

# Juice - Machine Learning with Rust

A brief introduction and architecture overview

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November 30, 2017

# Scope of Juice: Deep Learning, Artificial Neural Networks

# Scope of Juice: Deep Learning

Does:

- Deep Learning / Neural Networks

Not:

- Classic Machine Learning
- Bayes
- k-Means
- Decision Trees
- Support Vector Machine

# What I am not going to explain/show

- network architecture design
- speed comparisons
- fancy graphics

- Leaf
- Autumn AI 
- Goal: Re-pricing prediction for online merchants



1 Juice ← Leaf



2 Greenglas ← Cuticula

- Coaster ← Collenchyma



3 Org: Sparrow

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<sup>1</sup>make

<sup>2</sup>me

<sup>3</sup>pretty

# Motivation



**Competition: Tensorflow, Torch, Caffe, Theano**

# Sparrow Goals

- Easy to run
- Easy to integrate
- Easy to deploy on   
- Ready for Embedded <sup>4</sup>

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<sup>4</sup>anything 32bits and up with enough memory

An aerial photograph of a water park. The image shows several teal-colored slides winding through a lush green landscape. A red umbrella is visible on a path between the slides. In the upper right, a person is seen riding a blue raft on a slide. The scene is brightly lit, suggesting a sunny day.

