

CH 6. 1차 미지수 포함된 미분방정식

1차 미지수 포함된 미분방정식 (First-order linear coupled differential Equation)

General form

$$x'_1(t) = a_{11}(t)x_1(t) + a_{12}(t)x_2(t) + \dots + a_{1m}(t)x_m(t) + g_1(t)$$

$$x'_2(t) = a_{21}(t)x_1(t) + a_{22}(t)x_2(t) + \dots + a_{2m}(t)x_m(t) + g_2(t)$$

⋮

$$x'_m(t) = a_{m1}(t)x_1(t) + a_{m2}(t)x_2(t) + \dots + a_{mm}(t)x_m(t) + g_m(t)$$

Let

$$X(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \\ \vdots \\ x_m(t) \end{pmatrix}$$

$$A(t) = \begin{pmatrix} a_{11}(t) & a_{12}(t) & \cdots & a_{1m}(t) \\ a_{21}(t) & a_{22}(t) & \cdots & a_{2m}(t) \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}(t) & a_{m2}(t) & \cdots & a_{mm}(t) \end{pmatrix}$$

$$G(t) = \begin{pmatrix} g_1(t) \\ g_2(t) \\ \vdots \\ g_m(t) \end{pmatrix}$$

⇒ General Form

$$\underline{x'(t) = A(t)X(t) + G(t)}$$

If $G(t)=0$, homogeneous differential Equation

If $G(t)\neq 0$, non-homogeneous differential Equation

p=7

(07/21 6.1)

$$x_1' = 3x_1 + 3x_2 + 8$$

$$x_2' = x_1 + 5x_2 + 4e^{3t}$$

$$\Rightarrow \begin{pmatrix} x_1 \\ x_2 \end{pmatrix}' = \begin{pmatrix} 3 & 3 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} x_1 \\ x_2 \end{pmatrix} + \begin{pmatrix} 8 \\ 4e^{3t} \end{pmatrix}$$

solution

$$x_1(t) = 3e^{2t} + e^{6t} - 4e^{3t} - \frac{10}{3} \quad \Rightarrow \text{인수분해!!}$$

$$x_2(t) = -e^{2t} + e^{6t} + \frac{2}{3}$$

$$X(t) = \begin{pmatrix} x_1(t) \\ x_2(t) \end{pmatrix} = \begin{pmatrix} 3e^{2t} + e^{6t} - 4e^{3t} - \frac{10}{3} \\ -e^{2t} + e^{6t} + \frac{2}{3} \end{pmatrix}$$

solution vector *

p228

07/21 6.1

If $a_{ij}(t)$ and $g_j(t)$ are continuous, the differential equation

$$X' = A X + G \quad X(t_0) = X_0$$

has unique solution.

6.2 : Homogeneous equation

If x_1, x_2, \dots, x_k are solution of the homogeneous equation

$$\dot{x} = Ax,$$

$c_1 x_1 + c_2 x_2 + \dots + c_k x_k$ is also solution.

page

(Ex) 6.3)

$$\dot{x} = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} x$$

$$x_1 = \begin{pmatrix} -2e^{3t} \\ e^{3t} \end{pmatrix} \quad x_2 = \begin{pmatrix} (1-2t)e^{3t} \\ te^{3t} \end{pmatrix} \Rightarrow \text{独立 시켜 줄 것 !!}$$

solution vector

Then

$$c_1 x_1 + c_2 x_2 = \begin{pmatrix} -[2c_1 t + (2c_2 - c_1)]e^{3t} \\ (c_2 t + c_1)e^{3t} \end{pmatrix} \Rightarrow \text{独立 시켜 줄 것 !!}$$

is also solution vector.

P230

16.21.6.4: General solution of homogeneous equation

Consider a homogeneous equation

$$\dot{X} = A X,$$

where A is $m \times m$ matrix.

Let $X_1(t), X_2(t), \dots, X_m(t)$ are solution vectors of the

homogeneous equation and linearly-independent.

Then the general solution of the homogeneous equation is

$$X = C_1 X_1(t) + C_2 X_2(t) + \dots + C_m X_m(t)$$

* Linearly-independent condition:

$$\text{Let } X_1(t) = \begin{pmatrix} x_{11}(t) \\ x_{12}(t) \\ \vdots \\ x_{1m}(t) \end{pmatrix}, \quad X_2(t) = \begin{pmatrix} x_{21}(t) \\ x_{22}(t) \\ \vdots \\ x_{2m}(t) \end{pmatrix}, \quad \dots, \quad X_m(t) = \begin{pmatrix} x_{m1}(t) \\ x_{m2}(t) \\ \vdots \\ x_{mm}(t) \end{pmatrix}$$

Consider $m \times m$ determinant

$$W = \begin{vmatrix} x_{11}(t) & x_{12}(t) & \cdots & x_{1m}(t) \\ x_{21}(t) & x_{22}(t) & \cdots & x_{2m}(t) \\ \vdots & \vdots & & \vdots \\ x_{m1}(t) & x_{m2}(t) & \cdots & x_{mm}(t) \end{vmatrix}$$

If $W \neq 0$, $\{X_1, X_2, \dots, X_m\}$ is linearly-independent

If $W = 0$, $\{X_1, X_2, \dots, X_m\}$ is linearly-dependent. *

p230 (2021 6.4)

$$\dot{x} = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} x$$

$$x_1 = \begin{pmatrix} -2e^{3t} \\ e^{3t} \end{pmatrix} \quad x_2 = \begin{pmatrix} (1-2t)e^{3t} \\ te^{3t} \end{pmatrix}$$

solution vector

$$W = \begin{vmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{vmatrix} = -e^{6t} \neq 0$$

Therefore $\{x_1, x_2\}$ is linearly independent.

