

Exploring biological shape analysis through topology, geometry and statistics

Ph. D. summer school: Biomedical image analysis, 2024/08/13

Jon Sparring,
Department of Computer Science

UNIVERSITY OF COPENHAGEN



AI is pretty good at segmenting stuff, what's next?

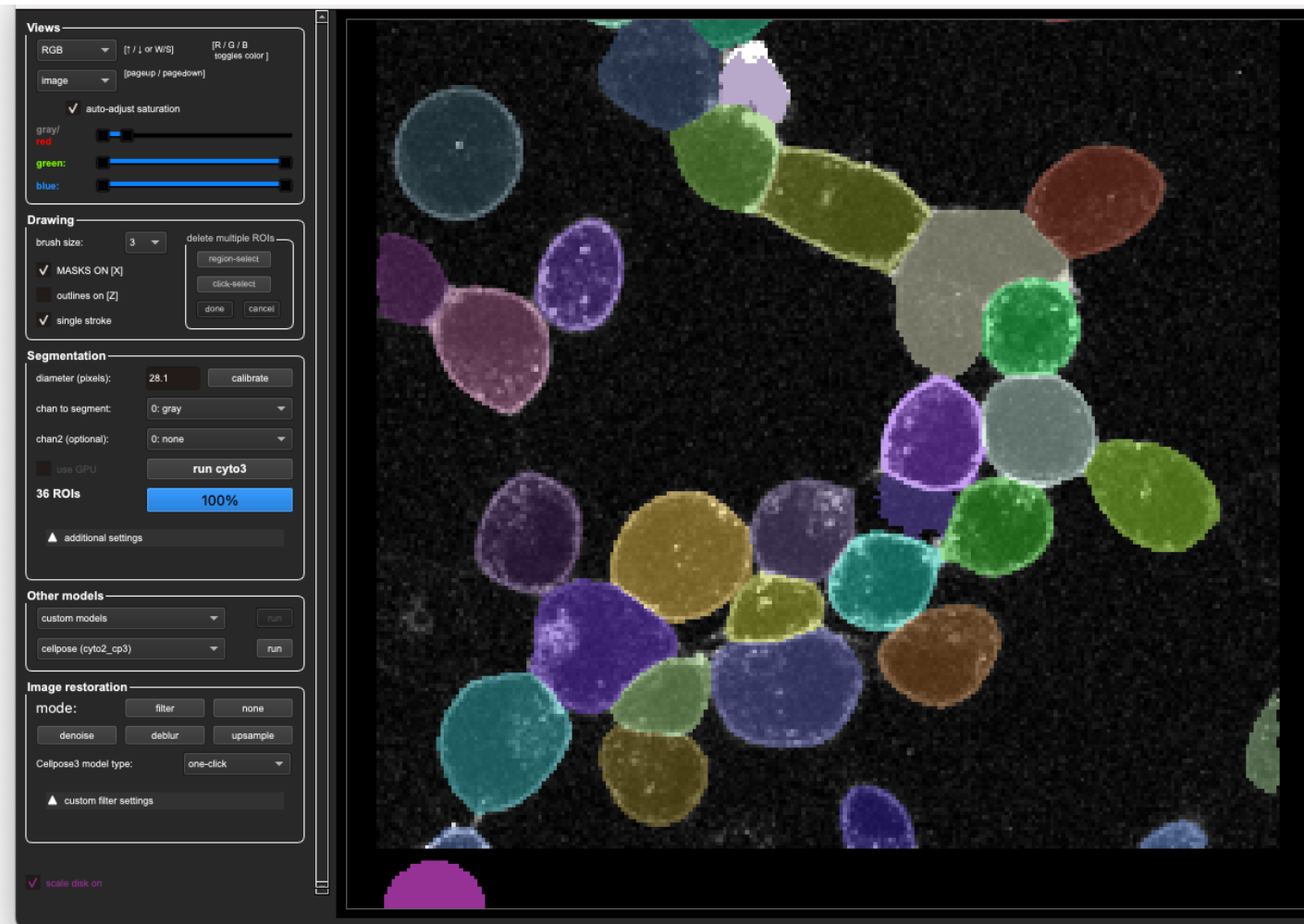


Image courtesy: Karen Martinez & Gabriella von Scheel von Rosing; AI: <http://www.cellpose.org/>

What to do next: Shape analysis

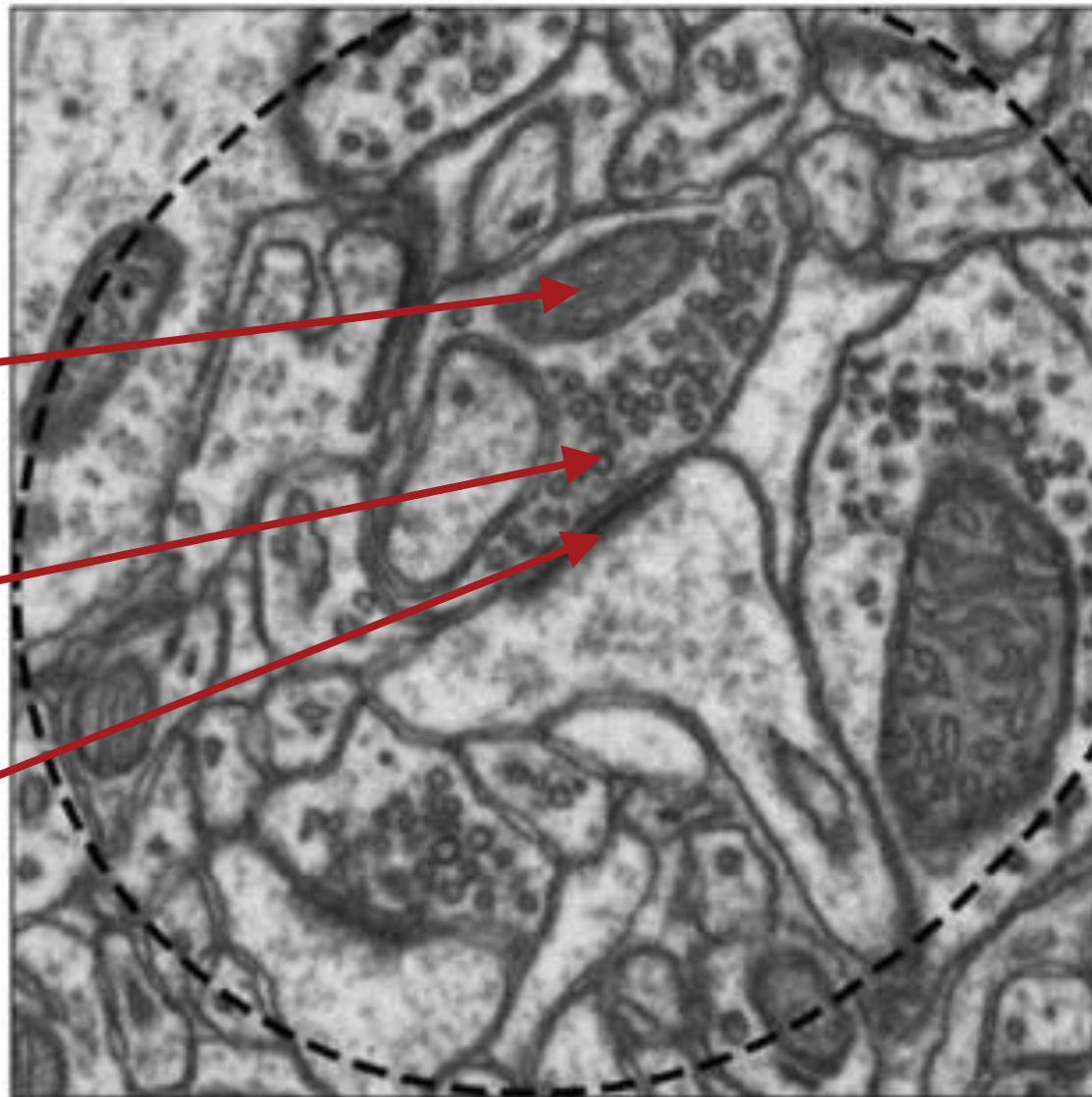
Focused ion-beam
scanning electron
microscopy (FIB-SEM)

Voxel size: $(5 \text{ nm})^3$

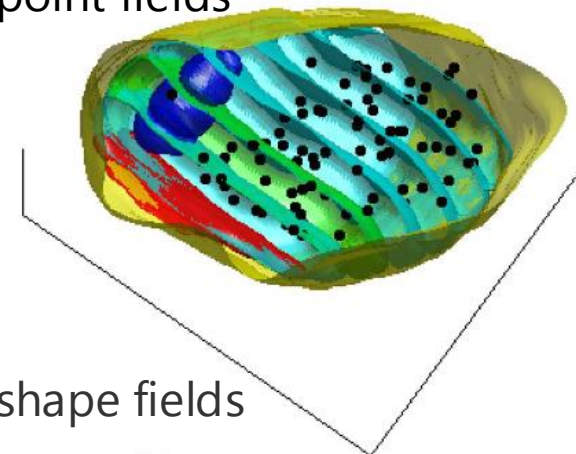
Mitochondria

Vessicles

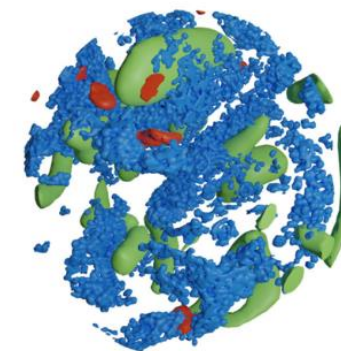
Active zone



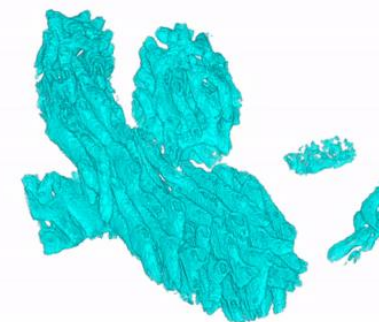
Spatial point fields



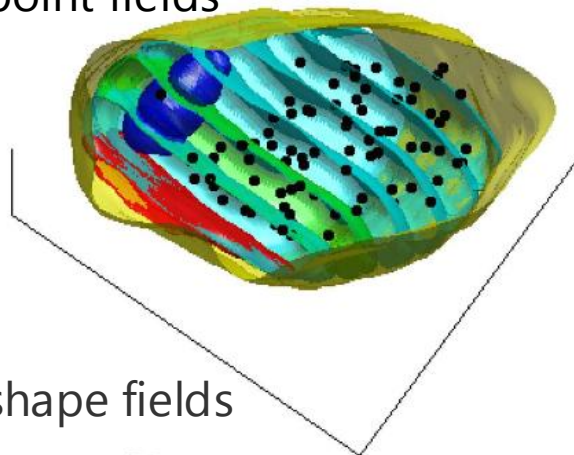
Spatial shape fields



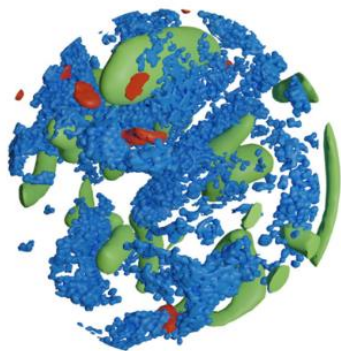
Topological data analysis



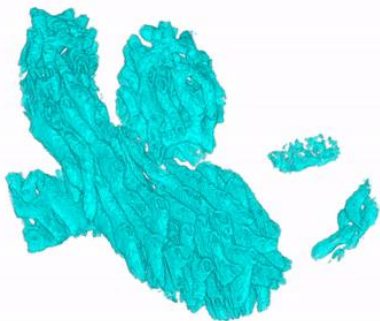
Spatial point fields



Spatial shape fields



Topological data analysis



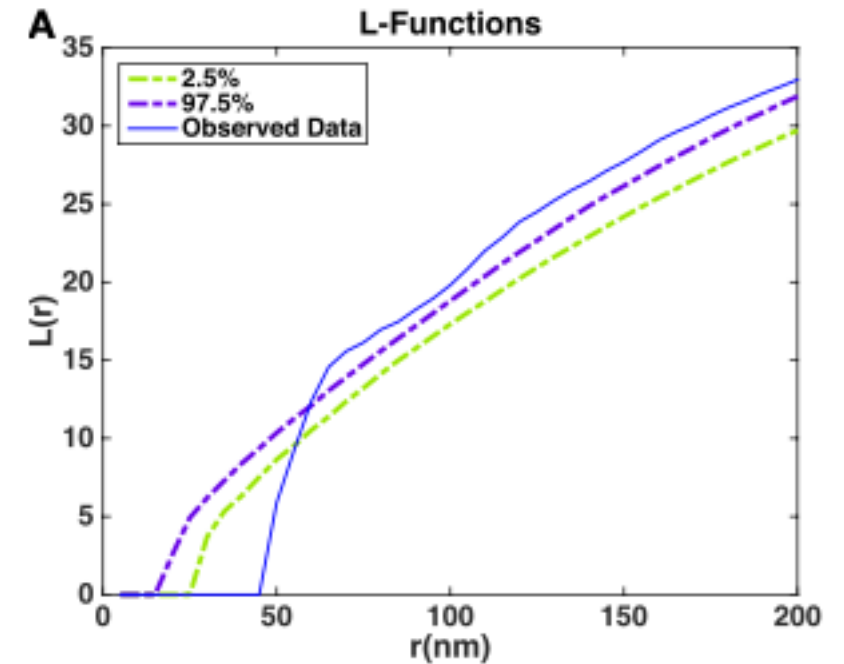
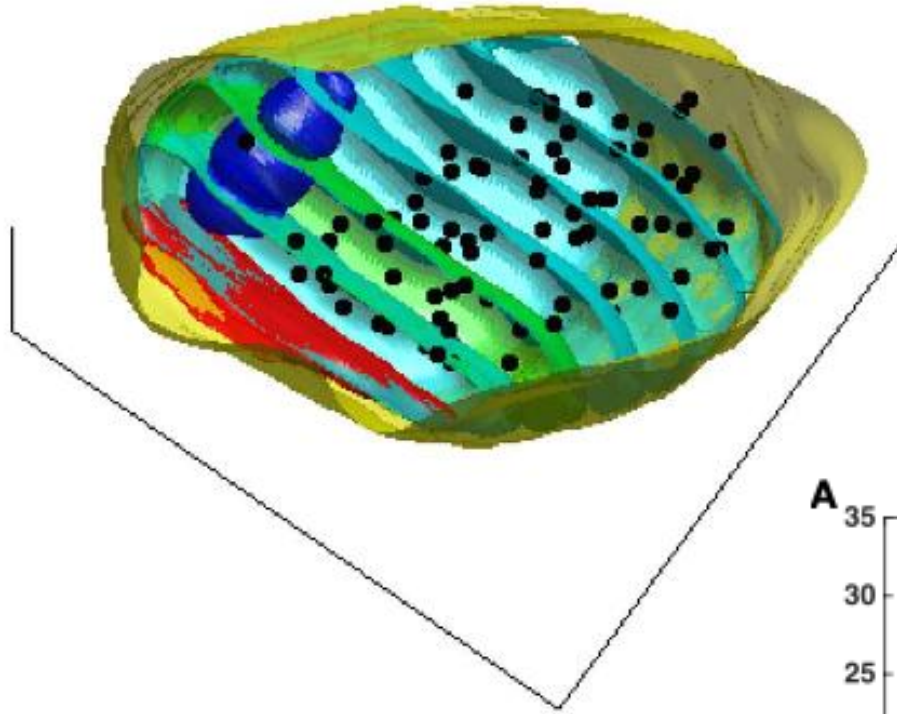
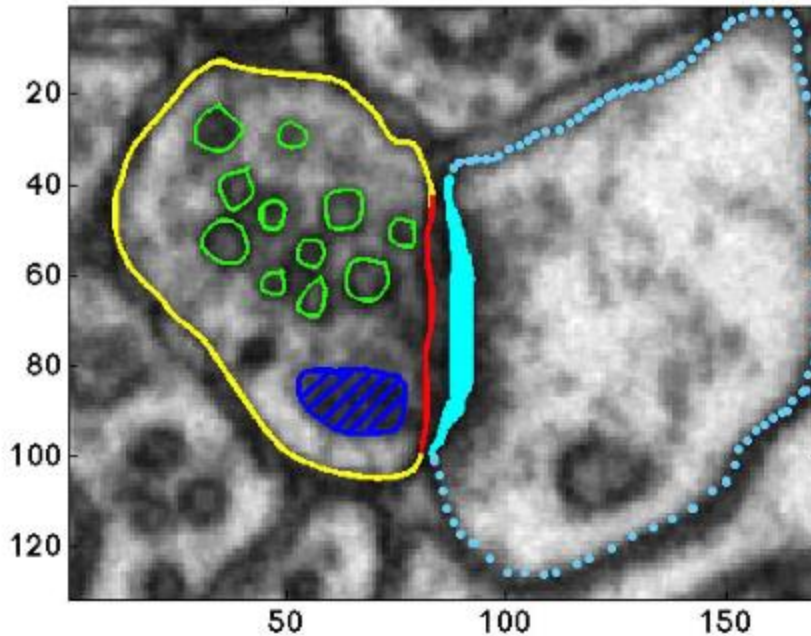
Literature

