

1 **Assessing the Impact of Graphical Quality on Automatic**
2 **Text Recognition in Digital Maps**

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9 **Abstract.** Converting geographic features (e.g., place names) in map images
10 into a vector format is the first step for incorporating cartographic information
11 into a geographic information system (GIS). With the advancement in compu-
12 tational power and algorithm design, map processing systems have been con-
13 siderably improved over the last decade. However, the fundamental map pro-
14 cessing techniques such as color image segmentation, (map) layer separation,
15 and object recognition are sensitive to minor variations in graphical properties
16 of the input image (e.g., scanning resolution). As a result, most map processing
17 results would not meet user expectations if the user does not "properly" scan
18 the map of interest, pre-process the map image (e.g., using compression or
19 not), and train the processing system, accordingly. These issues could slow
20 down the further advancement of map processing techniques as such unsuc-
21 cessful attempts create a discouraged user community, and less sophisticated
22 tools would be perceived as more viable solutions. Thus, it is important to un-
23 derstand what kinds of maps are suitable for automatic map processing and
24 what types of results and process-related errors can be expected. In this paper,
25 we shed light on these questions by using a typical map processing task, text
26 recognition, to discuss a number of map instances that vary in suitability for
27 automatic processing. We also present an extensive experiment on a diverse set
28 of scanned historical maps to provide measures of baseline performance of a
29 standard text recognition tool under varying map conditions (graphical quality)
30 and text representations (that can vary even within the same map sheet). Our
31 experimental results help the user understand what to expect when a fully or
32 semi-automatic map processing system is used to process a scanned map with
33 certain (varying) graphical properties and complexities in map content.

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34 **Keywords:** Digital Map Processing, Scanned Maps, Geographic Information
35 System, Text Recognition, Optical Character Recognition, Accuracy Assess-
36 ment

37 **1. Introduction**

38 Digital map processing refers to a set of techniques for converting map images
39 (created through scanning of paper maps or produced as electronic raster
40 maps) into the vector format. This conversion is usually the first step for incor-
41 porating geographic information encapsulated in maps (e.g., place names,
42 place types, build-up areas, contour lines) into a spatial-analytic environment,
43 such as a geographic information system (GIS). Since the early 80s, various
44 map processing systems (including both software and hardware tools) were
45 developed to facilitate manual map processing tasks. Today, the efficiency, ac-
46 curacy, and degrees of automation of map processing systems have been in-
47 creased considerably (concerning processing speed and the capability to pro-
48 cess a variety of maps and map features). The systems that are in place
49 nowadays can be classified by their capabilities into four categories: (1) Basic
50 raster-to-vector conversion tools with a minimum of automation (e.g., Esri
51 ArcScan²), which can be applied to a wide variety of map types with different
52 graphical conditions (by leveraging human vision), (2) Semi-automatic
53 systems, which provide some degrees of automation to reduce manual
54 digitization efforts (e.g., AutoCAD RasterDesign³), (3) Fully automatic systems
55 for processing a specific map type; this type-dependency often has the
56 disadvantage that the system relies on the user to fine tune the digitization
57 settings (requiring expert knowledge in image processing and graphics
58 recognition, e.g., Map Vectorizer⁴), and (4) Fully or semi-automatic systems
59 that are not limited to a particular map type but designed to extract only
60 specific types of map features (e.g., map labels (Chiang and Knoblock, 2014)).
61 The reader is referred to Henderson (2014) and Chiang, Leyk, and Knoblock
62 (2014) for detailed reviews on map processing techniques and systems.

63 Despite the exponential growth in computational power and advancement in
64 graphics recognition algorithms in the last decade, most fundamental

² <http://www.esri.com/software/arcgis/extensions/arcscan>

³ <http://www.autodesk.com/products/autocad-raster-design/overview>

⁴ <https://github.com/NYPL/map-vectorizer>

65 techniques that support automatic map processing such as color segmentation,
66 (map) layer separation, and object (or symbol) recognition are still limited
67 when processing low quality or complex map images (Cherkassky and Mulier,
68 1998; Cordella and Vento, 2000; Llados et al., 2002). These techniques are
69 sensitive to minor variations in graphical properties of the input image (e.g.,
70 different scanning parameters such as resolution) (Marr, 1982; Cherkassky and
71 Mulier, 1998) and usually require a priori knowledge of the map properties and
72 content (e.g., size of map objects, and cartographic styles). As a result, most
73 map processing systems would fail if the user does not "properly" prepare the
74 map document for processing and train and tune the underlying algorithms.
75 Since the general user rarely has expert knowledge of the underlying map pro-
76 cessing techniques, a map processing system is often perceived as a black box
77 that converts a map image into spatial data that are readily accessible in a GIS.
78 One significant implication is that after a few attempts to use a map processing
79 system, the user would give up if the results do not meet user expectations and
80 move to less sophisticated tools for manual raster-to-vector conversion. Not
81 only does this create a discouraged user community, but it also slows down
82 further development of advanced map processing techniques as less sophisti-
83 cated tools would be seen as more viable solutions.

84 Therefore, it is critical for a user to understand *what kinds of maps are suitable*
85 *for automatic (or semi-automatic) map processing and what types of re-*
86 *sults can be expected*. This directly relates to further questions concerning the
87 reliability and objectivity of accuracy assessments. Knowing how sensitive the
88 performance of map processing techniques will be based on variations in
89 graphical quality will inform the user how accuracy could vary across map
90 types and even within one map image in which target features may show differ-
91 ences in graphical properties. In this article, we shed light on such questions.
92 We choose a typical map processing task, text recognition, and discuss how the
93 degree of suitability for text recognition varies across map instances that differ
94 graphically. Furthermore, we carry out an experiment on text recognition in
95 scanned historical maps of various types and origins to demonstrate the impact
96 such variations can have on performance across different levels of graphical
97 quality. This experiment enables accuracy assessment of automatic text recog-
98 nition results for map labels in a variety of graphical conditions and provides a
99 guideline for estimating the suitability of a given map for automatic text pro-
100 cessing.

101 In the next section, we review various types of maps tested in the literature on
102 text recognition using automatic or semi-automatic map processing systems.

103 These maps carry different forms and types of text and show varying degrees of
104 complexity due to overlapping map layers and density of cartographic information.
105 Then we discuss in detail the most relevant properties of map images
106 affecting text recognition accuracy. Next, we introduce an automatic text
107 recognition system from our previous work (Chiang and Knoblock, 2014), and
108 describe an experiment on a set of scanned historical maps including Ordnance
109 Survey maps⁵ produced in the United Kingdom and several other maps
110 produced in the United States. The experiment demonstrates the baseline
111 performance of this text recognition system on maps with a variety of text
112 representations. We discuss how potential users can evaluate the suitability of
113 a map of interest for text recognition tasks. Finally, we present future outlooks
114 on how text processing in digital maps should further evolve to reach higher
115 degrees of automation and more robust recognition results.

116 **2. Common Map Types Subject to Automatic Text
117 Recognition and Related Accuracy Issues**

118 Text recognition from digital map images is one of the most common map pro-
119 cessing tasks, which determines the locations (e.g., bounding boxes or center
120 points) of text objects and generates machine editable strings for individual
121 text labels in the map (Ye and Doermann, 2014). A large number of studies on
122 text recognition in digital maps can be found in the literature (e.g., Nagy et al.,
123 1997; Velázquez and Levachkine, 2004; Gelbukh et al., 2004; Pouderoux et al.,
124 2007; Chiang and Knoblock, 2014; Simon et al., 2014). These studies in which
125 typically text labels are extracted from map images and incorporated into sub-
126 sequent processing steps of Optical Character Recognition (OCR) have a wide
127 range of applications such as building gazetteers, carrying out historical re-
128 search on location name changes or studying changes in the landscape and
129 land-use. In addition, extracting and removing map text can improve the
130 recognition of other geographic features such as cadastral boundaries (Cao and
131 Tan, 2002), vegetation features (Leyk et al., 2006), elevation contours
132 (Khotanzad and Zink, 2003) or roads (Li et al., 2000; Chiang and Knoblock,
133 2013).