**rusty-machine, vikos, rustlearn, prophet, nn, ...**

# Crates

<your application>

juice

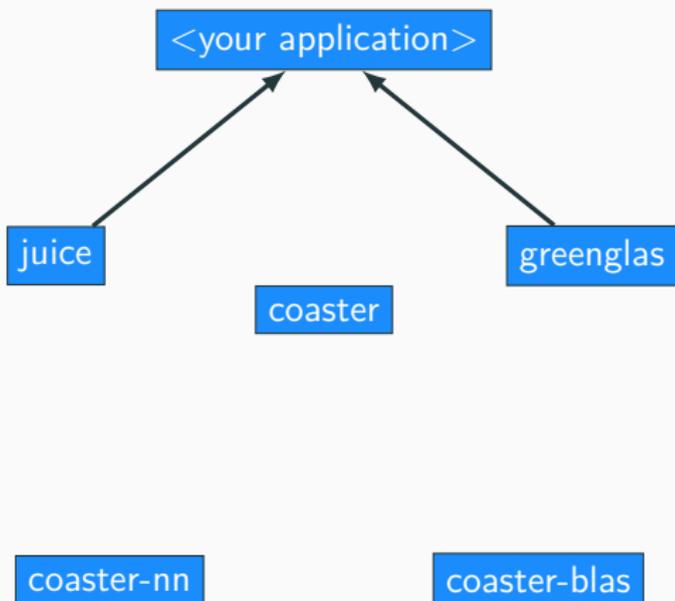
greenglas

coaster

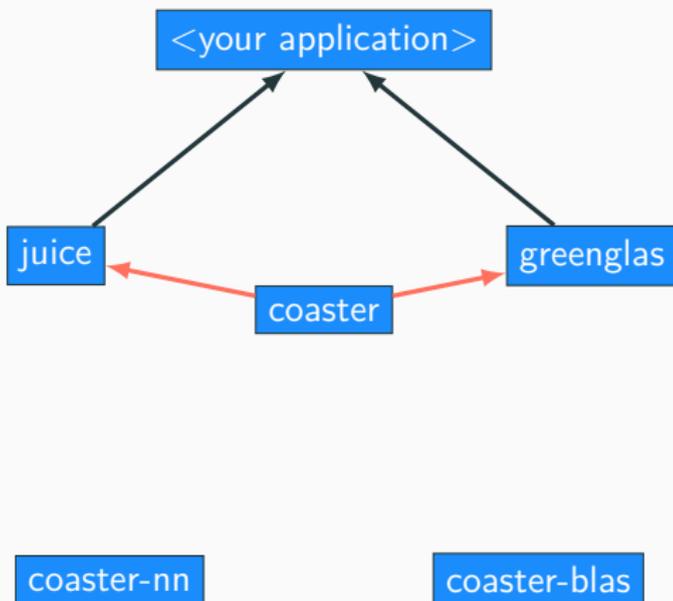
coaster-nn

coaster-blas

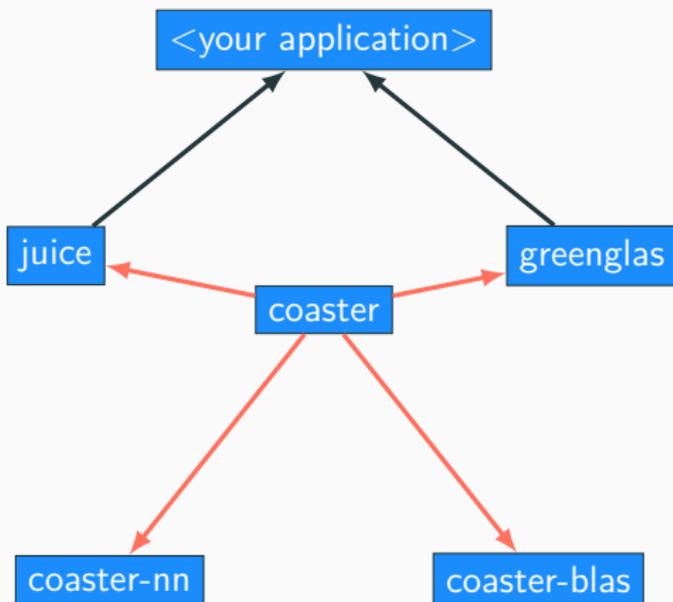
# Crates



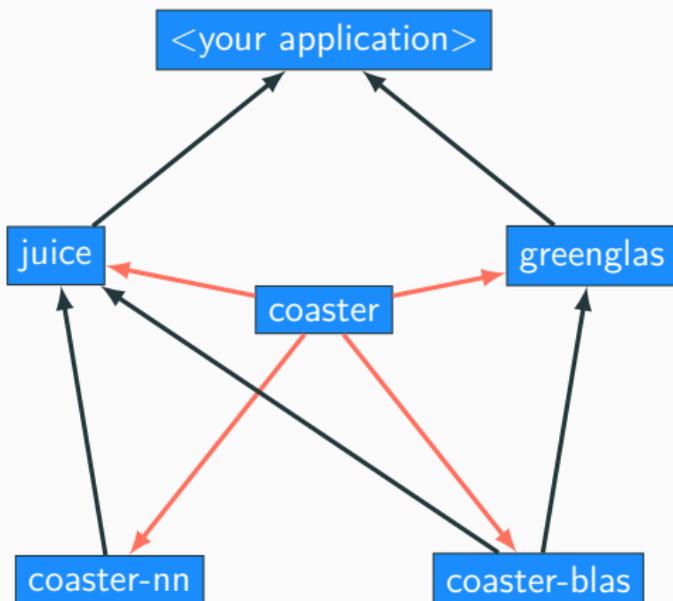
# Crates

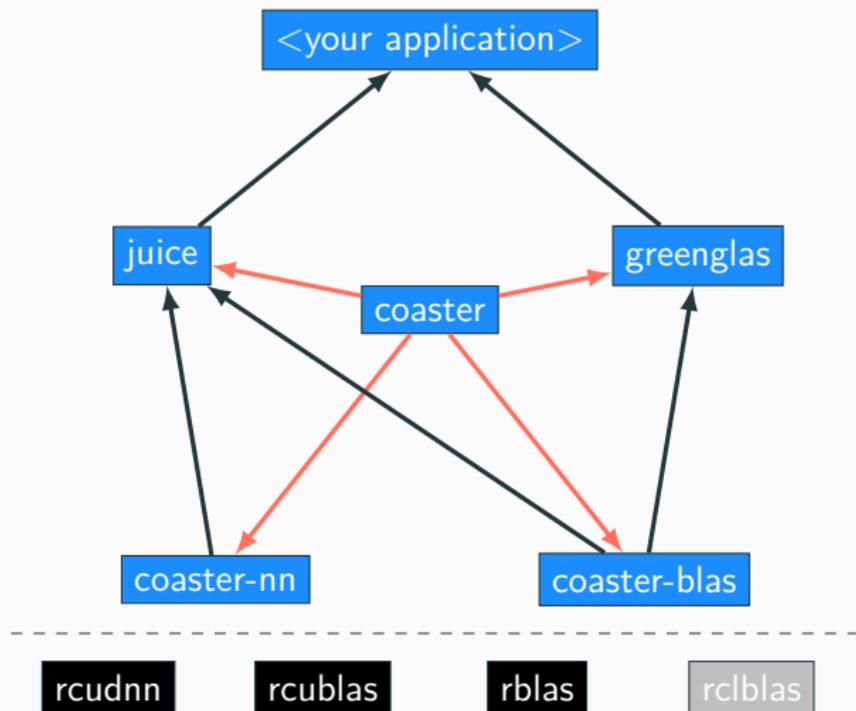


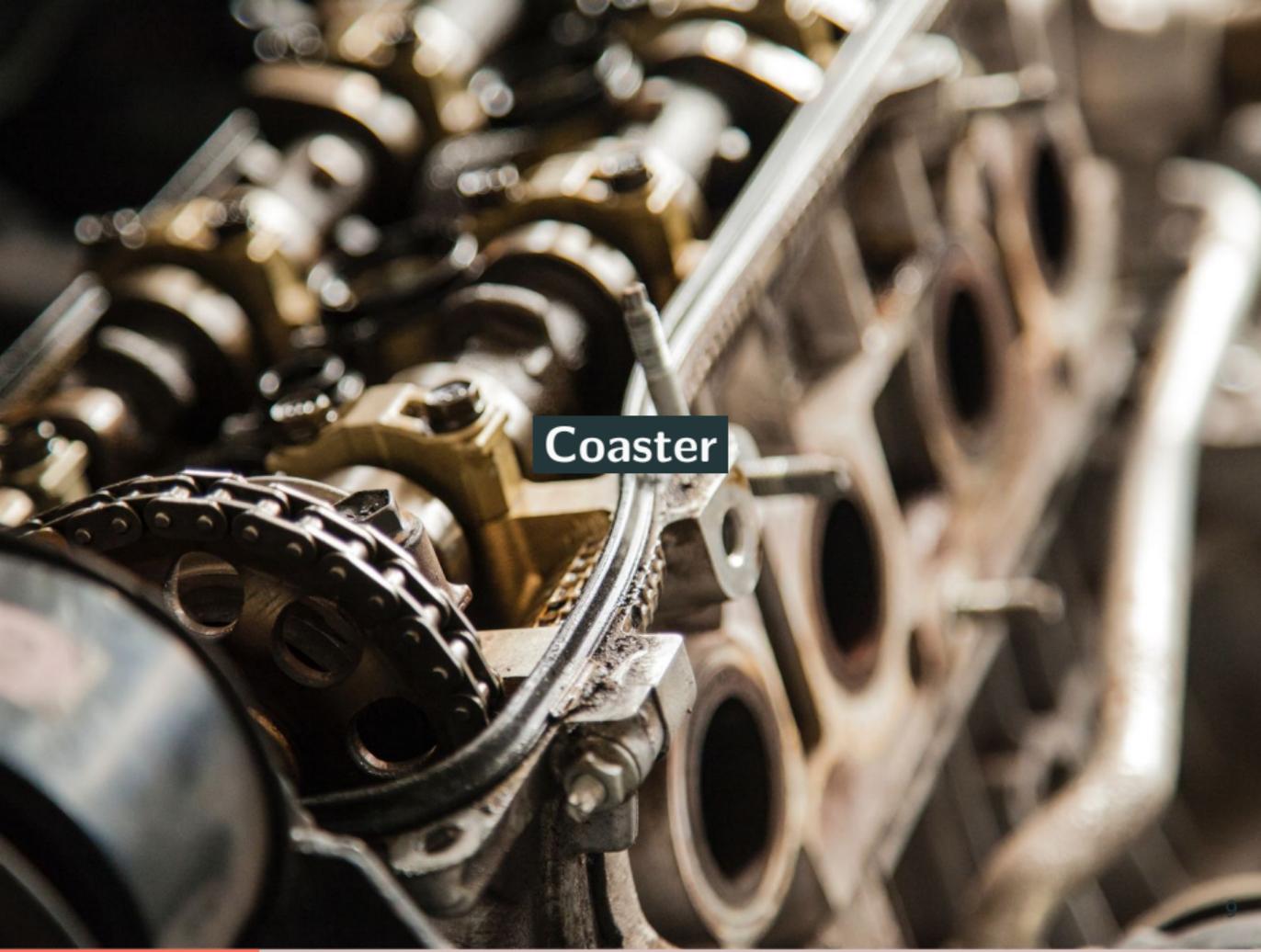
# Crates



# Crates





A close-up photograph of a mechanical engine component, likely a timing chain assembly. The image shows a metal chain with several links, some of which have circular