

Generalized sparse linear algebra framework for multi-GPU computations

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Introduction

Sparse linear algebra framework:

- Practical problem solving
- High-perforce libraries
- Values' types and functions
- Primitives: matrix, vector, scalar
- Operations: mxm, vxm, mxv, assign, reduce, transpose

Note 1: practical data is sparse Note 2: practical data is large

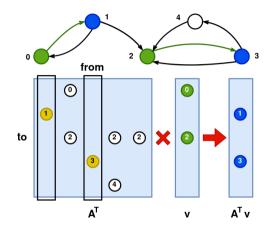


Figure: Graph traversal by matrix-vector multiplication

Applications

Algorithms

- Breadth-first search
- Shortest paths
- Maximal independent set
- ► Page rank
- ► Triangles counting
- Regular/CFL-reachability

Analysis tasks

- ► Static code analysis
- ► Graph database queries
- Bioinformatics

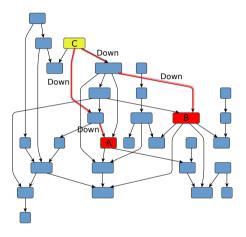


Figure: Navigational query $\overline{\mathbf{Down}}^n \mathbf{Down}^n$ for CFL-reachability

Background

- GraphBLAS
 - Mathematical notation translated into an C API
- GraphBLAS:SuiteSparse
 - GraphBLAS reference implementation
 - CPU-computations & high-performance
- GraphBLAST
 - ► CUDA C++ template based
 - Under-development | abandoned
- cuSPARSE, clSPARSE, bhSPARSE, GALATIC, cusp
 - General-purpose sparse linear algebra libraries
 - ► Under-development | outdated | single-GPU
- SPbLA, cuBool
 - ► OpenCL | CUDA | CPU
 - ► Single-GPU & optimized & boolean values only



GRAPHBLAS

Figure: GraphBLAS project logo (picture from graphblas.org)

Project: motivation and tasks

Motivation

- No complete and ready for usage GPU GraphBLAS implementation
- Existing math libraries limited in customization
- ► No multi-GPU support

Idea

- Generalized sparse linear algebra framework
- Verbose and declarative API
- No templates ⇒ C and Python wrapping

Challenges

- GPU programming is hard!
- Compute APIs verbose and low-level
- Numerous algorithms for particular operations



Figure: SPLA project logo (picture from spla project page)

Requirements

- User-defined types support
- User-defined functions support
- DAG-based expressions
- Automated internal hybrid storage format
- Automated multi-GPU work scheduling

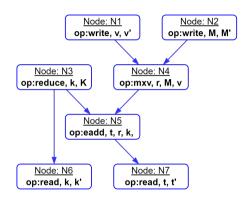


Figure: Example computational expression in DAG form. Note dependencies between nodes.

Implementation details

Dev-stack:

- ► C++17, CMake, C 99, Python 3
- ► Compute API: OpenCL 1.2¹
- Aux compute library: boost.compute²
- ► Tasking library: taskflow³

Strategy:

- Write generalized cl kernels
- Utilize boost meta-kernels library
- Handle values as raw byte sequences (POD)
- User-defined functions effectively are strings

```
template<class InputIterator, class MapIterator, class OutputIterator>
class gather kernel : public meta kernel
    gather kernel() : meta kernel("gather")
    void set range(MapIterator first.
                   MapIterator last.
                   InputIterator input.
                   OutputIterator result'
        m count = iterator range size(first, last):
            "const uint i = get global id(0):\n" <<
            result[expr<uint >("i")] << "=" <<
                input[first[expr<uint_>("i")]] << ";\n";
    event exec(command queue &queue)
        if(m count == 0) {
        return exec 1d(queue, 0, m count):
    size t m count:
```

Figure: Gather OpenCL meta-kernel (picture from boost.compute library)

¹https://www.khronos.org/opencl/

²https://github.com/boostorg/compute

 $^{^3} https://github.com/taskflow/taskflow\#dynamic-tasking$

Issues

- Work distribution between computational units
- Host-device synchronization
- Computational dependencies
- Storage format and data sharing
- Efficient CPU usage

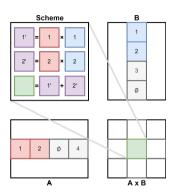


Figure: Example blocked sparse matrix storage. Evaluation of $A \times B$ for some result block. Note, each temporary block product is fully independent GPU task.

```
/* !!! Want to evaluate expression v = b \times A + reduce(K)^*
     /* 1. Make nodes */
     spla Expression MakeVxM(e, &node bxA, tmp1, NULL, mult, plus, b, A, NULL);
     spla Expression MakeMatrixReduce(e, &node rK, tmp2, NULL, plus, K, NULL);
     spla Expression MakeVectorEAdd(e, &node eadd, v, NULL, plus, tmp1, tmp2, NULL);
     /* 2. Setup deps */
     spla Expression Dependency(e, node bxA, node eadd):
10
     spla Expression Dependency(e, node rK, node eadd);
11
12
     /* 3. Submit */
13
     spla Expression Submit(e);
14
15
     /* 4.1 Do some usefull stuff and return back when ready */
16
     spla Expression GetState(e, &state):
17
18
     /* 4.2 Or block until ready */
19
     spla Expression Wait(e);
```

Figure: Evaluation of $v = b \times A + reduce(K)$ using **spla C API**, where v, b are vectors, A and K are matrices, defined somewhere earlier in the code. DAG is set up using expression node dependencies. Note, that we use generic *plus* and *mult*, which can be defined by the user.

Progress

- C++ Core API
- Primitives: matrix, vector, scalar
- Operations: mxm, vxm, assign, eadd
- Algorithms: bfs, sssp
- Hybrid storage format
 - Generic blocked matrix, vector
 - COO-format blocks
 - Empty blocks not stored
 - ▶ It is possible to add CSR, DCSR, Dense blocks
- Task-graph
 - ► Task for each DAG's node
 - Separate set of sub-tasks inside each node's task
 - Each sub-task is assigned to concrete GPU

Roadmap

- Operations: reduce, emult, transpose
- Algorithms: *tc*, *page-rank*, *connected-components*, etc.
- Fine tuning: optimizations, state of the art SpGEMM's
- C API wrapper & Python package (PyPI publication)

- SPLA project: https://github.com/JetBrains-Research/spla
- Email: egororachyov@gmail.com
- Materials:
 - ► Szuppe, J. 2016. Boost.Compute: A parallel computing library for C++ based on OpenCL. Proceedings of the 4th International Workshop on OpenCL.
 - ► Timothy A. Davis. 2019. Algorithm 1000: SuiteSparse:GraphBLAS: Graph Algorithms in the Language of Sparse Linear Algebra. ACM Trans. Math. Softw. 45, 4, Article 44 (December 2019), 25 pages. DOI:https://doi.org/10.1145/3322125
 - ▶ E. Orachev, M. Karpenko, A. Khoroshev and S. Grigorev. 2021. "SPbLA: The Library of GPGPU-Powered Sparse Boolean Linear Algebra Operations," IEEE International Parallel and Distributed Processing Symposium Workshops (IPDPSW), 2021, pp. 272-275, doi: 10.1109/IPDPSW52791.2021.00049.