134 A variety of map types that have been tested in the literature either for text
135 recognition or for removing map text labels include: cadastral or land register

⁵ <http://www.ordnancesurvey.co.uk/>

maps (e.g., Raveaux et al., 2008), road maps (e.g., Bin and Cheong, 1998; Itonaga et al., 2003; Dhar and Chanda, 2006; Bucha et al., 2007; Chiang et al., 2013; Chiang and Knoblock, 2013), hydrographic maps (e.g., Trier et al., 1997), city maps (e.g., Chen et al., 1999), utility maps (e.g., den Hartog et al., 1996), as well as topographic or other survey maps (e.g., Bessaïd et al., 2003; Miyoshi et al., 2004; Chen et al., 2006; Leyk et al., 2006; Leyk and Boesch, 2009; Xin et al., 2006; Henderson et al., 2009). We show several examples of the above map types in the next section to illustrate key characteristics and conditions relevant for text recognition in detail.

Most map processing systems cannot process different types of maps automatically, which is, in particular, true for text recognition. This is because maps have a complex layout in which text labels appear in various forms, colors and size categories, which requires manual identification of processing parameters and system training. Recent studies show an increasing potential to establish text recognition systems that provide reliable solutions across different types of maps, but their accuracy can vary significantly across map types (e.g., Chiang and Knoblock, 2014; Simon et al., 2014). Moreover, variations in text label characteristics (e.g., text color) can also occur within maps of the same types or even a single map page as a result of the scanning and image compression process, differences in map complexity, and inconsistencies of graphical quality in the original map (due to aging or bleaching). Thus, the same recognition method may perform differently in various parts of one map. Understanding such recognition sensitivities to variations in graphical properties can further improve the ability to forecast the potential for automatic text recognition and highlight possible recognition errors automatically. Importantly, this will also lead to realistic and objective accuracy assessments by differentiating graphical quality levels found among text labels in maps.

3. Key Characteristics Indicating the Potential for Automated Text Recognition in Maps

Much of the potential for a certain map to be processed with a high degree of automation is directly related to the number of studies that focus on this type of map (e.g., more studies exist on maps with Latin scripts compared to other languages). In this section, we present example maps of different types and discuss a variety of characteristics that can be used to estimate the suitability of

170 these maps for automatic text recognition and those that would indicate the
171 need for user intervention and manual digitization efforts.

172 The discussion is structured by the major characteristics of text labels and map
173 content: language (script), font, curvature and spacing, print and image qual-
174 ity, text color as well as map complexity. In general, the aim in most studies on
175 text recognition in maps is to detect, extract, and transfer text labels to an OCR
176 component, which then performs the final recognition process (Nagy et al.,
177 1997; Cao and Tan, 2000; Li et al., 2000; Velázquez and Levachkine, 2004;
178 Gelbukh et al., 2004; Pouderoux et al., 2007, Chiang and Knoblock, 2014).
179 How well map labels can be identified and recognized heavily depends on the
180 characteristics described below.

181 **3.1. Map Language**

182 Current OCR software packages, such as the open source Tesseract-OCR⁶ or
183 commercial ABBYY FineReader,⁷ support a wide range of language scripts, in-
184 cluding Latin, Chinese, Korean, Japanese, Hebrew, Arabic, and Indian scripts.
185 However, most of the text recognition work for processing raster maps is lim-
186 ited to Latin scripts, including Spanish (e.g., Gelbukh et al., 2004), French
187 (e.g., Pouderoux et al., 2007), and English (e.g., Chiang and Knoblock, 2014).
188 The main reason is that the document analysis techniques used for detecting
189 locations of text labels in maps are well developed for Latin scripts but less so
190 for other scripts. However, just as OCR progresses over the years from
191 handling only Latin scripts (Rice et al, 1995; Smith, 2007) to more complex
192 scripts, such as degraded Indian scripts (Shukla and Banka, 2014), we expect
193 further progress in developing automatic recognition methods that can handle
194 a variety of scripts in maps. Of course, the performance of text recognition
195 methods in maps with Latin script also depends on other graphical conditions
196 and map characteristics. Lower levels of general image quality will always im-
197 pact the extraction (e.g., coarse resolution images carry a limited potential for
198 automatic text recognition for any script).

199 **3.2. Map Fonts**

200 Maps with common typewritten fonts usually show the best results in automati-
201 c text recognition (Figures 1 and 2) compared to maps with less common fonts
202 (e.g., Fraktur, Antiqua) or stenciled and handwritten text. Text with uncom-

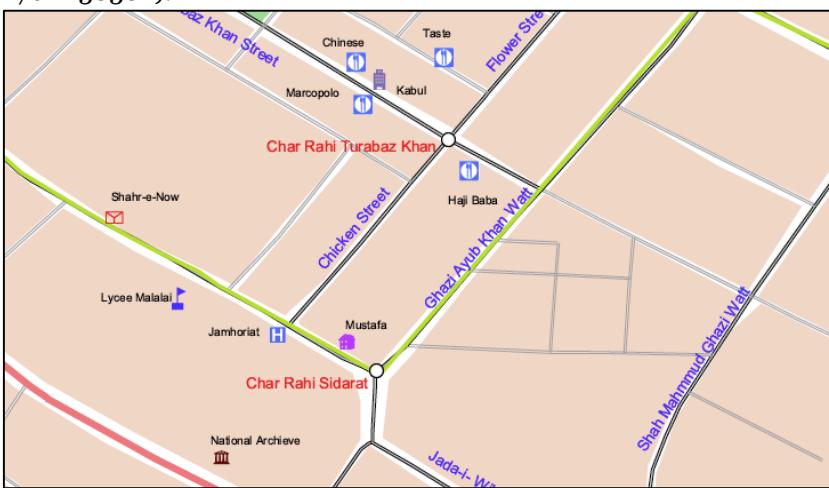
⁶ <https://code.google.com/p/tesseract-ocr/>

⁷ <http://finereader.abbyy.com/>

203 mon typewritten fonts requires additional training on specific character sets
204 and yields lower OCR accuracy (Helinski et al., 2012). Figure 3 shows an exam-
205 ple map with stenciled text. Historical maps are traditionally prepared with
206 manually written or stenciled text, which adds to the challenges in text recogni-
207 tion in older cartographic documents that can suffer from inferior graphical
208 quality and archiving effects (e.g., Gelbukh et al., 2004; Raveaux et al. 2007,
209 2008; Simon et al., 2014).



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211 **Figure 1.** An example of typewritten fonts in a scanned map for which OCR performs
212 well (Panama, USGS National Imagery and Mapping Agency (NIMA) ref. no.
213 E762X38382).



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215 **Figure 2.** An example of typewritten fonts in a computer generated map for which
216 OCR can perform well (Kabul city center, Afghanistan Information Management Ser-
217 vice).

218 **3.3. Character Spacing, Label Curvature and Orientation**

219 OCR software works most robustly if the input text labels are geometrically
220 straight (vertically positioned characters) with regular character spacing and
221 horizontal orientation. Such text labels also have a higher chance to be detected
222 automatically compared to labels with non-horizontal orientation (Figure 2),
223 curved labels (Figure 4) or labels with wide or irregular character spacing (Fig-
224 ures 3 and 5). Automatic systems often break curved labels and labels with
225 wide character spacing into separate string segments, which then require man-
226 ual post-processing to regroup these string segments (e.g., Velázquez and
227 Levachkine, 2004; Chiang and Knoblock, 2014).



228 **Figure 3.** Stenciled text in a historical map of Denmark.

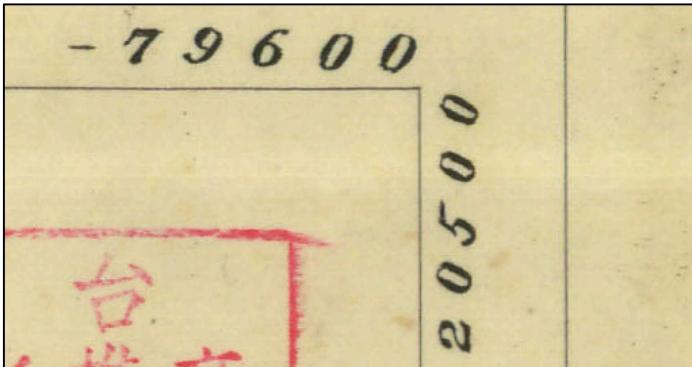
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231 **Figure 4.** Examples of curved labels in an Afghanistan map.

232 **Source:** United Nations

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Figure 5. Text labels with wide character spacing in a historical map of Taiwan.

