

Motivating and validating Bayesian and neural circuit models of decisions

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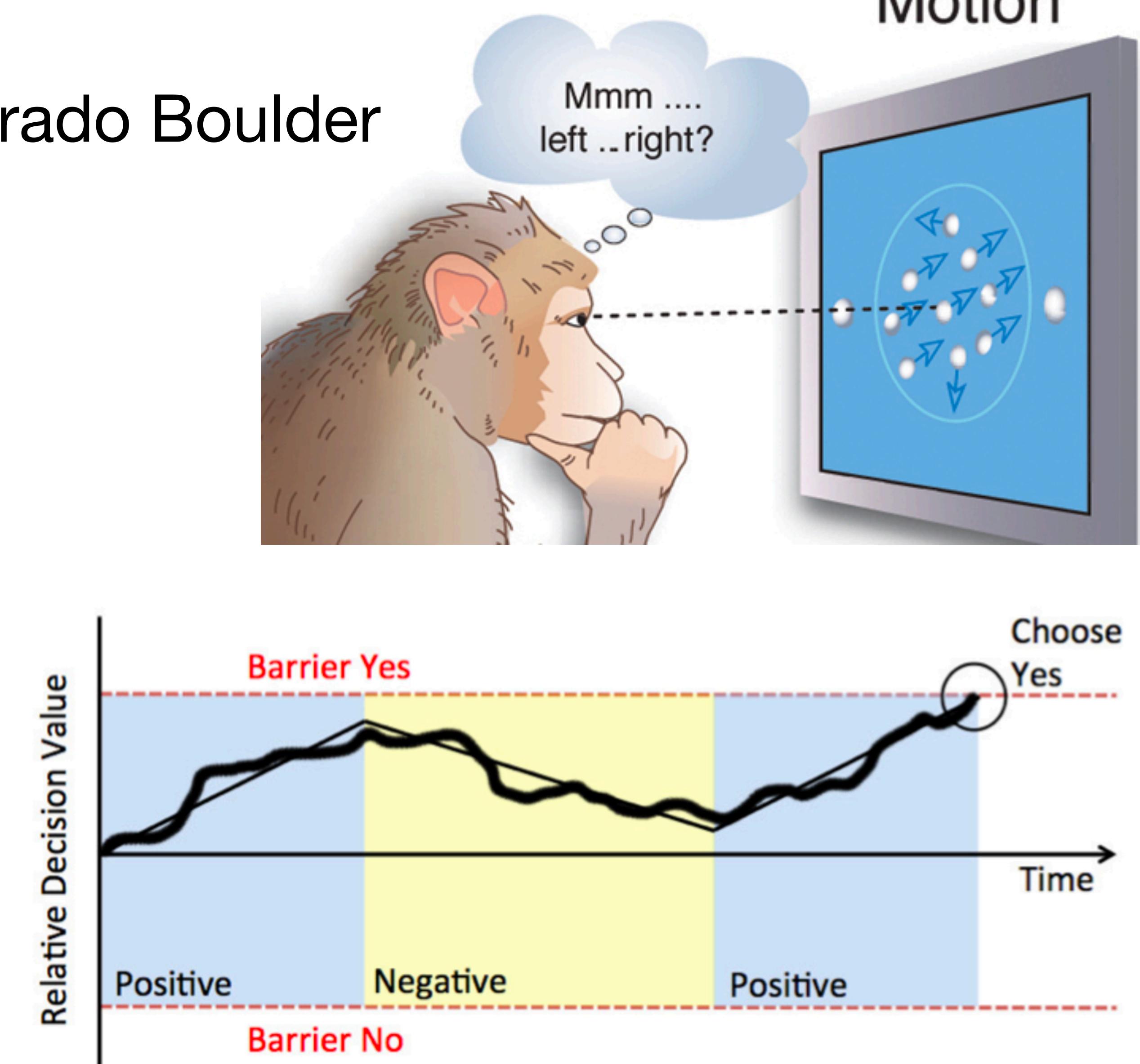
$$P(A|B) = \frac{P(B|A) P(A)}{P(B)}$$

LIKELIHOOD
the probability of "B" being TRUE given that "A" is TRUE

PRIOR
the probability of "A" being TRUE

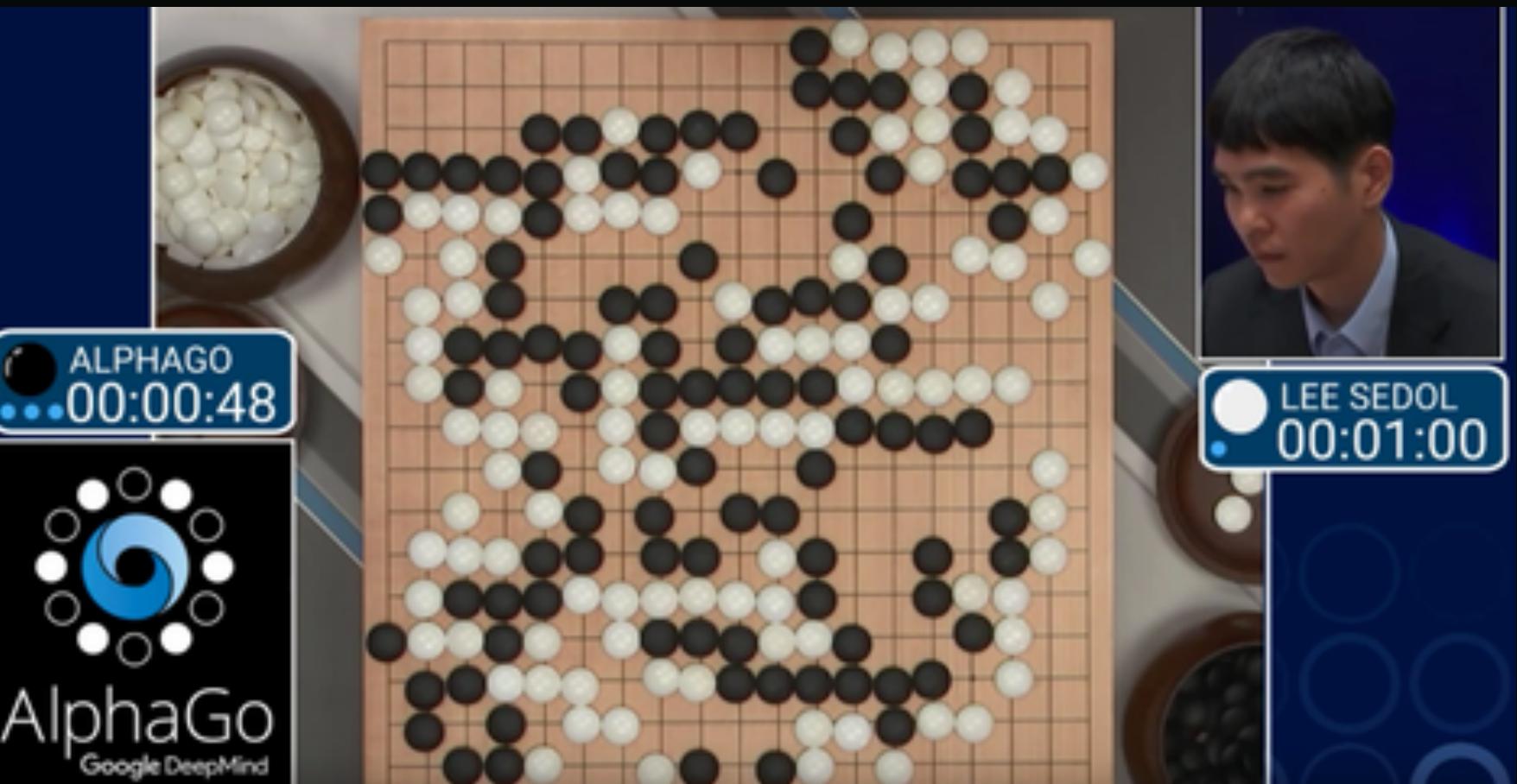
POSTERIOR
the probability of "A" being TRUE given that "B" is TRUE

The probability of "B" being TRUE



Outline

1. Bayes Rule and Bayesian inference
 - 1.1. Combining priors and observations
 - 1.2. Combing multiple observations within/across modalities
2. Two choice tasks
 - 2.1. Log likelihood ratio update and evidence accumulation
 - 2.2. Drift-diffusion model and decision statistics
3. Fitting models to data
 - 3.1. Maximum likelihood estimation
 - 3.2. Bayes factors for model identification
4. Competitive neural circuit models
 - 4.1. Mutual inhibition and winner take all networks
 - 4.2. Dependence of attractor structure on inputs

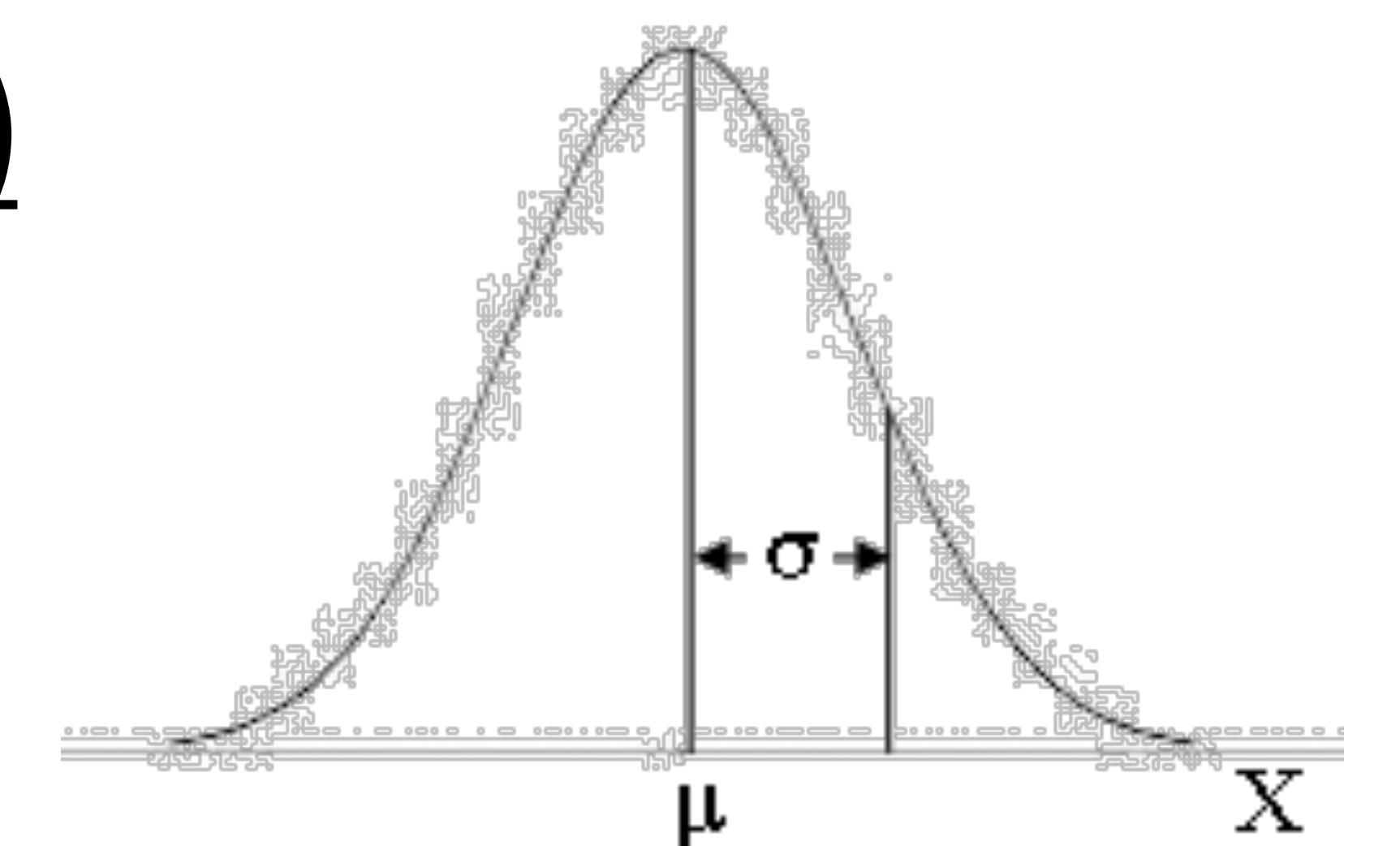


Probability primer (notation, etc)

