

# Lorentz-GATr

Lorentz-Equivariant  
Geometric Algebra Transformers  
for High-Energy Physics

Jonas Spinner\*, Victor Breso\*,  
Pim de Haan, Tilman Plehn,  
Jesse Thaler, Johann Brehmer

Young Scientists Meeting  
of the CRC TRR 257



UNIVERSITÄT  
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ZUKUNFT  
SEIT 1386

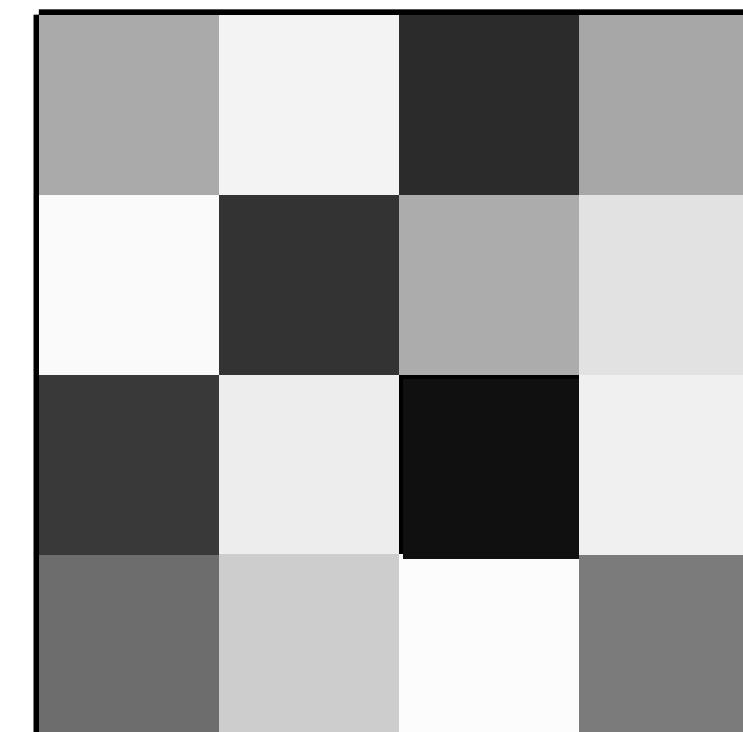
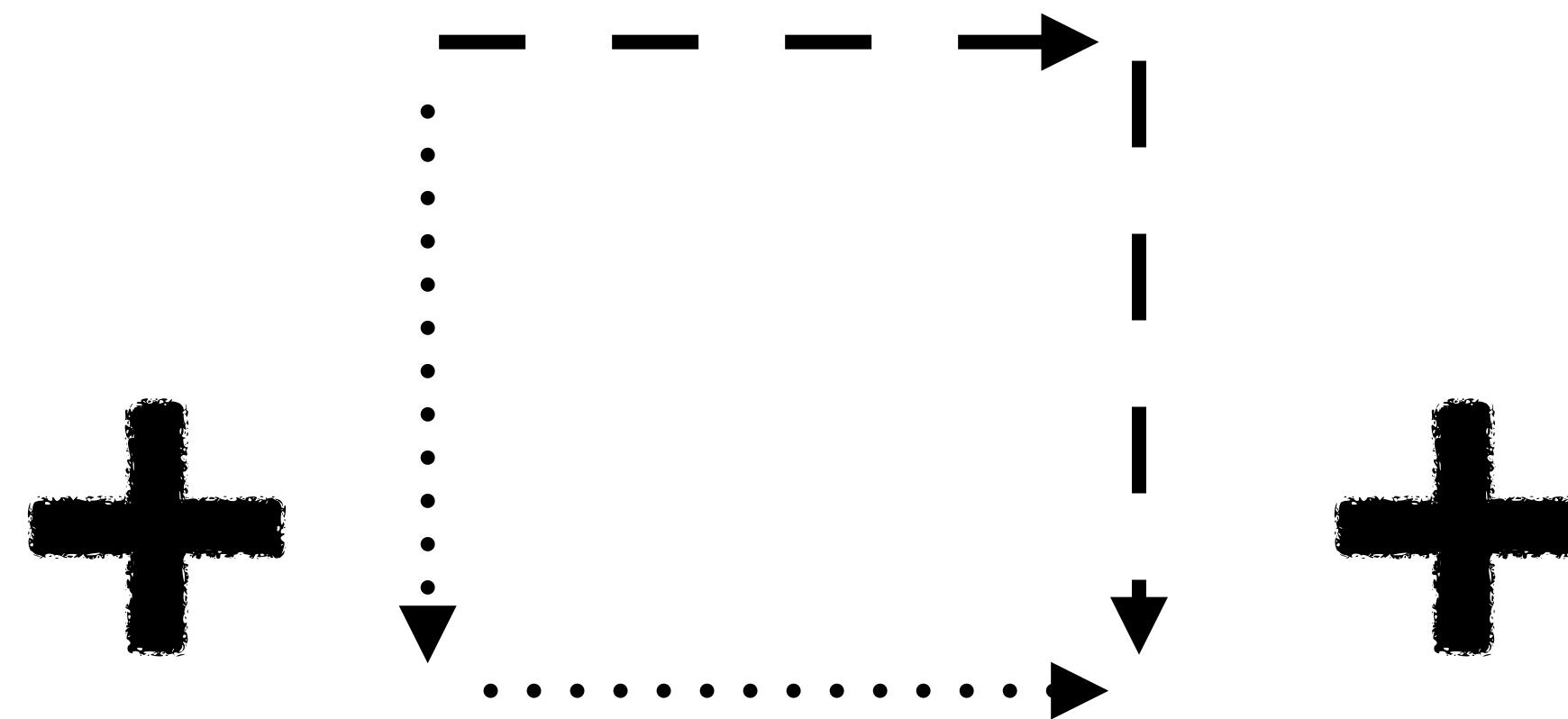
Lorentz symmetry is key in  
high-energy physics...

$$\begin{aligned}\mathcal{L} = & -\frac{1}{4} F_{\mu\nu} F^{\mu\nu} \\ & + i \bar{\psi} D^\mu \psi + h.c \\ & + \bar{\chi}_i \gamma_{ij} \chi_j \phi + h.c \\ & + |\nabla_\mu \phi|^2 - V(\phi)\end{aligned}$$

... so let's build it into  
our neural networks

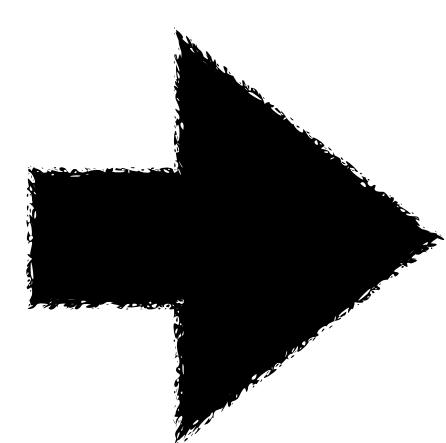
$$\begin{pmatrix} 1 \\ \gamma^\mu \\ \sigma^{\mu\nu} \\ \gamma^\mu \gamma_5 \\ \gamma_5 \end{pmatrix}$$

**Geometric algebra**  
representations

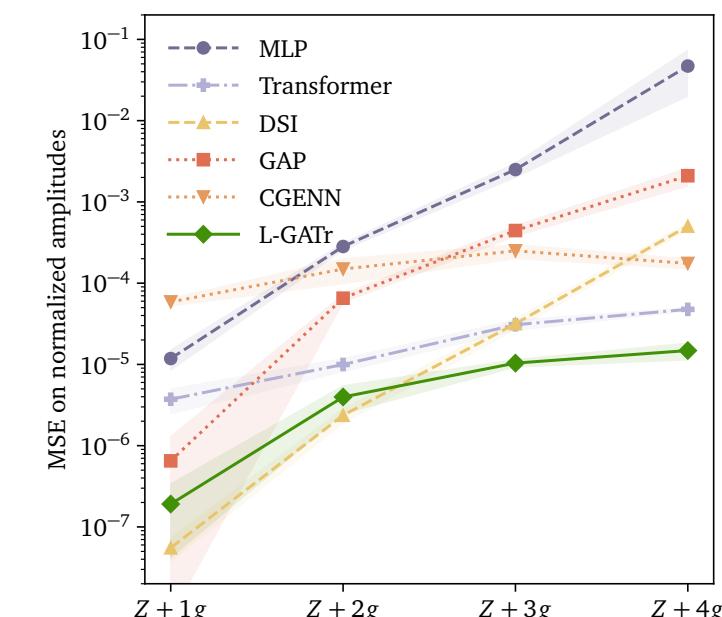


**Equivariant**  
layers

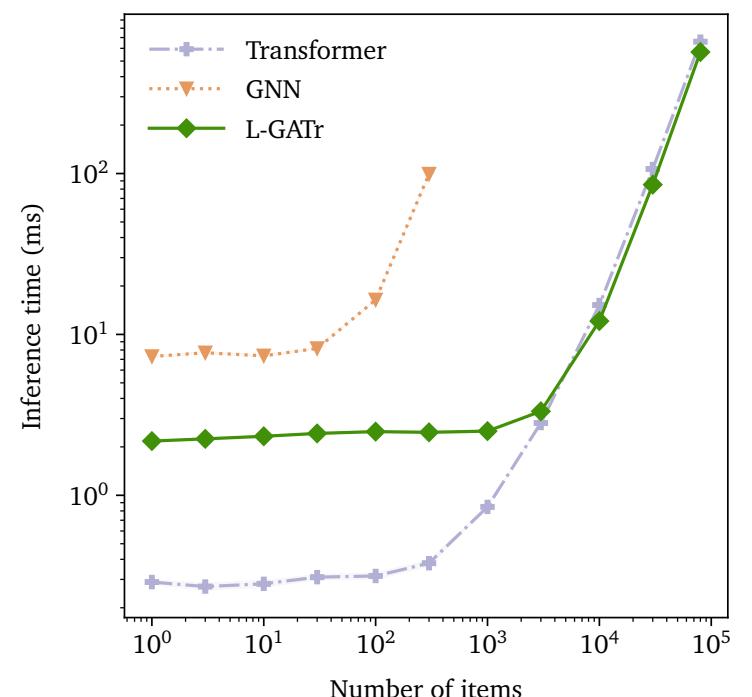
**Transformer**  
architecture



GATr was originally  
developed for E(3)  
arXiv:2305.18415



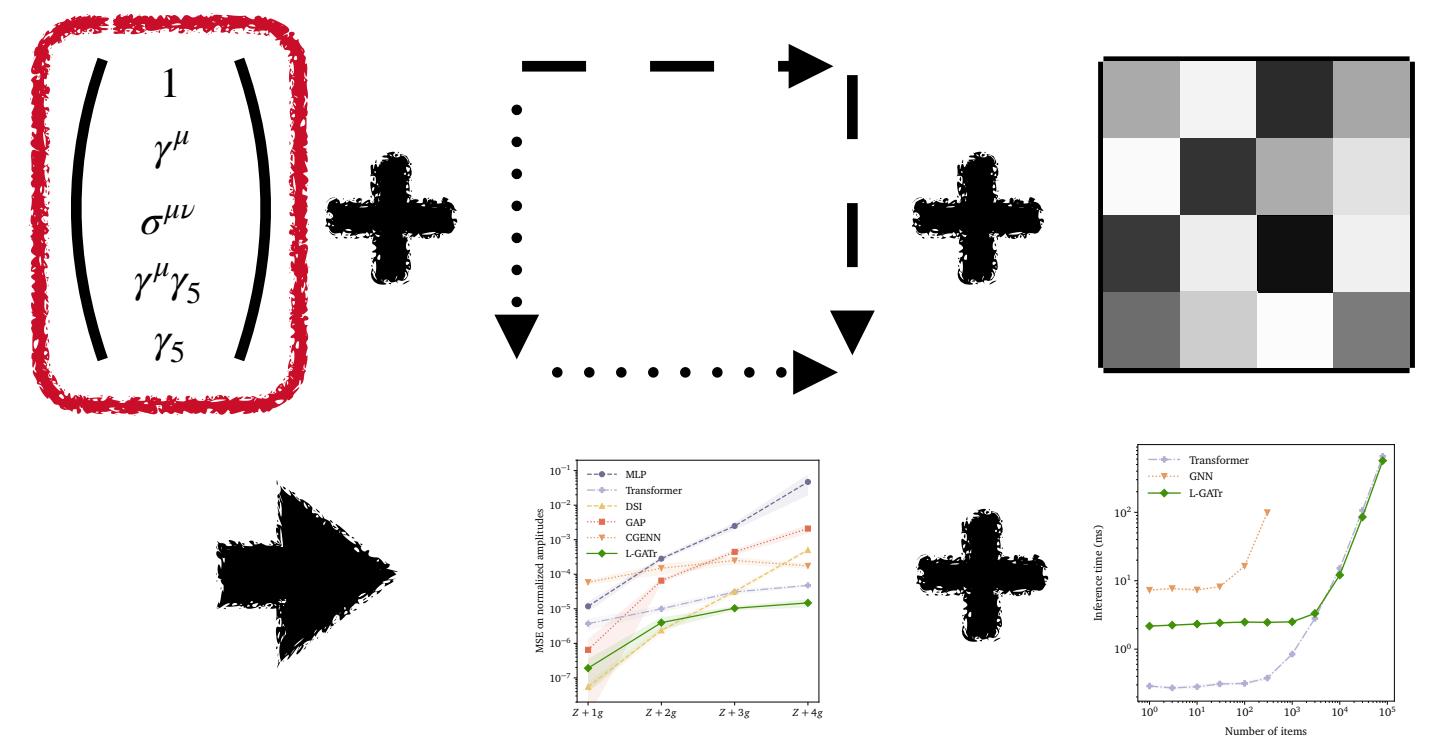
**Strong performance**  
on diverse problems



**Scalable**  
to thousands of tokens

# Ingredients

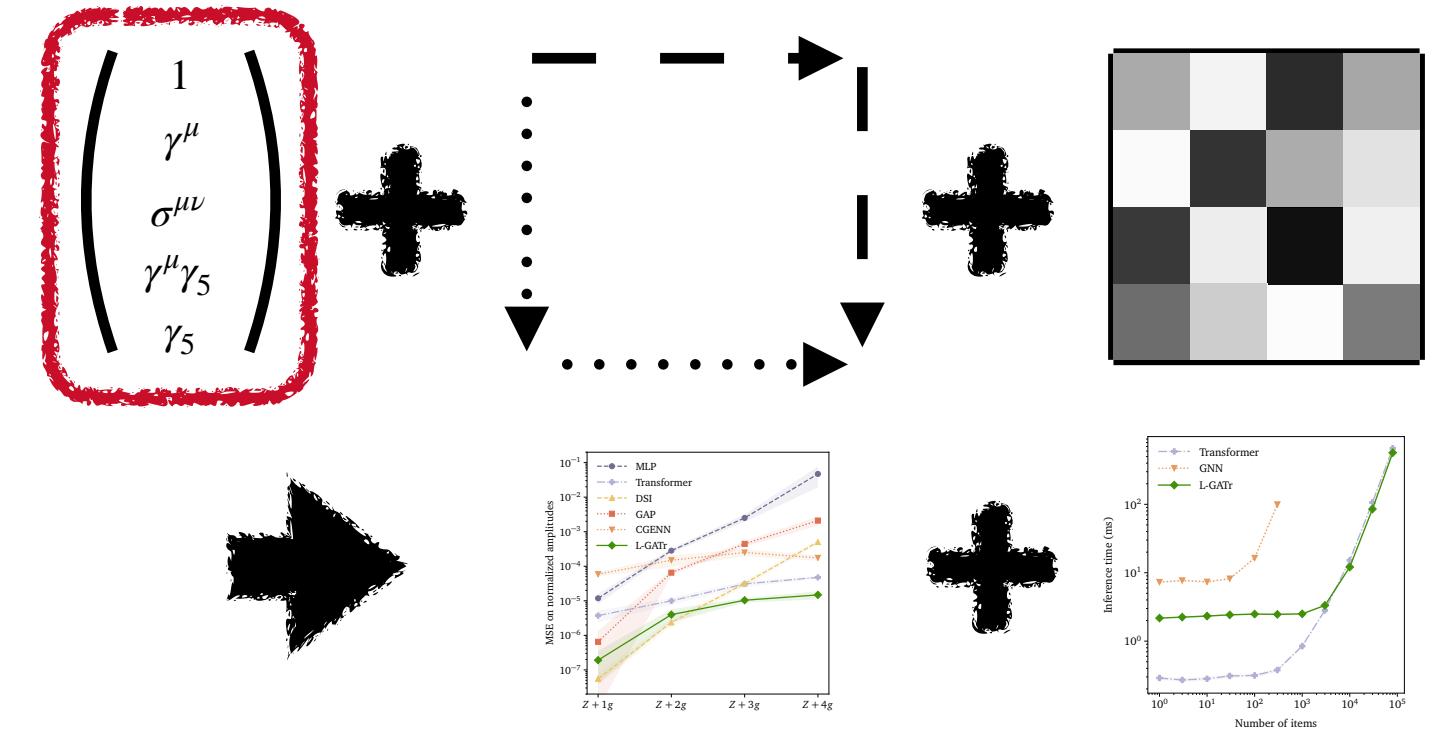
## Geometric algebra representations



- Basis elements  $\gamma^\mu$  of the geometric algebra defined by  $\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu}$
- Operations:  $\alpha x, \quad x + y, \quad x \cdot y$
- General multivector:  $x = x^S 1 + x_\mu^V \gamma^\mu + x_{\mu\nu}^T \sigma^{\mu\nu} + x_\mu^A \gamma^\mu \gamma_5 + x^P \gamma_5$

# Ingredients

## Geometric algebra representations

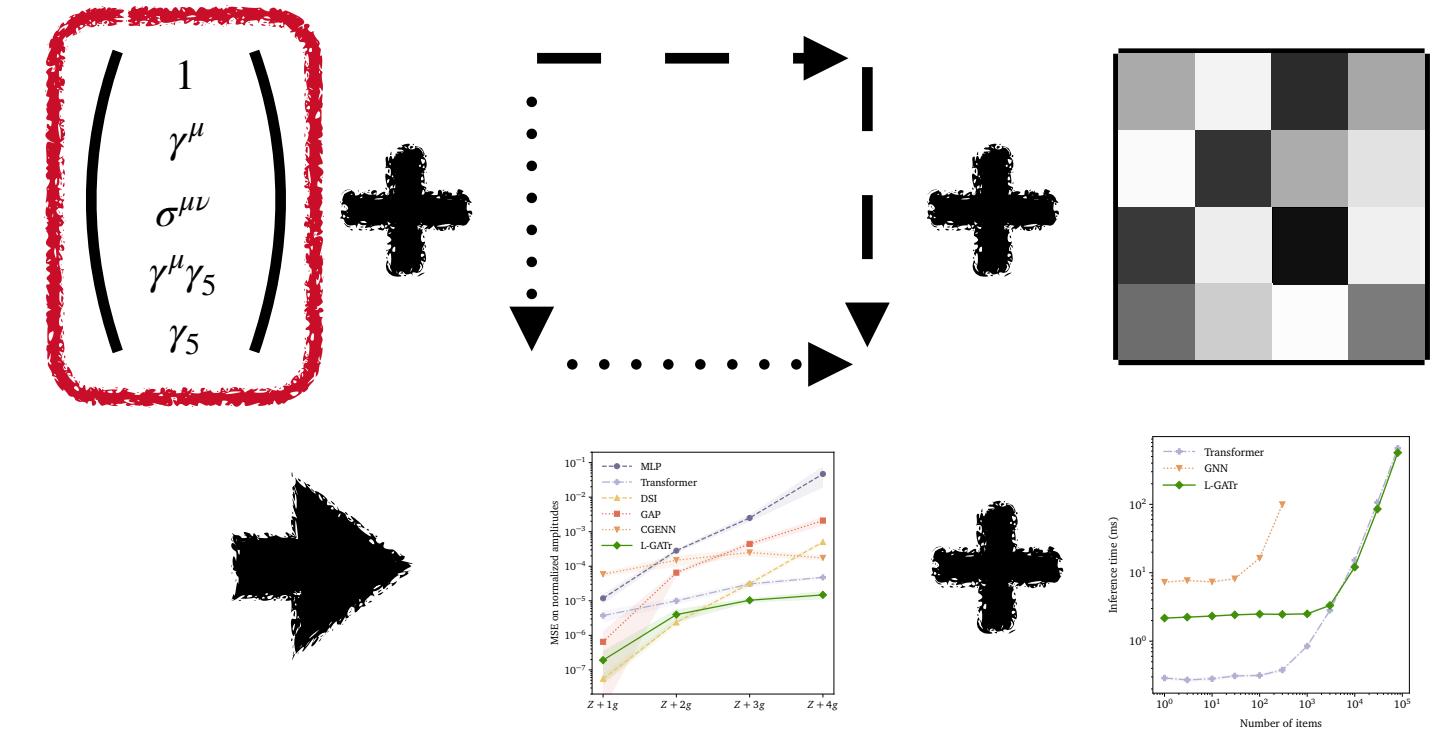


- Basis elements  $\gamma^\mu$  of the geometric algebra defined by  $\{\gamma^\mu, \gamma^\nu\} = 2g^{\mu\nu}$ 
  - Operations:  $\alpha x$ ,  $x + y$ ,  $x \cdot y$
  - General multivector:  $x = x^S 1 + x_\mu^V \gamma^\mu + x_{\mu\nu}^T \sigma^{\mu\nu} + x_\mu^A \gamma^\mu \gamma_5 + x^P \gamma_5$
- We embed multivectors as  $(x^S, x_0^V \dots x_3^V, x_{01}^T \dots x_{23}^T, x_0^A \dots x_3^A, x^P) \in \mathbb{R}^{16}$ 
  - Usually:  $x^S = \text{PID}$ ,  $x_\mu^V = p_\mu$ ,  $x^{T,A,P} = 0$
- L-GATr has  $n$  multivector and  $m$  scalar representations for each particle

