

**Image Processing Lab**  
**Sem 1**  
**Lab 3: Sampling and SVD**  
**23/08/2018**

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1. Try to complete the lab questions during the lab time (in lab submission)
  2. Please do not copy programs.
  3. Please find the peppers.png image in the Resources folder.
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**1. Sampling an image**

Use the peppers image and perform the following:

- (a) Downsample the image in spatial domain by removing alternate columns and rows , by a factor of 2 and 4
- (b) Reconstruct the image from the downsampled one by interpolation. Use bilinear interpolation in both cases and comment on the results obtained.
- (c) Comment on the various interpolation methods ,aliasing and about how you can avoid aliasing.

*Note:*

1. Bilinear interpolation equations:

$$output[2m][2n] = input[m][n]$$

$$output[2m][2n + 1] = (input[m][n] + input[m][n + 1])/2$$

$$output[2m + 1][2n] = (input[m][n] + input[m + 1][n])/2$$

$$output[2m + 1][2n + 1] = (input[m][n] + input[m + 1][n] + input[m][n + 1] + input[m + 1][n + 1])/4$$

2. For the factor of 4, do bilinear interpolations twice to reach the original image size.

**2. Eigen values and Singular values**

Find the eigen values and singular values of the matrix

$$A = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}$$

Explore further on the relation between eigen values and singular values.

### 3. Singular Value Decomposition

- (a) Perform SVD on the given image and identify its eigen images.

$$A = \begin{bmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{bmatrix}$$

- (b) Show the different stages of SVD of the following image:

$$A = \begin{bmatrix} 255 & 255 & 255 & 255 & 255 & 255 & 255 & 255 \\ 255 & 255 & 255 & 100 & 100 & 100 & 255 & 255 \\ 255 & 255 & 100 & 150 & 150 & 150 & 100 & 255 \\ 255 & 255 & 100 & 150 & 200 & 150 & 100 & 255 \\ 255 & 255 & 100 & 150 & 150 & 150 & 100 & 255 \\ 255 & 255 & 255 & 100 & 100 & 100 & 255 & 255 \\ 255 & 255 & 255 & 255 & 50 & 255 & 255 & 255 \\ 50 & 50 & 50 & 50 & 255 & 255 & 255 & 255 \end{bmatrix}$$

### 4. Approximating using SVD

- (a) Use the cameraman image and find its singular values
- (b) Choose some value  $k < n$ , where  $n$  is the rank of  $\Sigma$ , the singular matrix
- (c) Keep the first  $k$  singular values and the rest zeroes to get  $\hat{\Sigma}$
- (d) Reconstruct the image using these singular values
- (e) Calculate the error
- (f) Plot the error as a function of  $k$
- (g) Add some random noise to your input image and do similar approximation. Infer your results.