

$$f(t) \rightarrow \text{Laplace transform}$$

$$F(s) \equiv \mathcal{L}[f](s) \equiv \int_0^{\infty} e^{-st} f(t) dt$$

p86

(ex 3.1)

$$f(t) = e^{at}$$

$$\mathcal{L}[f](s) = \int_0^{\infty} e^{-st} e^{at} dt$$

$$= \int_0^{\infty} e^{-(s-a)t} dt$$

$$= \begin{cases} \frac{1}{s-a} & s > a \\ \infty & s < a \end{cases}$$

$$\Rightarrow F(s) = \frac{1}{s-a} \quad (s > a)$$

p87

(ex 3.2)

$$g(t) = \sin t$$

$$\mathcal{L}[g](s) \equiv \int_0^{\infty} dt e^{-st} \sin t$$

$$\int e^{-st} \sin t dt = -\frac{1}{1+s^2} e^{-st} (\cos t + \frac{s}{1} \sin t)$$

$$= -\frac{1}{1+s^2} \left[ e^{-st} (\cos t + s \sin t) \right]_{t=0}^{t=\infty}$$

$$= -\frac{1}{1+s^2} [0 - 1]$$

$$= \frac{1}{1+s^2} \quad (s > 0)$$

(2x) 1+2+3+...

$$f(t) = \begin{cases} 1 & 0 \leq t \leq a & 2a \leq t \leq 3a & 4a \leq t \leq 5a & \dots \\ -1 & a \leq t \leq 2a & 3a \leq t \leq 4a & 5a \leq t \leq 6a & \dots \end{cases}$$

$$F(s) = \int_0^{\infty} dt \, e^{-st} f(t)$$

$$= \left[ \int_0^a e^{-st} dt + \int_{2a}^{3a} e^{-st} dt + \int_{4a}^{5a} e^{-st} dt + \dots \right]$$

$$- \left[ \int_a^{2a} e^{-st} dt + \int_{3a}^{4a} e^{-st} dt + \int_{5a}^{6a} e^{-st} dt + \dots \right]$$

$$= \frac{1}{s} \left[ (1 - e^{-as}) + (e^{-2as} - e^{-3as}) + (e^{-4as} - e^{-5as}) + \dots \right]$$

$$- \frac{1}{s} \left[ (e^{-as} - e^{-2as}) + (e^{-3as} - e^{-4as}) + (e^{-5as} - e^{-6as}) + \dots \right]$$

$$= \frac{1}{s} \left[ 1 - 2 \{ e^{-as} - e^{-2as} + e^{-3as} - e^{-4as} + \dots \} \right]$$

$$\frac{e^{-as}}{1 + e^{-as}}$$

$$= \frac{1}{s} \left[ 1 - \frac{2e^{-as}}{1 + e^{-as}} \right]$$

$$= \frac{1}{s} \frac{1 - e^{-as}}{1 + e^{-as}}$$

$$= \frac{1}{s} \frac{e^{\frac{a}{2}s} - e^{-\frac{a}{2}s}}{e^{\frac{a}{2}s} + e^{-\frac{a}{2}s}}$$

$$= \frac{1}{s} \tanh\left(\frac{a}{2}s\right)$$

#

$$\int_a^b e^{-st} dt = \frac{1}{s} (e^{-as} - e^{-bs})$$

p90

(10.213.1)

$$\mathcal{L}[af+bg](s) = aF(s) + bG(s)$$

Ex)  $f(t) = \alpha e^{at} + \beta e^{bt}$  what is  $F(s)$ ?

$$F(s) = \alpha \underbrace{\mathcal{L}[e^{at}]}_{\frac{1}{s-a}} + \beta \underbrace{\mathcal{L}[e^{bt}]}_{\frac{1}{s-b}} \quad (\text{p89 formula 5})$$

$$= \frac{\alpha}{s-a} + \frac{\beta}{s-b}$$

$$= \frac{(\alpha+\beta)s - (\alpha\beta + b\alpha)}{(s-a)(s-b)}$$

Ex)  $F(s) = \frac{s-3}{(s-1)(s-2)}$  what is  $f(t)$ ?

$$F(s) = \frac{2}{s-1} - \frac{1}{s-2}$$

$$f(t) = 2 \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s-1}\right]}_{e^t} - \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s-2}\right]}_{e^{2t}}$$

$$= 2e^t - e^{2t}$$

\*

• Inverse Laplace Transform

$$\text{If } F(s) = \mathcal{L}[f](s),$$

$$f(t) = \mathcal{L}^{-1}[F](t)$$

p92

16.213.3

$$\mathcal{L}^{-1}[aF + bG] = a \mathcal{L}^{-1}[F] + b \mathcal{L}^{-1}[G]$$

Ex)

$$F(s) = \frac{3}{s-a} + \frac{5}{(s-b)^2}$$

$$f(t) = 3 \mathcal{L}^{-1}\left[\frac{1}{s-a}\right] + 5 \mathcal{L}^{-1}\left[\frac{1}{(s-b)^2}\right]$$

 $e^{at}$  $t e^{bt}$ 

(part formula 5, 6)

$$= 3e^{at} + 5te^{bt}$$

\*

을 Laplace 변환을 이용한 기법으로 풀기

제3.4

$$\mathcal{L}[f'](s) = sF(s) - f(0)$$

Pf)

$$\mathcal{L}[f'](s)$$

$$= \int_0^{\infty} dt \underbrace{e^{-st}}_u \underbrace{f'(t)}_{v'}$$

$$u = e^{-st}$$

$$v = f$$

$$u' = -s e^{-st}$$

$$v' = f'$$

$$= e^{-st} f(t) \Big|_{t=0}^{t=\infty} - \int_0^{\infty} dt (-s e^{-st}) f(t)$$

$$= -f(0) + s \int_0^{\infty} dt e^{-st} f(t) = F(s)$$

$$= sF(s) - f(0) \quad \#$$

(Ex)  $\mathcal{L}[\cos t]$

let

$$f'(t) = \cos t, \quad f(t) = \sin t$$

$$\mathcal{L}[\cos t] = s \underbrace{\mathcal{L}[\sin t]}_{\frac{1}{s^2+1}} - \overset{=0}{\sin 0} \quad (\text{p87 예제 3.2})$$

$$= \frac{s}{s^2+1} \quad \#$$

Abel 3.5

$$\mathcal{L}[f^{(n)}] = s^n F(s) - s^{n-1} f(0) - s^{n-2} f'(0) - \dots - s f^{(n-2)}(0) - f^{(n-1)}(0)$$

$$\mathcal{L}[f''] = s^2 F(s) - s f(0) - f'(0)$$

(Pf)  $\mathcal{L}[f'']$ 

$$f'' = (f')'$$

From Abel 3.4

$$\mathcal{L}[f''] = s \mathcal{L}[f'] - f'(0)$$

$$s F(s) - f'(0)$$

$$= s^2 F(s) - s f(0) - f'(0) \quad \times$$

예제 3.3

$$\frac{d^2 y}{dt^2} + 4 \frac{dy}{dt} + 3y = e^t \quad y(0) = 0, \quad y'(0) = 2$$