Geometric algebra = Clifford algebra

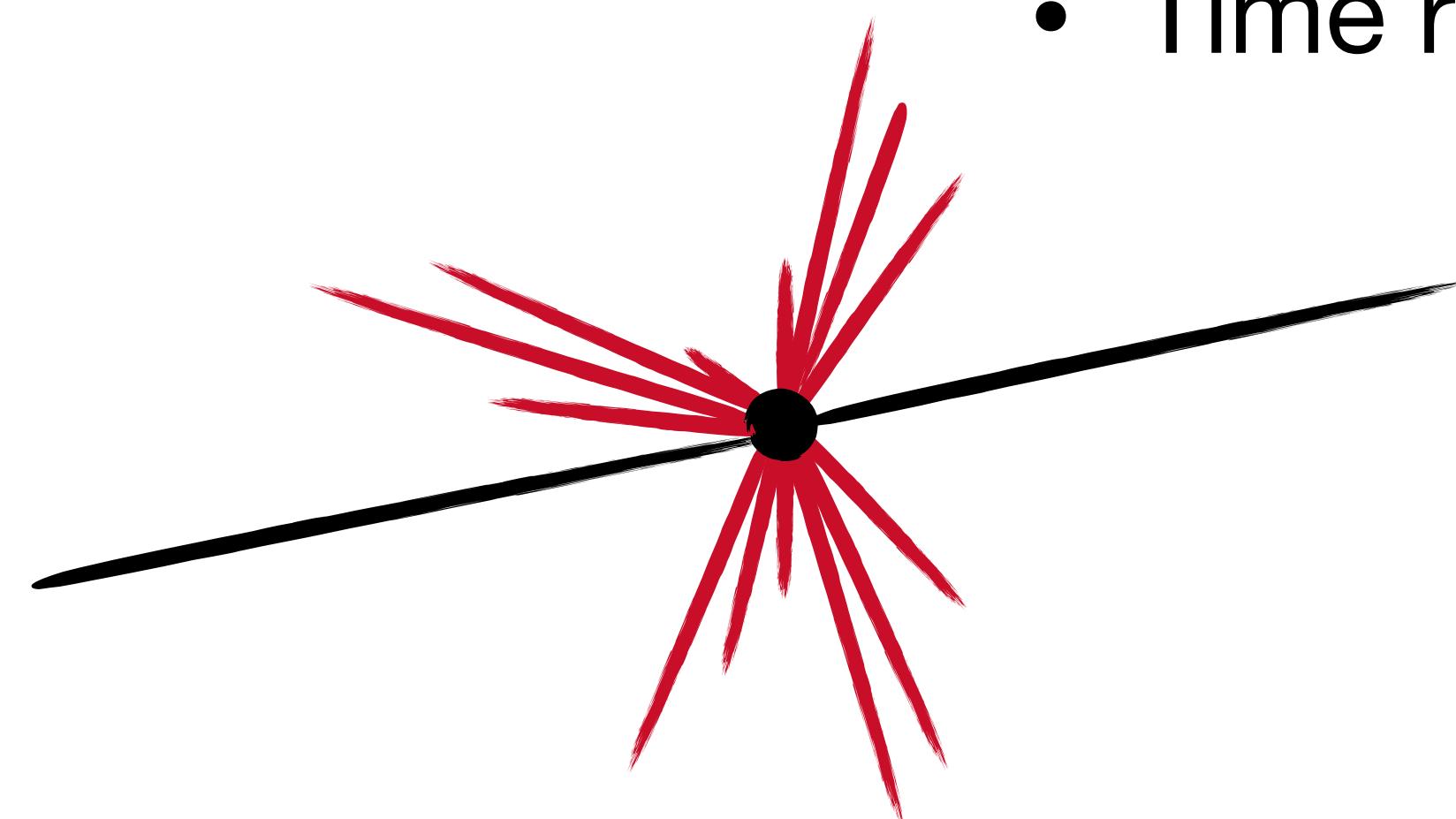
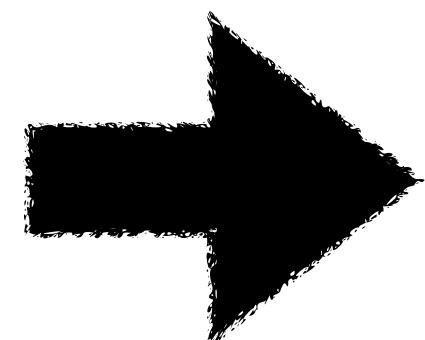
# Ingredients

## Symmetry breaking with spurious



Lorentz symmetry is rarely exact

- Beam direction in collider
- Detector effects
- ...?



Add a **spurion** to the particle list  
(either as token or channel)

- Beam reference:  $p^\mu = (0,0,0, \pm 1)$
- Time reference:  $p^\mu = (1,0,0,0)$

# Ingredients

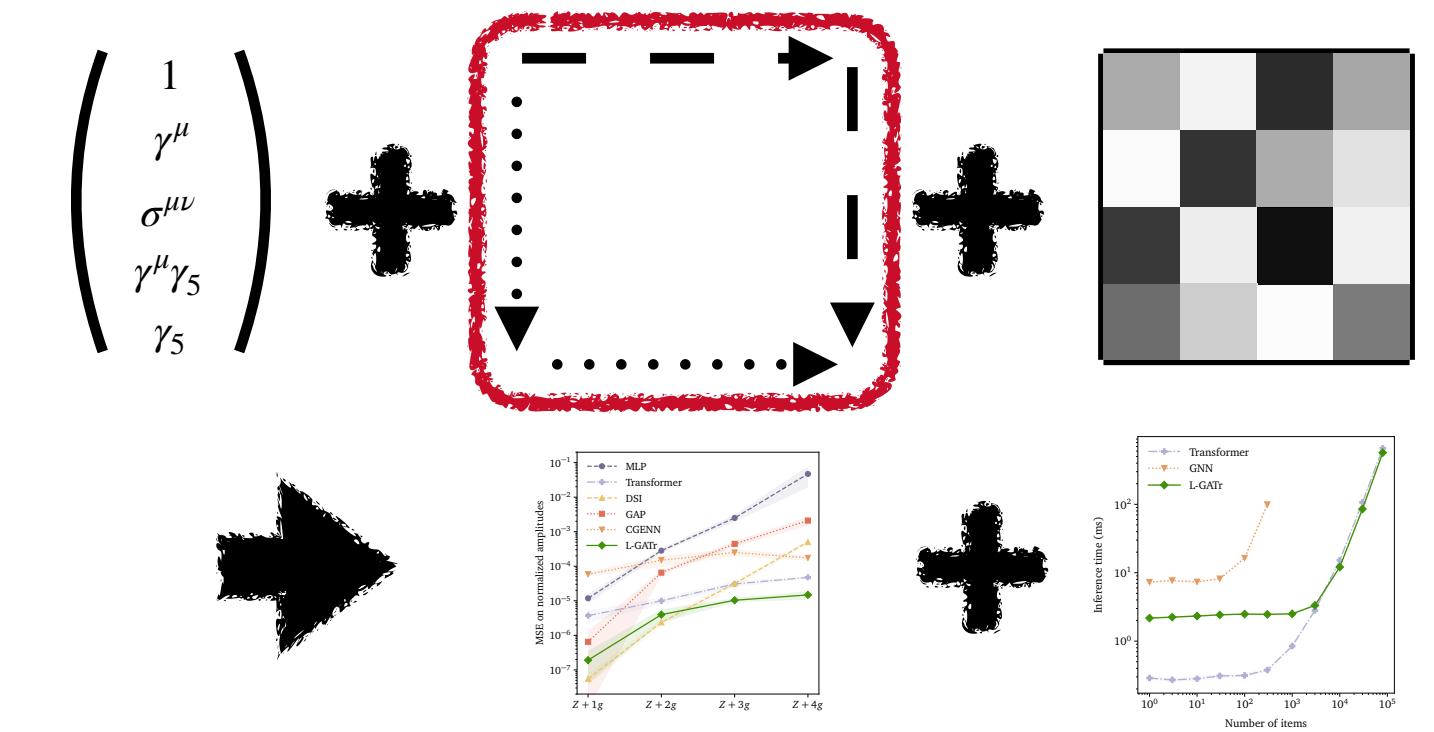
## Equivariance

neural network  
transformation  $\mathcal{N}$

symmetry group  
transformation  $\mathcal{G}$

$$\mathcal{G}(\mathcal{N}(x)) = \mathcal{N}(\mathcal{G}(x))$$

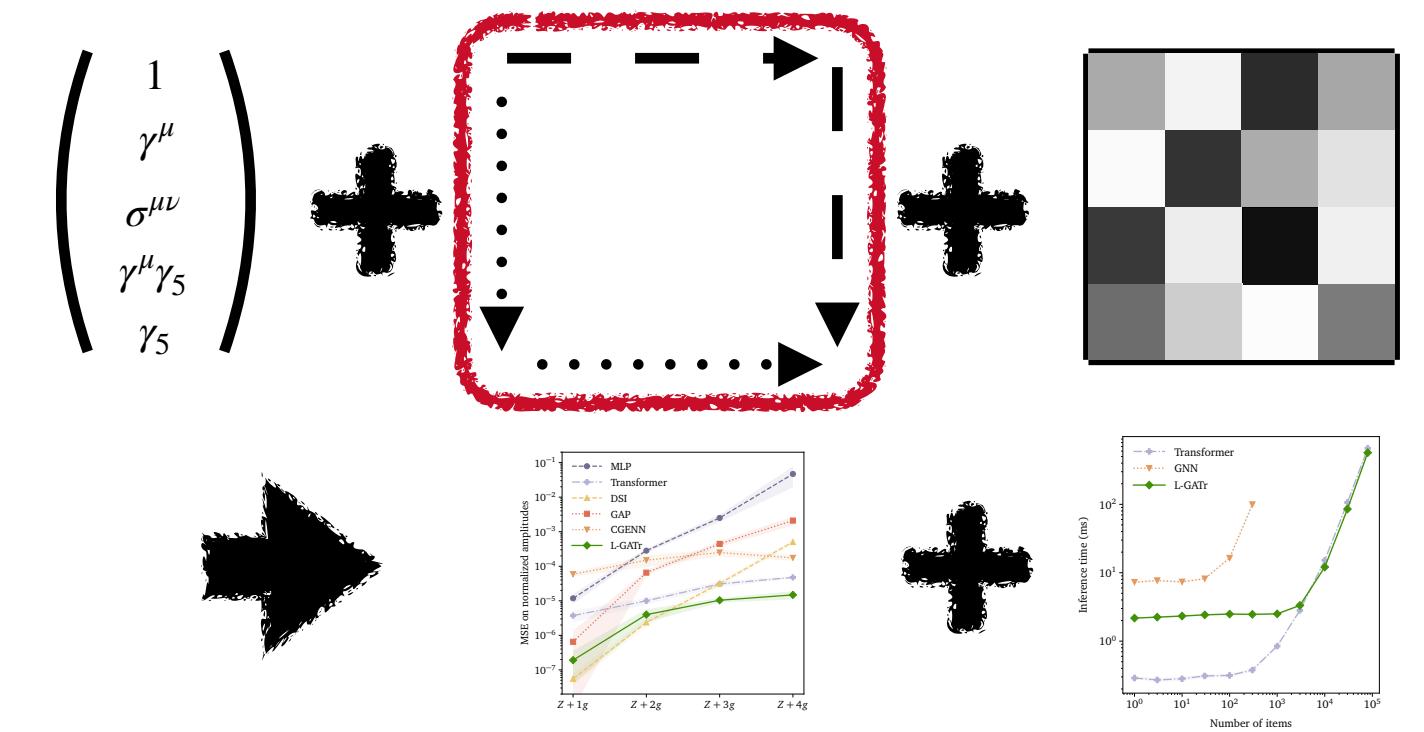
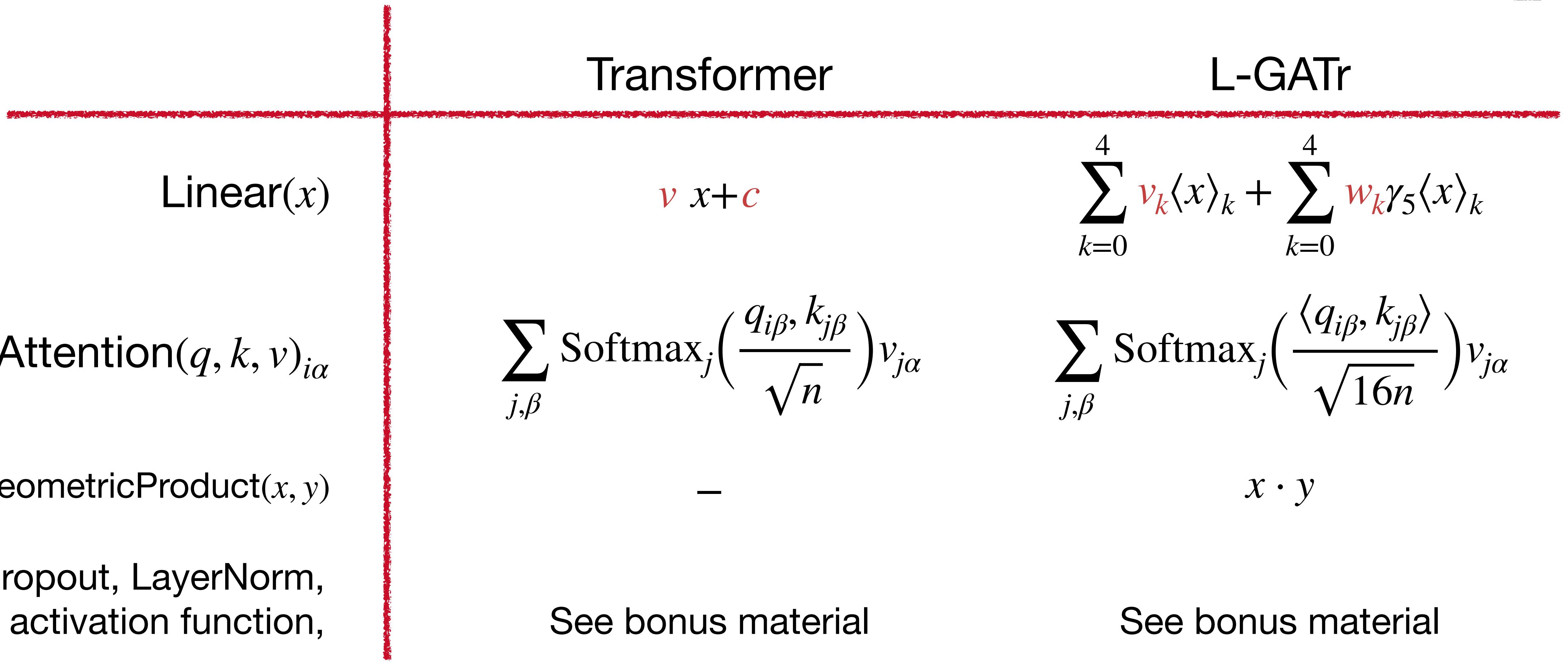
$\mathcal{G}$



Equivariance = Covariance

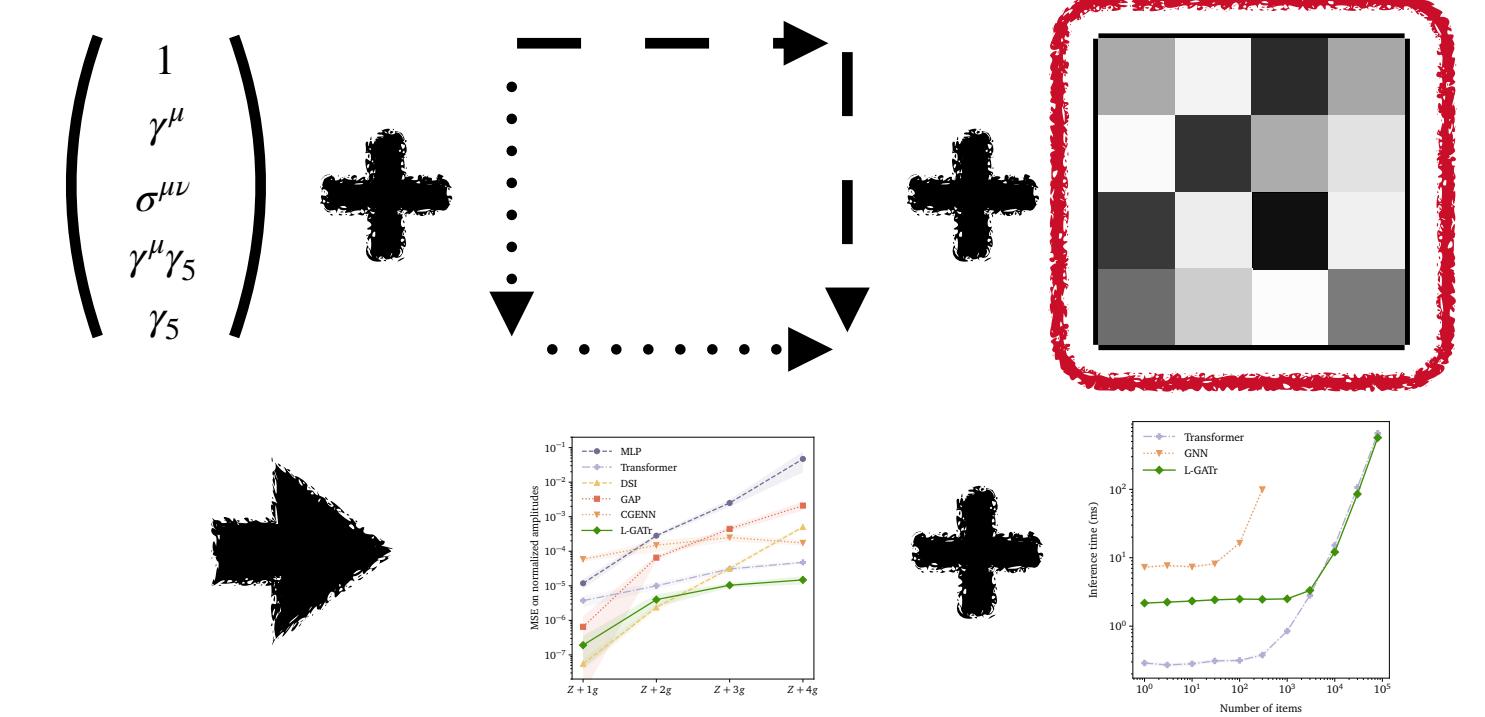
# Ingredients

## Equivariant layers



# Ingredients

## Transformer architecture

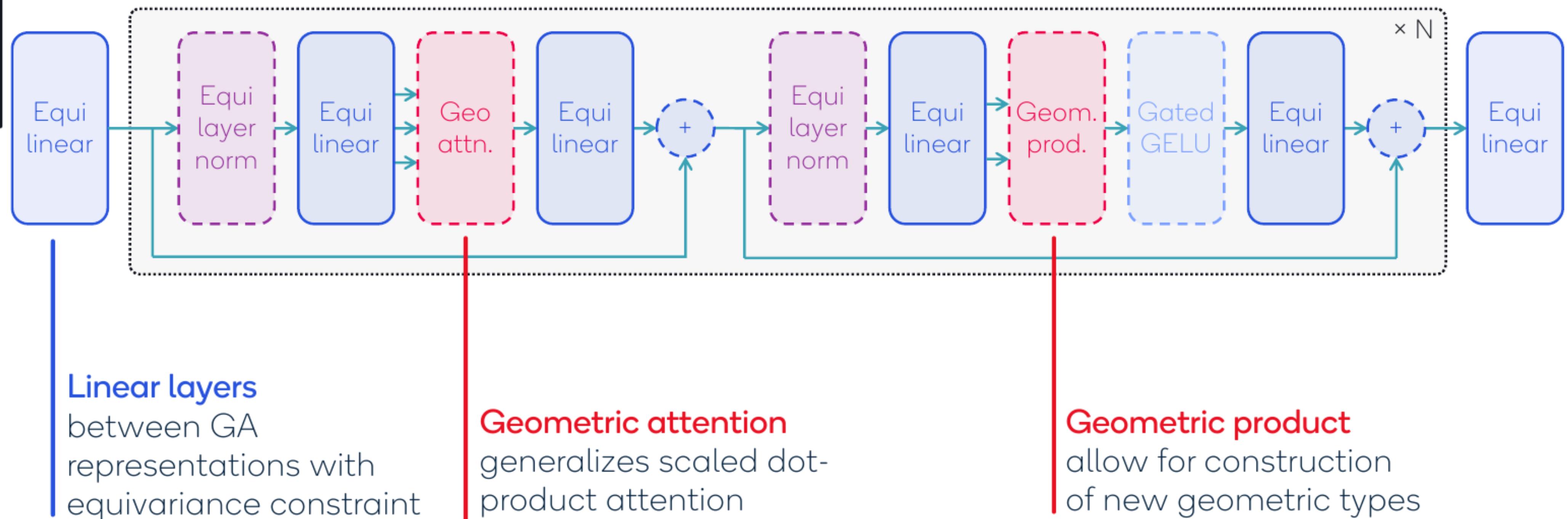


### Input and output data

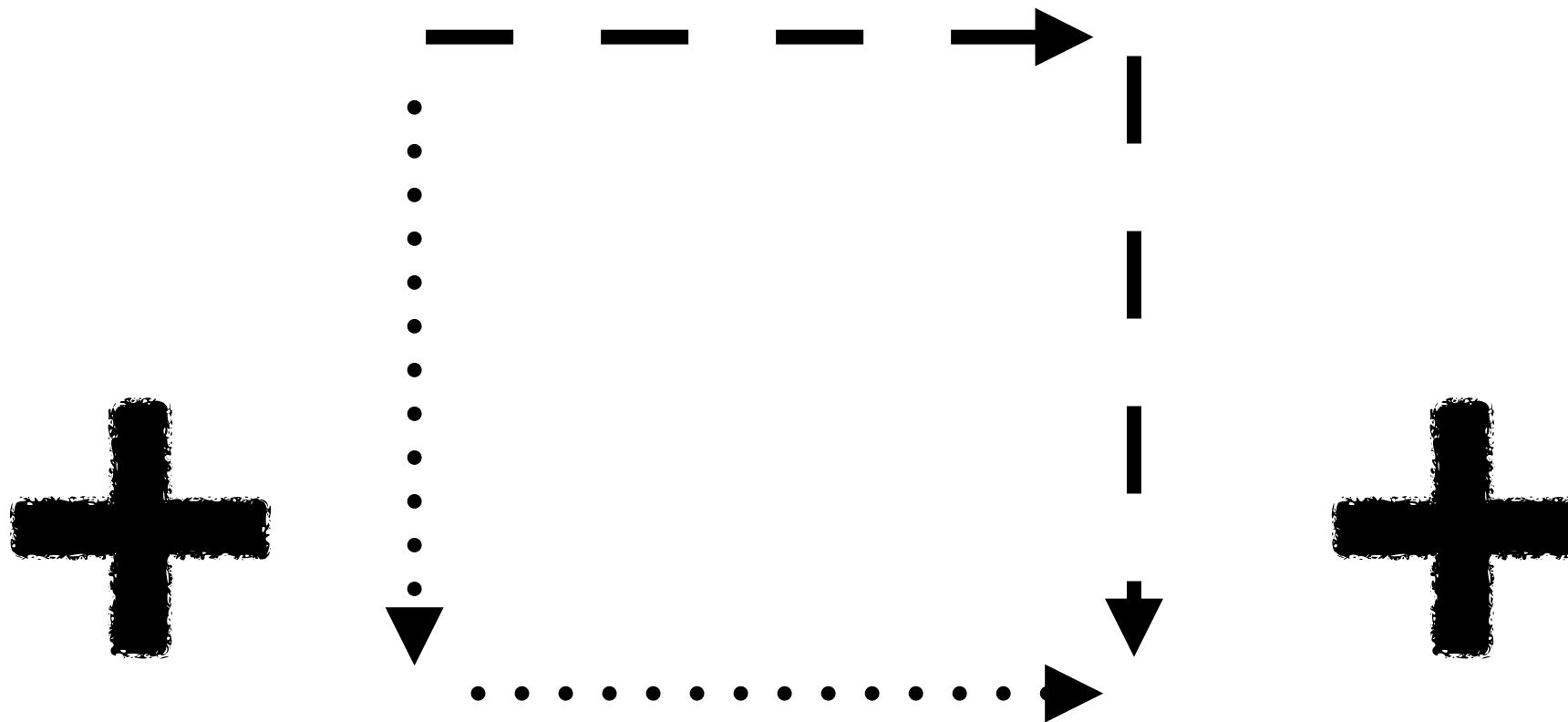
can have one or multiple token dimensions