General solution

$$x(t) = c_1 x_1 + c_2 x_2$$

$$\Rightarrow x(t) = c_1 \begin{pmatrix} -2e^{3t} \\ e^{3t} \end{pmatrix} + c_2 \begin{pmatrix} (1-2t)e^{3t} \\ te^{3t} \end{pmatrix}$$

$$= \begin{pmatrix} -2c_1 e^{3t} + c_2 (1-2t)e^{3t} \\ c_1 e^{3t} + c_2 t e^{3t} \end{pmatrix}$$

$$= \begin{pmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$= Q(t) \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$\Omega(t) = \begin{pmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{pmatrix}$$

* 기본행렬 (fundamental matrix)

P231

(07/21/6.5)

$$X' = \begin{pmatrix} 1 & -4 \\ 1 & 5 \end{pmatrix} X \quad X(0) = \begin{pmatrix} -2 \\ 2 \end{pmatrix}$$

general solution

$$X(t) = \Omega(t) \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

$$= \begin{pmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

$$X(0) = \begin{pmatrix} -2 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} = \begin{pmatrix} -2 \\ 2 \end{pmatrix}$$

$$-2C_1 + C_2 = -2$$

$$C_1 = 3$$

$$\Rightarrow C_1 = 3$$

$$C_2 = 4$$

$$\Rightarrow X(t) = \Omega(t) \begin{pmatrix} 3 \\ 4 \end{pmatrix} = \begin{pmatrix} -2e^{3t} & (1-2t)e^{3t} \\ e^{3t} & te^{3t} \end{pmatrix} \begin{pmatrix} 3 \\ 4 \end{pmatrix}$$

$$= \begin{pmatrix} -6e^{3t} + 4(1-2t)e^{3t} \\ 3e^{3t} + 4te^{3t} \end{pmatrix}$$

*

Ex 6.5 : non-homogeneous Equation

Let us consider non-homogeneous differential Equation:

$$\dot{x} = Ax + G$$

Let $x = \Sigma C$ be a general solution of the homogeneous equation $\dot{x} = Ax$, and \bar{x}_p be a particular solution of the non-homogeneous equation $\dot{x} = Ax + G$. Then the general solution of $\dot{x} = Ax + G$ is

$$x = \Sigma C + \bar{x}_p$$

P233

☞ 1차원적 homogeneous coupled linear differential Equation

$$\dot{x} = Ax \quad) - \textcircled{1}$$

A : constant $m \times m$ matrix

Let

$$x = \xi e^{\lambda t} \quad - \textcircled{2}$$

ξ : $(m \times 1)$ constant matrix

$$\textcircled{2} \rightarrow \textcircled{1}$$

$$\lambda \xi e^{\lambda t} = A \xi e^{\lambda t}$$

$$\Rightarrow A\xi = \lambda \xi \quad - \textcircled{3}$$

λ : eigenvalue of A

ξ : eigenvector of A

78v16.6

$$\dot{x} = Ax \Leftrightarrow \text{일반해}$$

A 의 eigenvalue = $\{\lambda_1, \lambda_2, \dots, \lambda_m\}$

A 의 eigenvector = $\{\xi_1, \xi_2, \dots, \xi_m\}$

$$x = c_1 \xi_1 e^{\lambda_1 t} + c_2 \xi_2 e^{\lambda_2 t} + \dots + c_m \xi_m e^{\lambda_m t}$$

P233

(2016.6)

$$\mathbf{x}' = \begin{pmatrix} 4 & 2 \\ 3 & 3 \end{pmatrix} \mathbf{x}$$

$$\mathbf{A} = \begin{pmatrix} 4 & 2 \\ 3 & 3 \end{pmatrix}$$

* eigenvalues

$$\begin{vmatrix} 4-\lambda & 2 \\ 3 & 3-\lambda \end{vmatrix} = 0$$

$$\lambda = 1 \text{ and } 6$$

* eigenvectors

$$(i) \lambda = 1$$

$$\begin{pmatrix} 4 & 2 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} a \\ b \end{pmatrix}$$

$$2a + 2b = 0$$

$$a=2, \quad b=-3 \quad \Rightarrow \quad \vec{z}_1 = \begin{pmatrix} 2 \\ -3 \end{pmatrix}$$

$$(ii) \lambda = 6$$

$$\begin{pmatrix} 4 & 2 \\ 3 & 3 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 6 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$a=b$$

$$\Rightarrow a=b=1 \quad \Rightarrow \quad \vec{z}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\mathbf{x}(t) = C_1 \vec{z}_1 e^{1t} + C_2 \vec{z}_2 e^{6t}$$

$$= C_1 \begin{pmatrix} 2 \\ -3 \end{pmatrix} e^t + C_2 \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{6t}$$

$$= \begin{pmatrix} 2C_1 e^t + C_2 e^{6t} \\ -3C_1 e^t + C_2 e^{6t} \end{pmatrix} = Q(t) \begin{pmatrix} C_1 \\ C_2 \end{pmatrix}$$

where

$$\mathcal{Q}(t) = \begin{pmatrix} 2e^t & e^{6t} \\ -3e^t & e^{6t} \end{pmatrix}$$