probability density
function

$$p(x)$$

probability a *random variable* X has a value
between x and $x + \Delta$ is about $\Delta \cdot p(x)$



example:
normal

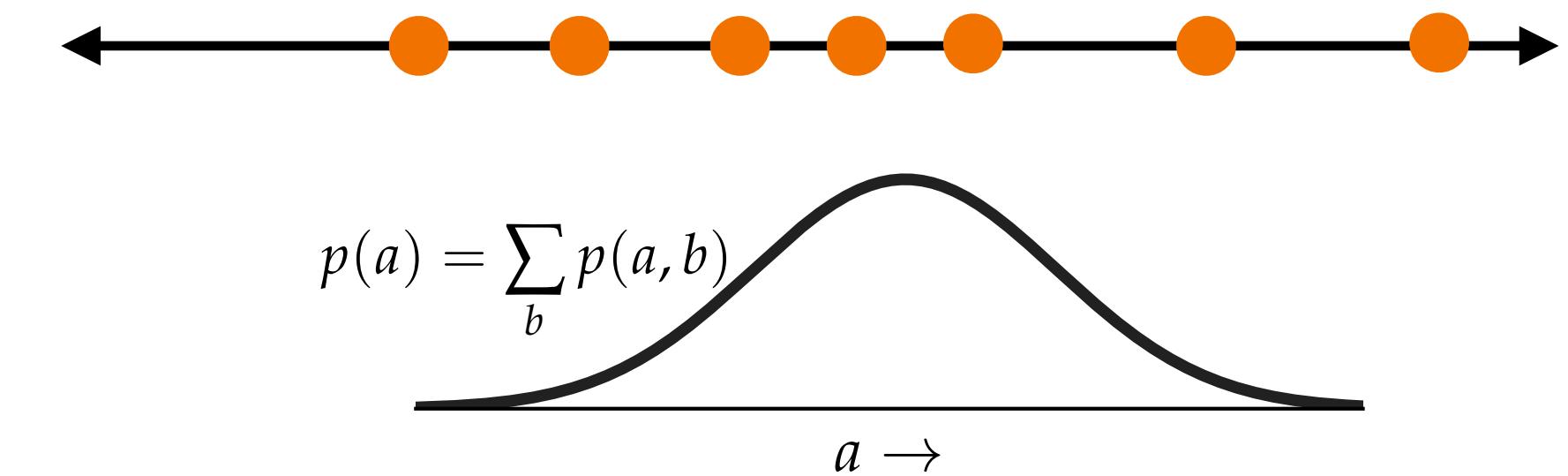
$$p(x) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(x-\mu)^2/2\sigma^2}$$

“drawing” a random variable
from a normal distribution

also
written

$$\mathcal{N}(+\mu, \sigma^2)$$

$$X \sim \mathcal{N}(+\mu, \sigma^2)$$



conditional
probability

$$p(x | y)$$

probability density of X given
the value y of another “event”

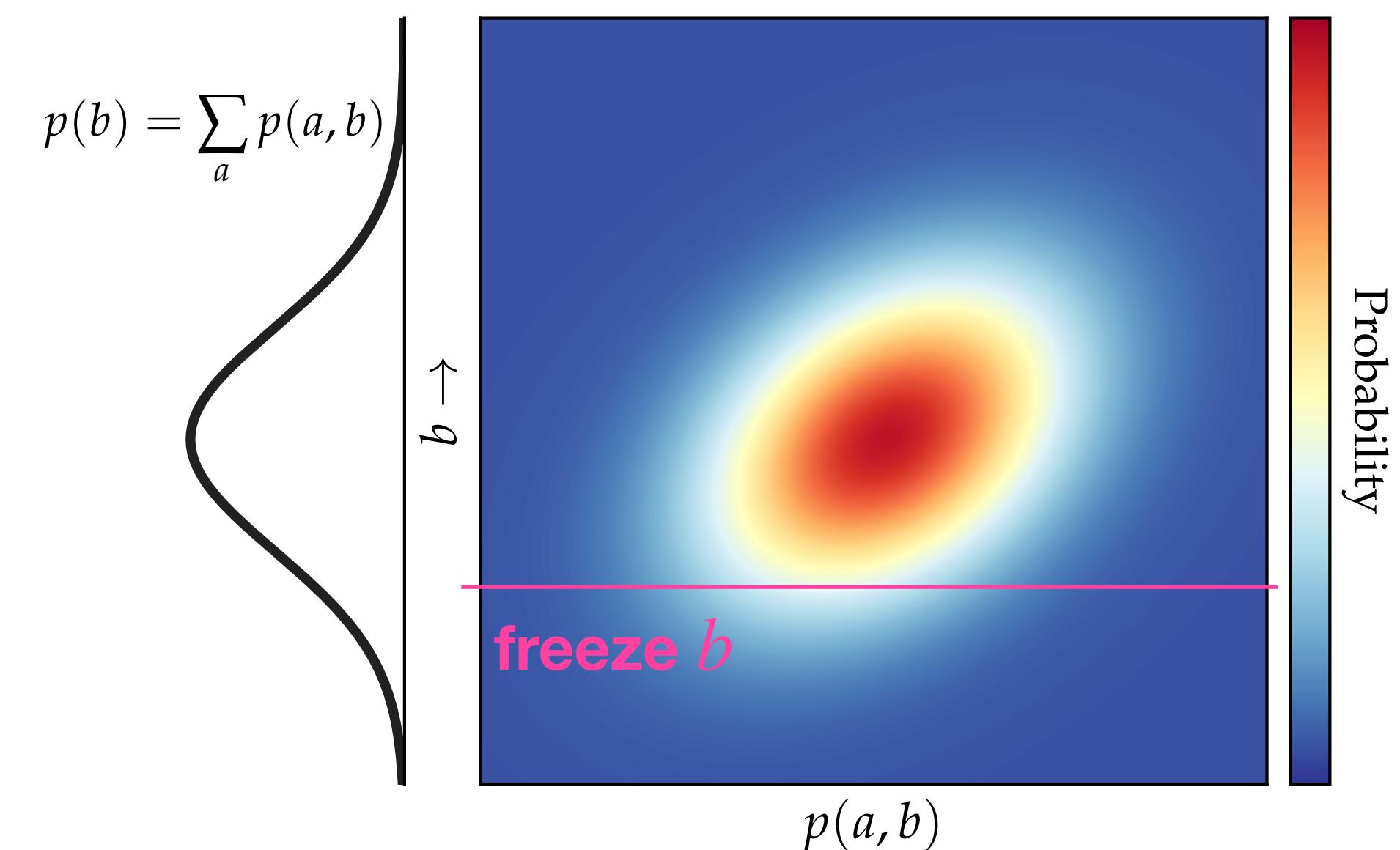
event could be: a completely different but correlated
random variable, a condition on the random variable X

example: correlated
normal random variables

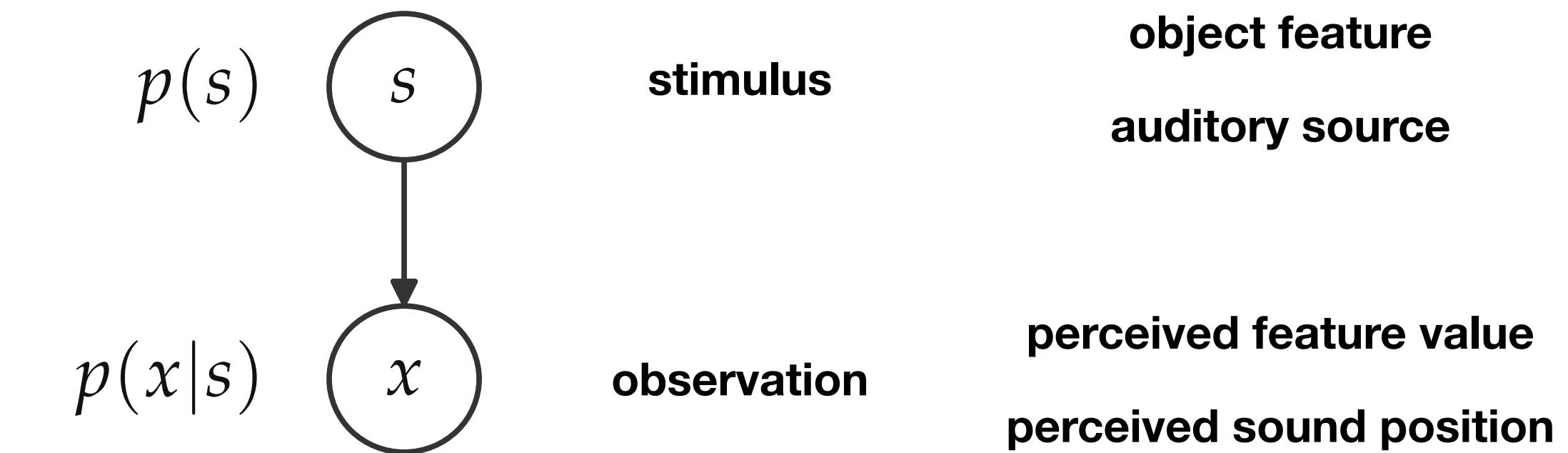
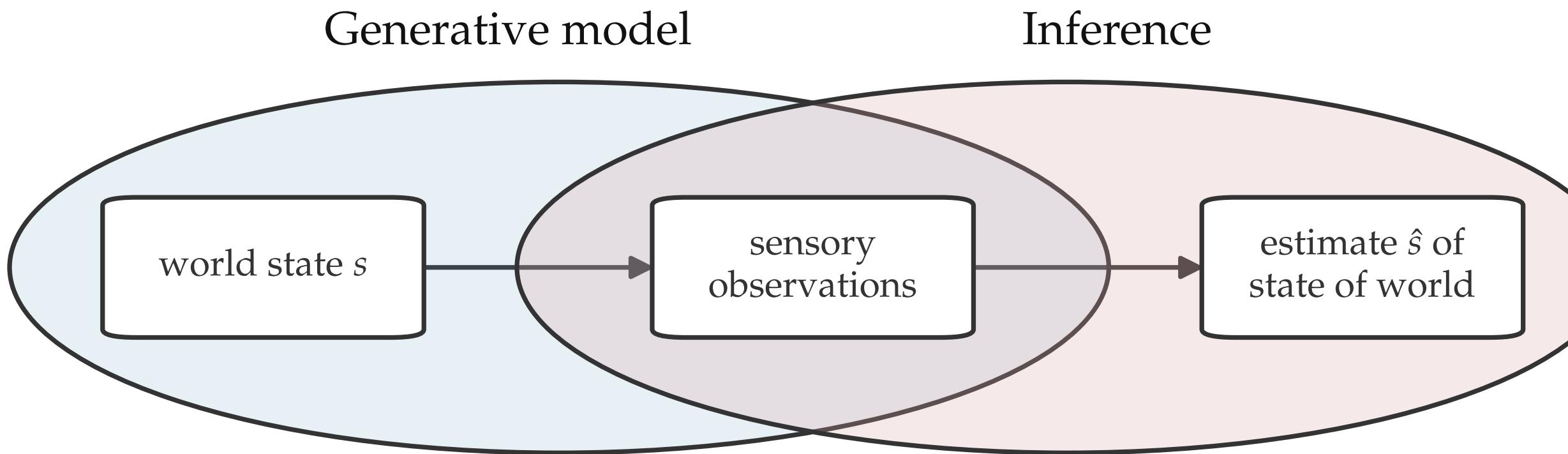
$$p(a | b) = \frac{p(a, b)}{p(b)}$$

could be:

