MLP.

$$p(\mathbf{x}|\mathbf{z}; \theta) = \prod_{d=1}^D \mathcal{N}(x_d | \mu_d(\mathbf{z}; \theta), \sigma_d^2(\mathbf{z}; \theta))$$

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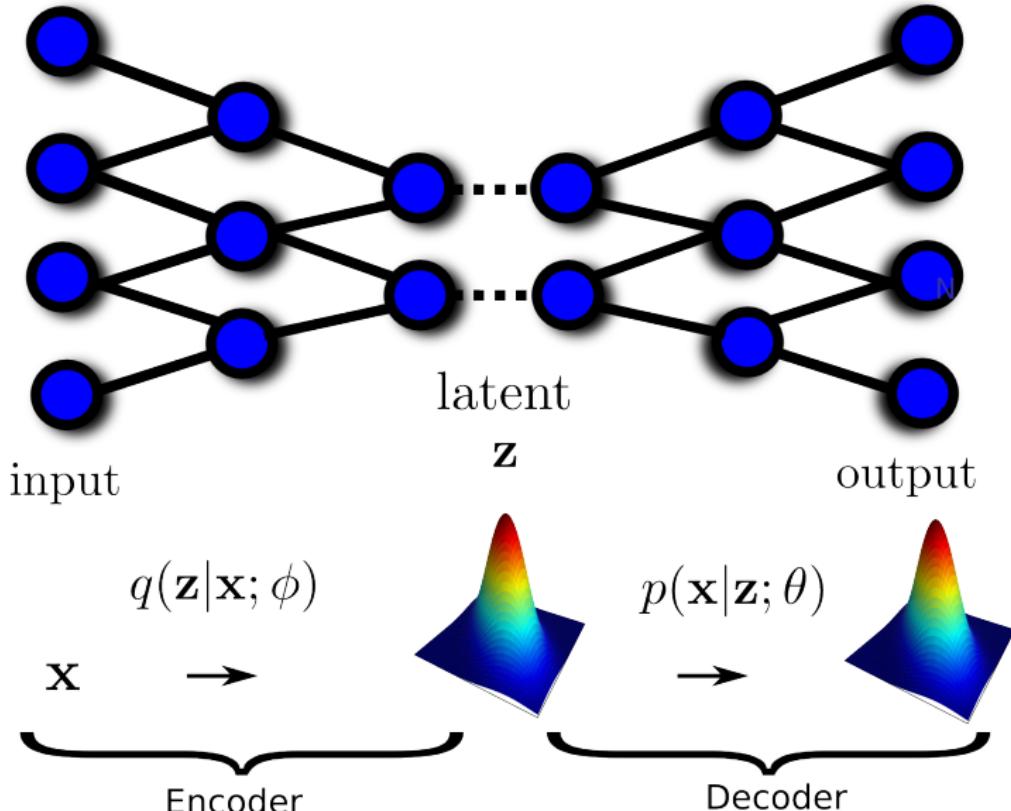
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- Adds a **recognition network** $q(\mathbf{z}|\mathbf{x}; \phi)$ that approximates $p(\mathbf{z}|\mathbf{x})$.