holes. The chain is connected to a metal rod or shaft. The background is filled with various other mechanical parts, including what appears to be a cylinder head with circular openings, all rendered in a shallow depth of field. The lighting is warm and focused on the foreground components.

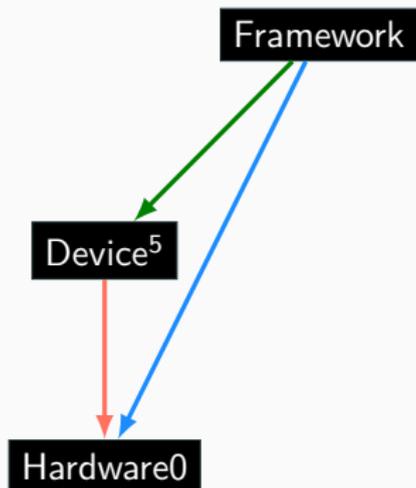
Coaster

# Abstraction

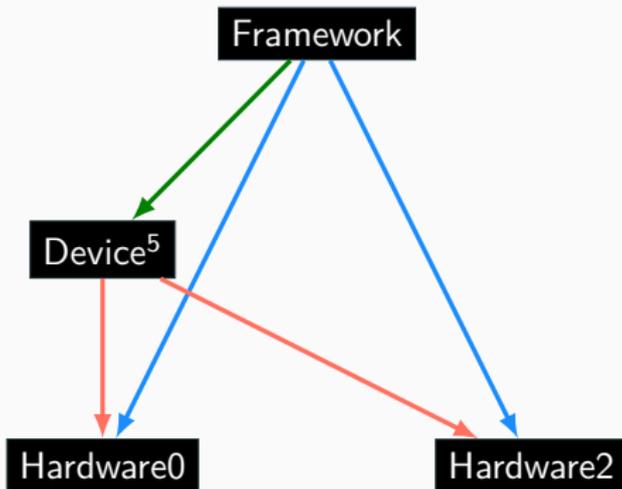
- device memory
- internal structure
- backend specific

```
pub struct SharedTensor<T> {  
    desc: TensorDesc,  
    locations: RefCell<Vec<TensorLocation>>,  
    up_to_date: Cell<BitMap>,  
}
```

