IID and Markov Models

Gaurav Sharma

University of Rochester

Dependence in Probabilistic Models

- Fundamentally, probabilistic models model dependence
 - Single variable across "time" and multiple variables
 - Will begin with single variable across "time"
 - Discrete time random process

$$X_1, X_2, \ldots X_n$$

indexed collection of RVs

► Full characterization: All Joint PMF/PDFs

$$p(x_1, x_2, \dots x_n) = \Pr\{X_1 = x_1, X_2 = x_2, \dots X_n = x_n\}$$

- Absolutely general: Can model any dependence
- How useful is it?
 - Almost useless, except in understanding assumptions underlying practical models

Independent Identically Distributed (IID)

- Simplest model for dependence
- ▶ X₁, X₂, . . . independent and identical distribution
- Factorization of Joint PMF

$$p(x_1, x_2, ..., x_n) = p(x_1)p(x_2)p(x_3)...p(x_n)$$

- Examples:
 - ► Good?
 - ▶ Bad?
- Usage Examples

Markov Models

- Allow more realistic models by incorporating dependency
- Conditional Independence
 - ▶ Past independent of future given present

$$\Pr\{X_{n+1} = x_{n+1} \mid X_n = x_n, X_{n-1} = x_{n-1}, \dots X_1 = x_1\}$$

=\Pr\{X_{n+1} = x_{n+1} \ | X_n = x_n\}

Factorization of Joint PMF

$$p(x_1, x_2, ... x_n) = p(x_1)p(x_2 \mid x_1)p(x_3 \mid x_2)...p(x_n \mid x_{n-1})$$

► Contrast with more general Bayes Rule based Factorization

$$p(x_1, x_2, \dots x_n) = p(x_1)p(x_2 \mid x_1)p(x_3 \mid x_2, x_1) \dots p(x_n \mid x_{n-1}, x_{n-2} \dots x_1)$$

Time-Invariant (Homogeneous) Markov Models

 Additional simplification: transition probabilities independent of time

$$\Pr\{X_{n+1} = x_{n+1} \mid X_n = x_n\} = \Pr\{X_2 = x_{n+1} \mid X_1 = x_n\}$$

$$\Pr\{X_{n+1} = j \mid X_n = i\} = \Pr\{X_2 = j \mid X_1 = i\} = P_{ii}$$

- ▶ Finite set of discrete outcomes: $X_n \in \{1, 2, ... L\}$
- ► L × L Transition probability matrix

$$\mathbf{P} = [P_{ij}]$$

Markov chain terminology sometimes restricted to this setting: discrete time and finite discrete outcome space

Markov Chain Characterization

► Full characterization of time-invariant Markov chain Recall,

$$p(x_1, x_2, \dots x_n) = p(x_1)p(x_2 \mid x_1)p(x_3 \mid x_2) \dots p(x_n \mid x_{n-1})$$
 (1)
$$p_i^{(n)} = p_{X_n}(i)$$

$$p^{(n)} = [p_i^{(n)}]$$

▶ $\mathbf{p}_{1\times I}^{(1)}$ and $\mathbf{P}_{L\times L}$ fully characterize the Markov chain

$$\mathbf{p}^{(n)} = \mathbf{p}^{(n-1)} \mathbf{P} = \mathbf{p}^{(1)} \mathbf{P}^{(n-1)}$$

Markov Chain Example I

- ▶ Is an IID process a Markov process?
- ► For a finite-state discrete time IID process:
 - ▶ What is **P**?
 - ▶ What is **p**⁽¹⁾?

Markov Chain Example II

Simple two state Markov Chain

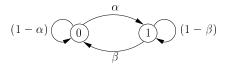


Figure: Transition Diagram representation of a Binary Markov Chain.

- ▶ What is **P**?
- ▶ What is p⁽¹⁾?
- Under what conditions does this degenerate into an IID process?

Time-invariance and stationarity

- ▶ Is a time-invariant Markov Chain (MC) stationary
- Depends on initial distribution
 - Example

Characterization of Finite-State Discrete Time Markov Chains

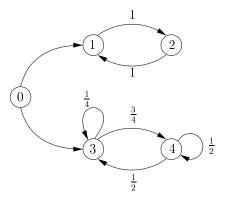


Figure: Characterization of states of a time-invariant Markov Chain.

Characterization of Finite-State Discrete Time Markov Chains

- Partitioning of States into Transient and Irreducible Sets
 - Transient states (impossible to return to from some reachable state)
 - ► An Irreducible set of states
 - Periodic or aperiodic (ergodic)
 - Markov Chain irreducible if all states form a single irreducible set
 - ► Focus particularly on irreducible ergodic MCs

Markov Model as a Representation for the Physical World

- ► Future state = function of current state
 - Possibly random function
 - independent of past
 - suitably chosen set of state variables should suffice
- Practical challenges
 - State space is too large
 - Not all states are observable
 - hidden/latent variables
- Observations are noisy

Summary

- Probabilistic models must tread a fine line between generality and utility
- Simplest model: IID
- Markov Models: More powerful class of models
- ► Important: Note distinction between distribution and temporal dependence
 - Specifically time and space of outcomes may independently be continuous or discrete