- Analysis of shape and spatial interaction of synaptic vesicles using data from focused ion beam scanning electron microscopy (FIB-SEM); M Khanmohammadi, RP Waagepetersen & J Sparring, *Frontiers in Neuroanatomy*, 2015
- Stoyan, D. (2006). *Fundamentals of Point Process Statistics*. In: Baddeley, A. et al. (eds) *Case Studies in Spatial Point Process Modeling*. *Lecture Notes in Statistics*, vol 185. Springer
- Mrkvička, Tomáš, et al. "A one-way ANOVA test for functional data with graphical interpretation." *Kybernetika* 56.3 (2020): 432-458.
- Stephensen, H.J.T., Svane, A.M., Villanueva, C.B. et al. Measuring Shape Relations Using r-Parallel Sets. *J Math Imaging Vis*, vol 63, 2021.
- Chazal F., Michel B., *An Introduction to Topological Data Analysis: Fundamental and Practical Aspects for Data Scientists*, In: *Frontiers in Artificial Intelligence*, vol 4, 2021

1. Spatial point fields



section202



Analysis of shape and spatial interaction of synaptic vesicles using data from focused ion beam scanning electron microscopy (FIB-SEM); M Khanmohammadi, RP Waagepetersen & J Sparring, *Frontiers in Neuroanatomy*, 2015

Ripley's K- and L-functions: expected number of neighboring points by radius

$$K(r) = \frac{1}{\lambda} \mathbb{E}[I(d_{ij} < r)]$$

(homogeneous|stationary|uniform) Poisson [point] (process|field)

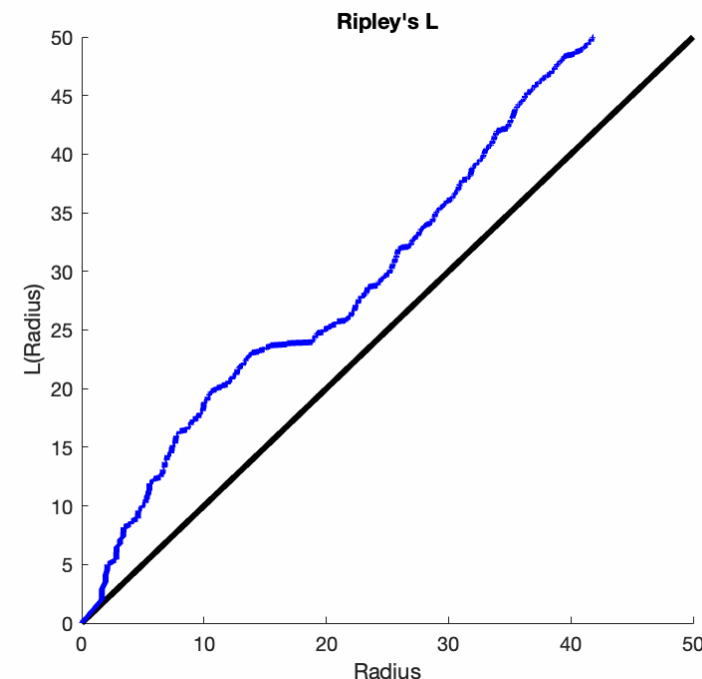
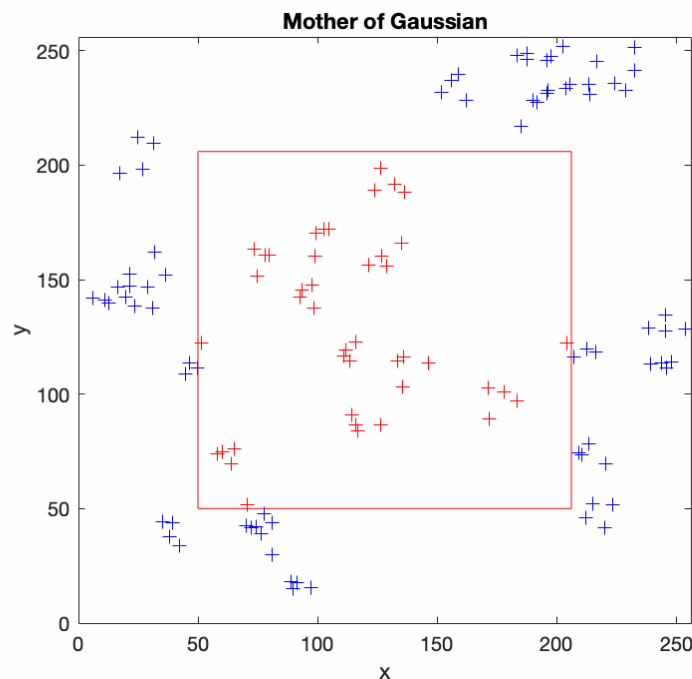
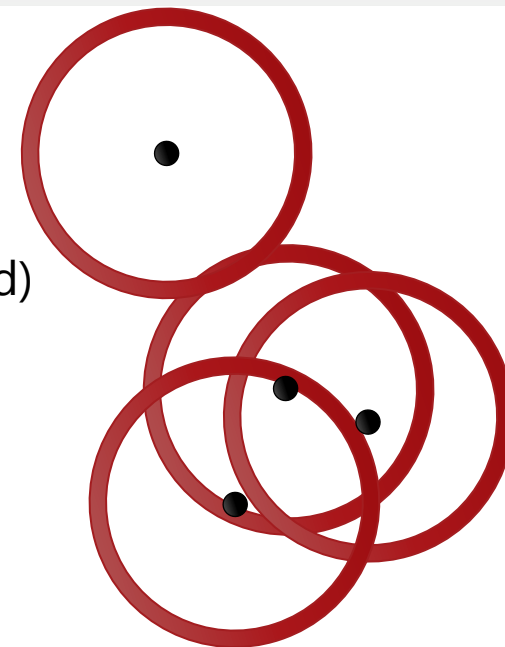
Euclidean d -space

$n \sim \text{Poisson}$

$x \sim \text{Uniform}$

$$L(r) = \sqrt{\frac{K(r)}{\pi}}$$

$$2\text{-space: } \lim_{n \rightarrow \infty} K(r) = \pi r^2$$



R and rpy2 demo:

<https://sporrington.github.io/bia2024/talk.pdf>

https://sporrington.github.io/bia2024/spatstat_bia2024.zip

<https://cran.r-project.org/>

<https://spatstat.org/>

<https://cran.r-project.org/web/packages/GET/vignettes/pointpatterns.pdf>

demoRpy2.py: Installation instructions for R, R-packages, and python packages:

```
# 1. Install R, which to my experience works best directly from https://cran.r-project.org/  
# then start R and install some packages:  
# install.packages("spatstat")  
# install.packages("lazyeval")  
# install.packages("GET")  
...
```

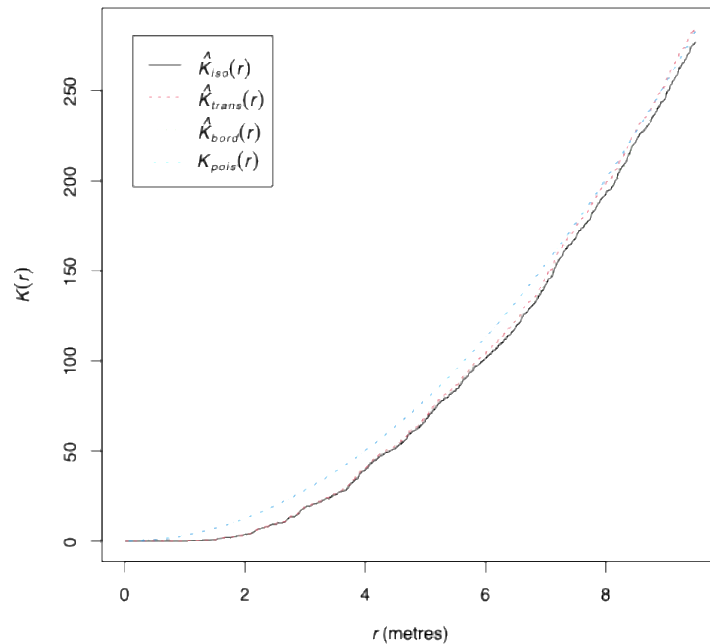
GETDemo.r

```
library("GET")
library("spatstat.model")
library("ggplot2")
X <- spruces
print(X)
plot(X)
k <- Kest(X)
print(k)
plot(k)
env <- envelope(X, nsim=1999, savefuns=TRUE, simulate=expression(runifpoint(ex=X)), verbose=FALSE)
print(env)
plot(env)
res <- global_envelope_test(env)
print(res)
plot(res)
```

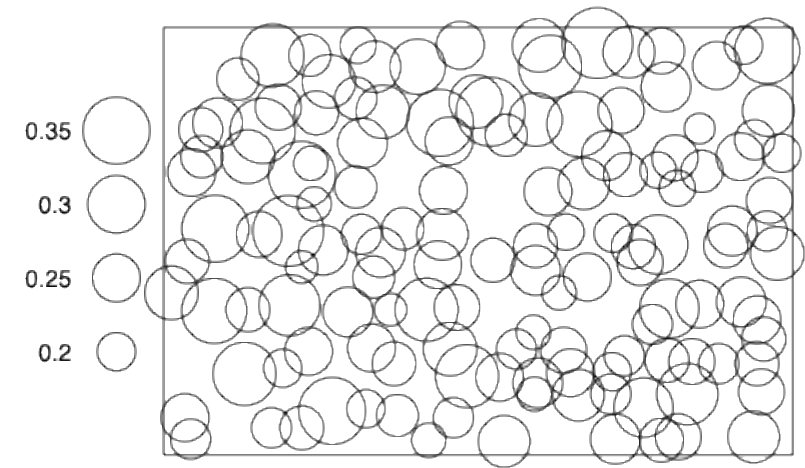
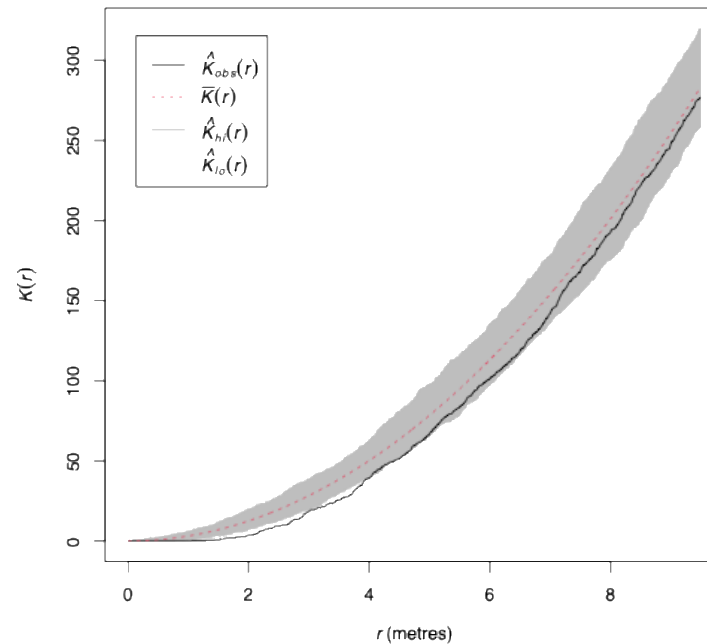
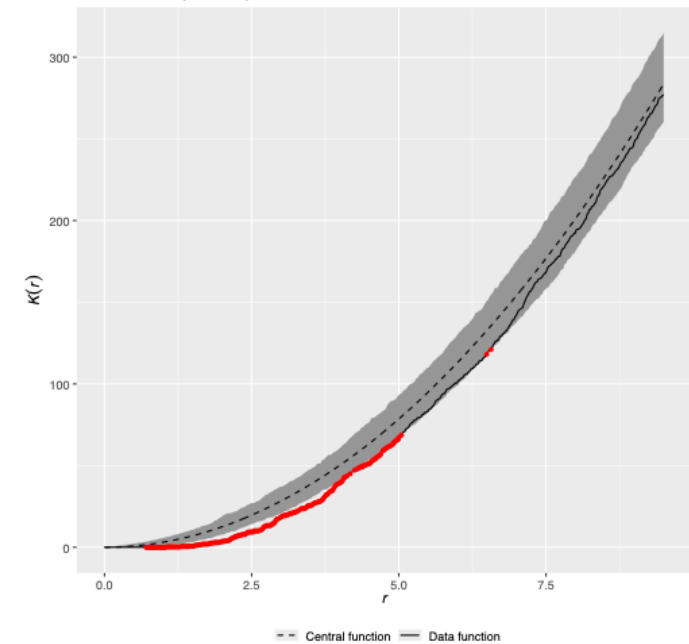

GETDemo.r

```
library("GET")
library("spatstat.model")
library("ggplot2")
X <- spruces
print(X)
plot(X)
k <- Kest(X)
print(k)
plot(k)
env <- envelope(X, nsim=1999, savefuns=TRUE, simulate=expression(runifpoint(ex=X)), verbose=FALSE)
print(env)
plot(env)
res <- global_envelope_test(env)
print(res)
plot(res)
```

k



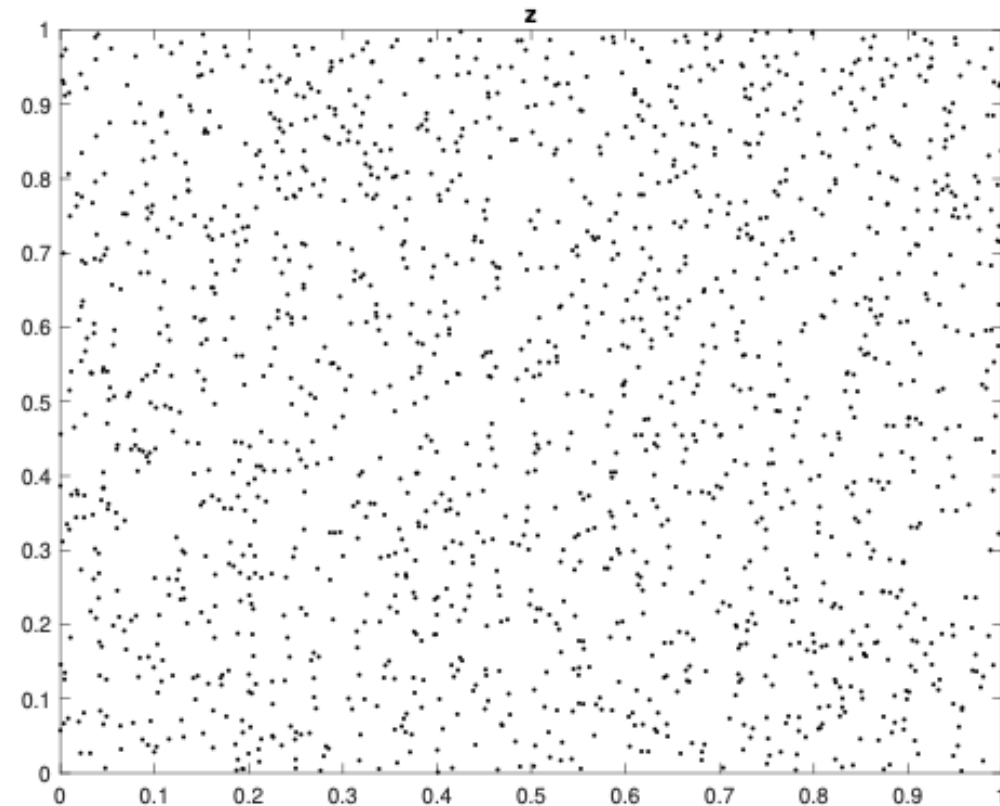
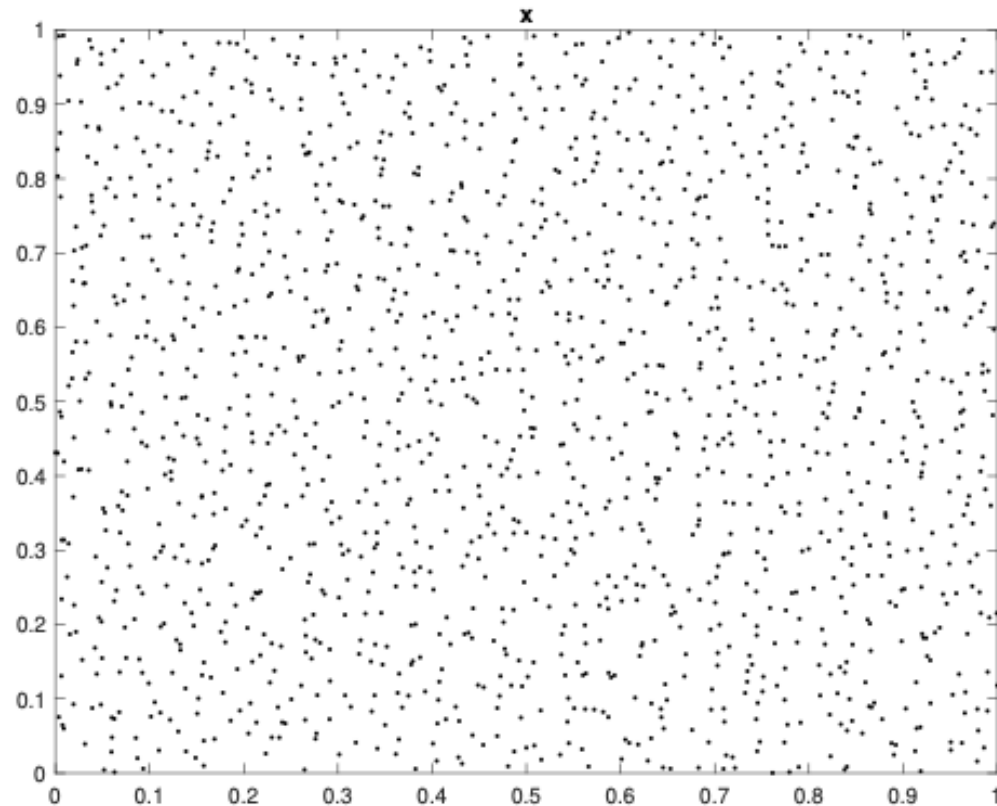
env