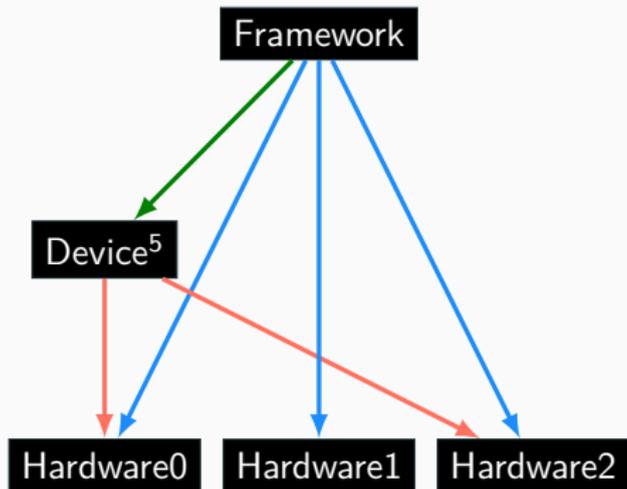
# Backend Abstraction<sup>6</sup>



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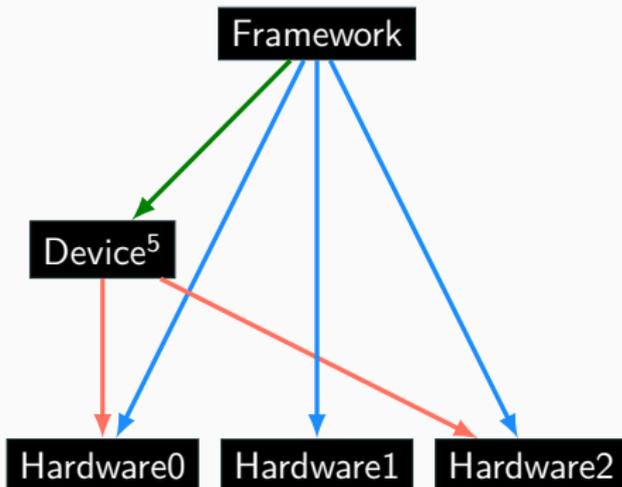


# Backend Abstraction<sup>6</sup>

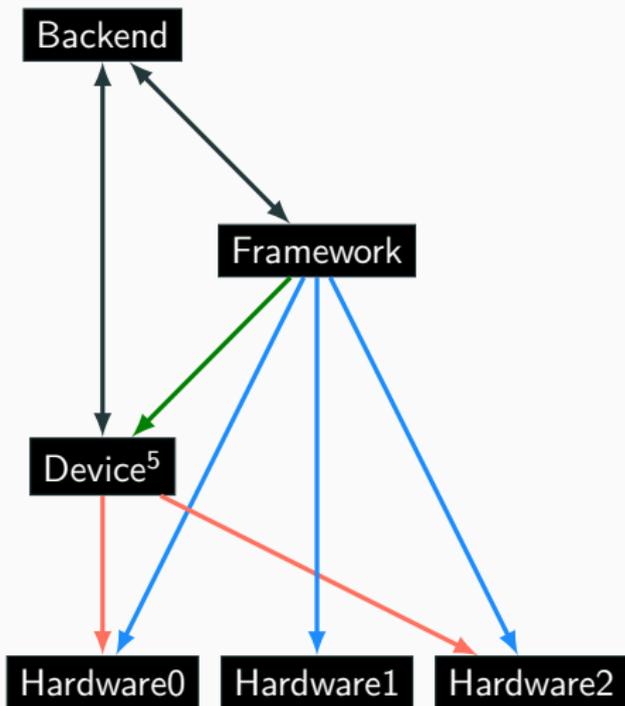


# Backend Abstraction<sup>6</sup>

Backend



# Backend Abstraction<sup>6</sup>



<sup>5</sup>better HardwareGroup/DeviceGroup

<sup>6</sup>the members, associated types differ!

```
/// Defines a Framework.
pub trait IFramework {
    /// The Hardware representation for this Framework.
    type H: IHardware;
    /// The Device representation for this Framework.
    type D: IDevice + Clone;
    /// The Binary representation for this Framework.
    type B: IBinary + Clone;
```