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3.4. Print Quality

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In general, automatic map processing systems rely on superior print quality of the original paper maps with a minimum of blurring and false coloring to produce accurate results (Henderson, 2014; Chiang, Leyk, and Knoblock, 2014). However, old printing technology was limited in quality and the final printout often suffered from such problems. Print quality is often related to and can be further decreased through bleaching of the map as a direct consequence of aging paper material and the archiving practice. How sensitive the paper material can be to the archiving conditions becomes obvious in historical maps of more than 100 years of age (Leyk et al., 2006). Figure 6 shows an example of blurring and false coloring. The quality of a printed map also depends on the engraving techniques (e.g., stone and copper engraving) used to produce older maps. The transition to modern production techniques varies among countries. Unfortunately, the original plates used for engraving have been disposed in many cases making the paper maps the only sources left. In summary, the degree of blurring, false coloring, and mixed colors provides a strong indication of the potential of automated recognition on a given map. Text in maps often overlaps with other map layers (e.g., Figures 4 and 6), which makes text recognition particularly sensitive to such general printing quality issues.

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3.5. Image Quality

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State-of-the-art OCR software (e.g., Tesseract-OCR and ABBYY FineReader) requires an image resolution of the scanned input image of at least 300 dots-per-inch (DPI) to achieve the best results in “well-conditioned” documents (e.g., see Yin and Huang, 2001; Liu, 2002; Pouderoux et al., 2007). This number increases for maps of high density and complexity such as topographic

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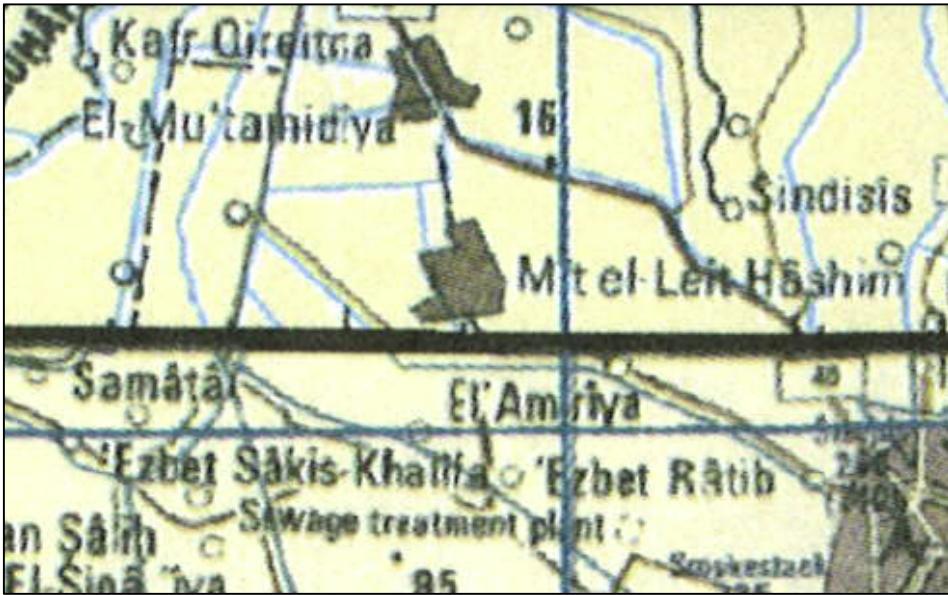
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maps (see Section 3.6). Figures 7 and 8 show a comparison of the text appearance in a map scanned with 150 DPI and 300 DPI, respectively. There are several instances in which images in digital map archives would be stored with a resolution too coarse to differentiate the smallest elements shown in a map. One of the main reasons is hardware limitations as scanners capable of scanning large format documents are expensive and scanning with high resolution is a time-consuming process. Since priority is generally given to a timely completion of a scanning project, such key parameters are often underestimated. As a guideline, the resolution of a scanned map image subject to automated information extraction should facilitate the graphical and visual distinction of the smallest entities in that map. This guideline relates to the concepts of resolution vs. detection in remote sensing imagery, i.e., to detect an object of a certain size the resolution has to be fine enough to be able to spatially and spectrally identify and characterize this object and reduce mixed pixel effects. Text in maps often has varying dimensions (i.e., line thickness) and thus represents a highly sensitive map element regarding resolution. Characters or character chains may become disconnected because thin object parts cannot be represented graphically with the pixel size given. In contrast, creating extremely high-resolution images may result in inefficient map processing. Also, a map image should not be processed by lossy image compression algorithms (e.g., JPEG⁸) as important structural elements become compromised and cannot be reproduced. Figure 9 illustrates how lossy compression of a map image results in pixelated map objects and increased color confusion.

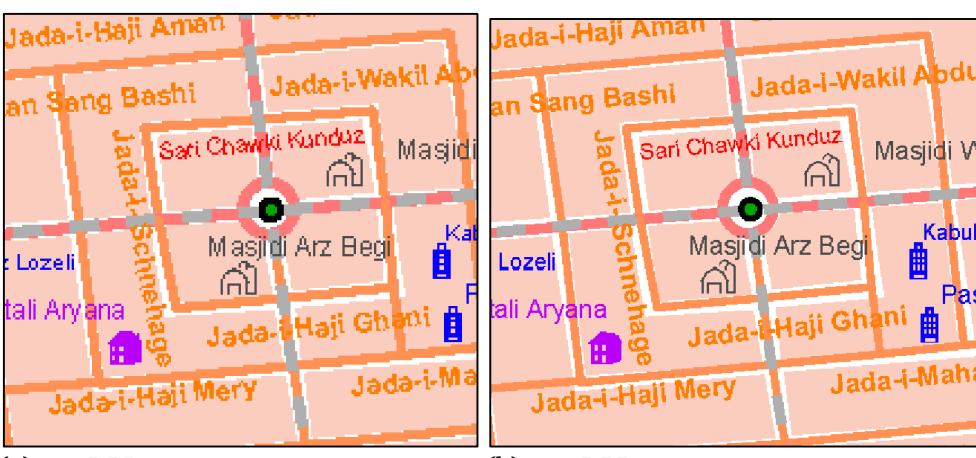
In addition to image resolution, the color encoding (if the map contains color layers) used for scanning and processing as well as the bit-depth of the image data are also important factors with regard to image quality. Color encoding is most relevant in preprocessing steps such as color image segmentation (Leyk, 2010; Leyk and Boesch, 2010) for generating clear character representations input to OCR (Chiang and Knoblock, 2014). Choices of color spaces include RGB (red, green, and blue), HSL (hue, saturation, and luminance), or CIE 1976 L*u*v. The bit-depth of the image indicates the maximum number of unique colors that can be represented in an image, which is important in recognition tasks in which objects to be distinguished are very similar in color. In most text recognition tasks, the use of 24-bit data during the scanning process is sufficient to produce clear text appearance (e.g., crisp character edges) for OCR.

⁸ <http://www.jpeg.org/>



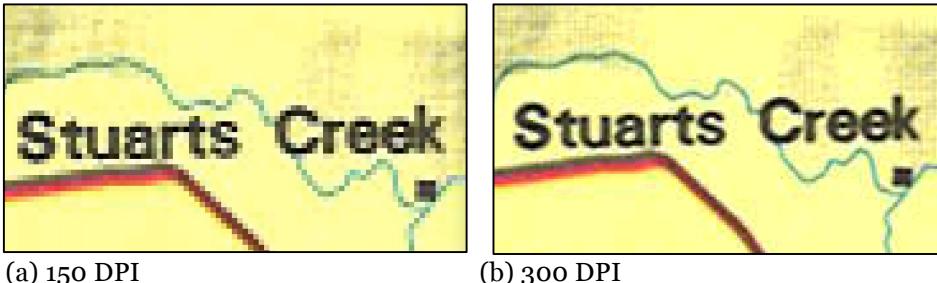
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Figure 6. An example of poor print quality in a NIMA evasion chart (EVC NH-36A, NIMA ref. no. EVCXXNH36A).



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Figure 7. Comparison of text appearance under different image resolutions (Kunduz city map, Afghanistan Information Management Service).



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Figure 8. Comparison of text appearance under different resolutions chosen for the scanning process; NIMA tactical pilotage chart (Australia, TPC Q-15A, NIMA ref. no. TPCXXQ15A).



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Figure 9. Low image resolution and lossy image compression compromise the appearance of text and map features (United Nations Environment Programme and United Nations Institute for Training and Research Operational Satellite Applications Programme map).

