# 凸优化project2报告

### 1 (a)

dual:

$$egin{aligned} \max _{y \in \mathbb{R}^m, s \in \mathbb{R}^n} b^T y \ s.\, t: A^T y + s = c \ s \geqslant 0 \end{aligned}$$

equal problem:

$$egin{aligned} \min_{y \in \mathbb{R}^m, s \in \mathbb{R}^n} -b^T y + l_{s \geqslant 0}(s) \ s. \ t: A^T y + s = c \end{aligned}$$

Augumented Lagrange Equation:

$$egin{aligned} L_
ho(y,s;x) &= -b^T y + l_{s\geqslant 0}(s) + x^T (A^T y + s - c) + rac{
ho}{2} ||A^T y + s - c||_2^2 \ &= -b^T y + l_{s\geqslant 0}(s) + rac{
ho}{2} [||A^T y + s - c||_2^2 + rac{2}{
ho} x^T (A^T y + s - c) + rac{1}{
ho^2} ||x||_2^2 - rac{1}{
ho^2} ||x||_2^2 ] \ &= -b^T y + l_{s\geqslant 0}(s) + rac{1}{2
ho} (||
ho(A^T y + s - c) + x||_2^2 - ||x||_2^2) \end{aligned}$$

Augumented Lagrange Equation:

$$egin{aligned} L_
ho(y;x) &= \inf_s L_
ho(y,s;x) \ &= L_
ho(y,s_0;x) \ where \ rac{\partial L_
ho(y,s;x)}{\partial s} = 0 \ and \ s_0 = \Pi_{s\geqslant 0}(-rac{x}{
ho} + c - A^Ty) \ &= -b^Ty + rac{1}{2
ho}(||
ho(A^Ty-c) + x + \Pi_{s\geqslant 0} - (x + 
ho(A^Ty-c))||_2^2 - ||x||_2^2) \ &= -b^Ty + rac{1}{2
ho}(||\Pi_{s\geqslant 0}(x + 
ho(A^Ty-c))||_2^2 - ||x||_2^2) \end{aligned}$$

ALM:

$$y^{k+1} = argmin_y L_
ho(y,x^k)$$
———这个子问题可以用 $homework5$ 里的方法求 $x^{k+1} = \Pi_{s\geqslant 0}(x^k + 
ho(A^Ty^{k+1} - c)$ 

# 1(b)

$$rac{\partial L_{
ho}(y,x^k)}{\partial y} = -b + A(\Pi_{s\geqslant 0}(x^k + 
ho(A^Ty - c)))$$

这里用梯度下降的方法求解子问题。收敛速度比较慢,原因可以用论文里的解释。就是说ALM就是dual问题的梯度下降,求解子问题也用梯度下降的话,理论上是更慢的。

- It has long been known that the augmented Lagrangian method for convex problems is a gradient ascent method applied to the corresponding dual problems
- This inevitably leads to the impression that the augmented Lagrangian method for solving SDP problems may converge slowly for the outer iteration sequence  $X_k$

具体算法可见程序源码。

## 1(c)

- 这里计算 $M(y)\inrac{\partial^2L_
  ho(y,x^k)}{y}$ , $M(z)=
  ho APA^T$ ,其中P是对角阵, $P_{ii}=1$ 若 $(x^k+
  ho(A^Ty-c))_i>=0$ , $P_{ii}=0$ 若 $(x^k+
  ho(A^Ty-c))_i<0$
- 按照论文里的算法2和算法3实现,具体算法见程序源码。

## 2 (a)

#### ADMM:

dual problem

$$egin{aligned} min - b^T y + l_{s\geqslant 0}(s) \ s.\ t \ A^T y + s = c \end{aligned}$$

ADMM algorithom:

$$egin{aligned} y^{k+1} &= argmin_y - b^T y + < x^k, A^T y > + rac{
ho}{2} ||A^T y + s^k - c||_2^2 \ y^{k+1} &= (
ho A A^T)^{-1} (b - A x^k - 
ho A (s^k - c)) \ s^{k+1} &= argmin_s l_{s \geqslant 0}(s) + < x^k, s > + rac{
ho}{2} ||A^T y^{k+1} + s - c||_2^2 \ s^{k+1} &= \Pi_{s \geqslant 0} (-rac{x^k}{
ho} + c - A^T y^{k+1}) \ x^{k+1} &= x^k + 
ho (A^T y^{k+1} + s^{k+1} - c) \end{aligned}$$

