

COM1006 Devices and Networks (Autumn)

COM1090 Computer Architectures

Lecture #10

Assembly language programming

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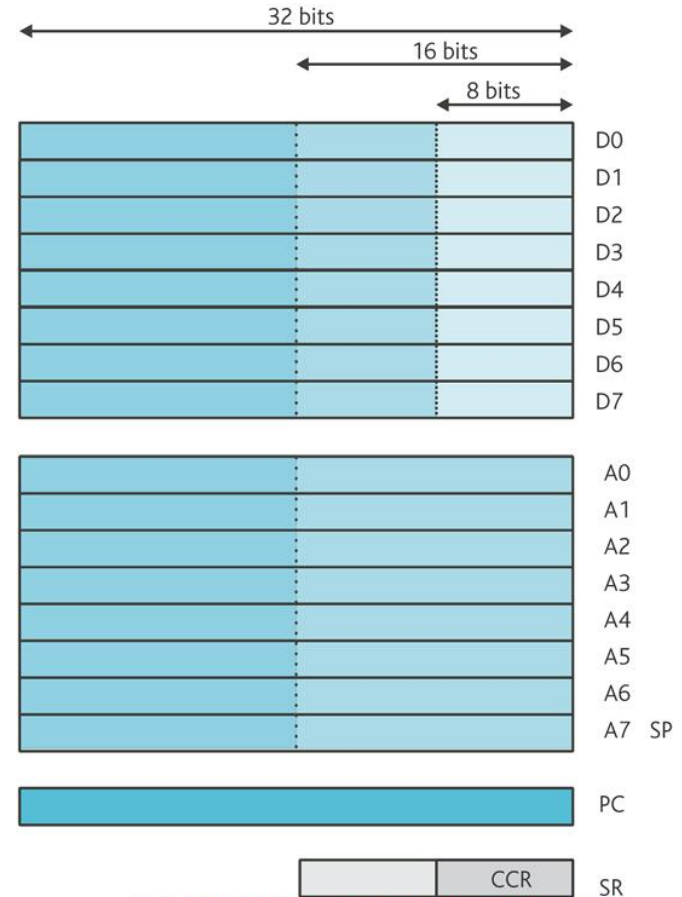
Based on Chapters 5-6 in Clements, Principles of Computer Hardware

► Aims of this lecture

- Learning **basics** of assembly language programming on the Motorola 68K as a typical CISC architecture.
- To demonstrate the EASy68K 68K assembler and simulator, which will be used in the tutorials.
- To see how variables are defined and stored in memory.
- To introduce common 68K instructions for
 - data movement
 - logical operations
 - arithmetic operations
 - branching instructions (flow control)

► Register sizes

- Data registers are 32 bits wide, but can be treated as if they were 8 or 16 bit wide.
- This is determined by size suffixes:
 - 8-bit: `.B`, e.g. `MOVE .B D0, D1`
 - 16-bit: `.W`, e.g. `MOVE .W D0, D1`
 - 32-bit: `.L`, e.g. `MOVE .L D0, D1`
- Not stating any suffix uses the **default of 16 bits**.



The status register contains information about the state (operating mode) of the computer.

► 68K Status flags

- The processor status register (PSR) records the outcome of an instruction (hence the state of the machine).
- It contains at least 4 bits (flags) whose values are (usually) set or cleared after each instruction has executed:

Z-bit	Set if the result of the operation is Zero
N-bit	Set if the result is Negative in a two's complement sense
C-bit	Set if the result yields a Carry-out
V-bit	Set if an oVerflow in two's complement has occurred

- Status flags are used to implement conditional behaviour.

► Variables in 68K

- Variables with given initial values are defined using the DC (Define Constant) command:

```
X    DC.B    12
```

- The suffix specifies **how many bytes** are being allocated.
- The „X“ at the start of the line defines a **label** for this variable. This label can be referred to, e.g. in `ADD X, D0`.
- Strings are defined as sequence of bytes. They are put in single quotes and **must terminate with a byte value 0**:

```
HelloMsg DC.B 'Hello World!', 0
```

- Good practice: keep all variable definitions separate from the code, e.g. at the end of the program.

► Demo in EASy68K: intro.X68

- Most popular 68000 Assembler and 68000 Simulator
- Available from <http://www.easy68k.com/>
- Demo programs will appear on module website.
- Demo shows
 - how the editor works
 - how programs can be assembled and executed step-by-step
 - how registers and flags change
 - where and how program and variables are stored in memory
 - labels like „X“ are replaced by their memory locations
 - to illustrate potential pitfalls with different word sizes

► Data movement instructions

- Data movement instructions are the most common types of instructions.

MOVE X, Y $[Y] \leftarrow [X]$

copies X to Y. One operand must be a register (usually D0-D7).

- Address registers A0-A7 are used for **indirect addressing**.