*

fundamental matrix

prob (2016.7)

$$x' = A_1 x$$

$$A = \begin{pmatrix} 2 & 0 & 1 \\ 0 & -2 & -2 \\ 0 & 2 & 0 \end{pmatrix}$$

* eigenvalues

$$\begin{vmatrix} 2-\lambda & 0 & 1 \\ 0 & -2-\lambda & -2 \\ 0 & 2 & \lambda \end{vmatrix} = 0$$

$$\lambda = 2, -1 \pm \sqrt{3}i$$

(i) $\lambda_1 = 2$

$$\begin{pmatrix} 2 & 0 & 1 \\ 0 & -2 & -2 \\ 0 & 2 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} \Rightarrow \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$2a + c = 2a$$

$$-2b - 2c = 2b$$

$$\Rightarrow \vec{z}_1 = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}$$

(ii) $\lambda_2 = -1 + \sqrt{3}i$

$$\begin{pmatrix} 2 & 0 & 1 \\ 0 & -2 & -2 \\ 0 & 2 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = (-1 + \sqrt{3}i) \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$(-3 + \sqrt{3}i)a = c$$

$$(1 + \sqrt{3}i)b = -2c$$

$$\Rightarrow \vec{z}_2 = \begin{pmatrix} 1 \\ -2\sqrt{3}i \\ -3 + \sqrt{3}i \end{pmatrix}$$

$$(iii) \lambda_3 = -1 - \sqrt{3}i$$

$$\begin{pmatrix} 2 & 0 & 1 \\ 0 & -2 & -2 \\ 0 & 2 & 0 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = (-1 - \sqrt{3}i) \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$-(2 + \sqrt{3}i)a = c$$

$$2b = (-1 - \sqrt{3}i)c$$

$$\Rightarrow \vec{z}_3 = \begin{pmatrix} 1 \\ 2\sqrt{3}i \\ -2 - \sqrt{3}i \end{pmatrix}$$

$$x = c_1 \vec{z}_1 e^{\lambda_1 t} + c_2 \vec{z}_2 e^{\lambda_2 t} + c_3 \vec{z}_3 e^{\lambda_3 t}$$

$$= Q(t) \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix}$$

where

$$Q(t) = \begin{pmatrix} e^{2t} & e^{(-1 + \sqrt{3}i)t} & e^{-(1 + \sqrt{3}i)t} \\ 0 & -2\sqrt{3}i e^{(1 + \sqrt{3}i)t} & 2\sqrt{3}i e^{-(1 + \sqrt{3}i)t} \\ 0 & (-3 + \sqrt{3}i) e^{(1 + \sqrt{3}i)t} & -(2 + \sqrt{3}i) e^{-(1 + \sqrt{3}i)t} \end{pmatrix}$$

Fundamental matrix

\Rightarrow different expression

$$\begin{aligned}
 & \tilde{\mathbf{z}}_2 e^{\lambda_2 t} \\
 &= \begin{pmatrix} 1 \\ -2\sqrt{3}i \\ -3 + \sqrt{3}i \end{pmatrix} e^{(-1+\sqrt{3}i)t} \\
 &= \left[\begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} + i \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \right] e^{-t} (\cos \sqrt{3}t + i \sin \sqrt{3}t) \\
 &= e^{-t} \left[\begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} \cos \sqrt{3}t - \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \sin \sqrt{3}t \right] \\
 &\quad + i e^{-t} \left[\begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} \sin \sqrt{3}t + \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \cos \sqrt{3}t \right]
 \end{aligned}$$

By same way

$$\begin{aligned}
 & \tilde{\mathbf{z}}_3 e^{\lambda_3 t} \\
 &= e^{-t} \left[\begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} \cos \sqrt{3}t - \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \sin \sqrt{3}t \right] \\
 &\quad - i e^{-t} \left[\begin{pmatrix} 1 \\ 0 \\ -3 \end{pmatrix} \sin \sqrt{3}t + \begin{pmatrix} 0 \\ -2\sqrt{3} \\ \sqrt{3} \end{pmatrix} \cos \sqrt{3}t \right]
 \end{aligned}$$

Thus we can choose two linearly-independent solutions as

$$x_1 = \tilde{\mathbf{z}}_1 e^{\lambda_1 t} = \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} e^{2t}$$

$$x_2 = \frac{1}{2} [\tilde{\mathbf{z}}_2 e^{\lambda_2 t} + \tilde{\mathbf{z}}_3 e^{\lambda_3 t}] = e^{-t} \begin{pmatrix} \cos \sqrt{3}t \\ 2\sqrt{3} \sin \sqrt{3}t \\ -3 \cos \sqrt{3}t - \sqrt{3} \sin \sqrt{3}t \end{pmatrix}$$

$$x_3 = \frac{1}{2i} [\tilde{\mathbf{z}}_2 e^{\lambda_2 t} - \tilde{\mathbf{z}}_3 e^{\lambda_3 t}] = e^{-t} \begin{pmatrix} \sin \sqrt{3}t \\ -2\sqrt{3} \cos \sqrt{3}t \\ -3 \sin \sqrt{3}t + \sqrt{3} \cos \sqrt{3}t \end{pmatrix}$$