### Attention blocks

can be stacked to large depth, gradients are propagated efficiently



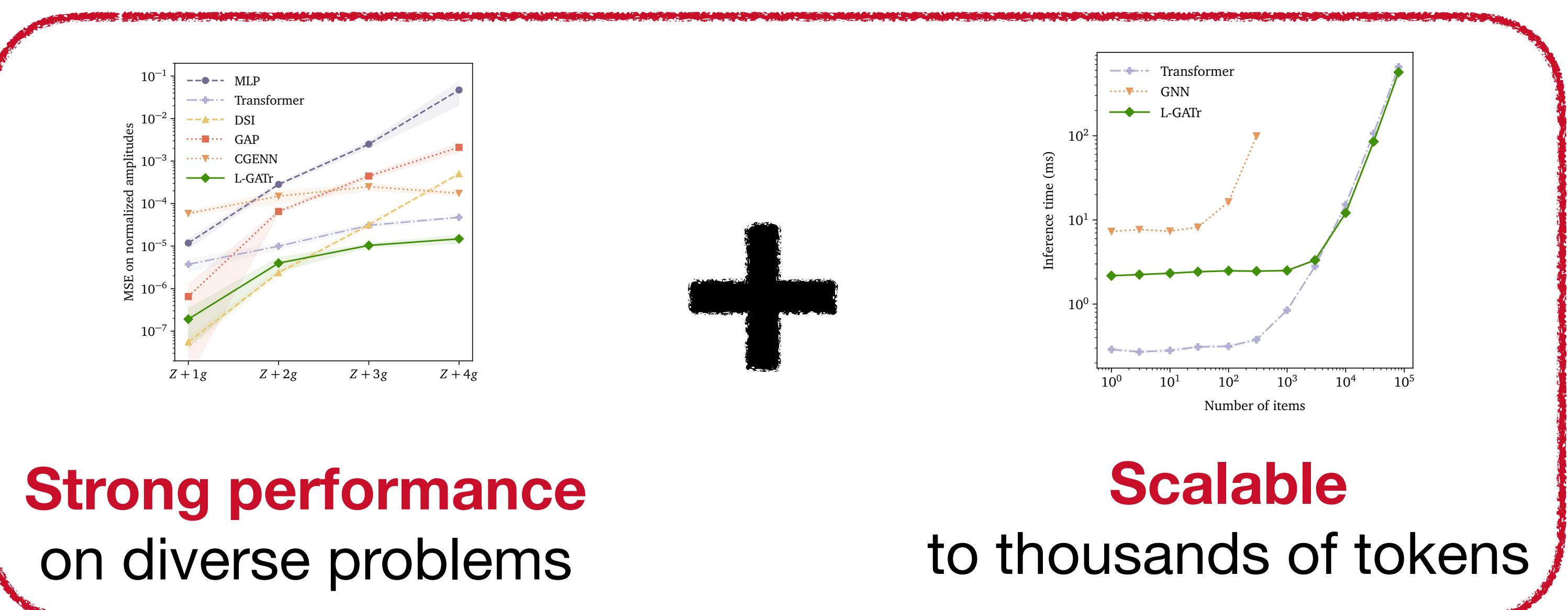
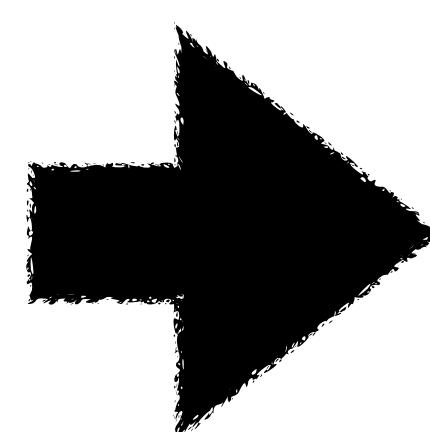
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**Geometric algebra**  
representations

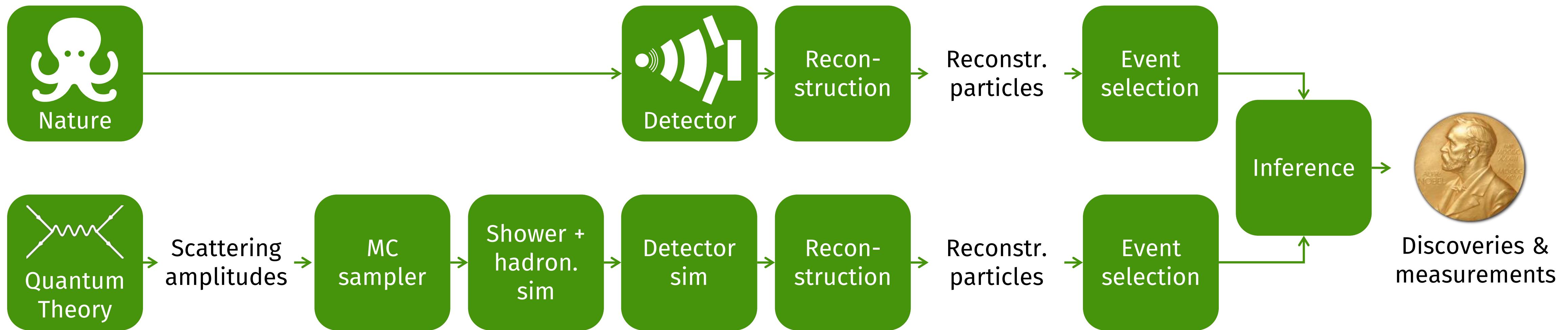
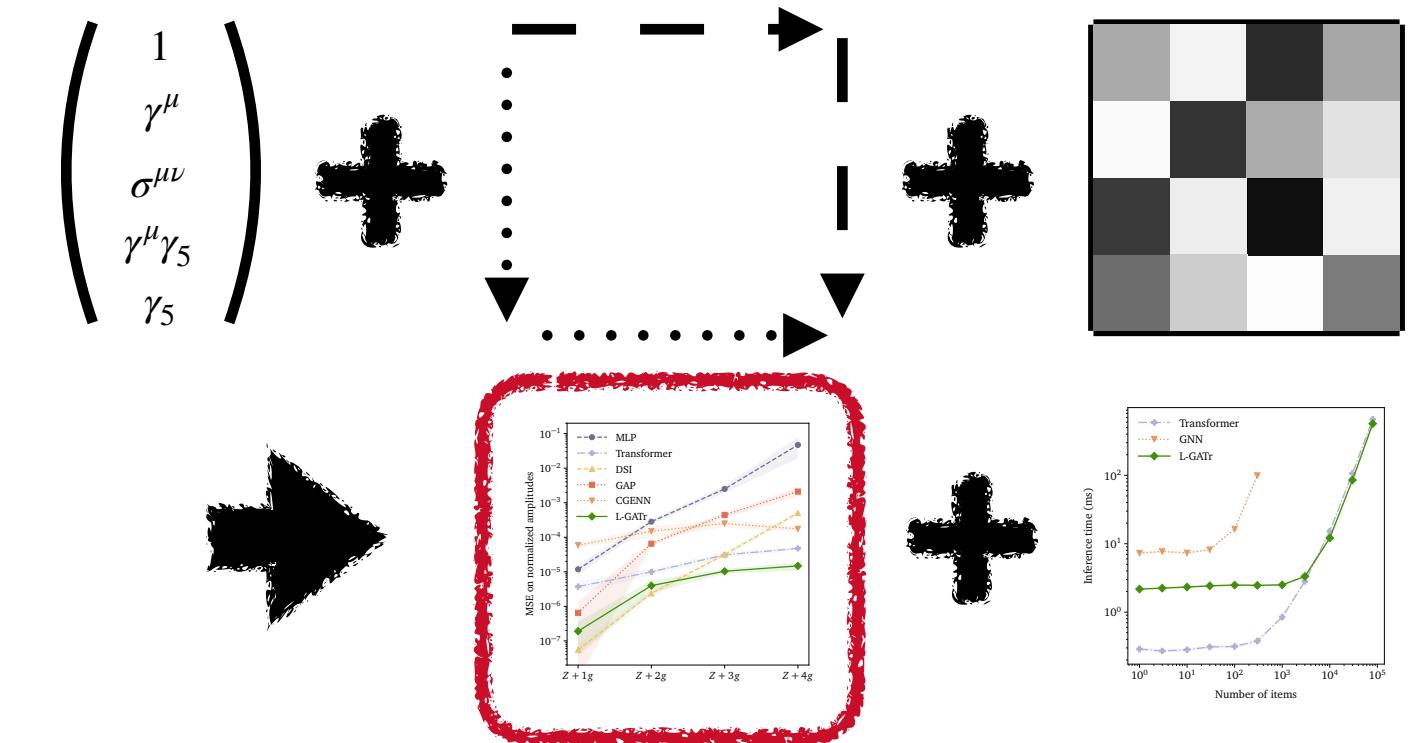
**Equivariant**  
layers

**Transformer**  
architecture



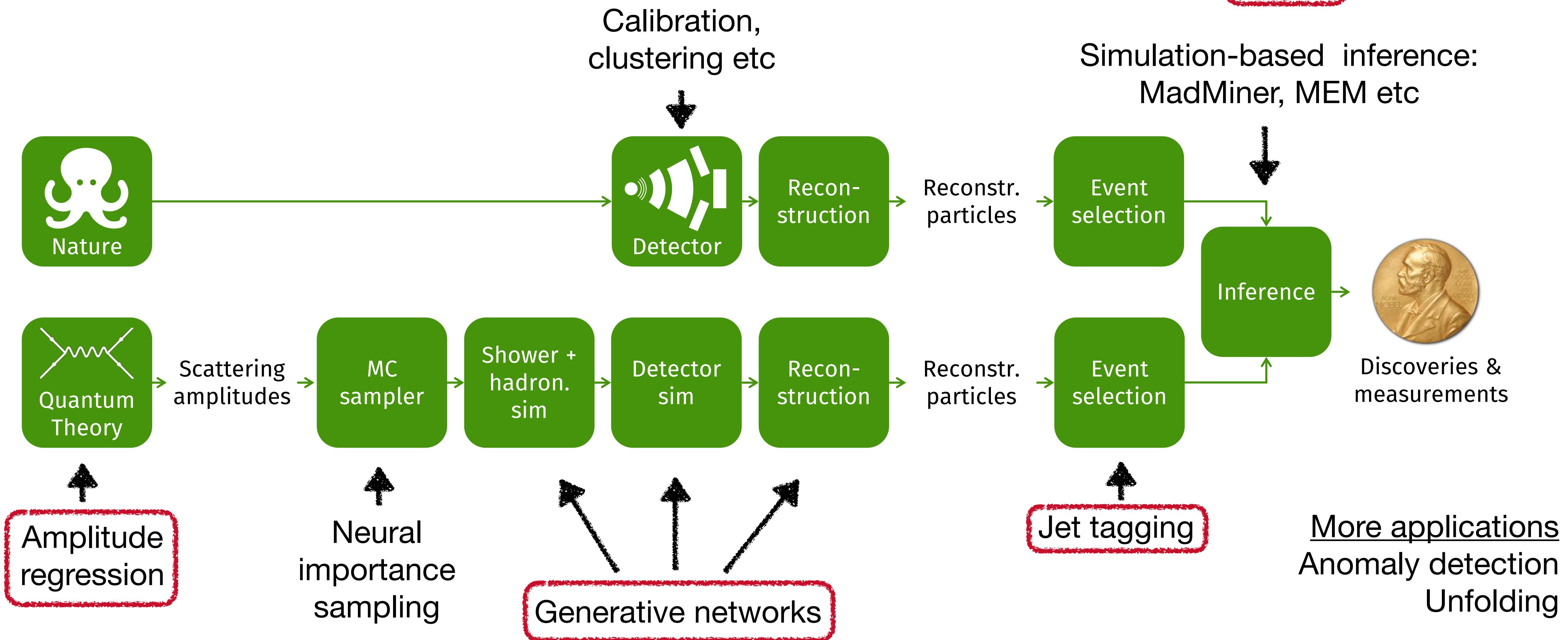
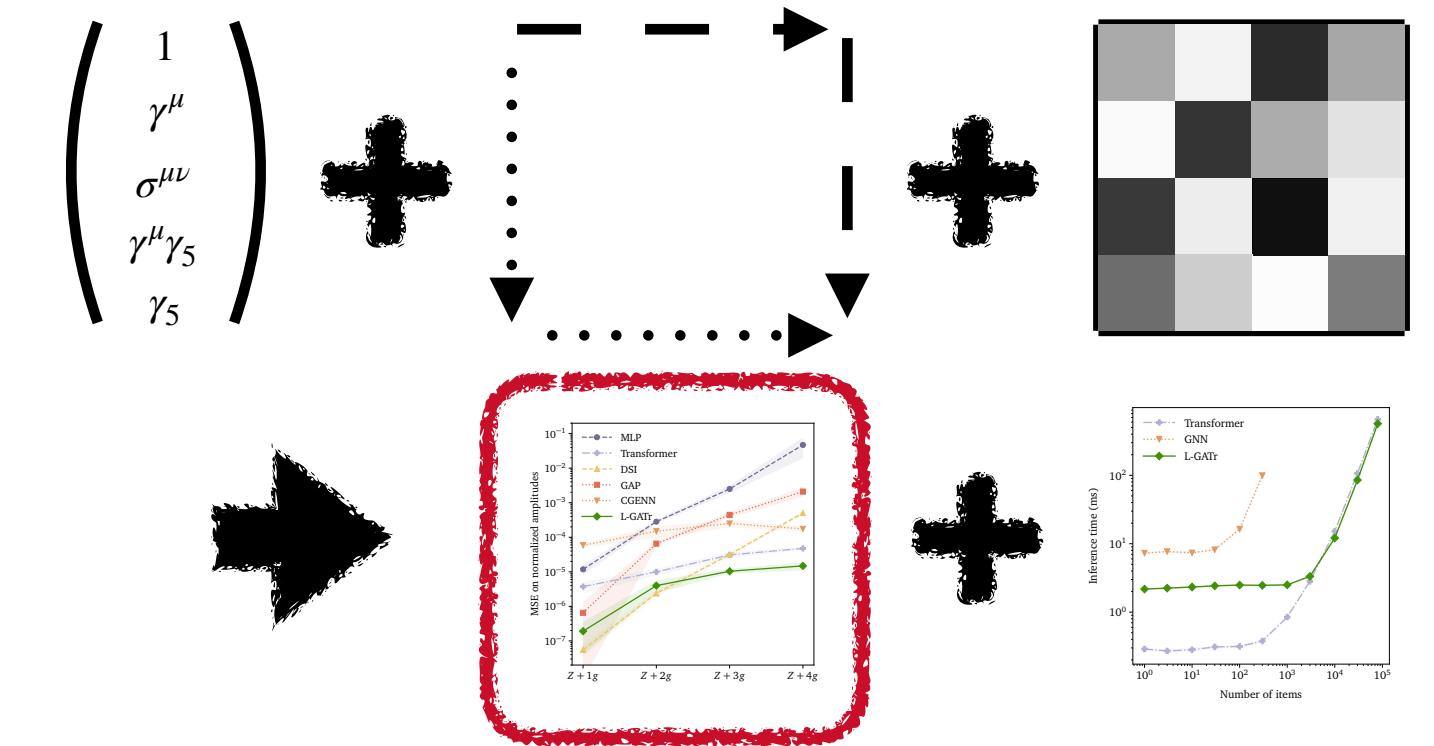
# Experiments

## LHC simulation chain



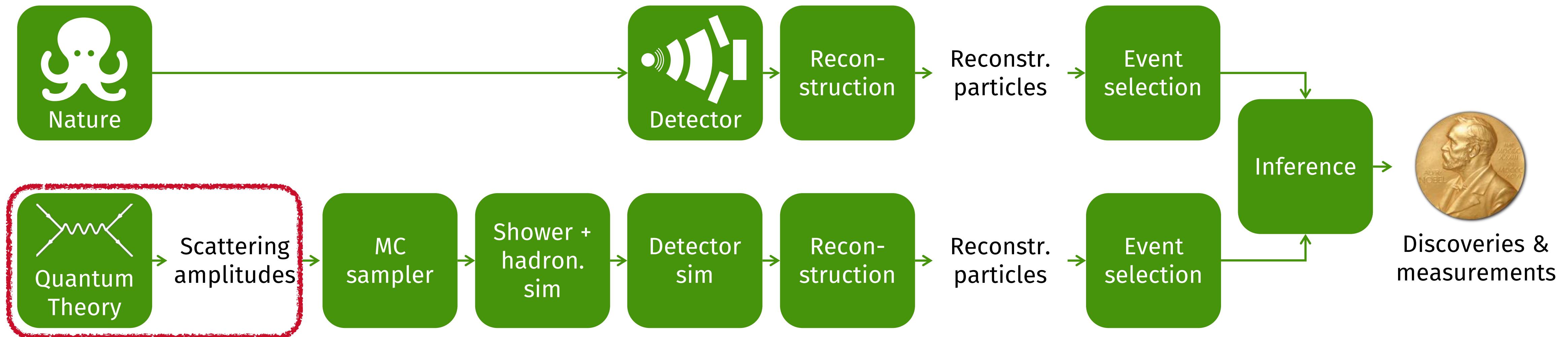
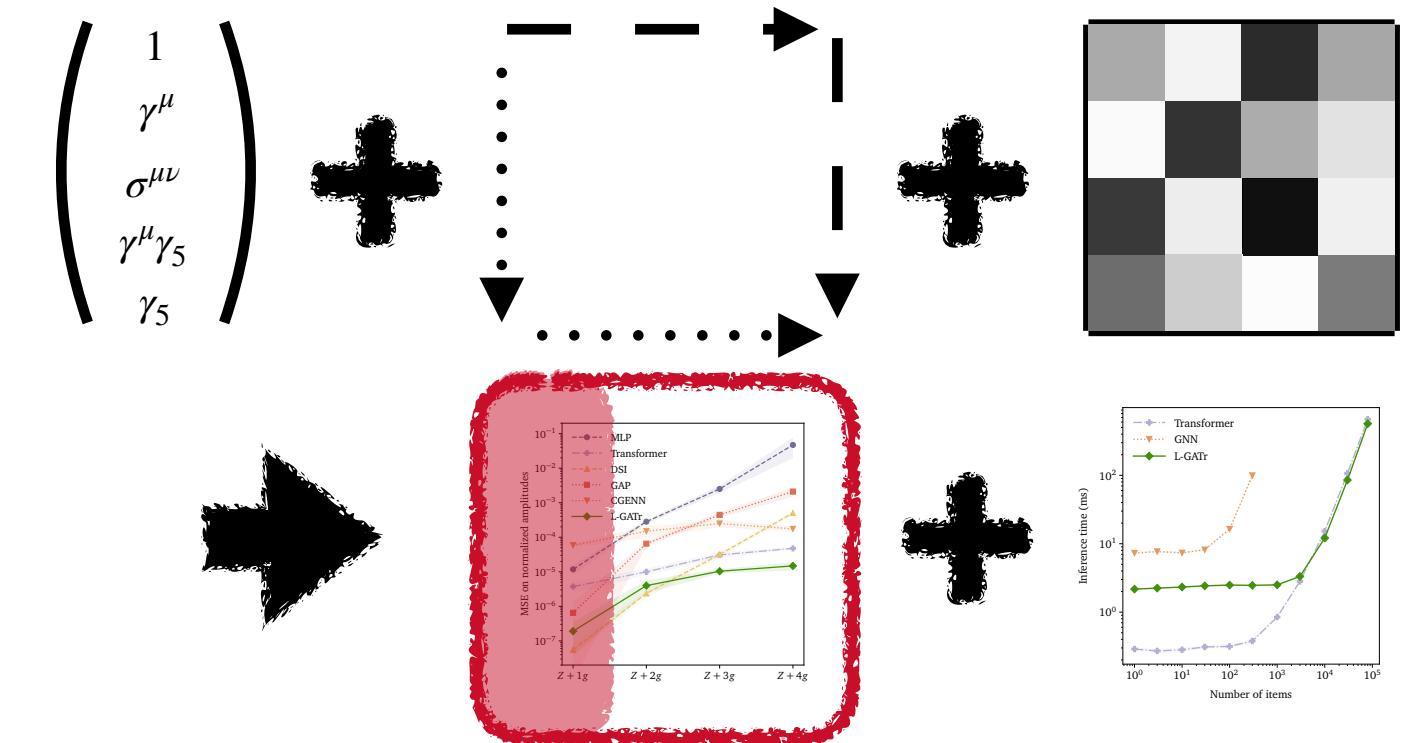
# Experiments