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3.6. Map Complexity

Maps can contain dense and overlapping map features (of the same or different color layers) and text (e.g., Figure 10), which makes map images a challenging document type for recognition tasks (Cordella and Vento, 2000; Llados et al., 2002). As a consequence, frequent instances of mixed colors and merged map objects may occur impeding the identification or separation of features or symbols. For highly complex maps, such as topographic maps, an image resolution of at least 500 DPI has been demonstrated suitable in recent research (e.g., Li et al., 2000; Liu, 2002; Leyk and Boesch, 2009; Chiang et al., 2014) in order to ensure that map processing techniques (including text recognition) produce robust results. Issues of image and print quality (as described above) in combination with map complexity can be found in historical maps, which therefore

represent particularly challenging documents for recognition tasks including text recognition (Simon et al., 2014).

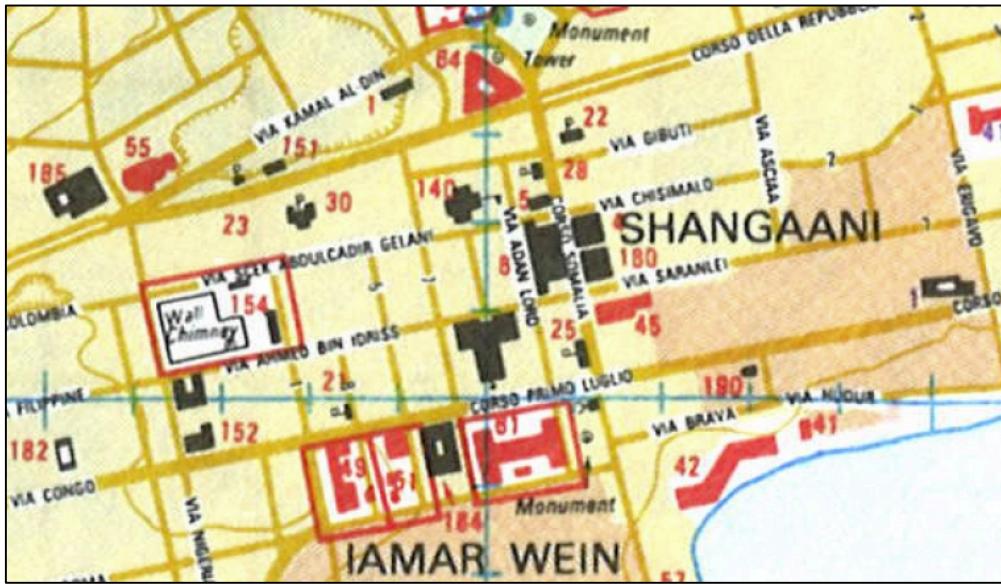
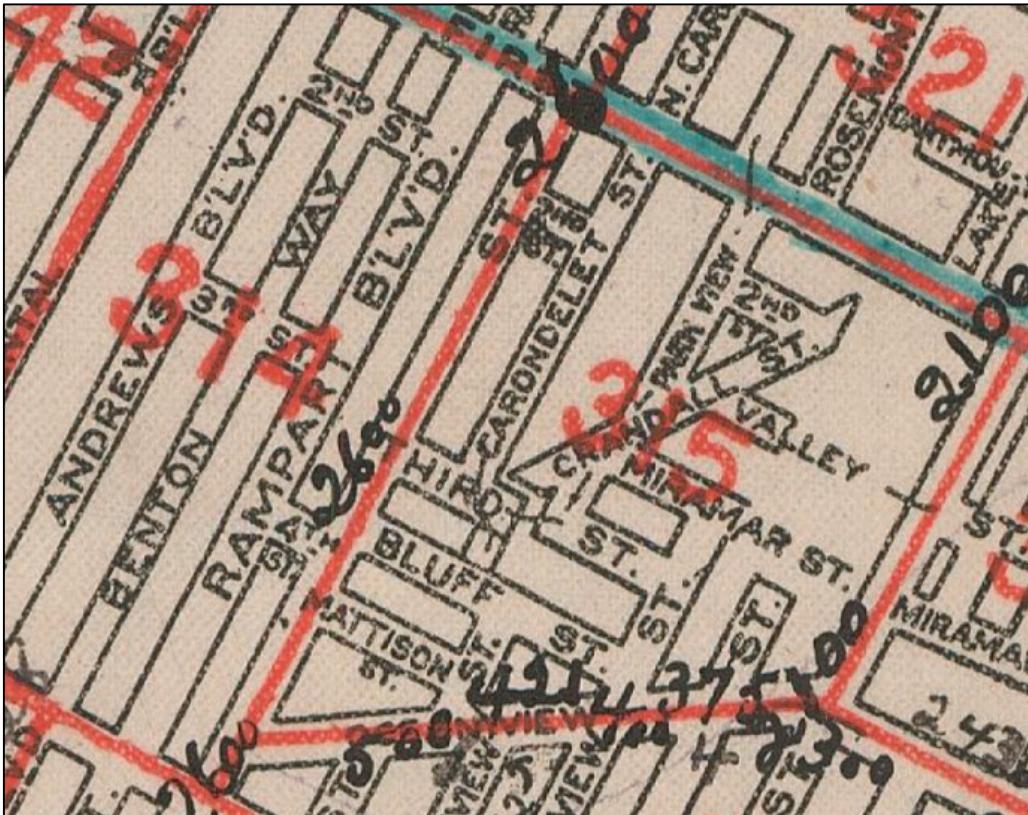


Figure 10. A sample map with complex and dense content, text with small fonts and in different colors (Muqdisho, Somalia, NJMA ref. no. EVTXXXMUODISHO).

3.7. Color of Map Features

Ideally, map features of the same type should have a distinct color avoiding merging and color mixing effects as mentioned above under print and image quality. However, Figure 11 shows one of many examples where the text labels and the road edges are both drawn in black. In this case, the recognition task would likely require manual post-processing for recovering the text labels that overlap with road edges. Even if text color would be different from other map layers, there may still be significant problems regarding color variations and mixed colors, i.e., colors may not be clearly differentiated everywhere as an issue of print quality. Image quality issues (e.g., bleaching, blurring, resolution, and color space used for scanning) may add to these points. In general, if text appears in the same color as other map layers, the success of text recognition will depend on the degree of complexity of the map and the frequency of overlaps between these layers.



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350 **Figure 11.** Both text and roads are drawn in black color; red precinct boundaries and
black text labels overlap resulting in mixed colors (1920 Los Angeles precinct map, Los
Angeles City Archive).

351 **4. Data and Experimental Setting**

352 This section describes the tested map products, the characteristics of the map
353 content (including map labels), and the test system.

354 **4.1. Tested Map Products and Their Characterization**

355 To demonstrate the differences in text recognition outcomes under varying
356 graphical conditions and text properties as discussed in Section 3, we tested the
357 performance of a text recognition tool for six different map products (Table 1),
358 including the 1920 6-inch Ordnance Survey topographic maps from the

359 National Library of Scotland,⁹ and United States historical railway, auto road
360 and mileage maps from the David Rumsey Map Collection.¹⁰

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362 **Table 1.** The metadata of the six tested map products.

Map Title / Coverage	DPI (approx.)	Map Scale	Publisher	Date
Ordnance Survey Six-inch Map, London, U.K.	406	1: 10,560	Ordnance Survey	1920
Cram's Railroad and Township Map, Florida ¹¹	336	1: 1,330,560	Cram Atlas Company	1875
Map of the Northern Pacific Railroad and connections ¹²	302	1: 7,500,000	Rand McNally	1879
Map Of Missouri, Showing Line and Land Grant of the St. Louis & San Francisco Railway ¹³	304	1: 1,966,700	Woodward, Tiernan & Hale	1879
Auto Road Map, Colorado ¹⁴	402	1: 1,700,000	Rand McNally	1927
Black and White Mileage Map, South Dakota ¹⁵	379	N/A	Rand McNally	1924

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364 Within several map pages from the Ordnance Survey six-inch map series of the
365 U.K., we tested ten map subsections near London each covering 1,000 x 1,000
366 square meters in the TQ grid (the British National Grid), equal to 1,512 x 1,512
367 pixels. For each of the historical U.S. maps, we selected one map subsection
368 ranging from 753 x 665 to 1,176 x 1,121 pixels for testing. Figures 12-18 show
369 examples of the test maps, which represent a wide range of variations in map
370 conditions and labeling styles. Based on the criteria relevant for text recogni-
371 tion (see Section 3), text labels in these maps can be characterized as follows:

⁹ <http://maps.nls.uk>

¹⁰ <http://www.davidrumsey.com>

¹¹ <http://www.davidrumsey.com/luna/servlet/s/81sbj5>

¹² <http://www.davidrumsey.com/luna/servlet/s/gev3rb>

¹³ <http://www.davidrumsey.com/luna/servlet/s/qlo120>

¹⁴ <http://www.davidrumsey.com/luna/servlet/s/1oscg7>

¹⁵ <http://www.davidrumsey.com/luna/servlet/s/8g46i4>

372 **Map Language and Fonts:**

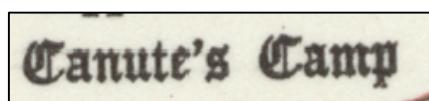
373 The Ordnance Survey maps have Latin scripts (English) and use common fonts
374 with the exceptions of some special locations (Figures 12 and 13). The other
375 historical maps have Latin scripts (English) and use uncommon fonts (likely
376 stenciled text) varying within the same map (Figures 14 – 18) (see Section 3.2).