- height & weight of an animal
- latitude & mean temp of city
- observed visual & auditory
stimuli from common source



Bayesian model of the world & Bayes rule



Bayes Rule

$$p(s|x) = \frac{p(x|s)p(s)}{p(x)}$$

$p(s|x)$ **posterior**

$p(x|s)$ **likelihood function**

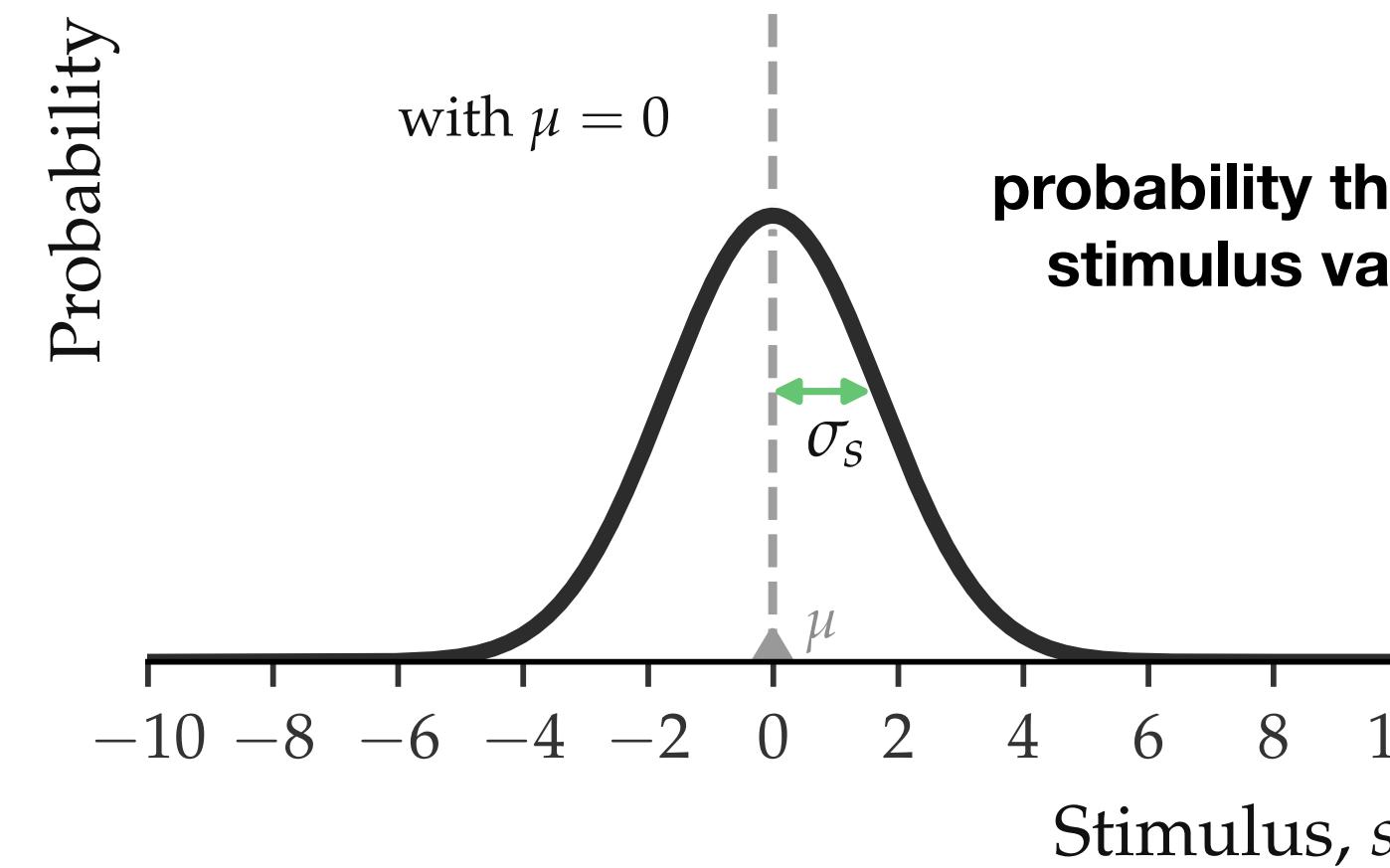
$p(s)$ **source prior**

$p(x)$ **observation prior**

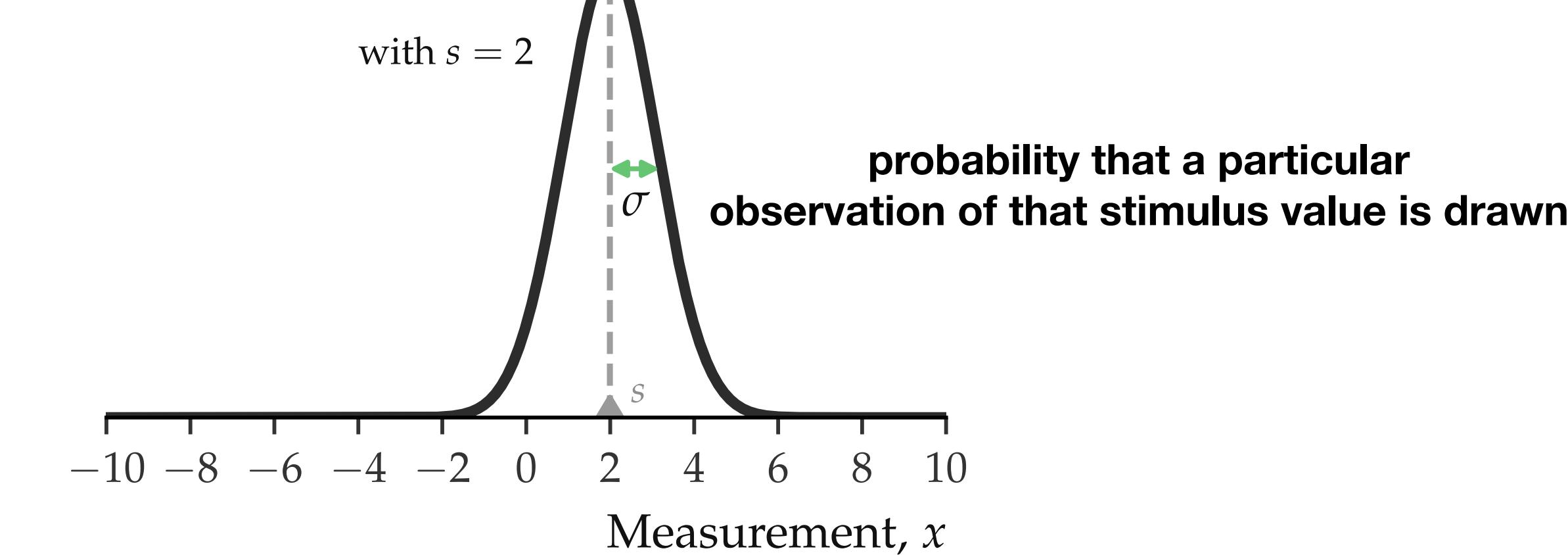
Example

normal distribution

$$p_s(s) = \frac{1}{\sqrt{2\pi\sigma_s^2}} e^{-\frac{(x-\mu)^2}{2\sigma_s^2}}$$



$$p_{x|s}(x|s) = \frac{1}{\sqrt{2\pi\sigma^2}} e^{-\frac{(x-s)^2}{2\sigma^2}}$$



Combining evidence with priors

$$p(s|x_1) = \frac{p(x_1|s)p(s)}{p(x_1)} \propto p(x_1|s)p(s)$$

scaling factor doesn't matter,
just the shape!

long
calculation

e.g., normal distributions

$$p(s|x_1) \propto \exp\left[-\frac{(x_1 - s)^2}{2\sigma^2}\right] \cdot \exp\left[-\frac{(s - \mu)^2}{2\sigma_s^2}\right] \propto C \cdot \exp\left[-\frac{(s - \mu_{\text{post}})^2}{2\sigma_{\text{post}}^2}\right]$$

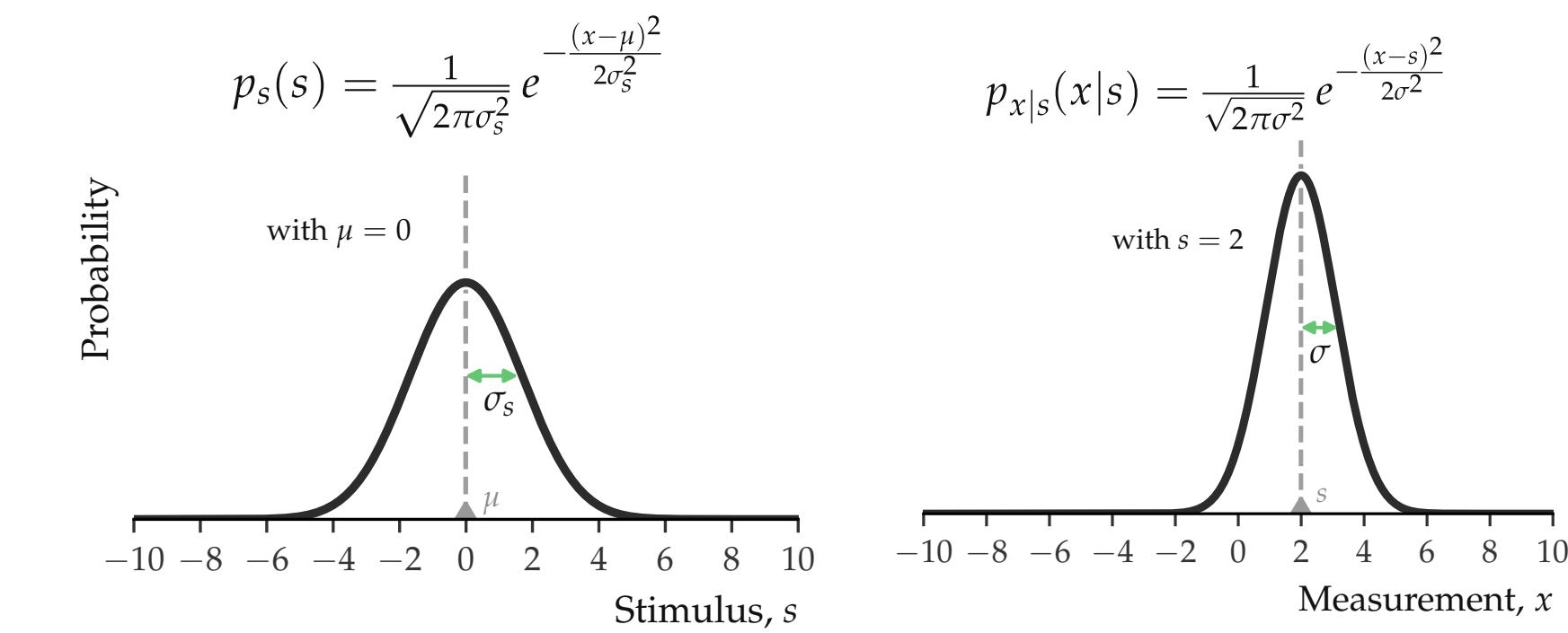
where $\mu_{\text{post}} = \frac{J_1 x_1 + J_s \mu}{J_1 + J_s}$

