

PROBLEM OF THE DAY 15

Shortest Path Problem: Dijkstra's Algorithm

Dijkstra's Algorithm: Suppose we want to find a shortest path from a given node (vertex) s to other nodes in a network (one-to-all shortest path problem)

- Node s is called a starting node (or initial) node
- Dijkstra's algorithm starts by assigning some initial values for the distances from node s and to every other node in the network.
- It operates in steps, where at each step the algorithm improves the distance values.
- At each step, the shortest distance from node s to another node is determined

Step 1. Initialization

- Assign distance zero to node s , and label it as Permanent. [The state of node s is $(0, p)$.]
- Assign to every other node a distance value of ∞ and label them as Temporary. [The state of every other node is (∞, t) .]
- Designate the node s as the current node

denotes when you're done w/ that node

Step 2. Distance Value Update and Current Node Designation Update

Let i be the current node.

- (1) Find the set J of nodes with temporary labels that can be reached from the current node i by a link (i, j) (edge). Update the distance values of these nodes.

- For each $j \in J$, the distance value d_j of node j (distance from node i) is updated as follows

$$d_j = \min\{d_j, d_i + c_{ij}\},$$

where c_{ij} is the cost (or length) of link (i, j) , as given in the graph network.

- (2) Determine a node j^* that has the smallest distance value d_{j^*} among all temporary nodes.

- (3) Change the label of node j^* to permanent and designate this node as the current node.

find new temporary node w/ shortest distance

Step 3. Termination Criterion

- If all nodes that can be reached from node s are labeled permanent, then stop - we are done.
- If we cannot reach any temporary labeled node from the current node, then all the temporary labels become permanent - we are done.
- Otherwise, go to Step 2.

subgraph in purple gives shortest route and forms a spanning tree

Question: In Dijkstra's algorithm, if we delete those links (edges) from our graph network that are not needed to specify the shortest path from node s to all other nodes, then what kind of spanning subgraph remains?

*① s + w + t
② current +*

(M) which of 4 as cost

(∞, t)

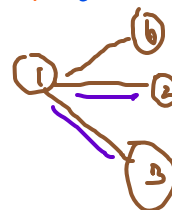
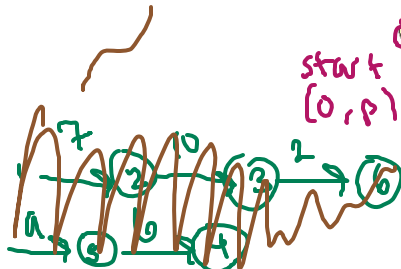
(∞, t)

start (0, p)

(∞, t)

7, p

"weighted graph" where the w is the distance



1. Find the shortest path from node A to node F.

