

SDS 383D: Exercises 3 – Linear smoothing and Gaussian processes

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Problem 1

Basic Concepts

(A)

Problem 2

Curve fitting by linear smoothing

In this problem, consider a general nonlinear regression with one predictor and one response, $y_i = f(x_i) + \epsilon_i$, where ϵ_i are mean-zero random variables.

- (A) For now, consider a linear regression on a response y_i with one predictor x_i , and both y_i and x_i have had their means subtracted, so the $y_i = \beta x_i + \epsilon_i$. Define $S_x := \sum_{i=1}^n x_i^2$. The least squares estimate for the coefficient, from Exercises 1, is

$$\begin{aligned}\hat{\beta} &= (X^T X)^{-1} X^T y \\ &= (x^T x)^{-1} x^T y \\ &= \frac{\sum_{i=1}^n x_i \cdot y_i}{\sum_{i=1}^n x_i^2} \\ &= \frac{\sum_{i=1}^n x_i \cdot y_i}{S_x} \\ &= \sum_{i=1}^n \frac{x_i}{S_x} \cdot y_i.\end{aligned}$$

So now our prediction $y^*|x^*$ is,

$$\begin{aligned}\hat{y}^* &= \hat{f}(x^*) \\ &= \hat{\beta} x^* \\ &= \left(\sum_{i=1}^n \frac{x_i}{S_x} \cdot y_i \right) \cdot x^* \\ &= \sum_{i=1}^n \left(\frac{x_i}{S_x} \cdot x^* \right) \cdot y_i,\end{aligned}$$

which we recognize as being in the form of the general *linear smoother*

$$\hat{f}(x^*) = \sum_{i=1}^n w(x_i, x^*) \cdot y_i$$

for some weight function $w(x_i, x^*)$. In particular, the weight function for linear regression gives weight to each y_i proportional to the value of x_i . Contrast this with the k -nearest neighbors smoothing weight function,

$$w_K(x_i, x^*) = \begin{cases} 1/K & \text{if } x_i \text{ is one of the } K \text{ closest sample points to } x^* \\ 0 & \text{otherwise} \end{cases},$$

which gives *equal* weight to y_i s but *only* to the k -nearest neighbors of x^* .

- (B) Now we have the very general weight function

$$w(x_i, x^*) = \frac{1}{h} \cdot K\left(\frac{x_i - x^*}{h}\right)$$

where $K(\bullet)$ is some kernel

Problem 3

Cross validation

(A)

Problem 4

Local polynomial regression

(A)

Problem 5

Gaussian processes

(A)

Problem 6

In nonparametric regression and spacial smoothing

(A)

R code for myfuns03.R

```
#####
##### Created by Spencer Woody on 11 Feb 2017 #####
#####

5 # =====
# Linear smoothing =====
# =====

lin.smooth <- function(x.new, x, y, kern.fun, h) {
10 # -----
# Linear smoother for some kernel function
# -----
# INPUTS:
# x.new – a new point for which to estimate f(x.new)
15 # x – a vector of covariates from previous observations
# y – a vector of responses from previous observations
# kern.fun – some kernel function (e.g. Gaussian)
# *** takes 2 arguments: distance (dist) and bandwidth (h)
# h is the bandwidth for the kernel function
20 # -----
# OUTPUT:
# weights – a vector of weights for a new observation
# -----

25 weights <- kern.fun(dist = x - x.new, h = h) / h
weights <- weights / sum(weights)

fit <- crossprod(weights, y)

30 return(fit)
}

kern.unif <- function(dist, h) {
35 # -----
# Uniform kernel function
# -----
# INPUTS:
# dist
# h is
40 # Sigma is the covariance matrix
# -----
# OUTPUT:
# kern – the value of the uniform kernel function
# -----

45 kern <- ( (dist / h) <= 1) / 2

return(kern)
}

50 kern.norm <- function(dist, h) {
# -----
```



```

# Gaussian (normal) kernel function
# -----
55 # INPUTS:
# dist the distance
# h is
# Sigma is the covariance matrix
# -----
60 # OUTPUT:
# kern is the value of the Gaussian kernel function
# -----

kern <- 1 / sqrt(2 * pi) * exp(-dist^2 / 2)

65 return(kern)
}

sprintf("Be sure to ")

70 make.noise <- function(x, f, res.fun) {
# -----
# Simulate noisy data from some non-linear function
# -----
75 # INPUTS:
# x - the number of points from noisy distribution
# f - a function for the expected value, E(y) = f(x)
# res.fun - a mean-zero function for the distribution of residuals
#          (e.g. rnorm(), etc.)
# -----
80 # OUTPUT:
# noise - the simulated data
# -----

85 noise <- f(x) + res.fun(n = length(x))

return(noise)
}

90 # =====
# Gaussian process =====
# =====

my.mvn <- function(n, mu, Sigma) {
95 # Simulate n draws from MVN(mu, Sigma)
#
# Note: this function assumes that X already has an intercept term
# (or doesn't, if we want to force OLS through the origin)
#
100 # INPUTS:
# n is the number of draws
# mu is the mean vector
# Sigma is the covariance matrix
#
105 # OUTPUT:

```

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# x is matrix of n draws from MVN(mu, Sigma) [with n rows, p columns]
#

# dimension of MVN
110 p <- length(mu)

# Check if inputs are valid (dimensions match, Sigma is square and p.s.d.)
cond<- (ncol(Sigma) != p) |
        (nrow(Sigma) != p) |
115         (max(eigen(Sigma)$values) <= 0)

if (cond) {
    return("Try again...")
}

120 # Generate n*p univariate standard normal variables
z     <- matrix(rnorm(n*p), nrow = p)

# Create a matrix containing copies of mu
125 mumat <- matrix(rep(mu, n), nrow = p)

# Decompose Sigma into Sigma = L %*% Lt
Lt <- chol(Sigma)

130 # Generate sample with affine transformation of z
x <- crossprod(Lt, z) + mumat

return(t(x))
}

135 ell2 <- function(x) {
    # Compute the ell2 norm of x, a vector in Euclidean space

    return(sqrt(sum(x^2)))
}

140 C.SE <- function(x.i, x.j, params = NA) {
    # -----
    # Compute the (i, j) element of a squared exp. covariance matrix
    # -----
    # INPUTS:
    # x.i and x.j are two vectors in same space (need not be [0, 1])
    # params should be a vector of three hyperparameters
    # 1) b
    # 2) tau1.sq
    # 3) tau2.sq
    # -----
    # OUTPUT:
    # c.se is the value of the Matern-5/2 covariance matrix for x.i and x.j
    # -----

```

```

160   if (prod(is.na(params))) {
       return("Must have three valid parameters.")
   }

165   if (length(params) != 3) {
       return("Must have three valid parameters.")
   }

       b      <- params[1]
       tau1.sq <- params[2]
       tau2.sq <- params[3]

170

       b      <- params[1]
       tau1.sq <- params[2]
       tau2.sq <- params[3]

175

       # Euclidean distance between x.i and x.j
       d <- ell12(x.i - x.j)

       c.se <- tau1.sq * exp(-0.5 * (d / b)^2) + tau2.sq * (x.i == x.j)

180   return(c.se)
}

C.M52 <- function(x.i, x.j, params = NA) {
185   # -----
       # Compute the (i, j) element of a Matern-5/2 covariance matrix
       # -----
       # INPUTS:
190   # x.i and x.j are two vectors in same space (need not be [0, 1])
       # params should be a vector of three hyperparameters
       # 1) b
       # 2) tau1.sq
       # 3) tau2.sq
195   # -----
       # OUTPUT:
       # c.m52 is the value of the Matern-5/2 covariance matrix for x.i and x.j
       # -----

200   if (prod(is.na(params))) {
       return("Must have three valid parameters.")
   }

205   if (length(params) != 3) {
       return("Must have three valid parameters.")
   }

       b      <- params[1]
       tau1.sq <- params[2]
       tau2.sq <- params[3]

210

```

```

# Euclidean distance between x.i and x.j
d <- ell2(x.i - x.j)

c.m52 <- tau1.sq * ( 1 + (5^0.5 * d / b) + (5 / 3 * (d / b)^2) ) *
  exp(-5^0.5 * d / b) + tau2.sq * (x.i == x.j)

return(c.m52)
}

make.covmat <- function(x, cov.fun, params = NA) {
  # -----
  # Compute the covariance matrix for a GP, given some cov. function
  # -----
  # INPUTS:
  # x is a vector of N values in [0, 1]
  # params should be a vector of three hyperparameters
  # 1) b
  # 2) tau1.sq
  # 3) tau2.sq
  # -----
  # OUTPUT:
  # covmat is the covariance matrix of GP
  # -----

  if (prod(is.na(params))) {
    return("Must have three valid parameters.")
  }

  if (length(params) != 3) {
    return("Must have three valid parameters.")
  }

  N <- length(x)

  covmat <- matrix(nrow = N, ncol = N)

  for (j in 1:N) {
    for (i in j:N) {
      covmat[i, j] <- cov.fun(x[i], x[j], params = params)
      covmat[j, i] <- covmat[i, j]
    }
  }

  return(covmat)
}

```

R code for exercises03.R

```
#####
##### Created by Spencer Woody on 11 Feb 2017 #####
#####

5 # =====
# Gaussian process =====
# =====

library(ggplot2)

10 source("myfuns03.R")

x.seq <- seq(0, 1, length.out = 100)

15 b <- 1
tau1.sq <- 1e-6
tau2.sq <- 1e-5

myparams <- c(b, tau1.sq, tau2.sq)

20 xCM52 <- make.covmat(x.seq, C.M52, params = myparams)
xSE <- make.covmat(x.seq, C.SE, params = myparams)
```