

Link between curves and M theoretical distributions

(Duane will cover this part I think)

Partition the mass and accretion time into M combinations of \mathcal{M}, \mathcal{T} where

$$\text{Sat. stellar mass: } \bigcup \mathcal{M}_j = [0, 10^9] M_{\odot}$$

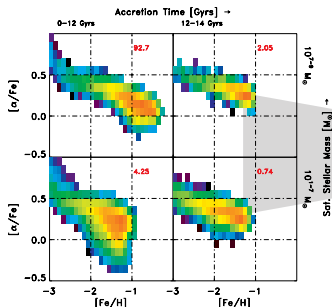
$$\text{Accretion time: } \bigcup \mathcal{T}_j = [0, 14] \text{Gyr}$$

$$f_j(x, y) = P(x, y | \text{Mass} \in \mathcal{M}_j, \text{Accretion time} \in \mathcal{T}_j)$$

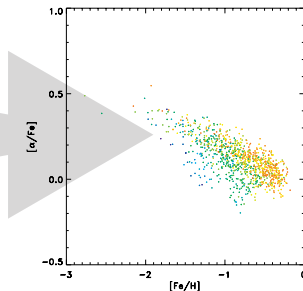
Each observation is generated from one of these M theoretical distributions

$$\left[\frac{Fe}{H}, \frac{\alpha}{Fe} \right]_{i=1}^N \text{ i.i.d} \sim F(x, y) = \sum_{j=1}^M \pi_j f_j(x, y)$$

Theoretical halo distributions



Observations



Finding the mixing proportions π

Standard maximum likelihood estimates of π won't work

$$\log L(\pi) = \sum_{i=1}^n \log \left(\sum_{j=1}^m \pi_j f_j(x_i, y_i) \right)$$

Suppose we knew which f_j each observation came from:

$$z_{ij} = \begin{cases} 1 & \text{if } (x_i, y_i) \sim f_j \\ 0 & \text{otherwise} \end{cases}$$

Then

$$\log L(\pi) = \sum_{i=1}^n \sum_{j=1}^m z_{ij} \log \{ \pi_j f_j(x_i, y_i) \} \quad (1)$$

Finding $\hat{\pi}$ using expectation maximization

- ▶ Find the expected value of the log likelihood, given the data
- ▶ Find the $\operatorname{argmax}_{\pi}$ of this expectation
- ▶ Repeat until $\log L(\pi)$ stabilizes

Find the expected value of the log likelihood, given the data

$$E_{\pi} \left[\log L(\pi) | \mathbf{x}, \mathbf{y} \right] = \sum_{i=1}^n \sum_{j=1}^m E_{\pi} [z_{ij} | x_i, y_i] \{ \log f_j(x_i, y_i) + \log \pi_j \}$$

$$\begin{aligned} \hat{w}_{ij}^{(t)} &= E_{\pi} [z_{ij} | x_i, y_i] \\ &= \Pr_{\pi}(z_{ij} | x_i, y_i) \\ &= \frac{p(x_i, y_i | z_{ij} = 1) p(z_{ij} = 1)}{p(x_i, y_i)} \\ &= \frac{\pi_j f_j(x_i, y_i)}{\sum_{j=1}^m \pi_j f_j(x_i, y_i)} \end{aligned}$$

Find the $\operatorname{argmax}_{\pi}$ of this expectation

$$\hat{\pi}^{(t)} = \operatorname{argmax}_{\pi} \mathbb{E} \left[\log L(\pi) | \mathbf{x}, \mathbf{y}, \hat{\pi}^{(t-1)} \right]$$

Accounting for the $m - 1$ free parameters of π , differentiation proceeds, for $k = 1, \dots, m - 1$, as:

$$\frac{\partial}{\partial \pi_k} \mathbb{E} \left[\log L(\pi) | \mathbf{x}, \mathbf{y} \right] = \sum_{i=1}^n \left\{ w_{ik}^{(t-1)} \frac{1}{\pi_k} - w_{im}^{(t-1)} \frac{1}{1 - \pi_1 - \dots - \pi_{m-1}} \right\}$$

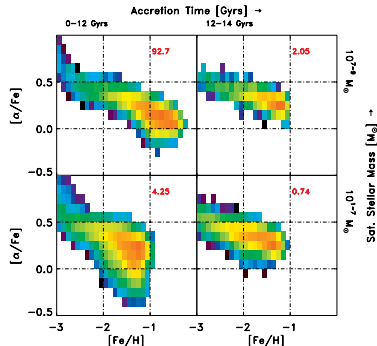
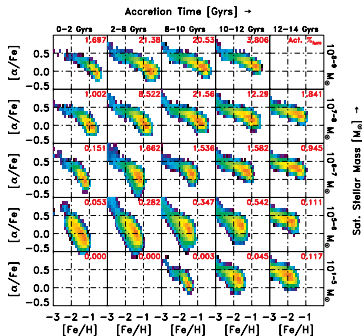
$$\frac{1}{\pi_k} \sum_{i=1}^n w_{ik}^{(t-1)} = \frac{1}{1 - \pi_1 - \dots - \pi_{m-1}} \sum_{i=1}^n w_{im}^{(t-1)}$$