Global envelope test: $p < 0.001$ 

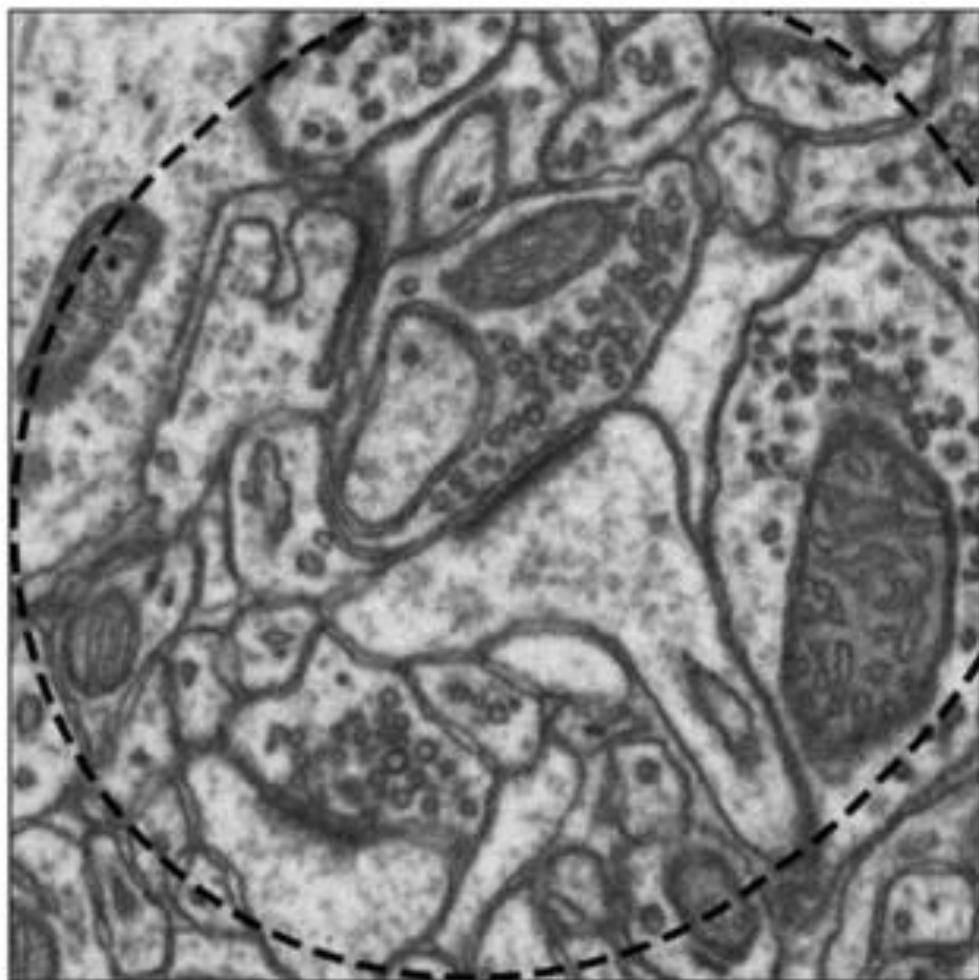
demoRpy2.py

```
40 # first we import a bunch of basic stuff and prepare working with rpy2
41 import rpy2
42 import rpy2.robjects as robjects
43 from rpy2.robjects.packages import importr
44 import matplotlib.pyplot as plt
45 import numpy as np
46 from rpy2.robjects import FloatVector
47 base = importr('base')
48 spatstat = importr('spatstat')
49 # shortcut
50 ro = robjects.r
51
52 # The following is an example of how to create a random 2-dimensional point pa
```

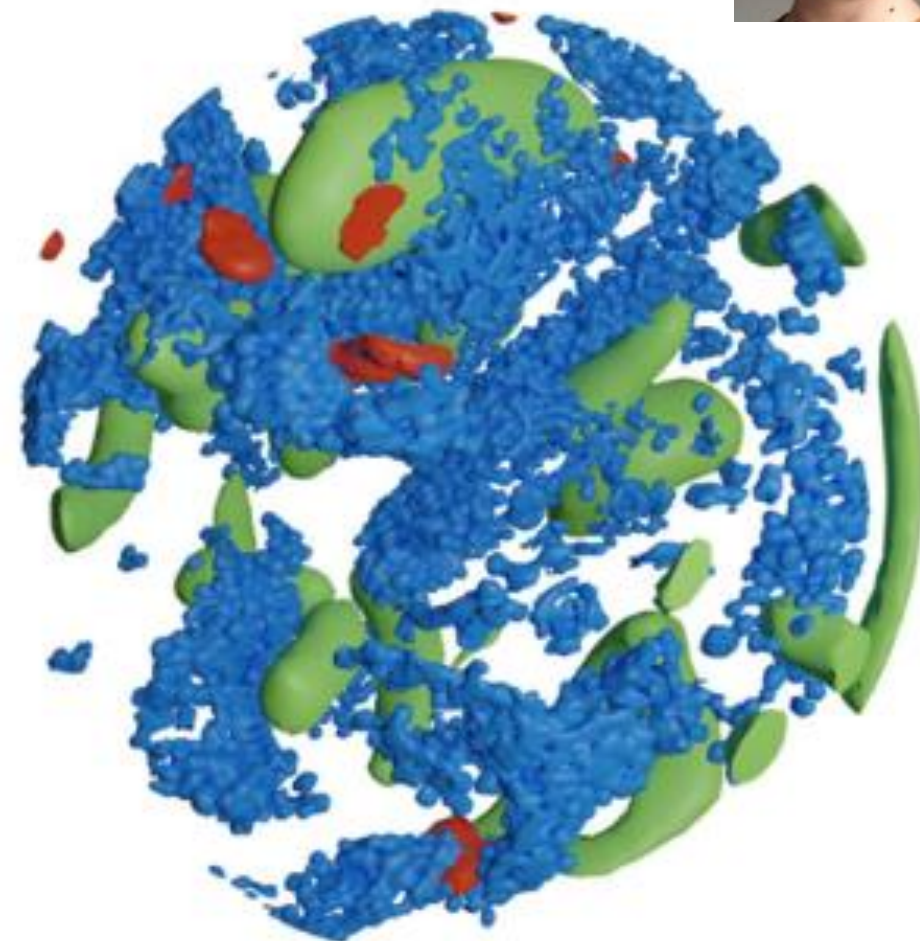
Exercise: Use GET's `global_envelope_test` to test whether `x.csv` and/or `z.csv` are likely to be random



2. Spatial shape fields: Real structures are not points, small structures are difficult to separate

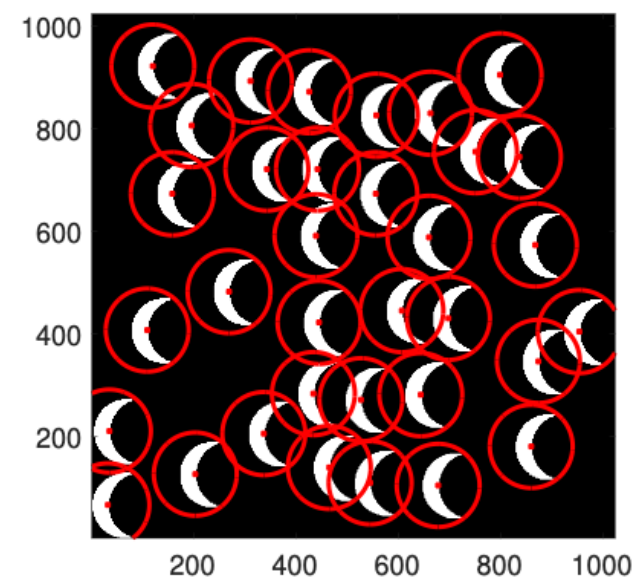
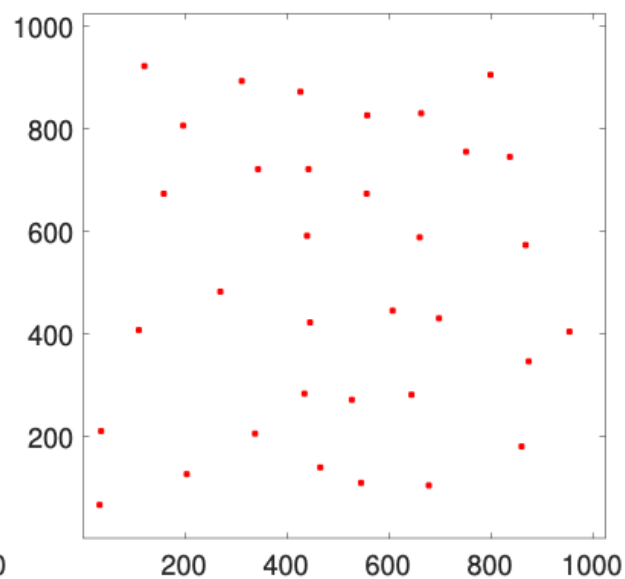
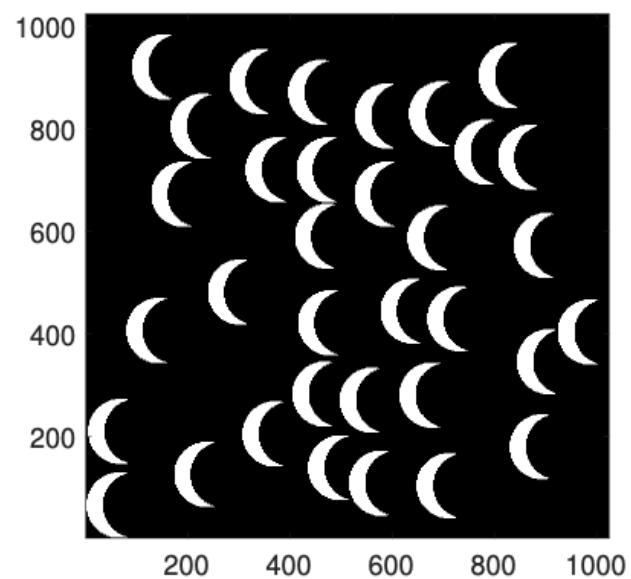
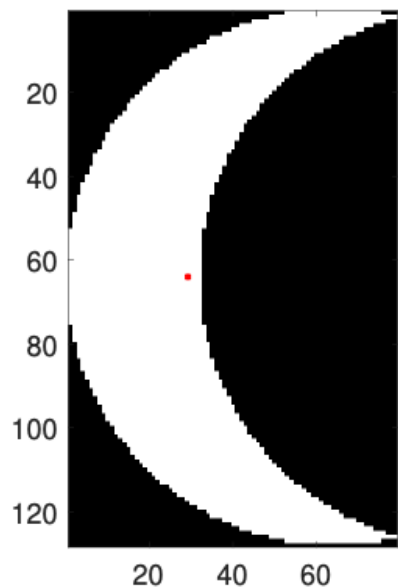


Deep Learning

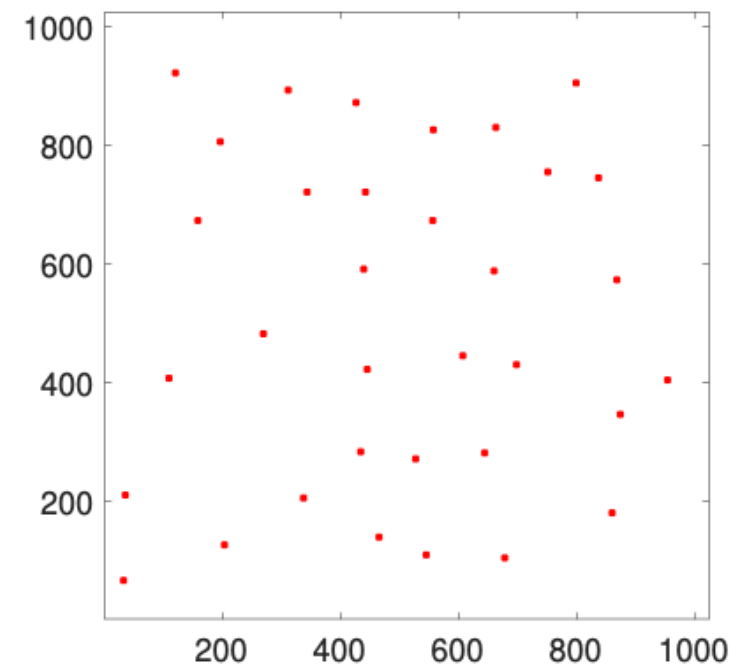
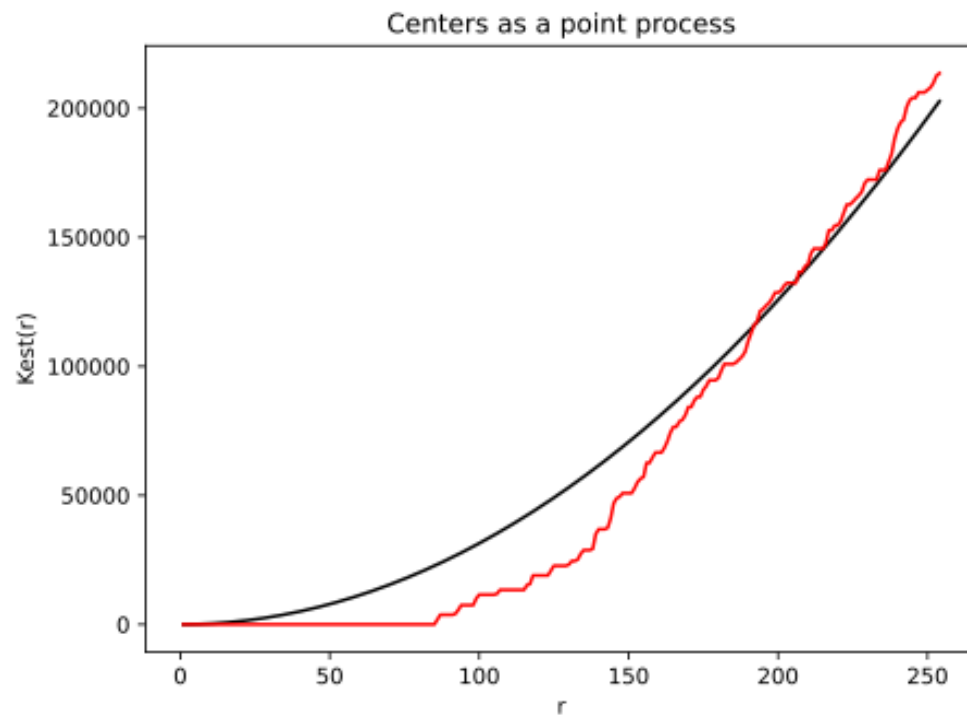
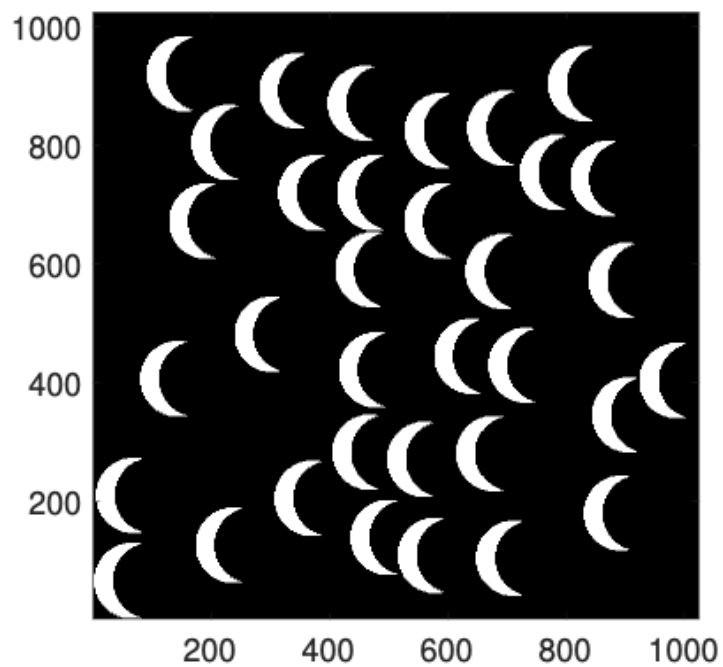


Measuring Shape Relations Using r-Parallel Sets; HJT Stephensen, AM Svane, CB Villanueva, SA Goldman, & J Sparring; Journal of mathematical imaging and vision, 2021