#### DRS:

primal problem

$$egin{aligned} & min \ \ c^T x \ s. \ t \ \ Ax = b \ \ x \geqslant 0 \end{aligned}$$

转换一下形式

$$egin{aligned} min \;\; g(x) + f(x) \ g(x) &= c^T x + l_{Ax=b}(x) \ f(x) &= l_{x\geqslant 0}(x) \end{aligned}$$

DRS algorithom:

$$egin{aligned} u^+ &= prox_{
ho g}(x+w) \ u^+ &= (-c
ho + x + w) + A^T(AA^T)^{-1}(b-A(-c
ho + x + w)) \ x^+ &= prox_{
ho f}(u^+ - w) \ x^+ &= \Pi_{s\geqslant 0}(u^+ - w) \ w^+ &= w + x^+ - u^+ \end{aligned}$$

# **2(b)-----**对某个问题用**ADMM**等价于对它的对偶问题用**DRS-----**

这里ADMM中出现的变量有 $y^{k+1}, s^{k+1}, x^{k+1}$ ,DRS中出现的变量有 $u^+, x^+, w^+$ .

它们之间的关系是:

$$u^+ = x^k + 
ho s^k + 
ho (A^T y^{k+1} - c) \ x^+ = x^{k+1} \ w^+ = 
ho s^{k+1}$$

可以结合2(a)验证关系成立。下面给出一般性的证明。

ADMM:

$$min \ f_1(x_1) + f_2(x_2) \ s.t: A_1x_1 + A_2x_2 = b$$

algorithom:

$$egin{aligned} x_1^{k+1} &= argmin_{x_1}f_1(x_1) + < A_1x_1, z^k > + rac{
ho}{2}||A_1x_1 + A_2x_2^k - b||_2^2 \ x_2^{k+1} &= argmin_{x_2}f_2(x_2) + < A_2x_2, z^k > + rac{
ho}{2}||A_1x_1^k + A_2x_2 - b||_2^2 \ z^{k+1} &= z^k + 
ho(A_1x_1^{k+1} + A_2x_2^{k+1}) \end{aligned}$$

DRS:

$$egin{aligned} min & b^Tz + f_1^*(-A_1^Tz) + f_2^*(-A_2^Tz) \ & g(z) := b^Tz + f_1^*(-A_1^Tz) \ & f(z) := f_2^*(-A_2^Tz) \end{aligned}$$

algorithom:

$$u^{+} = prox_{
ho g}(z+w) \ z^{+} = prox_{
ho f}(u^{+}-w) \ w^{+} = w + z^{+} - u^{+}$$

对对偶问题用proximal method 等价于对原问题用ALM。从而ADMM和DRS的关系得证。

下面具体证明

· proximal method:

$$egin{aligned} u^+ &= prox_{
ho g}(z+w) \ u^+ &= argmin_x b^T x + f_1^* (-A_1^T x) + rac{1}{2
ho} ||x-(z+w)||_2^2 &----(1) \end{aligned}$$

ALM:

$$egin{aligned} u^+ &= z + w + 
ho(A_1 \hat{x}_1 - b) & - - - - - (2) \ \hat{x}_1 &= argmin_{x_1} f_1(x_1) + < z + w, A_1 x_1 > + rac{
ho}{2} ||A_1 x_1 - b||_2^2 & - - - - - (3) \end{aligned}$$

上面三个等式等价:这里通过验证最优性条件说明,就是(2)的解满足(1)的最优性条件。

- 对(1)求导有:  $b A_1 \partial f_1^* (-A_1^T x) + \frac{1}{a} (x (z w)) = 0$
- 对(3)求导有:  $\partial f_1(x_1) + A_1^T(z+w) + \rho A_1^T(A_1x_1-b) = 0$
- 容易证明这里(2)满足(1)的最优性条件,其中要用到共轭函数之间的梯度的性质
- · proximal method

$$egin{aligned} z^+ &= prox_{
ho f}(u^+ - w) \ &= prox_{
ho f}(z + 
ho(A_1\hat{x}_1 - b)) \ &= argmin_x f_2^*(-A_2^T x) + rac{1}{2
ho}||z + 
ho(A_1\hat{x}_1 - b) - x||_2^2 \end{aligned}$$

ALM

$$z^+ = z + 
ho(A_1\hat{x}_1 - b) + 
ho A_2\hat{x}_2 \ \hat{x}_2 = argmin_{x_2}f_2(x_2) + < A_2x_2, z + 
ho(A_1\hat{x}_1 - b) > + rac{
ho}{2}||A_2x_2||_2^2$$