---

<sup>7</sup>or better: CPU

```
/// Defines a Framework.  
pub trait IFramework {  
    /// The Hardware representation for this Framework.  
    type H: IHardware;  
    /// The Device representation for this Framework.  
    type D: IDevice + Clone;  
    /// The Binary representation for this Framework.  
    type B: IBinary + Clone;
```

- cuda
- OpenCL
- Native<sup>7</sup>

---

<sup>7</sup>or better: CPU

```
pub struct Backend<F: IFramework> {  
    framework: Box<F>,  
    device: F::D,  
}
```

```
pub struct Backend<F: IFramework> {  
    framework: Box<F>,  
    device: F::D,  
}
```

Backend is tied to a Framework

Backend has a Device

Device has Hardwares

Juice



**Memory objects with arbitrary (but defined!)  
structure and dimensions**

**=**

**Blobs**

**=**

**SharedTensor**

**parameters**  
**=**  
**weights (+ bias)**

## Architecture

`trait ILayer` common interface that is expected to be impl'd by all layers

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<sup>8</sup>mostly a helper to make LayerConfig impl easier

<sup>9</sup>or any other for that matter, just i.e.

## Architecture

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**LayerType** holds configuration data for the particular layer<sup>8</sup>

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## Architecture

**trait ILayer** common interface that is expected to be impl'd by all layers

**LayerConfig** handles input and output tracking, name based

**LayerType** holds configuration data for the particular layer<sup>8</sup>

**PoolingConfig**<sup>9</sup> holds specific information

---

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<sup>9</sup>or any other for that matter, just i.e.

# Layers implemented

- activation ReLU
- activation Sigmoid
- activation TanH
- common Dropout<sup>10</sup>
- common Softmax
- common LogSoftmax
- common Convolution <sup>11</sup>
- common Linear
- common Pooling
- util Reshape
- util Flatten

---

<sup>10</sup>unmerged, but it is there pr#13

<sup>11</sup>the native impl has only forward impl

# Containers

- most common: **Sequential / SequentialConfig**
- **stackable, container in a container in a container** <sup>12</sup>
- are **Layers/LayerConfigs** too