Variational Autoencoder



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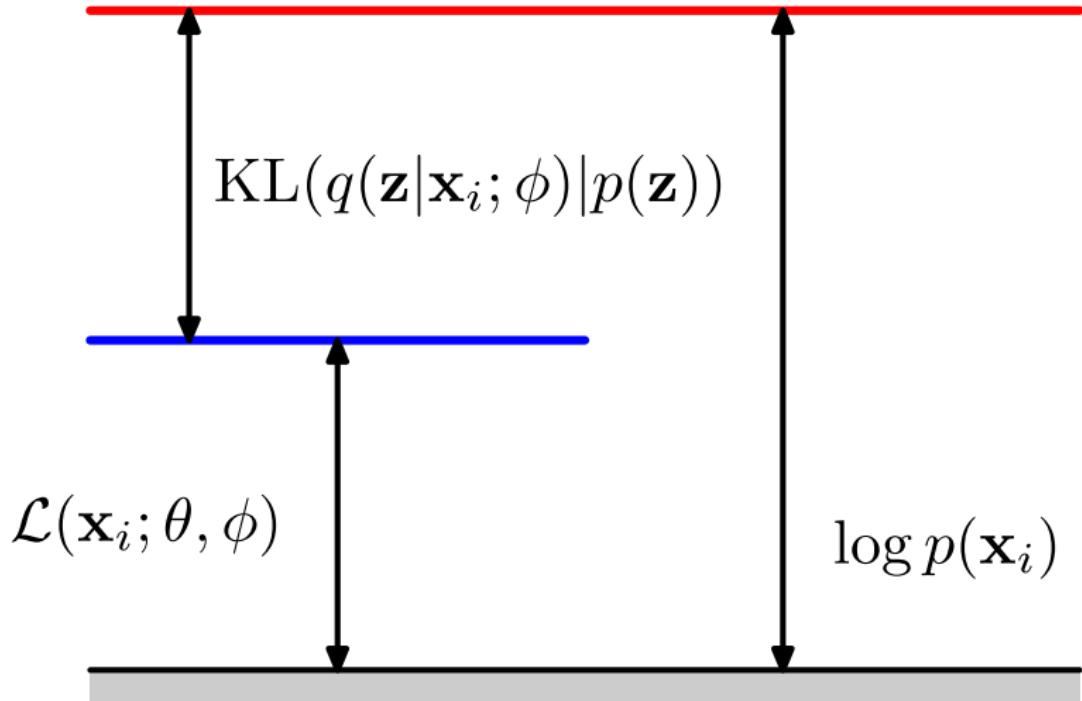
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Maximizing $\mathcal{L}(\mathbf{x}_i; \theta, \phi)$ w.r.t ϕ makes $\text{KL}(q(\mathbf{z}|\mathbf{x}_i; \phi) || p(\mathbf{z}|\mathbf{x}_i))$ very small, and maximizing w.r.t. θ should improve $\log p(\mathbf{x}_i)$.

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$$\mathbf{z}^{(m)} = \mathbf{L}(\mathbf{x}_i; \phi)^T \boldsymbol{\epsilon} + \boldsymbol{\mu}(\mathbf{x}_i; \phi), \quad \boldsymbol{\epsilon} \sim \mathcal{N}(\mathbf{0}, \mathbf{I})$$

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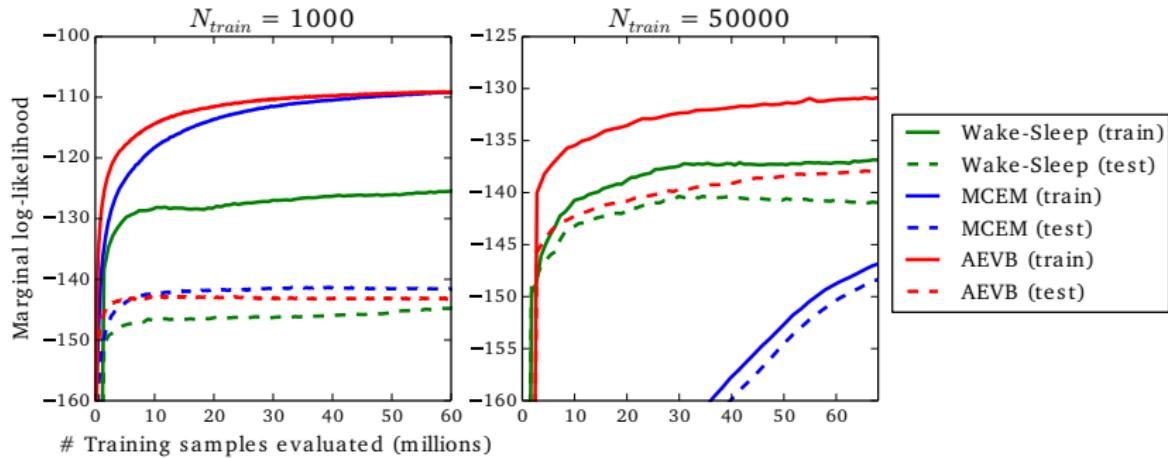
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We can use minibatches and stochastic gradients for training!
Furthermore, all MLP operations can be done in the GPU.