The instruction

LEA Text, A1 $[A1] \leftarrow \text{Text}$

(Load Effective Address) loads the address of “Text” in A1.

► Logical operations

- `CLR.L D0` $[D0] \leftarrow 0$
clears a register, i.e. sets its contents to 0.
- All common logical operations are available, e.g.:
 - `AND D0, D1` $[D1] \leftarrow [D1] \text{ AND } [D0]$
 - `OR #$00FF, D2` set lower 8 bits in D2
 - `EOR.B #%00000001, D3` toggle LSB in D3
 - `NOT D0` invert all bits in D0(.W)
- \$ indicates a **hexadecimal** number, % a **binary** number.
- There are various **shift** operations (left/right) :
 - logical shift $10011001 \rightarrow 00100110$ (fill with zeros)
 - arithmetic shift $10011001 \rightarrow 11100110$ (replicate sign bit)
 - rotation $10011001 \rightarrow 01100110$ (wrap around)

► Arithmetic instructions

- Addition:

`ADD.L #2, A0` $[A0] \leftarrow [A0] + 2$

Multiplication of two unsigned/signed register values, resp.:

`MULU D2, D3` $[D3] \leftarrow [D2] \times_{\text{unsigned}} [D3]$

`MULS D2, D3` $[D3] \leftarrow [D2] \times_{\text{signed}} [D3]$

Note: operands are the **lower 16 bits**, the result is **32 bits**.

Decrementing a register:

`SUB #1, D5` $[D5] \leftarrow [D5] - 1$

- ❓ Why don't we have ADDU vs. ADDS and SUBU vs. SUBS?

► Division

Division of two unsigned/signed register values, resp.:

`DIVU D2, D3` $[D3] \leftarrow [D3] /_{\text{unsigned}} [D2]$

`DIVS D2, D3` $[D3] \leftarrow [D3] /_{\text{signed}} [D2]$

Target register contains **result in lower 16 bits** and **remainder in upper 16 bits**.

- Remainder can be cleared away using

`AND.L #$0000FFFF, D3`

- Access the remainder using a right shift or

`SWAP D3` **swaps upper and lower 16 bits**

Division fails if division by 0 or if result does not fit in 16 bits.

► Input/Output in Motorola 68K

- Input/Output is performed by
 - 1) putting an instruction code in D0
 - 2) and calling the instruction

`TRAP #15`

- For instance, if D0 contains #13 then a null-terminated string at [A1] is printed on the screen.
- See demo hello-world.X68.
- Find a table of instruction codes in EASy68K under
Help → Help → Simulator I/O

► Flow control instructions

- An **unconditional jump** continues the program at a given address:

JMP GoHere [PC] ← GoHere

...

GoHere: ADD D1, D0

- The assembler translates the label “GoHere” to the memory location where the instruction `ADD D1, D0` is stored in memory.

► Conditional branches

- Conditional branches execute jumps depending on status flags. Status flags are set after an arithmetic operation or a **comparison**. Example of a do-while loop:

```
Loop      . . .  
          ADD #1, D5          increment D5  
          CMP #10, D5         is D5==10?  
          BNE Loop            if so, go to Loop
```

- CMP sets the status flags according to the result of the subtraction [D5]-10.
- BNE tests the value of the Z-bit. If it is not set (i.e. [D5]-10 is not 0) then we jump to `Loop` and do another iteration.
- Other branch commands test other bits (N, Z, V, C):
BGE (“≥”), BGT (“>”), BE (“=”), BLT (“<”), BLE (“≤”), ...

► Subroutines

- Subroutines can be called from anywhere in the program (like methods in Java).
- BSR and JSR (branch/jump to subroutine) store the address of the next instruction on the stack before branching.
- RTS (return from subroutine) pops the return address from the stack and returns there.

```
        BSR    Sub           [top of stack] ← Next, [PC] ← Sub
Next:   ADD    D0, D1

        . . .
Sub:    MOVE   #4, D0
        TRAP   #15
        RTS                    [PC] ← [top of stack]
```

- Subroutines can save registers on the stack (not discussed here).

► Things to remember

- For the assessment you should be able to **understand** and **write** simple Motorola 68K assembly language programs.
- Remember common Motorola 68K instructions.
- Remember to always add a „#“ to immediate values:

`ADD #4 , D0`

- Remember that the first operand is the source, the second one is the destination.
- Be careful when dealing with different word lengths – make sure to clear registers before using them.

► Summary

- Learned common Motorola 68K instructions.
- Seen the EASy68K assembler and simulator in action.
- Motorola 68K uses different word lengths for registers.
- Program and variables are stored alongside in memory.
- Input/Output routines can be called using `TRAP #15`.
- Branching instructions implement if-statements, loops, etc.
- Subroutines can be called from anywhere in the program; the return address for the program counter is stored on the stack.