stimulus estimate

and

$$\sigma_{\text{post}}^2 = \frac{1}{J_1 + J_s}$$

uncertainty on estimate



$$J_1 = \frac{1}{\sigma^2} \quad \text{and} \quad J_s = \frac{1}{\sigma_s^2}$$

“precisions”

precisions differentially
weight prior and observation

$$w_1 = \frac{J_1}{J_1 + J_s} \longrightarrow \mu_{\text{post}} = w_1 x_1 + (1 - w_1) \mu$$

bias due to prior

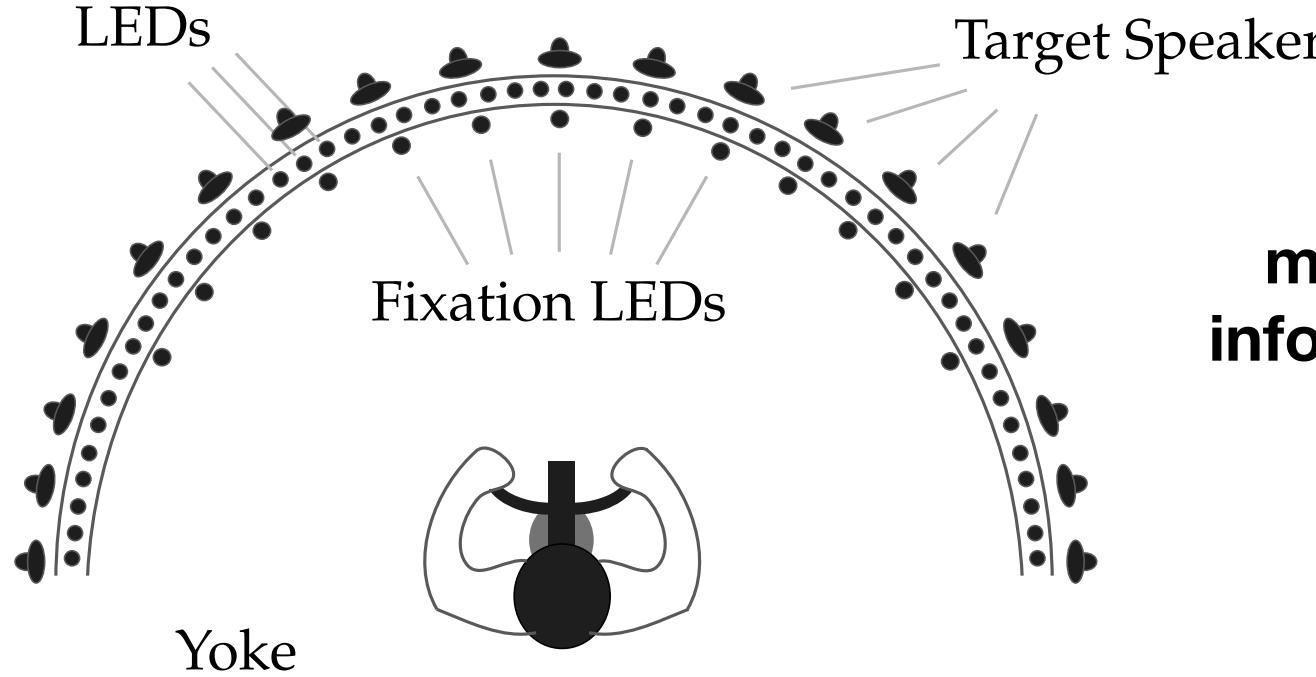
$$\text{Bias} [\mu_{\text{post}} | s] = E [\mu_{\text{post}} | s] - s = w_1 \langle x_1 \rangle + (1 - w_1) \mu - s = w_1 s - s + (1 - w_1) \mu = (1 - w_1)(\mu - s)$$

variance reduced
by prior

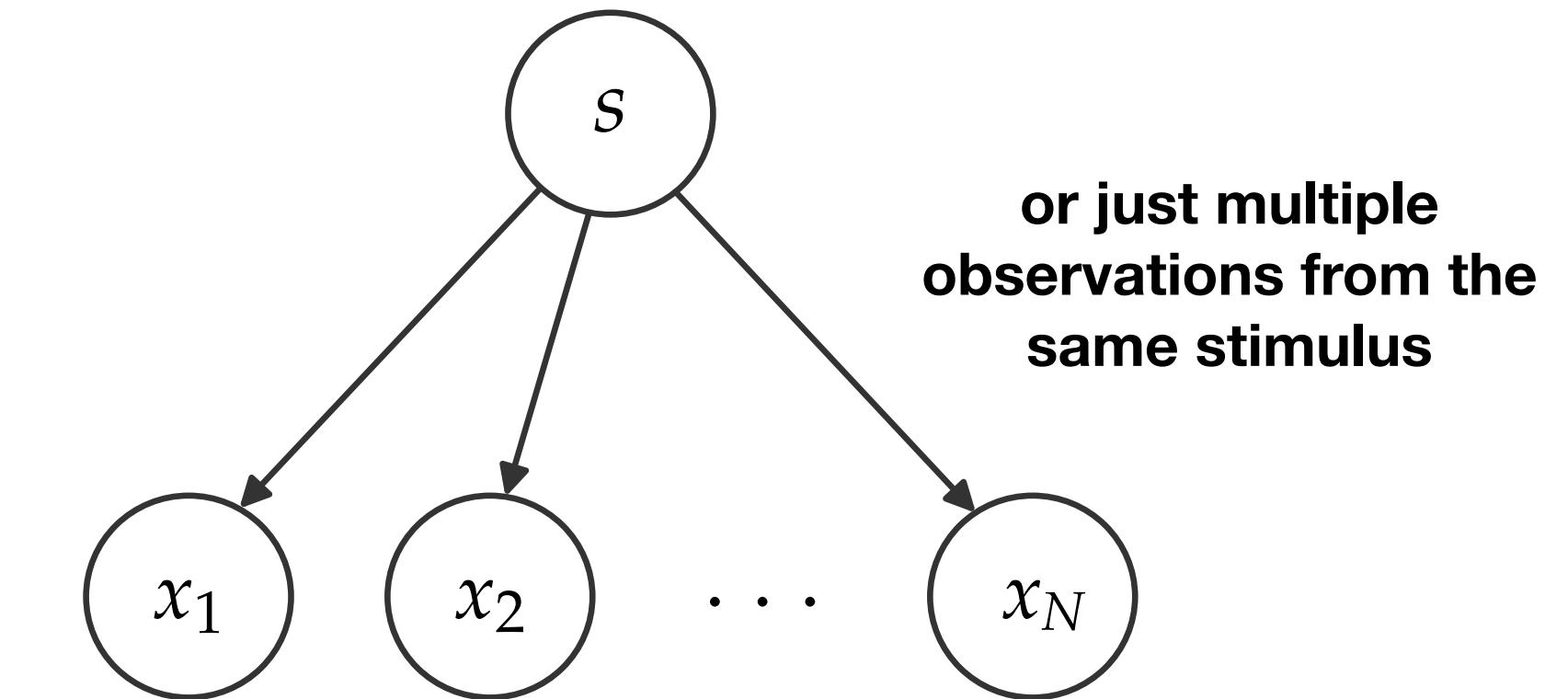
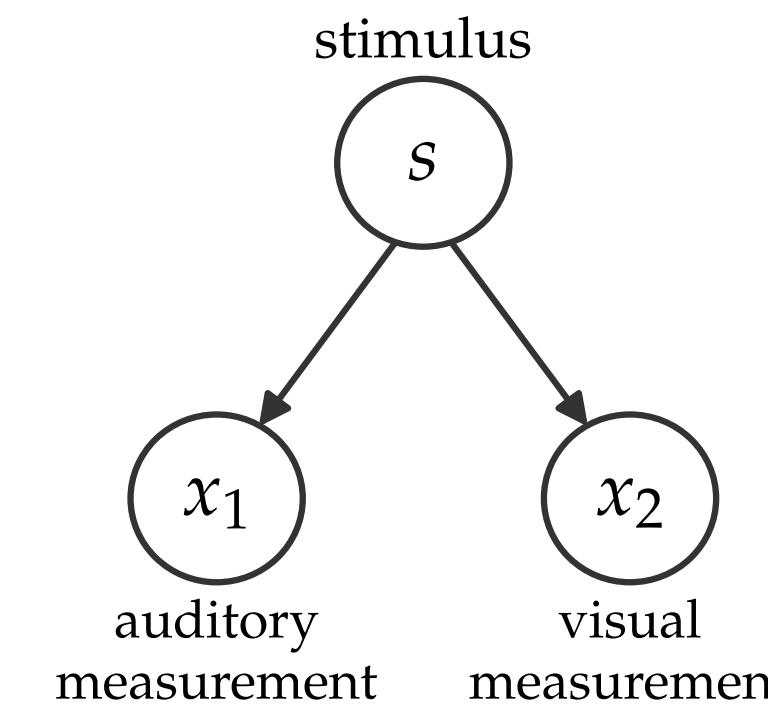
$$\text{Var} [\mu_{\text{post}} | s] = w_1^2 \text{Var} [x_1 | s] = w_1^2 \cdot \sigma^2 < \sigma^2$$

these two quantities “tradeoff” as prior is adjusted

Combining multiple pieces of evidence



may be combining info across modalities



two observation case

$$p(x_1, x_2 | s) = p(x_1 | s)p(x_2 | s)$$

if observations are
conditionally independent

assume normally distributed observations & prior

$$p(x_j | s) = \frac{1}{\sqrt{2\pi}\sigma_j} \exp \left[-\frac{(x_j - s)^2}{2\sigma_j^2} \right]$$

$$p(s | x_{1:2}) \propto p(x_1 | s)p(x_2 | s)p(s) \longrightarrow p(s | x_{1:2}) = C \exp \left[-\frac{(s - \mu_{\text{post}})^2}{2\sigma_{\text{post}}^2} \right]$$

$$\mu_{\text{post}} = w_1 x_1 + w_2 x_2 + (1 - w_1 - w_2)\mu$$

$$\sigma_{\text{post}}^2 = [J_1 + J_2 + J_s]^{-1} = J_{\text{post}}^{-1}$$

$$w_j = J_j / J_{\text{post}}$$

$$J_j = \frac{1}{\sigma_j^2}$$

multiple observations

$$p(s | x_{1:N}) \propto p(x_1 | s)p(x_2 | s) \cdots p(x_N | s)p(s)$$

$$\mu_{\text{post}} = \sum_{n=1}^N w_n x_n + \left(1 - \sum_{n=1}^N w_n \right) \mu$$