general solution

$$X = c_1 X_1 + c_2 X_2 + c_3 X_3$$

$$= Q(t) \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix}$$

where

$$Q(t) = \begin{pmatrix} e^{2t} & e^{-t} \cos \sqrt{3}t & e^{-t} \sin \sqrt{3}t \\ 0 & 2\sqrt{3} e^{-t} \sin \sqrt{3}t & -2\sqrt{3} e^{-t} \cos \sqrt{3}t \\ 0 & -e^{-t} (2 \cos \sqrt{3}t + \sqrt{3} \sin \sqrt{3}t) & e^{-t} (-3 \sin \sqrt{3}t + \sqrt{3} \cos \sqrt{3}t) \end{pmatrix} *$$

P237

(2021.6.8)

$$\textcircled{1} \quad X' = \begin{pmatrix} 5 & -4 & 4 \\ 12 & -11 & 12 \\ 4 & -4 & 5 \end{pmatrix} X$$

(i) eigenvalue

$$\begin{vmatrix} 5-\lambda & -4 & 4 \\ 12 & -11-\lambda & 12 \\ 4 & -4 & 5-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (\lambda+3)(\lambda-1)^2 = 0$$

$$\lambda = -3, 1 \quad (\text{重根})$$

(i) $\lambda_1 = -3$

$$\begin{pmatrix} 5 & -4 & 4 \\ 12 & -11 & 12 \\ 4 & -4 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = -3 \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\Rightarrow 2a - b + c = 0$$

$$3a - 2b + 2c = 0$$

$$\Rightarrow z_1 = \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix}$$

$$\text{vi) } \lambda_2 = 1$$

$$\begin{pmatrix} 5 & -4 & 4 \\ 12 & -11 & 10 \\ 4 & -4 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$a - b + c = 0$$

$$\vec{z}_1 = \begin{pmatrix} 1 \\ 1 \\ 0 \end{pmatrix} \quad \vec{z}_2 = \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix}$$

General solution

$$\begin{aligned} X &= c_1 \vec{z}_1 e^{\lambda_1 t} + c_2 \vec{z}_2 e^{\lambda_2 t} + c_3 \vec{z}_3 e^{\lambda_3 t} \\ &= c_1 \begin{pmatrix} 1 \\ 3 \\ 1 \end{pmatrix} \bar{e}^{3t} + c_2 \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} e^t + c_3 \begin{pmatrix} 1 \\ 0 \\ -1 \end{pmatrix} e^t \\ &= \begin{pmatrix} \bar{e}^{3t} & e^t & e^t \\ 3\bar{e}^{3t} & e^t & 0 \\ \bar{e}^{3t} & 0 & \bar{e}^t \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \\ c_3 \end{pmatrix} \quad * \end{aligned}$$

(M1/216.9)

$$x' = Ax \quad A = \begin{pmatrix} 1 & 3 \\ -3 & 7 \end{pmatrix}$$

* eigenvalue

$$\begin{vmatrix} 1-\lambda & 3 \\ -3 & 7-\lambda \end{vmatrix} = 0$$

$$\lambda = 4 \quad (\text{double root})$$

* eigenvector

$$\begin{pmatrix} 1 & 3 \\ -3 & 7 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 4 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\Rightarrow a = b$$

$$\vec{z}_1 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

$$\Rightarrow x_1 = \vec{z}_1 e^{\lambda t} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} e^{4t} \quad -\textcircled{1}$$

How to obtain x_2 ?

Put $x_2 = \vec{z}_1 t + e^{\lambda t} + \eta e^{\lambda t} \quad -\textcircled{2}$

Then

$$x_2' = \vec{z}_1 e^{\lambda t} + \lambda \vec{z}_1 t e^{\lambda t} + \lambda \eta e^{\lambda t} \quad -\textcircled{3}$$

$$Ax_2 = \underline{A \vec{z}_1 t e^{\lambda t} + A \eta e^{\lambda t}}$$

$$= \lambda \vec{z}_1$$

$$= \lambda \vec{z}_1 t e^{\lambda t} + A \eta e^{\lambda t} \quad -\textcircled{4}$$

If x_2 is solution vector, $x_2' = Ax_2$.

$$\Rightarrow \bar{z}_1 e^{\lambda t} + \lambda \eta e^{\lambda t} = A\eta e^{\lambda t}$$

$$\Rightarrow (A - \lambda I)\eta = \bar{z}_1 \quad - \textcircled{5}$$

For our case

$$\begin{pmatrix} -3 & 3 \\ -3 & 3 \end{pmatrix} \eta = \begin{pmatrix} 1 \\ 1 \end{pmatrix},$$

which gives

$$\eta = \begin{pmatrix} 1 \\ \frac{1}{3} \end{pmatrix} \quad - \textcircled{6}$$

$\textcircled{5} \rightarrow \textcircled{6}$

$$x_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix} + e^{4t} + \begin{pmatrix} 1 \\ \frac{1}{3} \end{pmatrix} e^{4t}$$

$$= \begin{pmatrix} t+1 \\ t+\frac{1}{3} \end{pmatrix} e^{4t} \quad - \textcircled{7}$$