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378 **Figure 12.** An example area of the tested Ordnance Survey map (TQ) (see Table 1).

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381 **Figure 13.** An example of an uncommon font in the Ordnance Survey maps.

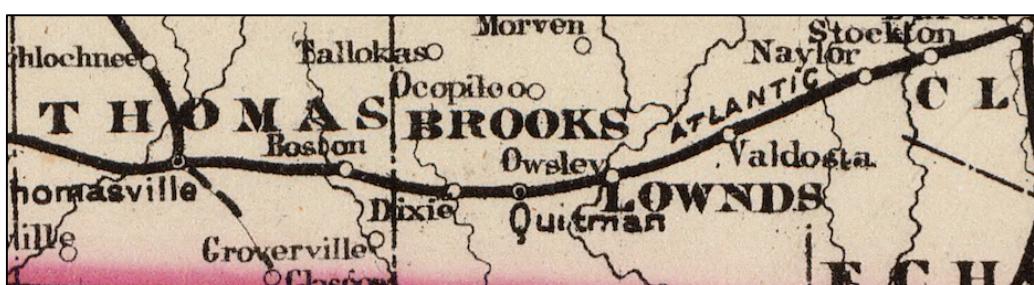
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383 **Print and Image Quality:**

384 The test map subsections are relatively free from print quality issues (discussed
385 in Section 3.4) with the exceptions of the Map of Missouri that shows a visible
386 fold line (Figure 15), and three other U.S. maps that were scanned out of books
387 and show bleed-through from the back side (Figures 15 – 17). The image format
388 of the test maps is TIFF without lossy compression. The exact scan resolutions
389 of the original maps were not available. We estimated the image resolutions
390 using the dimensions of the scanned images in pixels and the available sizes of
391 the map documents in inches. The estimated resolution for every test map was
392 higher than 300 DPI (Table 1). To test the impact of decreasing image quality
393 for text recognition, we manually scaled the image dimensions of each map to
394 165%, 132%, 66% (medium), 50% (low), 33%, and 17%, respectively, using the
395 bicubic interpolation. This interpolation method was carried out to simulate
396 different image resolutions and possible compression defects combined. Note
397 that when the map image was scaled up using the bicubic interpolation (165%
398 and 132%), the DPI of the image did not increase. Our goal was to use these
399 enlarged images to simulate the map content scanned at a higher DPI (e.g.,
400 larger font sizes and wider character spacing). We tested the performance of
401 text recognition in all 15 map sections for each image quality level.

402 **Label Curvature and Character Spacing, Map Complexity, and Color
403 of Map Features:**

404 The map layers of most maps tested are primarily represented in black (often
405 blurred) color except for the contour lines, hydrography, and railroads. Other
406 characteristics (label curvature, spacing, and map complexity) showed great
407 variation among the test maps and were therefore (together with above charac-
408 teristics) used to divide the map labels into three groups of general map prop-
409 erties relevant to recognition accuracy. These groups are described in the next
410 subsection.



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Figure 14. An example area of the tested Cram's Railroad and Township Map, Florida (see Table 1).

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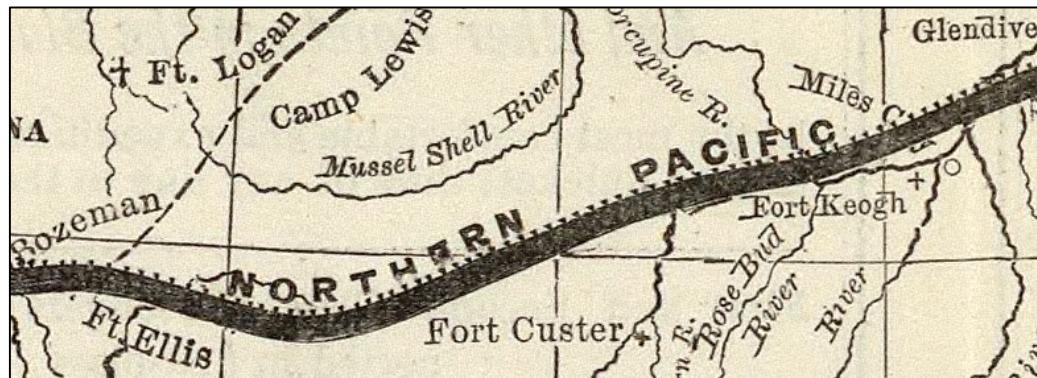


Figure 15. An example area of the tested Map of the Northern Pacific Railroad and connections (see Table 1).

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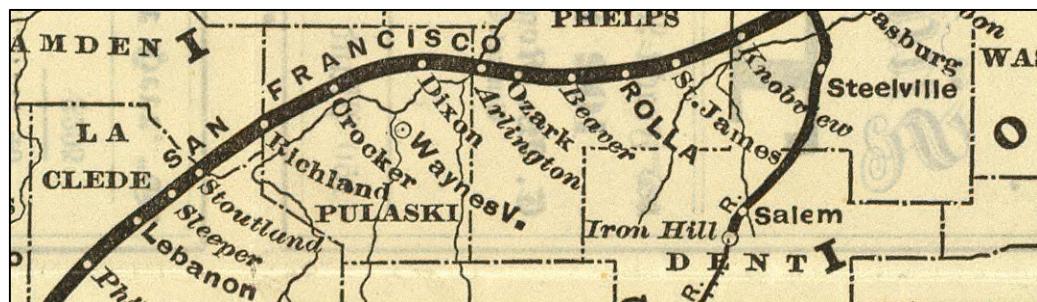
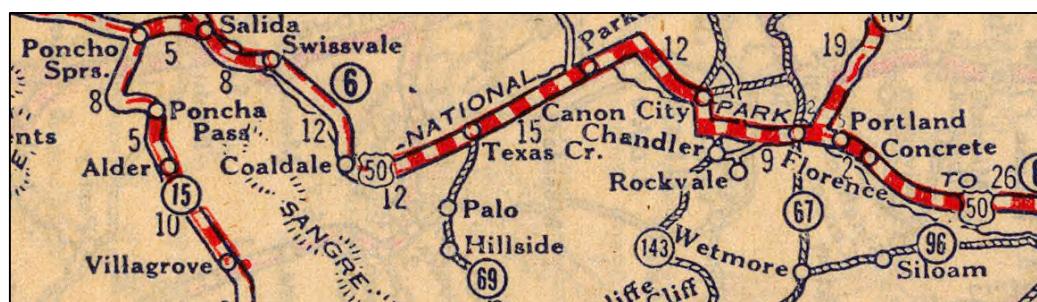


Figure 16. An example area of the tested Map Of Missouri, Showing Line and Land Grant of the St. Louis & San Francisco Railway (see Table 1).

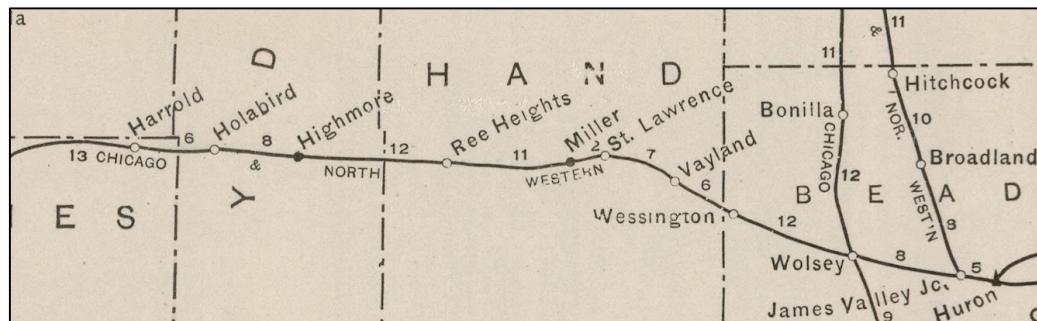
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Figure 17. An example area of the tested Auto Road Map, Colorado (see Table 1)..