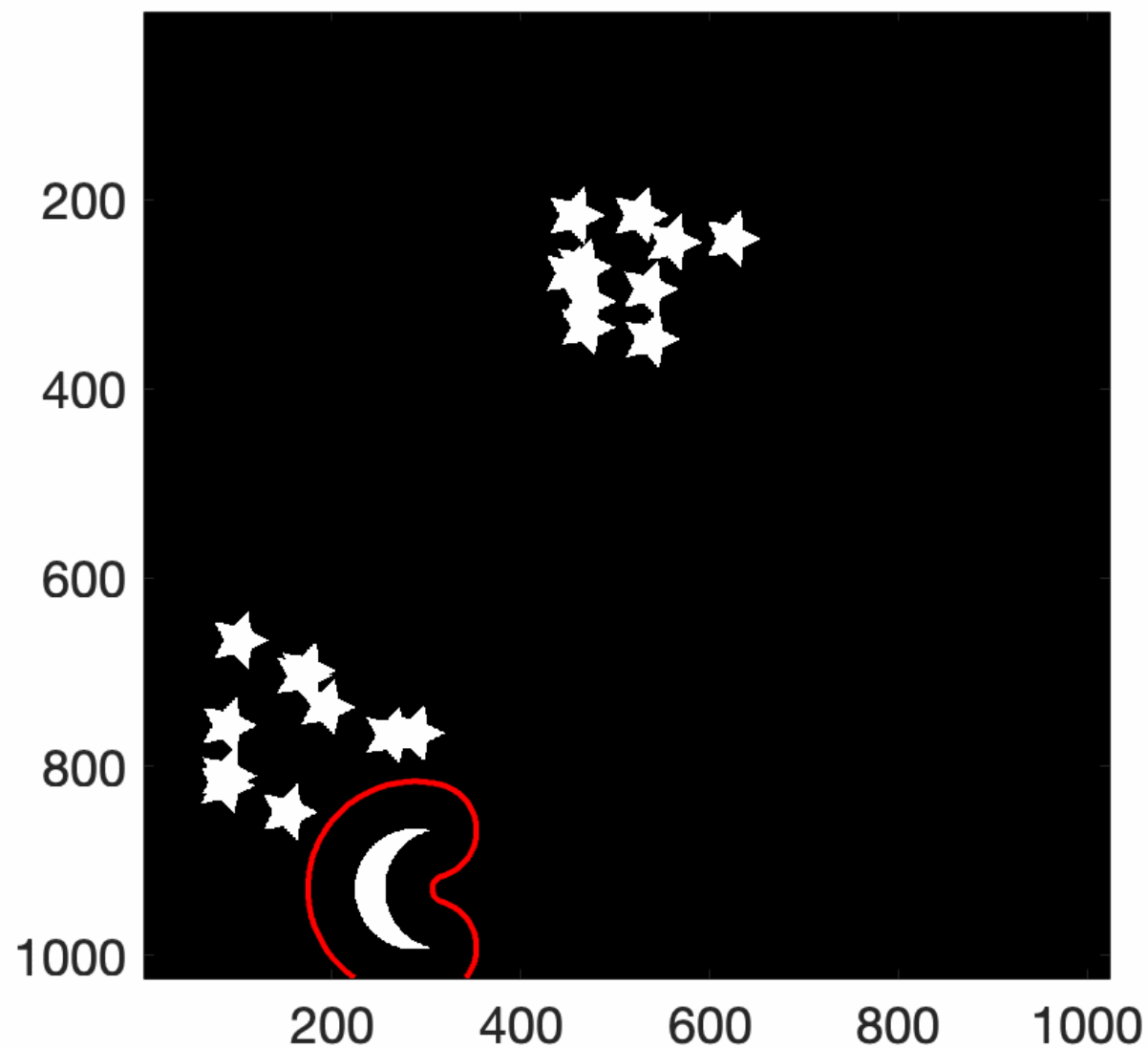
Not all shapes are well summarized as a reference point



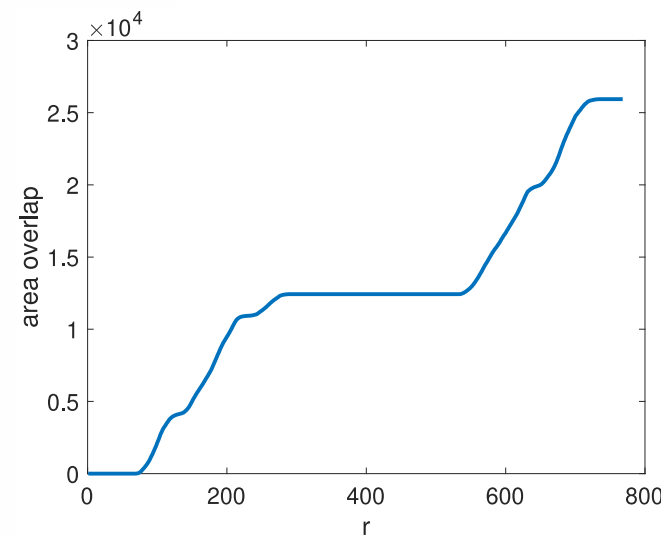
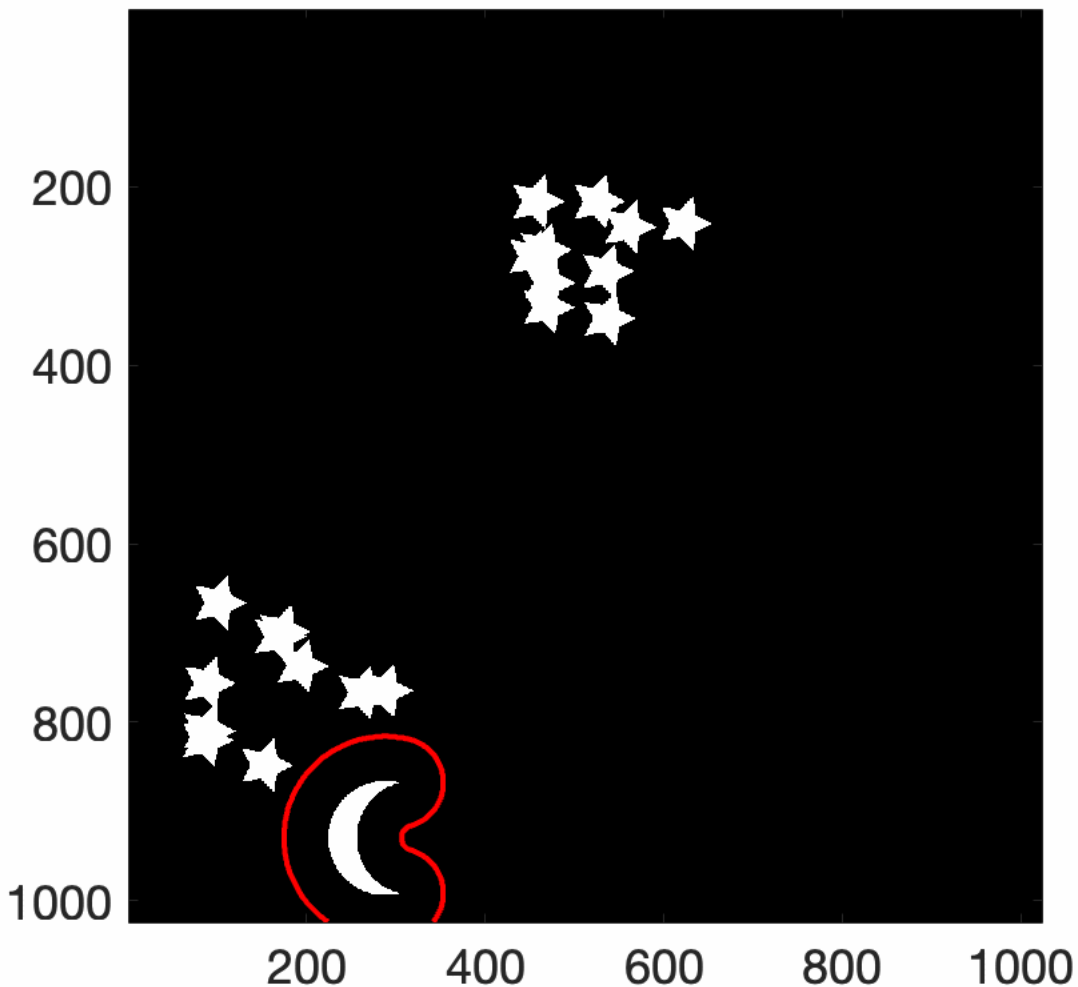
Ripley's K-function indicates strong repulsion



Shape relation measures = Interaction with distance fields



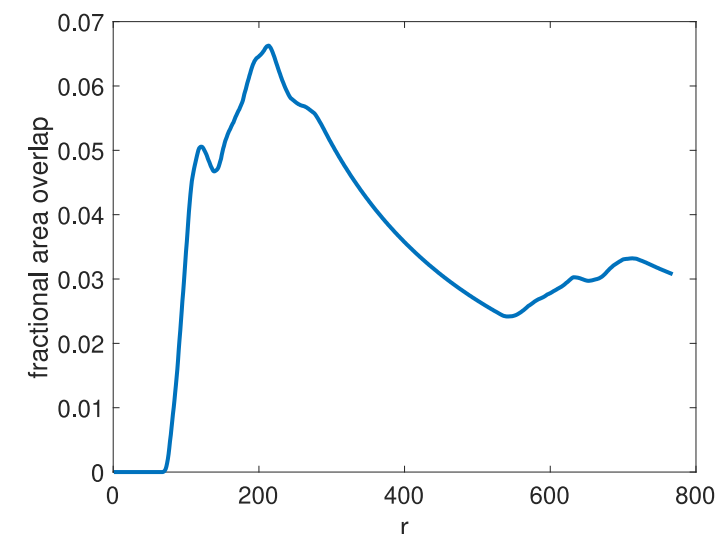
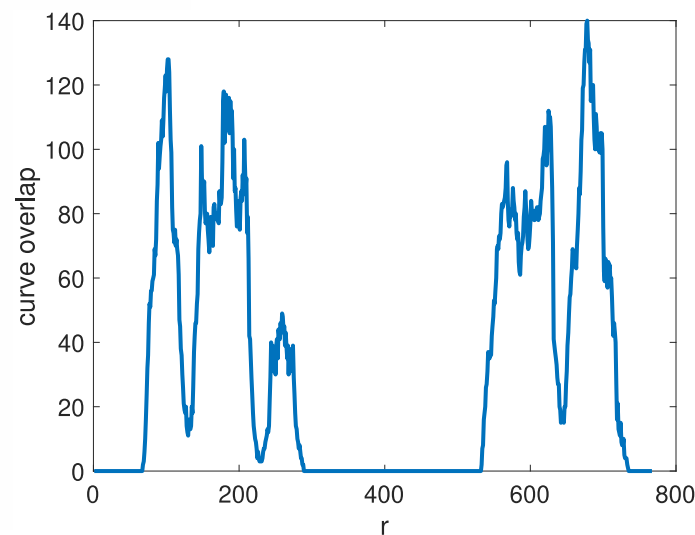
Shape relation measures: Some characteristic functions



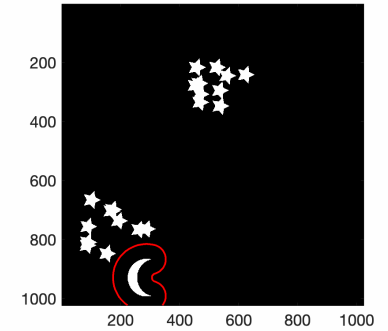
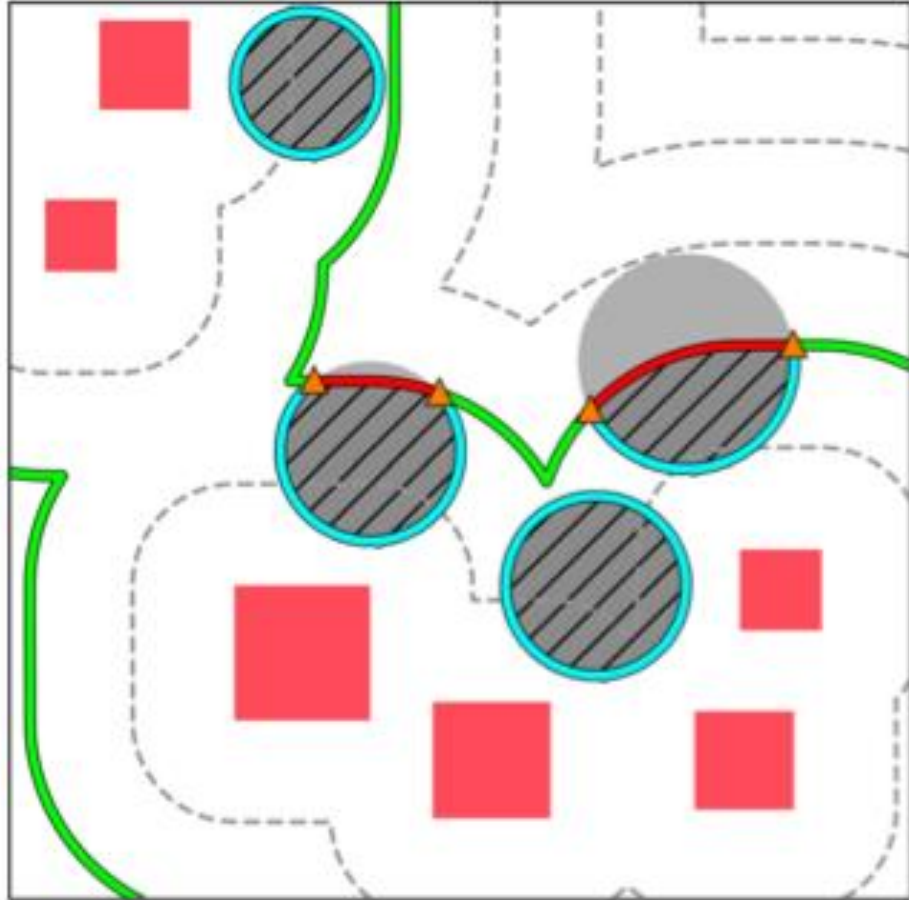
$$\mu_{00}(r) = \mathcal{H}(X \cap Y^r)$$

$$g_{00}(r) = \frac{d\mu_{00}(r)}{dr} = \mu_{01}(r)$$

$$f_{00}(r) = \frac{\mu_{00}(r)}{\mathcal{H}(Y^r)}$$







There can be only 4



$$Y^r = \{\alpha \in \mathbb{R}^d \mid \inf_{y \in Y} d(\alpha, y) \leq r\} \quad (1)$$

$$\mu_{\varepsilon, \varepsilon'}(X, Y^r) = \mathcal{H}^{d-\varepsilon-\varepsilon'}(\partial^\varepsilon X \cap \partial^{\varepsilon'} Y^r) . \quad (2)$$

$d = 2$	$(\varepsilon, \varepsilon')$	$\mathcal{H}^{d-\varepsilon-\varepsilon'}$	$\partial^\varepsilon X \cap \partial^{\varepsilon'} Y^r$	Interpretation of $\mu_{\varepsilon, \varepsilon'}(X, Y^r)$
	(0, 0)	Area	$X \cap Y^r$	Area of intersection
	(0, 1)	Curve length	$X \cap \partial Y^r$	Boundary length of intersection inside interior of X
	(1, 0)	Curve length	$\partial X \cap Y^r$	Boundary length of intersection inside boundary of X
	(1, 1)	Point counts	$\partial X \cap \partial Y^r$	Number of points in intersection of boundaries
$d = 3$	$(\varepsilon, \varepsilon')$	$\mathcal{H}^{d-\varepsilon-\varepsilon'}$	$\partial^\varepsilon X \cap \partial^{\varepsilon'} Y^r$	Interpretation of $\mu_{\varepsilon, \varepsilon'}(X, Y^r)$
	(0, 0)	Volume	$X \cap Y^r$	Volume of intersection
	(0, 1)	Surface area	$X \cap \partial Y^r$	Surface area of intersection inside interior of X
	(1, 0)	Surface area	$\partial X \cap Y^r$	Surface area of intersection inside boundary of X
	(1, 1)	Curve length	$\partial X \cap \partial Y^r$	Length of intersection of boundaries