## LHC simulation chain meets ML



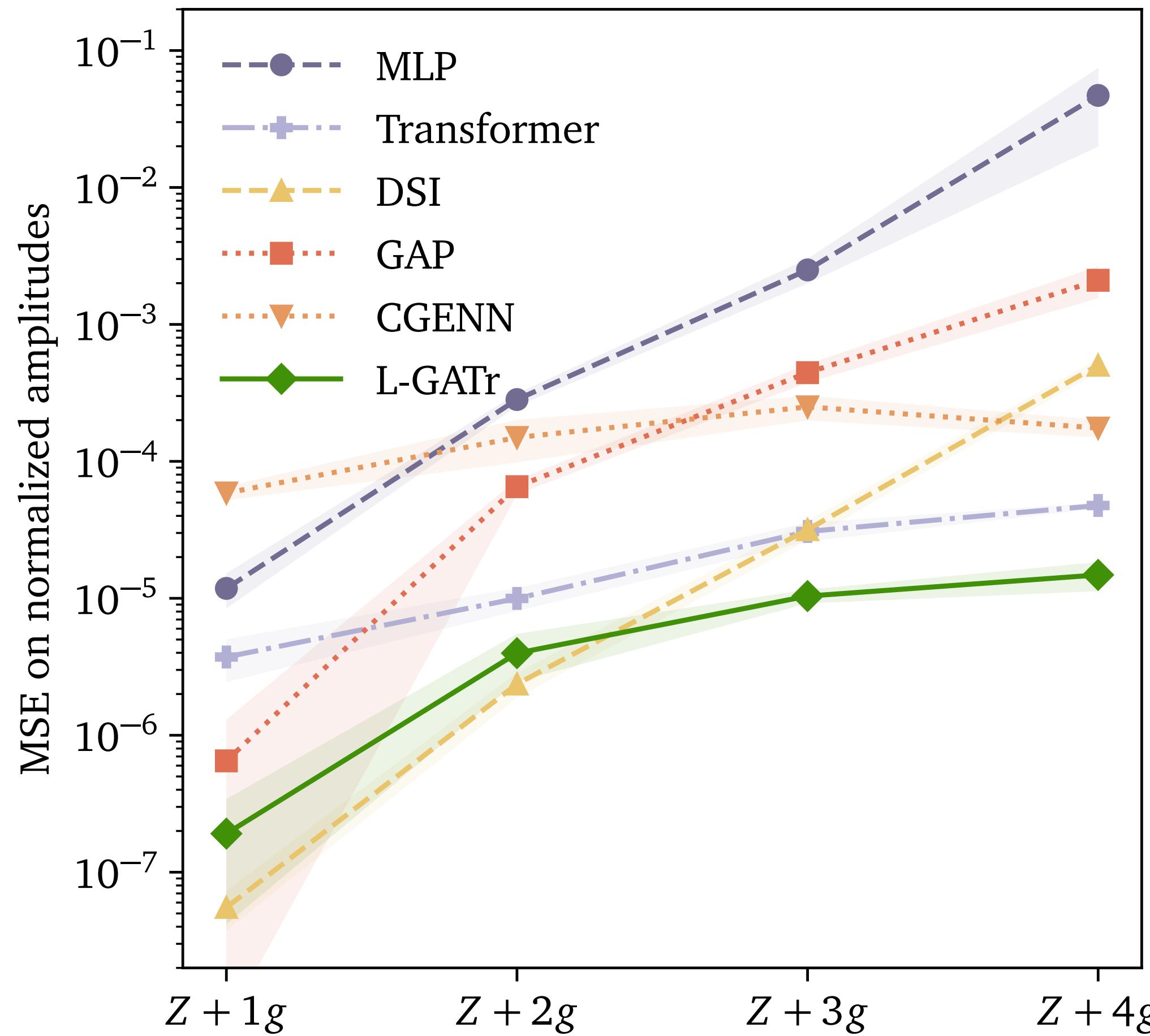
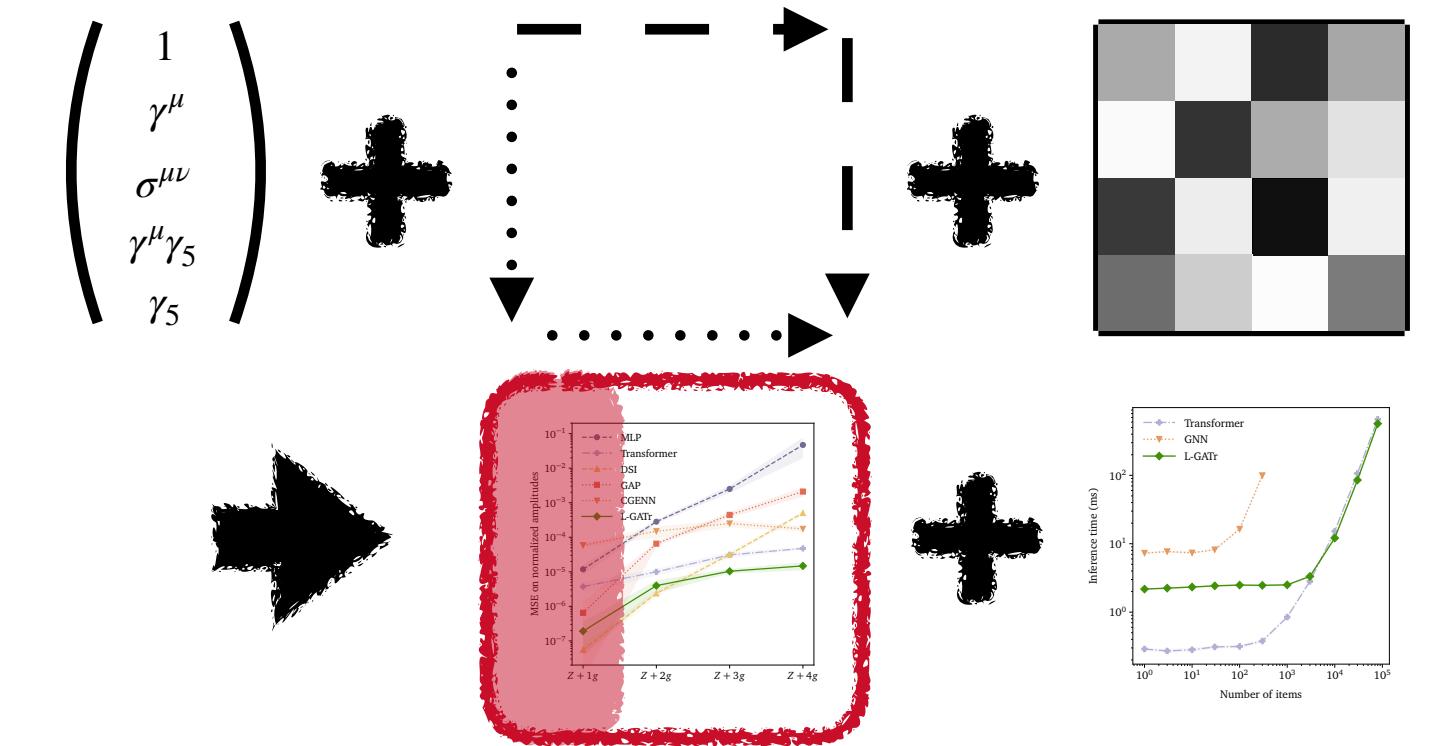
# Experiments

## Amplitude regression



# Experiments

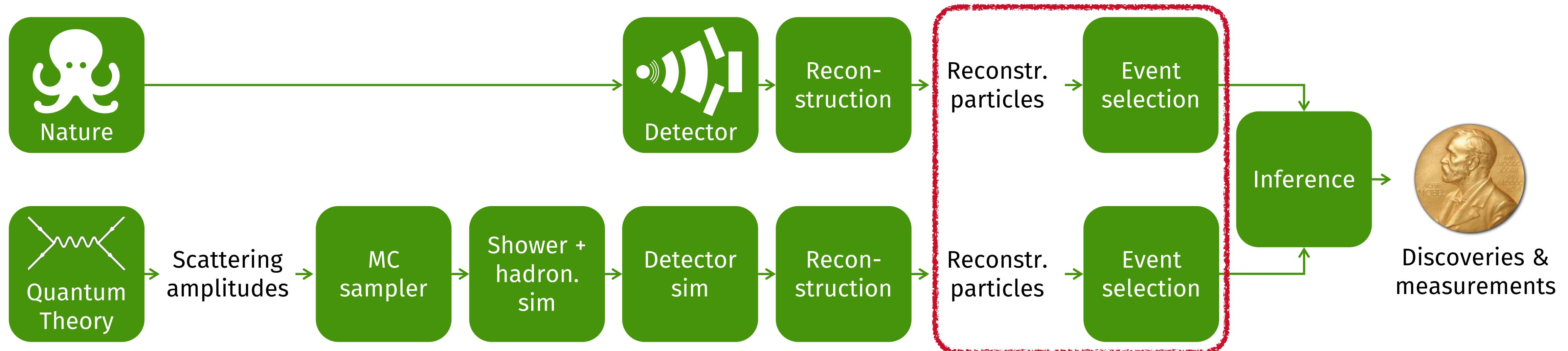
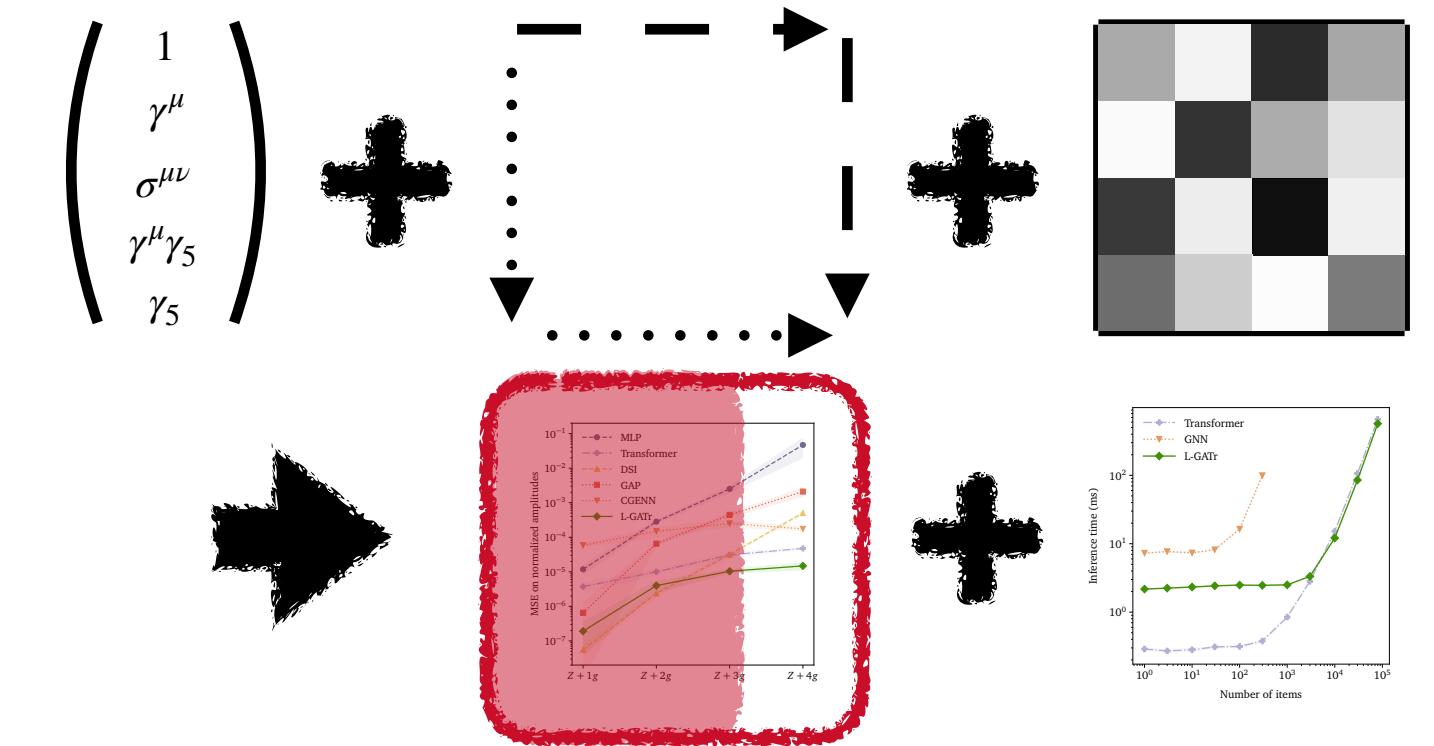
## Amplitude regression



L-GATr scales best to **high multiplicity**, where amplitude surrogates are most useful

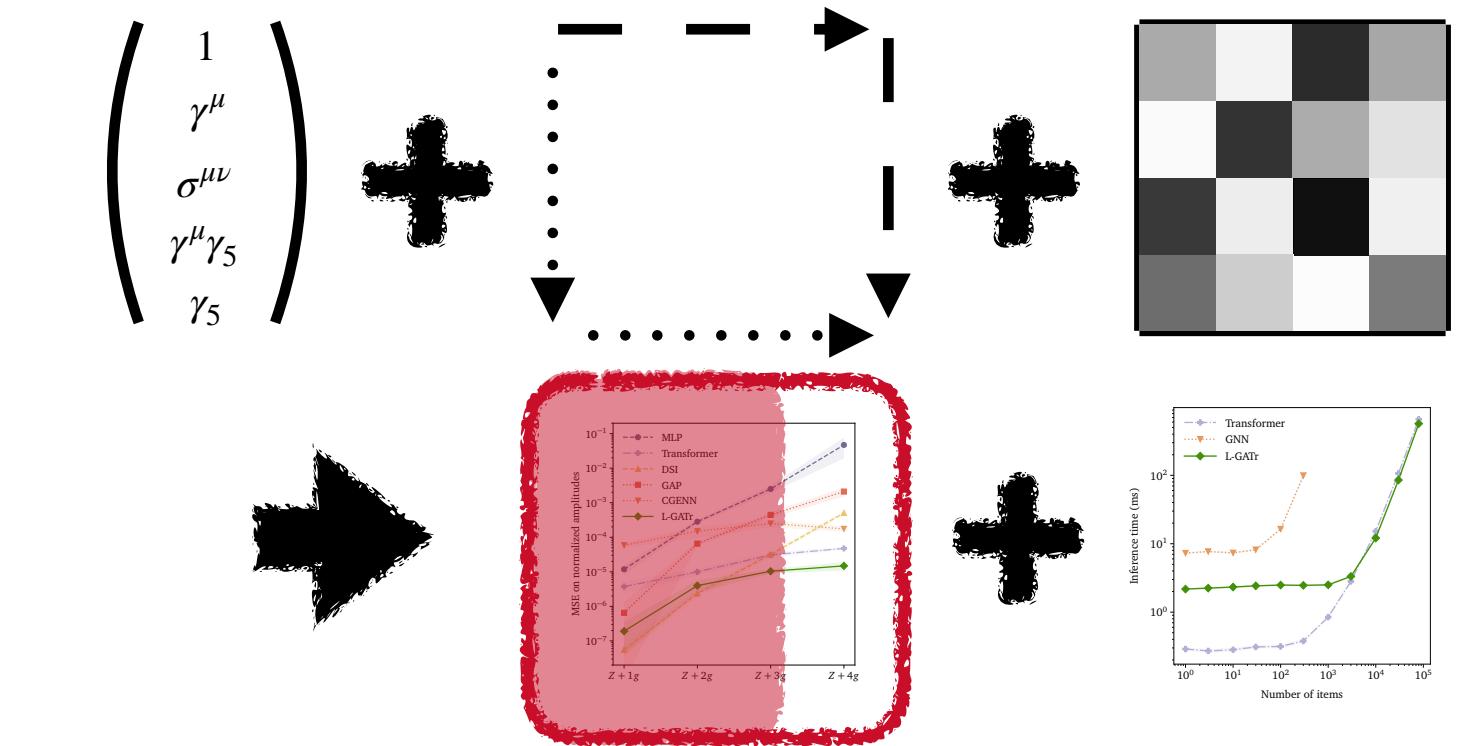
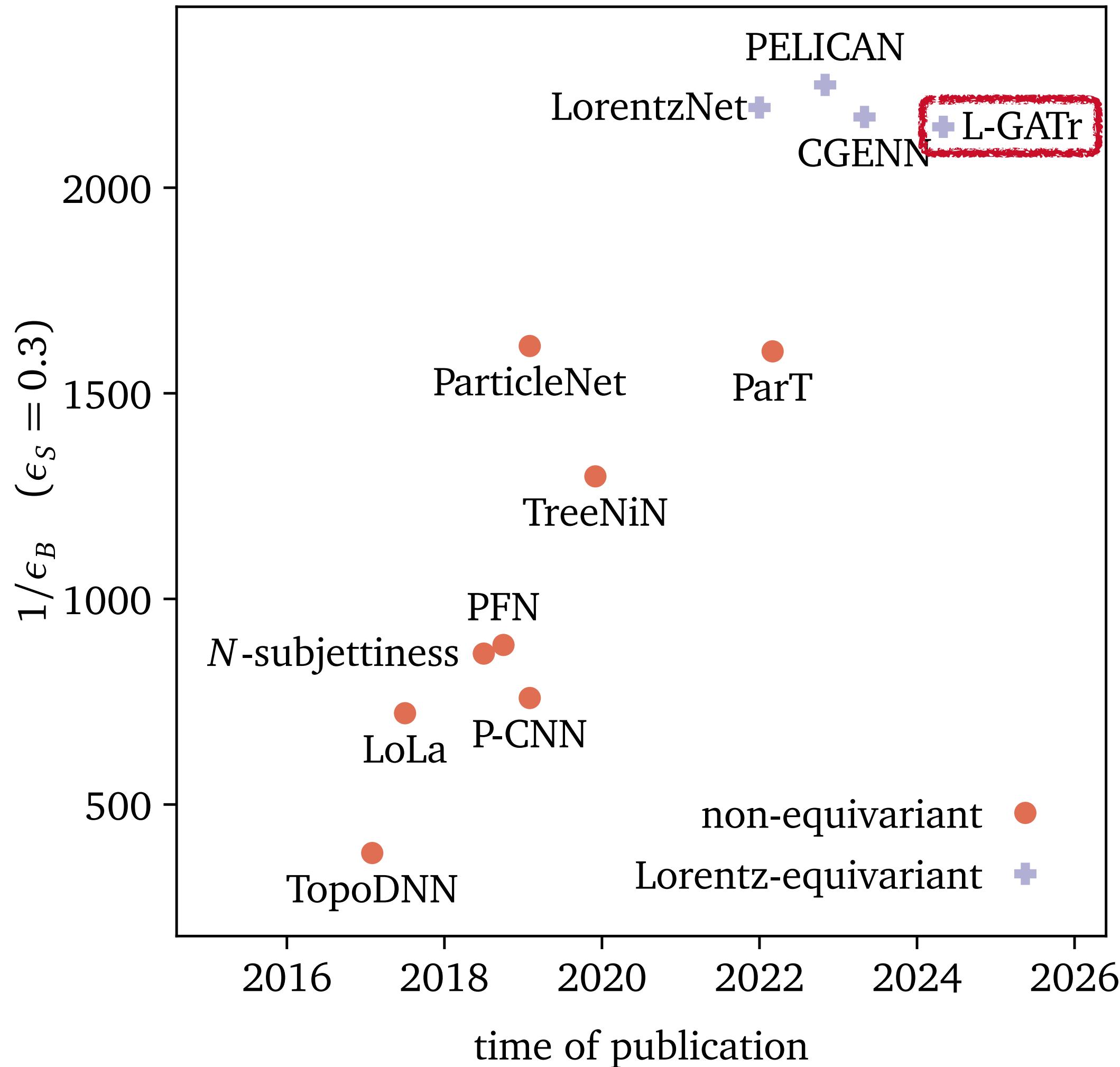
# Experiments

## Top tagging



# Experiments

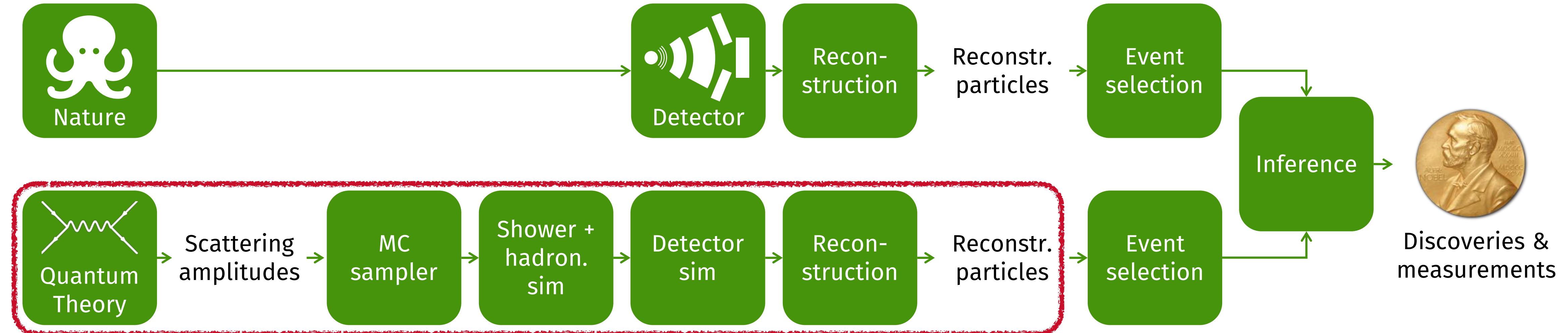
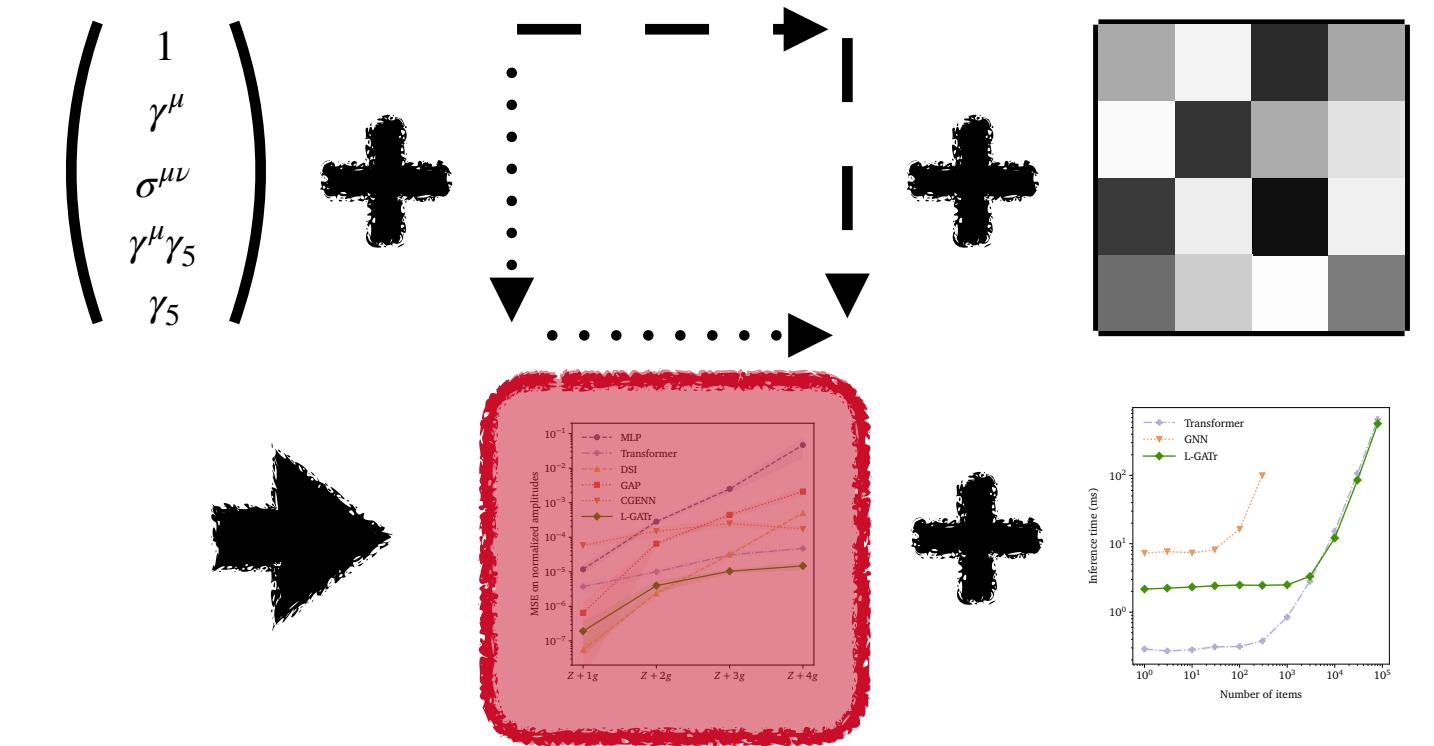
## Top tagging