General solution

$$x = c_1 x_1 + c_2 x_2$$

$$= \begin{pmatrix} e^{4t} & (t+1)e^{4t} \\ e^{4t} & (t+\frac{1}{3})e^{4t} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \times$$

(Ex 3) 6. (ii)

$$\dot{x}' = Ax \quad A = \begin{pmatrix} -2 & -1 & -5 \\ 25 & -7 & 0 \\ 0 & 1 & 3 \end{pmatrix}$$

* eigenvalue

$$\begin{vmatrix} -2-\lambda & -1 & -5 \\ 25 & -7-\lambda & 0 \\ 0 & 1 & 3-\lambda \end{vmatrix} = 0$$

$$\Rightarrow (\lambda+2)^3 = 0$$

$$\lambda = -2 \quad - \textcircled{1}$$

* eigenvector

$$\begin{pmatrix} -2 & -1 & -5 \\ 25 & -7 & 0 \\ 0 & 1 & 3 \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = -2 \begin{pmatrix} a \\ b \\ c \end{pmatrix}$$

$$\Rightarrow 5a - b = 0$$

$$b + 5c = 0$$

$$\Rightarrow \vec{z}_1 = \begin{pmatrix} -1 \\ -5 \\ 1 \end{pmatrix} \quad - \textcircled{2}$$

$$\Rightarrow x_1 = z_1 e^{\lambda t} = \begin{pmatrix} -1 \\ -5 \\ 1 \end{pmatrix} e^{-2t} \quad - \textcircled{2}$$

How to obtain x_2 and x_3 ?

Put

$$x_2 = \bar{z}_1 + e^{\lambda t} + \eta_1 e^{\lambda t} \quad - \textcircled{3}$$

Then

$$(A - \lambda I) \eta_1 = \bar{z}_1 \quad - \textcircled{4}$$

$$\Rightarrow \begin{pmatrix} 0 & -1 & -5 \\ 25 & -5 & 0 \\ 0 & 1 & 5 \end{pmatrix} \eta_1 = \begin{pmatrix} -1 \\ -5 \\ 1 \end{pmatrix}$$

$$\Rightarrow \eta_1 = \begin{pmatrix} -1 \\ -4 \\ 1 \end{pmatrix} \quad - \textcircled{5}$$

Thus

$$x_2 = \begin{pmatrix} -1 \\ -5 \\ 1 \end{pmatrix} + e^{-\lambda t} + \begin{pmatrix} -1 \\ -4 \\ 1 \end{pmatrix} e^{-\lambda t}$$

$$= \begin{pmatrix} -t-1 \\ -5t-4 \\ t+1 \end{pmatrix} e^{-\lambda t} \quad - \textcircled{6}$$

How to compute x_3 ? Put

$$x_3 = \frac{1}{2} \tilde{x}_1 t^2 e^{\lambda t} + \eta_2 t e^{\lambda t} + \eta_3 e^{\lambda t} \quad - \textcircled{8}$$

$$x'_3 = \frac{1}{2} \tilde{x}_1 t^2 e^{\lambda t} + \tilde{x}_1 t e^{\lambda t} + \eta_2 e^{\lambda t} + \lambda \eta_2 t e^{\lambda t} + \lambda \eta_3 e^{\lambda t} \quad - \textcircled{9}$$

$$\Delta x_3 = \frac{1}{2} \underbrace{A \tilde{x}_1 t^2 e^{\lambda t}}_{\lambda \tilde{x}_1} + A \eta_2 t e^{\lambda t} + A \eta_3 e^{\lambda t}$$

$$= \frac{1}{2} \tilde{x}_1 t^2 e^{\lambda t} + A \eta_2 t e^{\lambda t} + A \eta_3 e^{\lambda t} \quad - \textcircled{10}$$

Since $x'_3 = \Delta x_3$, we have

$$(A - \lambda I) \eta_2 = \tilde{x}_1 \quad - \textcircled{11}$$

$$(A - \lambda I) \eta_3 = \eta_2 \quad - \textcircled{12}$$

Comparing Eq. \textcircled{10} with Eq. \textcircled{11}, we have

$$\eta_2 = \eta_1 = \begin{pmatrix} -1 \\ -4 \\ 1 \end{pmatrix} \quad - \textcircled{13}$$

\textcircled{13} \rightarrow \textcircled{12}

$$\begin{pmatrix} 0 & -1 & -5 \\ -5 & -5 & 0 \\ 0 & 1 & 5 \end{pmatrix} \eta_3 = \begin{pmatrix} -1 \\ -4 \\ 1 \end{pmatrix}$$

$$\Rightarrow \eta_3 = \begin{pmatrix} -\frac{24}{5} \\ -4 \\ 1 \end{pmatrix} \quad - \textcircled{14}$$

\textcircled{13}, \textcircled{14} \rightarrow \textcircled{8}

$$x_3 = \begin{pmatrix} -\frac{1}{2} t^2 - t - \frac{24}{5} \\ -\frac{1}{2} t^2 - 4t - 4 \\ \frac{1}{2} t^2 + t + 1 \end{pmatrix} \bar{e}^{\lambda t} \quad - \textcircled{15}$$