L (1)

(A) 앞 chapter 의 방법

$$y = y_h + y_p$$

(i)  $y_h$ 

$$y'' + 4y' + 3y = 0$$

$$y = C_1 e^{-t} + C_2 e^{-3t}$$

$$\left( \begin{array}{l} y'' + Ay' + By = 0 \\ (i) A^2 > 4B \\ y = C_1 e^{at} + C_2 e^{bt} \\ a = \frac{-A + \sqrt{A^2 - 4B}}{2} \\ b = \frac{-A - \sqrt{A^2 - 4B}}{2} \end{array} \right)$$

(ii)  $y_p$ 

$$y_p = \alpha e^t$$

$$y_p'' + 4y_p' + 3y_p = \alpha e^t = e^t$$

$$\alpha = \frac{1}{8}$$

$$\Rightarrow y_p = \frac{1}{8} e^t$$

$$y = C_1 e^{-t} + C_2 e^{-3t} + \frac{1}{8} e^t$$

$$y' = -C_1 e^{-t} - 3C_2 e^{-3t} + \frac{1}{8} e^t$$

$$y(0) = C_1 + C_2 + \frac{1}{8} = 0$$

$$y'(0) = -C_1 - 3C_2 + \frac{1}{8} = 2$$

$$\} \Rightarrow C_1 = \frac{3}{4}, \quad C_2 = -\frac{7}{8}$$

$$y = \frac{3}{4} e^{-t} - \frac{7}{8} e^{-3t} + \frac{1}{8} e^t$$

(B) using Laplace transform

Let

$$Y(s) = \mathcal{L}[y]$$

(2)

Taking Laplace transform to Eq. (1)

$$\mathcal{L}[y''] + 4\mathcal{L}[y'] + 3\mathcal{L}[y] = \mathcal{L}[e^t]$$

$$[s^2 Y(s) - s \underbrace{y(0)}^0 - \underbrace{y'(0)}^0] + 4[sY(s) - \underbrace{y(0)}^0] + 3Y(s) = \frac{1}{s-1}$$

$$(s^2 + 4s + 3)Y(s) - 2 = \frac{1}{s-1}$$

$$\Rightarrow (s^2 + 4s + 3)Y(s) = \frac{1}{s-1} + 2 = \frac{2s-1}{s-1}$$

$$\Rightarrow Y(s) = \frac{2s-1}{(s-1)(s+1)(s+2)}$$

$$= \frac{1}{8} \frac{1}{s-1} + \frac{3}{4} \frac{1}{s+1} - \frac{7}{8} \frac{1}{s+2} \quad (3)$$

Taking inverse Laplace transform to Eq. (3)

$$y(t) = \frac{1}{8} e^t + \frac{3}{4} e^{-t} - \frac{7}{8} e^{-2t}$$

\*



[1] 제 1 이동 정리

p96

제 1 이동 정리 3.6

$$\mathcal{L}[e^{at} f(t)] = F(s-a)$$

제 1 이동 정리

Pf)

$$\mathcal{L}[e^{at} f(t)]$$

$$= \int_0^{\infty} dt e^{-st} e^{at} f(t)$$

$$= \int_0^{\infty} dt e^{-(s-a)t} f(t)$$

$$\int_0^{\infty} dt e^{-st} f(t) = F(s)$$

$$= F(s-a) \quad \times$$

p97

(제 1 이동 정리 3.4)

$$\mathcal{L}(t^3) = \frac{3!}{s^4} = \frac{6}{s^4}$$

(p97 formula 2)

$$\mathcal{L}(e^{7t} t^3) = \frac{6}{(s-7)^4}$$

note)

$$\mathcal{L}^{-1}(F(s-a)) = e^{at} f(t) = e^{at} \mathcal{L}^{-1}(F(s))$$

p97

(07/11/21)

$$F(s) = \frac{3s-1}{s^2-6s+2}$$

$$\mathcal{L}^{-1}[F] = ?$$

$$F(s) = \frac{3s-1}{s^2-6s+9-\eta}$$

$$= \frac{3(s-3+3)-1}{(s-3)^2-\eta}$$

$$= \frac{3(s-3)}{(s-3)^2-\eta} + \frac{8}{(s-3)^2-\eta}$$

$$= 3 F_1(s) + 8 F_2(s)$$

- ①

where

$$F_1(s) = \frac{s-3}{(s-3)^2-\eta}$$

} - ②

$$F_2(s) = \frac{1}{(s-3)^2-\eta}$$

$$\mathcal{L}^{-1}[F(s)] = 3 \mathcal{L}^{-1}[F_1(s)] + 8 \mathcal{L}^{-1}[F_2(s)] \quad - ③$$

$$\mathcal{L}^{-1}[F_1(s)] = e^{3t} \mathcal{L}^{-1}\left[\frac{s}{s^2-\eta}\right] = e^{3t} \cosh\sqrt{\eta}t \quad - ④ \quad (\text{p28 formula 22})$$

$$\mathcal{L}^{-1}[F_2(s)] = e^{3t} \mathcal{L}^{-1}\left[\frac{1}{s^2-\eta}\right] = e^{3t} \frac{1}{\sqrt{\eta}} \mathcal{L}^{-1}\left[\frac{\sqrt{\eta}}{s^2-\eta}\right] = \frac{1}{\sqrt{\eta}} e^{3t} \sinh\sqrt{\eta}t \quad - ⑤$$

$\sinh\sqrt{\eta}t \quad (\text{p28 formula 22})$

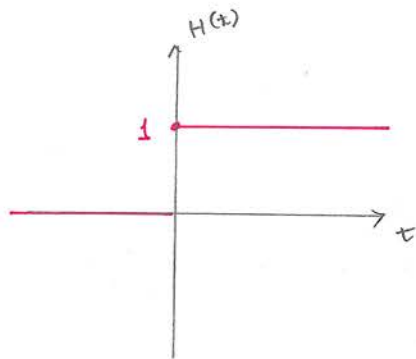
④, ⑤  $\rightarrow$  ③

$$\mathcal{L}^{-1}[F(s)] = 3 e^{3t} \cosh\sqrt{\eta}t + \frac{8}{\sqrt{\eta}} e^{3t} \sinh\sqrt{\eta}t$$