L-GATr is on par with the best equivariant (\*) baselines

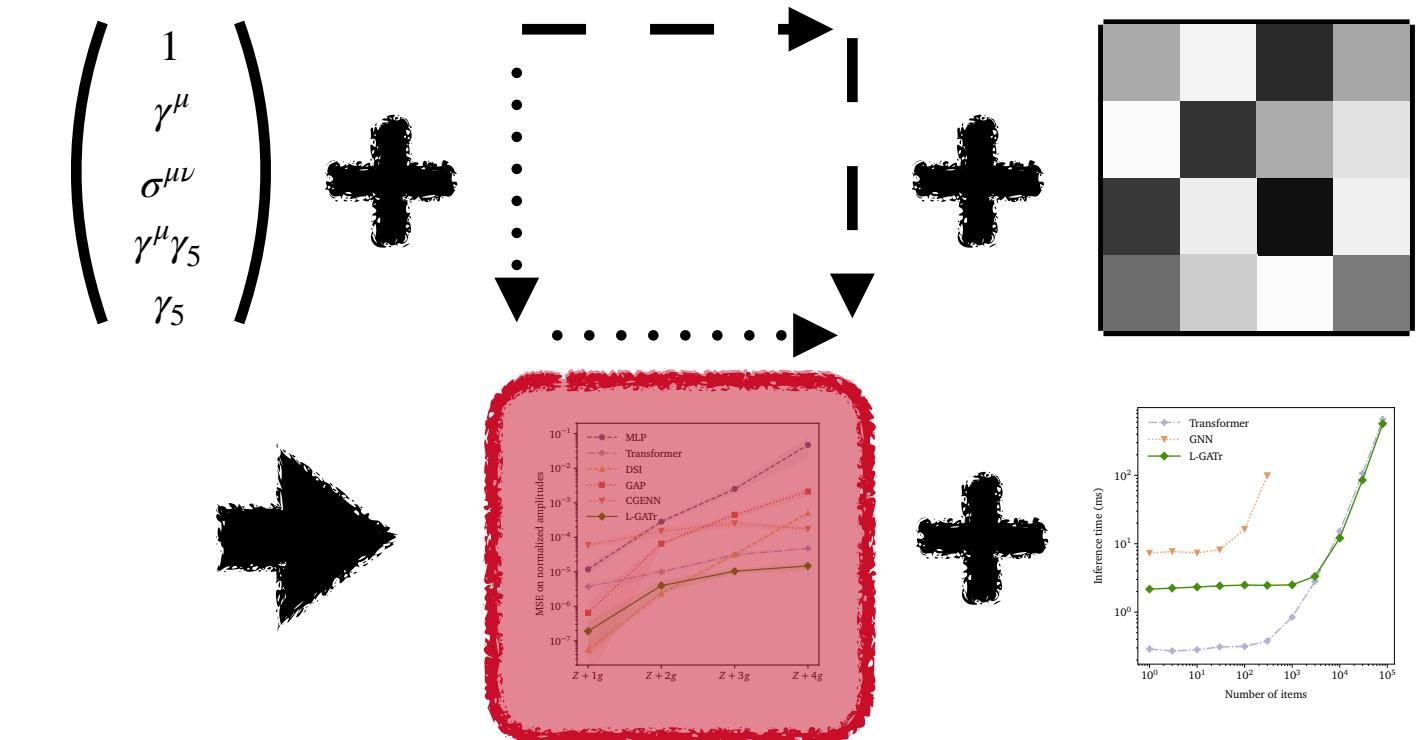
# Experiments

## Event generation



# Experiments

## Event generation



### Continuous normalising flows (CNF)

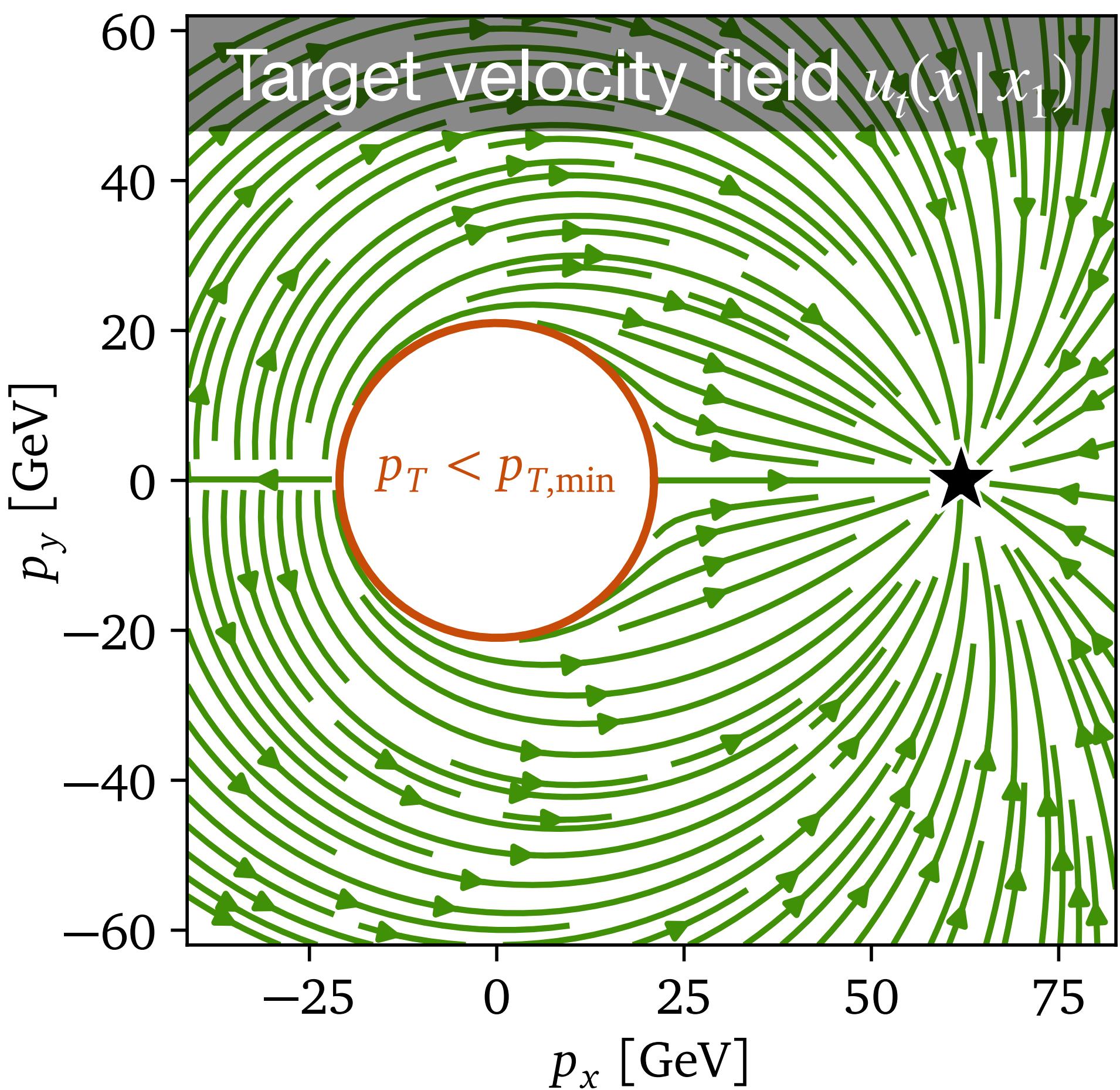
connect a simple base density  
to a complex target density  
through a neural differential equation

$$\frac{d}{dt}x = v_t(x)$$

Conditional flow matching (CFM)  
is a simple way to train CNFs  
by comparing the learned velocity  $v_t(x)$   
to a conditional target velocity  $u_t(x | x_1)$

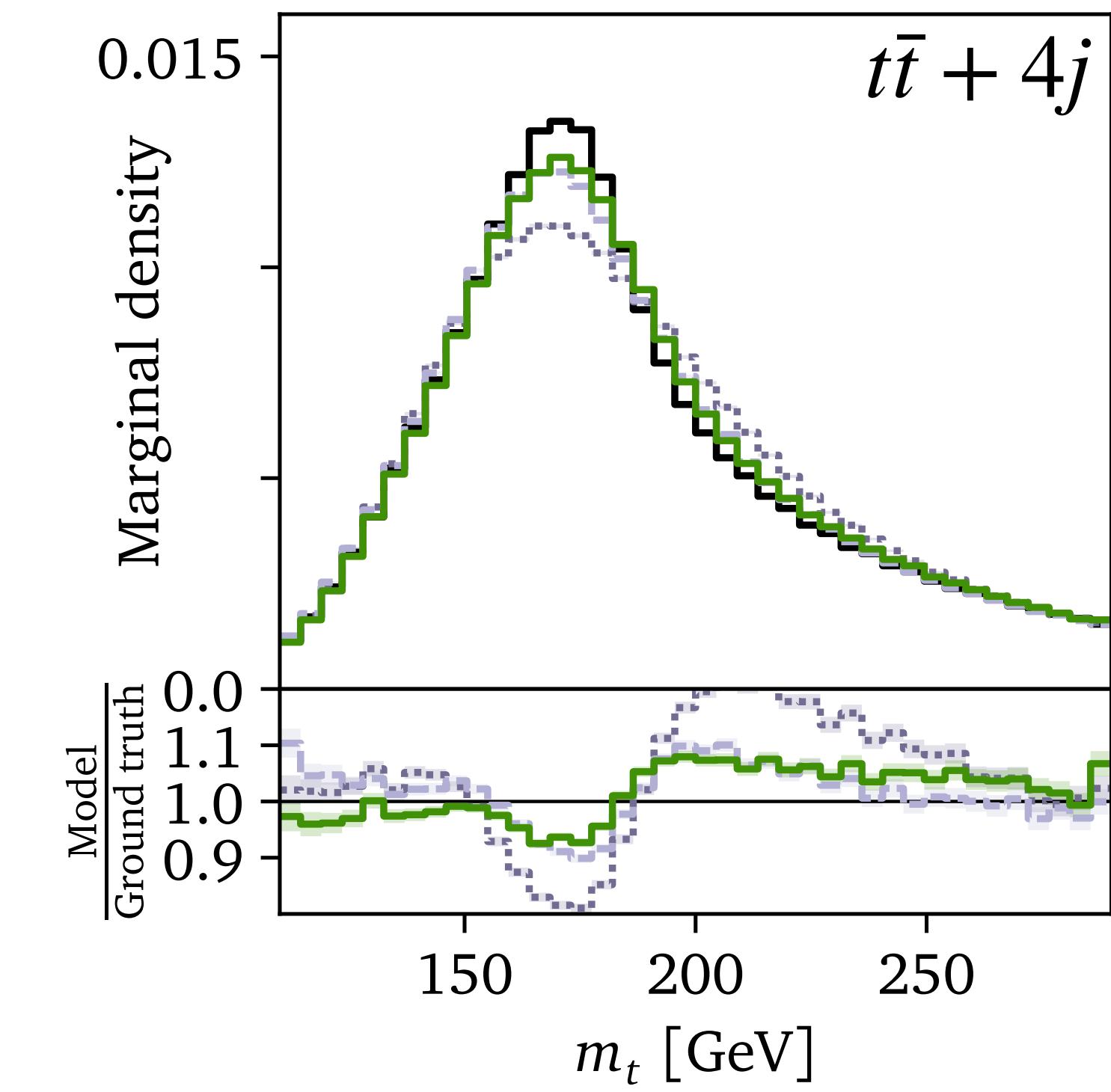
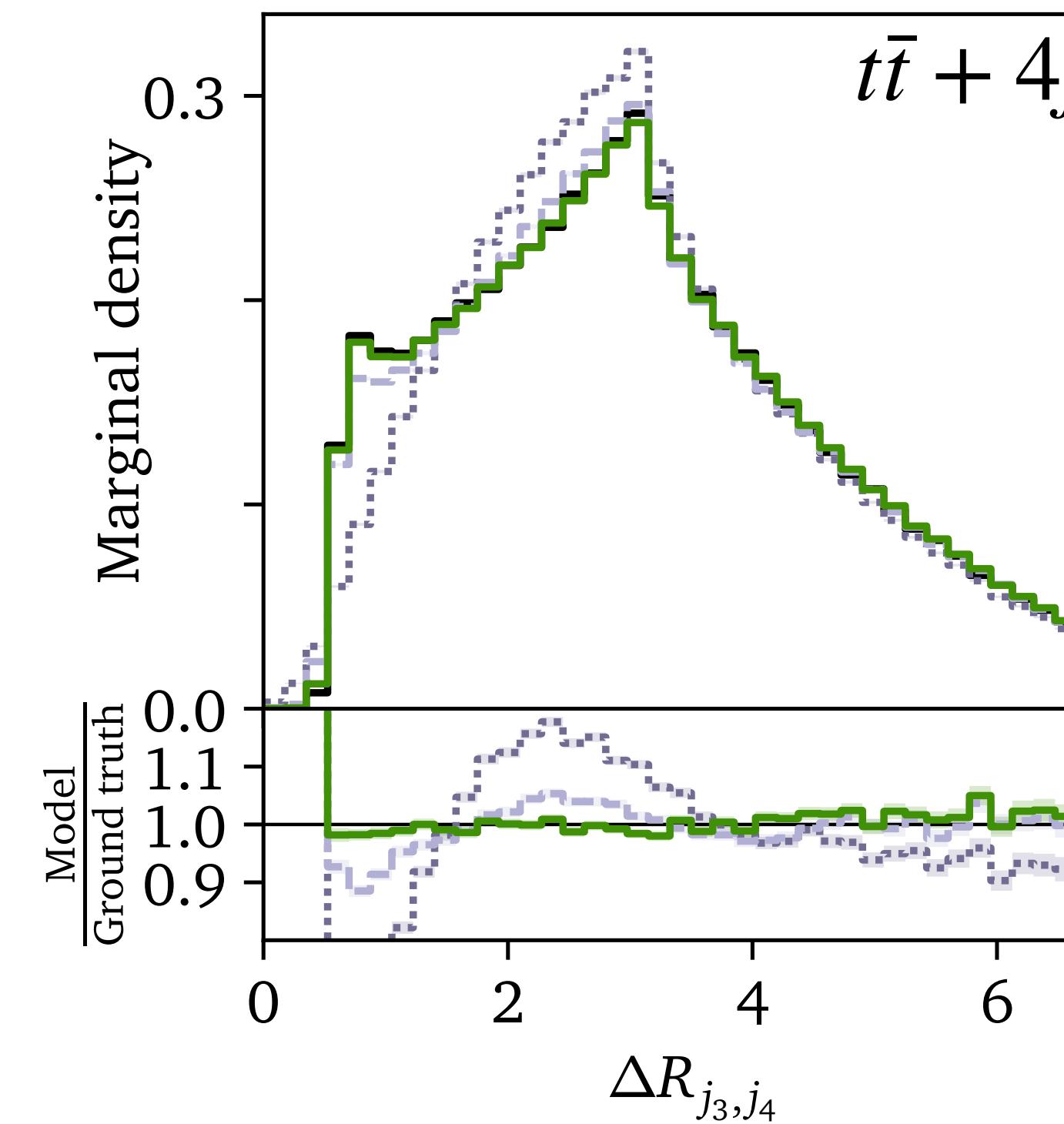
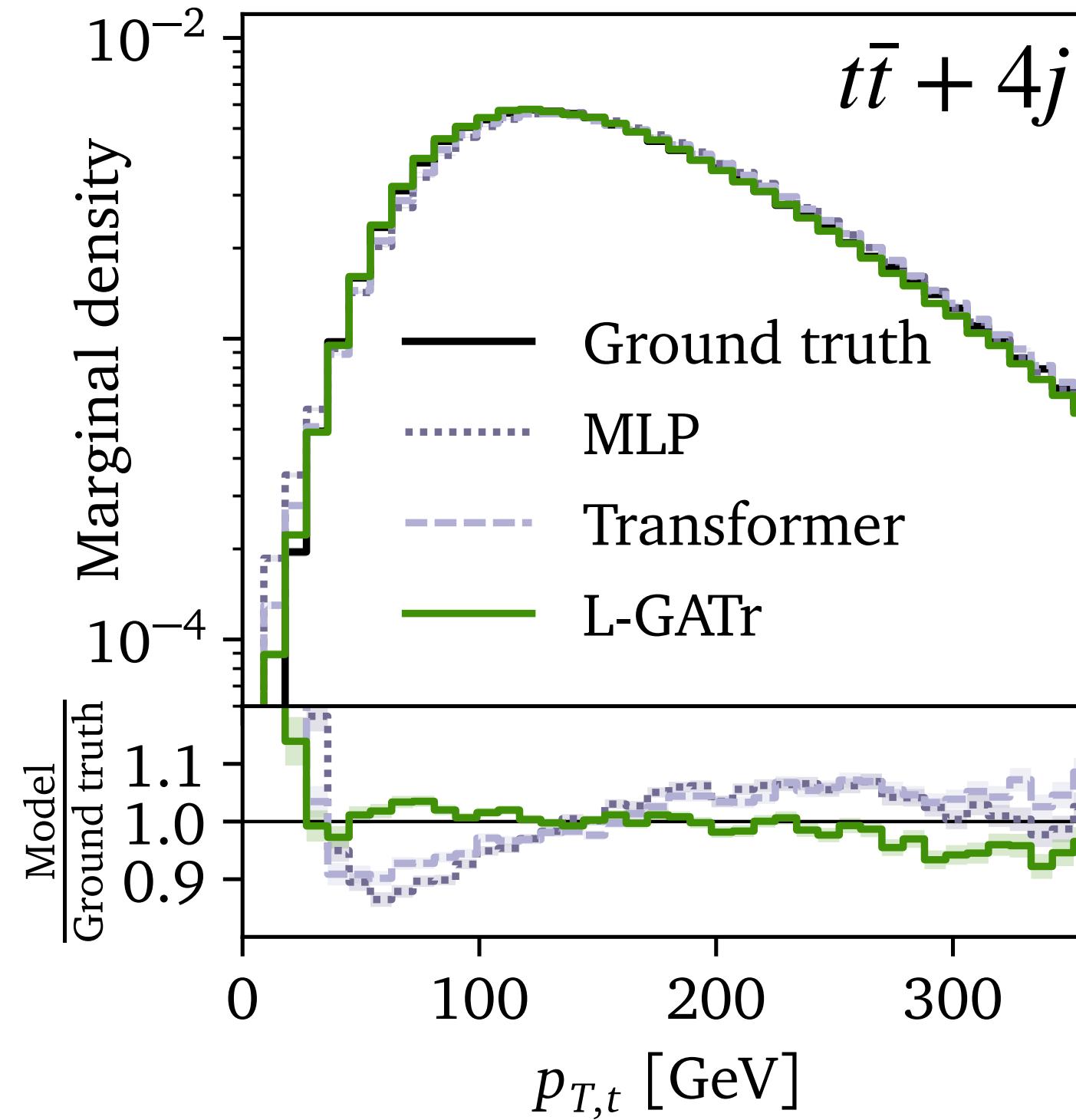
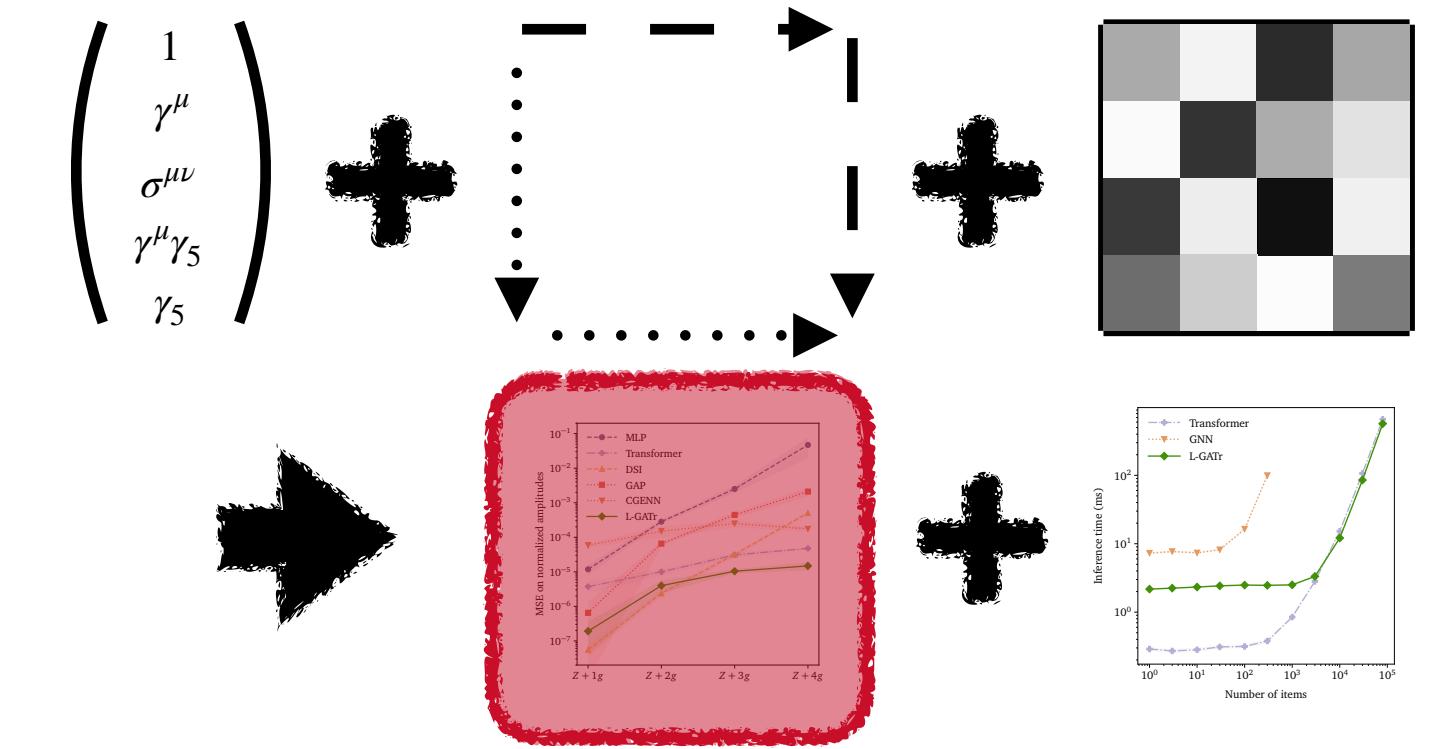
Continuous normalising flows  
arXiv:1806.07366