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Figure 18. An example area of the tested Black and White Mileage Map, South Dakota (see Table 1).

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4.2. Groups of Text Representations Based on Map Characteristics

Here, we define three groups of text representations of varying quality based on general map characteristics relevant to recognition. Each group contains characters in different sizes. Characters with a larger font size do not guarantee to have better recognition results than characters with a smaller font size in a map despite the common expectation that large font size would provide advantages for recognition similar to higher resolution. This is because map text that contains characters with larger font size typically shows wider character spacing, which makes processing this text label very difficult independently on resolution (Section 3.3). The recognition results of each group in Section 5 will demonstrate the impact of the map properties discussed in this article on the recognition accuracy.

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Group 1 “suitable” (with high suitability for text recognition):

These are mostly clear and clean (unblurred and saturated) text labels with characters that are in either common, uncommon, or stenciled fonts, do not overlap with other map features, are not surrounded by or close to groups of non-text features, are only slightly curved or multi-oriented, or have regular or slightly wider (than usual) character spacing (Figure 19).

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Group 2 “processable” (with moderate suitability for text recognition):

449 These are text labels that are slightly distorted, moderately curved, or may be
450 surrounded by or close to (but not overlapping with) one or more non-text ob-
451 jects similar in size compared to a character (e.g., tree symbols) (Figure 20).

452 **Group 3 “unsuitable” (with low suitability for text recognition):**
453 These are text labels with characters that overlap with non-text objects (Figure
454 21), are significantly curved¹⁶ (Figure 22), or have wide character spacing (Fig-
455 ure 23).



Figure 19. Example labels that are highly suitable for text recognition (Group 1).

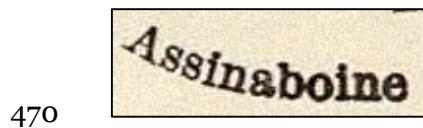
¹⁶ A word that deviates more than 30% from a straight label (Chiang and Knoblock, 2014)



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Figure 20. Example labels that are in noisy areas where nearby non-text symbols
(e.g., trees, terrain features, circular symbols) could mislead the text detection and
recognition algorithms (top), are slightly distorted or moderately curved (bottom)
(Group 2).

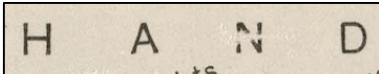


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Figure 21. Example labels that overlap with other feature layers (Group 3).



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471 **Figure 22.** An example text label that deviates more than 30% from a straight
472 label (Group 3).



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474 **Figure 23.** An example label that has a wide character spacing (Group 3).

475 **4.3. A Brief Description of the Text Recognition Method Used**

476 In order to conduct the experiment we used an open source text recognition
477 tool, Strabo, developed in our previous work (Chiang and Knoblock, 2014)¹⁷
478 that has been tested with a variety of map types (Chiang et al., 2014; Fernandes
479 and Chiang, 2015; Honarvar Nazari et al., 2015). Strabo is a semi-automatic
480 tool that can be trained by a user for processing a map of a certain type for text
481 recognition. Strabo has two main components: (1) A text detector that exploits
482 cartographic labeling principles to identify text pixels, groups the identified
483 text pixels into characters, and then merges characters into text strings, and (2)
484 A text recognizer that automatically determines the orientation of each
485 detected string using a skew detection algorithm, rotates the string to the
486 horizontal direction, and then uses Tesseract-OCR to convert the horizontal
487 labels to machine-readable datasets. A detailed technical description of Strabo
488 can be found in our previous publication (Chiang and Knoblock, 2014).

489 Recent efforts on integrating the text recognition capabilities in Strabo with a
490 GIS (Chiang et al., 2014; Fernandes and Chiang, 2015) attempt to establish an
491 end-to-end map digitization process from text label detection to OCR to result
492 curation within a single software platform. This direct transition eliminates the
493 need for manual data export/import procedures between GIS and OCR soft-
494 ware and facilitates a broader use of such technologies in applied research (e.g.,
495 extracting historical location names from maps to better understand landscape
496 conversions).

497 To train Strabo, the user delineates an example area that contains a map label.
498 Then Strabo detects text pixels in the example area and learns the colors that
499 represent text in the map.¹⁸ In this experiment, since the text layers are primar-
500 ily in black, we did not need to train Strabo. We used manually identified color

¹⁷ <https://github.com/spatial-computing/strabo-command-line-pub>

¹⁸ Details of Strabo training steps and demonstration videos can be access from <http://spatial-computing.github.io/#projects>

501 thresholds to extract the black layer from the Ordnance Survey maps. We used
502 an automatic color binarization method (Bradley and Roth, 2007) to extract
503 the black layers from the other test maps to save manual effort. Both the man-
504 ual and automatic color binarization methods generated clear text layers.

505 In this comparative study we used parameter settings for running processes in
506 Strabo as suggested in Chiang and Knoblock (2014) without parameter tuning
507 for each test map, as follows:

508 - Two text pixels can only be connected to one another if they are in direct ad-
509 jacency.

510 - A character can only be connected to another character (for constituting a text
511 label) if the ratio of sizes between the two characters (larger character divided
512 by the smaller character) is less than two. The size of a character refers to the
513 character width or height whichever is larger.

514 - In a text label, the space between two connected characters is less than $1/5$ of
515 the size of the larger character.

516 - A text label that is curved and deviating more than 30% from a straight label
517 (i.e., 234 degrees) will be broken into shorter labels for recognition.

518 As mentioned, the above steps in Strabo did not require training. For character
519 recognition, we used the Tesseract-OCR engine with its default training data
520 for English script without any additional training on the map font. To demon-
521 strate the impact of pure map characteristics on text recognition, we did not
522 use a dictionary to post-correct the results.

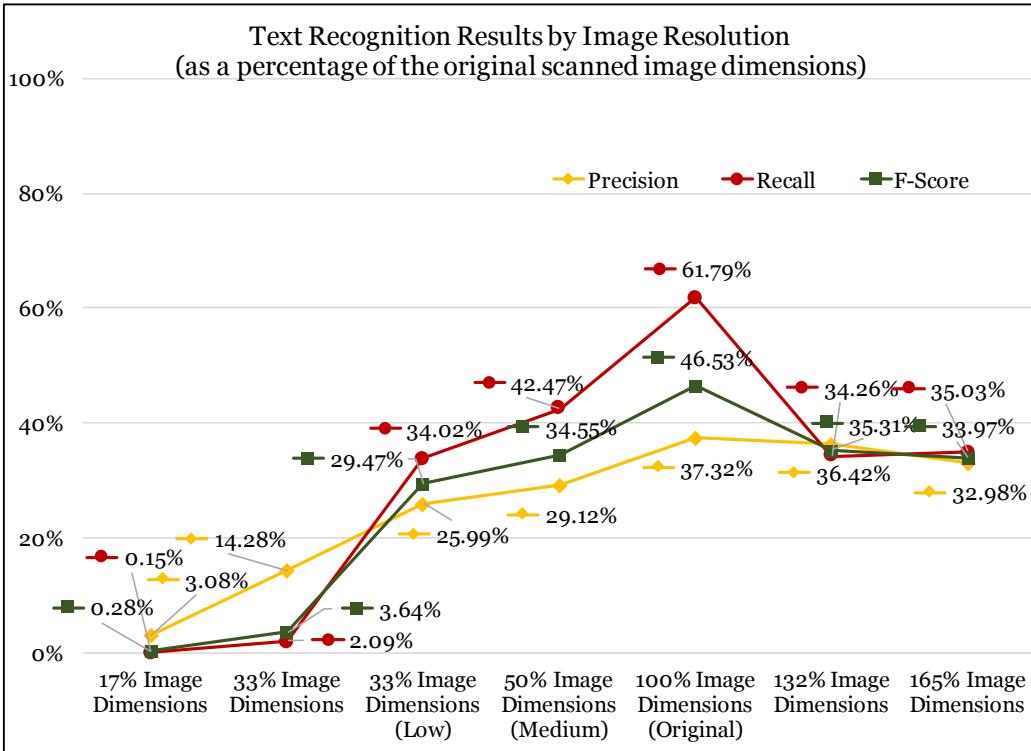
523 **5. Experimental Results and Discussion**