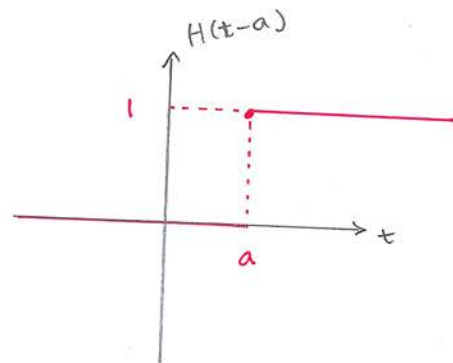
x

Heaviside 함수 (or step 함수)

$$H(t) = \begin{cases} 0 & t < 0 \\ 1 & t \geq 0 \end{cases}$$

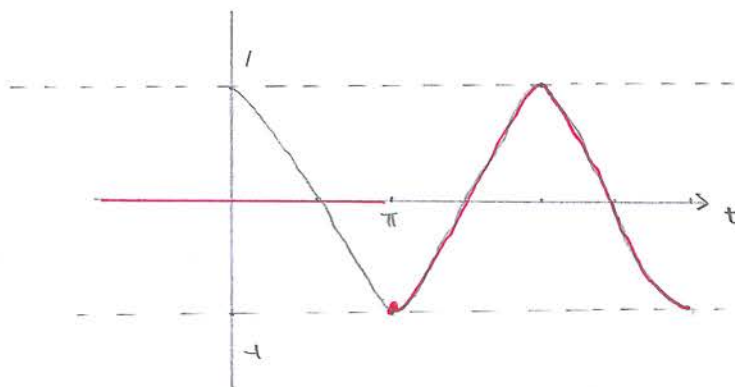


$$H(t-a) = \begin{cases} 1 & t \geq a \\ 0 & t < a \end{cases}$$



$$H(t-a)g(t) = \begin{cases} g(t) & t \geq a \\ 0 & t < a \end{cases}$$

(Ex)  $H(t-\pi) \cos t = \begin{cases} \cos t & t \geq \pi \\ 0 & t < \pi \end{cases}$



매개변수

$$H(t-a) - H(t-b)$$

$$(a < b)$$

$$= \begin{cases} 1 & t \geq a \\ 0 & t \leq a \end{cases} - \begin{cases} 1 & t > b \\ 0 & t < b \end{cases}$$

$$= \begin{cases} 0 & t \leq a \\ 1 & a \leq t \leq b \\ 0 & t \geq b \end{cases}$$

$$* [H(t-a) - H(t-b)] g(t) = \begin{cases} 0 & t \leq a \\ g(t) & a \leq t \leq b \\ 0 & b \leq t \end{cases}$$

switch off

switch on

switch off

[3] 21 &gt; 018 26 21

p101

2621 2.7

$$\mathcal{L}[H(t-a)f(t-a)] = e^{-as}F(s)$$

pf)

$$\mathcal{L}[H(t-a)f(t-a)]$$

$$= \int_0^{\infty} dt e^{-st} H(t-a) f(t-a)$$

$$= \int_0^a dt e^{-st} \overset{=0}{H(t-a)} f(t-a) + \int_a^{\infty} dt e^{-st} \overset{=1}{H(t-a)} f(t-a)$$

$$= \int_a^{\infty} dt e^{-st} f(t-a)$$

$$= \int_0^{\infty} du e^{-s(u+a)} f(u)$$

$$\downarrow u = t - a$$

$$= e^{-sa} \int_0^{\infty} du e^{-su} f(u)$$

$$\downarrow u \rightarrow \tau$$

$$= e^{-sa} \int_0^{\infty} dt e^{-st} f(t) \overset{F(s)}{}$$

$$= e^{-as} F(s)$$

x

note)

$$\mathcal{L}^{-1}[e^{-as}F(s)] = H(t-a)f(t-a)$$

p102

(8/11/2017)

$$g(t) = \begin{cases} 0 & t < 2 \\ t^2 + 1 & t \geq 2 \end{cases}$$

$$= H(t-2) (t^2 + 1)$$

$$= H(t-2) [ \{ (t-2) + 2 \}^2 + 1 ]$$

$$= H(t-2) [ (t-2)^2 + 4(t-2) + 5 ]$$

$$= H(t-2) (t-2)^2 + 4 H(t-2) (t-2) + 5 H(t-2)$$

$$G(s) = \mathcal{L}[g(t)]$$

$$= \mathcal{L}[H(t-2) (t-2)^2] + 4 \mathcal{L}[H(t-2) (t-2)] + 5 \mathcal{L}[H(t-2)]$$

$$= e^{-2s} \frac{\mathcal{L}[t^2]}{\frac{2}{s^3}} + 4 e^{-2s} \frac{\mathcal{L}[t]}{\frac{1}{s^2}} + 5 e^{-2s} \frac{\mathcal{L}[1]}{\frac{1}{s}}$$

(Formula 1, 2, 3; p87)

$$= e^{-2s} \left[ \frac{2}{s^3} + \frac{4}{s^2} + \frac{5}{s} \right]$$

P102

(문제 3.8)

$$\frac{dy}{dt} + 4 \frac{y}{t} = f(t) \quad y(0) = y'(0) = 0 \quad \left. \vphantom{\frac{dy}{dt} + 4 \frac{y}{t} = f(t)} \right\} - ①$$

$$f(t) = \begin{cases} 0 & t < 3 \\ t & t \geq 3 \end{cases} = H(t-3)t$$

Taking Laplace transform to Eq. ①

$$[s^2 Y(s) - s \overset{0}{y(0)} - \overset{0}{y'(0)}] + 4 Y(s) = \mathcal{L}[f(t)]$$

$$(s^2 + 4) Y(s) = \mathcal{L}[f(t)] \quad - ②$$

$$\mathcal{L}[f(t)]$$

$$= \mathcal{L}[H(t-3)t]$$

$$= \mathcal{L}[H(t-3)\{(t-3)+3\}]$$

$$= \mathcal{L}[H(t-3)(t-3)] + 3 \mathcal{L}[H(t-3)]$$

$$= e^{-3s} \underbrace{\mathcal{L}[t]}_{\frac{1}{s^2}} + 3 e^{-3s} \underbrace{\mathcal{L}[1]}_{\frac{1}{s}}$$

(제 2 이동 정리)

$$= e^{-3s} \left[ \frac{1}{s^2} + \frac{3}{s} \right]$$

$$= \frac{3s+1}{s^2} e^{-3s} \quad - ③$$

② → ④

$$Y(s) = \frac{3s+1}{s^2(s^2+4)} e^{-3s} \quad - ④$$

$$\frac{3s+1}{s^2(s^2+4)} = \frac{1}{4} \left[ \frac{3s+1}{s^2} - \frac{3s+1}{s^2+4} \right]$$

$$= \frac{3}{4} \frac{1}{s} + \frac{1}{4} \frac{1}{s^2} - \frac{3}{4} \frac{s}{s^2+4} - \frac{1}{4} \frac{1}{s^2+4} \quad - (7)$$

$$(7) \rightarrow (8)$$

$$Y(s) = \frac{3}{4} \frac{1}{s} e^{-2s} + \frac{1}{4} \frac{1}{s^2} e^{-2s} - \frac{3}{4} \frac{s}{s^2+4} e^{-2s} - \frac{1}{4} \frac{1}{s^2+4} e^{-2s} \quad - (8)$$

$$y(t) = \mathcal{L}^{-1}[Y]$$

$$= \frac{3}{4} \mathcal{L}^{-1}\left[\frac{1}{s} e^{-2s}\right] + \frac{1}{4} \mathcal{L}^{-1}\left[\frac{1}{s^2} e^{-2s}\right] - \frac{3}{4} \mathcal{L}^{-1}\left[\frac{s}{s^2+4} e^{-2s}\right] - \frac{1}{4} \mathcal{L}^{-1}\left[\frac{1}{s^2+4} e^{-2s}\right]$$