Conditional flow matching  
arXiv:2210.02747



# Experiments

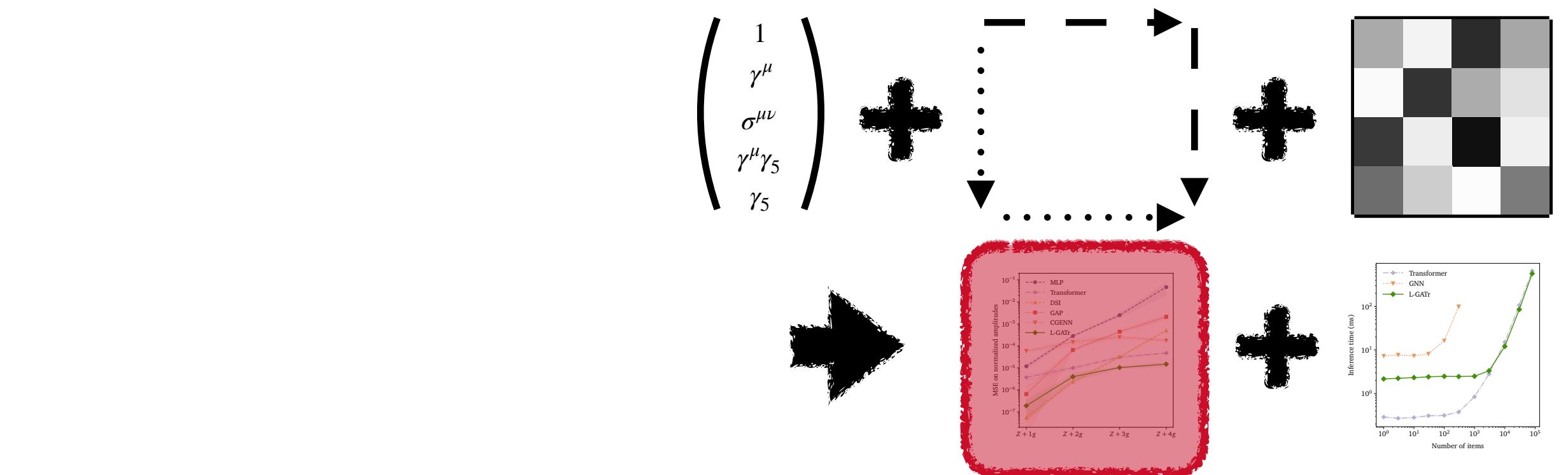
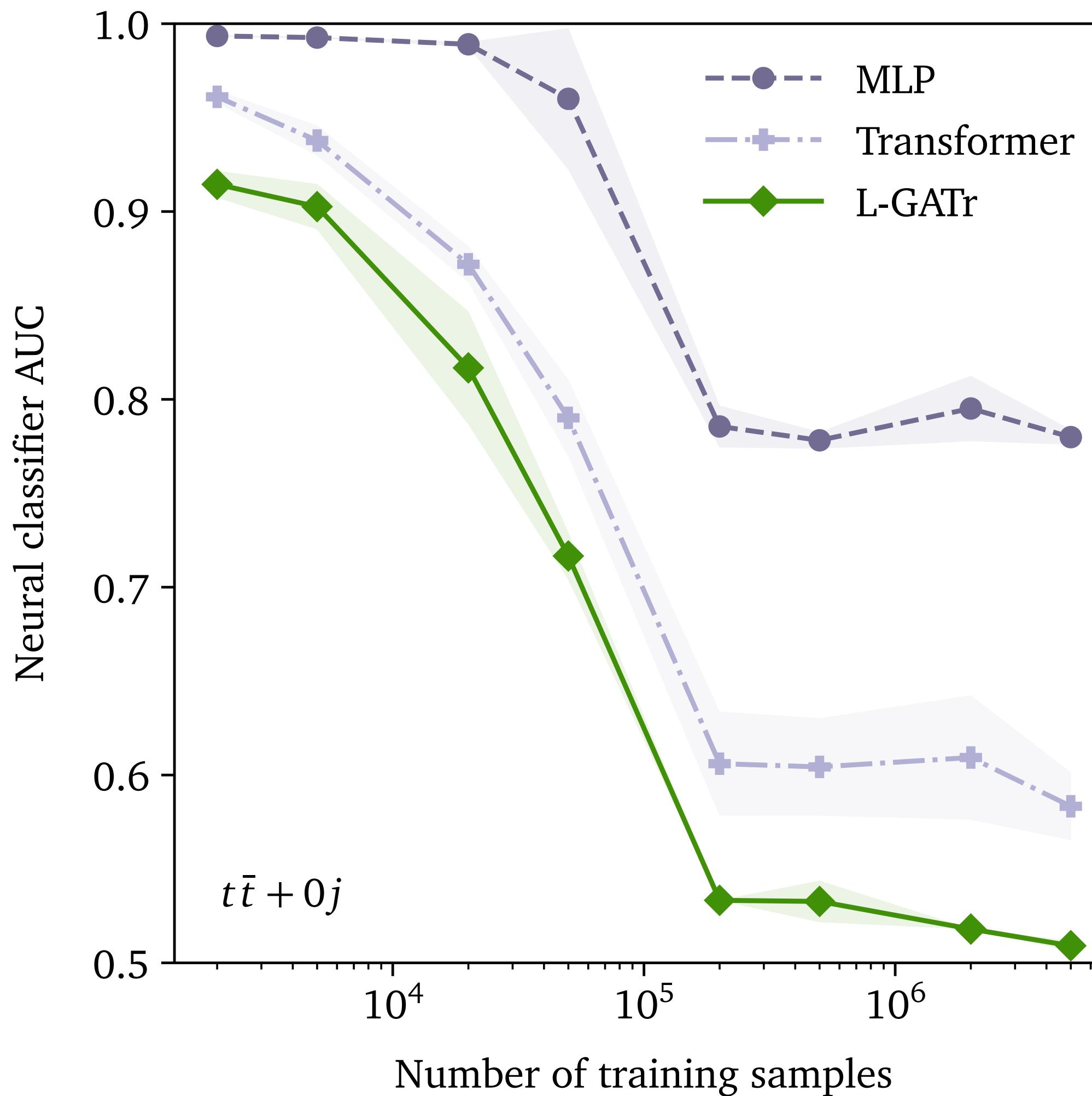
## Event generation



L-GATr helps with tricky kinematic features

# Experiments

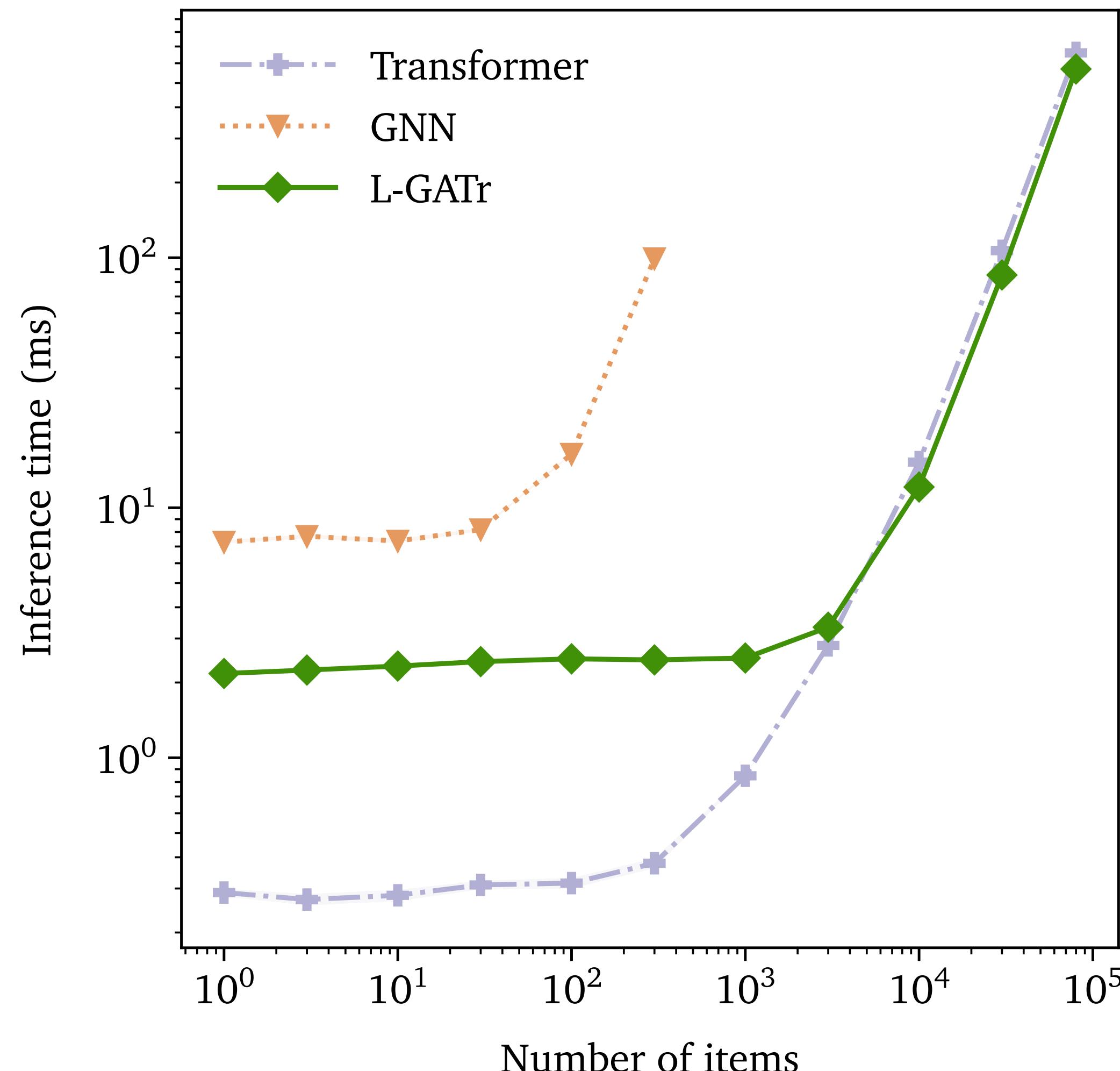
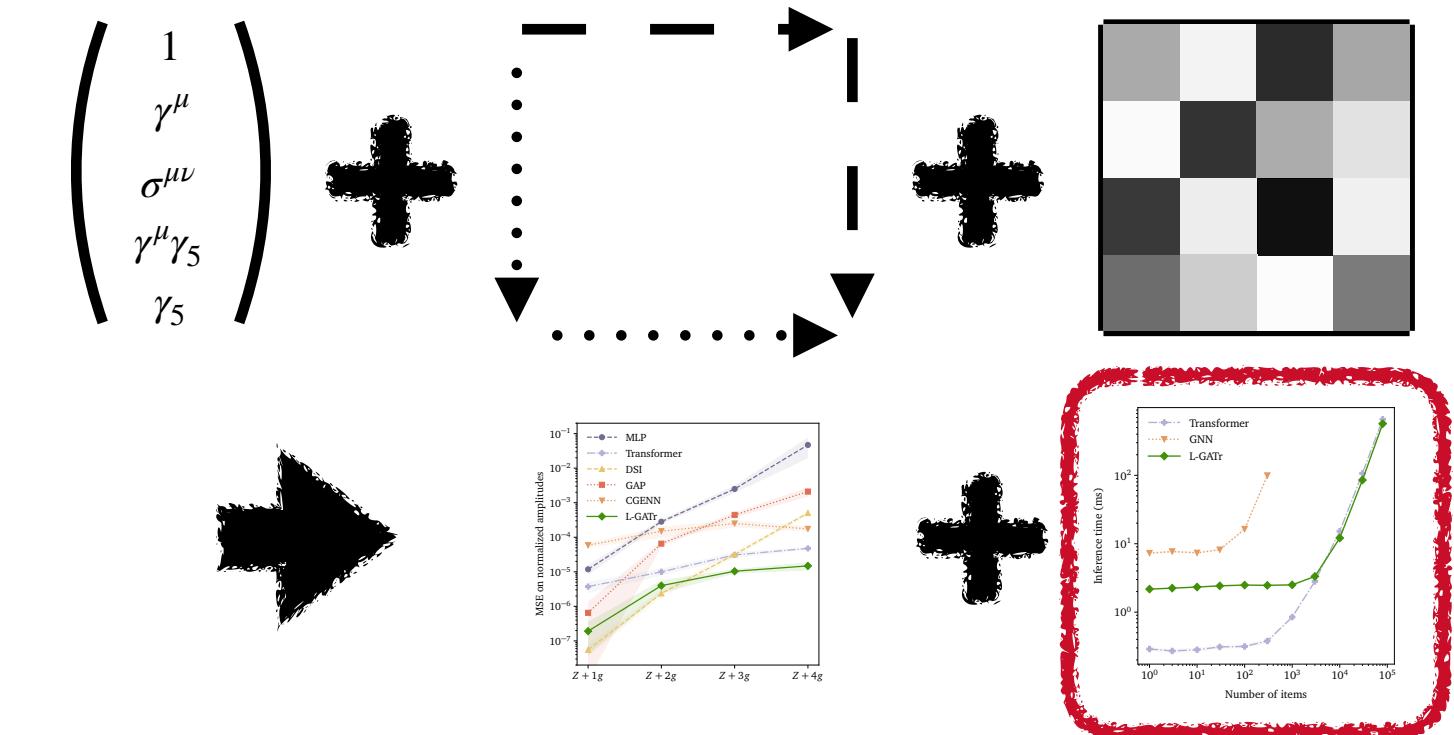
## Event generation



L-GATr generates samples that a classifier can almost not distinguish from the ground truth

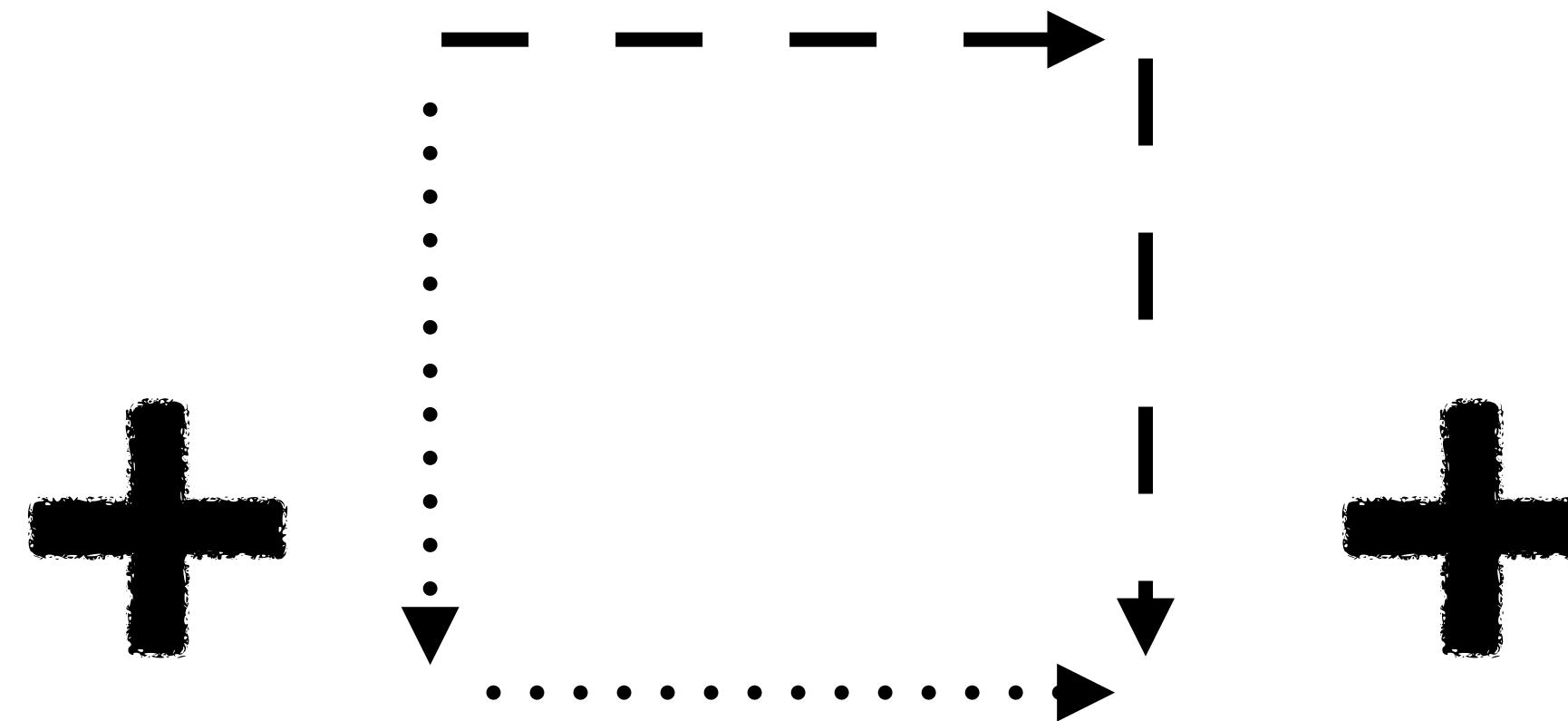
# Experiments

L-GATr can process thousands of particles



Transformers scale  
better than graph networks

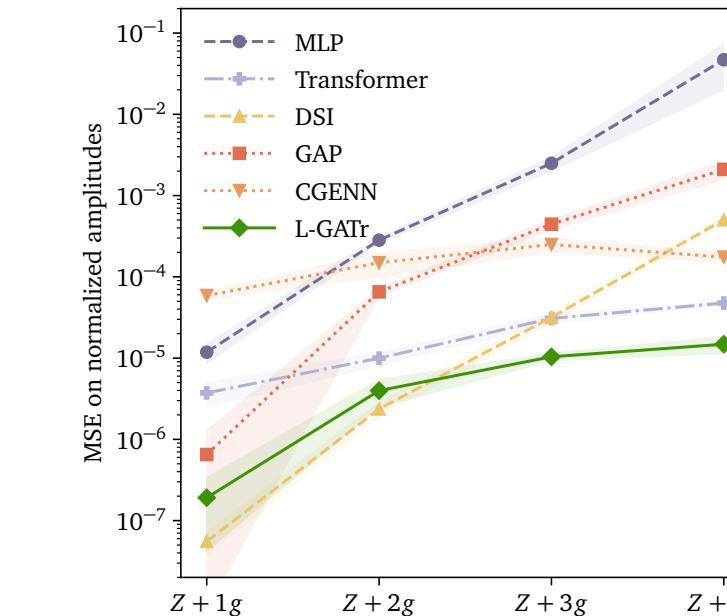
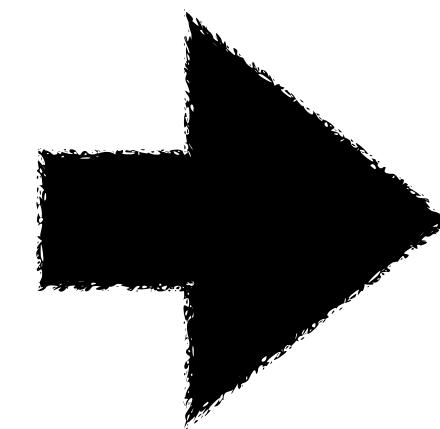
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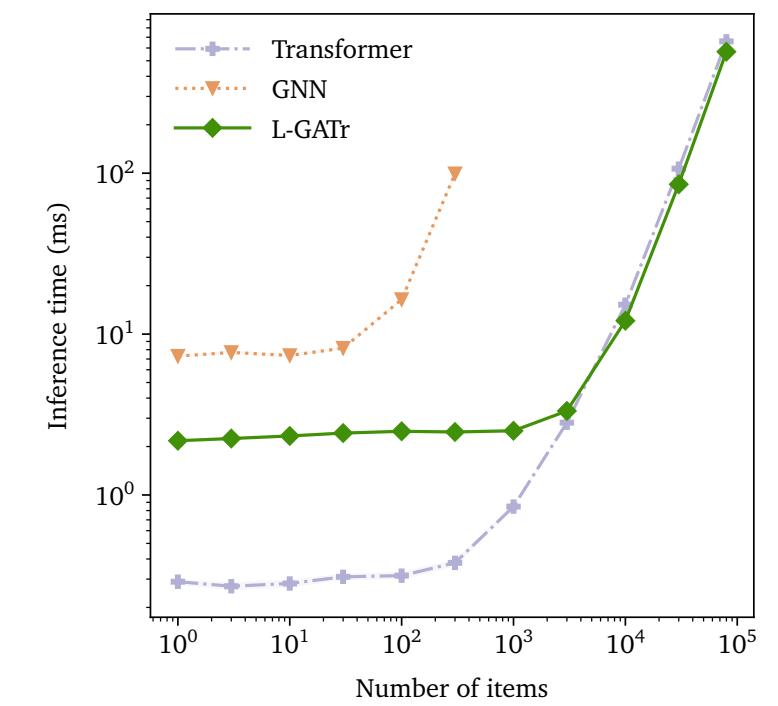
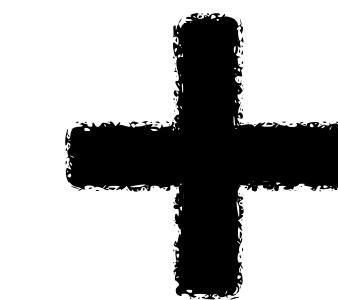
**Geometric algebra**  
representations

**Equivariant**  
layers

**Transformer**  
architecture



**Strong performance**  
on diverse problems



**Scalable**  
to thousands of tokens

**L-GATr** combines **equivariance** and **scalability**



Victor Bresó



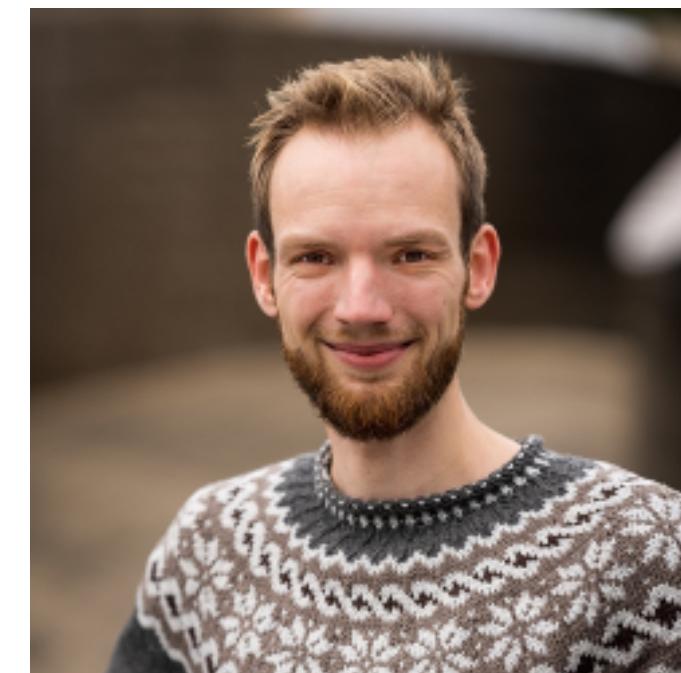
Pim de Haan



Tilman Plehn



Jesse Thaler



Johann Brehmer

## Geometric Algebra Transformer

E(3)-equivariant version

Johann Brehmer\*, Pim de Haan\*, Sönke Behrends, Taco Cohen  
NeurIPS 2023, arXiv:2305.18415



E(3)-GATr paper



E(3)-GATr code

## Lorentz-Equivariant Geometric Algebra Transformer for High-Energy Physics

Jonas Spinner\*, Victor Bresó\*, Pim de Haan,  
Tilman Plehn, Jesse Thaler, Johann Brehmer  
NeurIPS 2024, arXiv:2405.14806



L-GATr paper



L-GATr code

What would **you** use L-GATr for?