类似上面验证最优性条件的证明,可以知道结论成立。

这里也可以通过下式来推,容易理解但比较难推。

Moreau decomposition: 
$$z^+=z+
ho(A_1\hat{x}_1-b)+
ho\ prox_{
ho^{-1}f^*}(rac{z}{
ho}+A_1\hat{x}_1-b)$$

• 从而  $w^+ = A_2 \hat{x}_2$  和LP问题对应起来可知前面的关系式成立。

# 2(c) ------l1\_semi\_smooth\_newton\_method-----

- 首先这里的f(x),h(x)有很多种选择,老师课件上的M(x)写错了,这里按照论文里的方法选取。这里第一步是写出F(x)和J(x)的表达式剩下的就是按照论文里的算法实现。
- $f(x) = l_{Ax=b}(x)$ ,  $prox_{tf}(x) = (I A^T(AA^T)^{-1}A)x + A^T(AA^T)^{-1}b$
- $ullet h(x) = c^T x + l_{x>0}(x)$  ,  $prox_{th}(x) = \Pi_{s>0}(x-ct)$
- $F(x) = prox_{th}(x) prox_{tf}(2prox_{th}(x) x)$
- $M(x) \in \partial prox_{th}(x), M(x)_{ii} = 1$  $\preceq (x-ct)_i \geq 0, other M(x)_{ii} = 0$
- $\bullet \quad (I-A^T(AA^T)^{-1}A)(2M(x)-I) \in \partial prox_{tf}(2prox_{th}(x)-x)$
- $J(x) = M(x) (I A^{T}(AA^{T})^{-1}A)(2M(x) I)$

• mothod	objective	sum(abs(x	oum(obo(Av b))	used time	itorationa
method 数值实验的约	士 <b>val</b> u 古 <b>未:</b>	<0))	sum(abs(Ax-b))	used time	iterations

method	objective valu	sum(abs(x <0))	sum(abs(Ax-b))	used time	iterations
MOSEK	-12.709491462	0.0 0	1.29010069294e- 09	0.02344417572	NA
ALM	-12.72258707	0.0 0	0.138323246271	1.42455196381	977
ADMM	-12.70949251	-1.6925073e- 15	0.00679173425056	0.187272071838	4754
DRS	-12.70895734	0.0 0	0.0042776056052	0.184229850769	5701
semi_smooth	-12.70949531	0.0.0	0.00501662552313	0.30599999	605
newton_CG	-12.70949146	0.0.0	5.27267118855e- 12	0.384999990463	303

附件:

```
In [45]: runfile('C:/Users/wxp/Desktop/编程实验-凸优化/期末作业/期末作业.py',
MOSEK objective: -12.7094914621
MOSEK sum(abs(x-xs)): 0.228331169516
MOSEK sum(abs(Ax-b)) erro: 3.21964677141e-14
MOSEK sum(x[x<0]) erro: -3.75017555465e-11 35
ALM iteration times: 977
Alm: objective value : [[-12.72258707]]
Alm sum(abs(x-xs)): 0.193036357227
ALm sum(abs(Ax-b)) erro: 0.0685411447882
Alm sum(x[x<0]) erro: 0.0 0
Alm used time: 2.29299998283
ADMM iteration times: 4754
ADMM: objective value : [[-12.70949251]]
ADMM sum(abs(x-xs)): 0.234793441312
ADMM sum(abs(Ax-b)) erro: 0.0067917342504
ADMM sum(x[x<0]) erro: -1.5810757651e-15 31
ADMM used time: 0.158999919891
********
DRS iteration times: 5701
DRS: objective value : [[-12.70895734]]
DRS sum(abs(x-xs)): 0.268017459963
DRS sum(abs(Ax-b)) erro: 0.00427760560528
DRS sum(x[x<0]) erro: 0.0 0
DRS used time: 0.163000106812
11 semi smooth iteration times: 605
l1_semi_smooth objective value : [[-12.70949531]]
l1 semi smooth sum(abs(x-xs)): 0.669181344881
l1_semi_smooth sum(abs(Ax-b)) erro: 0.00501662552213
l1_semi_smooth sum(x[x<0]) erro: 0.0 0
l1 semi smooth used time : 0.316999912262
newton_cg iterations : 303
newton_cg objective value : [[-12.70949146]]
newton_cg sum(abs(x-xs)): 0.0800430472723
newton_cg sum(abs(Ax-b)) erro: 5.27267118855e-12
newton_cg sum(x[x<0]) erro: 0.0 0
newton_cg used time : 0.384999990463
```