

# An Intro to CGA

## Conformal Geometric Algebra

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*The extraordinary generality and simplicity of projective geometry led the English mathematician Cayley to exclaim: 'Projective Geometry is all of geometry'.*

Source: "Geometric Algebra with Applications in Science and Engineering" by Corrochano & Sobczyk

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## Definition

Letting  $\{w_k\}_{k=1}^m$  be the Gram-Schmidt orthonormalization of  $\{v_k\}_{k=1}^m$ , we have

$$\bigwedge_{k=1}^m v_k = \det \begin{bmatrix} v_1 \cdot e_1 & \dots & v_1 \cdot e_m \\ \vdots & \ddots & \vdots \\ v_m \cdot e_1 & \dots & v_m \cdot e_m \end{bmatrix} \bigwedge_{k=1}^m w_k,$$

where  $\{e_k\}_{k=1}^m$  is any orthonormal basis for the  $m$ -dimensional vector sub-space represented by this blade.

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- Its **attitude**,
- Its  $m$ -dimensional **hyper-volume**,
- Its **handedness**.

# Generating all Elements of a Geometric Algebra

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The geometric algebra  $\mathbb{G}(\mathbb{V}^n)$  is of dimension  $2^n$ .

# Adding Blades Together

## Definition

For any  $E \in \mathbb{G}(\mathbb{V}^n)$ , we let  $\langle E \rangle_k$  denote the grade  $k$  part of  $E$ , and so we may write  $E = \sum_{k=0}^n \langle E \rangle_k$ .

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All  $k$ -blades are  $k$ -vectors, but not all  $k$ -vectors are  $k$ -blades!

## Example

The following 2-vector cannot be written as a 2-blade.

$$e_1 \wedge e_2 + e_3 \wedge e_4$$

# The Inner Product

## Definition

In a Euclidean geometric algebra, we define for all integers  $i$  and  $j$ ,

$$e_i \cdot e_j = \delta_{ij},$$

where here,  $\delta_{ij}$  is the Kronecker delta.

## Definition

If for any vector  $v \in \mathbb{V}^n$ , we have  $v \cdot v = 0$ , we call  $v$  a null vector.

# The Inner Product (Continued)

## Definition

For any vector  $v \in \mathbb{V}^n$  and any  $m$ -blade  $B \in \mathbb{G}(\mathbb{V}^n)$ , we define

$$v \cdot B = - \sum_{i=1}^m (-1)^i (v \cdot b_i) \bigwedge_{j=1, j \neq i}^m b_j,$$

where  $B = \bigwedge_{k=1}^m b_k$ . We also define

$$B \cdot v = -(-1)^m v \cdot B.$$



# The Inner Product (Continued)

## Lemma

For any  $v \in \mathbb{V}^n$  and any blade  $B \in \mathbb{G}(\mathbb{V}^n)$ , we have

$$\begin{aligned}v \wedge B &= v_{\perp} \wedge B \\v \cdot B &= v_{\parallel} \cdot B.\end{aligned}$$

## Example

Consider  $v \cdot B$ , where  $B$  is a 2-blade. WLOG, choose  $a, b \in \mathbb{V}^n$  such that  $B = a \wedge b$ ,  $a \cdot b = 0$ ,  $|b| = 1$  and  $v \cdot b = 0$ . We then have

$$v \cdot B = (v \cdot a)b - (v \cdot b)a = |B| \frac{v \cdot a}{|a|} b.$$

# The Inner Product (Continued)

## Definition

For any two blades  $A, B \in \mathbb{G}(\mathbb{V}^n)$  of grades  $i$  and  $j$ , respectively, we define

$$A \cdot B = \begin{cases} a_1 \cdots a_i \cdot B & \text{if } i \leq j, \text{ (R to L assoc.)} \\ A \cdot b_1 \cdots b_j & \text{if } i \geq j, \text{ (L to R assoc.)} \end{cases}$$

where  $A = \bigwedge_{k=1}^i a_k$  and  $B = \bigwedge_{k=1}^j b_k$ .

# The Geometric Product

## Definition

For any vector  $v \in \mathbb{V}^n$  and any  $m$ -blade  $B \in \mathbb{G}(\mathbb{V}^n)$ , we define

$$vB = v \cdot B + v \wedge B,$$

and similarly,  $Bv = B \cdot v + B \wedge v$ .

## Example

For any two vectors  $a, b \in \mathbb{V}^n$ , we have

$$ab = a \cdot b + a \wedge b = |a||b| \cos \theta + B|a||b| \sin \theta = |a||b| \exp(\theta B),$$

where  $B = \frac{a \wedge b}{|a \wedge b|}$ .

