

# 1 Background

Given data  $(y_i, x_i, z_i), i = 1, \dots, n$  with outcome  $y_i \in \mathbb{R}$ , covariates  $x_i \in \mathbb{R}^p$  and effect modifiers  $z_i \in \mathbb{R}^q$  one assumes the varying coefficient model

$$y_i = \sum_{j=1}^p x_{ij} \beta_j(z_i) + \varepsilon_i = x_i^T \beta(z_i) + \varepsilon_i, \quad (1)$$

[2]. The coefficients  $\beta(\cdot) = (\beta_1(\cdot), \dots, \beta_p(\cdot))^T$  determine a (rather simple) functional, relationship between outcome  $y$  and (likely low dimensional) covariate  $x$ . The coefficients themselves are considered to be (potentially complex) functions of the (potentially high dimensional) effect modifier  $z$ .

Each varying coefficient mapping  $\beta_j(\cdot)$  is estimated using an ensemble of gradient boosted decision trees. This is done by iteratively minimizing a loss function

$$L(y, \beta) = \sum_{i=1}^n l(y_i, x_i^T \beta(z_i)). \quad (2)$$

The generic gradient boosting algorithm described in [1]. Is adapted for the varying coefficient scenario. The resulting procedure is sketched in Algorithm 1 below. A similar algorithm has already been described by [3].

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## Algorithm 1 VCBoost

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- 1:  $\beta_j^{(0)}(z) = 0, j = 1, \dots, p$
  - 2: **for**  $m = 1, \dots, \text{maxiter}$  **do**
  - 3:   **for**  $j = 1, \dots, p$  **do**
  - 4:      $\tilde{y}_i = -\frac{\partial l(y_i, x_i^T \beta_j^{(m-1)}(z_i))}{\partial \beta_j^{(m-1)}(z_i)} \quad \triangleright \text{negative gradient wrt. } \beta_j$
  - 5:      $h = \text{regression tree fit on } \{\tilde{y}_i, z_i\}_{i=1, \dots, n}$
  - 6:      $\rho = \text{argmin}_{\rho} [\sum_{i=1}^n l(y_i, x_i^T \beta_j^{(m-1)}(z_i) + \rho h(z_i) x_{ij})] \quad \triangleright \text{line search}$
  - 7:      $\beta_j^{(m)}(\cdot) = \beta_j^{(m-1)}(\cdot) + \rho h(\cdot)$
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The pseudoresponses  $\tilde{y}_i$  in Line 4 are obtained by noting that

$$\tilde{y}_i = -\frac{\partial l(y_i, x_i^T \beta_j^{(m-1)}(z_i))}{\partial \beta_j^{(m-1)}(z_i)} = -\frac{\partial l(y_i, x_i^T \beta_j^{(m-1)}(z_i))}{\partial x_i^T \beta_j^{(m-1)}(z_i)} x_{ij} \quad (3)$$

and the derivative remaining on the right hand side is the usual gradient based on the previous fitted responses  $x_i^T \beta_j^{(m-1)}(z_i)$ . Hence, this is easily determined for common loss functions. Also this part of the pseudo response is the same, regardless of the coordinate ( $j = 1, \dots, p$ ) currently handled in the inner loop.

A variation of the algorithm only computes  $\frac{\partial l(y_i, x_i^T \beta_j^{(m-1)}(z_i))}{\partial x_i^T \beta_j^{(m-1)}(z_i)}$  once during the outer loop and then updates all coefficient estimates before recomputing.

Also the line search determining the step size  $\rho$  can be done globally, e.g. determining one  $\rho$  based on all observations  $i = 1, \dots, n$  as shown above. Alternatively,

the line search can be done separately for each leaf in the regression tree  $h$  (see Eq. (18) in [1]).

As usual one can also introduce a learning rate  $< 1$  to shrink the step size for the update in row 7 of the algorithm.

Finally there would also be many hyper-parameters controlling the tree building process in line 5.

## 1.1 Details for specific loss functions

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## References

- [1] Jerome H Friedman. “Greedy function approximation: a gradient boosting machine”. In: *Annals of statistics* (2001), pp. 1189–1232.
- [2] Trevor Hastie and Robert Tibshirani. “Varying-coefficient models”. In: *Journal of the Royal Statistical Society: Series B (Methodological)* 55.4 (1993), pp. 757–779.
- [3] Yichen Zhou and Giles Hooker. “Tree boosted varying coefficient models”. In: *arXiv preprint arXiv:1904.01058* (2019).