General solution

$$X = C_1 X_1 + C_2 X_2 + C_3 X_3$$

$$= \begin{pmatrix} -e^{-t} & -(t+1)e^{-2t} & -\left(\frac{1}{2}t^2+t+\frac{2t}{5}\right)e^{-2t} \\ -5e^{-t} & -(5t+4)e^{-2t} & -\left(\frac{5}{2}t^2+4t+4\right)e^{-2t} \\ e^{-t} & (t+1)e^{-2t} & \left(\frac{1}{2}t^2+t+1\right)e^{-2t} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \\ C_3 \end{pmatrix} \quad \times$$

* eigenvalue λ ($\lambda_1 = -1$)

eigenvector $= \vec{z}_1$

$$X_1(t) = \vec{z}_1 e^{\lambda t}$$

$$X_2(t) = \vec{z}_1 t e^{\lambda t} + \vec{\eta}_1 e^{\lambda t}$$

$$X_3(t) = \frac{1}{2} \vec{z}_1 t^2 e^{\lambda t} + \vec{\eta}_2 t e^{\lambda t} + \vec{\eta}_3 e^{\lambda t}$$

$$X_4(t) = \frac{1}{3!} \vec{z}_1 t^3 e^{\lambda t} + \frac{1}{2!} \vec{\eta}_4 t^2 e^{\lambda t} + \vec{\eta}_5 t e^{\lambda t} + \vec{\eta}_6 e^{\lambda t}$$

$$\vdots$$

$$X_k(t) = \frac{1}{(k-1)!} \vec{z}_1 t^{k-1} e^{\lambda t} + \frac{1}{(k-2)!} \vec{\eta}_1 t^{k-2} e^{\lambda t} + \cdots + \vec{\eta}_{k-1} e^{\lambda t}$$

* Matrix Diagonalization

$$X' = A X \quad - (1)$$

if

$$A = P D P^{-1} \quad - (2)$$

where

$$D = \begin{pmatrix} \lambda_1 & 0 & 0 & \cdots & 0 \\ 0 & \lambda_2 & 0 & \cdots & 0 \\ \vdots & \vdots & \ddots & & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_m \end{pmatrix}, \quad - (3)$$

Eq. (1) becomes

$$X' = P D P^{-1} X \quad - (4)$$

Put

$$Z = P^{-1} X \quad - (5)$$

(5) \rightarrow (4)

$$Z' = D Z \quad - (6)$$

Thus

$$Z = Q_D(\pm) \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix} \quad - (7)$$

where

$$Q_D(\pm) = \begin{pmatrix} e^{\pm i\omega t} & 0 & \cdots & 0 \\ 0 & e^{\pm i\omega t} & \cdots & 0 \\ \vdots & \vdots & & \vdots \\ 0 & 0 & \cdots & e^{\pm i\omega t} \end{pmatrix} \quad - (8)$$

(7) \rightarrow (5)

$$X = P Z = P Q_D(\pm) \begin{pmatrix} c_1 \\ c_2 \\ \vdots \\ c_m \end{pmatrix} \quad - (9)$$

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(09/21 6.11)

$$x' = Ax \quad A = \begin{pmatrix} 3 & 3 \\ 1 & 5 \end{pmatrix}$$

• diagonalization

(1) eigenvalues

$$\begin{vmatrix} 3-\lambda & 3 \\ 1 & 5-\lambda \end{vmatrix} = 0$$

$$\lambda_1 = 2, \quad \lambda_2 = 6$$

(2) eigenvectors

(i) $\lambda_1 = 2$

$$\begin{pmatrix} 3 & 3 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 2 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\vec{z}_1 = \begin{pmatrix} -3 \\ 1 \end{pmatrix}$$

(ii) $\lambda_2 = 6$

$$\begin{pmatrix} 3 & 3 \\ 1 & 5 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 6 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\vec{z}_2 = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$$

(3) diagonalization

$$P = \begin{pmatrix} -3 & 1 \\ 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 2 & 0 \\ 0 & 6 \end{pmatrix} \quad P^{-1} = -\frac{1}{4} \begin{pmatrix} 1 & -1 \\ -1 & -3 \end{pmatrix}$$

$$\Rightarrow A = P D P^{-1}$$

$$\Rightarrow x' = P D \vec{P}^{-1} X$$

$$\Rightarrow \vec{P}^{-1} X' = D \vec{P}^{-1} X$$

$$\Rightarrow (\vec{P}^{-1} X)' = D (\vec{P}^{-1} X) \quad - \textcircled{0}$$

P_{out}

$$Z = \vec{P}^{-1} X \quad - \textcircled{2}$$

$\textcircled{3} \rightarrow \textcircled{1}$

$$Z' = D Z$$

$$Z = \begin{pmatrix} e^{2x} & 0 \\ 0 & e^{6x} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad - \textcircled{2}$$

$\textcircled{3} \rightarrow \textcircled{2}$

$$X = P Z$$

$$= \begin{pmatrix} -3 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} e^{2x} & 0 \\ 0 & e^{6x} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$= \begin{pmatrix} -3e^{2x} & e^{6x} \\ e^{2x} & e^{6x} \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad *$$

* non-homogeneous differential Eq.

$$\dot{x} = Ax + G \quad - \textcircled{1}$$

$$x = Q(t)C + \Phi_p(t) \quad - \textcircled{2}$$

$Q(t)C$: general solution of $\dot{x} = Ax$

$\Phi_p(t)$: particular solution of $\dot{x} = Ax + G$

How to derive $\Phi_p(t)$?