Results on the MNIST Dataset

100 hidden units in the MLP and 3 latent variables:



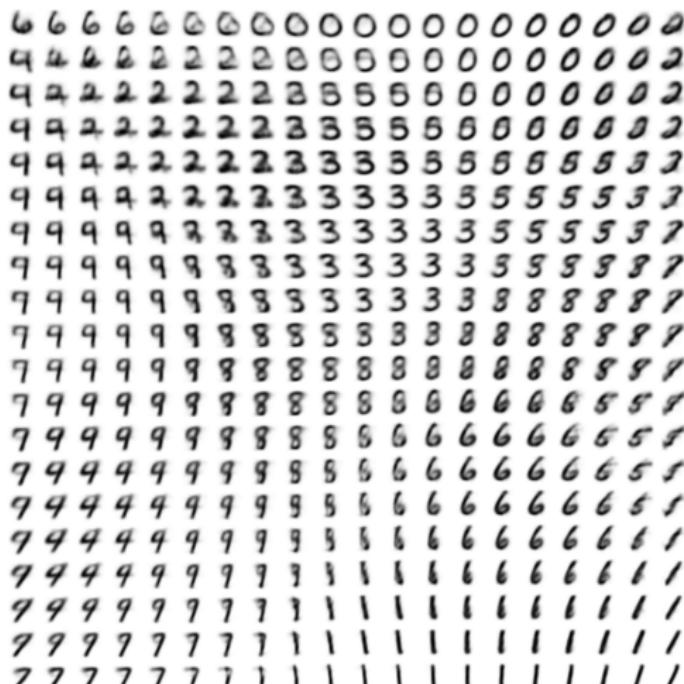
2D Manifolds Learned by the VAE

The z's are transformed using the inverse CDF of the standard Gaussian.



(a) Learned Frey Face manifold

(Kingma and Welling, 2014)



(b) Learned MNIST manifold

Generated samples from the MNIST

8 6 / 7 8 1 4 8 2 8	6 1 6 5 7 6 7 6 7 2	2 8 3 8 3 8 5 7 3 8
9 6 8 3 9 6 0 3 1 9	8 5 9 4 6 8 2 1 6 2	8 3 8 2 7 9 3 3 3 8
5 9 9 1 3 6 9 1 7 9	6 1 0 8 2 8 8 4 3 8	8 5 9 9 4 3 9 5 1 6
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0 4 6 1 2 3 2 0 8 8	6 9 9 4 2 7 2 3 2 3	7 4 3 6 3 0 3 6 0 1
9 7 5 4 9 3 4 8 5 1	2 6 4 5 6 0 9 7 9 8	2 1 8 0 4 7 1 8 0 0

(a) 2-D latent space

(b) 5-D latent space

(c) 10-D latent space

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On expectation that estimate is a **lower bound** on $\log p(\mathbf{x}_i)$:

$$\mathcal{L}_k(\mathbf{x}_i; \theta, \phi) = \mathbb{E} \left[\log \frac{1}{k} \sum_{m=1}^k w_m \right] \leq \log \mathbb{E} \left[\frac{1}{k} \sum_{m=1}^k w_m \right] = \log p(\mathbf{x}_i)$$

Importance Weighted Autoencoder

Improves the VAE by considering a **tighter lower bound** on $p(\mathbf{x}_i)$.

Consider an **importance sampling** estimate of $p(\mathbf{x}_i)$:

$$\begin{aligned}\log p(\mathbf{x}_i) &= \log \int p(\mathbf{x}_i|\mathbf{z}; \theta)p(\mathbf{z})d\mathbf{z} = \log \int p(\mathbf{x}_i|\mathbf{z}; \theta)p(\mathbf{z}) \frac{q(\mathbf{z}|\mathbf{x}_i; \phi)}{q(\mathbf{z}|\mathbf{x}_i; \phi)} d\mathbf{z} \\ &= \log \mathbb{E}_{q(\mathbf{z}|\mathbf{x}_i; \phi)} \left[\frac{p(\mathbf{x}_i|\mathbf{z}; \theta)p(\mathbf{z})}{q(\mathbf{z}|\mathbf{x}_i; \phi)} \right] \approx \log \frac{1}{k} \sum_{m=1}^k \frac{p(\mathbf{x}_i|\mathbf{z}^{(m)}; \theta)p(\mathbf{z}^{(m)})}{q(\mathbf{z}^{(m)}|\mathbf{x}_i; \phi)}\end{aligned}$$

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If $k = 1$ we obtain the VAE. $k > 1$ can only improve the bound.
Optimization is done as in the VAE.