L(9)

$$(i) \mathcal{L}^{-1}\left[\frac{1}{s} e^{-2s}\right]$$

$$\mathcal{L}^{-1}\left[\frac{1}{s}\right] = 1$$

Since

$$\mathcal{L}^{-1}[e^{-as} F(s)] = H(t-a) f(t-a) \quad - (9)$$

$$\mathcal{L}^{-1}\left[\frac{1}{s} e^{-2s}\right] = H(t-2) \quad - (10)$$

$$(ii) \mathcal{L}^{-1}\left[\frac{1}{s^2} e^{-2s}\right]$$

$$\mathcal{L}^{-1}\left[\frac{1}{s^2}\right] = t$$

$$\mathcal{L}^{-1}\left[\frac{1}{s^2} e^{-2s}\right] = H(t-2) (t-2) \quad - (11)$$



$$(iii) \mathcal{L}^{-1} \left[ \frac{s}{s^2+4} e^{-3s} \right]$$

$$\mathcal{L}^{-1} \left[ \frac{s}{s^2+4} \right] = \cos 2t$$

(see formula 12, p85)

$$\mathcal{L}^{-1} \left[ \frac{s}{s^2+4} e^{-3s} \right] = H(t-3) \cos 2(t-3) \quad - \textcircled{11}$$

$$(iv) \mathcal{L}^{-1} \left[ \frac{1}{s^2+4} e^{-3s} \right]$$

$$\mathcal{L}^{-1} \left[ \frac{1}{s^2+4} \right] = \frac{1}{2} \mathcal{L}^{-1} \left[ \frac{2}{s^2+4} \right] = \frac{1}{2} \sin 2t$$

(see formula 11, p85)

$$\mathcal{L}^{-1} \left[ \frac{1}{s^2+4} e^{-3s} \right] = H(t-3) \frac{1}{2} \sin 2(t-3) \quad - \textcircled{12}$$

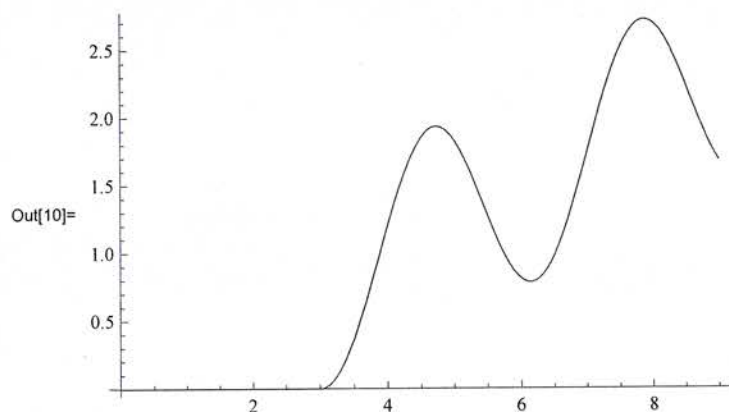
$$\textcircled{9}, \textcircled{10}, \textcircled{11}, \textcircled{12} \Rightarrow \textcircled{7}$$

$$y(t) = \frac{3}{4} H(t-3) + \frac{1}{4} H(t-3) (t-3) - \frac{3}{4} H(t-3) \cos 2(t-3) - \frac{1}{8} H(t-3) \sin 2(t-3)$$

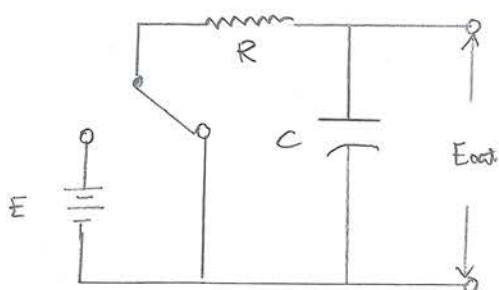
$$= H(t-3) \left[ \frac{1}{4} t - \frac{3}{4} \cos 2(t-3) - \frac{1}{8} \sin 2(t-3) \right]$$

$$= \begin{cases} 0 & t < 3 \\ \frac{1}{8} [2t - 6 \cos 2(t-3) - \sin 2(t-3)] & t \geq 3 \end{cases}$$

```
In[9]:= f[t_] := If[t < 3, 0, (1/8) (2 t - 6 Cos[2 (t - 3)] - Sin[2 (t - 3)])];
Plot[f[t], {t, 0, 9}]
```



[4] 전기 회로 분석



$$E = 10(V)$$

$$R = 250,000(\Omega)$$

$$C = 10^{-6}(F)$$

$$E_{out} = ? \text{ (출력전압)}$$

$$E \Rightarrow E [H(t-2) - H(t-3)] \quad - \textcircled{1}$$

$$iR + \frac{q}{C} = E [H(t-2) - H(t-3)]$$

$$i = \frac{dq}{dt}$$

$$\Rightarrow R \frac{dq}{dt} + \frac{1}{C} q = E [H(t-2) - H(t-3)] \quad - \textcircled{2}$$

$$q(0) = 0$$

Taking Laplace transform to Eq. ②

$$R[sQ(s) - q(0)] + \frac{1}{C} Q(s) = E [\mathcal{L}[H(t-2)] - \mathcal{L}[H(t-3)]] \quad - \textcircled{3}$$

$$\mathcal{L}[H(t-2)] = e^{-2s} \mathcal{L}[1] = \frac{1}{s} e^{-2s} \quad - \textcircled{4}$$

$$\mathcal{L}[H(t-3)] = e^{-3s} \mathcal{L}[1] = \frac{1}{s} e^{-3s}$$

제2 이동정리

③  $\rightarrow$  ④

$$(Rs + \frac{1}{C}) Q(s) - R \underline{q(0)} = \frac{E}{s} (e^{-2s} - e^{-3s})$$

$$Q(s) = (Rs + \frac{1}{C})^{-1} \frac{E}{s} (e^{-2s} - e^{-3s})$$

$$= \frac{CE}{s(RCs + 1)} (e^{-2s} - e^{-3s}) \quad - \textcircled{5}$$

Using

$$\frac{1}{s(RCs+1)} = \frac{1}{s} - \frac{RC}{RCs+1} \quad - \textcircled{6}$$

$$\Theta(s) = CE \left( \frac{1}{s} - \frac{RC}{RCs+1} \right) (e^{-2s} - e^{-3s})$$