$$J_{\text{post}} = \sum_{n=1}^N J_j + J_s$$

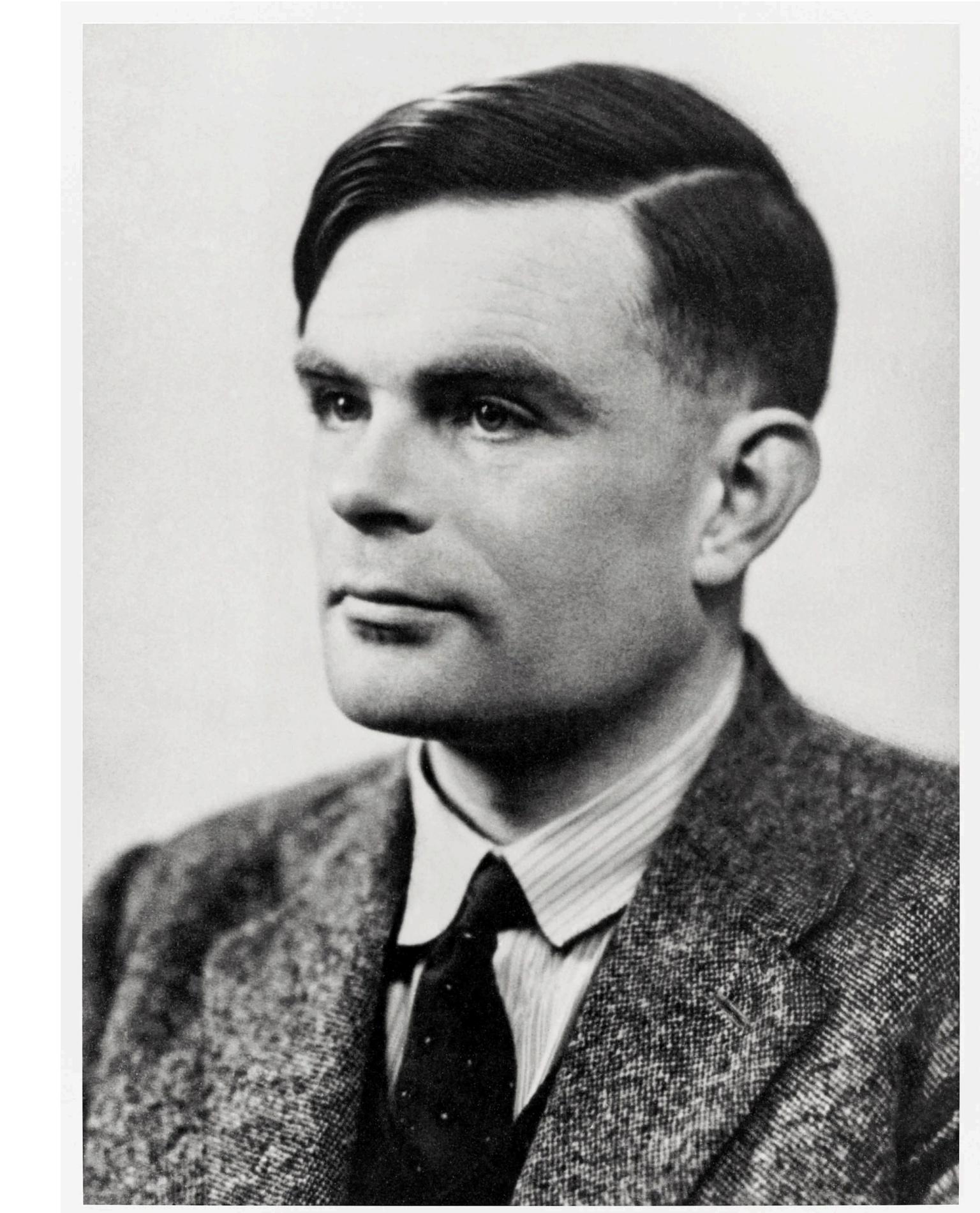
jupyter notebook

log likelihood ratio (LLR) update

$$\text{belief} = \log \frac{P(\text{choice A true} \mid \text{evidence})}{P(\text{choice B true} \mid \text{evidence})}$$

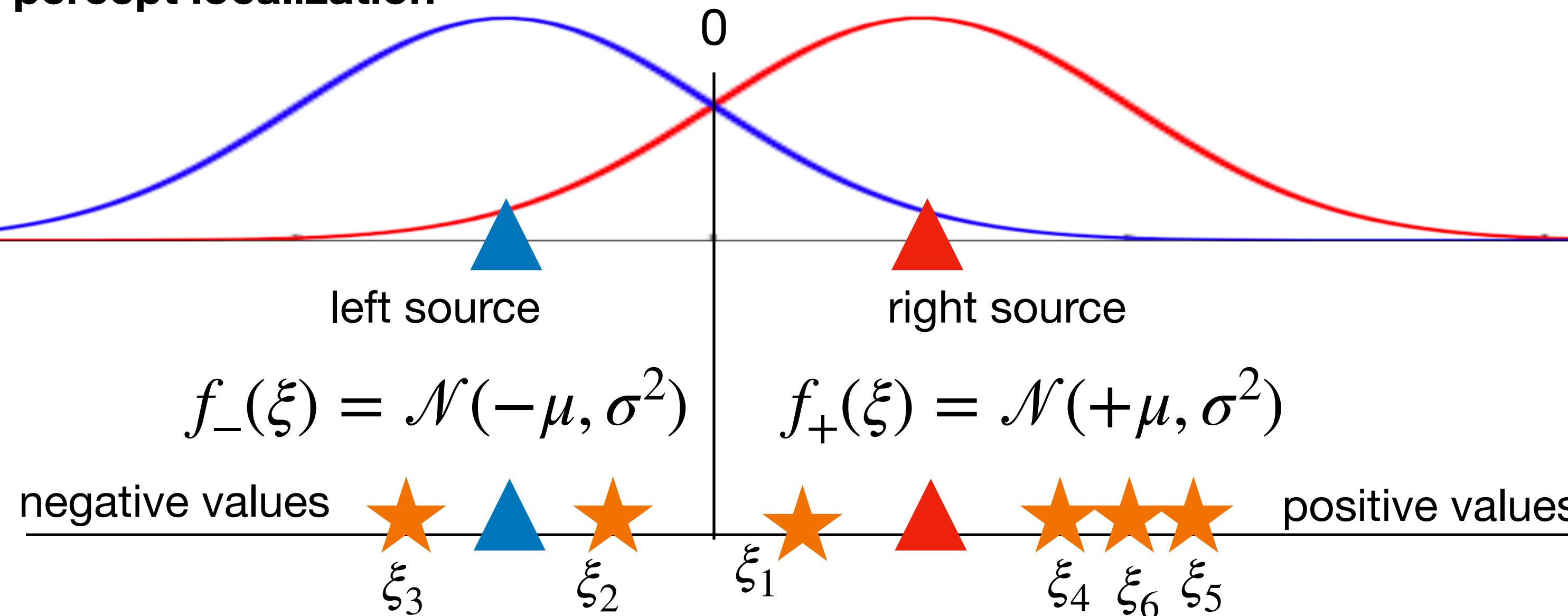


(Neyman & Pearson 1933;
Turing 1942;
Wald & Wolfowitz 1948)



Log-likelihood ratio update

percept localization



information from each observation: $\text{LLR}(\xi) = \log \frac{f_+(\xi)}{f_-(\xi)} = \frac{2\mu}{\sigma^2} \xi$ if positive: *right more likely*
if negative: *left more likely*

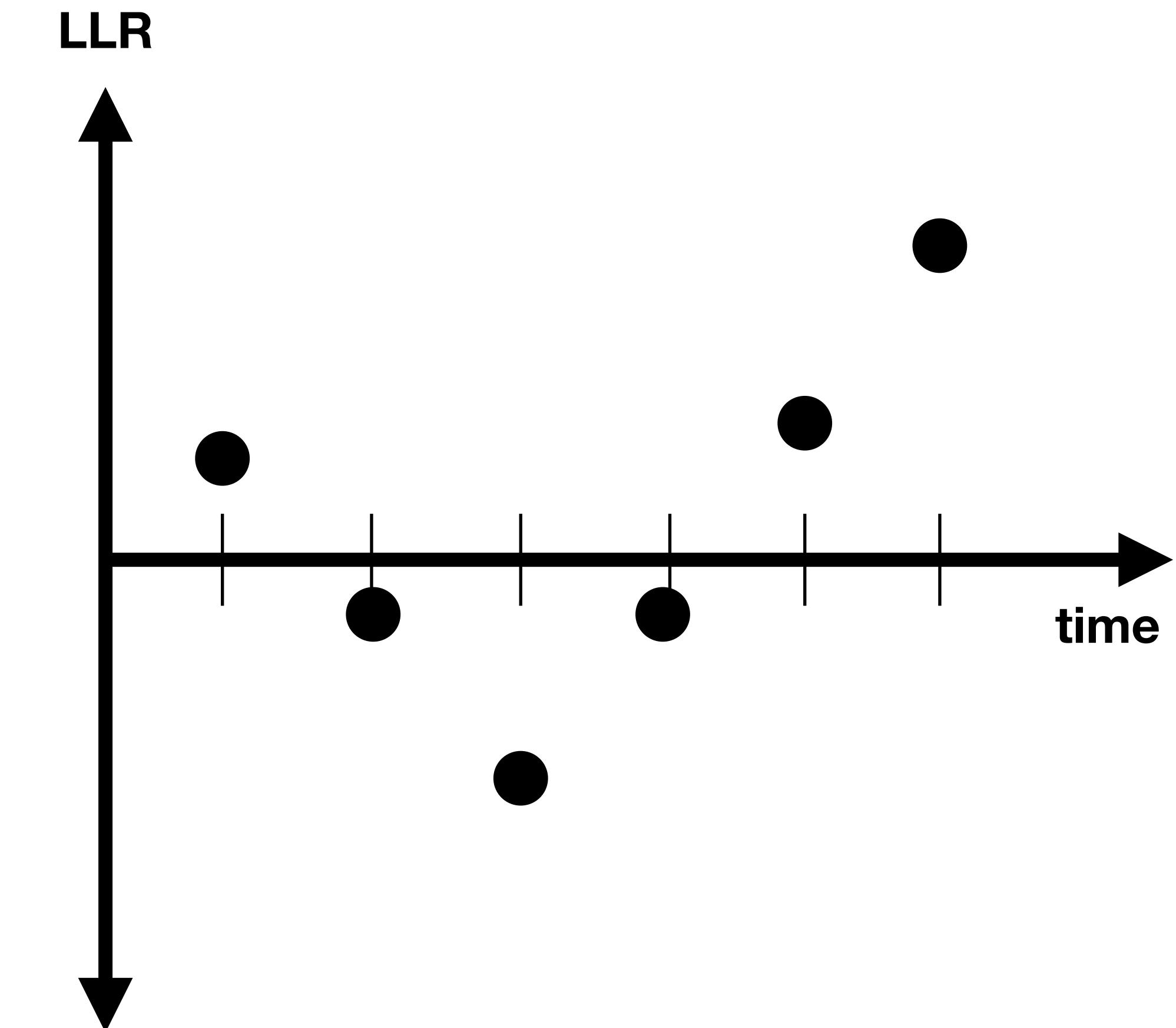
log likelihood ratio
(LLR) update
(Wald 1947; Gold & Shadlen 2002; Bogacz et al 2006)

$$\text{LLR}(\xi_{1:6}) = \frac{2\mu}{\sigma^2} \cdot [\xi_1 + \xi_2 + \xi_3 + \xi_4 + \xi_5 + \xi_6]$$

define $y_t = \text{LLR}(\xi_{1:t})$:

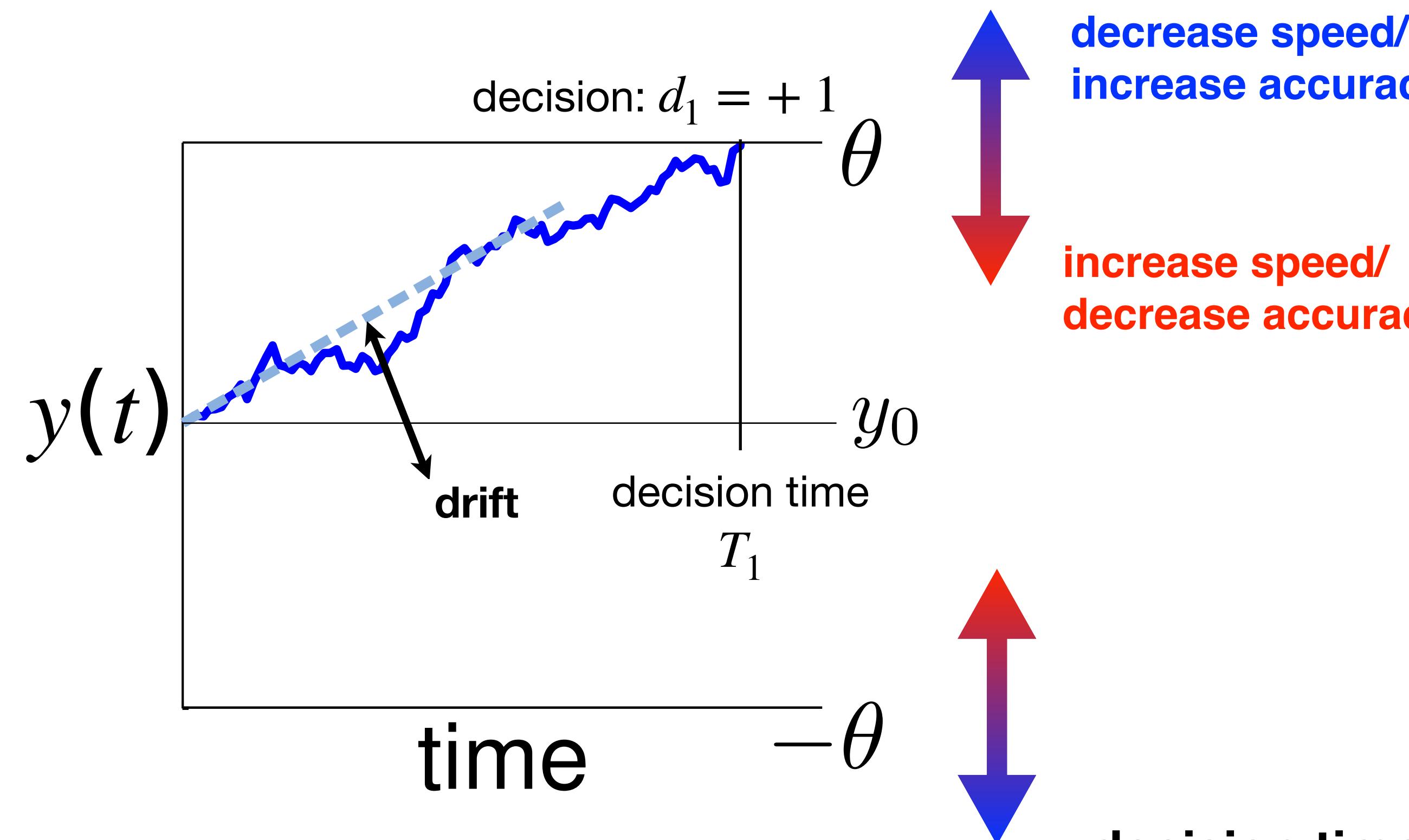
$$y_t \equiv y_{t-1} + \text{LLR}(\xi_t)$$

consider an observer who must determine the location of a stimulus (e.g., visual or auditory) source



Drift diffusion model and decision statistics

$$y_n - y_{n-1} = \text{LLR}(\xi_n) \quad \mapsto \quad \frac{dy}{dt} = \pm 1 + \sqrt{2} \cdot \xi(t)$$



trial-wise data

(d_1, T_1)	(d_2, T_2)	(d_3, T_3)	(d_4, T_4)	...
trial 1	trial 2	trial 3	trial 4	

accuracy

$$\text{Acc} = \frac{1}{N_{\text{trials}}} \sum_{n=1}^{N_{\text{trials}}} \delta_{d_n, +1}$$

$$\log \frac{P(H^+ | \xi_{1:t})}{1 - P(H^+ | \xi_{1:t})} = \theta \quad \rightarrow \quad P(H^+ | \xi_{1:t}) = \frac{1}{1 + e^{-\theta}}$$

decision time distribution: bin T_n into histograms

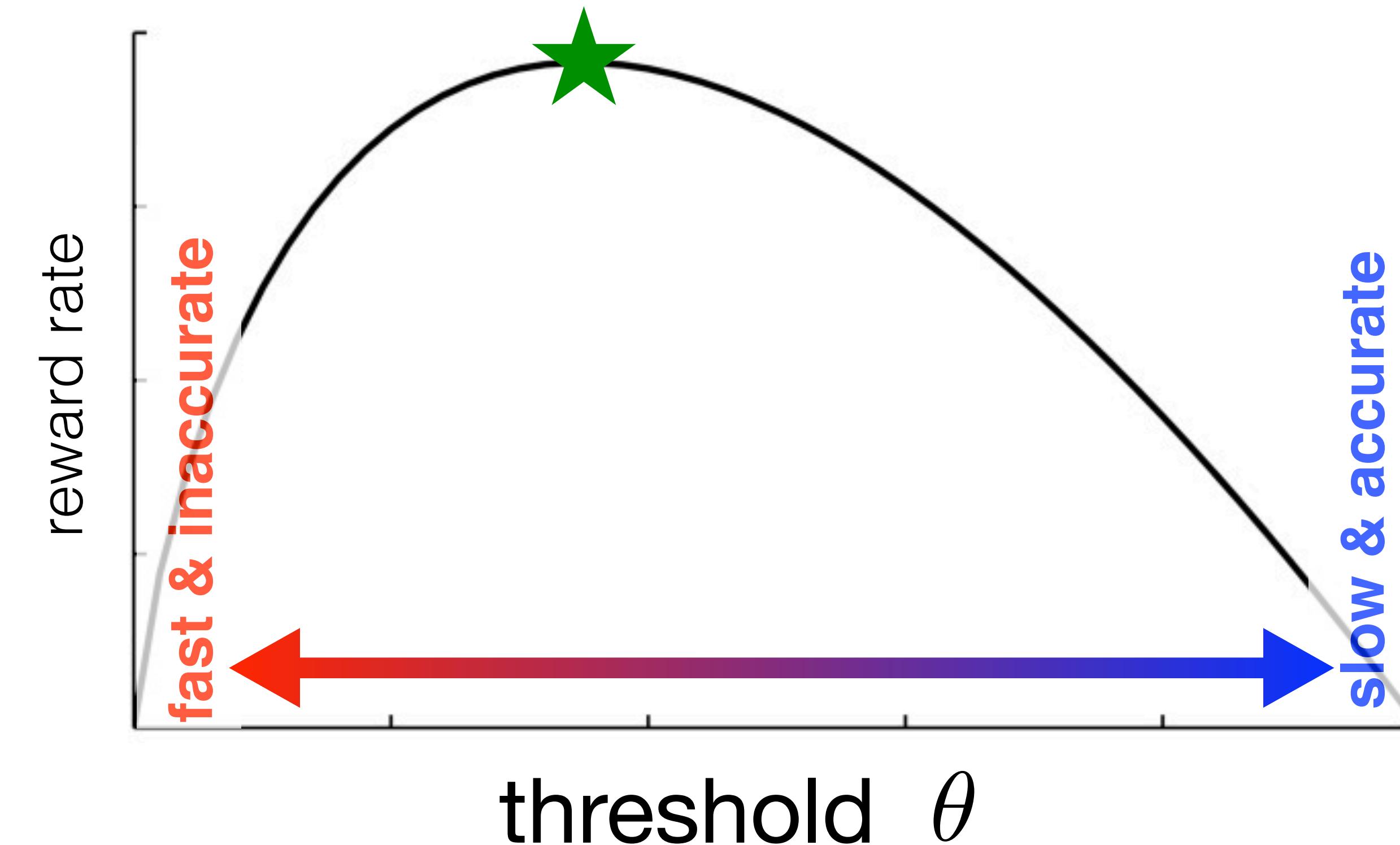
mean decision time:

$$\bar{T} = \frac{1}{N_{\text{trials}}} \sum_{n=1}^{N_{\text{trials}}} T_n$$

Reward rate

$$RR = \frac{\text{percent correct}}{(\text{decision time}) + (\text{penalty time})}$$

(Wald & Wolfowitz 1948;
Gold & Shadlen 2002)