524 We manually transcribed text labels in the test maps and identified their suita-
525 bility for text recognition (i.e., groups) to create the ground truth for validating
526 the experiments.¹⁹ The 15 test areas from the six map products of various types
527 contain a total of 5,700 characters. The overall character-level precision, recall,
528 and F-Score (the harmonic mean of precision and recall) for the original reso-
529 lution were 37.32%, 61.79%, and 46.53%, respectively. All three measures
530 dropped when the image resolution was reduced (Figure 24). Precision, recall,

¹⁹ Test maps and ground truth are available at: <https://github.com/spatial-computing/map-ocr-ground-truth>

531 and F-Score dropped with decreasing resolution (e.g., the F-Score decreased by
532 11.98% from the original to the medium resolution and by 5.08% from the me-
533 dium to the lowest resolution). The F-Score dropped to a mere 0.28% when the
534 image was resized to 17% of the original dimensions. Recall dropped sharply
535 from 61.79% to 42.47% from the original to the medium resolution. The main
536 reason for this observation is that after the first bicubic resampling, the resolu-
537 tion of every test map was lower than 300 DPI, which represents a critical
538 benchmark for OCR (See Section 3.5) in general. Furthermore, resampling in-
539 troduces noise that reduces graphical quality such as character clarity. This
540 type of noise is similar to the type of error that can be introduced during the
541 original sampling stage (scanning). Also, if the resampling process incorporates
542 a lossy compression algorithm, the medium- and low-resolution images would
543 show even nosier character representations and would have a lower recognition
544 rate.

545 Figure 25 shows two example results. In these instances, Strabo detected the
546 text locations correctly at all resolution levels, but Tesseract-OCR could not
547 recognize some of the characters in the medium- and low-resolution images.
548 Comparing the two cases, although “Wolsey” has a wider character spacing it
549 has a cleaner representation (fewer smudges and bleedings) than “MADISON”
550 in the original image. Therefore, when the image resolution was reduced to less
551 than 300 DPI, the OCR tool showed a better recognition result for the down-
552 sampled text label “Wolsey” than for “MADISON”.



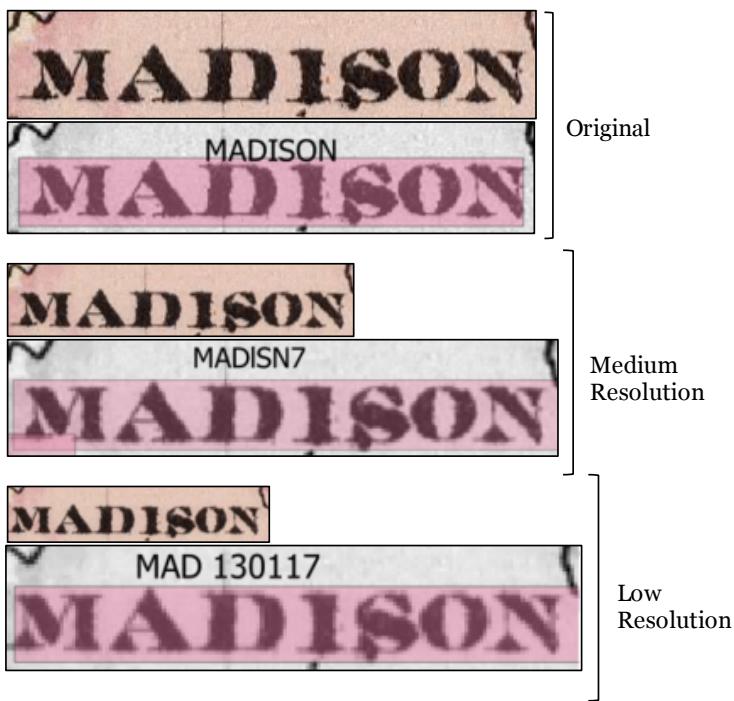
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Figure 24. Experimental results by image resolution level

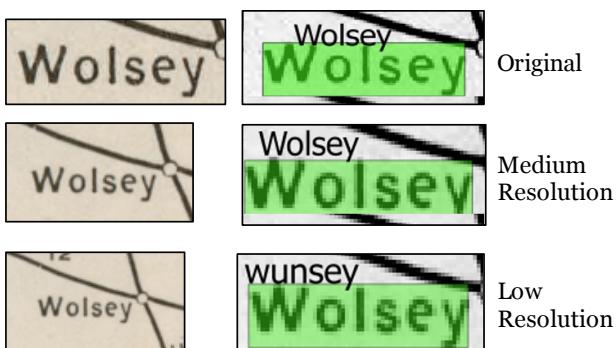
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Table 2 shows the character-level precision, recall, and F-Score for each character group (groups 1-3; see Section 4.2) at each of the tested image dimensions, including the original, medium, and low resolutions. Group 1 contains 2,024 characters (35.51% of the total number of characters). Group 2 contains 896 characters (15.72% of the total number of characters). A closer look at the results for Group 2 reveals that non-text objects near existing words could be incorrectly detected as characters and hence a text label could be incorrectly broken into several parts (Figure 26). Also, it should be noted that the F-Score of Group 2 in the original resolution was close to the F-Score of Group 1 in the medium resolution. This illustrates that an improperly prepared map scan could largely reduce the prospect of using an automatic/semi-automatic map processing tool even if the map labels were clean, clear, and noise-free. In addition, when the resolutions were lower than 300 DPI, non-text objects were more likely to be grouped with nearby characters, so the precision of Group 2 was even lower than Group 3 in both the medium and low resolutions.

570 The third group contains 2,780 characters (48.77% of the total number of char-
571 acters). In the experiment, this group included mostly text labels that overlap
572 with (or touch) other map features (e.g., lines) or appear significantly curved.
573 Strabo employed a recent method for detecting text labels overlapping with
574 other features (Honarvar Nazari et al., 2016), but such overlaps still pose a ma-
575 jor difficulty for OCR. As expected, Group 3 had the lowest values for recall and
576 F-Score across the three image resolutions.



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578 (a) The label “MADISON” in the test map of Florida



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580 (b) The label “Wolsey” in the test map of South Dakota

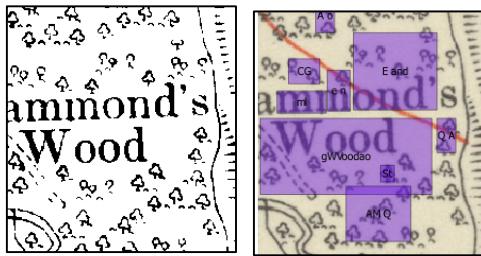
581 **Figure 25.** Comparison of text recognition results for the same text label at three dif-
582 ferent image resolutions for two cases. The color images (top in (a) and left in (b)) show
583 the map labels. The purple (a) and green (b) areas in the result images (bottom in (a)
584 and right in (b)) are the Strabo-identified text locations. The black characters on top of
585 the identified locations are the recognition results.

586 **Table 2.** Experimental results by character groups and image resolutions.

Image Dimension and Character Groups	Precision	Recall	F-Score
165% of the original image dimensions			
Group 1	41.31%	51.55%	45.87%
Group 2	24.56%	41.02%	30.72%
Group 3	28.82%	21.07%	24.34%
132% of the original image dimensions			
Group 1	44.74%	47.65%	46.15%
Group 2	27.84%	38.41%	32.29%
Group 3	32.71%	23.18%	27.13%
Original image (original resolution)			
Group 1	47.55%	83.50%	60.60%
Group 2	29.57%	71.65%	41.87%
Group 3	32.05%	42.81%	36.65%
66% of the original image dimensions (medium resolution)			
Group 1	37.32%	57.91%	45.39%
Group 2	20.46%	46.43%	28.41%
Group 3	26.51%	29.96%	28.13%
50% of the original image dimensions (low resolution)			
Group 1	31.30%	40.51%	35.31%
Group 2	16.84%	31.92%	22.05%
Group 3	23.07%	20.79%	21.87%
33% of the original image dimensions			
Group 1	19.02%	4.34%	7.07%
Group 2	4.28%	0.26%	0.49%

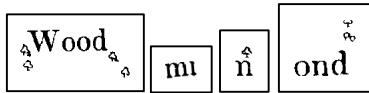
Group 3	9.09%	1.04%	1.86%
17% of the original image dimension			
Group 1	1.67%	0.06%	0.13%
Group 2	0.00%	0.00%	0.00%
Group 3	3.65%	0.26%	0.48%

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589 (a) The detected text labels (text is part of the black layer) in purple boxes and the
 590 recognition results (the text labeled inside the purple boxes in Arial)



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592 (b) Four of the detected text areas

593 **Figure 26.** A noisy text area (Group 2) and the text detection and recognition results
 594 for these characters and strings are shown.

