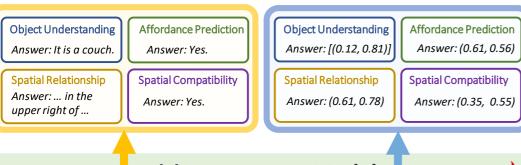
Stage1: Spatial Coordinate Bi-directional Alignment



Vision-Language Model



Coordinates Understanding



What object is at (0.12, 0.81)?



Is (0.1, 0.8) navigable for a mobile robot?

Spatial Compatibility

Collision after moving

object from (0.2, 0.3)

to (0.3, 0.5)?

Spatial Relationship

The relationship between objects at (0.3, 0.1) and (0.5, 0.5)

Coordinates Generation



Detect all the couches in the image.



Generate a navigable point for a robot.

Spatial Relationship

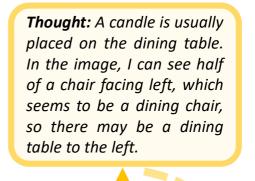


Point out the object located to the right of the notebook.

Spatial Compatibility

Generate a collisionfree location for the notebook.

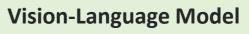
Stage2: Chain-of-Thought Spatial Grounding



Rationale

Action

Action: I would go to (0.15, 0.82) to find the candle.





Input Image

Given the image, where would you go to find a candle?

Chain-of-Thought Spatial Grounding

Instruction