$$= CE \left[ \frac{1}{s} e^{-2s} - \frac{1}{s} e^{-3s} - \frac{RC}{RCs+1} e^{-2s} + \frac{RC}{RCs+1} e^{-3s} \right] \quad - \textcircled{7}$$

$$q(t) = CE \mathcal{L}^{-1} \left[ \frac{1}{s} e^{-2s} \right] - CE \mathcal{L}^{-1} \left[ \frac{1}{s} e^{-3s} \right] - RC^2 E \mathcal{L}^{-1} \left[ \frac{1}{RCs+1} e^{-2s} \right]$$

$$+ RC^2 E \mathcal{L}^{-1} \left[ \frac{1}{RCs+1} e^{-3s} \right] \quad - \textcircled{8}$$

$$\mathcal{L}^{-1} [e^{-as} f(s)] = H(t-a) f(t-a) \quad - \textcircled{9}$$

$$(i) \mathcal{L}^{-1} \left[ \frac{1}{s} e^{-2s} \right]$$

$$\mathcal{L}^{-1} \left[ \frac{1}{s} \right] = 1$$

$$\mathcal{L}^{-1} \left[ \frac{1}{s} e^{-2s} \right] = H(t-2) \quad - \textcircled{10}$$

$$(ii) \mathcal{L}^{-1} \left[ \frac{1}{s} e^{-3s} \right] = H(t-3) \quad - \textcircled{11}$$

$$(iii) \mathcal{L}^{-1} \left[ \frac{1}{RCs+1} e^{-2s} \right]$$

$$\mathcal{L}^{-1} \left[ \frac{1}{RCs+1} \right]$$

$$= \mathcal{L}^{-1} \left[ \frac{1}{RC} \frac{1}{s + \frac{1}{RC}} \right]$$

$$= \frac{1}{RC} \mathcal{L}^{-1} \left[ \frac{1}{s + \frac{1}{RC}} \right]$$

$$= \frac{1}{RC} e^{-\frac{t}{RC}}$$

(Formula 5, p89)

$$\mathcal{L}^{-1} \left[ \frac{1}{RCs+1} e^{-2s} \right] = H(t-2) \frac{1}{RC} e^{-\frac{1}{RC}(t-2)} \quad - (12)$$

$$(iv) \mathcal{L}^{-1} \left[ \frac{1}{RCs+1} e^{-3s} \right] = H(t-3) \frac{1}{RC} e^{-\frac{1}{RC}(t-3)} \quad - (13)$$

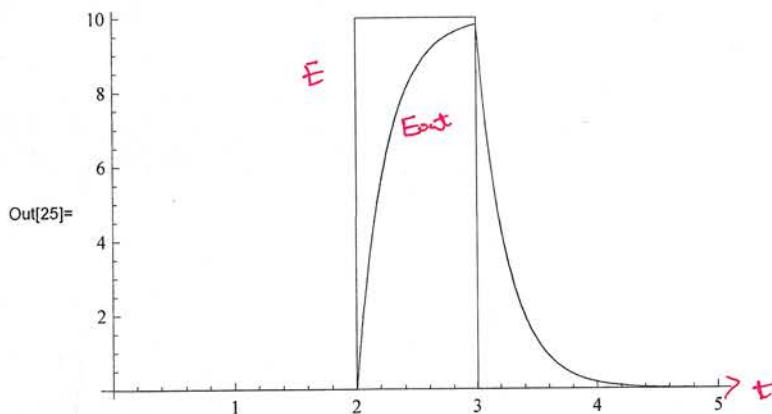
(10), (11), (12), (13)  $\rightarrow$  (14)

$$\begin{aligned} q(t) &= CE H(t-2) - CE H(t-3) - RC^2 E H(t-2) \frac{1}{RC} e^{-\frac{1}{RC}(t-2)} \\ &\quad + RC^2 E H(t-3) \frac{1}{RC} e^{-\frac{1}{RC}(t-3)} \\ &= CE H(t-2) \left[ 1 - e^{-\frac{1}{RC}(t-2)} \right] - CE H(t-3) \left[ 1 - e^{-\frac{1}{RC}(t-3)} \right] \quad - (14) \end{aligned}$$

$$E_{out} = \frac{q}{C}$$

$$\begin{aligned} &= E H(t-2) \left[ 1 - e^{-\frac{1}{RC}(t-2)} \right] - E H(t-3) \left[ 1 - e^{-\frac{1}{RC}(t-3)} \right] \\ &= 10 H(t-2) \left[ 1 - e^{-4(t-2)} \right] - 10 H(t-3) \left[ 1 - e^{-4(t-3)} \right] \end{aligned}$$

```
In[22]:= Ein[t_] := If[2 < t < 3, 10, 0];
H[t_] := If[t >= 0, 1, 0];
Eout[t_] := 10 H[t-2] (1 - Exp[-4 (t-2)]) - 10 H[t-3] (1 - Exp[-4 (t-3)]);
Plot[{Ein[t], Eout[t]}, {t, 0, 5}, PlotStyle -> {Red, Blue}]
```



Def: convolution

$$(f * g)(t) = \int_0^t f(t-\tau) g(\tau) d\tau$$

for  $g=1$  convolution

$$* (f * g)(t) = (g * f)(t)$$

(Pf)

$$(g * f)(t)$$

$$= \int_0^t g(t-\tau) f(\tau) d\tau$$

$$= \int_t^0 (-ds) g(s) f(t-s)$$

$$\downarrow s = t - \tau$$

$$= \int_0^t ds f(t-s) g(s)$$

$$\downarrow s \rightarrow \tau$$

$$= \int_0^t d\tau f(t-\tau) g(\tau)$$

$$= (f * g)(t)$$

\*

Def 3.8

Convolution theorem

$$\mathcal{L}[f * g] = F(s) G(s)$$

(Pf) Def 3.8

$$* \mathcal{L}^{-1}[FG] = (f * g)(t) = \int_0^t f(t-\tau) g(\tau) d\tau$$

(Q12.10)

$$f(t) = 2t^2 + \int_0^t f(t-\tau) e^{-\tau} d\tau \quad - \textcircled{1} \quad \text{उससे हमें पता है}$$

what is  $f(t)$ ?