Consequently

$$\hat{\pi}_k^{(t)} = \frac{\sum_{i=1}^n w_{ij}^{(t-1)}}{n}$$

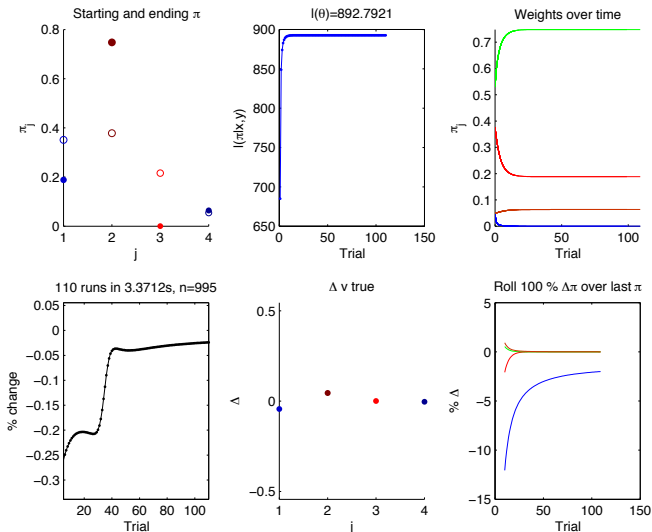
$$\hat{\pi}_m^{(t)} = 1 - \pi_1 - \dots - \pi_{m-1}$$

We used a 5x5 and a 2x2 set of theoretical distributions

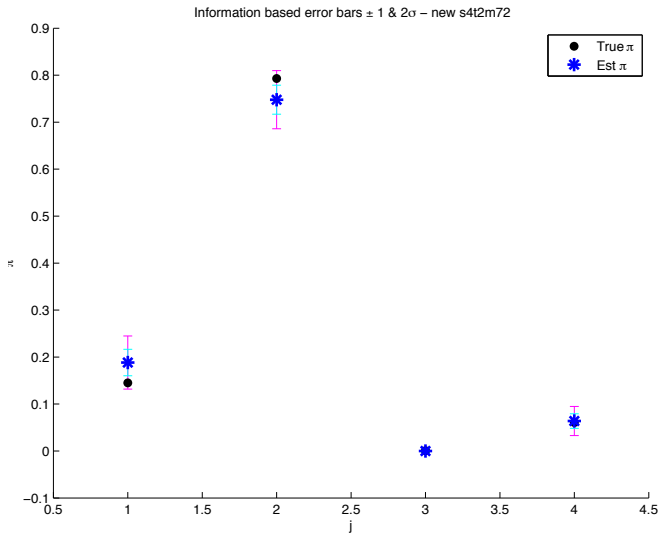


Simulation results

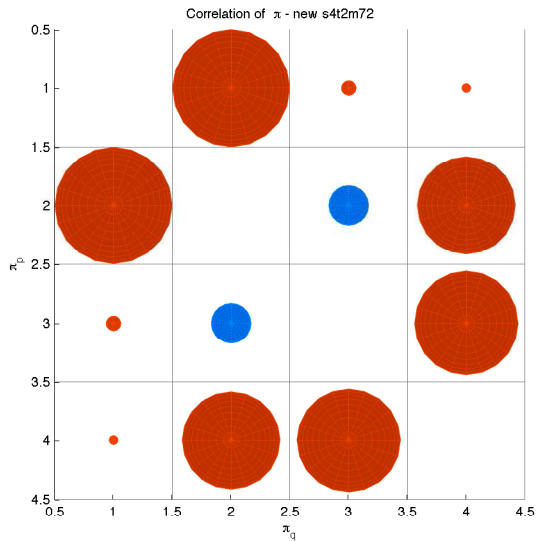
Works starting at about 1,000 observations, although larger π values are found with smaller data sets.



Confidence intervals



Correlation between π



Conclusion

Worked

- ▶ 2x2
- ▶ EM
- ▶ 5x5 in a few cases
- ▶ M-of-n bootstrapped errors

Did not work

- ▶ 5x5
- ▶ Parametric bootstrapped errors

Future improvements

- ▶ Non-arbitrary gridding
- ▶ Smoothing of f_j