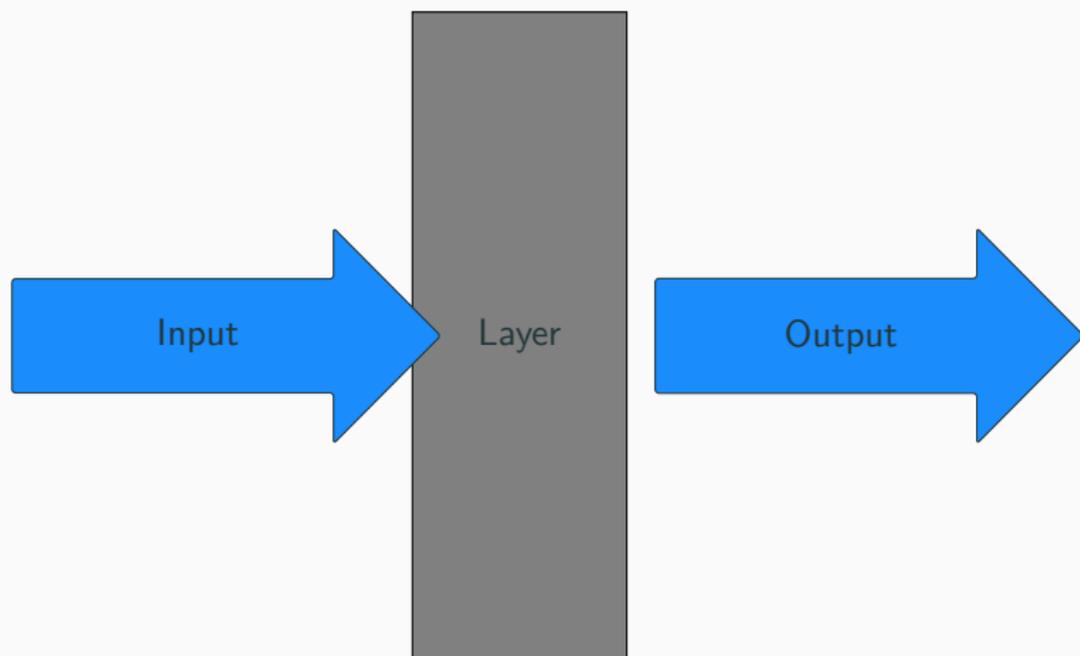
---

<sup>12</sup>no docker involved

**ILayer**

**ILayer**  
**=**  
**ComputeOutput**  
**+ ComputeInputGradient**  
**+ ComputeParametersGradient**

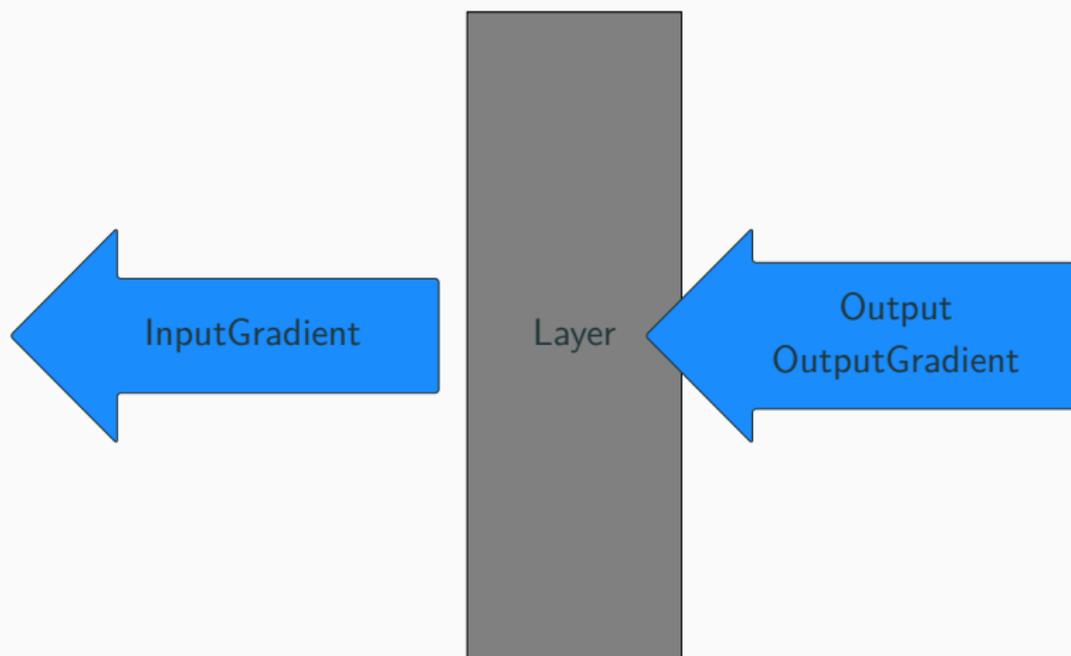
## DataFlow: ComputeOutput



## Layer: ComputeOutput

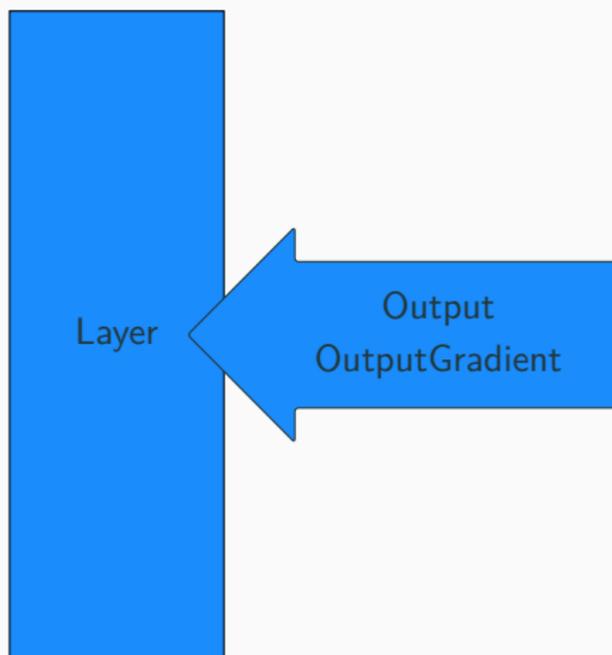
```
/// A Layer that can compute the output for a given input.
pub trait ComputeOutput<T, B: IBackend> {
    /// Compute output for given input
    /// and write them into `output_data`.
    fn compute_output(&self,
        backend: &B,
        weights_data: &[&SharedTensor<T>],
        input_data: &[&SharedTensor<T>],
        output_data: &mut [&mut SharedTensor<T>]);
}
```

## DataFlow: ComputeInputGradient



## Layer: ComputeInputGradient

```
/// A Layer that can compute the gradient with respect to its input.
pub trait ComputeInputGradient<T, B: IBackend> {
    /// Compute gradients with respect to the inputs
    /// and write them into `input_gradients`.
    fn compute_input_gradient(&self,
                               backend: &B,
                               weights_data: &[&SharedTensor<T>],
                               output_data: &[&SharedTensor<T>],
                               output_gradients: &[&SharedTensor<T>],
                               input_data: &[&SharedTensor<T>],
                               input_gradients: &mut [&mut SharedTensor<T>])
}
```