Taking Laplace transform to Eq. ①

$$F(s) = 2 \underbrace{\mathcal{L}[t^2]}_{\frac{2}{s^3}} + \underbrace{\mathcal{L}\left[\int_0^t f(t-\tau) e^{-\tau} d\tau\right]}_{(f * g)(t)} \quad \text{where } g(t) = e^{-t}$$

(Formula 3, p87)

$$= \frac{4}{s^3} + F(s) \underbrace{\mathcal{L}[e^{-t}]}_{\frac{1}{s+1}} \quad (\because \text{convolution theorem})$$

(Formula 5, p87)

$$= \frac{4}{s^3} + \frac{1}{s+1} F(s)$$

$$\Rightarrow F(s) = \frac{4(s+1)}{s^4} = 4 \frac{1}{s^3} + 4 \frac{1}{s^4} \quad - \textcircled{2}$$

Taking inverse Laplace transform to Eq. ②

$$f(t) = 4 \mathcal{L}^{-1}\left[\frac{1}{s^3}\right] + 4 \mathcal{L}^{-1}\left[\frac{1}{s^4}\right]$$

$$= 4 \frac{1}{2} \underbrace{\mathcal{L}^{-1}\left[\frac{2}{s^3}\right]}_{t^2} + 4 \frac{1}{6} \underbrace{\mathcal{L}^{-1}\left[\frac{3!}{s^4}\right]}_{t^3}$$

(Formula 3, p87)

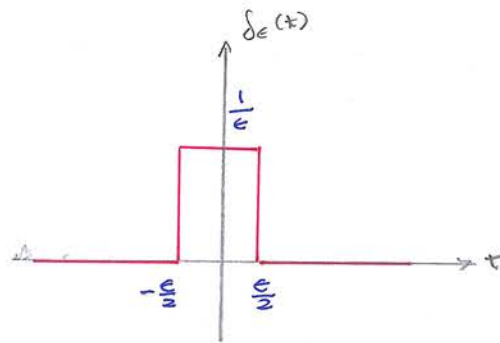
$$= 2t^2 + \frac{2}{3} t^3$$

X

P110  $\delta$  함수의 정적함수 및 Dirac- $\delta$  함수

$$\delta_\epsilon(t) = \frac{1}{\epsilon} \left[ H\left(t + \frac{\epsilon}{2}\right) - H\left(t - \frac{\epsilon}{2}\right) \right]$$

$$= \begin{cases} 0 & t < -\frac{\epsilon}{2} \\ \frac{1}{\epsilon} & -\frac{\epsilon}{2} \leq t < \frac{\epsilon}{2} \\ 0 & \frac{\epsilon}{2} \leq t \end{cases}$$



Dirac- $\delta$  함수

$$\delta(t) = \lim_{\epsilon \rightarrow 0} \delta_\epsilon(t)$$

$$\textcircled{1} \int_{-\infty}^{\infty} \delta(t) dt = 1$$

$$\textcircled{2} \delta(-t) = \delta(t)$$

$$\textcircled{3} \mathcal{L}[\delta(t)] = 1$$

~~:  $\delta$  함수의 여파특성 (filtering property)~~

$$\textcircled{4} \int_0^{\infty} f(t) \delta(t-a) dt = f(a)$$

( $a > 0$ ) :  $\delta$ -함수의 여파특성  
(filtering property)

$$\textcircled{3} \quad \mathcal{L}[d_\epsilon(t)]$$

$$= \frac{1}{\epsilon} \left[ \underbrace{\mathcal{L}\left[H\left(t + \frac{\epsilon}{2}\right)\right]}_{\frac{1}{s} e^{\frac{\epsilon}{2}s}} - \underbrace{\mathcal{L}\left[H\left(t - \frac{\epsilon}{2}\right)\right]}_{\frac{1}{s} e^{-\frac{\epsilon}{2}s}} \right]$$

(제2 이동 정리)

$$= \frac{1}{\epsilon} \frac{1}{s} \left[ e^{\frac{\epsilon}{2}s} - e^{-\frac{\epsilon}{2}s} \right]$$

$$= \sinh \frac{\epsilon}{2}s$$

$$(\because \sinh \theta \equiv \frac{e^\theta - e^{-\theta}}{2})$$

$$= \frac{2}{\epsilon} \frac{\sinh \frac{\epsilon}{2}s}{e}$$

$$\Rightarrow \mathcal{L}[d(t)]$$

$$= \lim_{\epsilon \rightarrow 0} \mathcal{L}[d_\epsilon(t)]$$

$$= \lim_{\epsilon \rightarrow 0} \frac{\sinh \frac{\epsilon}{2}s}{e}$$

$$= \lim_{\epsilon \rightarrow 0} \frac{\frac{s}{2} \cosh \frac{\epsilon}{2}s}{1}$$

로피탈 정리

$$= 1$$



④ Filtering property

$$\int_0^{\infty} f(t) \delta_{\epsilon}(t-a) dt$$

$$\delta_{\epsilon}(t-a) = \begin{cases} 0 & t < a - \frac{\epsilon}{2} \\ \frac{1}{\epsilon} & a - \frac{\epsilon}{2} \leq t < a + \frac{\epsilon}{2} \\ 0 & a + \frac{\epsilon}{2} \leq t \end{cases}$$

$$\begin{aligned} t &< a - \frac{\epsilon}{2} \\ a - \frac{\epsilon}{2} &\leq t < a + \frac{\epsilon}{2} \\ a + \frac{\epsilon}{2} &\leq t \end{aligned}$$

$$= \int_0^{a-\frac{\epsilon}{2}} f(t) \delta_{\epsilon}(t-a) dt$$

$$+ \int_{a-\frac{\epsilon}{2}}^{a+\frac{\epsilon}{2}} f(t) \delta_{\epsilon}(t-a) dt + \int_{a+\frac{\epsilon}{2}}^{\infty} f(t) \delta_{\epsilon}(t-a) dt$$

$$= \frac{1}{\epsilon} \int_{a-\frac{\epsilon}{2}}^{a+\frac{\epsilon}{2}} f(t) dt$$

$$\Rightarrow \int_0^{\infty} f(t) \delta(t-a) dt$$

$$= \lim_{\epsilon \rightarrow 0} \int_0^{\infty} f(t) \delta_{\epsilon}(t-a) dt$$

$$= \lim_{\epsilon \rightarrow 0} \frac{1}{\epsilon} \int_{a-\frac{\epsilon}{2}}^{a+\frac{\epsilon}{2}} f(t) dt$$

$$= f(a) \int_{a-\frac{\epsilon}{2}}^{a+\frac{\epsilon}{2}} dt = \epsilon f(a)$$

$$= f(a)$$

\*.

p113 (문제 3.11)

$$\frac{d^2 y}{dt^2} + 2 \frac{dy}{dt} + 2y = \delta(t-2) \quad y(0) = y'(0) = 0 \quad - \textcircled{1}$$

