Complexity of Pivot Algorithms

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Abstract

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1 Introduction

Simplex method was invented by Dantzig in 1947 [3] to solve the Linear Optimization (LP) problem. It was tableau pivoting based method and pivoting under certain rules. The rules can be flexible so many simplex variants have been developed afterwards. Another framework of pivot algorithm is criss-cross method, which was proposed by Zionts at 1969 [4] and then [5], [1] present finite criss-cross version independently around 1980s. Some variant pivot methods appeared by proposing different pivots rules. We will describe them in the following section. Mention Short simplex paths Although simplex method was generally efficient in practical, theoretically, Klee and Minty [2] in 1970s showed the worst case that, a specific type of LO problem, a variant of simplex method visited all vertices (exponential steps) until solve the problem to be optimal. The feasible region of such problems was call Klee-Minty cube whose corners have been "squashed". We will demonstrate some examples in the following section. For now, it is still an unaccomplished problem that to design a pivot algorithm and prove that the number of pivot steps is bounded by polynomial of number of variables and constraints. The paper is structured as follows: in Section 2 we define the LO problem, list the notation and (might present some algorithms); in section 3 we discuss the complexity of pivot algorithms and give a brief conclusion in the final section.

2 The pivot algorithm for LO

In this paper, we consider the Linear optimization problem of the standard form

$$\min \quad c^T x$$
s.t. $Ax = b$

$$x \ge 0$$

$$x \in \mathbb{R}^n, \ c \in \mathbb{R}^n, \ A \in \mathbb{R}^{m \times n}, \ b \in \mathbb{R}^m$$
(1)

Table 1: Notation n number of variables m number of constraints (assume $m \le n$)

3 Complexity - worst case

Given m constraints and n variables, there are at most $\binom{n}{m}$ possible basis, which is a upper bound for the number of iterations for pivot algorithms. When $m = \frac{n}{2}$, $\binom{n}{m}$ get its maximum $\binom{n}{\frac{n}{2}} \approx \sqrt{\frac{2}{\pi n}} 2^n$. Klee and Minty defined a type of LO problems which many pivot algorithms will visit all the vertices to find the optimal solution. Detailed introduction of Klee Minty cube can be referred to [6]. Here we demonstrate some simple examples. For such problem

$$\max \sum_{j=1}^{n} 2^{n-j} x_j$$
s.t.
$$2 \sum_{j=1}^{i-1} 2^{i-j} x_j + x_i \le 5^i$$

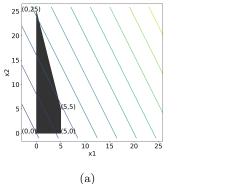
$$i = 1, \dots, n$$

$$x_j \ge 0$$

$$j = 1, \dots, n$$

When n=2 and n=3 the 2-d and 3-d Klee Minty LO problems are

$$\begin{array}{lllll} \max & 2x_1+x_2 & \max & 4x_1+2x_2+x_3 \\ \mathrm{s.t.} & x_1 \leq 5 & \mathrm{s.t.} & x_1 \leq 5 \\ & 4x_1+x_2 \leq 25 & 4x_1+x_2 \leq 25 \\ & x_1 \geq 0, \ x_2 \geq 0. & x_1 \geq 0, \ x_2 \geq 0, \ x_3 \geq 0. \end{array}$$



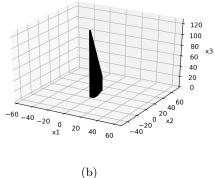


Figure 1: (a) Feasible region of 2-d Klee Minty Cube with contour lines (b) Feasible region of 3-d Klee Minty Cube

The feasible region of 2-d and 3-d Klee Minty problems are shown in Figure 1. It can be illustrated that they look like "squashed" square and cube, which are very ill-conditioned. We apply primal simplex method (a) least-index version and (b) Dantzig (the nonbasis with biggest reduced cost enters) pivot rules to demonstrate the number of pivot steps. The tableau result of least-index pivot rule is shown in Table 2. Note the results of Dantzig pivot rule and least-index rule coincide.

Table 2: Tableau of primal simplex method (least index version), the element with a * is the pivot element.

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	rhs	x_1	x_2	s_1	s_2	
\overline{z}	0	2	1	0	0	at vetex $(0,0)$
s_1	5	1*	0	1	0	
s_2	25	4	1	0	1	
\overline{z}	-10	0	1	-2	0	at vetex $(5,0)$
x_1	5	1	0	1	0	
s_2	5	0	1*	-4	1	
\overline{z}	-15	0	0	2	-1	at vetex $(5,5)$
x_1	5	1	0	1*	0	
x_2	5	0	1	-4	1	
\overline{z}	-25	-2	0	0	-1	at vetex $(0,25)$
s_1	5	1	0	1	0	
x_2	25	4	1	0	1	

4 Conclusion

Conclusion...

References

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