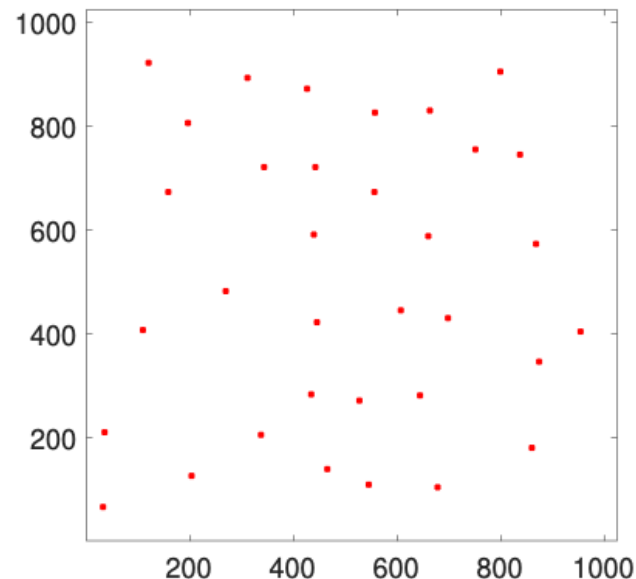
Spatial point fields vs. shape fields: shapeRelation.py

$$\mu_{00}(r) = \mathcal{H}(X \cap Y^r)$$

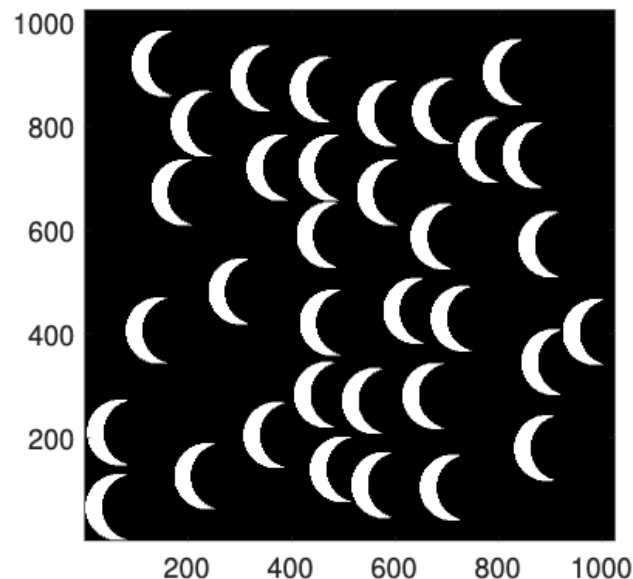
$$g_{00}(r) = \frac{d\mu_{00}(r)}{dr} = \mu_{01}(r)$$

$$f_{00}(r) = \frac{\mu_{00}(r)}{\mathcal{H}(Y^r)}$$

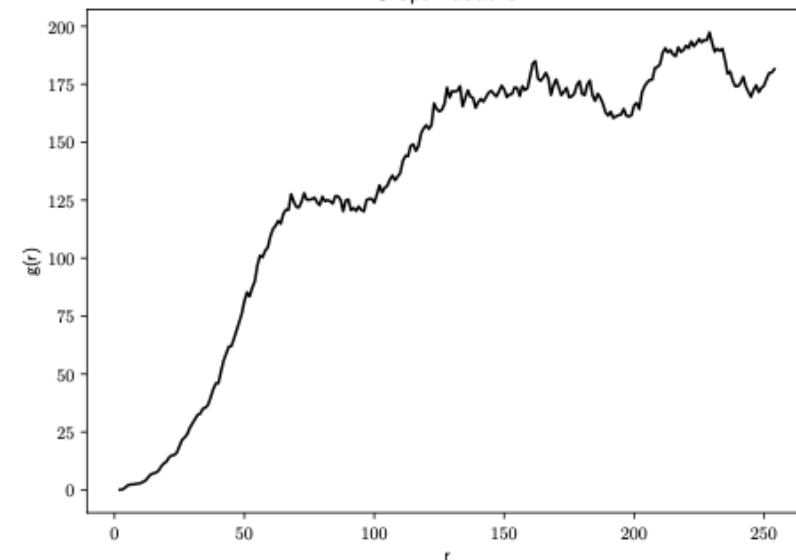
Shape Relations



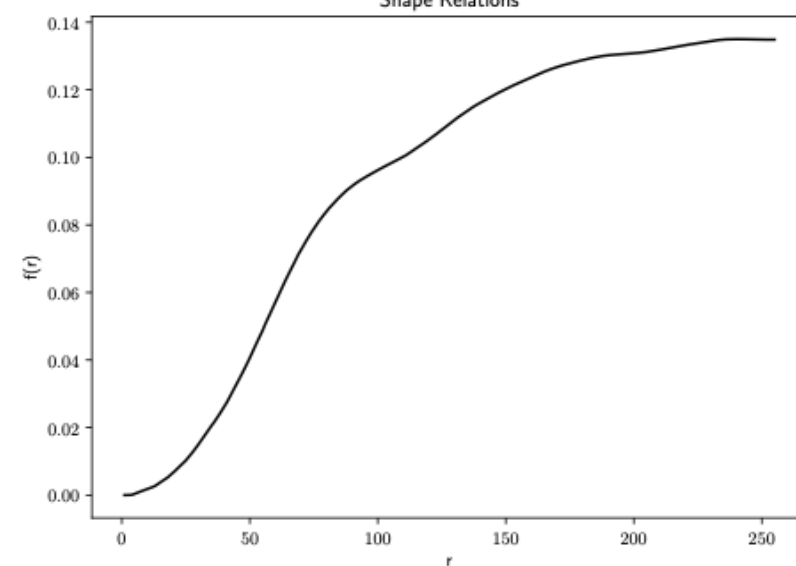
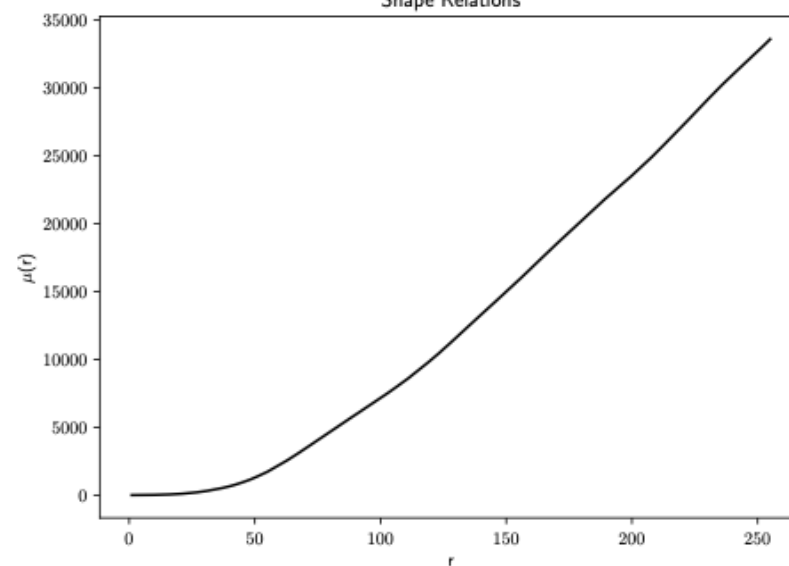
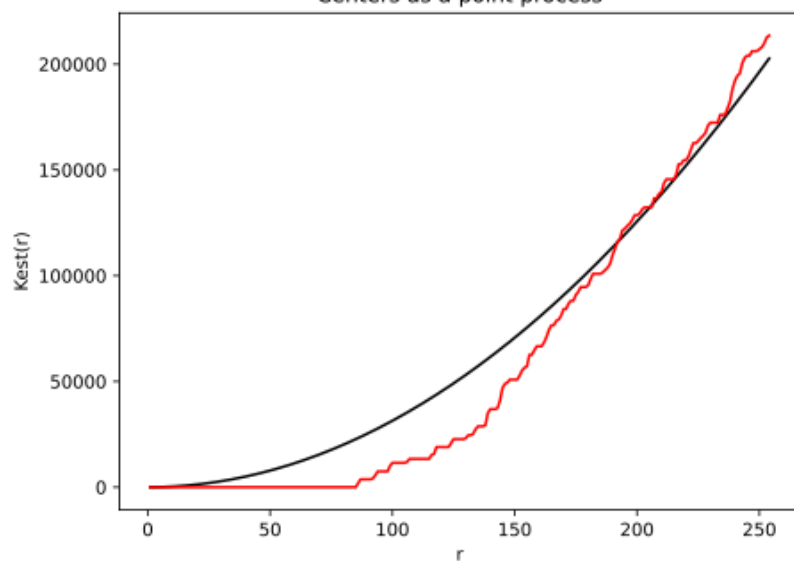
Centers as a point process



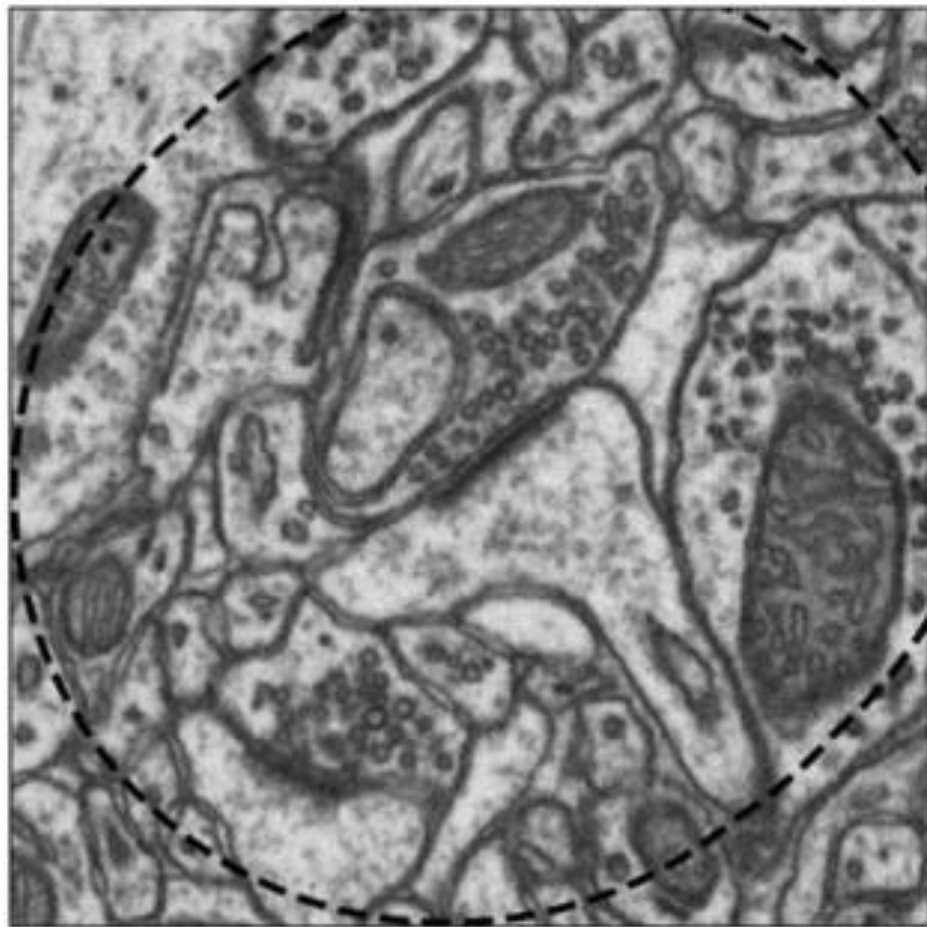
Shape Relations



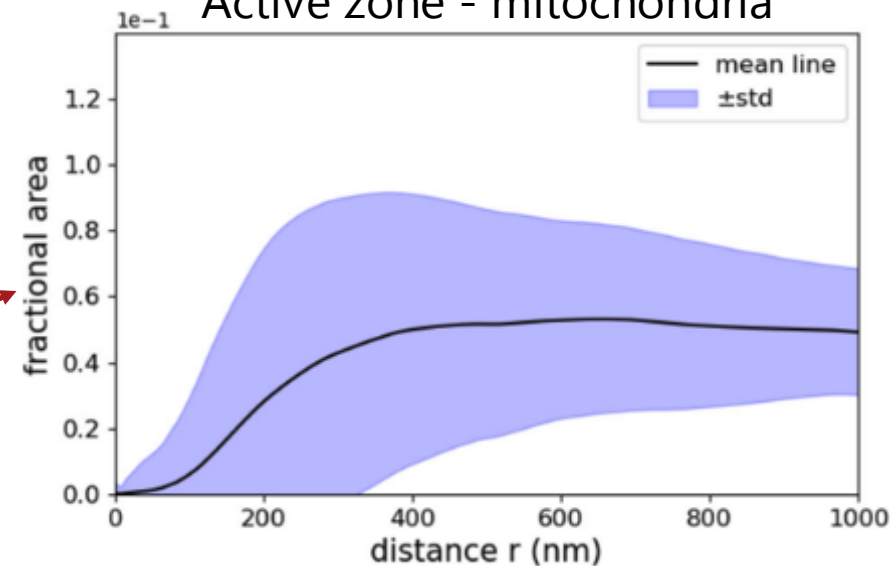
Shape Relations



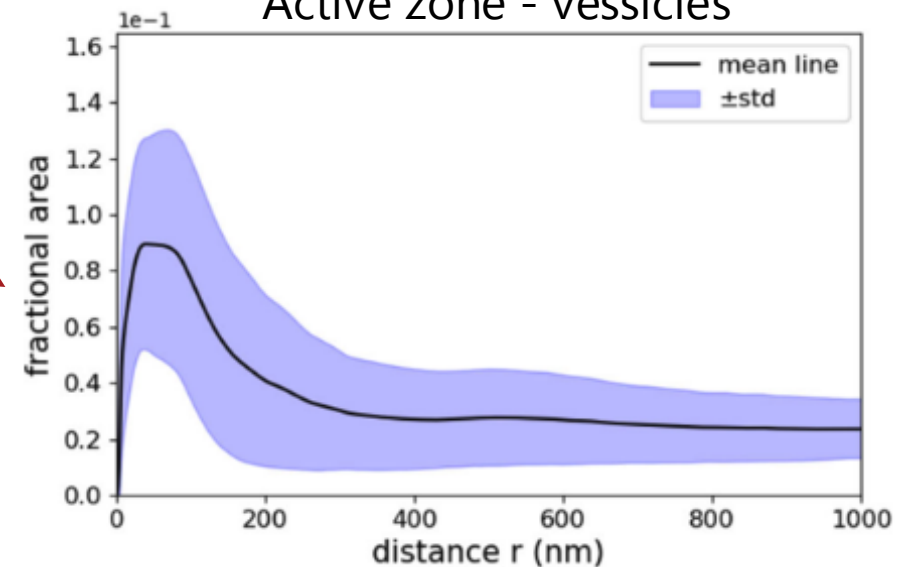
Shape relations for statistical summary of families of shapes and their relations