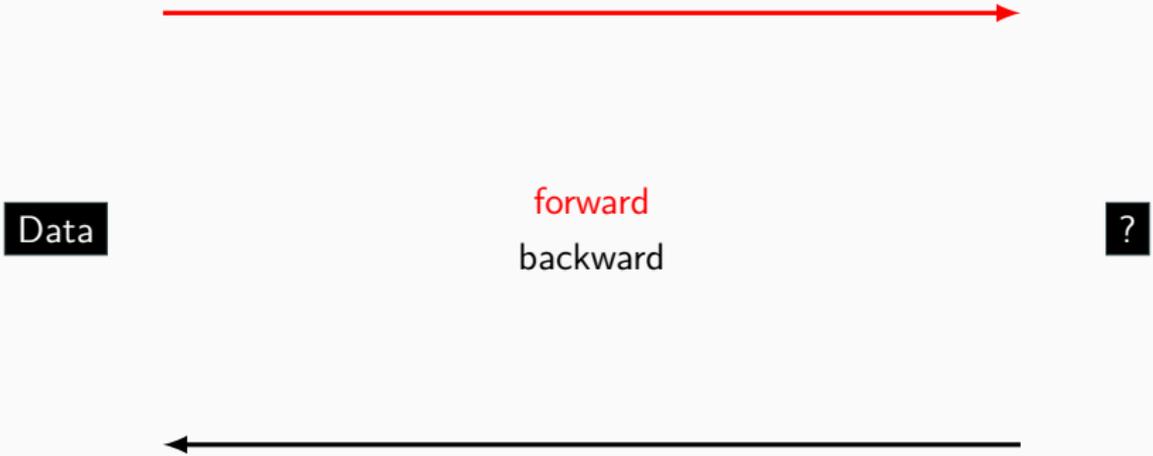
## Layer: ComputeParametersGradient

```
/// A Layer that can compute the gradient with respect to its parameter
pub trait ComputeParametersGradient<T, B: IBackend> {
    /// Compute gradients with respect to the parameters
    /// and write them into `parameters_gradients`.
    fn compute_parameters_gradient(&self,
                                   backend: &B,
                                   output_data: &[&SharedTensor<T>],
                                   output_gradients: &[&SharedTensor<T>],
                                   input_data: &[&SharedTensor<T>],
                                   parameters_gradients: &mut [&mut SharedTensor<T>],
                                   // not required for all layers,
                                   // only those with internal state to be optimized
    )
}
```



Something is still missing.

# Something is still missing (?)



**Solver**

- connects forward and backward layer
- optimized towards objective<sup>13</sup>
- contains almost all tuneable hyperparameters<sup>14</sup>

---

<sup>13</sup>implicitly defined loss function

<sup>14</sup>Parameters which are not optimized towards

```
pub struct SolverConfig {  
  pub name: String,  
  pub network: LayerConfig,  
  pub objective: LayerConfig,  
  pub solver: SolverKind,  
  // more..  
}
```

A roller coaster track with two cars. The track is dark grey and features several loops and drops. The support structure is white. The sky is overcast and grey. A dark green rectangular box with white text is centered over the middle of the image.

**Be Fast, Stay Fast**

- 95% spent in optimized libraries (i.e. cudnn)
- avoid implementing things manually (blas)
- skip operations if possible
- provide in place operations
- never re-allocate device memory if possible / hold device mem as long as possible

# Alexnet example (network cfg)

```
extern crate env_logger;
extern crate coaster as co;
extern crate juice;

use co::prelude::*;

let mut cfg = SequentialConfig::default();
cfg.add_input("data", &[128, channels, px_dim, px_dim]);

let conv1_layer_cfg = ConvolutionConfig {
    num_output: 64,
    filter_shape: vec![11],
    padding: vec![2],
    stride: vec![4],
};

cfg.add_layer(LayerConfig::new("conv1", conv1_layer_cfg));
cfg.add_layer(LayerConfig::new("conv1/relu", LayerType::ReLU));
```

# Alexnet example (network cfg)

```
cfg.add_layer(LayerConfig::new("conv2",
    ConvolutionConfig {
        num_output: 192,
        filter_shape: vec![5],
        padding: vec![2],
        stride: vec![1],
    }));
cfg.add_layer(LayerConfig::new("conv2/relu",
    LayerType::ReLU));
cfg.add_layer(LayerConfig::new("pool2",
    PoolingConfig {
        mode: PoolingMode::Max,
        filter_shape: vec![3],
        stride: vec![2],
        padding: vec![0],
    }));
```

# Alexnet example (network cfg)

```
// more layers ..
cfg.add_layer(LayerConfig::new("fc1",
    LinearConfig { output_size: 4096 }));
cfg.add_layer(LayerConfig::new("fc2",
    LinearConfig { output_size: 4096 }));
cfg.add_layer(LayerConfig::new("fc3",
    LinearConfig { output_size: 1000 }));

// create pseudo probabilities + log
cfg.add_layer(LayerConfig::new("log_softmax", LayerType::LogSoftmax));

// set up backends
let backend = Rc::new(Backend::<Cuda>::default().unwrap());

let mut network = Layer::from_config(backend.clone(),
    &LayerConfig::new("alexnet",
        LayerType::Sequential(cfg)));
```