# The Geometric Product (Continued)

## Example

It can be shown that

$$v \cdot B = \frac{1}{2}(vB - (-1)^m Bv),$$

and

$$v \wedge B = \frac{1}{2}(vB + (-1)^m Bv).$$

# The Geometric Product (Continued)

## Definition

For any set of  $m$  vectors  $\{v_k\}_{k=1}^m \subset \mathbb{V}^n$ , a product

$$\prod_{k=1}^m v_k$$

is called a versor if for all integers  $k$ ,  $v_k^{-1}$  exists.

If there exists an integer  $k$  such that  $v_k^{-1}$  does not exist, I call it a pseudo versor.

## Lemma

*In a **Euclidean** geometric algebra, any blade can be written as a versor by the Gram-Schmidt orthogonalization process.*

# The Geometric Product (Continued)

## Example

For any two multivectors  $A, B \in \mathbb{G}(\mathbb{V}^n)$ , we have

$$AB = \phi^{-1}(\phi(A)\phi(B)),$$

where  $\phi$  is an algebraic transformation mapping a multivector to its multi-pseudo-vector form.

## Lemma

*The Gram-Schmidt process cannot always be used on blades taken from a **non-Euclidean** geometric algebra!*

## Proof.

Consider  $a \wedge b$ . If  $a \cdot b \neq 0$  and  $a, b$  are null, then there does not exist a scalar  $\lambda$  such that  $a \cdot (b + \lambda a) = 0$  or  $(a + \lambda b) \cdot b = 0$ .  $\square$

# Blade to Multi-Pseudo-Versor Form

Let  $B \in \mathbb{G}(\mathbb{V}^n)$  be a blade of grade  $m > 1$  where  $B = \bigwedge_{k=1}^m b_k$ .  
We then have

$$\begin{aligned}\phi(B) &= B = b_1 B^{(1)} - b_1 \cdot B^{(1)} \\ &= b_1 \phi(B^{(1)}) - \sum_{i=2}^m (-1)^i (b_1 \cdot b_i) \phi(B^{(1)(i)}),\end{aligned}$$

where  $B^{(i)}$  is notation for the  $(m-1)$ -blade  $\bigwedge_{k=1, k \neq i}^m b_k$ .

## Example

For the blade  $a \wedge b$ , we have  $\phi(a \wedge b) = ab - a \cdot b$ .

# Pseudo-Versor to Multivector Form

Let  $V \in \mathbb{G}(\mathbb{V}^n)$  be a versor of size  $m > 1$  where  $V = \prod_{k=1}^m v_k$ . We then have

$$\begin{aligned}\phi^{-1}(V) &= V = v_1 \sum_{k=0}^m \langle V^{(1)} \rangle_k = \\ &\langle \phi^{-1}(V^{(1)}) \rangle_0 v_1 + \sum_{k=2}^m \left( v_1 \wedge \langle \phi^{-1}(V^{(1)}) \rangle_k + v_1 \cdot \langle \phi^{-1}(V^{(1)}) \rangle_k \right),\end{aligned}$$

where  $V^{(i)}$  is notation for the  $(m-1)$ -sized pseudo-versor  $\prod_{k=1, k \neq i}^m v_k$ .

## Example

For the versor  $ab$ , we have  $\phi^{-1}(ab) = a \cdot b + a \wedge b$ .



# The Geometric Product (Again)

## Lemma

*For any two blades  $A, B \in \mathbb{G}(\mathbb{V}^n)$  of grades  $i$  and  $j$ , respectively, it can be shown that*

$$A \cdot B = \langle AB \rangle_{|i-j|},$$

*and*

$$A \wedge B = \langle AB \rangle_{i+j}.$$

# The Reverse

## Definition

For any  $m$ -sized versor  $V \in \mathbb{G}(\mathbb{V}^n)$  where  $V = \prod_{k=1}^m v_k$ , we define

$$\tilde{V} = \prod_{k=1}^m v_{m-k+1}.$$

We can extend this definition to any multivector if we let the reverse operator distribute over addition.