Put

$$\Phi_p(t) = Q(t)U(t) \quad - \textcircled{3}$$

$\textcircled{3} \rightarrow \textcircled{1}$

$$\underline{Q'(t)U(t) + Q(t)U'(t)} = A\dot{Q}(t)U(t) + G$$

$$= A\dot{Q}(t)$$

$$A\dot{Q}(t)U(t) + Q(t)U'(t) = A\dot{Q}(t)U(t) + G$$

$$U'(t) = \dot{Q}^{-1}(t)G$$

$$\underline{\underline{U(t) = \int \dot{Q}^{-1}(t)G dt}} \quad - \textcircled{4}$$

$\textcircled{4} \rightarrow \textcircled{3}$

$$\boxed{\Phi_p(t) = Q(t) \int \dot{Q}^{-1}(t)G dt}$$

*

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(OMR 6.12)

$$\dot{x} = Ax + B \quad A = \begin{pmatrix} 1 & -10 \\ -1 & 4 \end{pmatrix} \quad B = \begin{pmatrix} e^t \\ \sin t \end{pmatrix}$$

(i) General solution of homogeneous Equation

① eigenvalues

$$\begin{vmatrix} 1-\lambda & -10 \\ -1 & 4-\lambda \end{vmatrix} = 0$$

$$\lambda = -1, 6$$

② eigenvectors

$$(i) \lambda_1 = -1$$

$$\begin{pmatrix} 1 & -10 \\ -1 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = - \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\vec{z}_1 = \begin{pmatrix} 5 \\ 1 \end{pmatrix}$$

$$(ii) \lambda_2 = 6$$

$$\begin{pmatrix} 1 & -10 \\ -1 & 4 \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = 6 \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\vec{z}_2 = \begin{pmatrix} -2 \\ 1 \end{pmatrix}$$

$$x_Q = Q(t) \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} \quad \text{--- ①}$$

$$Q(t) = \begin{pmatrix} 5e^{-t} & -2e^{6t} \\ e^{-t} & e^{6t} \end{pmatrix} \quad \text{--- ②}$$

$$Q^{-1}(t) = \frac{1}{7} \begin{pmatrix} e^t & 2e^t \\ -e^{6t} & 5e^{6t} \end{pmatrix} \quad \text{--- ③}$$

(ii) Particular solution

(17)

$$\vec{Q}^1(t) B$$

$$= \frac{1}{7} \begin{pmatrix} e^{2t} & 2e^{2t} \\ -e^{-6t} & 5e^{-6t} \end{pmatrix} \begin{pmatrix} e^t \\ \sin t \end{pmatrix}$$

$$= \frac{1}{7} \begin{pmatrix} e^{2t} + 2 \sin t e^t \\ -e^{-6t} + 5 \sin t e^{-6t} \end{pmatrix} \quad - \textcircled{4}$$

$$\int (e^{2t} + 2 \sin t e^t)^t dt = \frac{1}{2} e^{2t} + e^t (\sin t - \cos t) \quad \} - \textcircled{4}$$

$$\int (-e^{-6t} + 5 \sin t e^{-6t}) dt = \frac{1}{5} e^{-6t} - \frac{5}{39} e^{-6t} (6 \sin t + \cos t)$$

* Formula

$$\int \sin t e^{at} dt = \frac{e^{at} [-\cos t + a \sin t]}{1+a^2}$$

$$\Rightarrow \int \vec{Q}^1(t) B(t) dt = \begin{pmatrix} \frac{1}{14} e^{2t} + \frac{1}{7} e^t (\sin t - \cos t) \\ \frac{1}{35} e^{-6t} - \frac{5}{259} e^{-6t} (6 \sin t + \cos t) \end{pmatrix} \quad - \textcircled{4}$$

Thus,

$$\begin{aligned} \vec{x}_p(t) &= Q(t) \int \vec{Q}^1(t) B(t) dt \\ &= \begin{pmatrix} \frac{3}{10} e^{2t} + \frac{35}{39} \sin t - \frac{25}{39} \cos t \\ \frac{1}{10} e^{-6t} + \frac{1}{39} \sin t - \frac{6}{39} \cos t \end{pmatrix} \quad - \textcircled{5} \end{aligned}$$

Thus

$$\vec{x}(t) = \begin{pmatrix} 5e^{-6t} & -2e^{6t} \\ e^{-6t} & e^{6t} \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} + \begin{pmatrix} \frac{3}{10} e^{2t} + \frac{35}{39} \sin t - \frac{25}{39} \cos t \\ \frac{1}{10} e^{-6t} + \frac{1}{39} \sin t - \frac{6}{39} \cos t \end{pmatrix} \quad *$$