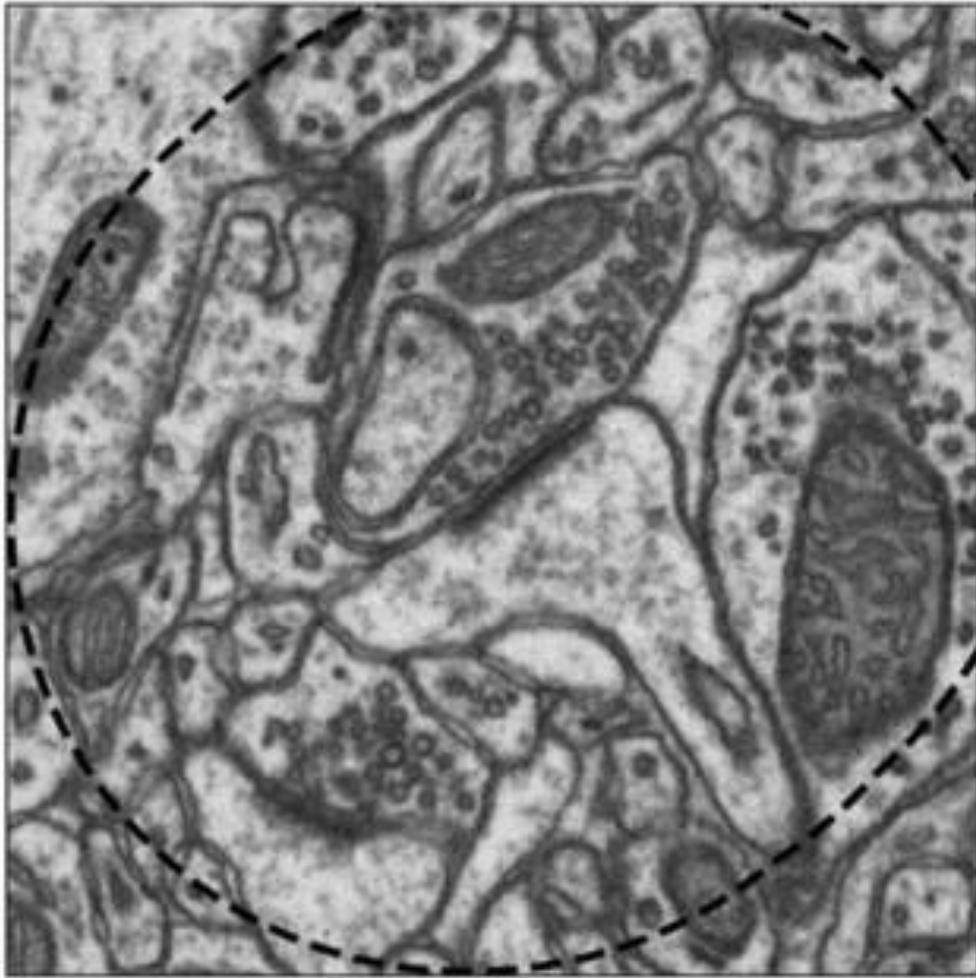
Active zone - mitochondria



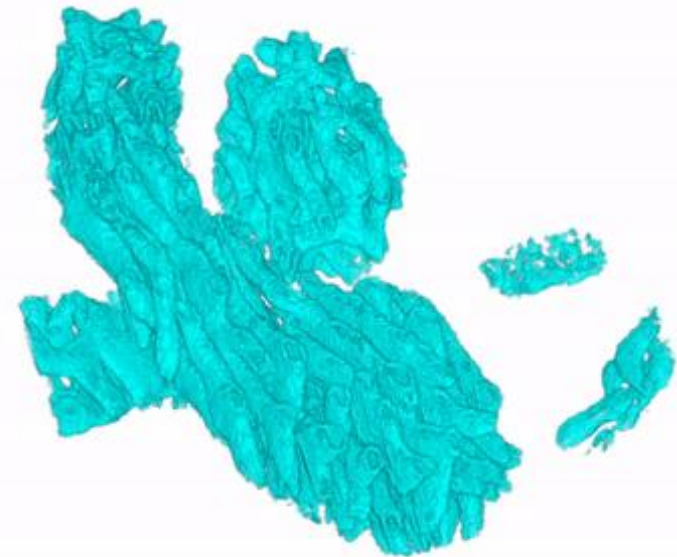
Active zone - vesicles



3. With a little help from topology: Cristae membranes in Mitochondria

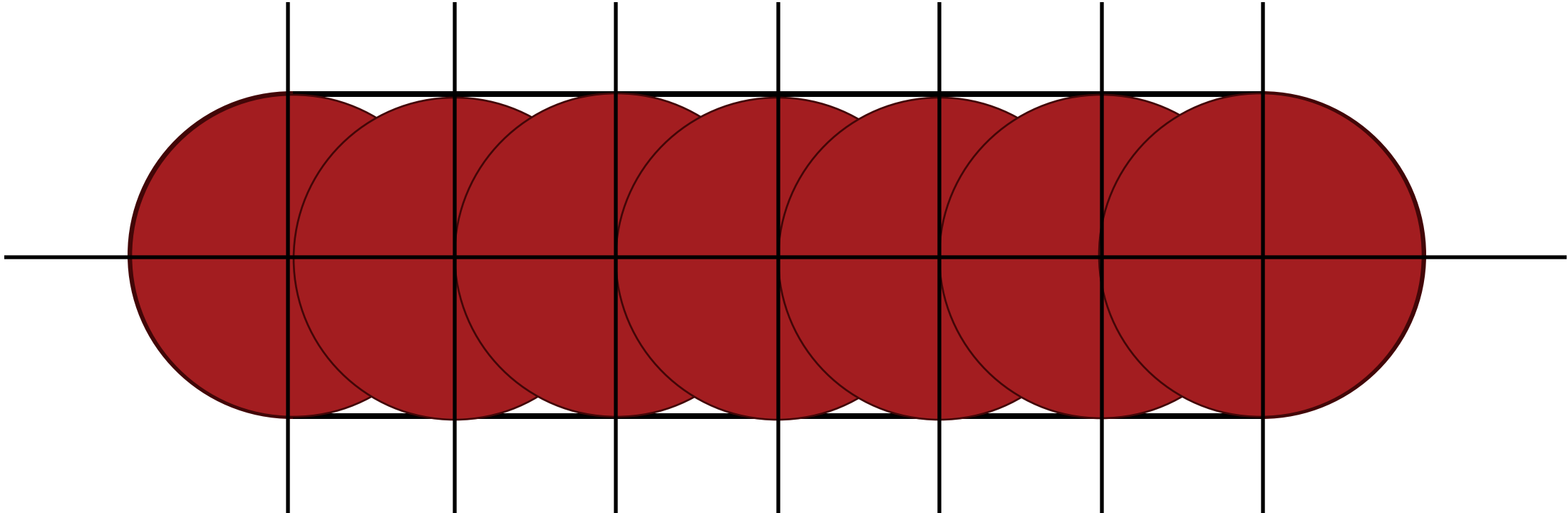


Deep Learning

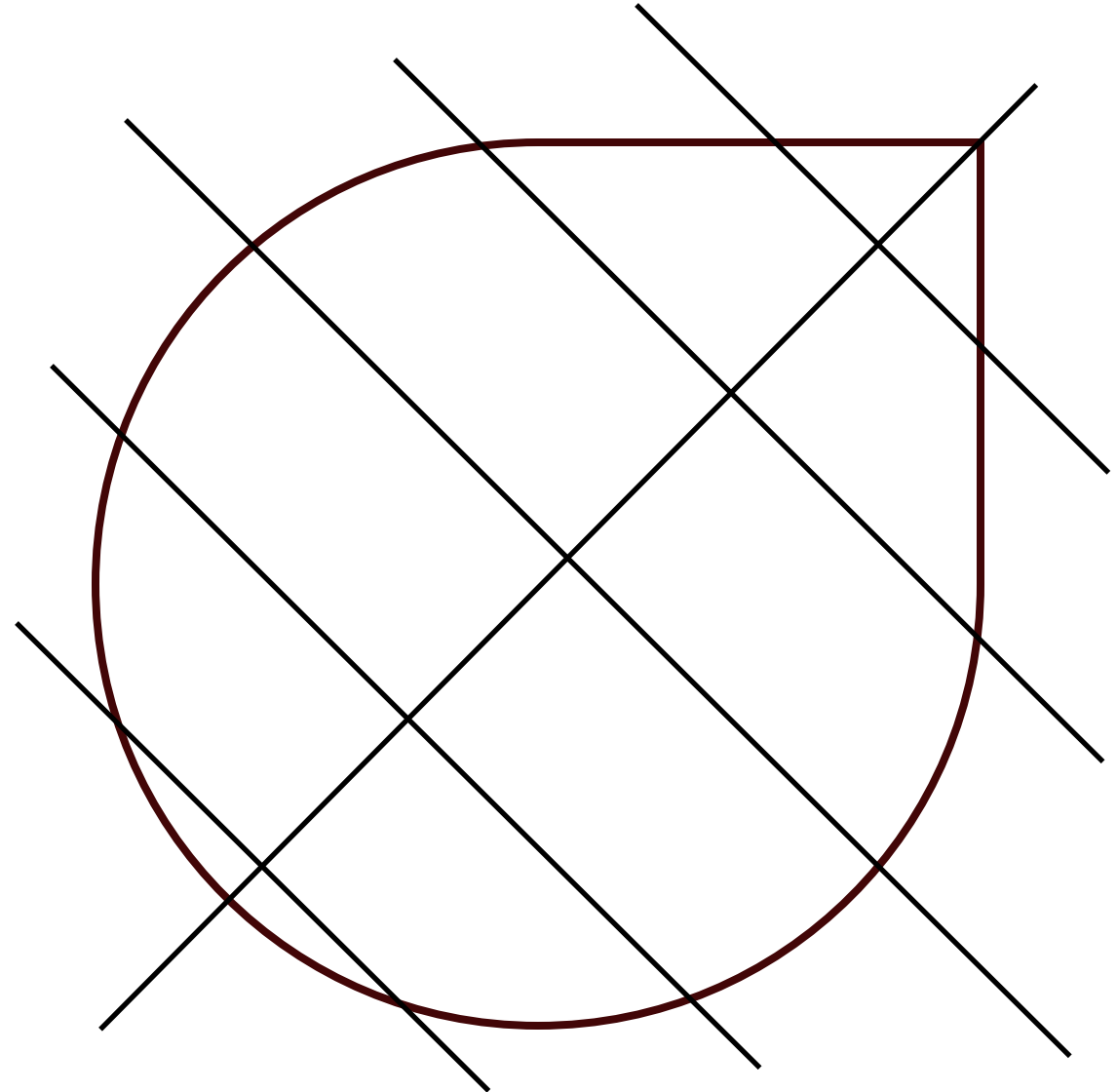
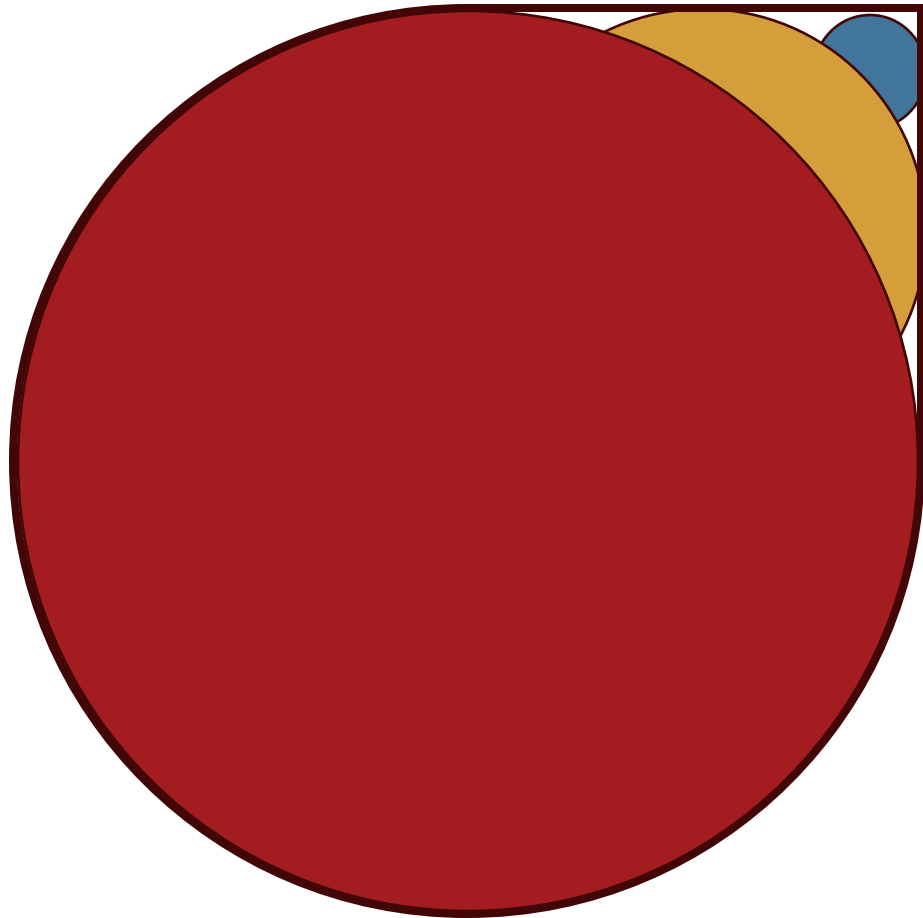


Extracting Mitochondrial Cristae Characteristics from 3D Focused Ion Beam Scanning Electron Microscopy Data, C Wang, L Østergaard, S Hasselholt, & J Sparring, to appear in Communications Biology, 2024

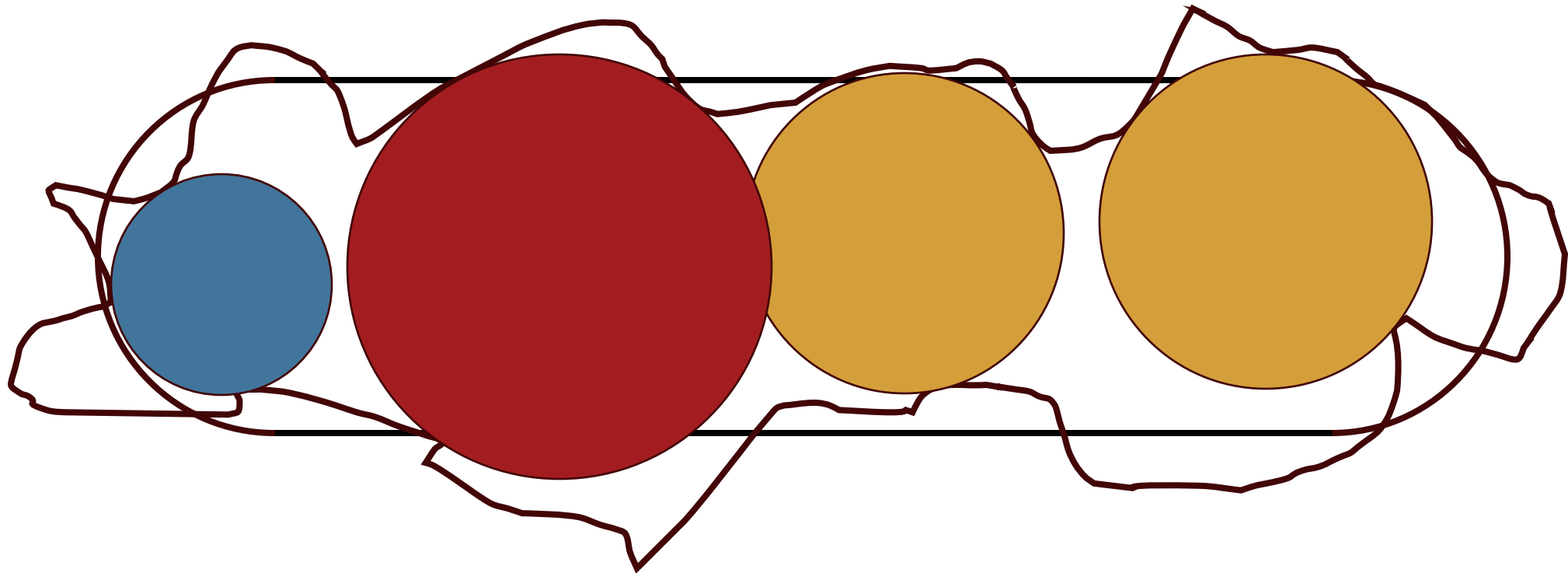
Local thickness is biased, but what is the definition of thickness?



Local thickness is biased, but what is the definition of thickness?



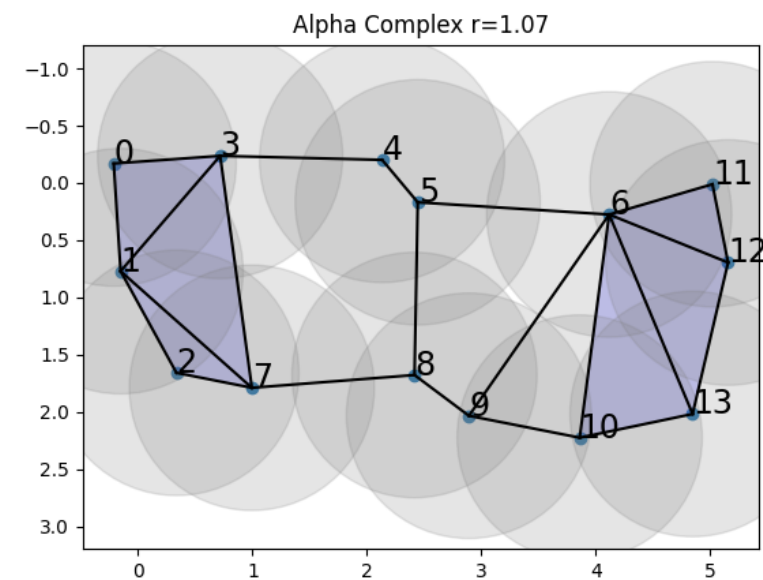
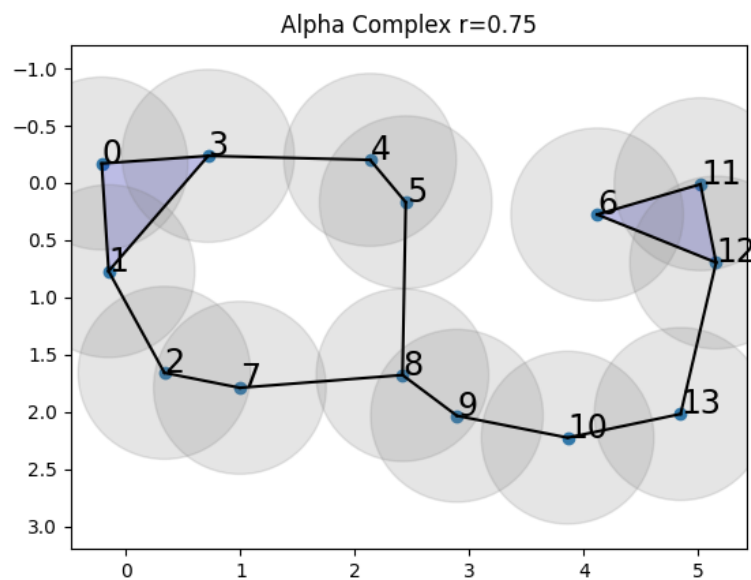
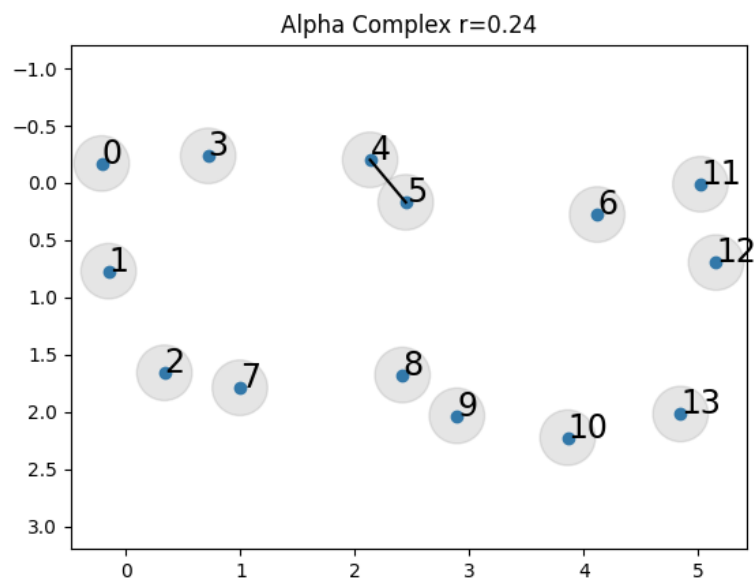
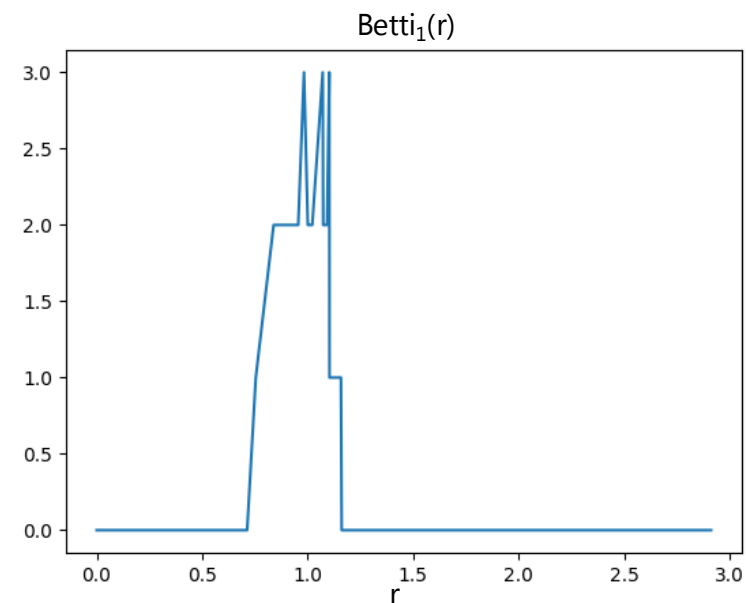
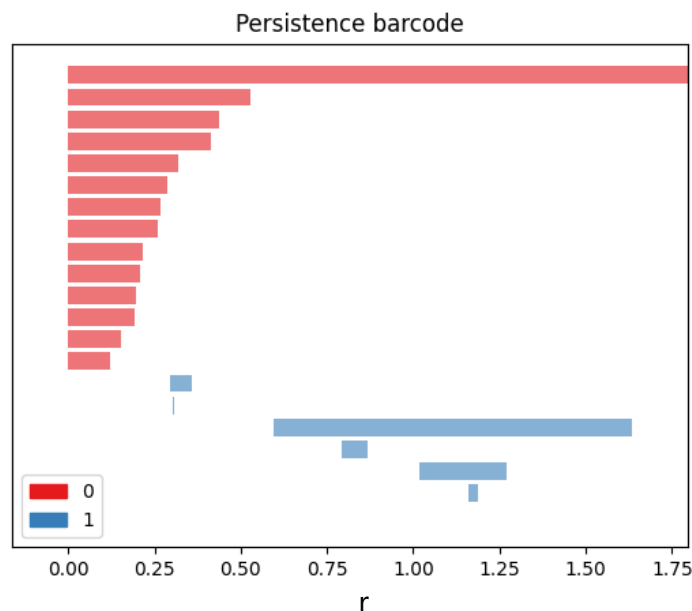
Local thickness is biased, but what is the definition of thickness?