Taking Laplace transform to Eq. ①

$$[s^2 Y(s) - \overset{=0}{s} y(0) - \overset{=0}{y'(0)}] + 2[sY(s) - \overset{=0}{y(0)}] + 2Y(s) = \mathcal{L}[\delta(t-2)]$$

$$(s^2 + 2s + 2) Y(s) = \mathcal{L}[\delta(t-2)] \quad - \textcircled{2}$$

$$\mathcal{L}[\delta(t-2)]$$

$$= \int_0^{\infty} dt e^{-st} \delta(t-2)$$

↓ Filtering property

$$= e^{-2s} \quad - \textcircled{3}$$

② → ③

$$Y(s) = \frac{e^{-2s}}{s^2 + 2s + 2} \quad - \textcircled{4}$$

$$y(t) = \mathcal{L}^{-1}\left[\frac{e^{-2s}}{s^2 + 2s + 2}\right] \quad - \textcircled{5}$$

$$\mathcal{L}^{-1}\left[\frac{1}{s^2 + 2s + 2}\right]$$

$$= \mathcal{L}^{-1}\left[\frac{1}{(s+1)^2 + 1}\right]$$

$$= e^{-t} \mathcal{L}^{-1}\left[\frac{1}{s^2 + 1}\right]$$

(∵  $\mathcal{L}^{-1}[F(s-a)] = e^{at} f(t)$ ) 제1 이동정리

sint (formula 11, p88)

$$= e^{-t} \sin t \quad - \textcircled{6}$$

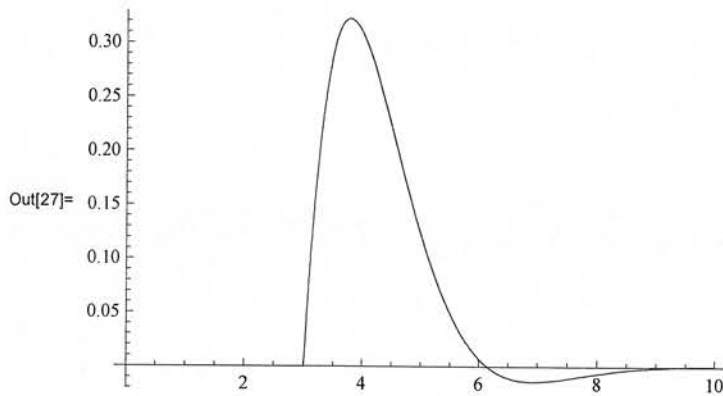
Using ⑥

$$y(t) = \mathcal{L}^{-1} \left[ \frac{e^{-2s}}{s^2 + 2s + 2} \right]$$

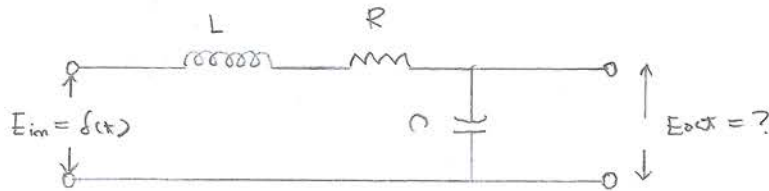
$$= H(t-2) e^{-(t-2)} \sin(t-2)$$

( $\because \mathcal{L}^{-1}[e^{-as} F(s)] = H(t-a) f(t-a)$ ) 제2 이동 정리

```
In[26]:= H[t_] := If[t >= 0, 1, 0];
Plot[H[t - 3] Exp[-(t - 3)] Sin[t - 3], {t, 0, 10}]
```



(09/31/2.12)



$$L = 1 \text{ H}$$

$$R = 10 \Omega$$

$$C = 0.01 \text{ F}$$

$$L \frac{di}{dt} + iR + \frac{q}{C} = E_{in} = \delta(t)$$

$$i = \frac{dq}{dt}$$

$$L \frac{d^2q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = \delta(t) \quad - \textcircled{1}$$

$$q(0) = \frac{dq}{dt}(0) = 0$$

Taking Laplace transform to Eq. ①

$$L \left[ s^2 Q(s) - s \underline{q(0)} - \underline{q'(0)} \right] + R \left[ s Q(s) - \underline{q(0)} \right] + \frac{1}{C} Q(s) = 1$$

$$(Ls^2 + Rs + \frac{1}{C}) Q(s) = 1$$

$$Q(s) = \frac{1}{Ls^2 + Rs + \frac{1}{C}}$$

$$= \frac{1}{L} \frac{1}{s^2 + \frac{R}{L}s + \frac{R^2}{4L^2} + \left( \frac{1}{LC} - \frac{R^2}{4L^2} \right)}$$

$$= \frac{1}{L} \frac{1}{\left( s + \frac{R}{2L} \right)^2 + \left( \frac{1}{LC} - \frac{R^2}{4L^2} \right)} \quad - \textcircled{2}$$

$$g(t) = \mathcal{L}^{-1}[Q(s)]$$

$$= \frac{1}{L} \mathcal{L}^{-1} \left[ \frac{1}{\left(s + \frac{R}{2L}\right)^2 + \left(\frac{1}{LC} - \frac{R^2}{4L^2}\right)} \right]$$

$$= \frac{1}{L} e^{-\frac{R}{2L}t} \mathcal{L}^{-1} \left[ \frac{1}{s^2 + \left(\frac{1}{LC} - \frac{R^2}{4L^2}\right)} \right] \quad (\because \mathcal{L}^{-1}[F(s-a)] = e^{at} f(t))$$

제1 이동 정리

$$= \frac{1}{L} e^{-\frac{R}{2L}t} \frac{1}{\sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}} \mathcal{L}^{-1} \left[ \frac{\sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}}{s^2 + \left(\frac{1}{LC} - \frac{R^2}{4L^2}\right)} \right]$$

$$\sin \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}} t \quad (\text{Formula 11: p88})$$

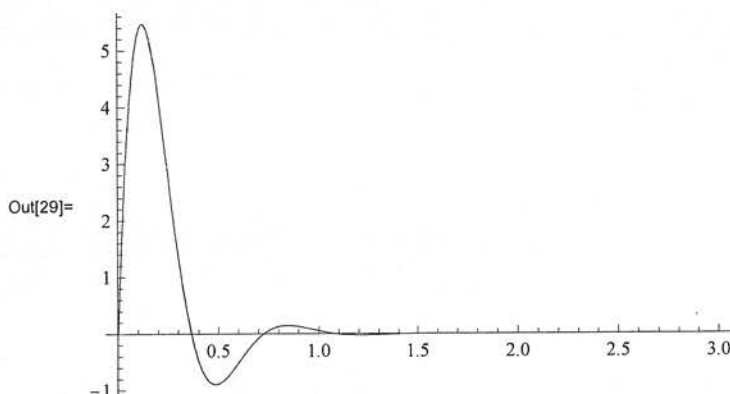
$$= \frac{1}{L \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}} e^{-\frac{R}{2L}t} \sin \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}} t \quad - \textcircled{2}$$

$$E_{out}(t) = \frac{1}{C} g(t)$$

$$= \frac{1}{LC \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}}} e^{-\frac{R}{2L}t} \sin \sqrt{\frac{1}{LC} - \frac{R^2}{4L^2}} t$$

$$= \frac{20}{\sqrt{3}} e^{-5t} \sin(5\sqrt{3}t)$$

In[29]:= Plot[(20 / Sqrt[3]) Exp[-5 t] Sin[5 Sqrt[3] t], {t, 0, 3}, PlotRange -> All]