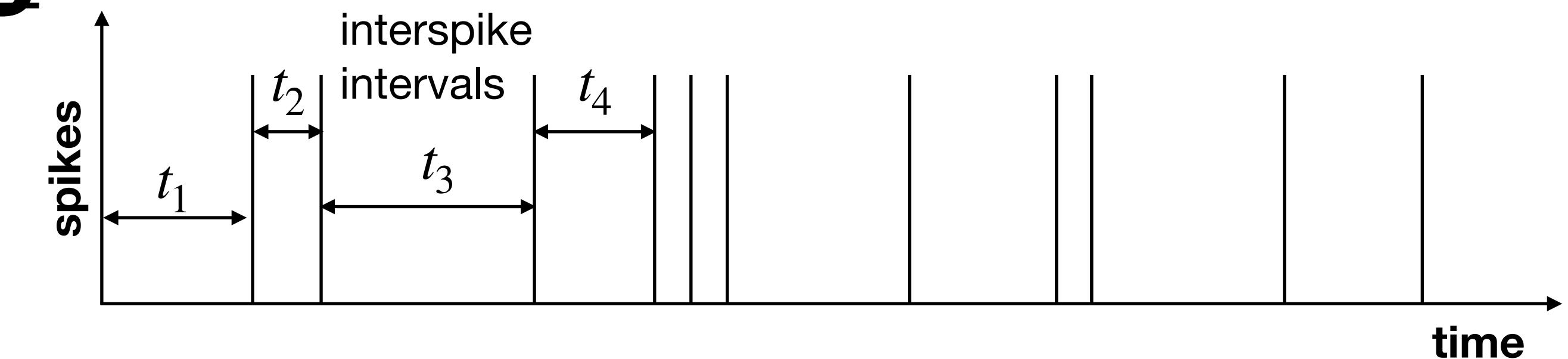


jupyter notebook

Bayesian parameter fitting

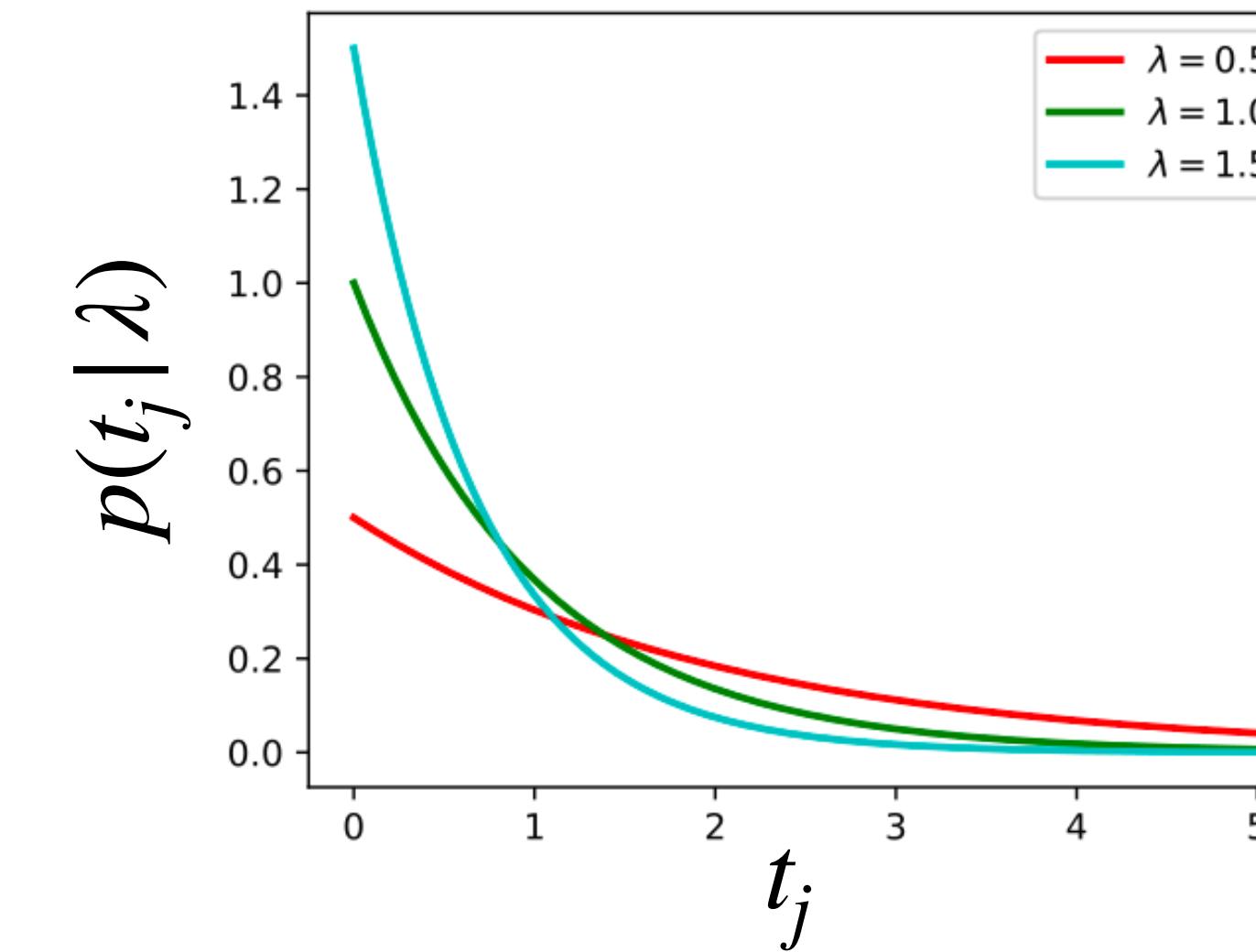
Bayes rule can also be used to fit models

consider a Poisson neuron model with rate parameter λ



interspike intervals are exponentially distributed

$$p(t_j | \lambda) = \lambda e^{-\lambda t_j}$$



Poisson model assumes independence of consecutive spike time intervals

$$p(t_{1:N} | \lambda) = p(t_1 | \lambda)p(t_2 | \lambda) \cdots p(t_N | \lambda)$$

assume λ is not known; we can use Bayes rule to invert the above to find it

$$p(\lambda | t_{1:N}) \propto p(t_1 | \lambda)p(t_2 | \lambda) \cdots p(t_N | \lambda)p(\lambda)$$

might use flat “improper” $p(\lambda) = c$ or something simple $p(\lambda) = e^{-\lambda t_0}$

a major advantage of Bayesian parameter fitting is each observation can be incorporated sequentially to update estimate

$$p(\lambda | t_{1:N}) \propto p(t_N | \lambda) \cdot p(\lambda | t_{1:N-1})$$

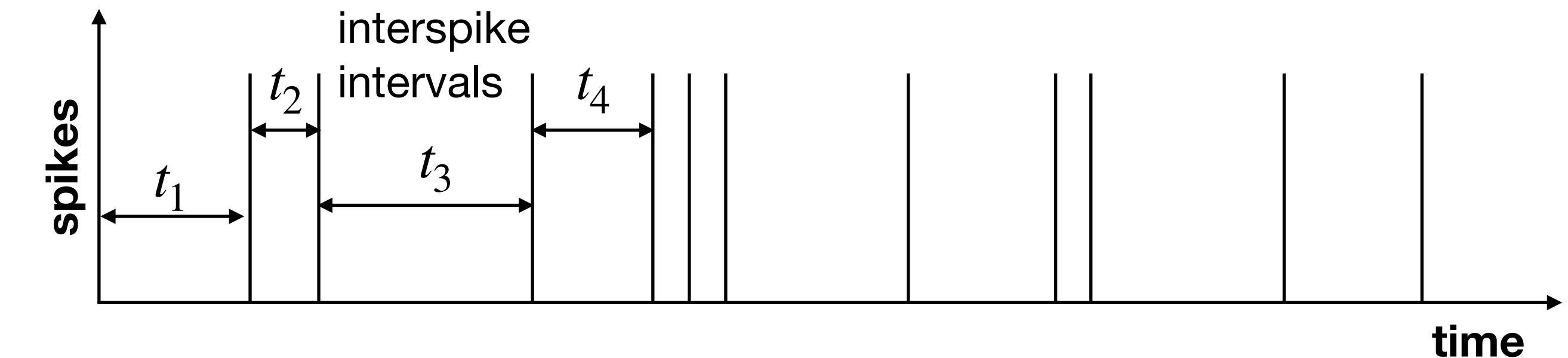
example with exponential waiting times

$$p(\lambda | t_{1:N}) \propto \lambda e^{-\lambda t_1} \lambda e^{-\lambda t_2} \cdots \lambda e^{-\lambda t_N} e^{-\lambda t_0} = \lambda^N e^{-\lambda \sum_{n=0}^N t_n}$$

Bayesian model selection

what if we are deciding between two types of model?

let's say intervals are maybe exponentially or perhaps Gamma distributed: let's see which model is more likely!



$$p(t_j | \lambda) = \lambda e^{-\lambda t_j}$$

exponential

$$p(\lambda) = e^{-\lambda}$$

presumed prior

$$p(t_j | \lambda) = \frac{\beta^{\alpha+1}}{\alpha!} \lambda^\alpha e^{-\beta\lambda}$$

Gamma

$$p(\alpha, \beta) = e^{-\alpha-\beta}$$

presumed prior

OK, now make a few observations from spikes and compute the observation/data (not parametric) posterior for either model

$$\text{exponential} \quad p(t_{1:N} | \lambda) = C_e \lambda^N e^{-\lambda \sum_{n=1}^N t_n}$$

$$\text{Gamma} \quad p(t_{1:N} | \alpha, \beta) = C_g \left(\prod_{n=1}^N t_n \right)^\alpha e^{-\beta \cdot \sum_{n=1}^N t_n}$$

Bayes factor: integrate observation posterior against prior to obtain total model likelihood and compare between models

$$BF = \frac{\sum_{\alpha=0}^{\infty} \int_0^{\infty} p(t_{1:N} | \alpha, \beta) p(\alpha, \beta) d\beta}{\int_0^{\infty} p(t_{1:N} | \lambda) p(\lambda) d\lambda}$$

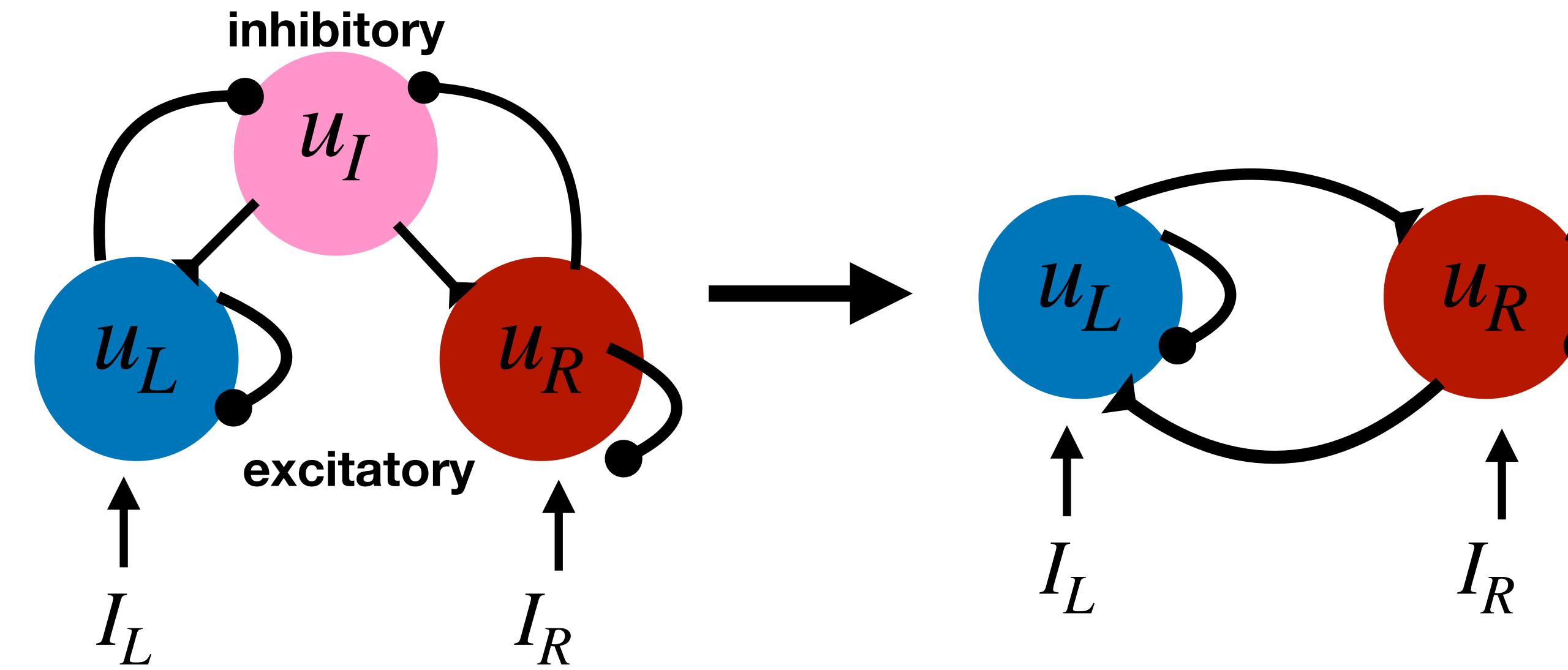
if $BF > 1$, then top model is more likely

if $BF < 1$, then bottom model is more likely

jupyter notebook

Mutual inhibition and winner take all circuits

How can decisions be implemented in a neural circuit? One classic proposed and observed mechanism is mutual inhibition.