(Burda et al., 2016)

Experimental Results

# stoch. layers	k	MNIST				OMNIGLOT			
		VAE		IWAE		VAE		IWAE	
		NLL	active units	NLL	active units	NLL	active units	NLL	active units
1	1	86.76	19	86.76	19	108.11	28	108.11	28
	5	86.47	20	85.54	22	107.62	28	106.12	34
	50	86.35	20	84.78	25	107.80	28	104.67	41
2	1	85.33	16+5	85.33	16+5	107.58	28+4	107.56	30+5
	5	85.01	17+5	83.89	21+5	106.31	30+5	104.79	38+6
	50	84.78	17+5	82.90	26+7	106.30	30+5	103.38	44+7

(Burda *et al.*, 2016)

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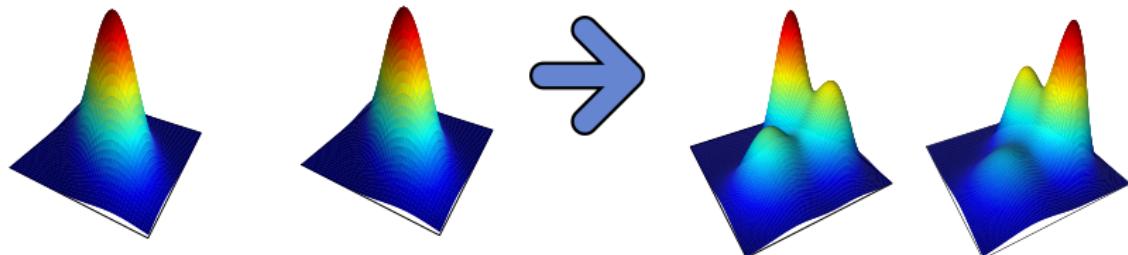
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$$q(\mathbf{z}|\mathbf{x}; \phi) \quad p(\mathbf{x}|\mathbf{z}; \theta) \quad q(\mathbf{z}|\mathbf{x}) \quad p(\mathbf{x}|\mathbf{z})$$



Training the Model

Given a dataset $\{\mathbf{x}_i\}_{i=1}^N$ the **objective** is:

$$\sum_{i=1}^N \mathcal{L}_k(\mathbf{x}_i; \Omega) = \sum_{i=1}^N \mathbb{E} \left[\log \sum_{m=1}^k \frac{p(\mathbf{x}_i | \mathbf{z}^{(m)}; \theta^{(m)}) p(\mathbf{z}^{(m)})}{q(\mathbf{z}^{(m)} | \mathbf{x}_i; \phi^{(m)})} \right]$$

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- ① Sample the NN activations $\mathbf{A} = \mathbf{XW} + \mathbf{b}\mathbf{1}^\top$, which are Gaussian.
- ② Instead of sampling $M \times H \times D$ variables, we sample $M \times H$.

(Kingma *et al.*, 2015)

Experimental Results: MNIST and Omniglot

- We consider 1-layer MLP with 400 units and 40 latent variables.
- We compare with a model that considers uncertainty only in ϕ .
- We set the number of importance samples $k = 25$.

Average test log-likelihood for each method.

Dataset	IWAE	IWAEU	IWAEU _{rec}
MNIST	-95.182±0.022	-94.346±0.025	-94.709±0.025
Omniglot	-118.771±0.035	-118.540±0.049	-118.647±0.031

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Future Work:

- ① Carry out extra experiments to explore if the gains are also obtained with **bigger and deeper** neural networks.
- ② Combine with **black-box-alpha** for training and explore **other models** (e.g., ladder variational autoencoders).

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