(07/21/3.13)

$$\left. \begin{aligned} x'' - 2x' + 3y' + 2y &= 4 \\ 2y' - x' + 3y &= 0 \\ x(0) = x'(0) = y(0) &= 0 \end{aligned} \right\} - (1)$$

Taking Laplace transform to Eq. (1)

$$[s^2 X(s) - \overset{=0}{s x(0)} - \overset{=0}{x'(0)}] - 2[sX(s) - \overset{=0}{x(0)}] + 3[sY(s) - \overset{=0}{y(0)}] + 2Y(s) = 4 \frac{1}{s}$$

$$(s^2 - 2s)X(s) + (3s + 2)Y(s) = \frac{4}{s} \quad - (2)$$

$$2[sY(s) - \overset{=0}{y(0)}] - [sX(s) - \overset{=0}{x(0)}] + 3Y(s) = 0$$

$$-sX(s) + (2s + 3)Y(s) = 0 \quad - (3)$$

$$\Rightarrow X(s) = \frac{2(2s + 3)}{s^2(s + 2)(s - 1)}$$

$$Y(s) = \frac{2}{s(s + 2)(s - 1)} \quad - (4)$$

$$X(s) = \frac{-\frac{7}{2}s - 3}{s^2} + \frac{1}{6} \frac{1}{s + 2} + \frac{10}{3} \frac{1}{s - 1}$$

$$= -\frac{7}{2} \frac{1}{s} - 3 \frac{1}{s^2} + \frac{1}{6} \frac{1}{s + 2} + \frac{10}{3} \frac{1}{s - 1} \quad - (5)$$

$$Y(s) = -\frac{1}{s} + \frac{1}{3} \frac{1}{s + 2} + \frac{2}{3} \frac{1}{s - 1} \quad - (6)$$

$$x(t) = \mathcal{L}^{-1}[X(s)]$$

$$= -\frac{7}{2} \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s}\right]}_{=1} - 3 \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s^2}\right]}_t + \frac{1}{6} \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s+2}\right]}_{e^{-2t}} + \frac{10}{2} \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s-1}\right]}_{e^t} \quad (\text{part})$$

$$= -\frac{7}{2} - 3t + \frac{1}{6} e^{-2t} + \frac{10}{2} e^t$$

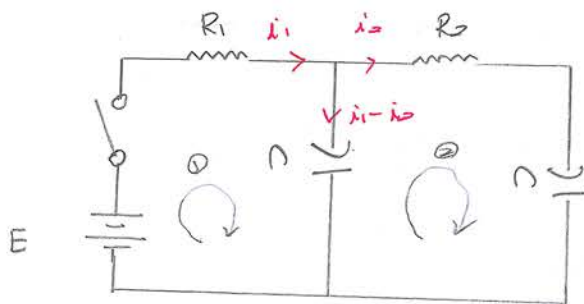
$$y(t) = \mathcal{L}^{-1}[Y(s)]$$

$$= -\underbrace{\mathcal{L}^{-1}\left[\frac{1}{s}\right]}_{=1} + \frac{1}{2} \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s+2}\right]}_{e^{-2t}} + \frac{2}{2} \underbrace{\mathcal{L}^{-1}\left[\frac{1}{s-1}\right]}_{e^t}$$

$$= -1 + \frac{1}{2} e^{-2t} + \frac{2}{2} e^t$$

✕

(or 13.15)



$$E = 10(V)$$

$$R_1 = 40(\Omega)$$

$$R_2 = 60(\Omega)$$

$$C = \frac{1}{20}(F)$$

Let

$$i_1 = \frac{dq_1}{dt} \quad i_2 = \frac{dq_2}{dt} \quad - (1)$$

From loop ①

$$i_1 R_1 + \frac{q_1 - q_2}{C} = E \quad - (2)$$

From loop ②

$$i_2 R_2 + \frac{q_2}{C} = \frac{q_1 - q_2}{C} \quad - (3)$$

Using Eq. ① Eq. ② and ③ becomes

$$R_1 \frac{dq_1}{dt} + \frac{1}{C} (q_1 - q_2) = E \quad - (4)$$

$$R_2 \frac{dq_2}{dt} + \frac{1}{C} (-q_1 + 2q_2) = 0 \quad - (5)$$

$$q_1(0) = q_2(0) = 0$$



Taking Laplace transform to Eq ⑥ and ⑦

$$R_1 [s Q_1(s) - \underbrace{g_1(0)}_{=0}] + \frac{1}{C} [Q_1(s) - Q_2(s)] = E \frac{1}{s}$$

$$(R_1 s + \frac{1}{C}) Q_1(s) - \frac{1}{C} Q_2(s) = \frac{E}{s} \quad - \text{⑧}$$

$$R_2 [s Q_2(s) - \underbrace{g_2(0)}_{=0}] + \frac{1}{C} [-Q_1(s) + 2 Q_2(s)] = 0$$

$$-\frac{1}{C} Q_1(s) + (R_2 s + \frac{2}{C}) Q_2(s) = 0 \quad - \text{⑨}$$

From ⑧ and ⑨

$$Q_1(s) = \frac{E (C R_2 s + 2)}{s [C R_1 R_2 s^2 + (2 R_1 + R_2) s + \frac{1}{C}]} = \frac{1}{4} \frac{s+4}{s(s+1)(s+6)} \quad - \text{⑩}$$

$$Q_2(s) = \frac{E}{s [C R_1 R_2 s^2 + (2 R_1 + R_2) s + \frac{1}{C}]} = \frac{1}{2} \frac{1}{s(s+1)(s+6)} \quad - \text{⑪}$$

$$Q_1(s) = \frac{1}{4} \left[ \frac{2}{s} - \frac{3}{5} \frac{1}{s+1} - \frac{1}{15} \frac{1}{s+6} \right]$$

$$= \frac{1}{6} \frac{1}{s} - \frac{3}{20} \frac{1}{s+1} - \frac{1}{60} \frac{1}{s+6}$$

$$\Rightarrow g_1(t) = \frac{1}{6} - \frac{3}{20} e^{-t} - \frac{1}{60} e^{-6t}$$

$$\Rightarrow i_1 = \frac{dg_1}{dt} = \frac{3}{20} e^{-t} + \frac{1}{10} e^{-6t}$$

$$Q_2(s) = \frac{1}{2} \left[ \frac{1}{6} \frac{1}{s} - \frac{1}{5} \frac{1}{s+1} + \frac{1}{30} \frac{1}{s+6} \right]$$

$$= \frac{1}{12} \frac{1}{s} - \frac{1}{10} \frac{1}{s+1} + \frac{1}{60} \frac{1}{s+6}$$

$$q_2(t) = \frac{1}{12} - \frac{1}{10} e^{-t} + \frac{1}{60} e^{-6t}$$

$$\Rightarrow i_2(t) = \frac{dq_2}{dt} = \frac{1}{10} e^{-t} - \frac{1}{10} e^{-6t}$$

x