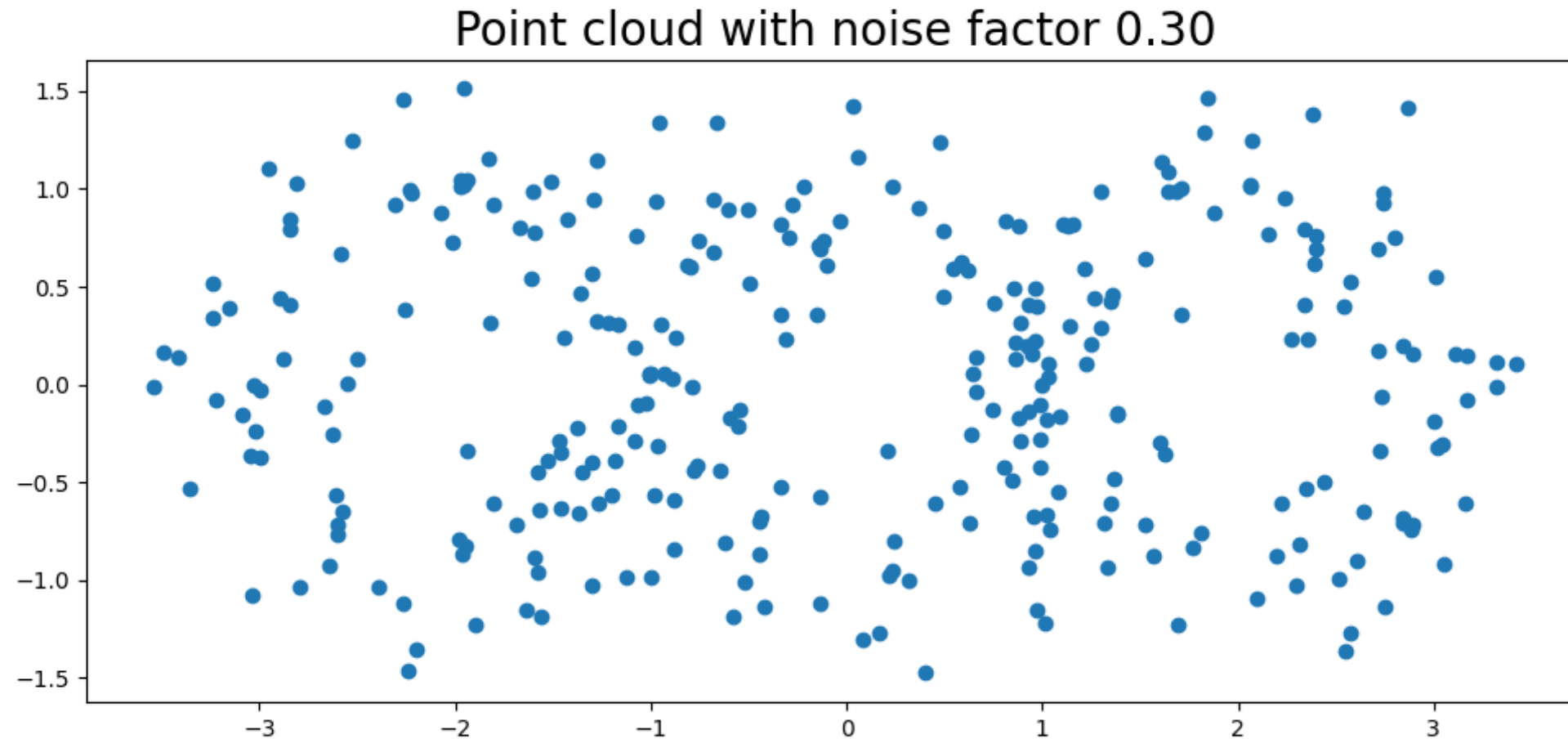
Persistent homology and friends: <https://gudhi.inria.fr/>

Simplex $\sigma = [x_0, x_1, \dots, x_k]$ is in the
alpha complex if

$$\bigcap_{x_i \in \sigma} B(x_i, r) \neq \emptyset$$

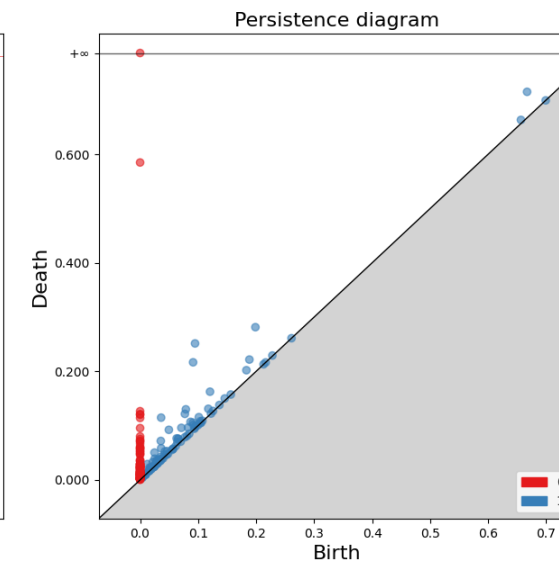
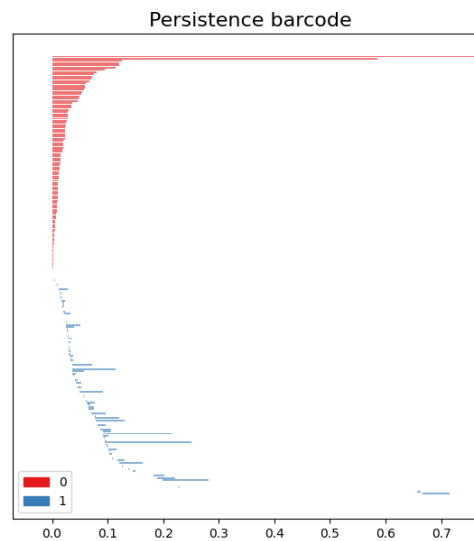
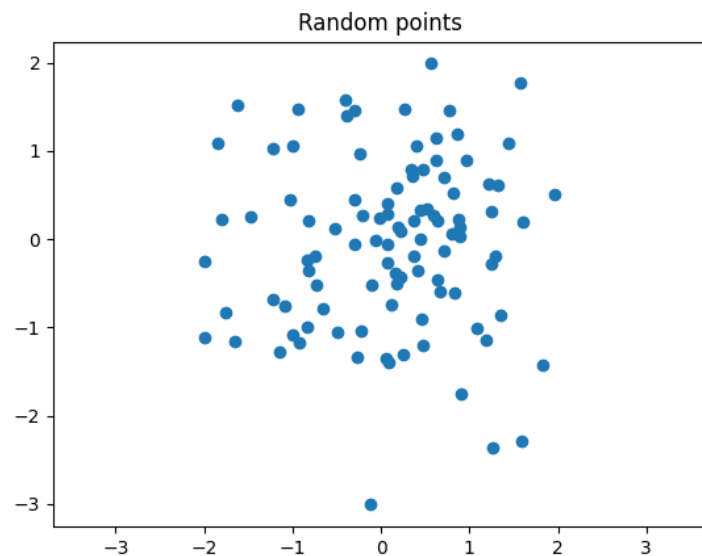


Persistence under noise: $\text{dgm} = \text{dgm}^{\text{Signal}} \cup \text{dgm}^{\text{Noise}}$

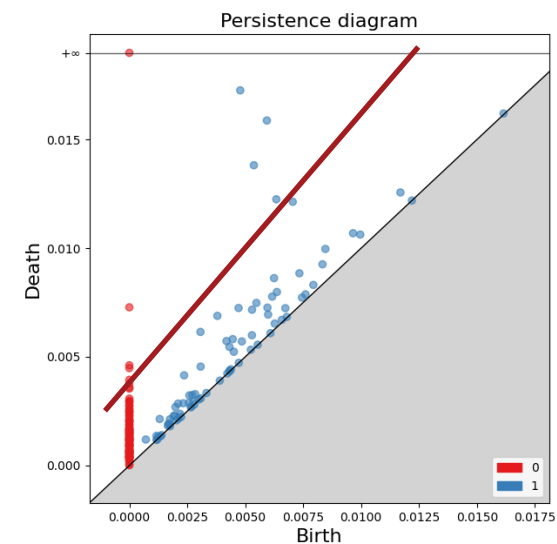
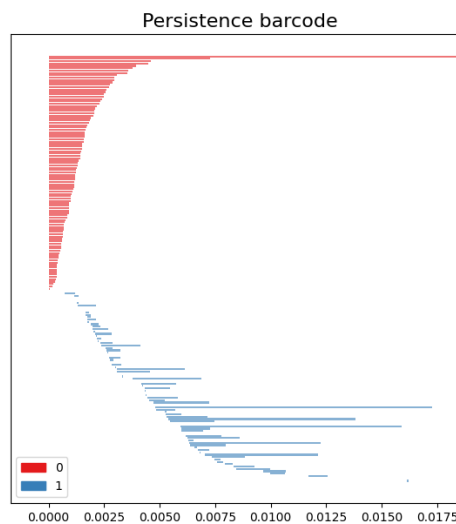
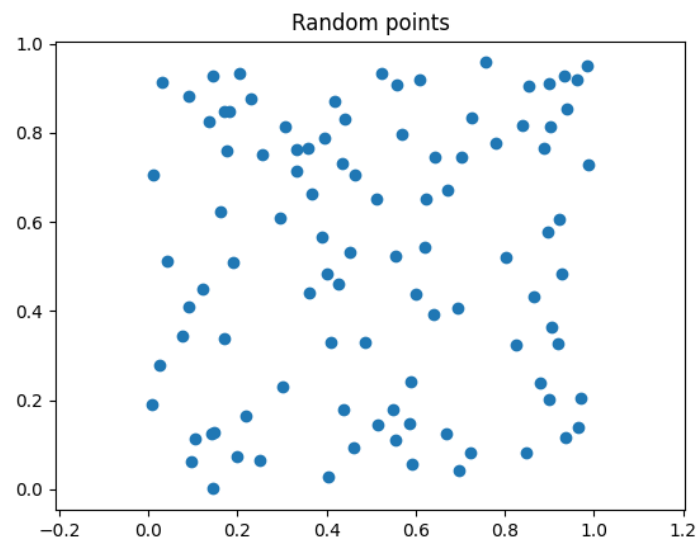


Pure noise

Normal



Uniform



Bobrowski & Skraba, "A universal null-distribution for topological data analysis", Nature/Scientific Reports, 2023

Random points:

$$x \in S(d), \quad x \sim f, \quad p = (r_{\text{birth}}, r_{\text{death}})$$

Left-skewed Gumbel distribution:

$$F(x) = 1 - e^{-e^x}, \quad f(x) = e^{x-e^x}, \quad \mu = -\gamma = -0.57721, \quad \sigma^2 = \frac{\pi^2}{6}$$

Transformation:

$$\rho = \ln \ln \frac{r_{\text{death}}}{r_{\text{birth}}}$$

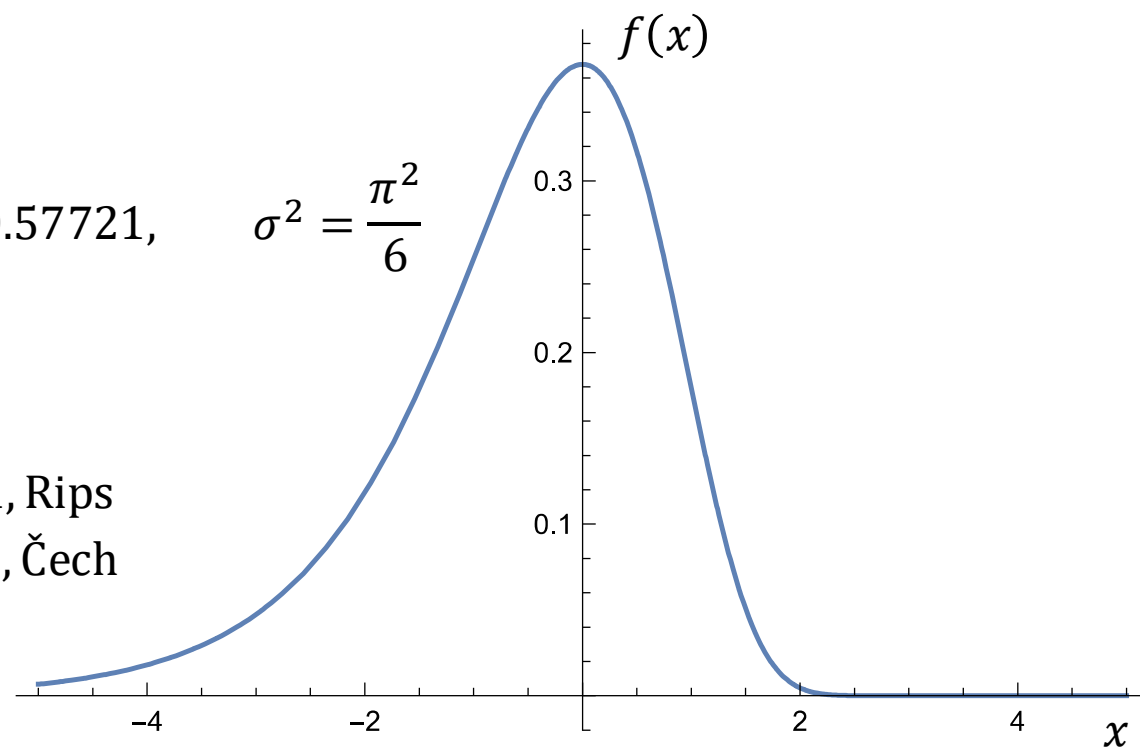
$$x = \frac{(\rho - \bar{\rho})}{\beta} - \gamma, \quad \bar{\rho} = \frac{1}{|\text{dgm}_k|} \sum_{p \in \text{dgm}_k} \rho, \quad \beta = \begin{cases} 1, \text{Rips} \\ 2, \text{Čech} \end{cases}$$

Bonferroni testing (family-wise error rate $< \alpha$):

$$P(x \geq x_0 | x \text{ is noise}) = 1 - F(x) = e^{-e^{x_0}}$$

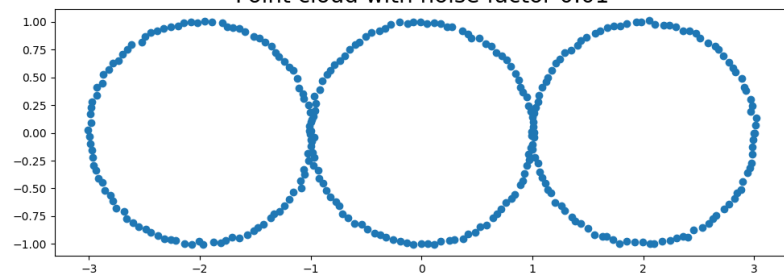
$$\text{dgm}_k^{\text{Signal}}(\alpha) = \left\{ p \in \text{dgm}_k : e^{-e^x} < \frac{\alpha}{|\text{dgm}_k|} \right\}$$

$$e^\rho = \ln \frac{r_{\text{death}}}{r_{\text{birth}}} = (-1)^\beta e^{\beta\gamma + \bar{\rho}} \left(\ln \frac{\alpha}{|\text{dgm}_k|} \right)^\beta$$