## Definition

For any multivector  $E \in \mathbb{G}(\mathbb{V}^n)$ , we may write

$$\tilde{E} = \phi^{-1}(\tilde{\phi}(E)).$$

# The Inverse

## Lemma

For any  $m$ -sized versor  $V \in \mathbb{G}(\mathbb{V}^n)$  where  $V = \prod_{k=1}^m v_k$ , we have

$$V^{-1} = \left( \prod_{k=1}^m |v_k| \right)^{-1} \tilde{V}.$$

## Lemma

For any **Euclidean**  $m$ -blade  $B \in \mathbb{G}(\mathbb{V}^n)$  where  $B = \bigwedge_{k=1}^m b_k$ , we have

$$B^{-1} = (-1)^{m(m-1)/2} \frac{\tilde{B}}{|B|}.$$

## Example

If  $v \in \mathbb{V}^n$  is a null vector, then  $v^{-1}$  does not exist.

# Conjugation by Versors

## Lemma

*Conjugation by versors is outermorphic. That is, for any versor  $V = \prod_{k=1}^i v_k$ , and any blade  $B = \bigwedge_{k=1}^j b_k$ , we have*

$$VBV^{-1} = \bigwedge_{k=1}^j Vb_kV^{-1}.$$

The proof of this is not too hard to get, but too big to put here.

## Example

A given rotor  $R \in \mathbb{G}(\mathbb{V}^n)$  is a versor that rotates points  $v \in \mathbb{V}^n$  by versor conjugation. It therefore rotates blades as well!

# Blades Can Represent Vector Spaces

## Definition

For any vector  $v \in \mathbb{V}^n$  and any  $m$ -blade  $B \in \mathbb{G}(\mathbb{V}^n)$  where  $B = \bigwedge_{k=1}^m b_k$ , we say that

$$v \in B \text{ if and only if } v \in \text{span}\{b_k\}_{k=1}^m$$

## Lemma

*We have  $v \in B$  if and only if  $v \wedge B = 0$ .*

## Lemma

*We have  $v \in B^*$  if and only if  $v \cdot B = 0$ .*

## Proof.

Notice that  $0 = v \cdot B = (v \wedge BI)I$  if and only if  $v \wedge BI = 0$ . □

# How Blades Can Represent Geometry

Let  $\mathbb{V}^n$  denote a **Euclidean** vector space.

Let  $\mathbb{V}$  denote any other vector space.

Let  $p : \mathbb{V}^n \rightarrow \mathbb{G}(\mathbb{V})$  be a blade-valued function of points.

## Definition

Given any blade  $B \in \mathbb{G}(\mathbb{V})$ , we say that  $B$  **directly** represents the geometry that consists of all points

$$G(B) = \{x \in \mathbb{V}^n | p(x) \in B\}.$$

## Definition

Given any blade  $B \in \mathbb{G}(\mathbb{V})$ , we say that  $B$  **dually** represents the geometry that consistent of all points

$$G^*(B) = \{x \in \mathbb{V}^n | p(x) \in B^*\}.$$

# Intersecting Geometries

## Lemma

*For any two blades  $A, B \in \mathbb{G}(\mathbb{V})$  such that  $A \wedge B \neq 0$ , we have*

$$G^*(A) \cap G^*(B) = G^*(A \wedge B).$$

## Proof.

$$\begin{aligned} & p(x) \in A^* \text{ and } p(x) \in B^* \\ \text{iff } & p(x) \notin A \text{ and } p(x) \notin B \\ \text{iff } & p(x) \notin A \wedge B \\ \text{iff } & p(x) \in (A \wedge B)^* \end{aligned}$$



# Combining Geometries

## Lemma

*For any two blades  $A, B \in \mathbb{G}(\mathbb{V})$  such that  $A \wedge B \neq 0$ , we have*

$$G(A) \cup G(B) \subseteq G(A \wedge B).$$

## Proof.

$$\begin{aligned} & p(x) \in A \text{ or } p(x) \in B \\ \implies & p(x) \in A \wedge B \end{aligned}$$



Let  $C \subset A \wedge B$  represent the smallest vector sub-space such that  $p(x) \in C$ . Then we might have  $C \not\subset A$  and  $C \not\subset B$ .



# Finally, The Conformal Model

Let  $\mathbb{V}^n$  be a vector-subspace of  $\mathbb{V}$ .

If  $\{e_k\}_{k=1}^n$  is any basis for  $\mathbb{V}^n$ , let  $\{e_k\}_{k=1}^n \cup \{o, \infty\}$  be a basis for  $\mathbb{V}^n$ .

## Definition

For any vector  $v \in \mathbb{V}^n$ , we define  $v \cdot o = v \cdot \infty = 0$ . We define  $o \cdot \infty = \infty \cdot o = -1$ . Each of  $o$  and  $\infty$  are defined as null.