# Alexnet example (classifier cfg)

```
let mut classifier_cfg = SequentialConfig::default();
classifier_cfg.add_input("network_out", &[batch_size, 10]);
classifier_cfg.add_input("label", &[batch_size, 1]);
// set up nll loss
let nll_layer_cfg = NegativeLogLikelihoodConfig { num_classes: 10 };
let nll_cfg = LayerConfig::new("nll",
                               LayerType::NegativeLogLikelihood(nll_layer_cfg));
classifier_cfg.add_layer(nll_cfg);
```

# Alexnet example (training/backward pass, 1)

```
// set up solver
let mut solver_cfg = SolverConfig {
    minibatch_size: batch_size,
    base_lr: learning_rate,
    momentum: momentum,
    ..SolverConfig::default()
};
solver_cfg.network = LayerConfig::new("network", cfg);
solver_cfg.objective = LayerConfig::new("classifier",
    classifier_cfg);
let mut solver = Solver::from_config(backend.clone(),
    &solver_cfg);

// set up confusion matrix
let mut confusion = ConfusionMatrix::new(10);
confusion.set_capacity(Some(1000));
```

# Alexnet example (training/backward pass, 2)

```
let inp = SharedTensor::<f32>::new(&[batch_size, channels, px_dim, py_dim]);
let label = SharedTensor::<f32>::new(&[batch_size, 1]);
let inp_lock = Arc::new(RwLock::new(inp));
let label_lock = Arc::new(RwLock::new(label));

for _ in 0..(example_count / batch_size) {
    let mut targets = Vec::new();
    for (batch_n, (label_val, input)) in decoded_images
        .by_ref()
        .take(batch_size)
        .enumerate() {
        let mut inp = inp_lock.write().unwrap();
        let mut label = label_lock.write().unwrap();
        write_batch_sample(&mut inp, &input, batch_n);
        write_batch_sample(&mut label, &[label_val], batch_n);
        targets.push(label_val as usize);
    }
}
// ...
```

# Alexnet example (training/backward pass, 2)

```
for _ in 0..(example_count / batch_size) {
    // ...
    // train the network!
    let inferred_out = solver.train_minibatch(
        inp_lock.clone(),
        label_lock.clone());
    let mut inferred = inferred_out.write().unwrap();
    let predictions = confusion.get_predictions(&mut inferred);

    confusion.add_samples(&predictions, &targets);
    println!(
        "Last sample: {} | Accuracy {}",
        confusion.samples().iter().last().unwrap(),
        confusion.accuracy()
    );
}
```

# Alexnet example (prediction/inference/forward pass)

```
let inp = SharedTensor::new(&[1, channels, px_dim, px_dim]);  
let inp_lock = Arc::new(RwLock::new(inp));  
let predictions = network.forward(&[inp_lock.clone()]);  
// do something with those predictions
```

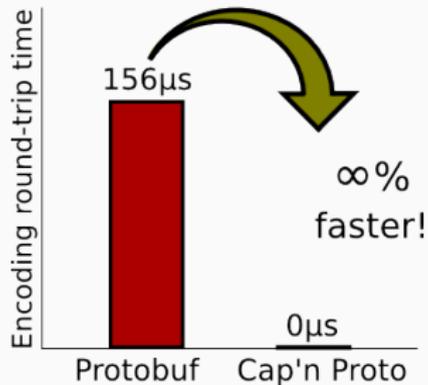
**mnist, fashion-mnist**

`github.com/spearow/juice-examples`



**save/load/store/export**

- interface to other languages
- load, store weights and the layer architecture
- it executes *really fast!*





**What happened in 2017?**

# Summary 2017

- Learning a whole lot more about rust <sup>15</sup>
- Merging remaining large pull request <sup>16</sup>
- impl Dropout in coaster-nn for backends cuda and native
- Setting up CI ci.spearow.io / @sirmergealot 🇩🇪
- Auto generating config files for CI spearow/ci
- Fight a lot with CI, get GPU hardware access from containers from garden hypervisor <sup>17</sup>

---

<sup>15</sup>build.rs, bindgen, PhantomData, Any trait and more

<sup>16</sup>hands down @alexandermorozov

<sup>17</sup>Still an ugly hack



# Roadmap 2018

- Recursive Neural Networks / Long Term Short Term Memory [coaster-nn]
- OpenCL Backend [juice/coaster-nn]
- Autodiff [juice/coaster-nn]
- Accuracy enum instead of type usage [juice/greenglas/coaster]

- Honour biases [juice]
- Gradient calculation for ND-convolution native backend [coaster-nn]
- Regression examples [juice-examples]
- Add preprocessing filters <sup>18</sup> [greenglas]

---

<sup>18</sup>FFT, wavelet, denoise, addnoise, cutout, rescale, blur, ..

**Questions?**

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**sparrow.io**

**gitter.im/sparrow/juice**

# Credits

Presentation by Bernhard Schuster - ahoi.io  
Theme by Matze Vogelsang and contributors -  
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