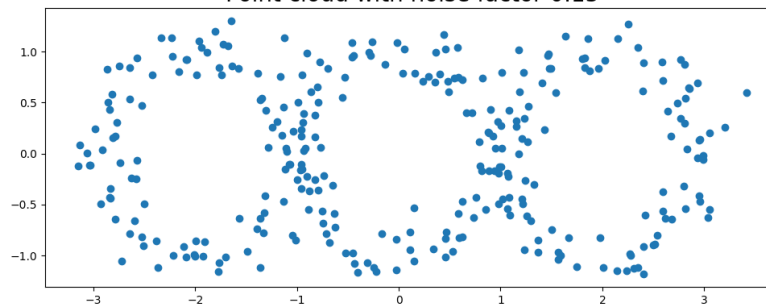


The universal distribution can separate very noisy cases

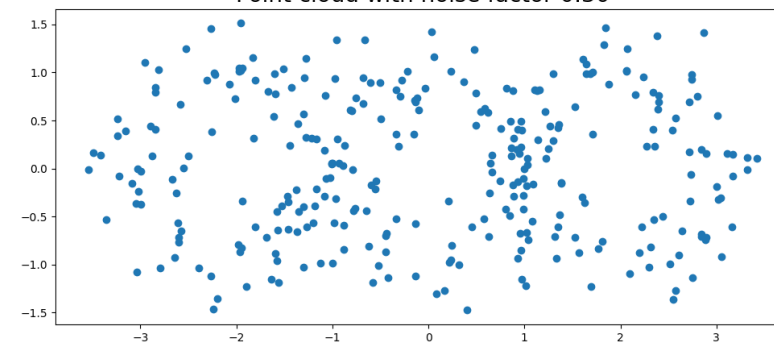
Point cloud with noise factor 0.01



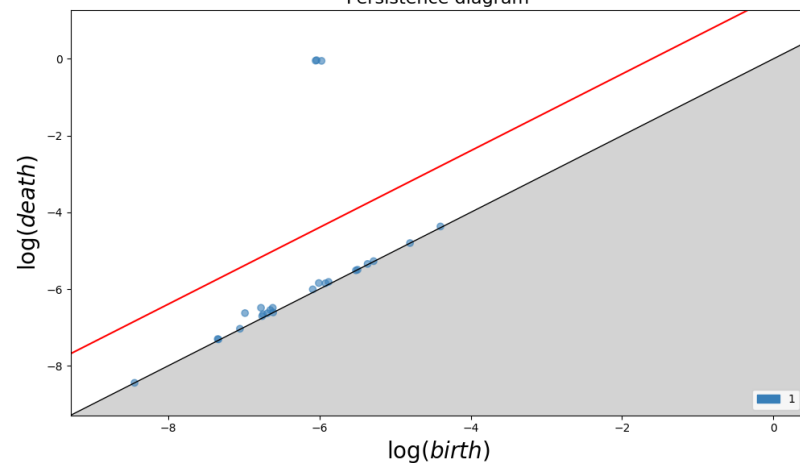
Point cloud with noise factor 0.15



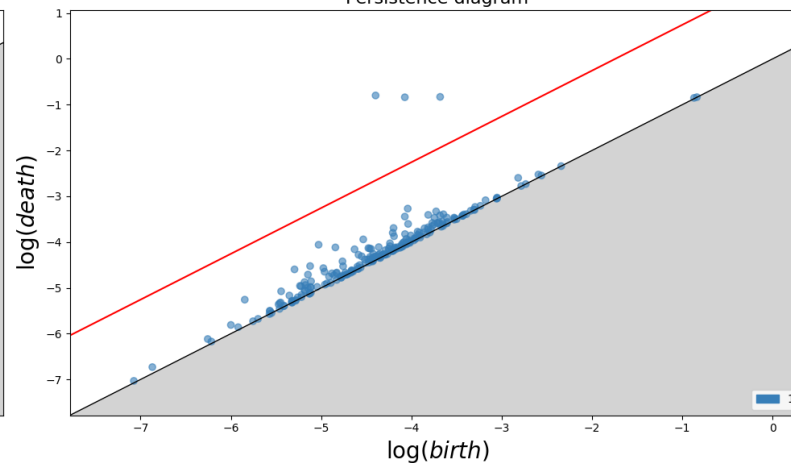
Point cloud with noise factor 0.30



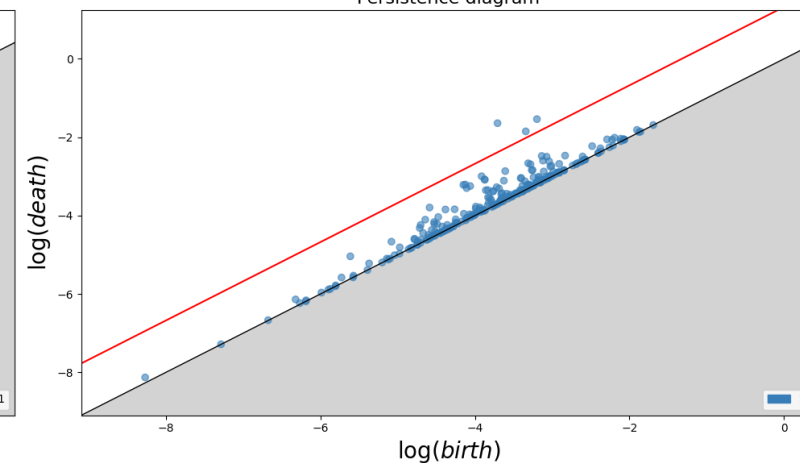
Persistence diagram



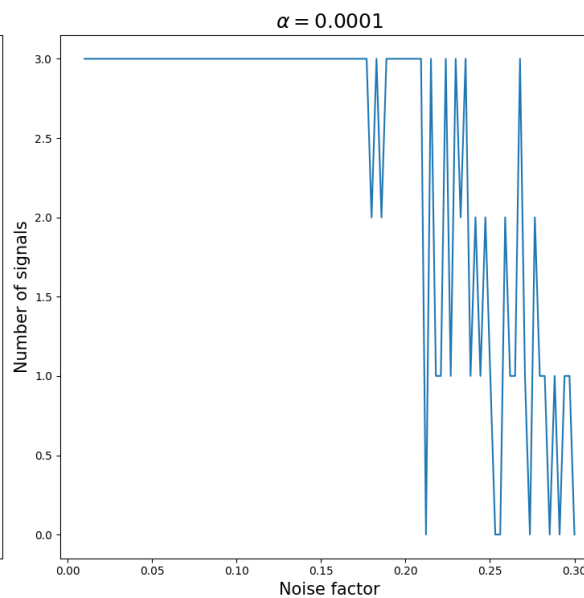
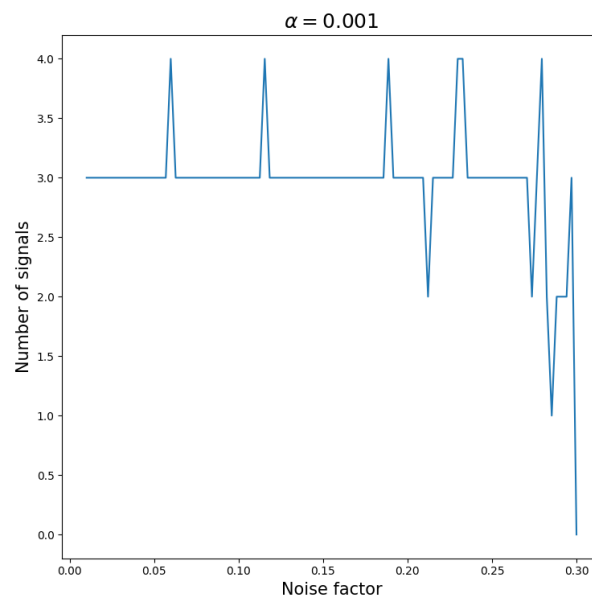
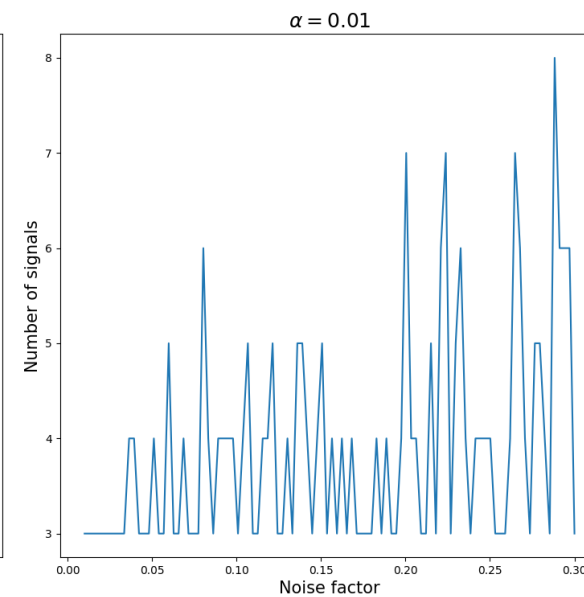
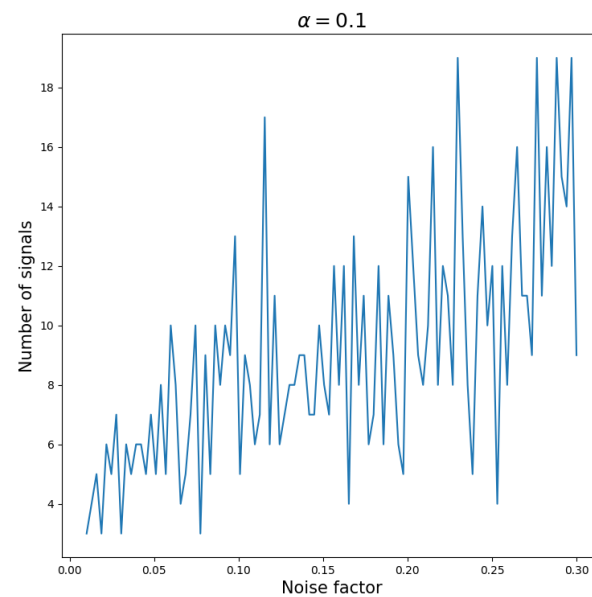
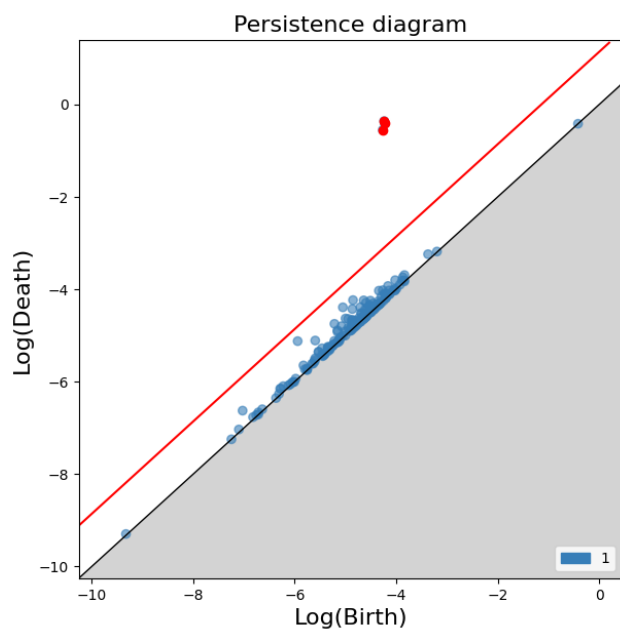
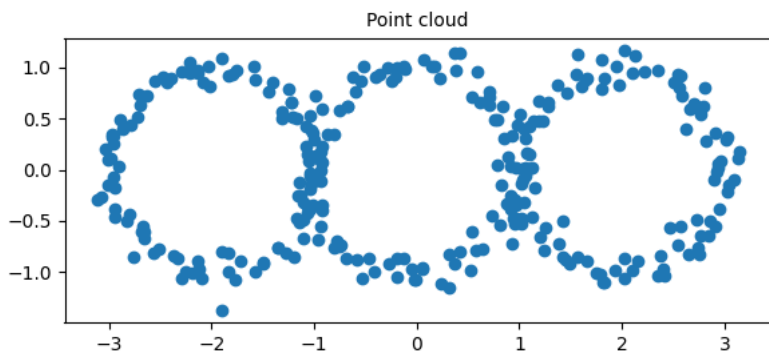
Persistence diagram



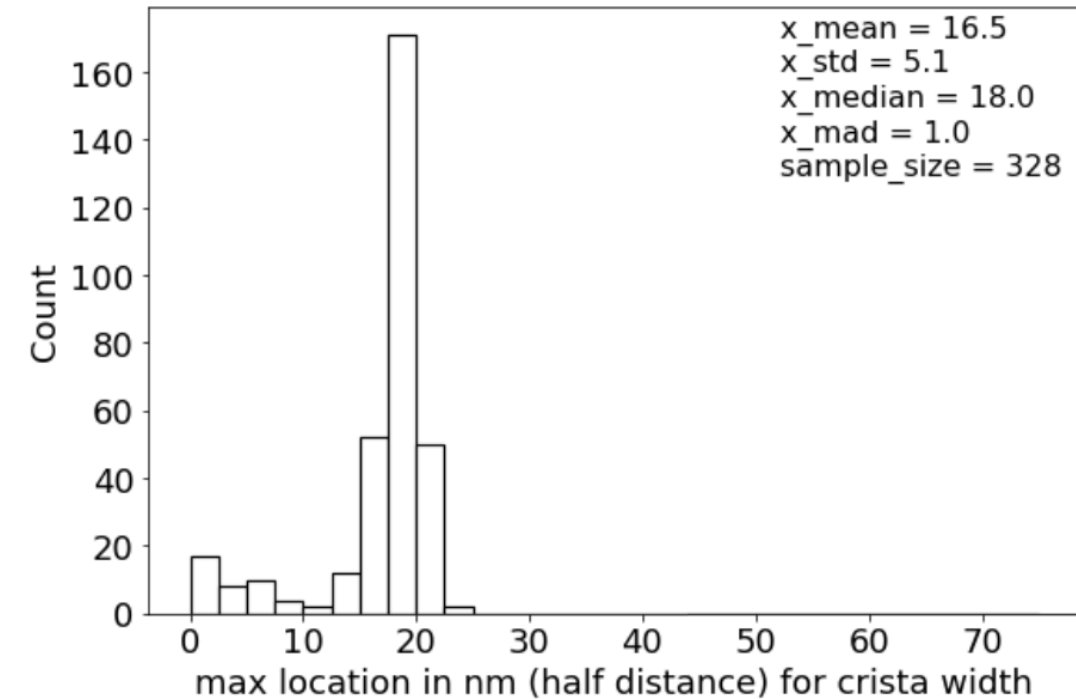
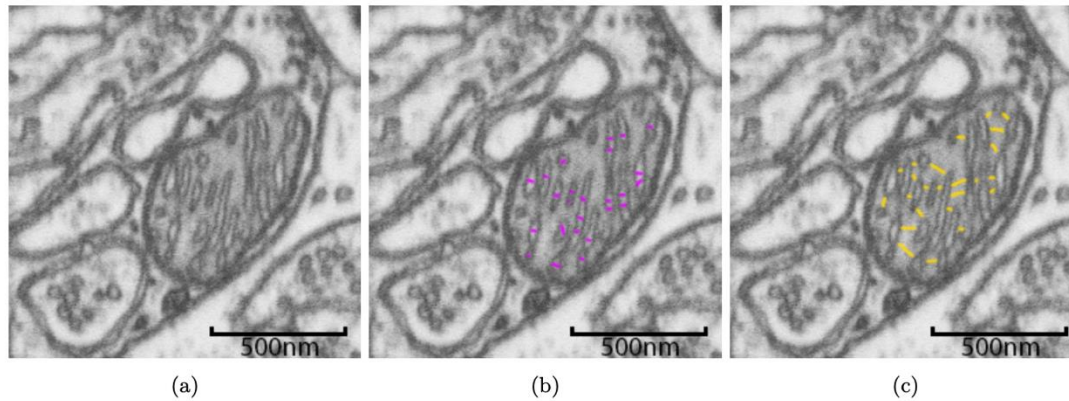
Persistence diagram



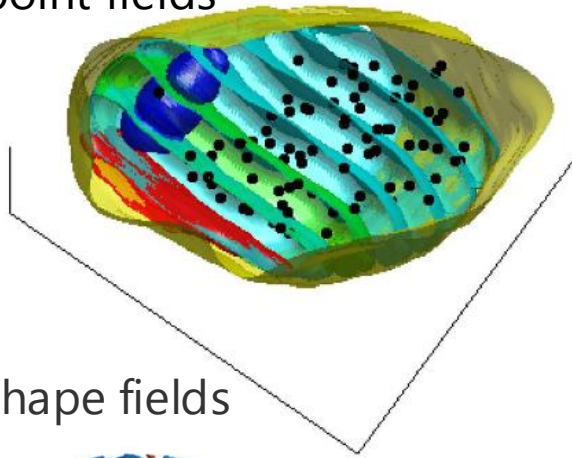
Family-wise error rate



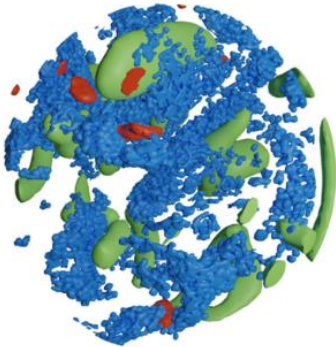
Persistent homology: Statistical measures on H_0



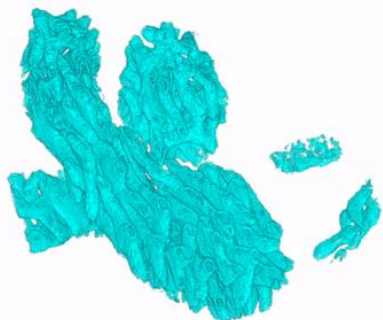
Spatial point fields



Spatial shape fields



Topological data analysis



Statistical summary of object collections

Pair correlation and Ripley's K functions summarize 1st order point relations – e.g., do the vesicles cluster?

Hausdorff measures on overlapping sets extend notion of points to shapes – e.g., are mitochondria seen close to the synapse?

Filtrations bring topological concepts to measurements – e.g., what is the average tubular radius of complicated objects