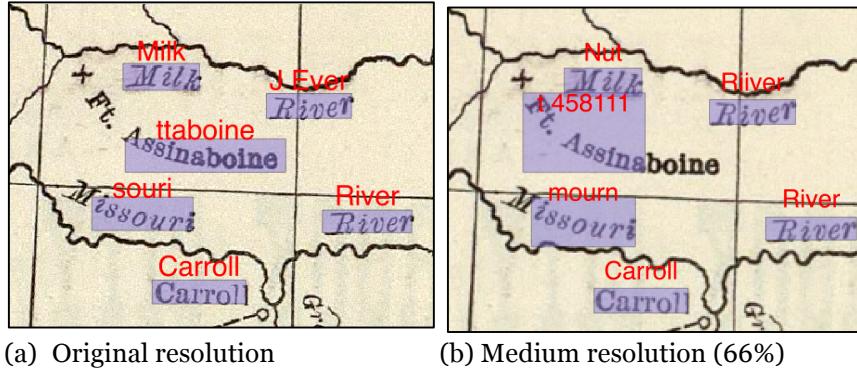
595 Further, when the image dimension was increased (132% and 165%), the
 596 recognition results showed a decrease in all accuracy measures compared to
 597 the results from the original resolution. This shows that after scanning, we
 598 could not add more information (i.e., to increase the DPI) to the map image for
 599 improving the recognition results (by upscaling the image). Table 2 also shows
 600 that when the image resolution dropped to 17% of the original resolution (less
 601 than 100 DPI), we could not correctly detect any character in Group 2. This was
 602 due to the fact that beyond 100 DPI, most of the characters became too blurry
 603 to be detected after the bicubic resampling.

604 Figure 27 shows some example recognition results for text labels from every
 605 group at the three different resolutions. The word “Milk” was only correctly
 606 recognized in the original resolution. The uncommon character style of “Milk”
 607 resulted in poor OCR results when the resolution decreased. The curved words

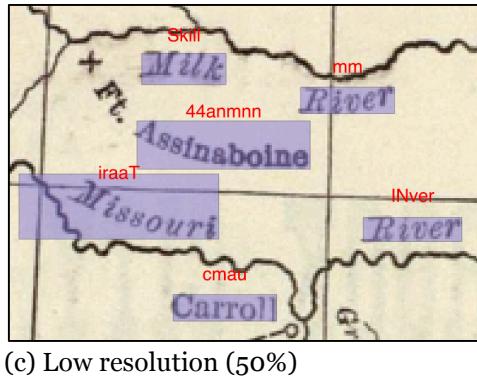
608 “Ft. Assinaboine” and “Missouri” were broken into smaller parts during the
609 text detection steps, so only parts of them were recognized by OCR. Moreover,
610 curved strings were difficult for OCR to process. As an example, all characters
611 except one of the detected label “Ft. Assina” in the medium resolution were
612 recognized incorrectly. As can be seen in Figure 27(c), when the resolution was
613 reduced, Tesseract-OCR was unable to correctly segment individual characters
614 in a detected label because the character spacing was too small. For example,
615 the word “Caroll” was recognized as “cmau” in the low-resolution image be-
616 cause Tesseract-OCR grouped some adjacent characters as single characters.
617 Also, the characters “Ri” in the lower occurrence of the label “River” were in-
618 correctly segmented into the two characters “IN”. The problem of erroneous
619 character segmentation becomes more problematic when a word overlaps with
620 other map features. For example, the characters “Ri” in the top occurrence of
621 the label “River” were incorrectly segmented into the three characters “J E” in
622 the original resolution because of the grid line between “R” and “i”. When the
623 resolution decreased to medium, the characters “Ri” were segmented into “Rii”
624 because the number of pixels between “R”, the gridline, and “i” were smaller
625 (than in the original) and hence the space character was not in the recognition
626 result.

627 As can be seen in Table 2, even when a map was carefully prepared (scanned)
628 such that high levels of image quality could be warranted, significant chal-
629 lenges remain in recognizing map text in a fully automated setting due to the com-
630 plexities and variations in map properties. These graphical properties, here of
631 characters and text labels, could even vary considerably across one map sheet,
632 and the performance of map processing techniques directly relates to such
633 properties. Such variations would remain hidden if accuracy would only be
634 assessed over all labels as a whole without distinguishing between levels of
635 graphical quality, feature representations, and map products. If incorporated
636 into accuracy assessments this knowledge provides a more objective basis to
637 estimate the suitability of a considered map for automatic processing (e.g., text
638 recognition). For example, if the vast majority of characters or text labels in the
639 map of interest belong to Group 1 and the resolution satisfies basic benchmarks
640 for robust OCR performance the user could expect a good potential for auto-
641 mated or semi-automated map processing. In contrast, if most characters
642 would be categorized as Group 3 the potential for automation would be ex-
643 pected to be very low without further tuning or training. This potential would
644 be expected to further decrease for lower levels of image resolution.

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Figure 27. Example text labels and their recognition results (text labels in red) across the three test image resolutions. The images of the medium and low resolution are enlarged here to better illustrate the results. The labels “Milk” (deformed characters), “River” (top, overlapping with a grid line), “Ft. Assinaboine” (curved over 30%), “Missouri” (overlapping with the grid line and curved over 30%) belong to Group 3. The label “River” (bottom right, uncommon font) belongs to Group 2 and the label “Carroll” is an example of Group 1.

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Overall, in the described experiments additional OCR training and incorporating and tuning symbol recognition algorithms to remove non-text objects would likely improve the recognition accuracy in Groups 1 and 2 but still require user intervention to some degree. In Group 3, additional text/graphics separation techniques and dictionaries could be used to recover overlapping text in the OCR step, but this would require great amounts of effort by the user. For example, in a string “House”, if the character “s” was removed due to overlapping features and “Hou e” was recognized, a dictionary containing the word

664 “House” could facilitate the reconstruction of the full word. Finally,
665 crowdsourcing approaches such as CAPTCHA²⁰ could be used to scale up the
666 result curation task and make it possible for an organization or user to process
667 large volume map series with reasonable degrees of efficiency.

668 **6. Summary and Outlook**

669 This article discussed a variety of criteria to evaluate the suitability of scanned
670 and digitally produced maps for automatic map processing using text recogni-
671 tion as the target application. This discussion fills an important gap in the liter-
672 ature which to-date has not seen an explicit and systematic assessment of the
673 potential impacts of graphical quality issues on automatic or semi-automatic
674 map processing tasks. The usefulness of the map/text criteria was demon-
675 strated in an extensive experiment to test a common text recognition tool for maps,
676 Strabo, for different map products at varying image resolutions. The results for
677 each resolution were assessed, separately, for three groups of text representa-
678 tions defined based on the graphical characteristics of map text. This study is
679 meant to support potential users of map processing tools to better understand
680 (1) whether or not the map images of interest are suitable candidates for higher
681 degrees of automation in map processing, (2) how much user intervention
682 would be required and (3) how much variation in methods performance and
683 thus in intervention needs can be expected. We view this article as a first step
684 to systematically evaluate the potential to successfully process different maps
685 and map series using an automatic or semi-automatic recognition system. Such
686 a state-of-the-art introduction manual, here focused on text recognition, will
687 help users interested in applying digital map processing systems to better
688 understand current possibilities from the perspective of graphical quality and
689 inherent uncertainty. This discussion could be further extended to other pro-
690 cessing techniques such as line detection or symbol recognition in scanned
691 maps.

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694 ern California under the Undergraduate Research Associates Program (URAP).

²⁰ <http://www.captcha.net/>

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696 ment ground truth and Ronald Yu for managing the Strabo GitHub repository.

697

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