$$\frac{du_L}{dt} = -u_L + f(I_L + \alpha u_L - \beta u_R)$$

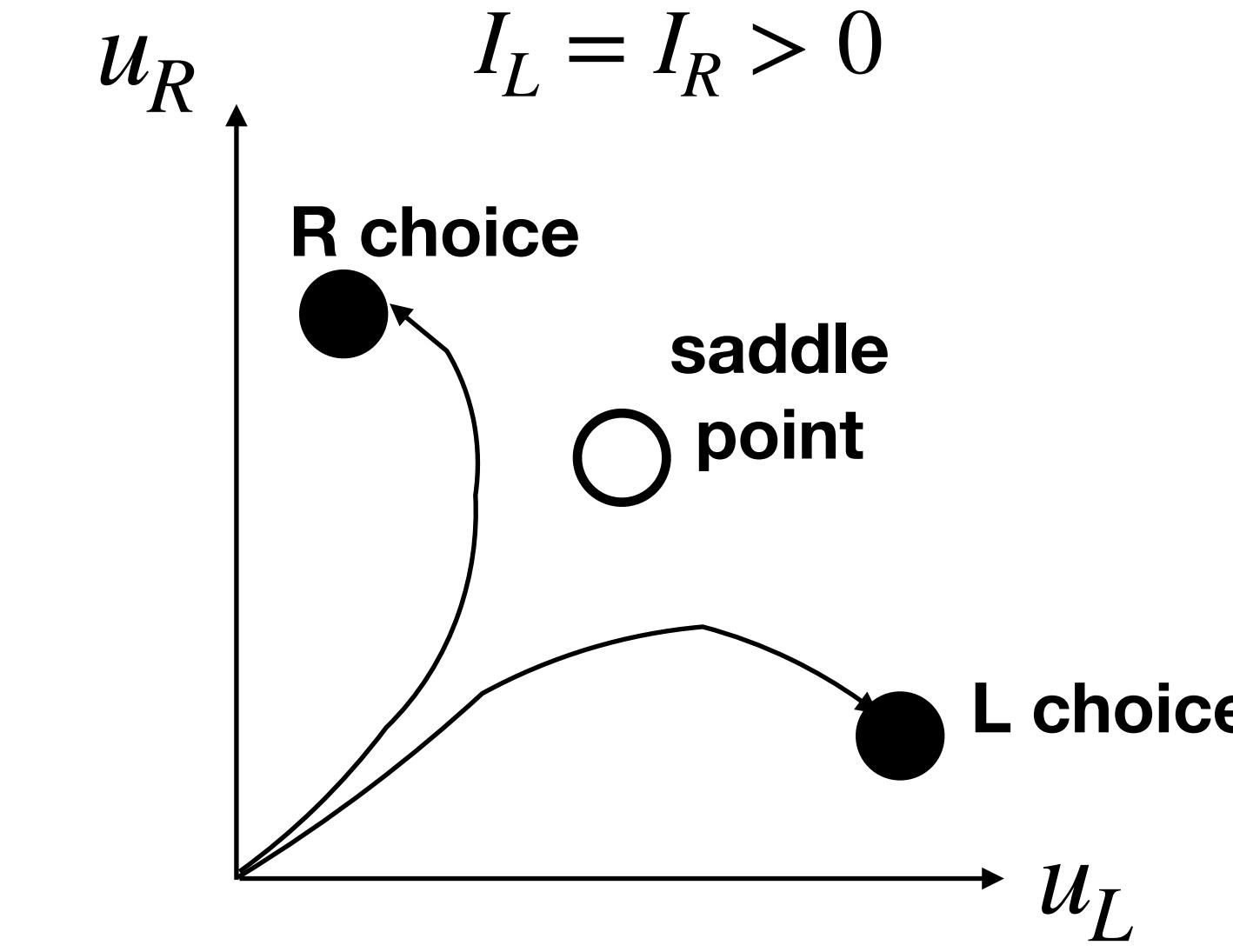
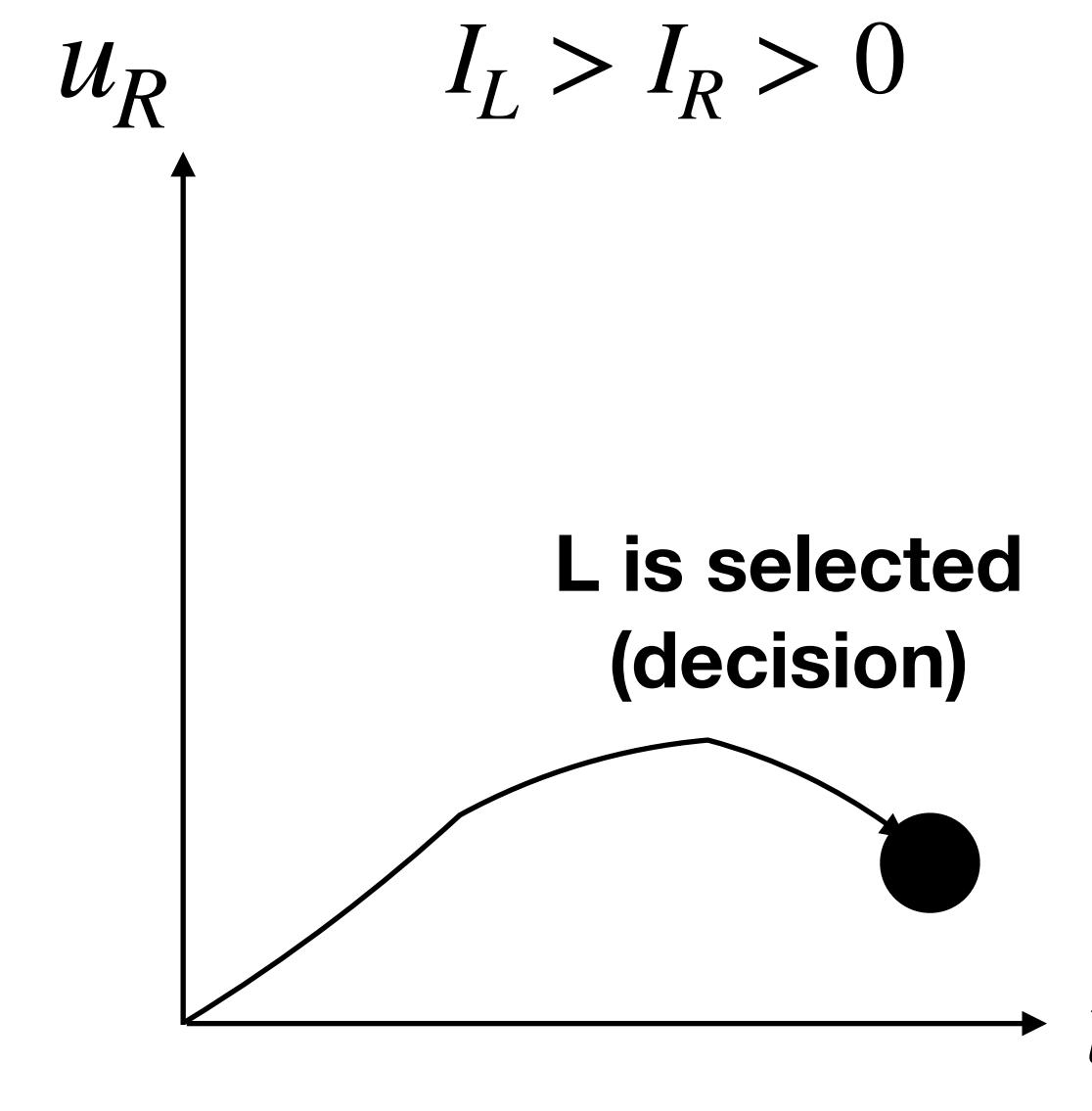
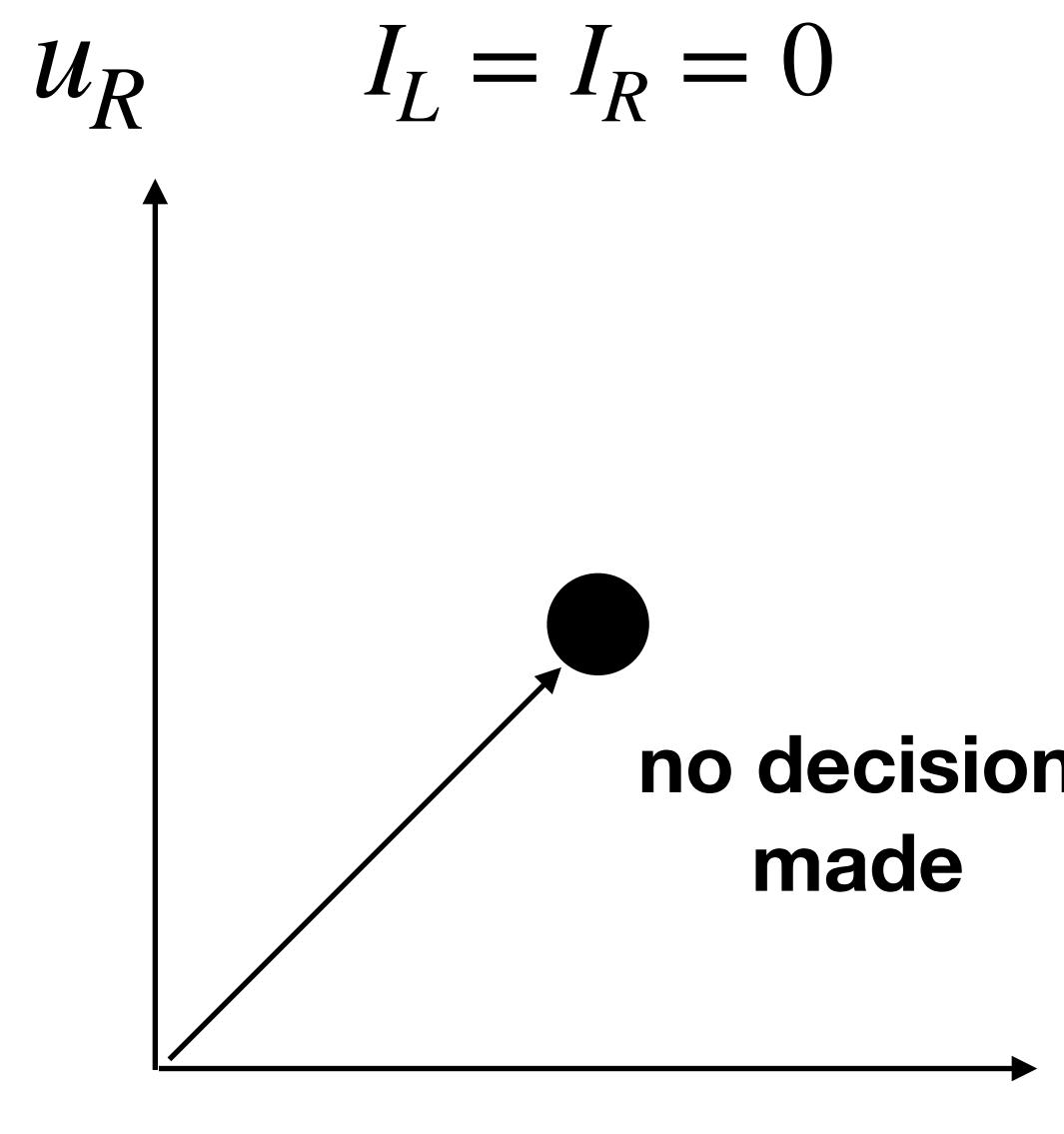
left pop differential equation

$$\frac{du_R}{dt} = -u_R + f(I_R + \alpha u_R - \beta u_L)$$

right pop differential equation

$$f(x) = \frac{1}{1 + e^{-\gamma x}}$$

firing rate function



jupyter notebook