## Definition

We define  $p : \mathbb{V}^n \rightarrow \mathbb{G}(\mathbb{V})$  as

$$p(x) = o + x + \frac{1}{2}x^2\infty.$$

What we can now discover about this model of geometry is almost endless!

# Vectors In The Conformal Model

## Lemma

*For any  $x \in \mathbb{V}^n$  and any scalar  $r > 0$ , the vector*

$$p(x) - \frac{1}{2}r^2\infty$$

*dually represents an  $n$ -dimensional hyper-sphere.*

## Lemma

*For any  $x \in \mathbb{V}^n$  and any unit-length vector  $v \in \mathbb{V}^n$ , the vector*

$$v + (x \cdot v)\infty$$

*dually represents an  $(n - 1)$ -dimensional hyper-plane.*

# Generating All Rounds And Flats

## Lemma

Let  $\{\sigma_k\}_{k=1}^m$  be a sequence of *dual*  $n$ -dimensional hyper-spheres. Then

$$\bigwedge_{k=1}^m \sigma_k$$

may be a *dual*  $(n - m + 1)$ -dimensional hyper-sphere.

## Lemma

Let  $\{\pi_k\}_{k=1}^m$  be a sequence of *dual*  $(n - 1)$ -dimensional hyper-planes. Then

$$\bigwedge_{k=1}^m \pi_k$$

may be a *dual*  $(n - m)$ -dimensional hyper-plane.

# General Term For Coplanar

## Definition

A set of  $m + 2$  points  $\{x_k\}_{k=1}^{m+2}$  are **co- $m$ -hyper-planar** if...

For  $m = 0$ , the points are identical,

For  $m = 1$ , the points are collinear,

For  $m = 2$ , the points are coplanar,

For  $m = 3$ , the points are co-hyper-planar,  
etc...

## Lemma

*If  $m + 1$  points  $\{x_k\}_{k=1}^{m+1} \subset \mathbb{V}^n$  are non-co- $(m - 1)$ -hyper-planar, then  $\{p(x_k)\}_{k=1}^{m+1}$  is a linearly independent set.*

# Fitting Rounds To Points

## Lemma

For  $m + 1$  points  $\{x_k\}_{k=1}^{m+1}$  on an  $m$ -dimensional hyper-sphere that are non-co- $(m - 1)$ -hyper-planar, the blade

$$\bigwedge_{k=1}^{m+1} p(x_k)$$

*directly* represents the  $m$ -dimensional hyper-sphere.

## Proof.

Let the  $(n - m + 1)$ -blade  $B$  **dually** represent the sphere. Then for all  $k$ , we have  $p(x_k) \in B^*$  and  $\text{grade}(B^*) = n + 2 - (n - m + 1) = m + 1$ . Lastly,  $\{p(x_k)\}_{k=1}^{m+1}$  is a linearly independent set. □

# Fitting Flats To Points

## Lemma

For  $m + 2$  points  $\{x_k\}_{k=1}^{m+2}$  on an  $m$ -dimensional hyper-plane that are (1) non-co- $(m - 1)$ -hyper-planar and (2) non-co- $m$ -hyper-spherical, the blade

$$\bigwedge_{k=1}^{m+2} p(x_k)$$

*directly* represents the  $m$ -dimensional hyper-plane.

## Proof.

Let the  $(n - m)$ -blade  $B$  *dually* represent the plane. By (1) and (2),  $\{p(x_k)\}_{k=1}^{m+2}$  is linearly independent. Then  $\text{grade}(B^*) = n + 2 - (n - m) = m + 2$ . □

# Fitting Flats To Points (Continued)

## Lemma

*For  $m + 1$  points  $\{x_k\}_{k=1}^{m+1}$  on an  $m$ -dimensional hyper-plane that are non-co- $(m - 1)$ -hyper-planar, the blade*

$$\infty \wedge \bigwedge_{k=1}^{m+1} p(x_k)$$

*directly represents the  $m$ -dimensional hyper-plane.*

# Conformal Transformations

## Lemma

*Let  $V \in \mathbb{G}(\mathbb{V})$  be a versor. Let the  $m$ -blade  $B \in \mathbb{G}(\mathbb{V})$  directly represent any geometry of the conformal model, (except a flat point). Then the transformation*

$$VBV^{-1} = \bigwedge_{k=1}^m Vp(x_k)V^{-1}$$

*is understood if  $Vp(x_k)V^{-1}$  is understood.*

Compare this idea to linear transformations determined by a basis of a vector space.