Chapter-wise software and hardware list Chapter-wise software and hardware list	Chapter number	Software required (With version) (all open source)	Hardware specifications (not required)	OS required	
	1 - 10	ROS Indigo		Linux/ Ubuntu 14.4	
	2 - 9	Gazebo 2.2			
	3 & 4	TurtleBot packages	TurtleBot 2		
	6	Baxter Simulator & Baxter SDK	Rethink Robotics Research Baxter 1.1.1		
	7	Hector Gazebo packages & Crazyflie software	Bitcraze Crazyflie 2.0 & Crazyradio PA		
	9	rocon packages			