* Matrix diagonalization

$$x' = Ax + g \quad \text{--- (1)}$$

$$A = P D P^{-1}$$

$$D = \begin{pmatrix} \lambda_1 & 0 & 0 & \cdots & 0 \\ 0 & \lambda_2 & 0 & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & \lambda_m \end{pmatrix}$$

$$\left\{ \begin{array}{l} \\ \\ \end{array} \right. \quad \text{--- (2)}$$

(2) \rightarrow (1)

$$x' = P D P^{-1} x + g$$

$$P^{-1} x = P^{-1} x' = D P^{-1} x + P^{-1} g \quad \text{--- (3)}$$

Put

$$z = P^{-1} x \quad \text{--- (4)}$$

(4) \rightarrow (3)

$$z' = D z + P^{-1} g \quad \text{--- (5)}$$

Let

$$z = \begin{pmatrix} z_1 \\ z_2 \\ \vdots \\ z_m \end{pmatrix} \quad P^{-1} g = \begin{pmatrix} f_1(t) \\ f_2(t) \\ \vdots \\ f_m(t) \end{pmatrix}$$

Then

$$z'_1 = \lambda_1 z_1 + f_1(t)$$

$$z'_2 = \lambda_2 z_2 + f_2(t)$$

Linear form

$$\vdots$$

$$z'_m = \lambda_m z_m + f_m(t)$$

$$\frac{dy}{dx} + p(x) y = Q(x)$$

$$y = e^{\int p dx} \left[\int Q e^{\int p dx} dx + C \right]$$

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(解答 6.13)

$$x' = \begin{pmatrix} 3 & 3 \\ 1 & 5 \end{pmatrix} x + \begin{pmatrix} \delta \\ 4e^{3x} \end{pmatrix} \quad -\textcircled{1}$$

$$P = \begin{pmatrix} -3 & 1 \\ 1 & 1 \end{pmatrix} \quad D = \begin{pmatrix} 2 & 0 \\ 0 & 6 \end{pmatrix} \quad P^{-1} = -\frac{1}{4} \begin{pmatrix} 1 & -1 \\ -1 & -3 \end{pmatrix} \quad \boxed{2} -\textcircled{2}$$

$$A = P D P^{-1}$$

 $\textcircled{2} \rightarrow \textcircled{1}$

$$x' = P D P^{-1} x + \begin{pmatrix} \delta \\ 4e^{3x} \end{pmatrix}$$

$$(P^{-1}x)' = D(P^{-1}x) + P^{-1} \begin{pmatrix} \delta \\ 4e^{3x} \end{pmatrix}$$

put

$$z = P^{-1}x \quad -\textcircled{2}$$

then

$$z' = Dz + \begin{pmatrix} -2 + e^{3x} \\ 2 + 3e^{3x} \end{pmatrix} \quad -\textcircled{3}$$

put $z = \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} \quad -\textcircled{4}$

 $\textcircled{3} \rightarrow \textcircled{4}$

$$\begin{pmatrix} z'_1 \\ z'_2 \end{pmatrix} = \begin{pmatrix} 2 & 0 \\ 0 & 6 \end{pmatrix} \begin{pmatrix} z_1 \\ z_2 \end{pmatrix} + \begin{pmatrix} -2 + e^{3x} \\ 2 + 3e^{3x} \end{pmatrix}$$

$$\Rightarrow z'_1 = 2z_1 + (-2 + e^{3x}) \quad) \quad -\textcircled{4}$$

$$z'_2 = 6z_2 + (2 + 3e^{3x})$$

Solution

$$\begin{aligned} z_1(t) &= C_1 e^{2t} + e^{3t} + 1 \\ z_2(t) &= C_2 e^{6t} - e^{2t} - \frac{1}{3} \end{aligned} \quad) \quad - \textcircled{1}$$

$$\Rightarrow z(t) = \begin{pmatrix} C_1 e^{2t} + e^{3t} + 1 \\ C_2 e^{6t} - e^{2t} - \frac{1}{3} \end{pmatrix} \quad - \textcircled{2}$$

 $\textcircled{2} \rightarrow \textcircled{2}$

$$x = P z$$

$$= \begin{pmatrix} -3 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} C_1 e^{2t} + e^{3t} + 1 \\ C_2 e^{6t} - e^{2t} - \frac{1}{3} \end{pmatrix}$$

$$= \begin{pmatrix} -3C_1 e^{2t} + C_2 e^{6t} - 4e^{3t} - \frac{10}{3} \\ C_1 e^{2t} + C_2 e^{6t} + \frac{2}{3} \end{pmatrix}$$

$$= \Sigma(t) \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} + \begin{pmatrix} -4e^{3t} - \frac{10}{3} \\ \frac{2}{3} \end{pmatrix} \quad - \textcircled{3}$$

where

$$\Sigma(t) = \begin{pmatrix} -3e^{2t} & e^{6t} \\ e^{2t} & e^{6t} \end{pmatrix} \quad - \textcircled{4}$$

\times

(01) 6. 14)

$$X(0) = \begin{pmatrix} -3 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} C_1 \\ C_2 \end{pmatrix} + \begin{pmatrix} -\frac{20}{3} \\ \frac{11}{3} \end{pmatrix} = \begin{pmatrix} 2 \\ -7 \end{pmatrix}$$

$$C_1 = -\frac{17}{4}, \quad C_2 = -\frac{41}{12}$$

$$X(t) = \begin{pmatrix} -3 e^{2t} & e^{6t} \\ e^{2t} & e^{6t} \end{pmatrix} \begin{pmatrix} -\frac{17}{4} \\ -\frac{41}{12} \end{pmatrix} + \begin{pmatrix} -4e^{3t} - \frac{10}{3} \\ \frac{5}{3} \end{pmatrix} *$$