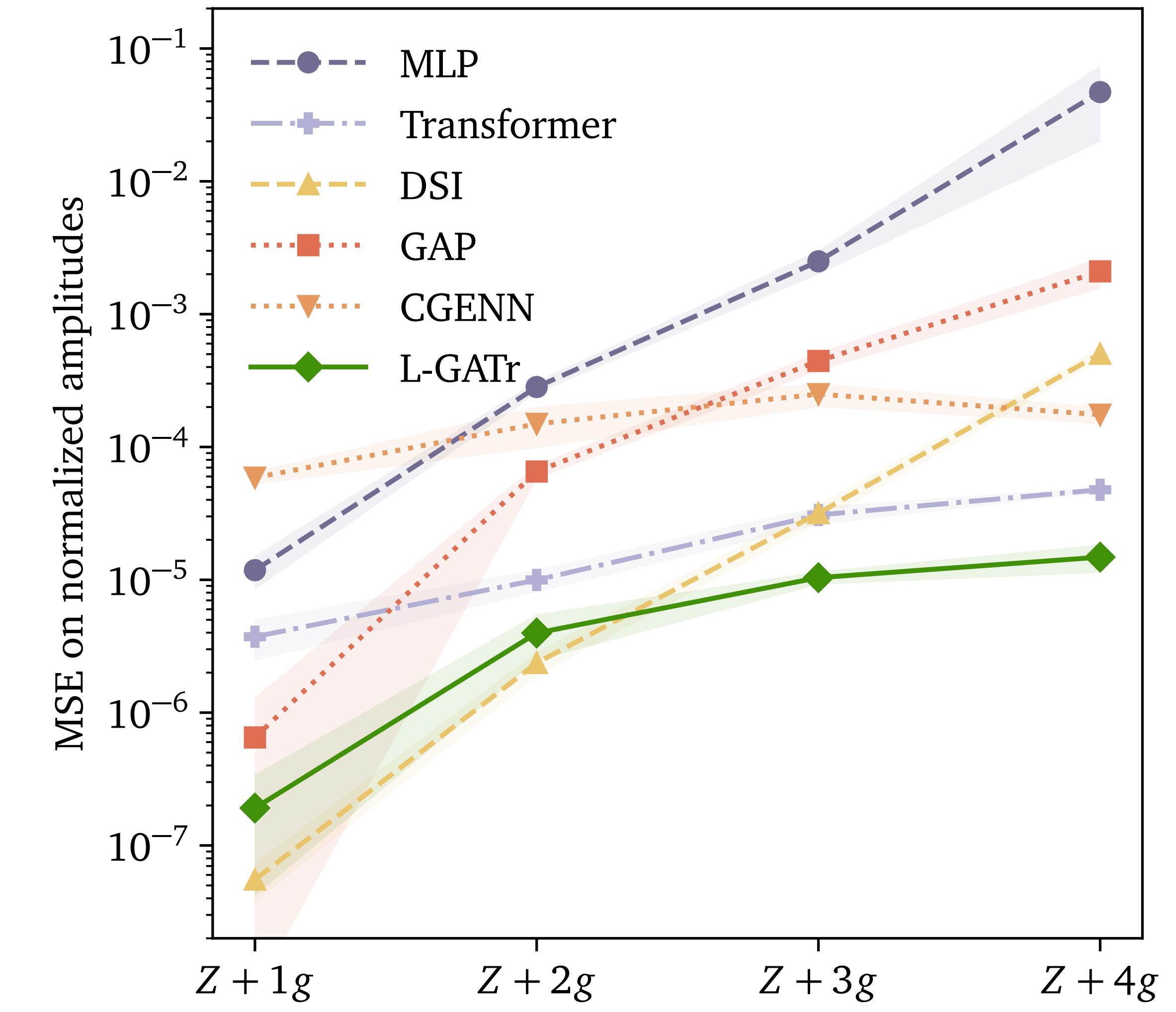
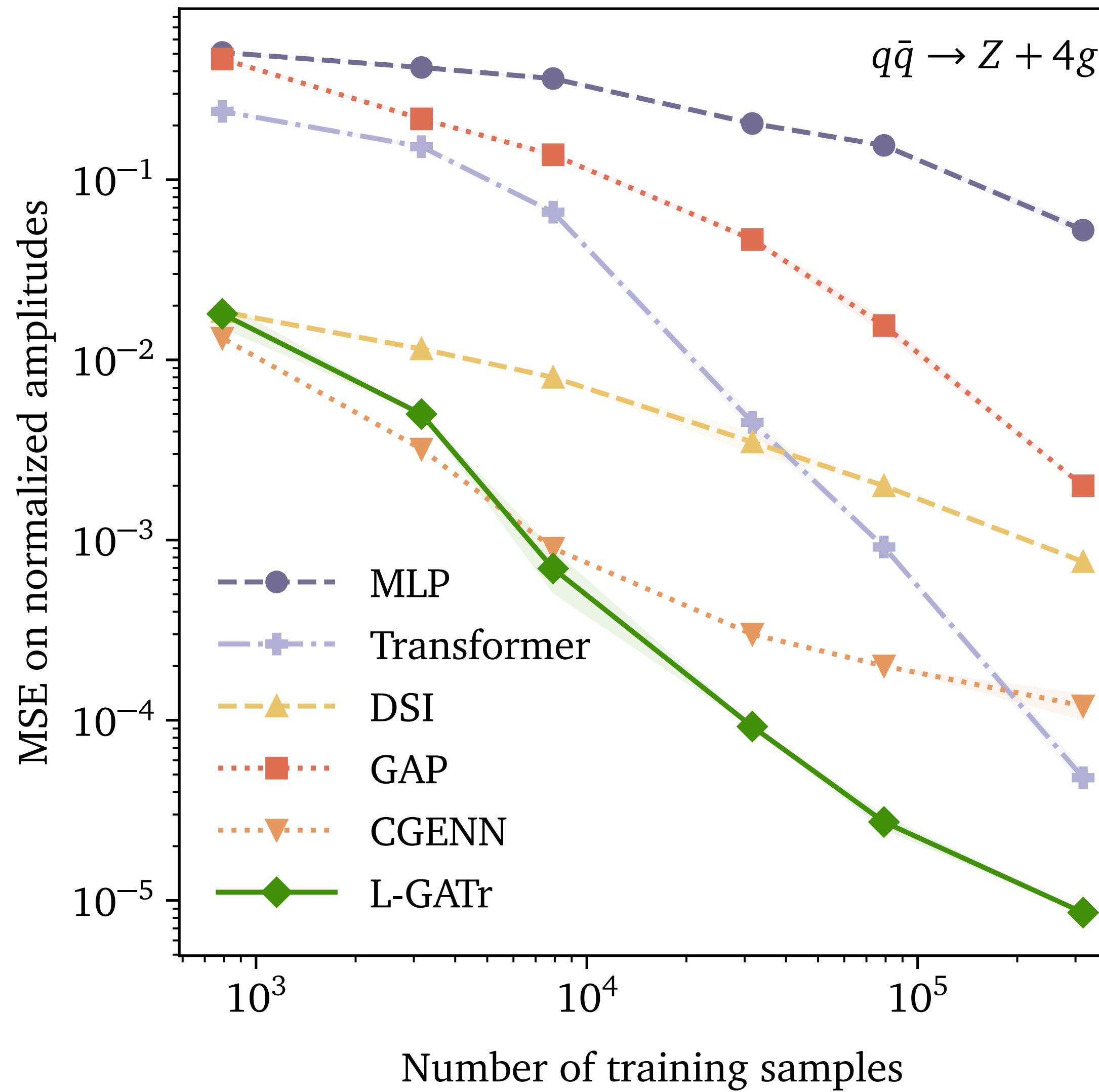
# Bonus material

# Ingredients

## Equivariant layers

	Transformer	L-GATr
Linear( $x$ )	$v \ x + c$	$\sum_{k=0}^4 v_k \langle x \rangle_k + \sum_{k=0}^4 w_k \gamma_5 \langle x \rangle_k$
Attention( $q, k, v$ ) $_{i\alpha}$	$\sum_{j,\beta} \text{Softmax}_j \left( \frac{q_{i\beta}, k_{j\beta}}{\sqrt{n}} \right) v_{j\alpha}$	$\sum_{j,\beta} \text{Softmax}_j \left( \frac{\langle q_{i\beta}, k_{j\beta} \rangle}{\sqrt{16n}} \right) v_{j\alpha}$
GP( $x, y$ )	-	$x \cdot y$
LayerNorm( $x$ )	$x / \sqrt{\frac{1}{n} \sum_{c=1}^n x_c^2 + \epsilon}$	$x / \sqrt{\frac{1}{n} \sum_{c=1}^n \sum_{k=0}^4 \left  \langle \langle x_c \rangle_k, \langle x_c \rangle_k \rangle \right  + \epsilon}$
Act( $x$ )	GELU( $x$ )	GELU( $\langle x \rangle_0$ ) $x$

# Amplitude regression



# Experiments

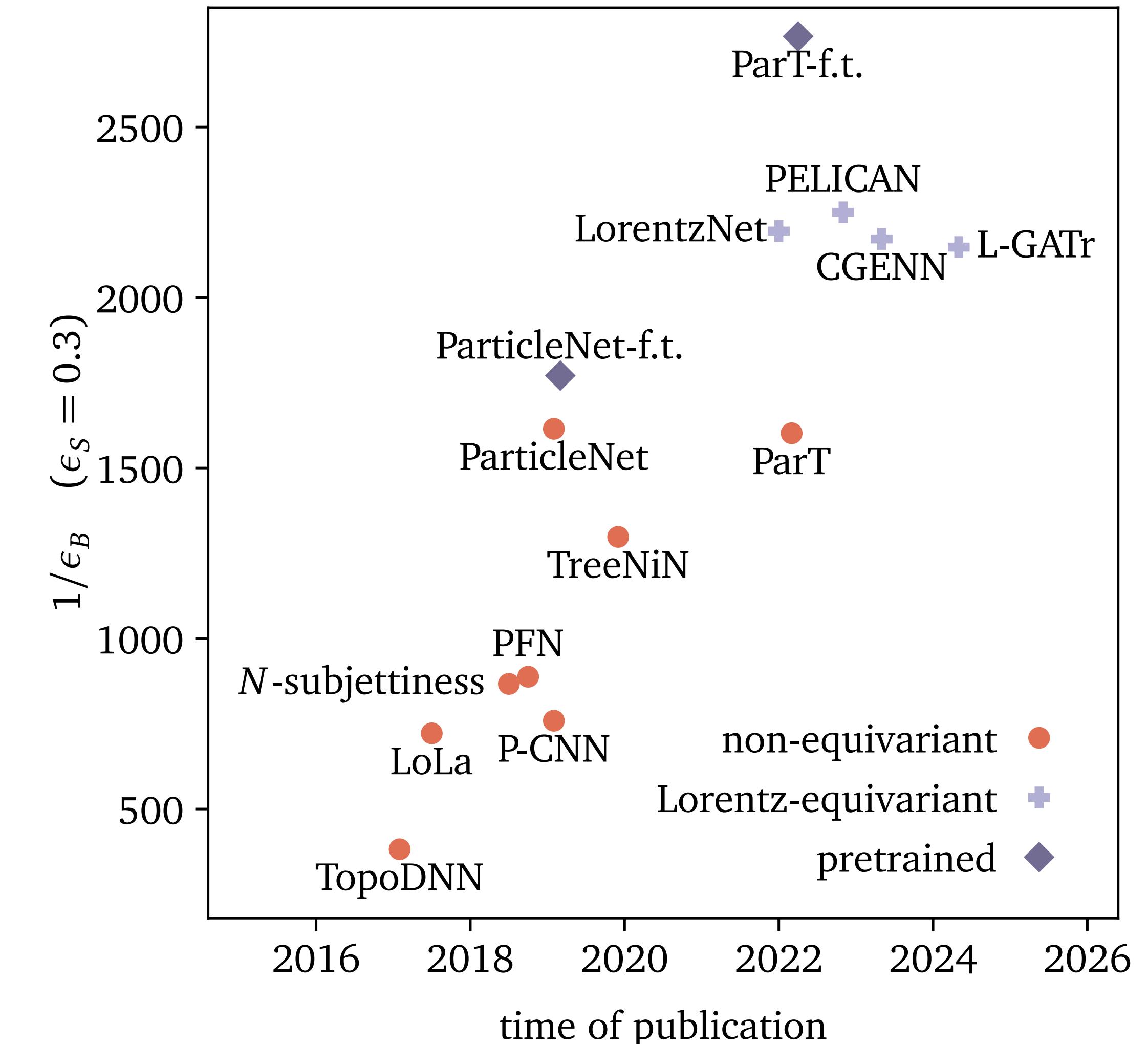
## Top tagging

Model	Accuracy	AUC	$1/\epsilon_B$ ( $\epsilon_S = 0.5$ )	$1/\epsilon_B$ ( $\epsilon_S = 0.3$ )
TopoDNN [48]	0.916	0.972	–	<b>295</b> $\pm$ 5
LoLa [15]	0.929	0.980	–	<b>722</b> $\pm$ 17
P-CNN [1]	0.930	0.9803	<b>201</b> $\pm$ 4	<b>759</b> $\pm$ 24
$N$ -subjettiness [61]	0.929	0.981	–	<b>867</b> $\pm$ 15
PFN [50]	0.932	0.9819	<b>247</b> $\pm$ 3	<b>888</b> $\pm$ 17
TreeNiN [57]	0.933	0.982	–	<b>1025</b> $\pm$ 11
ParticleNet [63]	0.940	0.9858	<b>397</b> $\pm$ 7	<b>1615</b> $\pm$ 93
ParT [64]	0.940	0.9858	<b>413</b> $\pm$ 16	<b>1602</b> $\pm$ 81
LorentzNet* [41]	0.942	0.9868	<b>498</b> $\pm$ 18	<b>2195</b> $\pm$ 173
CGENN* [67]	0.942	0.9869	500	<b>2172</b>
PELICAN* [9]	<b>0.9426</b> $\pm$ 0.0002	<b>0.9870</b> $\pm$ 0.0001	–	<b>2250</b> $\pm$ 75
<b>L-GATr (ours)*</b>	0.9417 $\pm$ 0.0002	0.9868 $\pm$ 0.0001	<b>548</b> $\pm$ 26	2148 $\pm$ 106

# Experiments

## Top tagging

- New paradigm: **Transfer learning**  
Pretrain model on large dataset, then fine-tune on target dataset
- Transformers transfer better than graph networks



# Experiments

## Conditional Flow Matching

Continuous normalising flows (CNF)

connect a simple base density  
to a complex target density  
through a neural differential equation

$$\frac{d}{dt}x = v_t(x)$$

Conditional flow matching (CFM)

is a simple way to train CNFs  
by comparing the learned velocity  $v_t(x)$   
to a conditional target velocity  $u_t(x | x_1)$

$$\mathcal{L} = \mathbb{E}_{t,x,x_1} \|v_t(x) - u_t(x | x_1)\|^2$$

Continuous normalising flows  
arXiv:1806.07366

Conditional flow matching  
arXiv:2210.02747

# Experiments

## Target velocities for CFM

In conditional flow matching (CFM),  
the **choice of target velocity** can be  
more important than the architecture

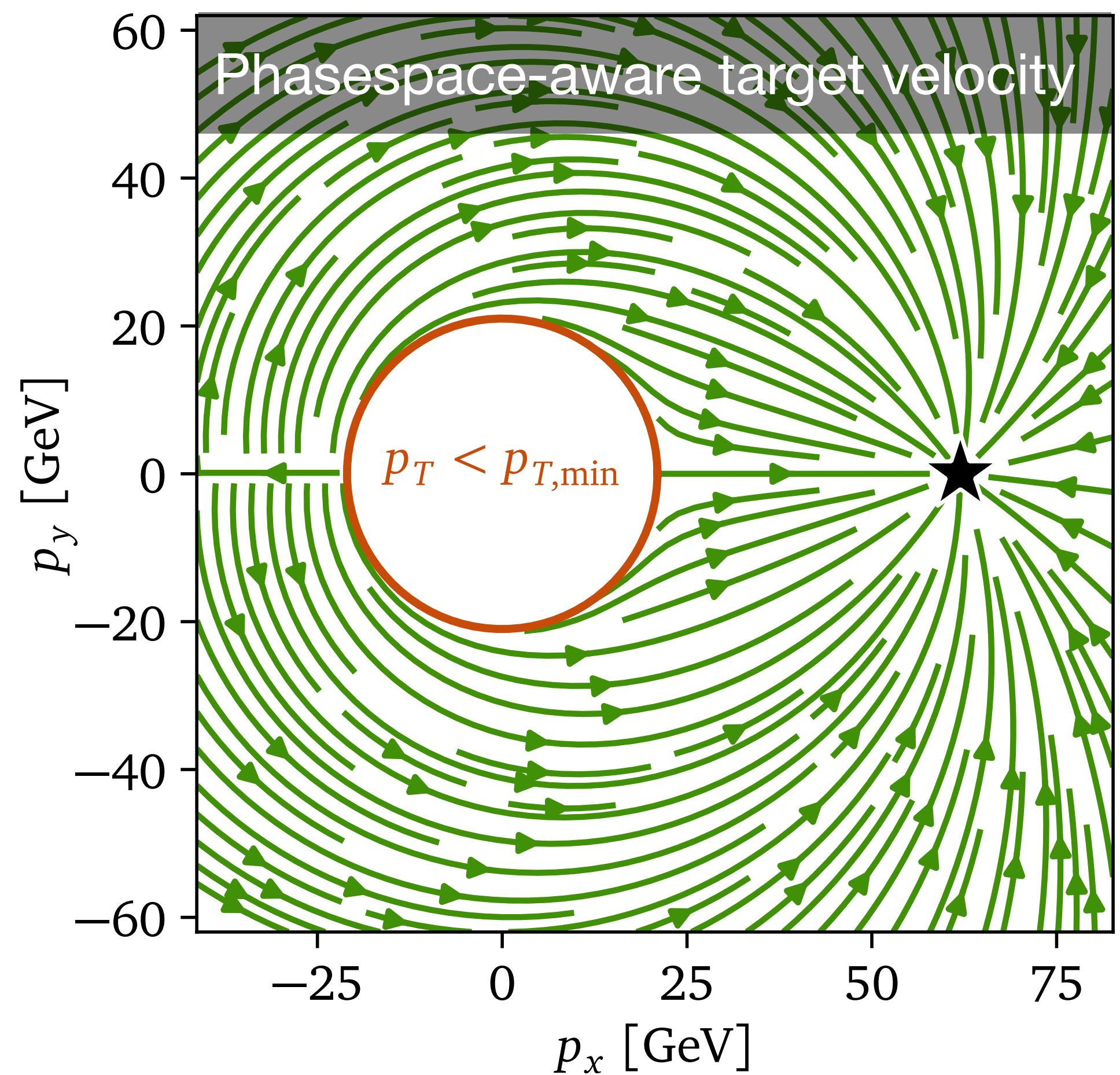
# Experiments

## Target velocities for CFM

In conditional flow matching (CFM),  
the **choice of target velocity** can be  
more important than the architecture

Target velocity	Architecture	AUC
Euclidean	L-GATr	0.99
Phasespace-aware	MLP	0.78
Phasespace-aware	L-GATr	<b>0.51</b>

Riemannian Flow Matching  
arXiv:2302.03660



# Event generation

## Target velocities for CFM

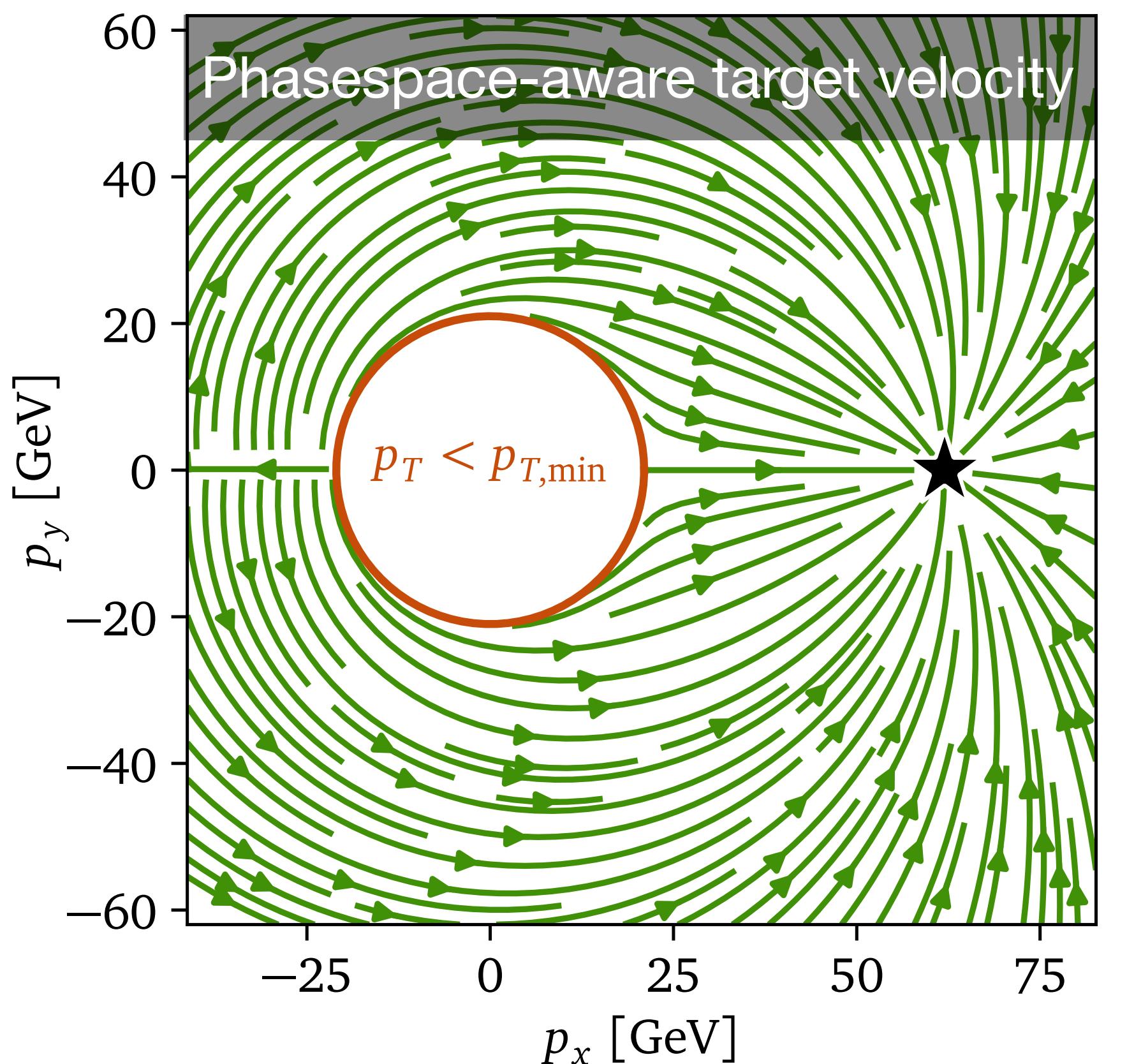
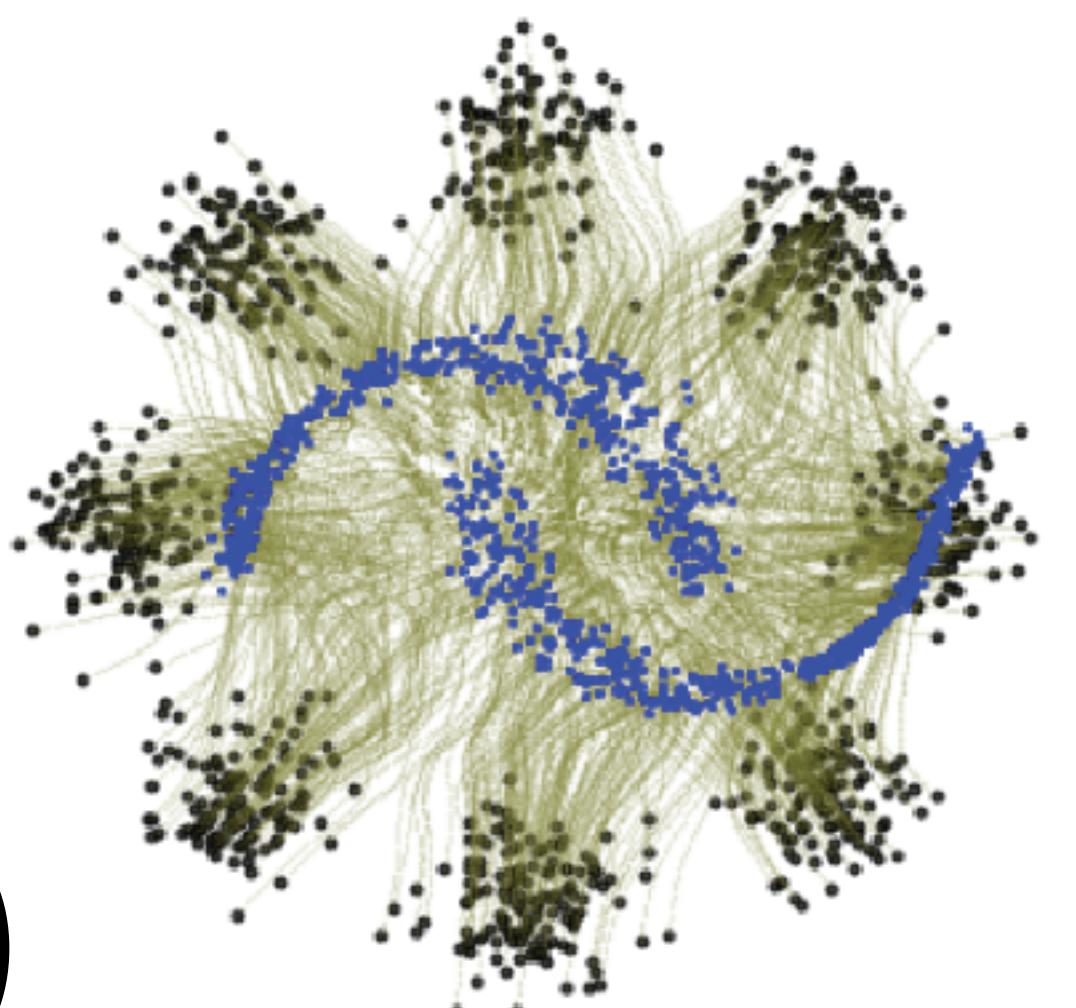
$$p = (E, p_x, p_y, p_z) = f(y) = \left( \sqrt{m^2 + p_T^2 \cosh^2 \eta}, p_T \cos \phi, p_T \sin \phi, p_T \sinh \eta \right)$$

$$y = (y_m, y_p, \phi, \eta), \quad m^2 = \exp(y_m), \quad p_T = p_{T,\min} + \exp(y_p)$$

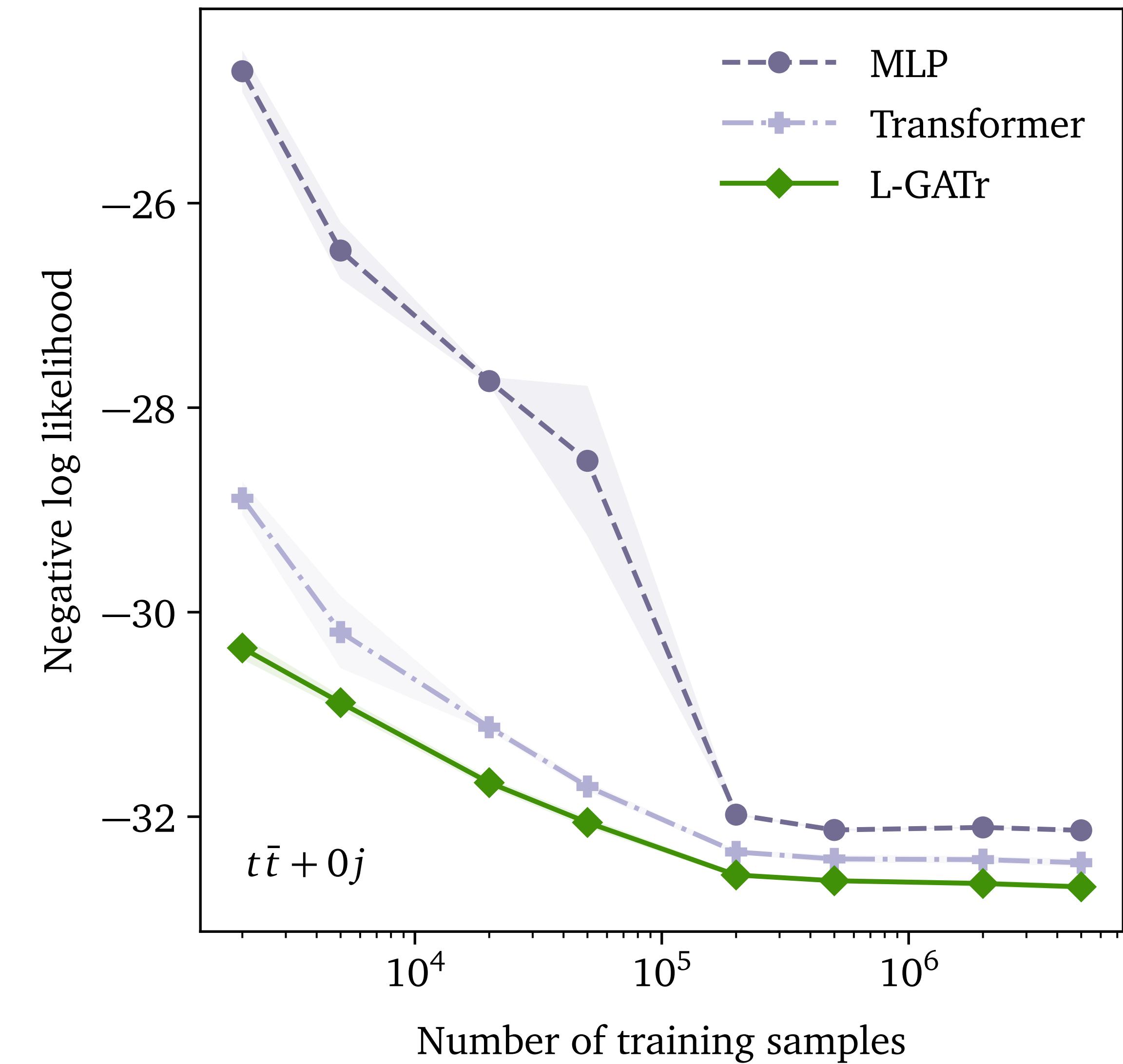
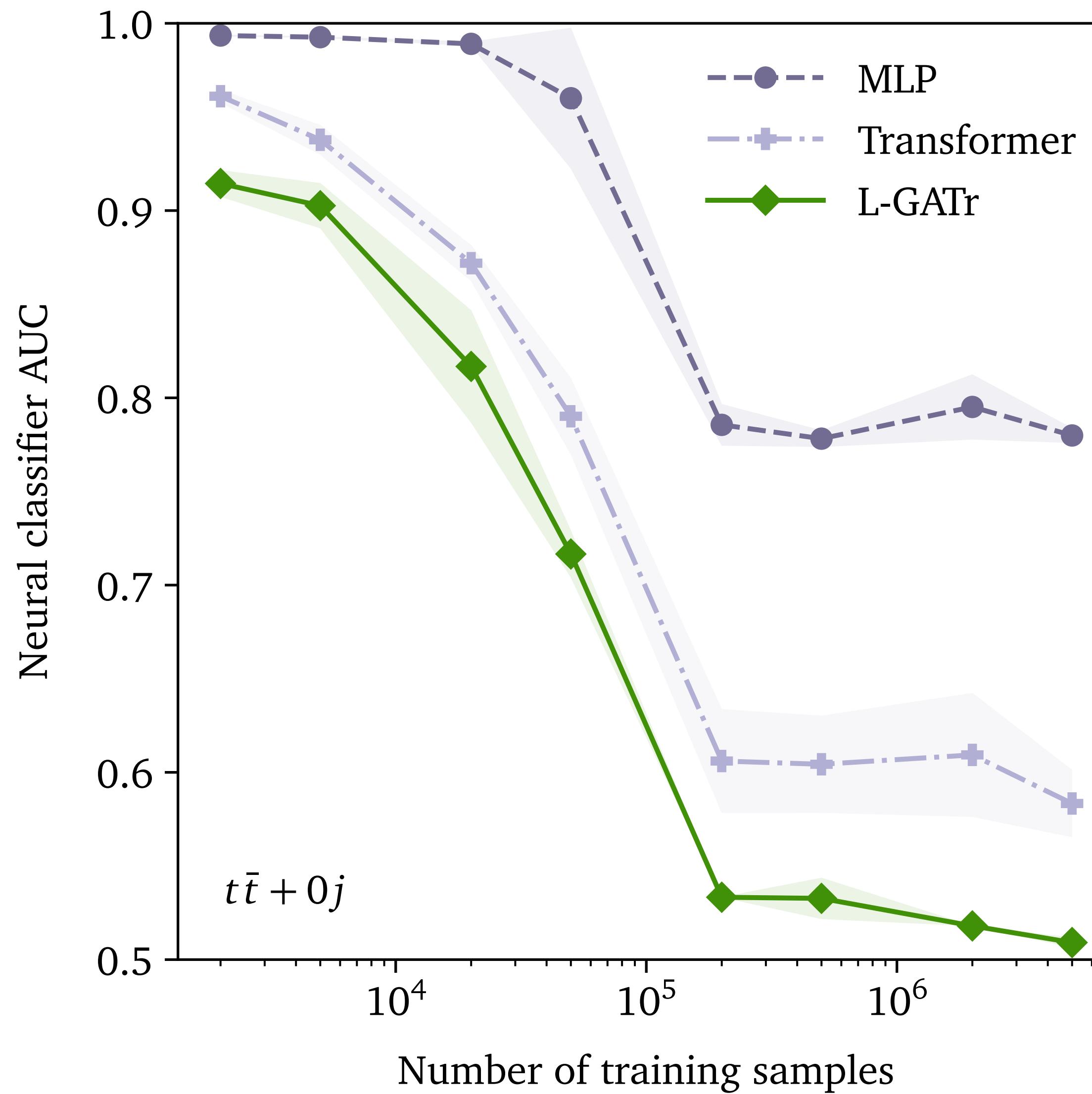
Target velocities can be

constant in  $p = (E, p_x, p_y, p_z)$  ('euclidean')

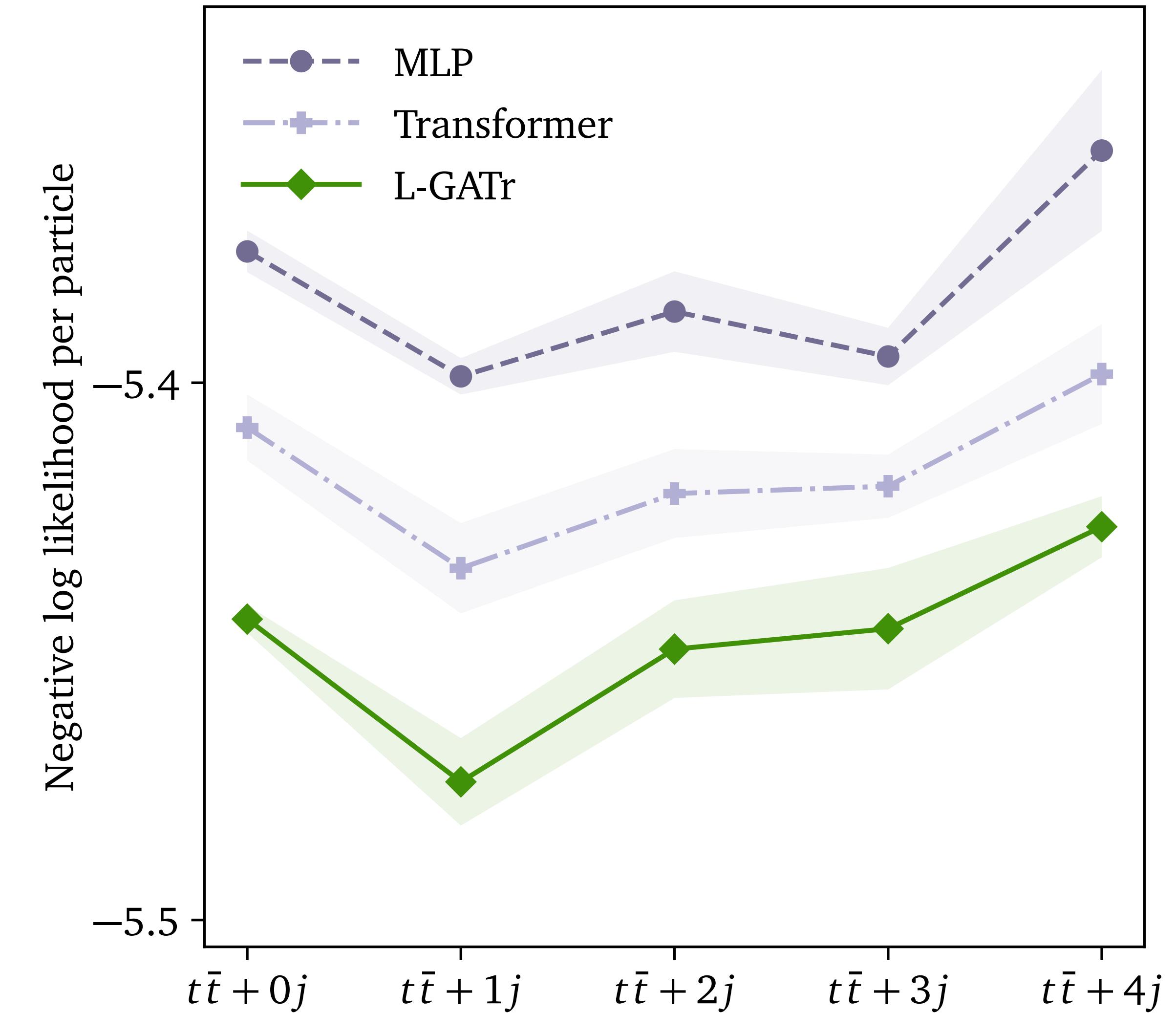
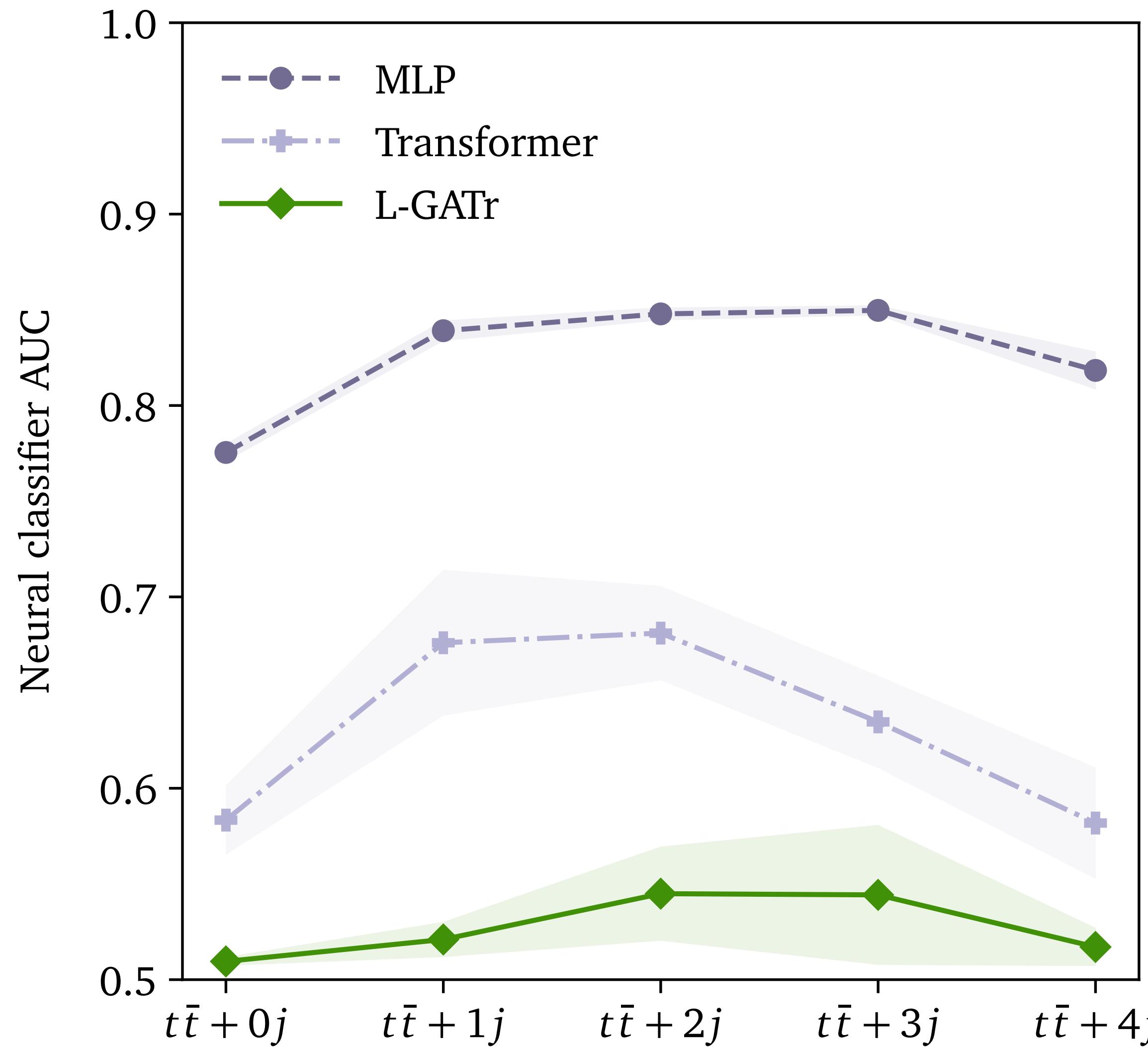
constant in  $y = (y_m, y_p, \phi, \eta)$  ('phasespace-aware')



# Event generation



# Event generation



# Symmetry breaking with spurious

Sources of symmetry breaking

- Real world: Beam direction, detector geometry...  
Symmetry-breaking object: Beam direction spurion
- Generation: Have to break  $SO(1,3) \rightarrow SO(3)$  because generative networks can only be defined on compact groups  
Symmetry-breaking object: Time direction spurn

We break the symmetry by adding the spurious as extra token or as extra channel for each token